

Algorithme

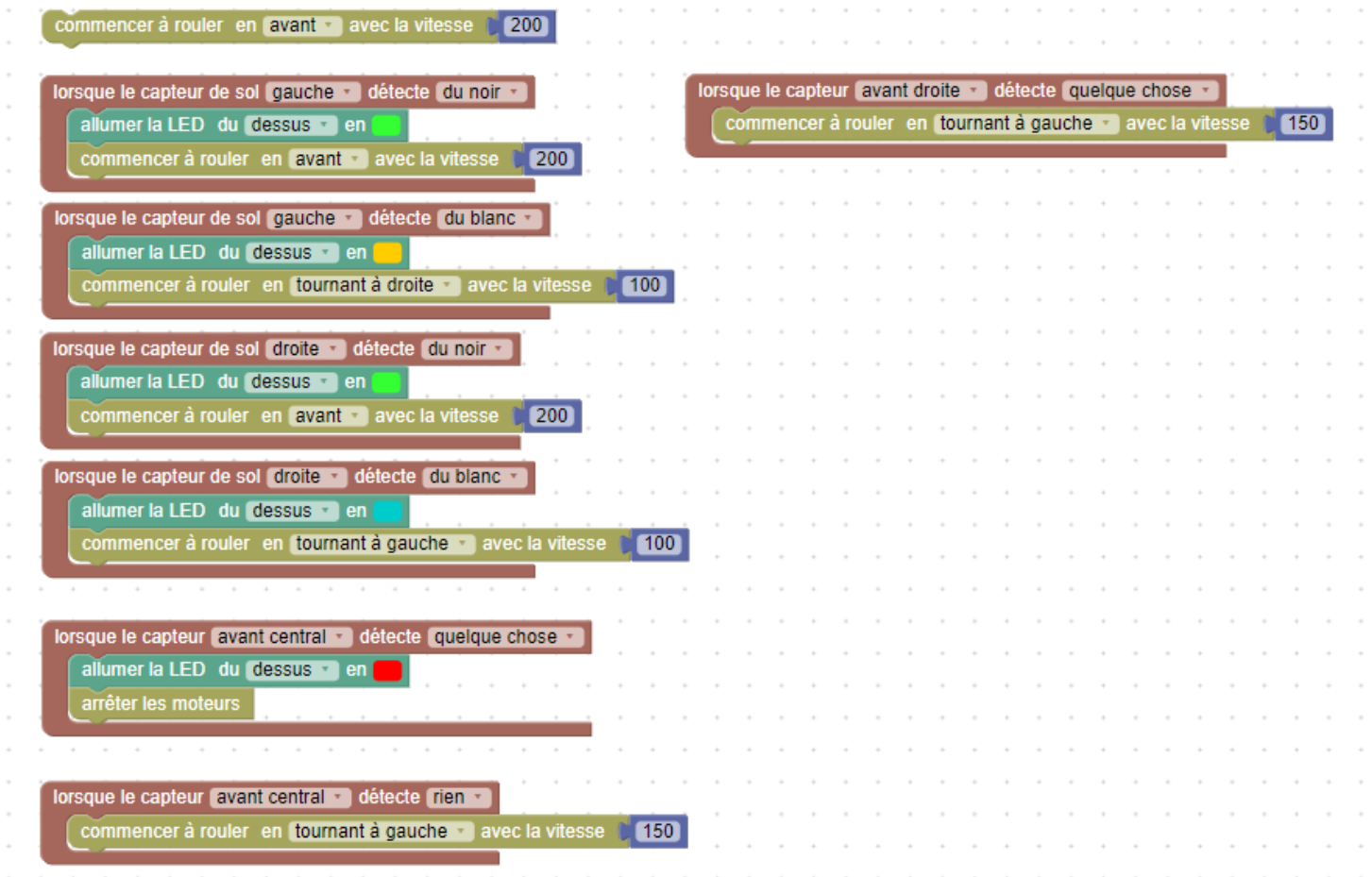
ILI6 et IMP29
Groupe B



En partenariat avec

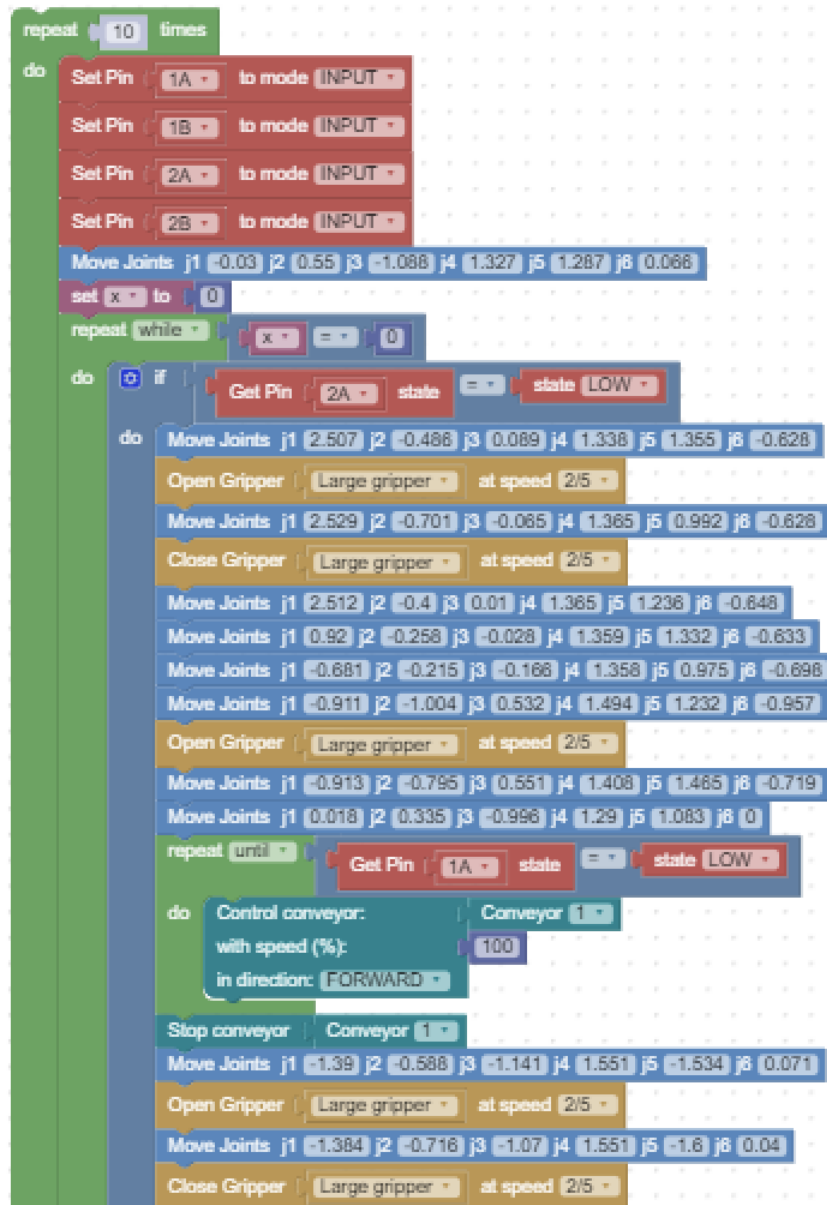


Algorithme Station 0



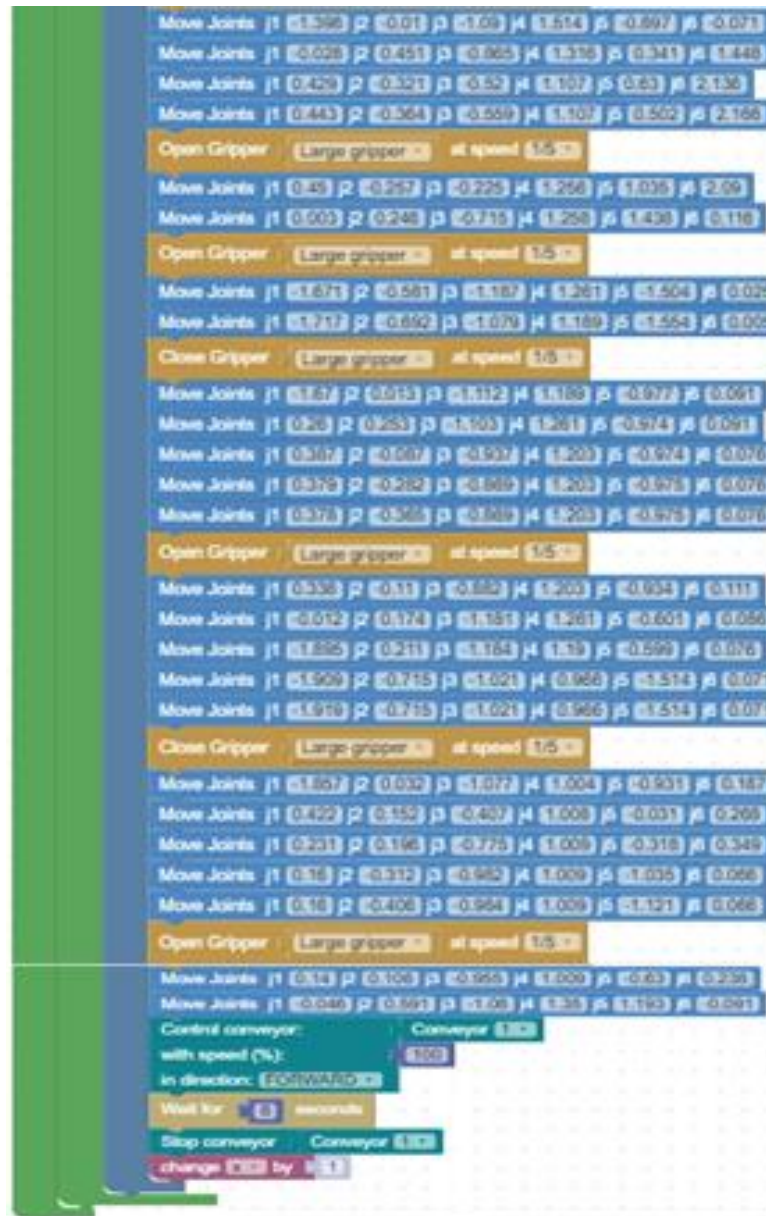
