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# basics - math

basics

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**Argomenti.**

- **Calcolo**
  - Calcolo multivariabile e calcolo vettoriale in spazi euclidei 2D e 3D
  - Algebra lineare e multilineare su spazi con prodotto interno
  - Calcolo lineare e multilineare su spazi con prodotto interno
- **Geometria**
  - Geometria differenziale
- **Calcolo delle variazioni** (qui e/o nella scuola superiore?)
- **Calcolo complesso**
  - Analisi complessa
  - **Teoria delle trasformate:** Fourier, Laplace



**Part I**

**Multivariable Calculus**





## INTRODUCTION TO MULTI-VARIABLE CALCULUS

### 1.1 Function

### 1.2 Limit

### 1.3 Derivatives

### 1.4 Integrals

### 1.5 Theorems

#### 1.5.1 Green's lemma

$$\begin{aligned}\int_S \frac{\partial F}{\partial y} dx dy &= - \oint_{\partial S} F dx \\ \int_S \frac{\partial G}{\partial x} dx dy &= \oint_{\partial S} G dy\end{aligned}$$

#### Proof for simple domains.

In a simple domain in  $x$ , so that the closed contour  $\partial S$  is delimited by the curves  $y = Y_1(x)$ ,  $y = Y_2(x) > Y_1(x)$ , for  $x \in [x_1, x_2]$ ,

$$\begin{aligned}\int_S \frac{\partial F}{\partial y} dx dy &= \int_{x=x_1}^{x_2} \int_{y=Y_1(x)}^{Y_2(x)} \frac{\partial F}{\partial y} dy dx = \\ &= \int_{x=x_1}^{x_2} [F(x, Y_2(x)) - F(x, Y_1(x))] dx = \\ &= - \int_{x=x_1}^{x_2} F(x, Y_1(x)) dx - \int_{x=x_2}^{x_1} F(x, Y_2(x)) dx = \\ &= - \oint_{\partial S} F(x, y) dx\end{aligned}$$

In a simple domain in  $y$ , so that the closed contour  $\partial S$  is delimited by the curves  $x = X_1(y)$ ,  $x = X_2(y) > X_1(y)$  for  $y \in [y_1, y_2]$ ,

$$\begin{aligned}
 \int_S \frac{\partial G}{\partial x} dx dy &= \int_{y=y_1}^{y_2} \int_{x=X_1(y)}^{X_2(y)} \frac{\partial G}{\partial x} dx dy = \\
 &= \int_{y=y_1}^{y_2} [G(X_2(y), y) - G(X_1(y), y)] dy = \\
 &= \int_{y=y_1}^{y_2} G(X_1(y), y) dy + \int_{y=y_2}^{y_1} G(X_2(y), y) dy = \\
 &= \oint_{\partial S} G(x, y) dy
 \end{aligned}$$

**Part II**

**Differential Geometry**



## INTRODUCTION TO DIFFERENTIAL GEOMETRY



## **Part III**

# **Vector and Tensor Algebra and Calculus**





**TENSOR ALGEBRA**



## TENSOR CALCULUS IN EUCLIDEAN SPACES

This section deals with tensor calculus in Euclidean space or on manifolds embedded in Euclidean spaces, focusing on  $d$ -dimensional spaces with  $d \leq 3$ .

This section may rely on results of *differential geometry*.

### 4.1 Coordinates



**Part IV**

**Functional Analysis**



## INTRODUCTION TO FUNCTIONAL ANALYSIS

- Lebesgue integral
- $L^p$ ,  $H^p$  function spaces
- Banach and Hilbert spaces





## DISTRIBUTIONS (OR GENERALIZED FUNCTIONS)

...

