Spatial Patterns in Nature

An Entry-Level Introduction to Their Emergence and Dynamics

SIAM DS23, Minitutorial MT1-2

Robbin Bastiaansen, Peter van Heijster, Frits Veerman

Minitutorial overview and slides:

bastiaansen.github.io/MTpatterns/patternMT.html





Peter van Heijster, Chair of Applied Mathematics, Biometris, Wageningen University & Research

Peter is an **applied analyst** and his research focusses on **nonlinear dynamics**, and in particular on understanding **pattern formation**. The aim of his research is to get a better understanding of the pattern formation processes in **paradigmatic mathematical models** (often with *scale separation*) and to apply the new insights to more **biologically-realistic models** from the Life Sciences and Mathematical Biology and Ecology.





Robbin Bastiaansen

Assistant Professor

Mathematical Institute Utrecht University &

Institute for Marine and Atmospheric Research Utrecht (IMAU) Utrecht University

Robbin is an applied mathematician and his research focusses on mathematics of and for climate, by the use of techniques and insights from nonlinear dynamical systems theory. The aim of his research is to get a better fundamental insight in climate and ecosystem responses due to forcings, and to develop and improve estimation and projection methodologies.



Frits Veerman (Mathematical Institute, Leiden University, The Netherlands)

develops analytical tools to investigate and predict phenomena such as pattern formation in spatially extended, nonlinear, dynamical systems, with a focus on applications in biology and ecology

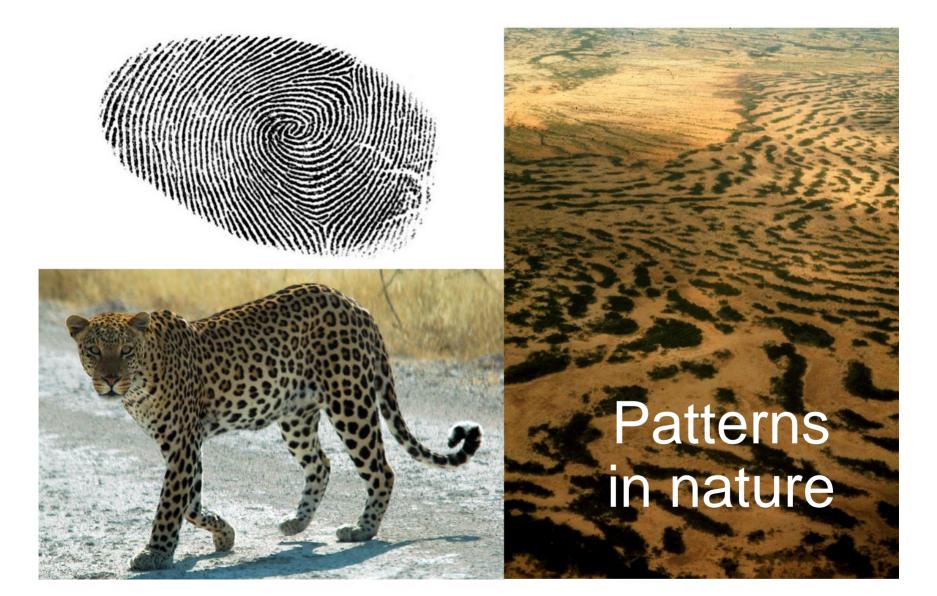
substituting for **Arjen Doelman**(Mathematical Institute, Leiden
University,
The Netherlands)