Algorithme sur robot mobile Thymio

Algorithme Station 1



Partie 1

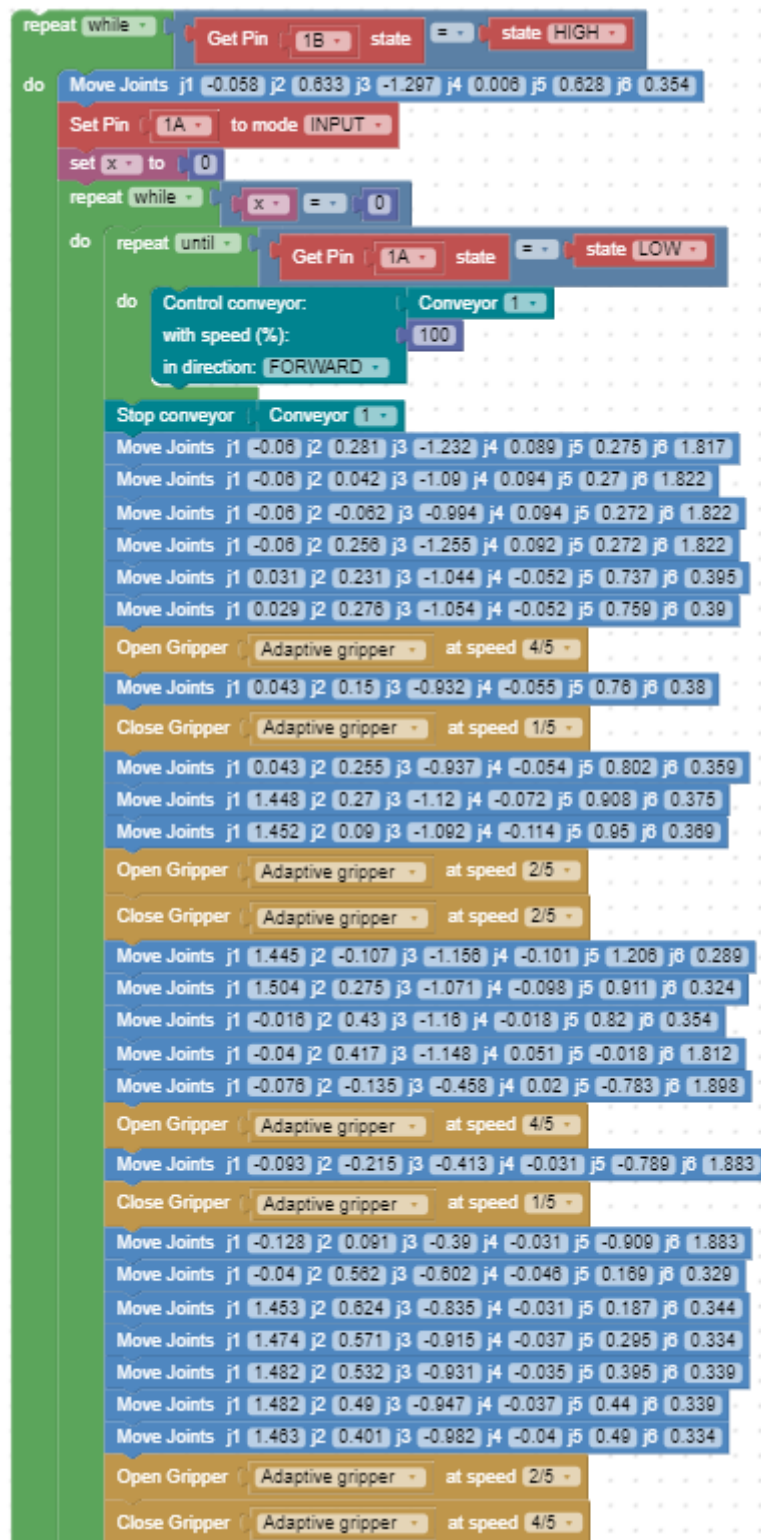
Algorithme



Partie 2

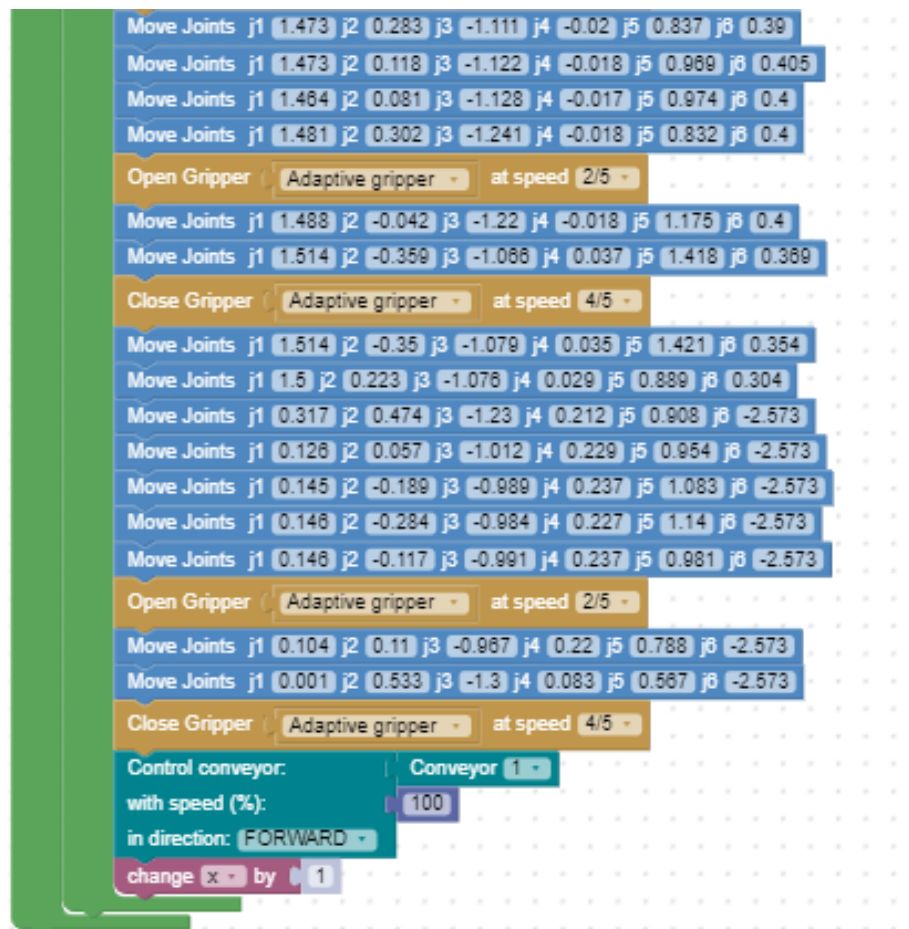
Algorithme sur robot mobile Niryo One

