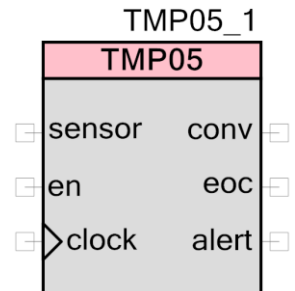


TMP05 Temp Sensor Interface

1.10

Features

- Supports up to four TMP05 or TMP06 digital temperature sensors connected in daisy chain mode only
- Continuous and one-shot modes of operation
- Supports frequencies from 100 to 500 kHz
- Supports temperature range from 0 to 70 Celsius degree



General Description

The TMP05 Temp Sensor Interface component is a simple, easy to use component capable of interfacing with Analog Device's TMP05/06 digital temperature sensors in **daisy chain mode only**. You can configure the component and monitor the temperature readings in one of two ways:

- The continuous monitoring option allows you to record temperatures in a continuous fashion, at a sample rate dictated by the temperature sensor(s)
- One-shot mode triggers the temperature measurement at a rate you can control control.

The first mode is intended for use in an environment where temperature variations are abrupt and need to be monitored frequently. The second option should be used when temperature measurements only need to be sampled once in a while or in applications where minimizing power consumption is important.

Note Since the component supports digital temperature sensors in daisy chain mode only, the device must be configured in daisy chain mode even when only a single device is connected.

When to Use a TMP05 Interface

The TMP05 Temp Sensor Interface component should be used in thermal management applications that require monitoring the temperatures of several remote subsystems. This component is designed to directly interface to TMP05/06 temperature sensors that produce a PWM output whose duty cycle is directly related to ambient temperature.

Modes of Component Operation

Two modes of operation are supported in the TMP05 Temp Sensor Interface component: continuous and one-shot.

- In continuous mode, temperature measurements occur at the fastest possible rate, dictated by the conversion time of the sensors.
- In one-shot mode, temperature measurements occur at a rate dictated by application firmware. In this mode, the designer can set the rate of temperature monitoring

Input/Output Connections

This section describes the various input and output connections for the TMP05Intf.

sensor – Input

For single sensor applications, this input should be connected to the TMP05 temperature sensor output. That output is a pulse-width modulated digital signal whose duty cycle is proportional to temperature.

For multi-sensor applications where the TMP05 temperature sensors are daisy chained together, this input should be connected to the output of the final TMP05 temperature sensor in the daisy chain.

When interfacing to open-drain output TMP06 sensors, this signal requires a pull-up resistor for proper operation. This can be achieved using internal pull-up resistors on the selected PSoC GPIO pin or externally on the circuit board

en – Input

Active high enable. Set this pin to a low level to disable the component.

clock – Input

Clock that operates this block. Must be between 100 kHz and 500 kHz.

conv – Output

Conversion Start output. To start monitoring the temperatures, TMP05 sensors require a trigger input with specific timing constraints on low and high times. This output provides a trigger input to the first TMP05 sensor connected in daisy-chain mode.

eoc – Output

End of conversion output. This signal pulses active high for one clock cycle when a new temperature measurement is available. When sensors are connected in daisy chain mode, this

signal indicates a measurement has been made on all sensors. The eoc signal should not assert until data is ready to be obtained by the APIs (after any internal processing).

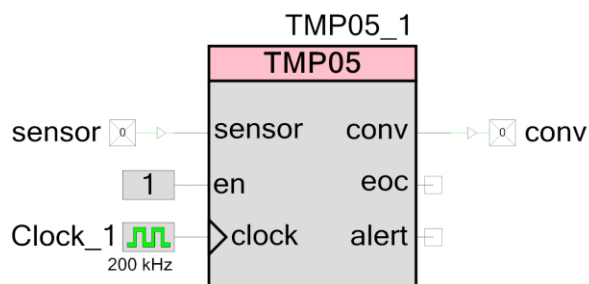
alert – Output

Temperature conversion error output. This signals pulses active high one clock cycle when the temperature sensor measurement times out. This could occur due to a fault in one or more of the attached temperature sensors or in the case of connection failure to the sensor(s).