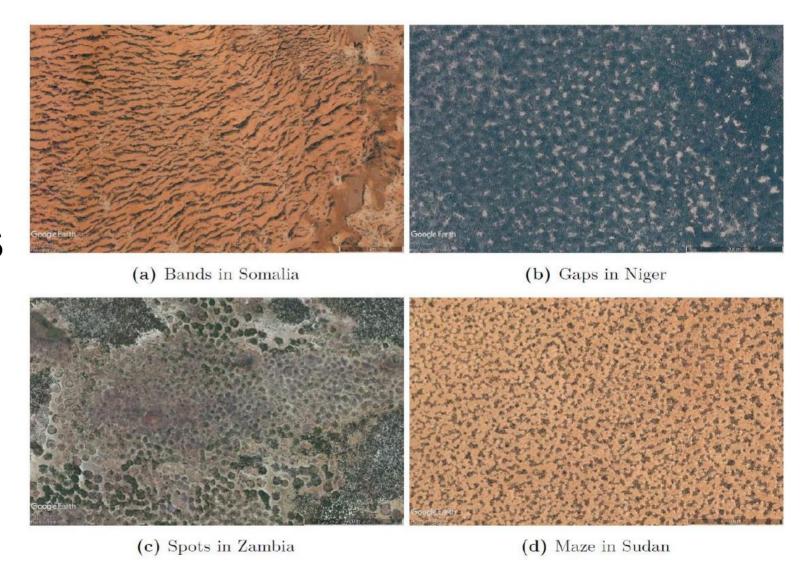


Minitutorial setup

- Introduction
- Multistability and patterns
- Explicit construction of front solutions
 - Existence
 - Stability
- Dynamics of existing structures
- Summary & Outlook



Dryland eco-systems



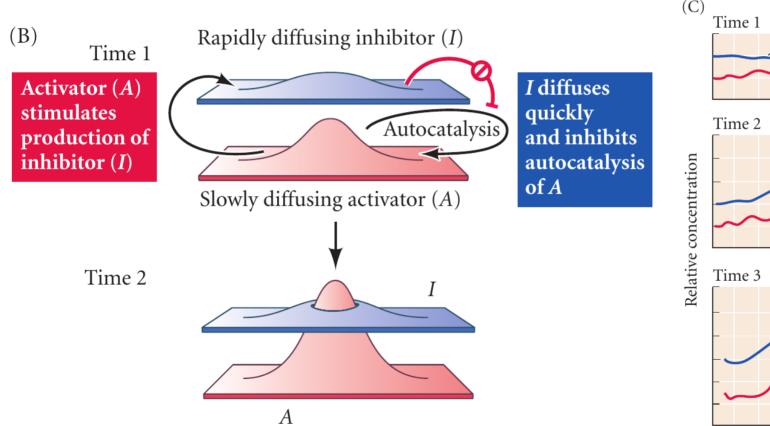
Patterns in developmental biology

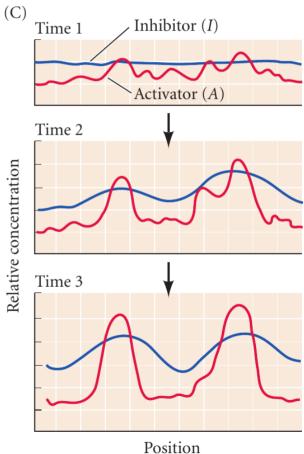


Questions / research topics

- How and when do these patterns form?
- What are the underlying mechanisms behind pattern formation?
- When are initial conditions and/or external factors important?
- Can we predict the pattern wavelength?
- Are observed patterns stationary or transient?
- How about pattern stability/robustness?

Turing pattern formation





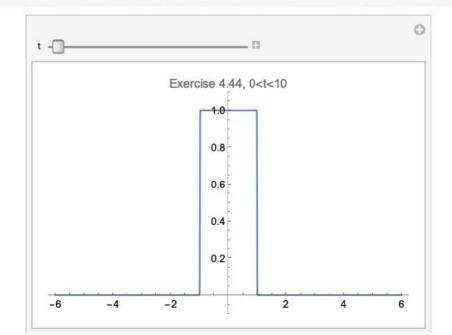
- Turing 1952: Stable uniform state in a kinetic system (ODE) can become unstable when you add diffusion (PDE).
- Diffusion driven pattern formation (nowadays: Turing patterns).
- Counter intuitive: Diffusion was/is thought of having a stabilising effect.