### 6.1 Dirac's delta

Dirac's delta  $\delta(x)$  is a distribution, or generalized function, with the following properties

1.

$$\int_D \delta(x - x_0) dx = 1 \quad \text{if } x_0 \in D$$

2.

$$\int_D f(x) \delta(x - x_0) dx = f(x_0) \quad \text{if } x_0 \in D$$

for  $\forall f(x)$  “regular” **todo** *what does regular mean?*

#### 6.1.1 Dirac's delta in terms of regular functions

Approximations ...

$$\delta(x) \sim r_\varepsilon(x) = \begin{cases} \frac{1}{\varepsilon} & x \in [-\frac{\varepsilon}{2}, \frac{\varepsilon}{2}] \\ 0 & \text{otherwise} \end{cases}$$

as

1. Unitarity

$$\int_{x=-\infty}^{\infty} r_\varepsilon(x - x_0) dx = \int_{x=x_0-\frac{\varepsilon}{2}}^{x_0+\frac{\varepsilon}{2}} \frac{1}{\varepsilon} dx = 1,$$

for  $\forall \varepsilon$ ;

2. Shift property, using mean-value theorem of continuous functions

$$\int_{x=-\infty}^{\infty} r_\varepsilon(x - x_0) f(x) dx = \int_{x=x_0-\frac{\varepsilon}{2}}^{x_0+\frac{\varepsilon}{2}} \frac{1}{\varepsilon} f(x) dx = \frac{1}{\varepsilon} \varepsilon f(\xi),$$

with  $\xi \in [x_0 - \frac{\varepsilon}{2}, x_0 + \frac{\varepsilon}{2}]$ , for the mean value theorem. As  $\varepsilon \rightarrow 0$ ,  $\xi \rightarrow x_0$ , and thus

$$\int_{x=-\infty}^{\infty} r_\varepsilon(x - x_0) f(x) dx \rightarrow f(x_0)$$

$$\delta(x) \sim t_\varepsilon(x) = \begin{cases} \frac{2}{\varepsilon} \left(1 - \frac{2|x|}{\varepsilon}\right) & x \in \left[-\frac{\varepsilon}{2}, \frac{\varepsilon}{2}\right] \\ 0 & \text{otherwise} \end{cases}$$

as

1. Unitarity

$$\int_{x=-\infty}^{\infty} t_\varepsilon(x - x_0) dx = \int_{x=x_0-\frac{\varepsilon}{2}}^{x_0+\frac{\varepsilon}{2}} \frac{2}{\varepsilon} \left(1 - \frac{2|x|}{\varepsilon}\right) dx = \frac{1}{2} \frac{2}{\varepsilon} = 1,$$

for  $\forall \varepsilon$ ;

2. Shift property, using mean-value integration scheme in  $x \in [x_0 - \frac{\varepsilon}{2}, x_0], x \in [x_0, x_0 + \frac{\varepsilon}{2}]$  (**todo why?**)

$$\begin{aligned} \int_{x=-\infty}^{\infty} t_\varepsilon(x - x_0) f(x) dx &= \int_{x=x_0-\frac{\varepsilon}{2}}^{x_0+\frac{\varepsilon}{2}} \frac{2}{\varepsilon} \left(1 - \frac{2|x-x_0|}{\varepsilon}\right) f(x) dx = \\ &= \int_{x=x_0-\frac{\varepsilon}{2}}^{x_0} \frac{2}{\varepsilon} \left(1 - \frac{2|x-x_0|}{\varepsilon}\right) f(x) dx + \int_{x=x_0}^{x_0+\frac{\varepsilon}{2}} \frac{2}{\varepsilon} \left(1 - \frac{2|x-x_0|}{\varepsilon}\right) f(x) dx = \\ &= \frac{\varepsilon}{2} \frac{2}{\varepsilon} \left(1 - \frac{2\varepsilon}{\varepsilon 4}\right) f\left(x_0 - \frac{\varepsilon}{4}\right) dx + \frac{\varepsilon}{2} \frac{2}{\varepsilon} \left(1 - \frac{2\varepsilon}{\varepsilon 4}\right) f\left(x_0 + \frac{\varepsilon}{4}\right) dx = \\ &= \frac{1}{2} f\left(x_0 - \frac{\varepsilon}{4}\right) + \frac{1}{2} f\left(x_0 + \frac{\varepsilon}{4}\right) \end{aligned}$$

