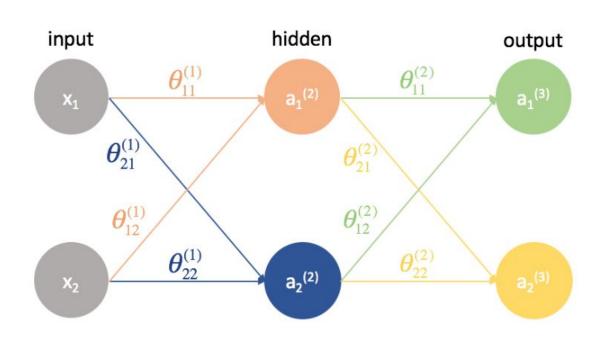
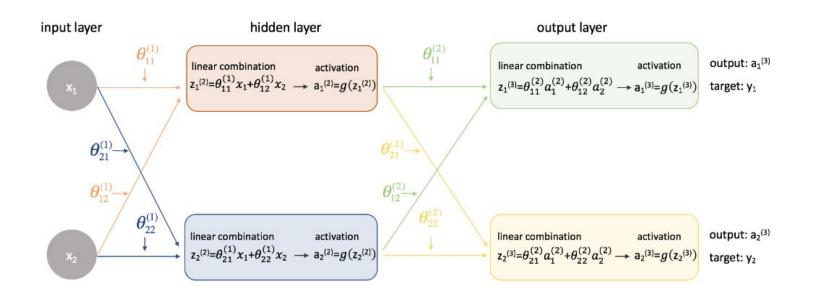
# THIS IS CS5045!

GCR:ioc7cdl

# P.S. THESE SLIDES ARE USELESS IF YOU DO NOT ATTEND CLASSES

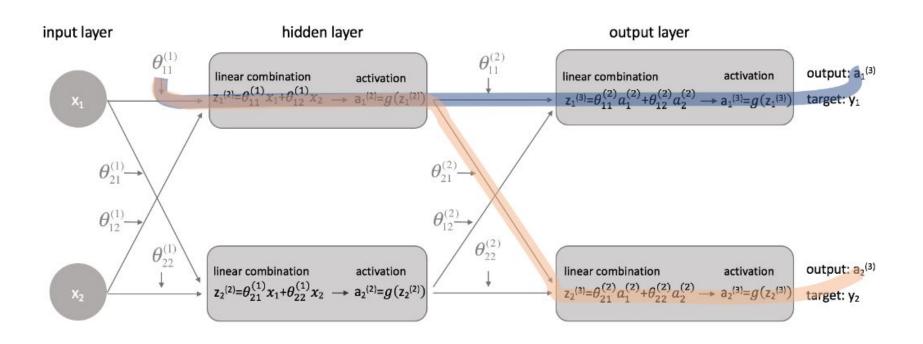
# NEURAL NETWORKS





Loss calculation

$$J\left( heta
ight) = rac{1}{2m}\sum\left(y_i - \mathrm{a}_i^{(2)}
ight)^2$$



The derivative chain for the blue path is:

$$\left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{1}^{(3)}}\right)\left(\frac{\partial \mathbf{a}_{1}^{(3)}}{\partial z_{1}^{(3)}}\right)\left(\frac{\partial z_{1}^{(3)}}{\partial \mathbf{a}_{1}^{(2)}}\right)\left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial z_{1}^{(2)}}\right)\left(\frac{\partial z_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right)$$

The derivative chain for the orange path is:

$$\left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right)\left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial z_{2}^{(3)}}\right)\left(\frac{\partial z_{2}^{(3)}}{\partial \mathbf{a}_{1}^{(2)}}\right)\left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial z_{1}^{(2)}}\right)\left(\frac{\partial z_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right)$$

Combining these, we get the total expression for  $\frac{\partial J(\theta)}{\partial \theta_{i}^{(1)}}$ .

$$\frac{\partial J(\theta)}{\partial \theta_{11}^{(1)}} = \left(\frac{\partial J(\theta)}{\partial \mathbf{a}_{1}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(3)}}{\partial z_{1}^{(3)}}\right) \left(\frac{\partial z_{1}^{(3)}}{\partial \mathbf{a}_{1}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial z_{1}^{(2)}}\right) \left(\frac{\partial z_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right) + \left(\frac{\partial J(\theta)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial z_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial \mathbf{a}_{1}^{(2)}}\right) \left(\frac{\partial z_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right)$$