[wikipedia]

Heat equation:

$$U_t = U_{xx}$$



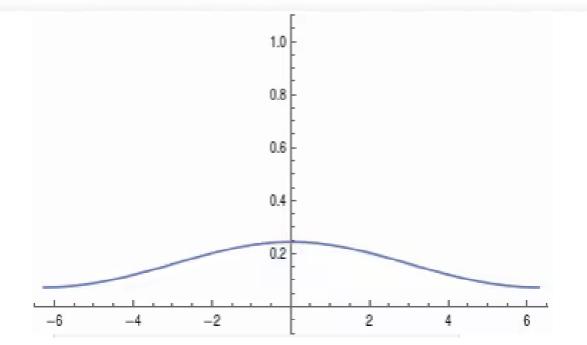
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[wikipedia]

Heat equation:





Stable uniform state in a kinetic system (ODE) can become unstable when you add diffusion (PDE)

Kinetic system (ODE):
$$\left(\begin{array}{c} u \\ v \end{array} \right)_t = \gamma \left(\begin{array}{c} F(u,v) \\ G(u,v) \end{array} \right) \text{,} \qquad \mathbf{w} = \begin{pmatrix} u \\ v \end{pmatrix}$$

Want: (0,0) to be stable fixed point, so F(0,0)=G(0,0)=0 and

Stable uniform state in a kinetic system (ODE) can become unstable when you add diffusion (PDE)

add diffusion (PDE):
$$\left(\begin{array}{c} u \\ v \end{array} \right)_t = \gamma \left(\begin{array}{c} F(u,v) \\ G(u,v) \end{array} \right) + \left(\begin{array}{c} u_{xx} \\ {\color{red} d} v_{xx} \end{array} \right)$$

Question: Can (0,0) transform into an unstable fixed point?

Stable uniform state in a kinetic system (ODE) can become unstable when you add diffusion (PDE)

Recall, for (0,0) to be a stable fixed point for the ODE, we needed:

$$F_u + G_v < 0$$
 & $F_u G_v > F_v G_u$ (**)

Therefore, the sum of the eigenvalues of the PDE

$$\lambda_1 + \lambda_2 = \gamma(F_u + G_v) - k^2(1 + \mathbf{d})$$

is always negative.

Stable uniform state in a kinetic system (ODE) can become unstable when you add diffusion (PDE)

$$\begin{pmatrix} u \\ v \end{pmatrix}_t = \gamma \begin{pmatrix} F(u,v) \\ G(u,v) \end{pmatrix} + \begin{pmatrix} u_{xx} \\ \frac{d}{d}v_{xx} \end{pmatrix}$$

So, the four conditions for Turing Instability are

$$F_u + G_v < 0$$

$$F_u G_v > F_v G_u$$

$$dF_u + G_v > 0$$

$$(dF_u + G_v)^2 > 4d(F_u G_v - F_v G_u)$$

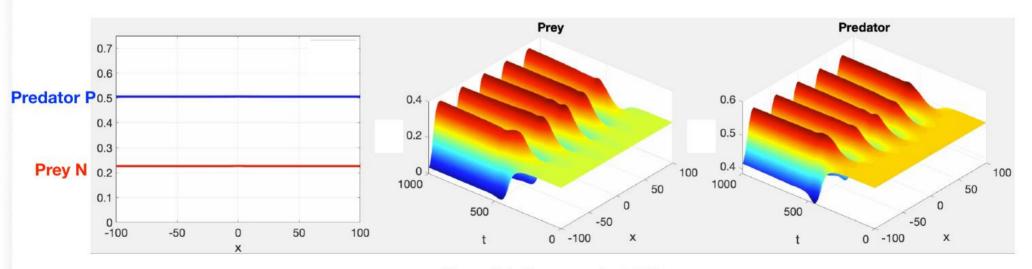
and since we have five "unknowns" we can realise this!

DIFFUSION CAN HAVE A DESTABILISING EFFECT!!