Algorithme Station 2



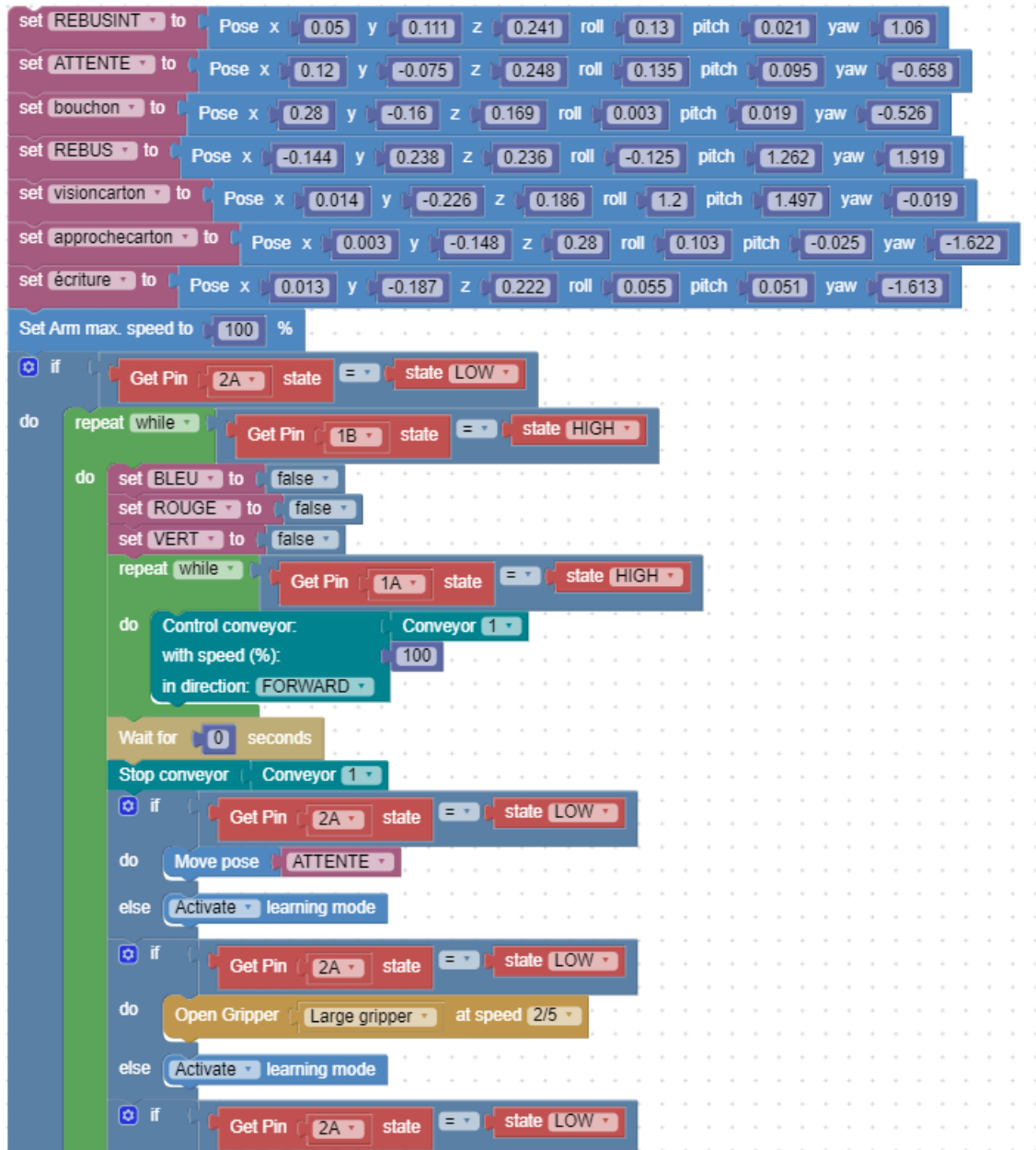
Algorithme

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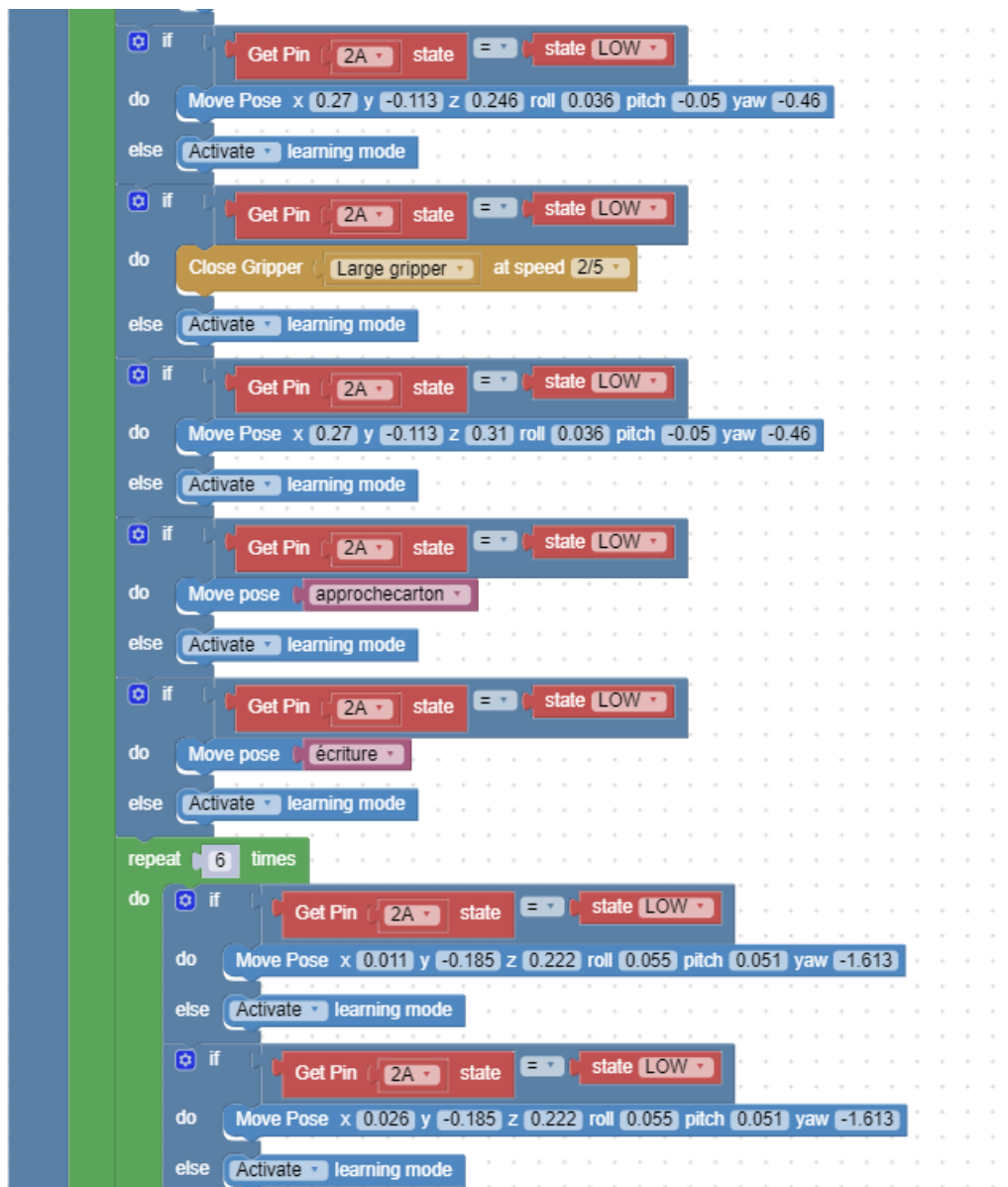
Algorithme sur robot mobile Niryo One

