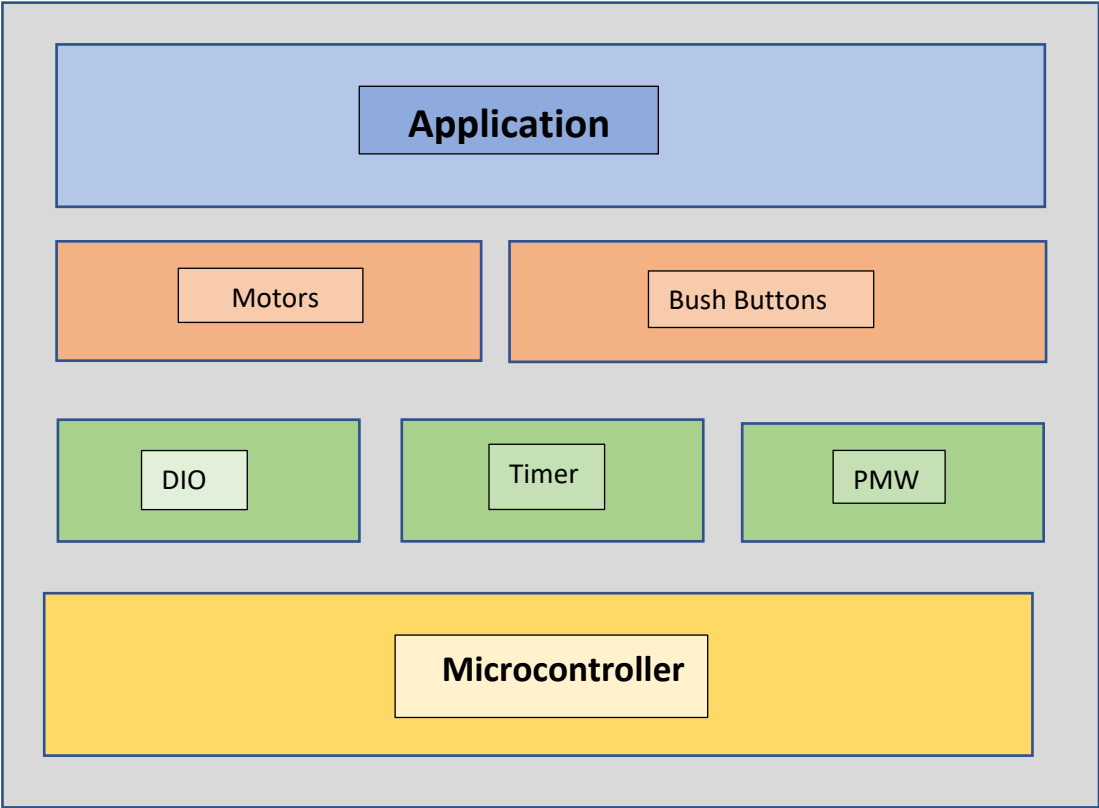
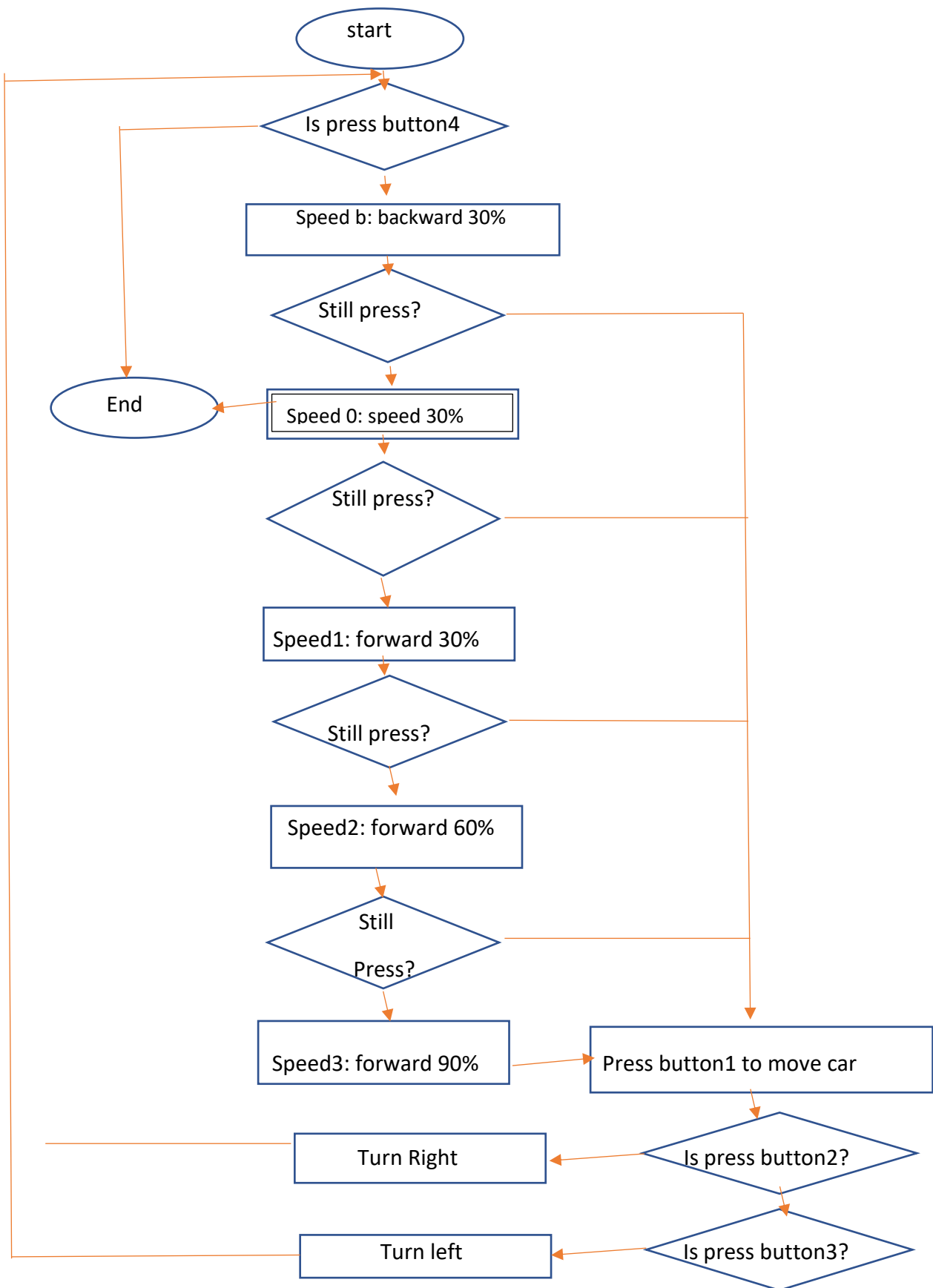


# Static Design





# Skeleton

```
int main()
{
    /* If you press button4 = 1 :
    Yes: speed b();
    If button4 = 1
    Yes : speed0();
    No : wait until button1 = 1
    If button4 = 1
    Yes : speed1();
    No : wait until button1 = 1
    If button4 = 1
    Yes : speed2();
    No : wait until button1 = 1
    If button4 = 1
    Yes : speed3();
    No : wait until button1 = 1

    If you press button2 = 1    turnRight();
    If you press button3 = 1    turnLeft(); */
}

Void speed b()
{
    /*backward , speed = 30%*/
}

Void speed0()
{
    /*forward , speed = 30%*/
}

Void speed1()
{
    /*forward , speed = 30%*/
}

Void speed2()
{
    /*forward , speed = 60%*/
}

Void speed3()
{
    /*forward , speed = 90%*/
}

Void turnRight()
{ /* increase left motor speed and decrease right motor*/ }
Void turnLeft()
{ /* increase Right motor speed and decrease left motor*/ }
```