Schematic Macro Information

This section contains pertinent information for the schematic macro in the TMP05 Interface.

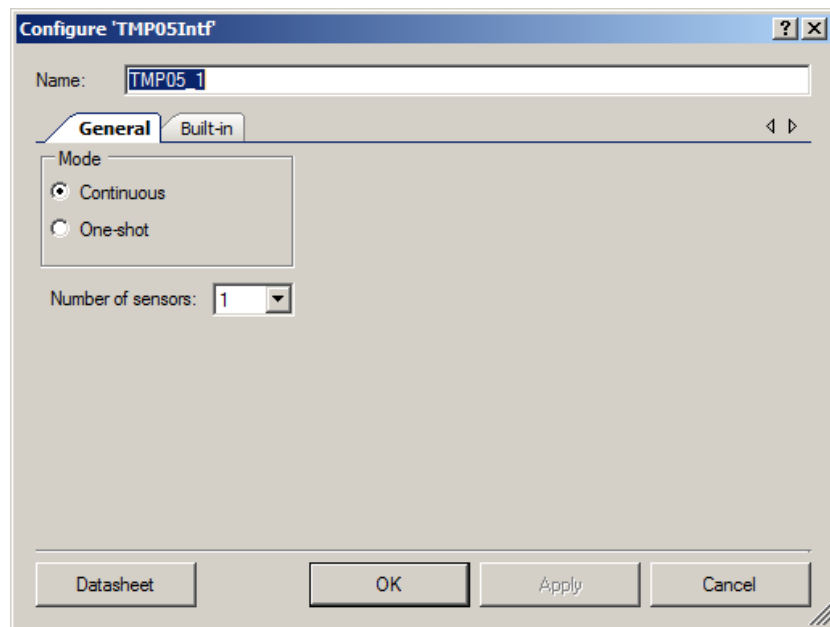
The default TMP05 Interface in the Component Catalog is a schematic macro using a TMP05 Interface component with default settings. It is connected to clock, a Logic High component and Digital Input/Output pins.



Component Parameters

Drag a TMP05 Interface component onto your design and double-click it to open the Configure dialog. This dialog has one tab to guide you through the process of setting up the TMP05 Interface component.

General Tab



The **General** tab provides the following parameters.

Continuous

This parameter is used to specify the operating mode of the component. This parameter is a Boolean value to select between continuous and one-shot modes of operation. Valid values for this parameter are true and false. Default setting is true, enabling a continuous mode of operation.

Number of Sensors

This parameter is used to specify the number of TMP05 temperature sensors that are connected in daisy-chain mode. Currently the component can support up to four TMP05 temperature sensors. Valid range for this parameter is 1-4. Default setting is 1.

Clock Selection

There is no internal clock in this component. You must attach a clock source.

Application Programming Interface

Application Programming Interface (API) routines allow you to configure the component using software. The following table lists and describes the interface to each function. The subsequent sections cover each function in more detail.

By default, PSoC Creator assigns the instance name "TMP05_1" to the first instance of a component in a given design. You can rename it to any unique value that follows the syntactic rules for identifiers. The instance name becomes the prefix of every global function name, variable, and constant symbol. For readability, the instance name used in the following table is "TMP05".