As  $\varepsilon \rightarrow 0$

$$\int_{x=-\infty}^{\infty} t_\varepsilon(x - x_0) f(x) dx \rightarrow f(x_0)$$

**Approximation 1.** For  $\alpha \rightarrow +\infty$ ,

$$\varphi_\alpha(x) = \sqrt{\frac{\alpha}{\pi}} e^{-\alpha x^2} \sim \delta(x)$$

Fourier transform of  $\varphi_\alpha(x)$  reads

$$\begin{aligned} \mathcal{F}\{\varphi_\alpha(x)\}(k) &= \int_{x=-\infty}^{+\infty} \varphi_\alpha(x) e^{-ikx} dx = \\ &= \int_{x=-\infty}^{+\infty} \sqrt{\frac{\alpha}{\pi}} e^{-\alpha x^2} e^{-ikx} dx = \\ &= \sqrt{\frac{\alpha}{\pi}} \int_{x=-\infty}^{+\infty} e^{-\alpha(x+i\frac{k}{2\alpha})^2} dx e^{-\frac{k^2}{4\alpha}} = \\ &= \sqrt{\frac{\alpha}{\pi}} \sqrt{\frac{\pi}{\alpha}} e^{-\frac{k^2}{4\alpha}} = e^{-\frac{k^2}{4\alpha}}, \end{aligned}$$

for  $\alpha \rightarrow +\infty$ ,

$$\mathcal{F}\{\varphi_\alpha(x)\}(k) \rightarrow 1$$

and thus  $\varphi_\alpha(x) \rightarrow \delta(x)$  for  $\alpha \rightarrow +\infty$ .

**Approximation 2.** For  $a \rightarrow +\infty$

$$\frac{1}{2\pi} \int_{k=-2\pi a}^{2\pi a} e^{ikx} dk = \int_{y=-a}^{+a} e^{i2\pi yx} dy \sim \delta(x)$$

or

$$\begin{aligned}\delta(x) &\sim \frac{1}{2\pi} \int_{k=-2\pi a}^{2\pi a} e^{ikx} dk = \frac{1}{2\pi} \left( \int_{k=-2\pi a}^0 e^{ikx} dk + \int_0^{k=2\pi a} e^{ikx} dk \right) = \frac{1}{2\pi} \int_{k=0}^{2\pi a} (e^{ikx} + e^{ikx}) dx = \frac{1}{\pi} \int_{x=0}^{2\pi a} \cos(kx) dk \\ &= \int_{y=-a}^{+a} e^{i2\pi yx} dy = \dots = \int_{y=0}^a (e^{i2\pi yx} + e^{i2\pi yx}) dy = 2 \int_{y=0}^a \cos(2\pi yx) dy .\end{aligned}$$

**Approximation 3.** For  $a \rightarrow +\infty$

$$\frac{\sin(2\pi xa)}{\pi x} \sim \delta(x)$$

Directly follows from integral of approximation 2,

$$\int_{y=-a}^{+a} e^{i2\pi yx} dy = \frac{1}{i2\pi x} e^{i2\pi yx} \Big|_{y=-a}^{+a} = \frac{1}{\pi x} \frac{e^{i2\pi ax} - e^{-i2\pi ax}}{2i} = \frac{\sin(2\pi xa)}{\pi x}$$

**Approximation 4.** For  $x \in [-\pi, \pi]$ , and  $N \rightarrow +\infty$

$$\frac{1}{2\pi} \sum_{n=-N}^N e^{inx} = \frac{1}{2\pi} \frac{\sin((N + \frac{1}{2})x)}{\sin(\frac{x}{2})} \sim \delta(x)$$