Algorithme Station 3



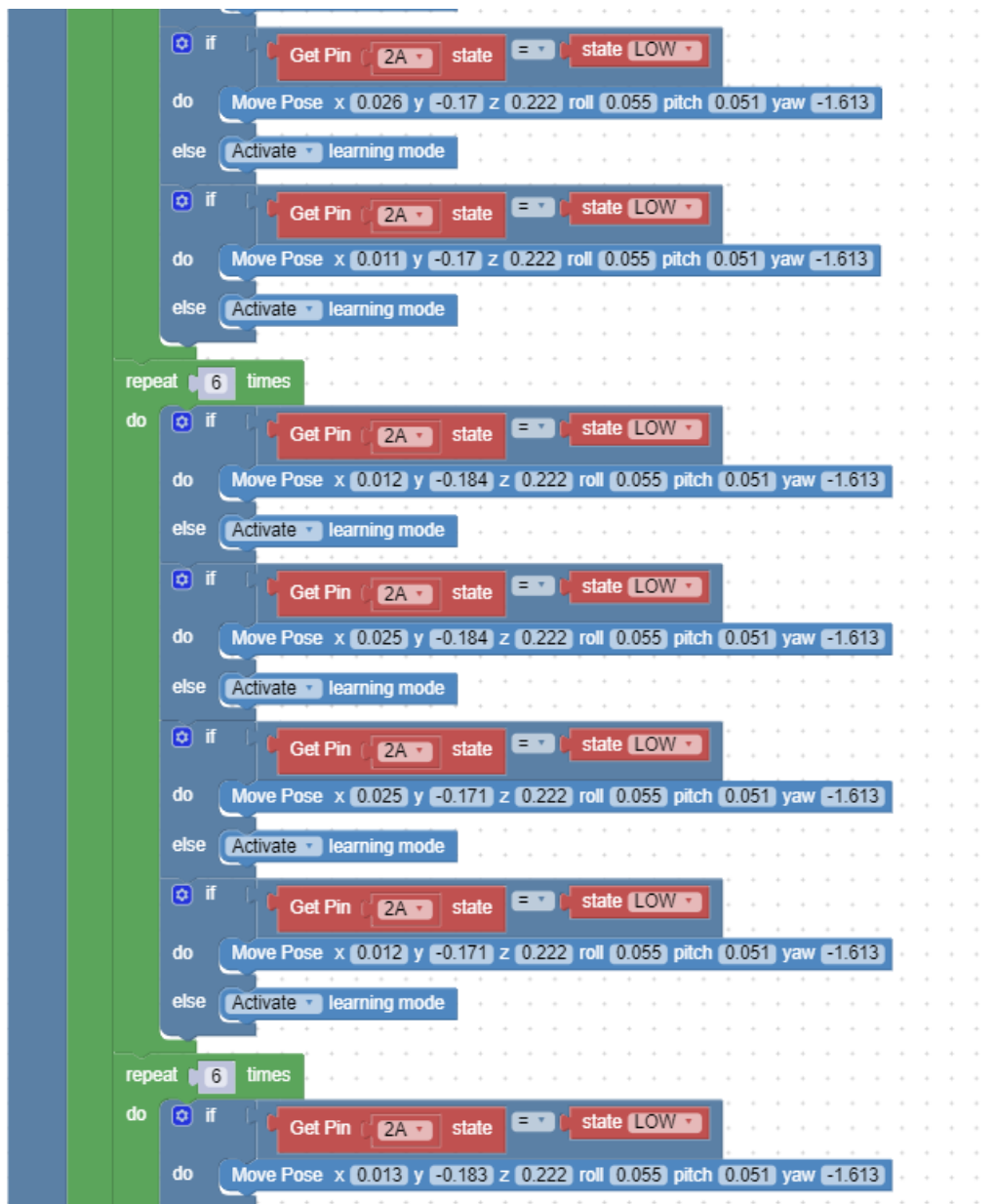
Algorithme

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Algorithmme

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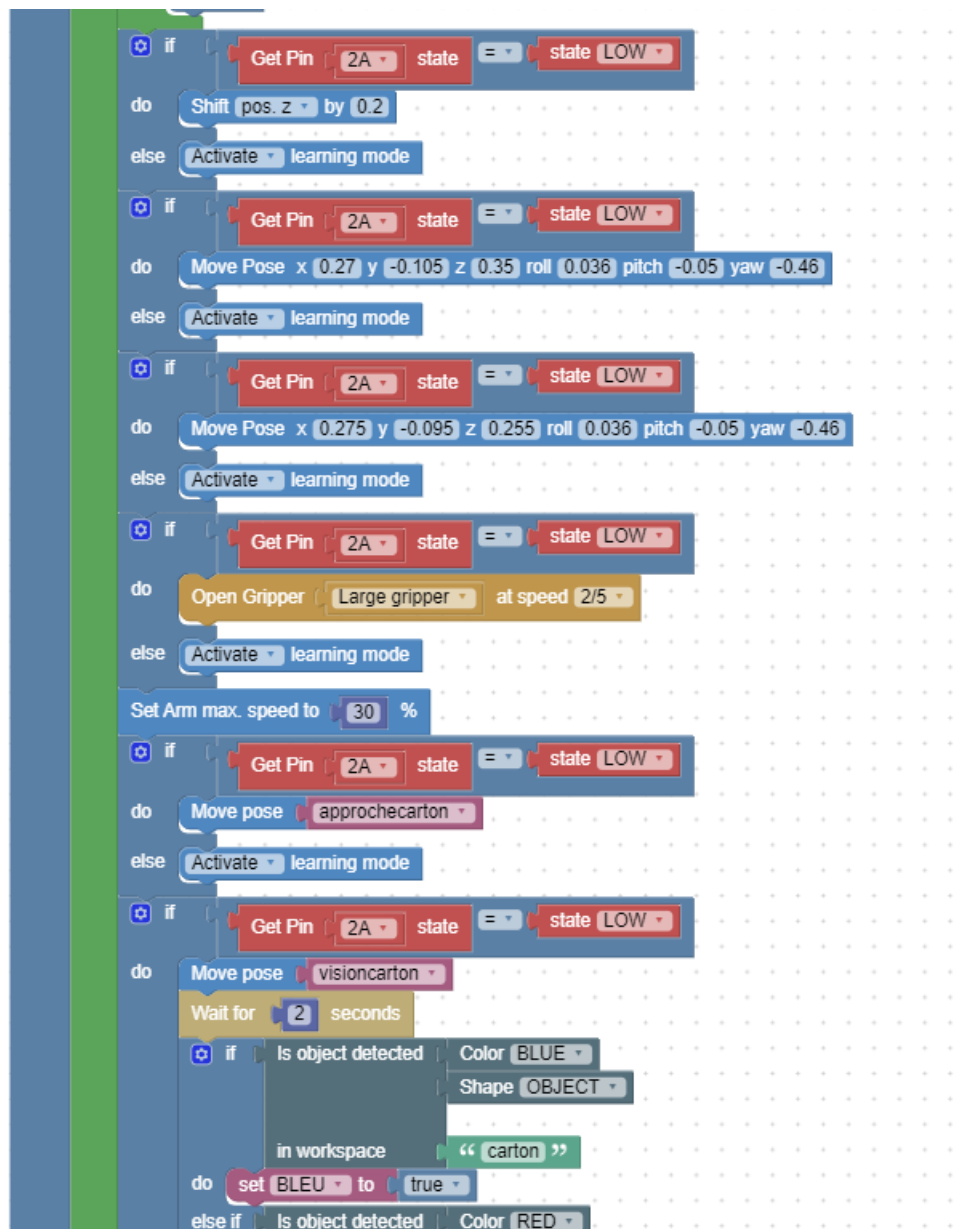
Algorithm