Functions

Function	Description
TMP05_Start()	Starts the component
TMP05_Stop()	Stops the component
TMP05_Init()	Initializes the component
TMP05_Enable()	Enables the component
TMP05_Trigger()	Triggers the interfaced TMP05 sensors to start temperature measurement depending upon the mode of operation
TMP05_GetTemperature()	Calculates the temperature(s) in degrees Celsius
TMP05_SetMode()	Sets the operating mode of the component
TMP05_DiscoverSensors()	Automatically detects how many temperature sensors are daisy-chained to the component
TMP05_ConversionStatus()	Returns current state of temperature conversion (busy, completed or error)
TMP05_SaveConfig()	Saves the current state of the component before entering low power mode
TMP05_RestoreConfig()	Restores the previous state of the component after waking from low power mode
TMP05_Sleep()	Puts the component into low power mode
TMP05_Wakeup()	Wakes the component up from low power mode

void TMP05_Start(void)

Description:	Starts the component. Calls the TMP05_Init() API if the component has not been initialized before. Calls the enable API.
Parameters:	None
Return Value:	None
Side Effects:	None

void TMP05_Stop (void)

Description:	Disables and stops the component
Parameters:	None
Return Value:	None
Side Effects:	None

void TMP05_Init(void)

Description:	Initializes the component
Parameters:	None
Return Value:	None
Side Effects:	None

void TMP05_Enable(void)

Description:	Enables the component
Parameters:	None
Return Value:	None
Side Effects:	None

void TMP05_Trigger (void)

Description:	Provides a valid strobe/trigger output on the conv terminal.
Parameters:	None
Return Value:	None
Side Effects:	None

int16 TMP05_GetTemperature (uint8 SensorNum)

Description:	Calculates the temperature in degrees Celsius
Parameters:	uint8 SensorNum - The TMP05 sensor number from 0..3
Return Value:	Temperature in 1/100ths degrees C of the requested sensor.
Side Effects:	None

void TMP05_SetMode (uint8 mode)

Description:	Sets the operating mode of the component
Parameters:	uint8 mode - operating mode: <ul style="list-style-type: none">▪ MODE_CONTINUOUS - Continuous mode▪ MODE_ONESHOT - One-shot mode
Return Value:	None
Side Effects:	None

uint8 TMP05_DiscoverSensors (void)

Description: This API is provided for applications that might have a variable number of temperature sensors connected. It automatically detects how many temperature sensors are daisy-chained to the component. The algorithm starts by checking to see if the number of sensors actually connected matches the NumSensors parameter setting in the Basic Tab of the component customizer. If not, it will retry assuming 1 less sensor is connected. This process will repeat until the actual number of sensors connected is known.

Confirming whether or not a sensor is attached or not takes a few hundred milliseconds per sensor per iteration of the algorithm. To limit the sensing time, reduce the NumSensors parameter setting in the Basic Tab of the component customizer to the maximum number of possible sensors in the system.

Parameters: none

Return Value: uint8 - representing the number of sensors actually connected (0..4)

Side Effects: None

uint8 TMP05_ConversionStatus (void)

Description: Enables firmware to synchronize with the hardware

Parameters: none

Return Value: uint8 status code:

- STATUS_IN_PROGRESS - Conversion in progress
- STATUS_COMPLETE - Conversion complete
- STATUS_ERROR - Sensor Error

Side Effects: None

void TMP05_SaveConfig (void)

Description: Saves the user configuration of the TMP05 non-retention registers. This routine is called by TMP05_Sleep() to save the component configuration before entering sleep.

Parameters: None

Return Value: None

Side Effects: None

void TMP05_RestoreConfig (void)

Description:	Restores the user configuration of the TMP05 non-retention registers. This routine is called by TMP05_Wakeup() to restore the component configuration when exiting sleep.
Parameters:	None
Return Value:	None
Side Effects:	None

void TMP05_Sleep (void)

Description:	Stops the TMP05 operation and saves the user configuration along with the enable state of the TMP05.
Parameters:	None
Return Value:	None
Side Effects:	None

void TMP05_Wakeup (void)

Description:	Restores the user configuration and restores the enable state.
Parameters:	None
Return Value:	None
Side Effects:	None

Global Variables

Variable	Description
TMP05_initVar	<p>The initVar variable is used to indicate initial configuration of this component. This variable is pre-pended with the component name. The variable is initialized to zero and set to 1 the first time TMP05_Start() is called. This allows for component initialization without re-initialization in all subsequent calls to the TMP05_Start() routine.</p> <p>If re-initialization of the component is required the TMP05_Stop() routine should be called followed by the TMP05_Init() and TMP05_Enable().</p>

Variable	Description
TMP05_busyFlag	The busyFlag variable is used to indicate component measuring. The variable is initialized to zero after component initialization is used or after measuring is finished and set to 1 after TMP05_Trigger API is called.