**Integral**  $I = \int_{-\infty}^{+\infty} e^{-\alpha x^2} dx$

$$\begin{aligned}I^2 &= \int_{x=-\infty}^{+\infty} e^{-\alpha x^2} dx \int_{y=-\infty}^{+\infty} e^{-\alpha y^2} dy = \\ &= \int_{x=-\infty}^{+\infty} \int_{y=-\infty}^{+\infty} e^{-\alpha(x^2+y^2)} dx dy = \\ &= \int_{\theta=0}^{2\pi} \int_{r=0}^{+\infty} e^{-\alpha r^2} r dr d\theta = \\ &= 2\pi \frac{1}{2\alpha} \int_{r=0}^{+\infty} e^{-\alpha r^2} d(\alpha r^2) = \\ &= \frac{\pi}{\alpha} \left[ -e^{-\alpha r^2} \right] \Big|_{r=0}^{+\infty} = \frac{\pi}{\alpha} .\end{aligned}$$



**Part V**

**Complex Calculus**



## COMPLEX ANALYSIS

### 7.1 Complex functions, $f : \mathbb{C} \rightarrow \mathbb{C}$

A complex function  $f$  of complex variable  $z = x + iy$ ,  $f : \mathbb{C} \rightarrow \mathbb{C}$ , can be written as

$$f(z) = \tilde{u}(z) + i\tilde{v}(z) = u(x, y) + iv(x, y) ,$$

as the sum of its real part  $u(z)$  and  $i$  times its imaginary part  $v(x, y)$ . Here  $x, y \in \mathbb{R}$ , while  $\tilde{u}(z), \tilde{v}(z) : \mathbb{C} \rightarrow \mathbb{R}$  and  $u(x, y), v(x, y) : \mathbb{R}^2 \rightarrow \mathbb{R}$ . With some abuse of notation, tilde won't be always explicitly written when arguments of real and imaginary parts of  $f$  functions won't be written.

#### 7.1.1 Limit

$$\lim_{z \rightarrow z_0} f(z) = f(z_0) \quad , \quad \forall \varepsilon > 0 \exists \delta > 0 \text{ s.t. } |f(z) - f(z_0)| < \delta \forall z \text{ s.t. } |z - z_0| < \varepsilon, z \neq z_0 .$$

#### 7.1.2 Derivative

Using the definition of *limit of complex functions*, the derivative of a function  $f : \mathbb{C} \rightarrow \mathbb{C}$ , if it exists, is the limit of incremental ratio,

$$f'(z) = \lim_{\Delta z \rightarrow 0} \frac{f(z + \Delta z) - f(z)}{\Delta z} .$$

#### 7.1.3 Line Integrals

Given a line  $\gamma \in \mathbb{C}$ , whose parametric form is  $z(s)$ , with regular parametrization with parameter  $s \in [s_0, s_1]$ ,

$$\int_{\gamma} f(z) dz = \int_{s=s_0}^{s_1} f(z(s)) z'(s) ds .$$

## 7.2 Holomorphic Functions - Analytic Functions

### Definition 1

A holomorphic function is a function whose *derivative* exists.

Examples of analytic functions. todo...

### 7.2.1 Cauchy-Riemann conditions

For a holomorphic function  $f(z) = u(x, y) + iv(x, y)$ , Cauchy-Riemann conditions

$$\begin{cases} u_{/x} = v_{/y} \\ u_{/y} = -v_{/x} \end{cases}$$

hold. The evaluation of the derivative once with  $\Delta z = \Delta x$  and once with  $\Delta z = i\Delta y$

$$\begin{aligned} f'(z) &= \lim_{\Delta z \rightarrow 0} \frac{f(z + \Delta z) - f(z)}{\Delta z} = \\ &= \begin{cases} \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x, y) - f(x, y)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{u(x + \Delta x, y) + iv(x + \Delta x, y) - u(x, y) - iv(x, y)}{\Delta x} = u_{/x} + iv_{/x} \\ \lim_{\Delta y \rightarrow 0} \frac{f(x, y + \Delta y) - f(x, y)}{i\Delta y} = \lim_{\Delta y \rightarrow 0} \frac{u(x, y + \Delta y) + iv(x, y + \Delta y) - u(x, y) - iv(x, y)}{i\Delta y} = -iu_{/y} + v_{/y} \end{cases} \end{aligned}$$

provides the proof.