#### **Layer 2 Parameters**

$$\begin{split} \frac{\partial J\left(\theta\right)}{\partial \theta_{11}^{(2)}} &= \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{1}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(3)}}{\partial z_{1}^{(3)}}\right) \left(\frac{\partial z_{1}^{(3)}}{\partial \theta_{11}^{(2)}}\right) \\ \frac{\partial J\left(\theta\right)}{\partial \theta_{12}^{(2)}} &= \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{1}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(3)}}{\partial z_{1}^{(3)}}\right) \left(\frac{\partial z_{1}^{(3)}}{\partial \theta_{12}^{(2)}}\right) \end{split}$$

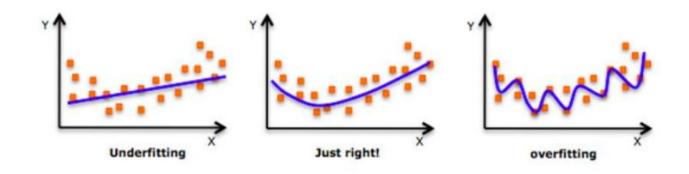
$$rac{\partial J\left( heta
ight)}{\partial heta_{21}^{(2)}} = \left(rac{\partial J\left( heta
ight)}{\partial ext{a}_{2}^{(3)}}
ight) \left(rac{\partial ext{a}_{2}^{(3)}}{\partial z_{2}^{(3)}}
ight) \left(rac{\partial z_{2}^{(3)}}{\partial heta_{21}^{(2)}}
ight)$$

$$\frac{\partial \theta_{21}^{(2)}}{\partial \theta_{22}^{(2)}} = \left(\frac{\partial J(\theta)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial z_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial z_{2}^{(3)}}\right) \left(\frac{\partial z_{2}^{(3)}}{\partial \theta_{22}^{(2)}}\right)$$

#### Layer 1 Parameters

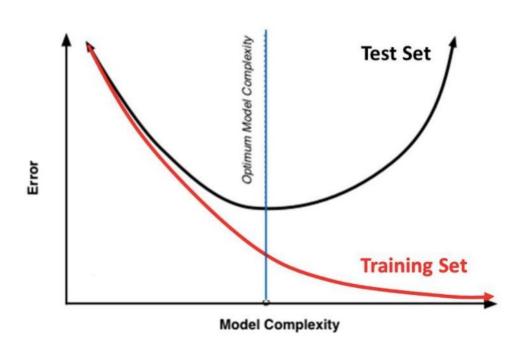
$$\frac{\partial J\left(\theta\right)}{\partial \theta_{11}^{(1)}} = \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{1}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(3)}}{\partial z_{1}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial \mathbf{a}_{1}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial z_{2}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial z_{1}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{1}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{1}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{1}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{1}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{1}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{1}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{1}^{(2)}}{\partial \theta_{11}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{2}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(2)}}{\partial \theta_{21}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{2}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(2)}}{\partial \theta_{21}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{2}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(2)}}{\partial \theta_{21}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{2}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(2)}}{\partial \theta_{21}^{(1)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(2)}}{\partial \mathbf{a}_{2}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(2)}}{\partial \theta_{21}^{(2)}}\right) + \left(\frac{\partial J\left(\theta\right)}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(3)}}{\partial \mathbf{a}_{2}^{(3)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(2)}}{\partial \mathbf{a}_{2}^{(2)}}\right) \left(\frac{\partial \mathbf{a}_{2}^{(2)}}{\partial \mathbf{a}_{2}^{$$