Macro Callbacks

Macro callbacks allow users to execute code from the API files that are automatically generated by PSoC Creator. Refer to the PSoC Creator Help and *Component Author Guide* for the more details.

In order to add code to the macro callback present in the component's generated source files, perform the following:

- Define a macro to signal the presence of a callback (in *cyapicallbacks.h*). This will “uncomment” the function call from the component's source code.
- Write the function declaration (in *cyapicallbacks.h*). This will make this function visible by all the project files.
- Write the function implementation (in any user file).

Callback Function ^[1]	Associated Macro	Description
TMP05_EOC_ISR_Int_EntryCallback	TMP05_EOC_ISR_INT_ENTRY_CALLBACK	Used at the beginning of the TMP05_EOC_ISR_Int() interrupt handler to perform additional application-specific actions.
TMP05_EOC_ISR_Int_ExitCallback	TMP05_EOC_ISR_INT_EXIT_CALLBACK	Used at the end of the TMP05_EOC_ISR_Int() interrupt handler to perform additional application-specific actions.

Sample Firmware Source Code

PSoC Creator provides numerous example projects that include schematics and example code in the Find Example Project dialog. For component-specific examples, open the dialog from the Component Catalog or an instance of the component in a schematic. For general examples, open the dialog from the Start Page or **File** menu. As needed, use the **Filter Options** in the dialog to narrow the list of projects available to select.

Refer to the “Find Example Project” topic in the PSoC Creator Help for more information.

¹ The callback function name is formed by component function name optionally appended by short explanation and “Callback” suffix.

MISRA Compliance

This section describes the MISRA-C:2004 compliance and deviations for the component. There are two types of deviations defined:

- project deviations – deviations that are applicable for all PSoC Creator components
- specific deviations – deviations that are applicable only for this component

This section provides information on component-specific deviations. Project deviations are described in the MISRA Compliance section of the *System Reference Guide* along with information on the MISRA compliance verification environment.

The TMP05 Temp Sensor Interface component does not have any specific deviations.

This component has the following embedded components: Interrupt, Status Register, Control Register. Refer to the corresponding component datasheet for information on their MISRA compliance and specific deviations.

API Memory Usage

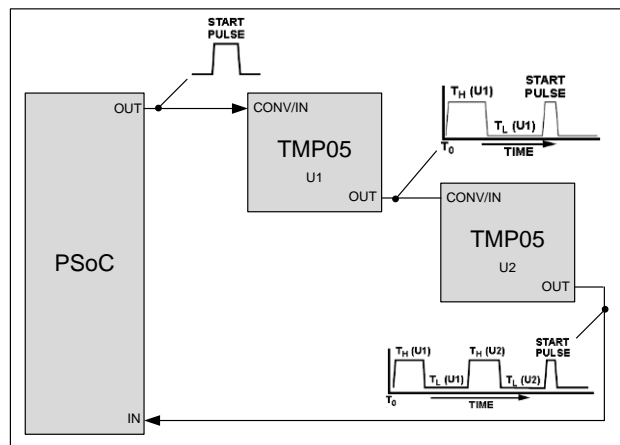
The component memory usage varies significantly, depending on the compiler, device, number of APIs used and component configuration. The following table provides the memory usage for all APIs available in the given component configuration.

The measurements have been done with the associated compiler configured in Release mode with optimization set for Size. For a specific design the map file generated by the compiler can be analyzed to determine the memory usage.