### 7.2.2 Cauchy Theorem

For a holomorphic function  $f, f : \Omega \subseteq \mathbb{C} \rightarrow \mathbb{C}$

$$\oint_{\gamma} f(z) dz = 0 ,$$

for  $\forall \gamma \subset \Omega$ . Proof follows from *Green's lemma*, and *Cauchy-Riemann conditions*

$$\begin{aligned} \oint_{\gamma} f(z) dz &= \oint_{\gamma} (u(x, y) + iv(x, y)) (dx + idy) = \\ &= \oint_{\gamma} (u dx - v dy) + i \oint_{\gamma} (u dy + v dx) = \\ &= - \int_S \left( \underbrace{u_{/y} + v_{/x}}_{=0} \right) dx dy + i \int_S \left( \underbrace{u_{/x} - v_{/y}}_{=0} \right) dx dy = 0 . \end{aligned}$$



## 7.3 Useful integrals

### 7.3.1 Independence of line integral for holomorphic functions

For a function  $f(z)$  analytic in  $D$ , the line integral on paths  $\ell_{ab,i}$  with the same extreme points  $a, b$  contained in  $D$  is independent on the path, but only depends on the extreme points  $a, b$ ,

$$\int_{\ell_{ab,1}} f(z) dz = \int_{\ell_{ab,2}} f(z) dz$$

The proof readily follows, using [Cauchy theorem](#) applied to a function  $f(z) : D \subseteq \mathbb{C} \rightarrow \mathbb{C}$ , analytic in  $D$ , and splitting the closed path  $\gamma$  into two paths  $\ell_1, \ell_2$  with the same extreme points,  $\gamma = \ell_1 \cup (-\ell_2)$

$$0 = \oint_{\gamma} f(z) dz = \int_{\ell_1} f(z) dz + \int_{-\ell_2} f(z) dz = \int_{\ell_1} f(z) dz - \int_{\ell_2} f(z) dz.$$

### 7.3.2 Sum and difference of line integrals

### 7.3.3 Integral of $z^n$

Given a path  $\gamma$  embracing  $z = 0$  only once in counter-clockwise direction, and  $n \in \mathbb{Z}$

$$\oint_{\gamma} z^n dz = \begin{cases} 2\pi i & \text{if } n = -1 \\ 0 & \text{otherwise} \end{cases}$$

Since  $z^n$  is analytic everywhere (**todo prove it!** *Add a section with proofs for common functions*) except for  $z = 0$ , it's possible to evaluate the integral on a circle with center  $z = 0$  and radius  $R$ . Using polar expression of the complex numbers on the circle,  $z = Re^{i\theta}$ ,  $\theta \in [0, 2\pi]$ ,  $R$  const, the differential becomes  $dz = iRe^{i\theta}d\theta$  and the integral

$$\begin{aligned} \oint_{\gamma} z^n dz &= \int_{\theta=0}^{2\pi} (Re^{i\theta})^n iRe^{i\theta}d\theta = \\ &= i \int_{\theta=0}^{2\pi} R^{n+1} e^{i(n+1)\theta} d\theta = \\ &= \begin{cases} \text{if } n = -1 & : i2\pi \\ \text{otherwise} & : iR^{n+1} \frac{1}{i(n+1)} e^{i(n+1)\theta} \Big|_{\theta=0}^{2\pi} = \frac{R^{n+1}}{n+1} (1-1) = 0 \end{cases} \end{aligned}$$

## 7.4 Meromorphic functions

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### Definition 2

A meromorphic function in a domain is a function holomorphic everywhere except for a (finite?) number of poles. **check**