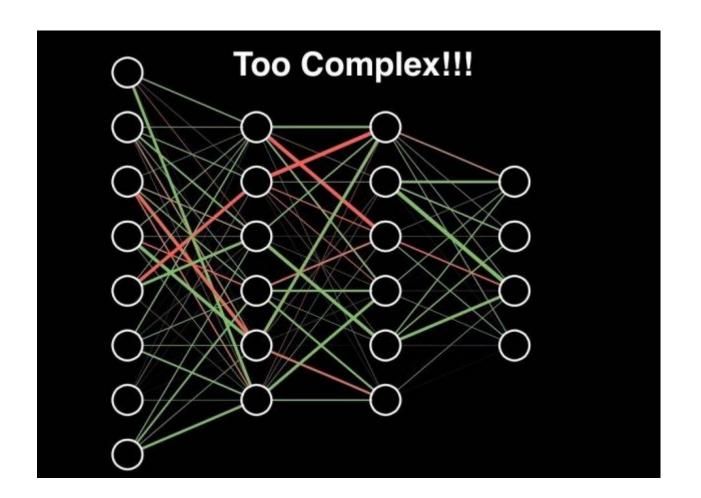
### DISCUSSION ON ASSIGNMENT NETWORK



As move towards right, poor performance on unseen data

**Training Vs. Test Set Error** 

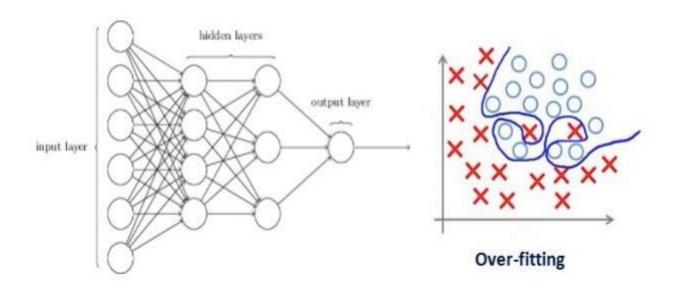




#### WHAT IS REGULARIZATION?

Regularization is a technique which makes slight modifications to the learning algorithm such that the model generalizes better

This in turn improves the model's performance on the unseen data as well

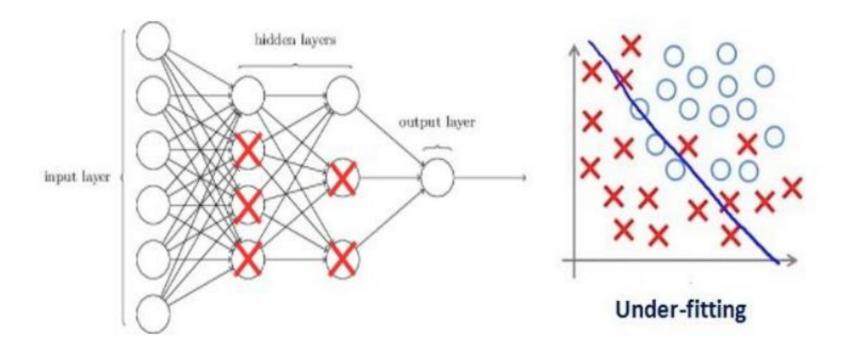


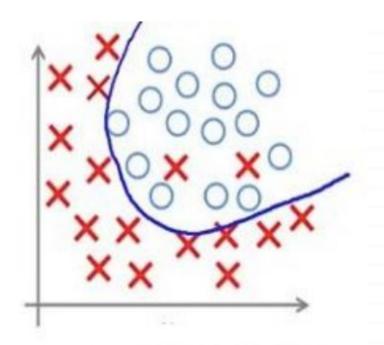
In machine learning, regularization penalizes the coefficients

In deep learning, it actually penalizes the weight matrices of the nodes

Assume that our regularization coefficient is so high that some of the weight matrices are nearly equal to zero

This will result in a much simpler linear network and slight underfitting of the training data.





Such a large value of the regularization coefficient is not that useful

We need to optimize the value of regularization coefficient in order to obtain a well-fitted model as shown in the image below

Appropriate-fitting

- L1 and L2 regularization
- DropOut
- Data Augmentation
- Early Stopping

#### READING ASSIGNMENT

Read Neural Network L2 Regularization Using Python -- Visual Studio Magazine.pdf

Read Neural Network L1 Regularization Using Python -- Visual Studio Magazine.pdf

#### L1 L2 REGULARIZATION

#### L1 Regularization

Modified loss = Loss function + 
$$\lambda \sum_{i=1}^{n} |W_i|$$

#### L2 Regularization

Modified loss function = Loss function + 
$$\lambda \sum_{i=1}^{n} W_i^2$$

$$E = \frac{1}{2} * \sum (t_k - o_k)^2 + \lambda * \sum |w_i|$$
squared error L1 weight penalty

$$\frac{\partial E}{\partial w_{jk}} \quad \text{gradient}$$
 
$$\Delta w_{jk} = -1 * \eta * \left[ x_j * (o_k - t_k) * o_k * (1 - o_k) \right] \pm \lambda \right]$$
 learning rate signal