Configuration	PSoC 3 (Keil_PK51)		PSoC 4 (GCC)		PSoC 5LP (GCC)	
	Flash Bytes	SRAM Bytes	Flash Bytes	SRAM Bytes	Flash Bytes	SRAM Bytes
Continuous	807	8	654	11	640	11
One shot	805	8	650	11	636	11

Functional Description

The component uses one input and one output pin for interfacing with a single sensor or multiple TMP05 sensors in daisy chain mode (shown below).



The TMP05 sensor has three modes of operation:

- Continuously converting mode
- Daisy-chained mode
- One-shot mode

A three-state function control input pin (FUNC) sampled at power-up determines the mode in which the device will operate. Setting the FUNC pin to a high state allows multiple TMP05s to be connected in daisy chained mode. In that mode, multiple TMP05 temperature sensors can be connected, which enables TMP05 Interface component to read all the sensors through the same two-wire interface.

In this configuration, TMP05 Interface component generates a “Start” pulse to begin a new temperature-to-PWM conversion cycle. The output of the first TMP05 sensor begins with its own PWM output, followed by a new Start pulse that it generated internally. The output of the second TMP05 sensor begins with the PWM output of the previous sensor, followed by its own PWM output and terminated by a new Start pulse that it generated internally.

When more sensors are daisy-chained in this fashion, the final return signal to PSoC contains the PWM outputs from all sensors starting with the output of the first sensor, followed by the output from the second sensor and so on until the terminating Start pulse is detected. Temperature-to-PWM conversion then stops until TMP05 Interface component generates another Start pulse. The system-level connection scheme and expected waveforms are above.

Temperature calculated using the equation provided in the TMP05/06 datasheet:

$$\text{Temperature} = 421 - 751 * (T_H/T_L)$$

Resources

The TMP05 component is placed throughout the UDB array. The component utilizes the following resources.

Configuration	Resource Type					
	Datapath Cells	Macrocells	Status Cells	Control Cells	DMA Channels	Interrupts
All	2	12	1	1	–	1

DC and AC Electrical Characteristics

The following values indicate expected performance and are based on initial characterization data.

TMP05 Interface AC Specifications

Parameter	Description	Min	Typ	Max	Units
f _{CLOCK}	Component clock frequency	100	–	500	kHz

Performance

The measurements below have been gathered using a CPU speed of 24 MHz, with the associated compiler configured in Release mode. These numbers should be treated as approximations and used to determine necessary trade-offs.

GetTemperature API

No. of computation cycles (8051)	No. of computation cycles (ARM cortex M0)	No. of computation cycles (ARM cortex M3)
1230	100	60

Component Changes

This section lists the major changes in the component from the previous version.

Version	Description of Changes	Reason for Changes / Impact
1.10.c	Minor datasheet edits.	
1.10.b	Minor datasheet edits.	
1.10.a	Datasheet update.	Added Macro Callbacks section.
1.10	PSoC4 support added.	
	Updated datasheet with features, general description, resources, memory usage and performance.	
1.0	Version 1.0 is the first release of the TMP05Intf component	

© Cypress Semiconductor Corporation, 2013-2017. This document is the property of Cypress Semiconductor Corporation and its subsidiaries, including Spansion LLC ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as provided by Cypress, unmodified) to make, use, distribute, and import the Software solely for use with Cypress hardware products. Any other use, reproduction, modification, translation, or compilation of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Cypress products are not designed, intended, or authorized for use as critical components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or system could cause personal injury, death, or property damage ("Unintended Uses"). A critical component is any component of a device or system whose failure to perform can be reasonably expected to cause the failure of the device or system, or to affect its safety or effectiveness. Cypress is not liable, in whole or in part, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from or related to all Unintended Uses of Cypress products. You shall indemnify and hold Cypress harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of Cypress products.

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.