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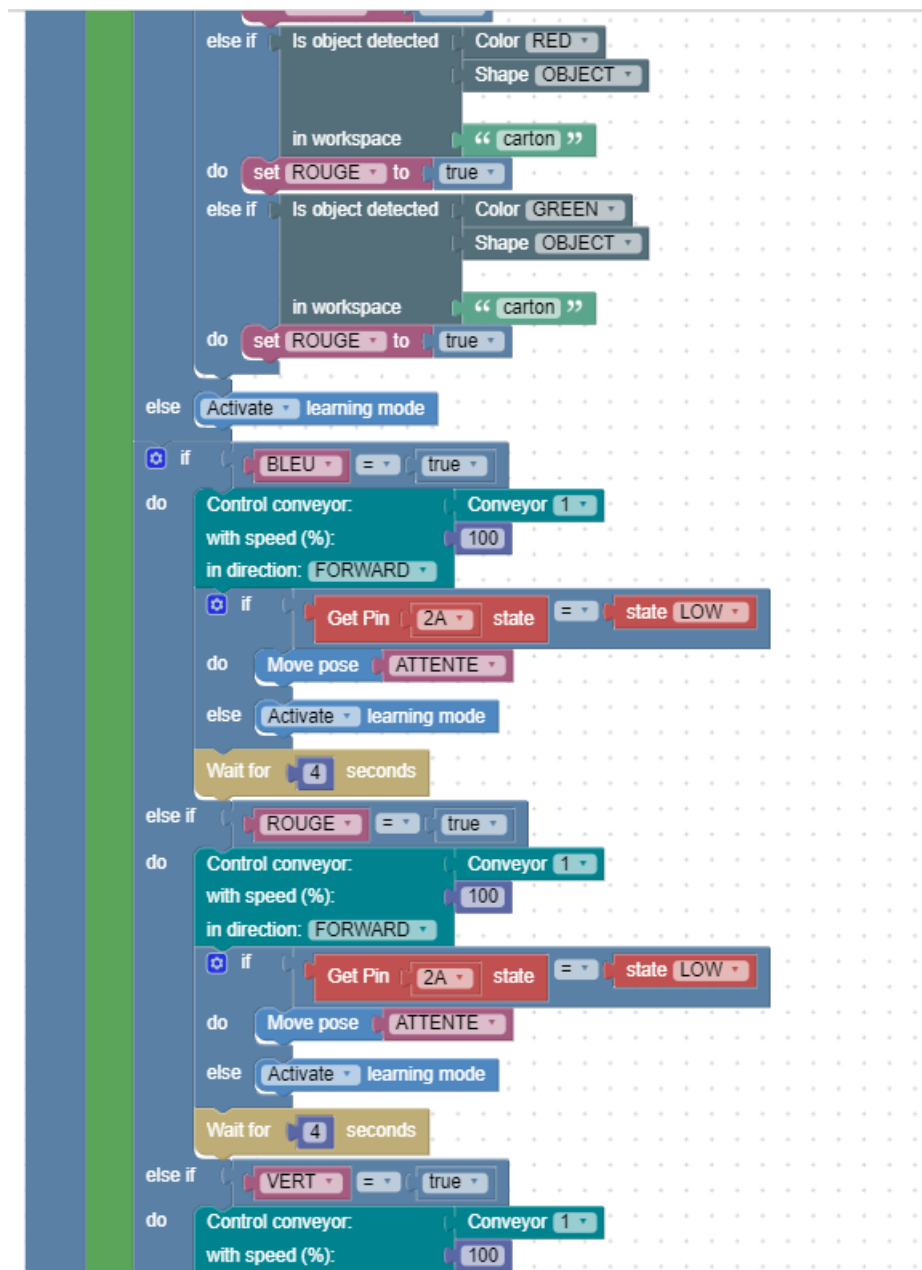
Algorithmme

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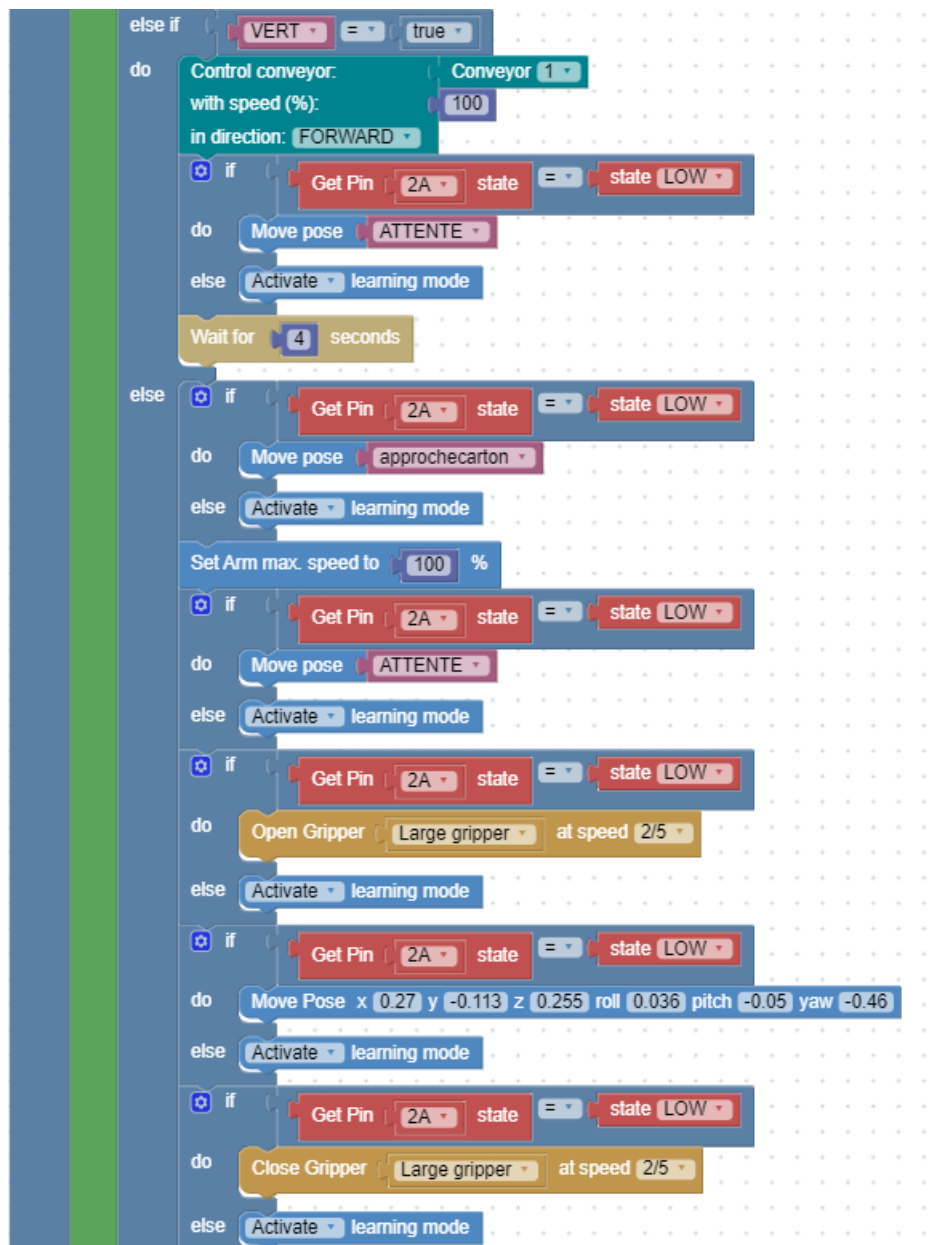
Algorithme

