

Assignment 1: Modeling with DAGs

Andrew Lemke

```
In [1]: import pandas as pd
        from pgmpy.models import BayesianModel, BayesianNetwork
        from pgmpy.estimators import BayesianEstimator
```

Loading the data

The raw data comes in the form of a csv.

```
In [2]: data_file = 'transportation_survey.txt'
```

```
In [3]: raw_data = pd.read_csv(
        data_file
    )
```

```
In [4]: raw_data.head(10)
```

```
Out[4]:
```

	A	S	E	O	R	T
0	adult	F	high	emp	small	train
1	young	M	high	emp	big	car
2	adult	M	uni	emp	big	other
3	old	F	uni	emp	big	car
4	young	F	uni	emp	big	car
5	young	F	uni	emp	big	car
6	adult	F	high	emp	small	other
7	adult	F	high	emp	big	other
8	adult	M	high	emp	big	car
9	adult	M	high	emp	big	car

The default options for loading the csv worked well.

Building the DAG

The variables in the model are:

- **Age**, young for those under 30, old for those over 60, and adult for those between young and old
- **Sex**, the sex of the individual, M or F

- **E**ducation, whether the individual completed high school only (high) or has a university degree (uni)
- **O**ccupation, (self) employed or (emp)loyee
- **R**esidence, if the person lives in a (small) or (big) city
- **T**ransport, the preferred means of travel of the individual

DAG



```
In [5]: # the relationships are put in as pairs of source node to destination node
model = BayesianNetwork(
    [('A', 'E'), ('S', 'E'), ('E', 'O'), ('E', 'R'), ('O', 'T'), ('R', 'T')]
)
```

Learning the conditional probabilities

Since we do not have any priors to distribute on, we will use the `K2` prior type, which is a dirichlet distribution with every pseudo count set to 1. If we had some other data to indicate some prior to distribute on (for example a similar dataset from another similar country) we could use it as a prior.

```
In [6]: estimator = BayesianEstimator(model, raw_data)
```

```
In [7]: # T is the node we desire the conditional probability distribution on
cpd_C = estimator.estimate_cpd('T', prior_type="K2")
```

```
In [8]: print(cpd_C)
```

O	O(emp)	...	O(self)	O(self)
R	R(big)	...	R(big)	R(small)
T(car)	0.7007299270072993	...	0.4166666666666667	0.5
T(other)	0.1362530413625304	...	0.3333333333333333	0.25
T(train)	0.1630170316301703	...	0.25	0.25

```
In [9]: for x in estimator.get_parameters('K2'):
        print(x)
```

```

+-----+-----+
| A(adult) | 0.387674 |
+-----+-----+
| A(old)   | 0.139165 |
+-----+-----+
| A(young) | 0.473161 |
+-----+-----+

+-----+-----+-----+-----+
| A      | A(adult)      | ... | A(young)      |
+-----+-----+-----+-----+
| S      | S(F)          | ... | S(M)          |
+-----+-----+-----+-----+
| E(high) | 0.5185185185185185 | ... | 0.7642276422764228 |
+-----+-----+-----+-----+
| E(uni)  | 0.48148148148148145 | ... | 0.23577235772357724 |
+-----+-----+-----+-----+

+-----+-----+
| S(F)    | 0.521912 |
+-----+-----+
| S(M)    | 0.478088 |
+-----+-----+

+-----+-----+-----+-----+
| E      | E(high)      | E(uni)      |
+-----+-----+-----+-----+
| O(emp) | 0.9794520547945206 | 0.9716981132075472 |
+-----+-----+-----+-----+
| O(self) | 0.02054794520547945 | 0.02830188679245283 |
+-----+-----+-----+-----+

+-----+-----+-----+-----+
| E      | E(high)      | E(uni)      |
+-----+-----+-----+-----+
| R(big)  | 0.7568493150684932 | 0.9339622641509434 |
+-----+-----+-----+-----+
| R(small) | 0.24315068493150685 | 0.0660377358490566 |
+-----+-----+-----+-----+

+-----+-----+-----+-----+-----+
| O      | O(emp)      | ... | O(self)      | O(self) |
+-----+-----+-----+-----+-----+
| R      | R(big)      | ... | R(big)      | R(small) |
+-----+-----+-----+-----+-----+
| T(car)  | 0.7007299270072993 | ... | 0.4166666666666667 | 0.5 |
+-----+-----+-----+-----+-----+
| T(other) | 0.1362530413625304 | ... | 0.3333333333333333 | 0.25 |
+-----+-----+-----+-----+-----+
| T(train) | 0.1630170316301703 | ... | 0.25 | 0.25 |
+-----+-----+-----+-----+-----+

```

The below cell is the last table in another form. The first row of the table above is the first of the three array sets below. The first line is $P(T=\text{car} \mid O=\text{emp}, R=\text{big})$, $P(T=\text{car} \mid O=\text{emp}, R=\text{Small})$, the next line is $P(T=\text{car} \mid O=\text{self}, R=\text{big})$, $P(T=\text{car} \mid O=\text{self}, R=\text{Small})$.

The next two blocks are similar for other and train.

```
In [10]: cpd_C.values
```

```
Out[10]: array([[0.70072993, 0.51764706],
               [0.41666667, 0.5       ]],

          [[0.13625304, 0.09411765],
               [0.33333333, 0.25       ]],

          [[0.16301703, 0.38823529],
               [0.25       , 0.25       ]]])
```

```
In [11]: cpd_C.variables
```

```
Out[11]: ['T', 'O', 'R']
```

Assessment Questions

1. Which factorization is factorized along the DAG (Markov factorization).

We look to the graph to find the answer.

$p(A)(S) p(E|A, S) p(O|E)p(R|E) p(T|O, R)$

2. Which is true about Node E (education):

Again, the graph shows us the answer. The parents of E are A and S. The children (the outward edges) are E and R.

3. Suppose we modify the network by removing the edge from E to O. Which local distributions (factors in the factorization) change?

With parameter modularity, changes to one node's distribution do not change other nodes' distributions. Here, the distributions are affected by a structural change to the graph. By removing edge EO, O becomes a root node--it's probability is no longer conditioned on E. This does not change the distribution on E, as E is not conditioned on O. Even though R is conditioned on O, the change to O does not alter $p(T|O, R)$ due to the parameter modularity.

asdf

A categorical variable has three outcomes with probabilities p_1 , p_2 , and p_3 . You place a Dirichlet prior on these probabilities with concentration parameters 1, 1, and 1. In data with 20 observations you observe 10 instances of class 1, 2 instances of class 2, and 8 instances of class 3. What are the concentration parameters of the posterior.

With a Dirichlet prior of 1, 1, 1, we get a uniform prior. When we get new observations, we incorporate them.

priors:

```
p1 = 1
p2 = 1
p3 = 1
```

With the new observations distributed on this prior,

```
p1 = 1 + 10
p2 = 1 + 2
p3 = 1 + 8
```

Resources

- dirichlet
 - <https://www.youtube.com/watch?v=nfBNOWv1pgE>
 - <https://www.youtube.com/watch?v=gWgsKyEjclw>
- pgmpy
 - <https://pgmpy.org/models/bayesiannetwork.html>
 - https://pgmpy.org/param_estimator/bayesian_est.html
 - <https://pgmpy.org/factors/discrete.html#module-pgmpy.factors.discrete.JointProbabilityDistribution>
 - <https://pgmpy.org/examples/Learning%20Parameters%20in%20Discrete%20Bayesian%20N>