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## 7.4.1 Singularities

### Definition 3 (Pole)

A pole of order  $n$  of a function  $f(z)$  is a complex number  $a$  so that

$$f(z) = \frac{\phi(z)}{(z-a)^n},$$

with  $\phi(z)$  holomorphic in  $\phi(a) \neq 0$

**Examples.** ...

### Definition 4 (Branch)

**Examples.**  $f(z) = z^{\frac{1}{2}}$

### Definition 5 (Removable singularities)

**Example.**  $f(z) = \frac{\sin z}{z}$

**Other irregularities.**

## 7.4.2 Laurent Series

Given a function  $f(z)$ , in a disk  $D_{a,\varepsilon} : 0 < |z-a| < \varepsilon$ , its Laurent series centered in  $a$  is the convergent (to  $f(z)$ , **todo** which type of convergence?) series

$$f(z) \sim \sum_{n=-\infty}^{+\infty} a_n (z-a)^n, \quad (7.1)$$

with

$$a_n = \frac{1}{2\pi i} \int_{\gamma} f(z) (z-a)^{-(n+1)} dz \quad (7.2)$$

and  $\gamma$  embracing  $z = a$  once counter-clockwise. Proof follows immediately inserting the expressions of the coefficients  $a_n$  and using the *integral of  $z^n$* . Evaluating the integral (7.2) of the coefficients of the Laurent series, using (7.1) to replace  $f(z)$  with its series

$$\begin{aligned} a_n &= \frac{1}{2\pi i} \oint_{\gamma} \sum_{m=-\infty}^{+\infty} a_m (z-a)^m (z-a)^{-(n+1)} dz = \\ &= \frac{1}{2\pi i} \oint_{\gamma} \sum_{m=-\infty}^{+\infty} a_m (z-a)^{m-n-1} dz = \\ &= \frac{1}{2\pi i} \oint_{\gamma} a_n z^{-1} dz = \\ &= a_n. \end{aligned}$$

**todo** Some freestyle with function and its convergent series...add some detail, and the meaning of convergence

### 7.4.3 Cauchy formula

For an analytic function  $f(z)$ ,

$$f(a) = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(z)}{z-a} dz$$

Proof readily follows using the *integral of  $z^n$*  on the Taylor series of  $\frac{f(z)}{z-a}$  whose  $0^{th}$  order term reads  $f(a)$ ,

$$\frac{1}{2\pi i} \oint_{\gamma} \frac{f(a) + \sum_{m=1}^{+\infty} f'(a)(z-a)^m}{z-a} dz = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(a)}{z-a} dz = f(a) \frac{2\pi i}{2\pi i} = f(a) .$$

### 7.4.4 Residues

#### Definition 6 (Residue)

The residue of function  $f$  in  $a$ ,  $\text{Res}(f, a)$  is a complex number  $R$  so that  $f(z) - \frac{R}{(z-a)}$  has analytic antiderivative in a disk  $D_{a,\varepsilon} : 0 < |z-a| < \varepsilon$ .

**todo** Explain this definition. Couldn't be possible to use  $\text{Res}(f, a) = \frac{1}{2\pi i} \oint_{\gamma} f(z) dz = a_{-1}$  instead?

#### Properties.

- If  $f(z)$  is analytic in  $D_{a,\varepsilon}$  and has a pole of order  $n$  in  $z = a$ , its Laurent series has  $a_m = 0$  for  $m < n$  and reads

$$f(z) = \sum_{m=-n}^{+\infty} a_m (z-a)^m , \quad (7.3)$$

with  $a_{-n} \neq 0$ . Since  $f(z)$  has a pole of order  $n$  in  $z = a$ , it can be written as

$$f(z) = \frac{\phi(z)}{(z-a)^n} ,$$

with  $\phi(z)$  analytic in  $D_{a,\varepsilon}$  and  $\phi(a) \neq 0$ . Since  $\phi(z)$  is analytic, it has a Taylor series (or a Laurent series with non-negative powers),

$$\phi(z) \sim \sum_{m=0}^{+\infty} b_m (z-a)^m ,$$

**(todo prove it! Extension of the real case. Add a link to the proof)** and thus

$$f(z) \sim \sum_{m=0}^{+\infty} b_m (z-a)^{m-n} = \sum_{m=-n}^{+\infty} b_{m+n} (z-a)^m = \sum_{m=-n}^{+\infty} a_m (z-a)^m ,$$

with  $a_m = b_{m+n}$ .