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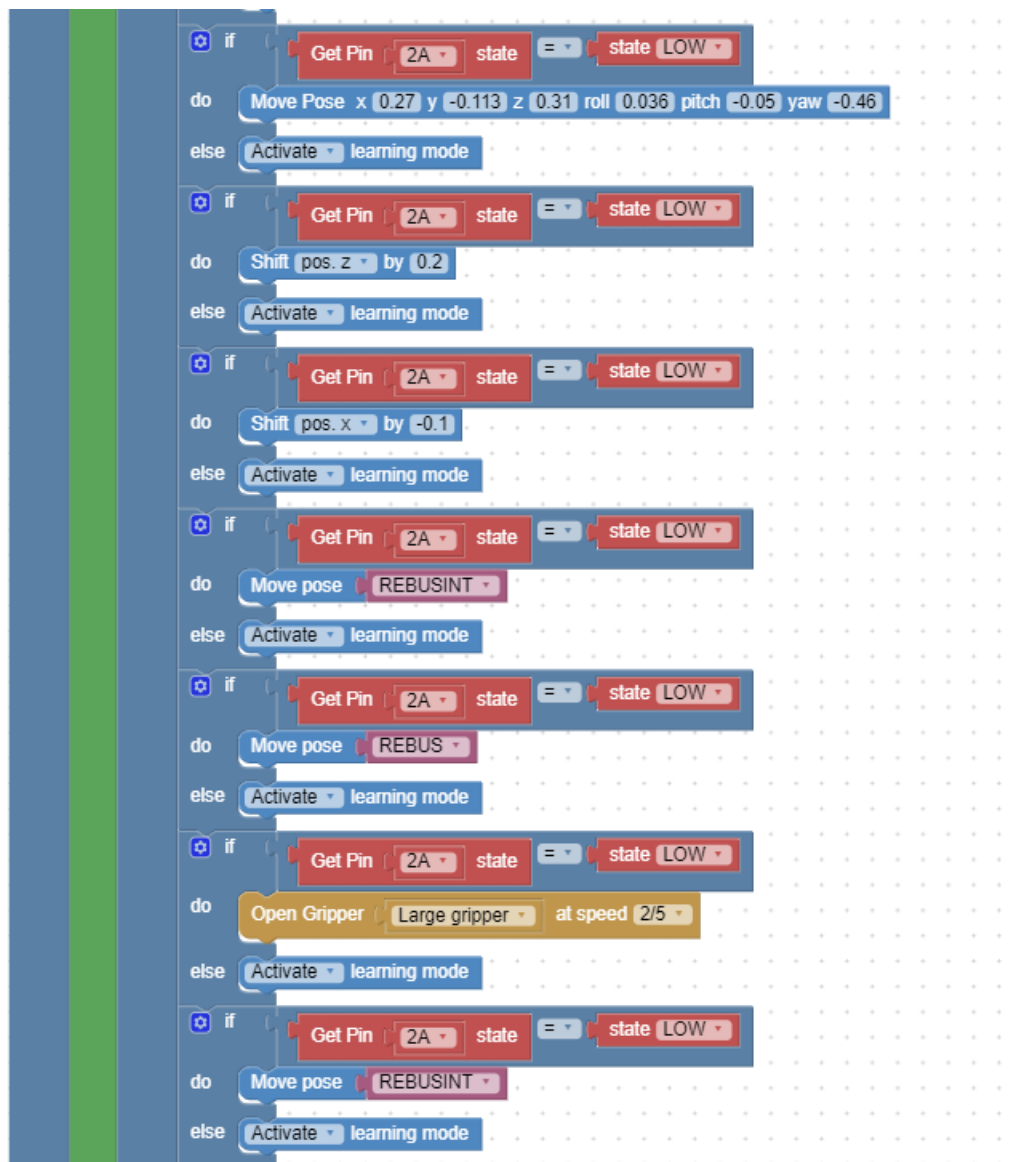
Algorithme

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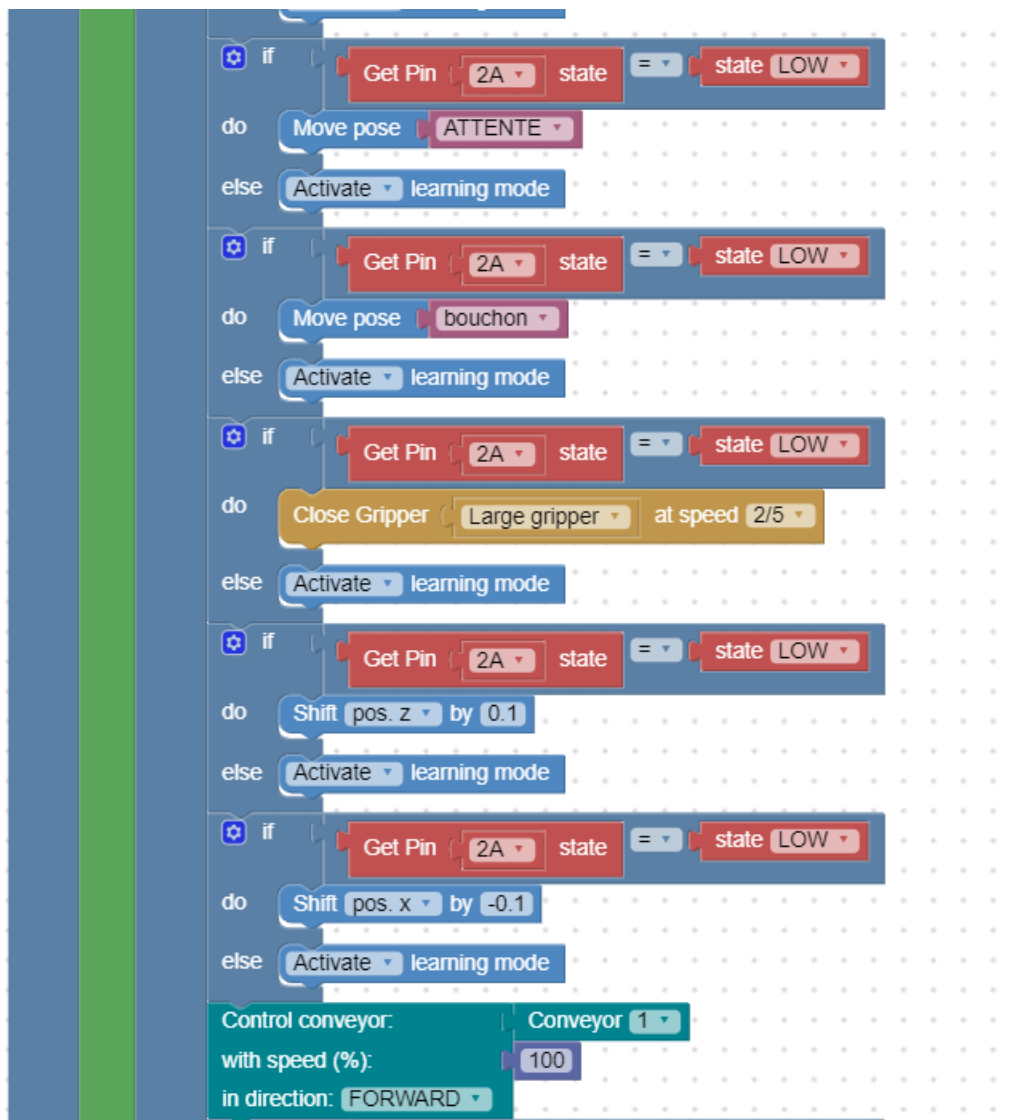
Algorithme