Example: Diffusive Holling-Tanner predator-prey model with an alternative food source for the predator

$$N_t = rN\left(1 - \frac{N}{K}\right) - \frac{qNP}{N+a} + D_1 N_{xx},$$

$$P_t = sP\left(1 - \frac{P}{hN+c}\right) + D_2 P_{xx}.$$

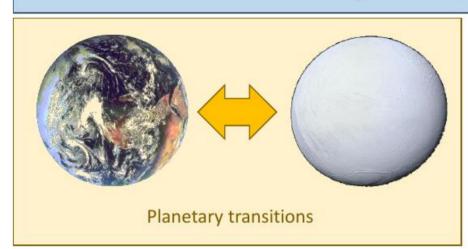


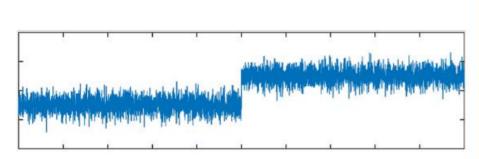
[Arancibia-Ibarra et al., 2021]



Tipping Points

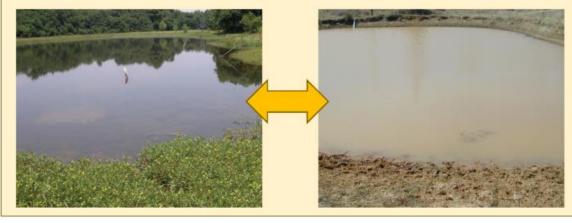
IPCC AR6 (2021): "a critical threshold beyond which a system reorganizes, often abruptly and/or irreversibly"







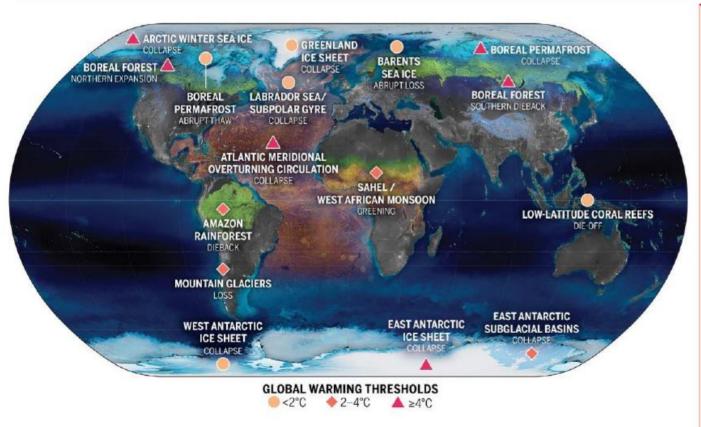
Ecosystem shifts



Tipping Points

IPCC AR6 (2021):

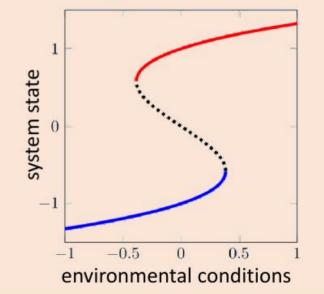
"a critical threshold beyond which a system reorganizes, often abruptly and/or irreversibly"



