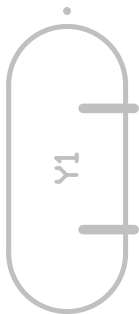


# PMOD CAN Bus Controller

J1

J2

JLCJLCJLCJLC



IC1

Mode 0  
IN  
1

Mode 1  
IN  
1

TXCAN  
Mode 0  
Mode 1  
RXCAN  
GND  
3.3V

S1

S2

J3

3.3V

END

SCK

MISO

MOSI

\CS

3.3V

END

OSC\_IN

MODE 1

MODE 0

RTS

3.3V

END

TX2

TX1

TX0

INT

3.3V

END

BF

RX1

RX0

RTS