- For simple closed path  $\gamma$  (embracing  $a$  only once counter-clockwise) in  $D_{a,\varepsilon}$ ,

$$\oint_{\gamma} f(z) dz = 2\pi i a_{-1} = 2\pi i \text{Res}(f, a) \quad (7.4)$$

The proof readily follows, using the *integral of  $z^n$*  and Laurent series (7.1) of  $f(z)$ ,

$$\oint_{\gamma} f(z) dz = \oint_{\gamma} \sum_{m=-\infty}^{+\infty} a_m (z-a)^m dz = 2\pi i a_{-1} .$$

- For a pole  $a$  of order  $n$ , the following holds

$$a_{-1} = \frac{1}{(n+1)!} \lim_{z \rightarrow a} \frac{d^{n-1}}{dz^{n-1}} [(z-a)^n f(z)]$$

The proof follows using Laurent series `{eq}\`eq:laurent:pole-n` for a function with pole of order  $n$ , and evaluating the  $(n-1)^{th}$  order derivative

$$\begin{aligned} \frac{d^{n-1}}{dz^{n-1}} [(z-a)^n f(z)] &= \frac{d^{n-1}}{dz^{n-1}} \left[ (z-a)^n \sum_{m=-n}^{+\infty} a_m (z-a)^m \right] = \\ &= \frac{d^{n-1}}{dz^{n-1}} \left[ \sum_{m=-n}^{+\infty} a_m (z-a)^{m+n} \right] = \\ &= \frac{d^{n-1}}{dz^{n-1}} \left[ \sum_{m=0}^{+\infty} a_{m-n} (z-a)^m \right] = \\ &= \frac{d^{n-2}}{dz^{n-2}} \left[ \sum_{m=0}^{+\infty} m a_{m-n} (z-a)^{m-1} \right] = \\ &= \frac{d^{n-3}}{dz^{n-3}} \left[ \sum_{m=0}^{+\infty} m(m-1) a_{m-n} (z-a)^{m-2} \right] = \\ &= \dots = \\ &= \left[ \sum_{m=0}^{+\infty} m! a_{m-n} (z-a)^{m-n+1} \right] \end{aligned}$$

and then letting  $z \rightarrow a$ , so that only the term with  $m-n+1=0$  survives

$$\lim_{z \rightarrow a} \frac{d^{n-1}}{dz^{n-1}} \left[ (z-a)^n \sum_{m=-n}^{+\infty} a_m (z-a)^m \right] = (n-1)! a_{-1} .$$

## 7.4.5 Residue Theorem

### Theorem 1 (Residue Theorem)

Given  $f(z)$  with a finite number of poles  $p_n \in D$ , then

$$\int_{\gamma} f(z) dz = 2\pi i \sum_n I(\gamma, p_n) \text{Res}(f, p_n) ,$$

being  $\gamma$  a path in  $D$ , and  $I(\gamma, p_n)$  the winding index of the path  $\gamma$  around pole  $p_n$  (+1 for each counter-clockwise loop, -1 for each clockwise loop).

The proof readily follows extending the result for a single pole (7.4) to general number of poles and general paths  $\gamma$  embracing (with sign) each pole  $p_n$   $I(\gamma, p_n)$  times, with the same techniques shown in section [Sum and difference of line integrals](#).

## 7.4.6 Evaluation of integrals

## 7.4.7 Inverse Laplace Transform

Given Laplace transform

$$F(s) := \mathcal{L}\{f(t)\}(s) := \int_{t=0^-}^{+\infty} f(t)e^{-st} dt ,$$

the inverse transform can be evaluated as

$$f(t) = \mathcal{L}^{-1}\{F(s)\}(t) := \lim_{T \rightarrow +\infty} \frac{1}{2\pi i} \int_{s=a-iT}^{a+iT} e^{st} F(s) ds ,$$

with  $a > \operatorname{Re}\{p_n\}$  for each pole of the function  $F(s)$ , evaluated on the vertical line  $s = a + iy$ ,  $y \in [-T, T]$ ,  $ds = idy$ ,