Mathematics

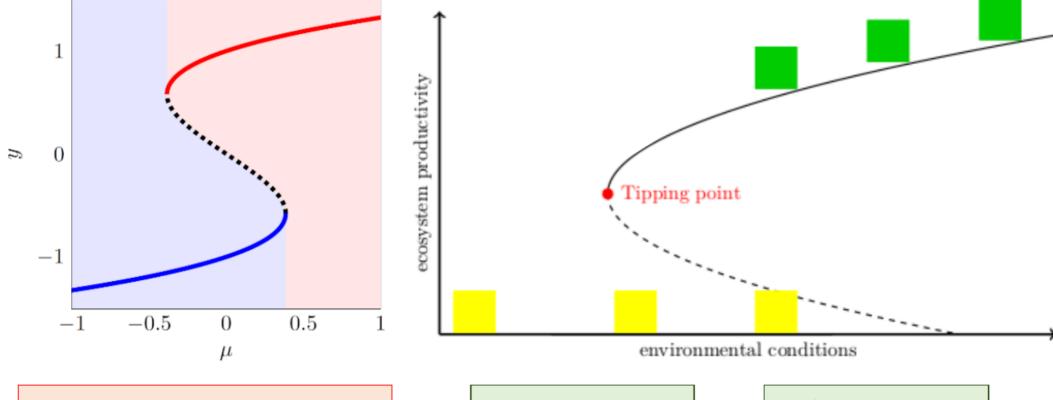
Tipping points ↔ Bifurcations

$$\frac{dy}{dt} = f(y, \mu)$$



source: McKay et al, 2022

Classic Theory of Tipping

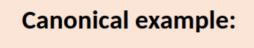


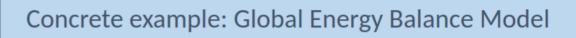
$$\frac{dy}{dt} = y(1 - y^2) + \mu$$

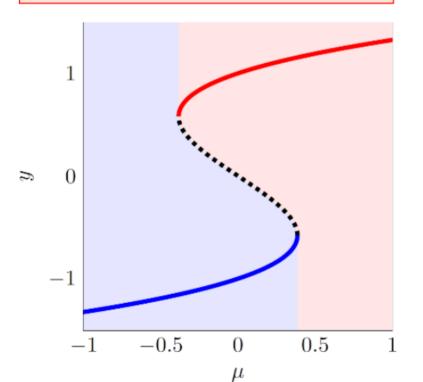
$$\frac{d\vec{y}}{dt} = f(\vec{y}; \mu)$$

$$\begin{cases} \frac{du}{dt} = f(u, v; \mu) \\ \frac{dv}{dt} = g(u, v; \mu) \end{cases}$$

Tipping in ODEs (1)









[Holling, 1973] [Noy-Meier, 1975] [May, 1977]

Tipping

[Ashwin et al, 2012]

Bifurcation-Tipping: Basin disappears

Noise-Tipping : Forced outside Basin

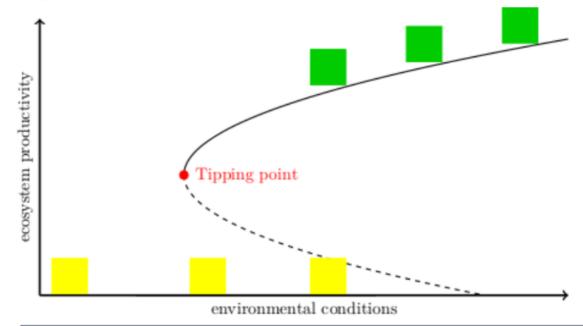
Rate-Tipping: (more complicated)

Tipping in ODEs (2)

Two components:

includes common models:

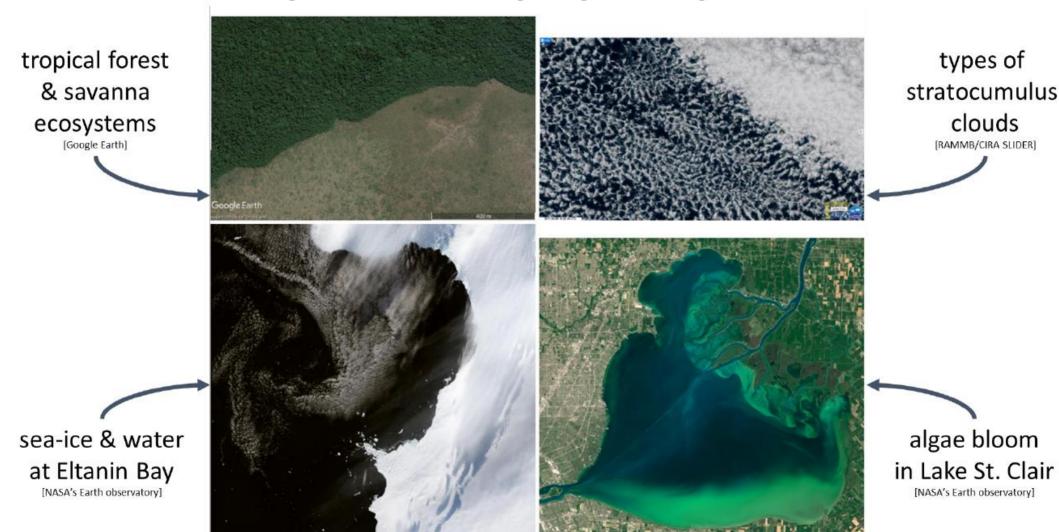
- Predetor-Prey
- Activator-Inhibitor



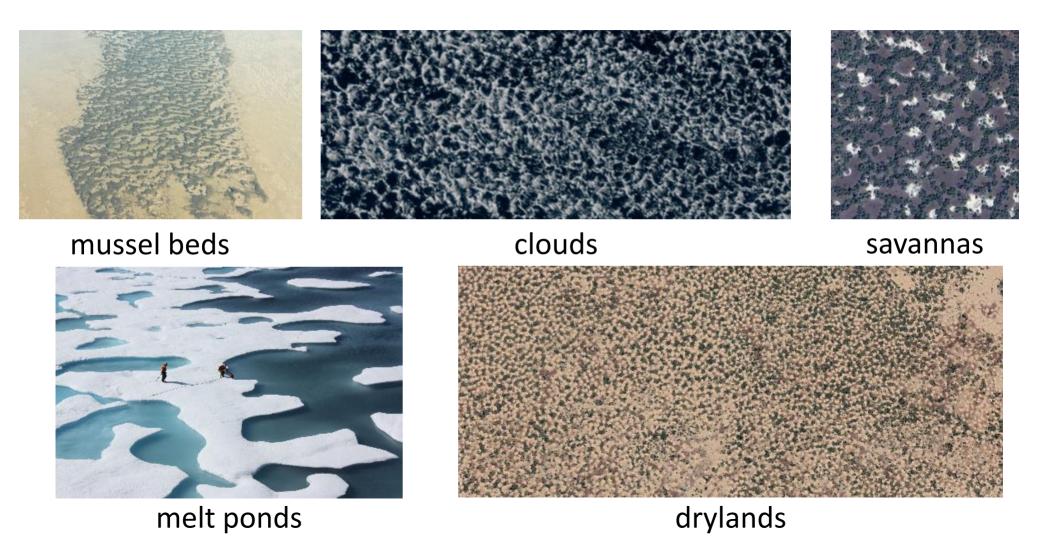
Examples of tipping in ODEs include:

- Forest-Savanna bistability
- Deep ocean exchange
- Cloud formation
- Ice sheet melting
- Turbidity in shallow lakes

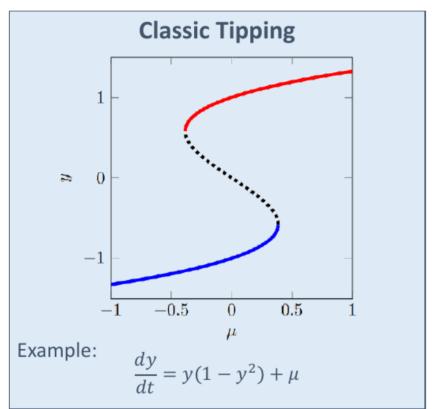
Reality is not always spatially-uniform!