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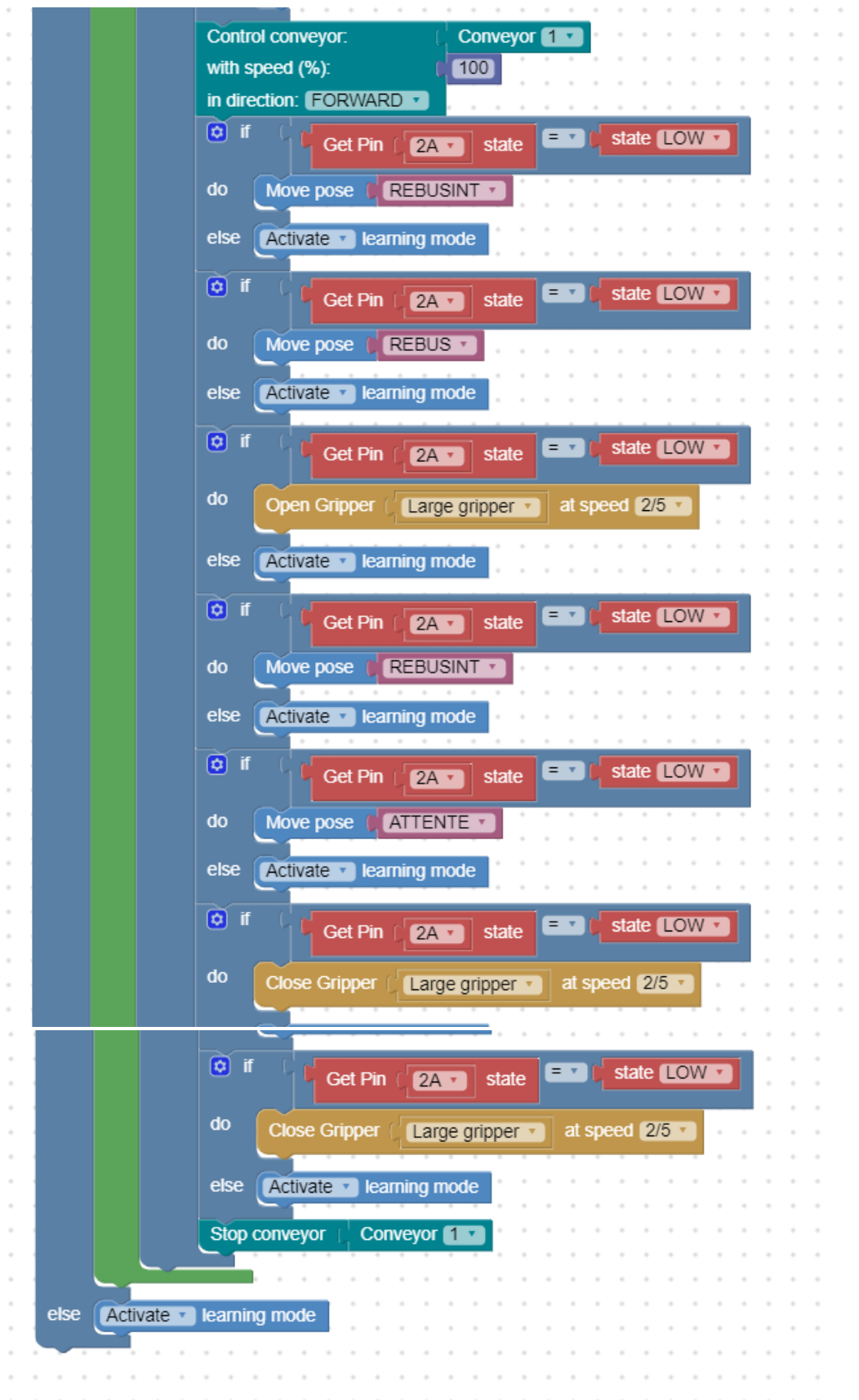
Algorithme

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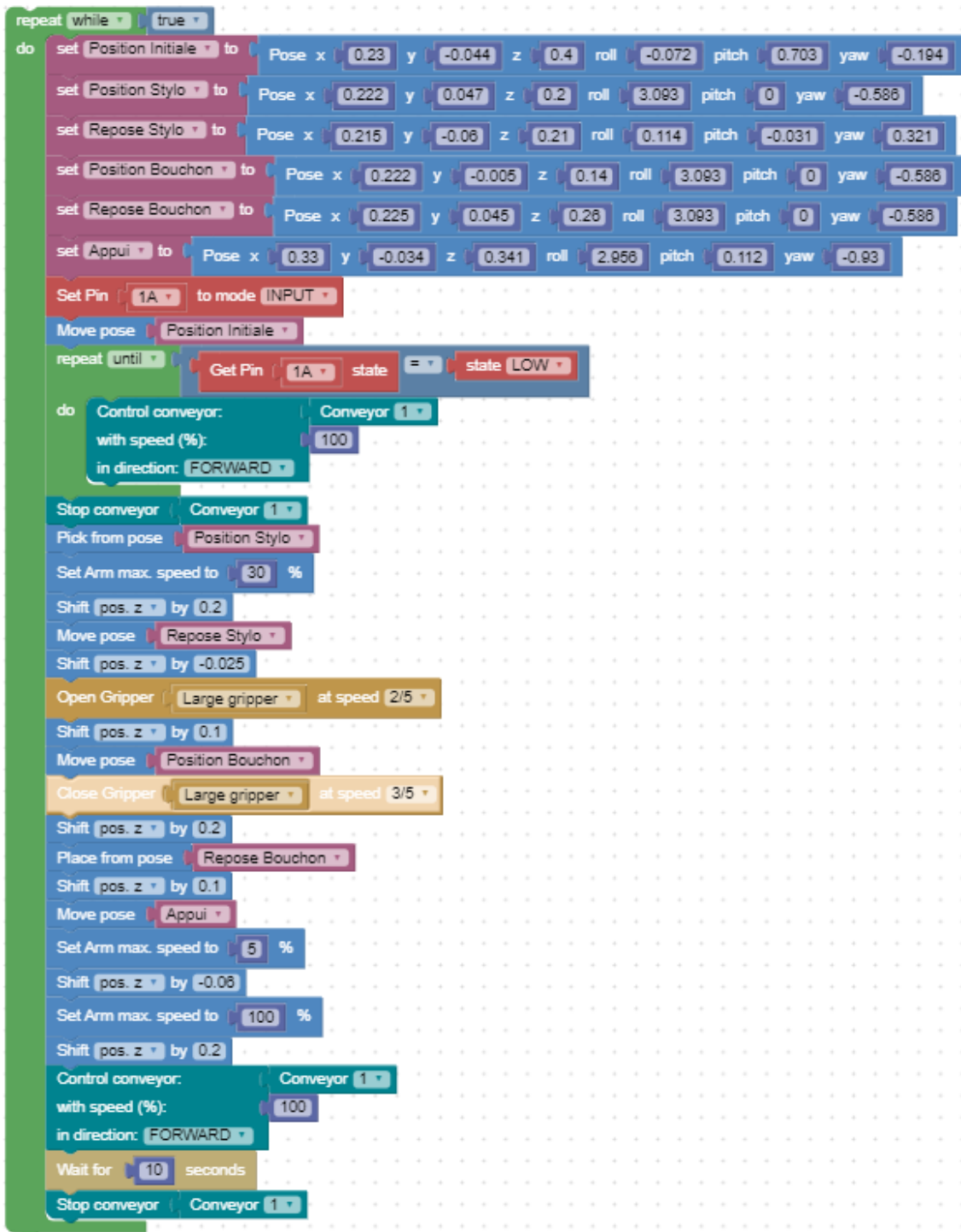
Algorithme