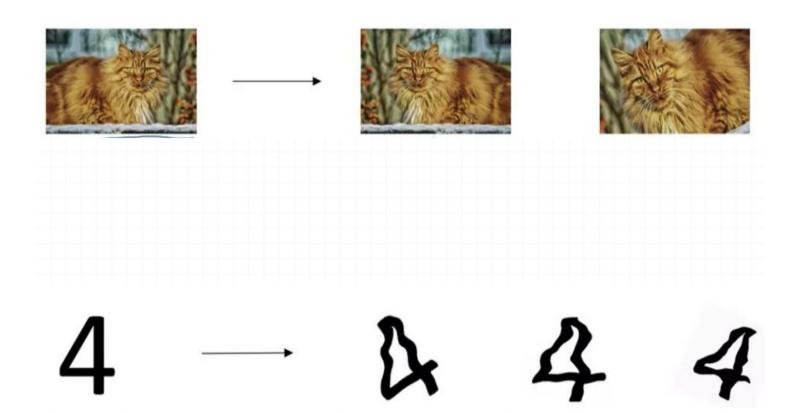
$$w_{jk} = w_{jk} + \Delta w_{jk}$$

$$E = \frac{1}{2} * \sum (t_k - o_k)^2 + \frac{\lambda}{2} * \sum w_i^2$$
plain error weight penalty

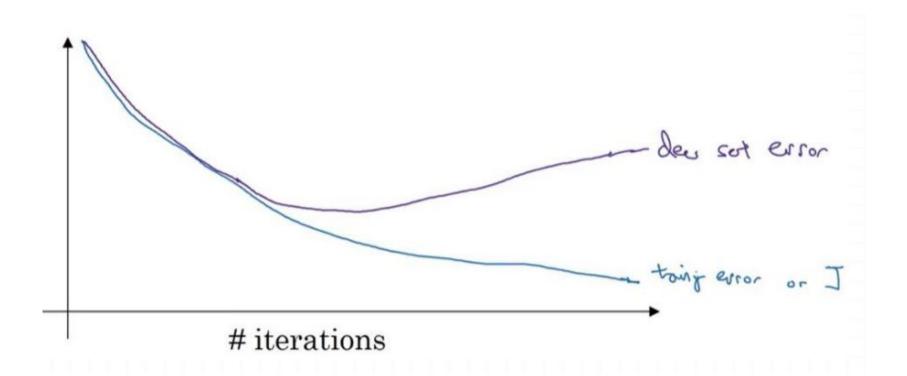
elegant math
$$\frac{\partial E}{\partial w_{jk}} \text{ gradient}$$

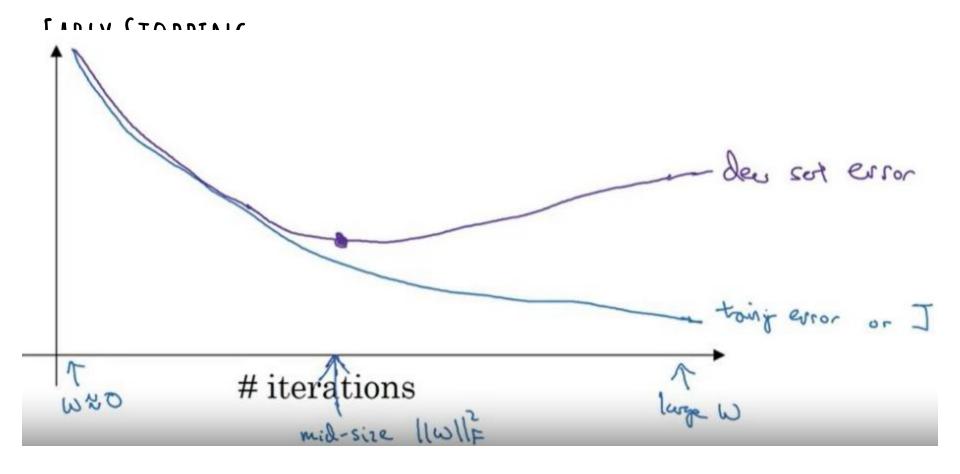
$$\Delta w_{jk} = \eta * \left[ x_j * (o_k - t_k) * o_k * (1 - o_k) \right] + \left[ \lambda * w_{jk} \right]$$
learning signal rate

## DATA AUGMENTATION



## EARLY STOPPING





#### DROP OUT

The network with dropout during a single forward pass

Dropout

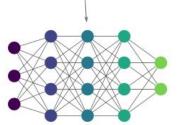
Network regularization

For each forward pass during training, set the output of each node to zero with probability **P**.

Nodes set to zero during forward passes

**Dropout** is the equivalent of training several independent, smaller networks on the same task. The final model is like an ensemble of smaller networks, reducing variance and providing more robust predictions.

For testing and inference use the entire network





#### REFERENCES

https://www.jeremyjordan.me/neural-networks-training/

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i/dropout in neural networks what it is and how it/?rdt=5583
7

https://www.analyticsvidhya.com/blog/2018/04/fundamentals-de
ep-learning-regularization-techniques/