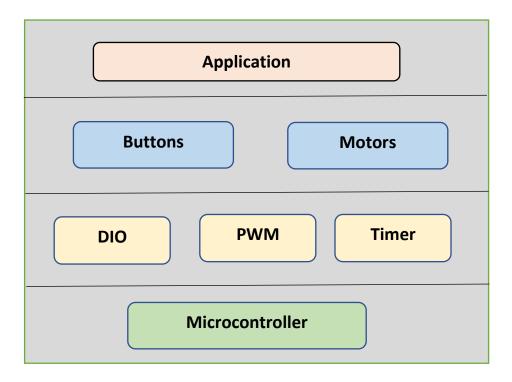
# Static Design



### **Buttons Interface:**

```
uint8_t Button_Read (Port port_number, Pin pin_number);
```

### **MOTORS Interface:**

```
void Motor_Init ( );
void Motor_start (uint8 speed, Direction dir);
void Set_Speed (uint8_t duty_cycle);
void Set_Direction (uint8_t dir);
void Motor_Stop ( );
```

## **DIO Interface:**

```
void DIO_Init (const DIO_ConfigType *Config_Ptr);
void DIO_Set ( Port port_number, Pin pin_number);
void DIO_Clear ( Port port_number, Pin pin_number);
void DIO_Toggle ( Port port_number, Pin pin_number);
uint8_t DIO_Read ( Port port_number, Pin pin_number);
```

### Timers Interface:

```
void Timer_init(const Timer_ConfigType * Config_Ptr);
void Timer_Start (uint64_ ticks);
void Timer_stop(uint8 timer_number);
```