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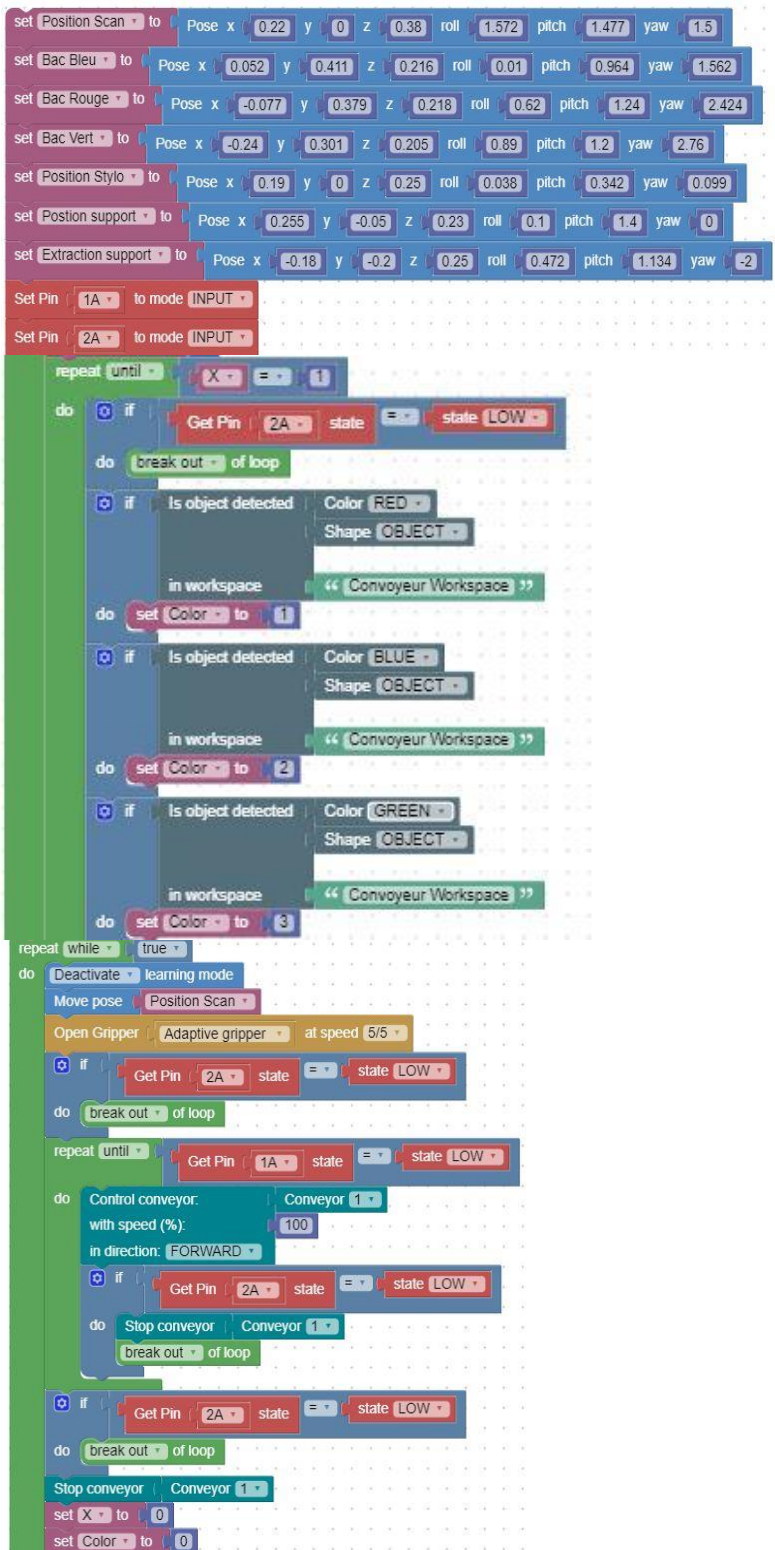
Algorithme sur robot mobile Niryo One

Algorithme Station 4

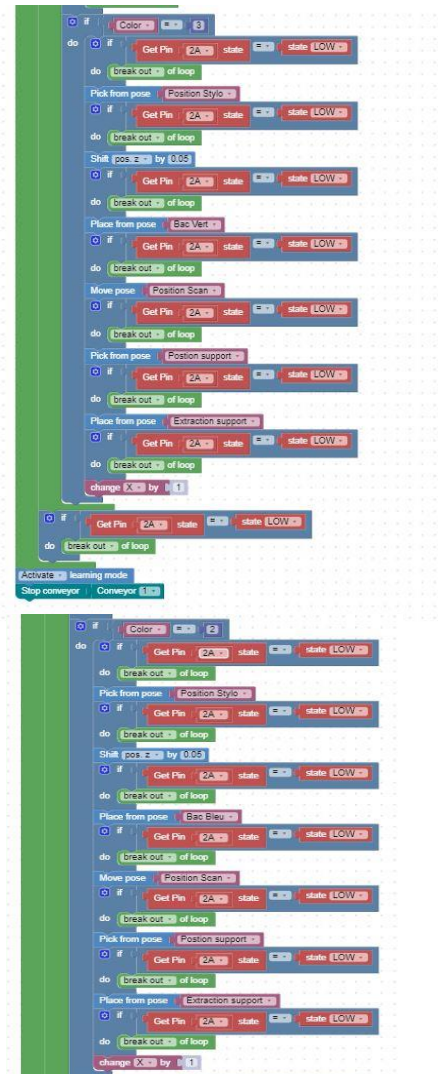


Algorithme sur robot mobile Niryo One

Algorithme Station 5

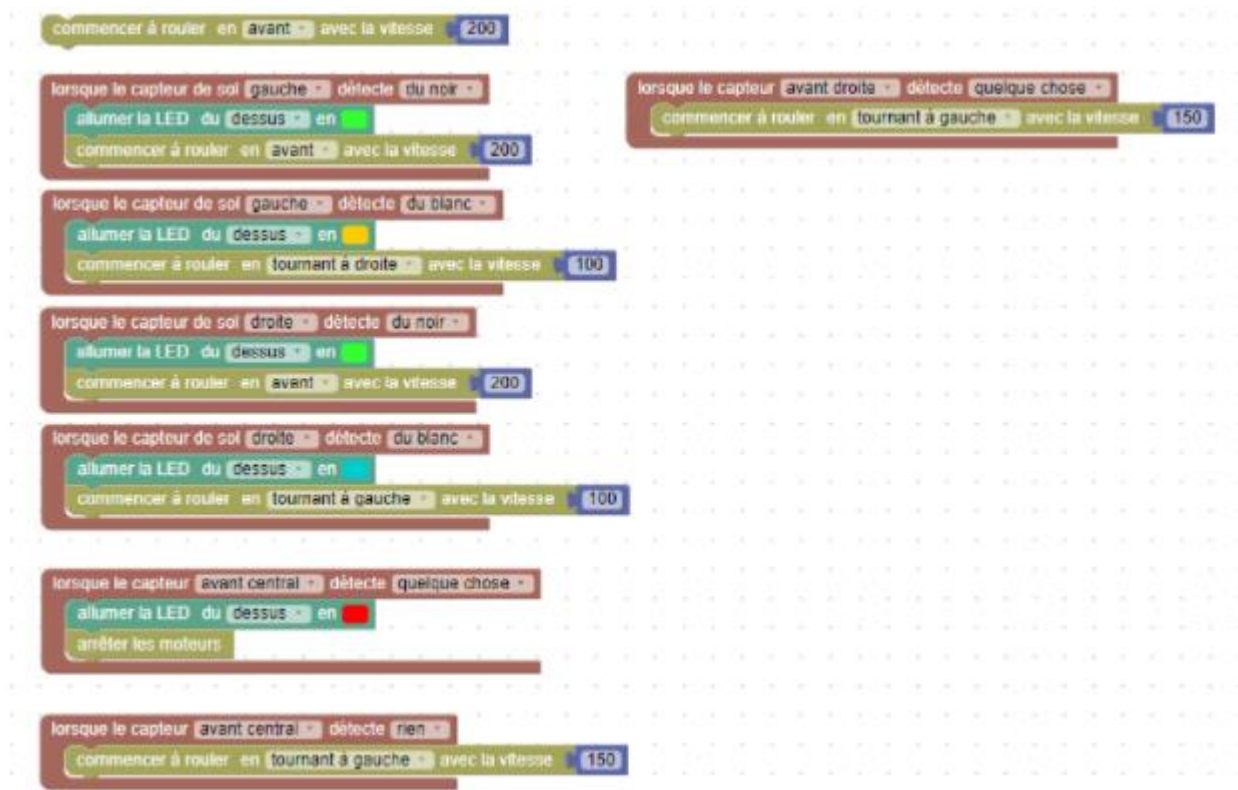


Algorithme



Algorithme sur robot mobile Niryo One

Algorithme Station 6



Algorithme sur robot mobile Thymio