Bastian Lang

From MAS-Students ss15

Topic: Real World Optimization of Energy Efficient Vehicle Control

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Contents

- 1 Abstract
- 2 Introduction
- 3 Problem Formulation
 - 3.1 What is this project about?
 - 3.2 Why is it relevant?
 - 3.3 What have other people done in this field?
 - 3.4 Why is that not sufficient?
 - 3.5 What is the deficit addressed in this project?
- 4 State of the Art
 - 4.1 Reading Reports
 - 4.1.1 paper_title (todo)
 - 4.1.2 paper title (todo)
 - 4.1.3 paper title (todo)
 - 4.1.4 paper title (todo)
 - 4.1.5 paper title (todo)
 - 4.1.6 paper title (todo)
 - 4.1.7 paper title (todo)
 - 4.1.8 paper title (todo)
 - 4.1.9 paper title (todo)
 - 4.1.10 paper title (todo)
 - 4.1.11 paper title (todo)
 - 4.1.12 paper title (todo)
 - 4.1.13 paper title (todo)
 - 4.1.14 paper title (todo)
 - 4.2 Conclusions
 - 4.3 References
 - 4.4 Appendix
 - 4.4.1 A. Online literature search
 - 4.4.2 B. Sources
 - 4.4.3 C. List of top research labs/researchers

Abstract

Introduction

Problem Formulation

What is this project about?

- Creating an energy efficient vehicle control for a real-world e-bike
- Transferring and evaluating the controller on the real device
- Applying ways to cross the reality gap
- Improving the vehicle model

Why is it relevant?

- Energy-efficiency is important in transportation as even small improvements result in huge savings of energy
- There is still much room for improvements as even simple driver-training programs have yielded impressive results

What have other people done in this field?

- Use of optimal control theory
- Use of graph search algorithms
- Use of heuristics to prune search space
- Use of inverted system equations to avoid discretization
- Applying noise to the EA to make solutions robust
- Use of transferability measure to estimate real world performance
- Application of evolutionary algorithms to evolve a controller in simulation

Why is that not sufficient?

- Complexity and computation speed is not good enough for real time application
- Not all system equations can be inverted and it is non-trivial
- Vehicle control only developed in simulation without preparations for transfer to real world

■ Transfer algorithms do not have many real world applications so far, only proof of concepts

What is the deficit addressed in this project?

■ The controller so far has only been developed in simulation and not on the real device

State of the Art

Reading Reports

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References

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B. Sources

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C. List of top research labs/researchers

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