$$\begin{aligned} \lim_{T \rightarrow +\infty} \frac{1}{2\pi i} \int_{s=a-iT}^{a+iT} e^{st} F(s) ds &= \lim_{T \rightarrow +\infty} \frac{1}{2\pi i} \int_{s=a-iT}^{a+iT} e^{st} \int_{\tau=0^-}^{+\infty} f(\tau) e^{-s\tau} d\tau ds = \\ &= \lim_{T \rightarrow +\infty} \frac{1}{2\pi i} \int_{y=-iT}^{iT} e^{(a+iy)t} \int_{\tau=0^-}^{+\infty} f(\tau) e^{-(a+iy)\tau} d\tau idy = \\ &= \lim_{T \rightarrow +\infty} \frac{1}{2\pi} \int_{y=-iT}^{iT} \int_{\tau=0^-}^{+\infty} e^{iy(t-\tau)} e^{a(t-\tau)} f(\tau) d\tau dy = \\ &= \dots \\ &= \int_{\tau=0^-}^{+\infty} \delta(t-\tau) e^{a(t-\tau)} f(\tau) d\tau = f(t) . \end{aligned}$$

having used the transform of *Dirac's delta*  $\delta(t) = \frac{1}{2\pi} \int_{\omega=-\infty}^{+\infty} e^{-j\omega t} d\omega$ .

**todo** If  $a > \operatorname{Re}\{p_n\}$ , the contour build with the vertical line with real part  $a$  and the arc of circumference on its



## LAPLACE TRANSFORM

$$\mathcal{L}\{f(t)\}(s) := \int_{t=0^-}^{+\infty} f(t) e^{st} dt = F(s) .$$

### 8.1 Inverse transform

$$f(t) = \mathcal{L}^{-1}\{F(s)\} = \dots$$

### 8.2 Properties

**Linearity.**

*Dirac delta.*

$$\mathcal{L}\{\delta(t)\} = \int_{t=0^-}^{+\infty} \delta(t) e^{st} dt = 1$$

**Time delay.**

**Derivative.**

**Integral.**

**Initial value.**

**Final value.**





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## FOURIER TRANSFORMS

- Fourier series: continuous time, periodic function in time
- Fourier transform: continuous time, non-periodic function in time
- Discrete Fourier transform (DFT):
- Discrete time Fourier transform (DTFT):

### 9.1 Fourier Series

For a  $T$ -periodic function,

$$g(t)$$

### 9.2 Fourier Transform

$$\mathcal{F}\{g(t)\}(f) := \int_{t=-\infty}^{+\infty} g(t) e^{-i2\pi ft} dt.$$

#### 9.2.1 Properties

**Linearity.**

*Dirac delta.*

$$\mathcal{L}\{\delta(t)\} = \int_{t=-\infty}^{+\infty} \delta(t) e^{-i2\pi ft} dt = 1$$

**Time delay.**

**Derivative.**

**Integral.**

**Initial value.**

**Final value.**

### 9.2.2 Inverse Fourier Transform

$$\mathcal{F}^{-1} \{G(f)\} (t) := \int_{f=-\infty}^{+\infty} G(f) e^{i2\pi f t} df.$$

**Proof using Dirac's delta expression.**

$$\begin{aligned} \mathcal{F}^{-1} \{G(f)\} (t) &:= \int_{f=-\infty}^{+\infty} G(f) e^{i2\pi f t} df = \int_{f=-\infty}^{+\infty} \int_{\tau=-\infty}^{+\infty} g(\tau) e^{-i2\pi f \tau} e^{i2\pi f t} d\tau df = \\ &= \int_{f=-\infty}^{+\infty} \int_{\tau=-\infty}^{+\infty} g(\tau) e^{-i2\pi f \tau} e^{i2\pi f t} df d\tau = \\ &= \int_{f=-\infty}^{+\infty} \int_{\tau=-\infty}^{+\infty} g(\tau) e^{i2\pi f (t-\tau)} df d\tau = \\ &= \int_{\tau=-\infty}^{+\infty} g(\tau) \delta(t-\tau) d\tau = g(t). \end{aligned}$$

**Proof.**

**Part VI**

**Calculus of Variations**



## INTRODUCTION TO CALCULUS OF VARIATIONS



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