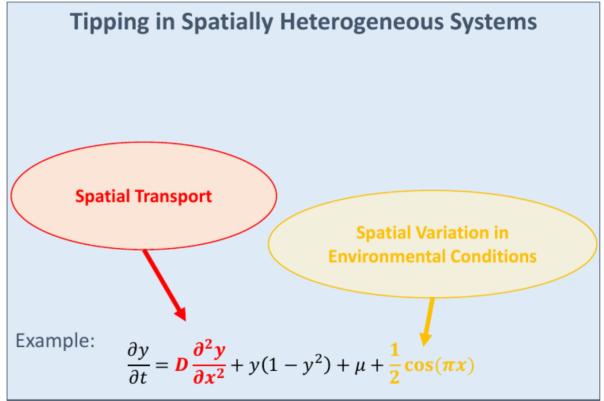


Examples of spatial patterning – regular patterns



A spatially heterogeneous world



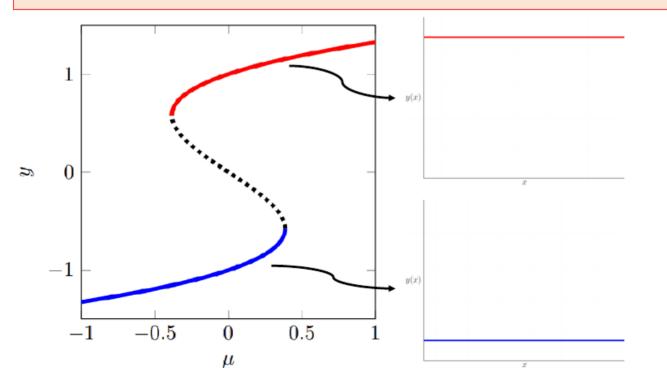


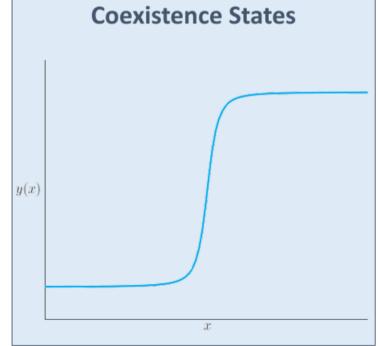
Stationary front solutions in bistable PDEs with coefficients that vary in space

Coexistence states

Bistable (Allen-Cahn/Nagumo) equation:

$$\frac{\partial y}{\partial t} = y(1 - y^2) + \mu + D \frac{\partial^2 y}{\partial x^2}$$



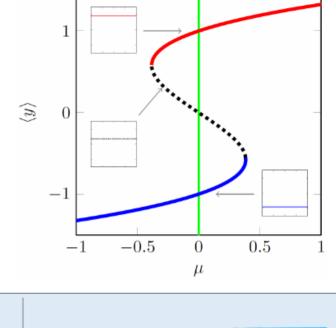


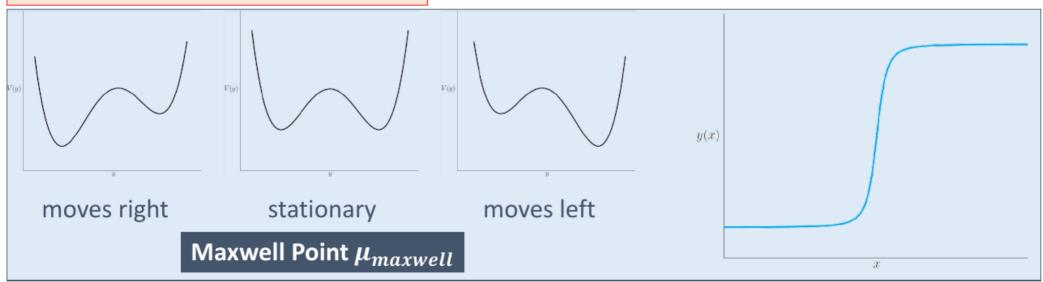
Front Dynamics

$$\frac{\partial y}{\partial t} = D \frac{\partial^2 y}{\partial x^2} + f(y; \mu)$$

Potential function $V(y; \mu)$:

$$\frac{\partial V}{\partial y}(y;\mu) = -f(y;\mu)$$



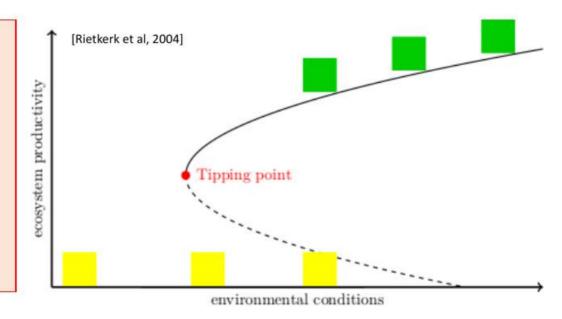


Patterns in models

Add spatial transport:

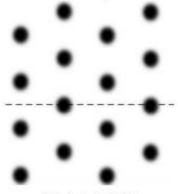
Reaction-Diffusion equations:

$$\begin{cases} \frac{du}{dt} = f(u, v) + D_u \Delta u \\ \frac{dv}{dt} = g(u, v) + D_v \Delta v \end{cases}$$





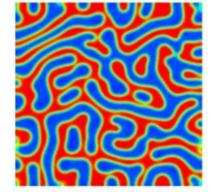
[Klausmeier, 1999]



[Gilad et al. 2004]



[Rietkerk et al. 2002]

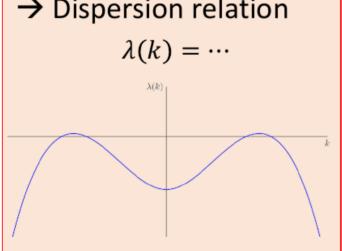


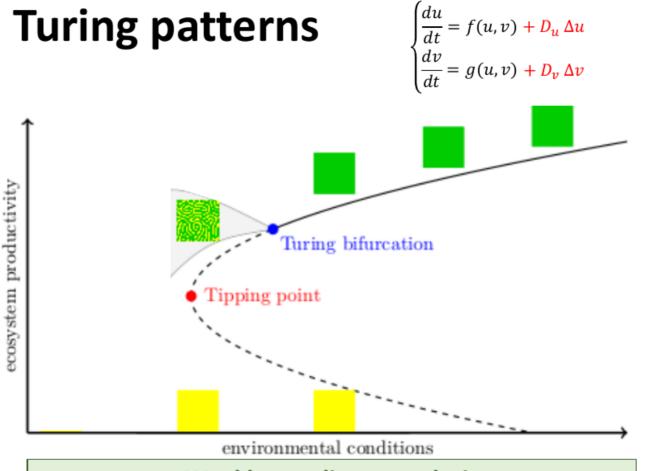
[Liu et al. 2013]

Instability to nonuniform perturbations

$$\binom{u}{v} = \binom{u_*}{v_*} + e^{\lambda t} e^{ikx} \binom{\bar{u}}{\bar{v}}$$

→ Dispersion relation





Weakly non-linear analysis

Ginzburg-Landau equation / Amplitude Equation & Eckhaus/Benjamin-Feir-Newel criterion [Eckhaus, 1965; Benjamin & Feir, 1967; Newell, 1974]

Busse balloon

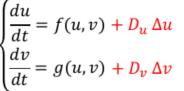
A model-dependent shape in (parameter, observable) space that indicates all stable patterned solutions to the PDE.

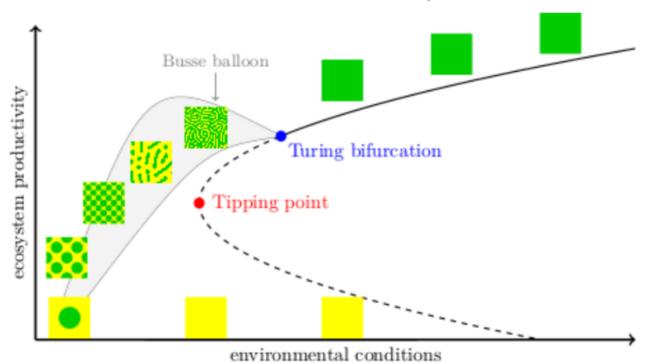
Construction Busse balloon

Via numerical continuation

few general results on the shape of Busse balloon

Busse balloon





Busse balloon

Idea originates from thermal convection [Busse, 1978]

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