1. A majority bin (MB), generative (GG), k-nearest neighbours (KNN) and multi-layer perceptron (MLP) classifiers were implemented (Q2), evaluated and compared in Table 2 (Q3), for classification of 5 different human activities. GG fits Gaussian prior probability distributions of the form $p(\mathbf{x}|C_k) = a \exp{(\mathbf{x} - \mu)^T \Sigma_k^{-1}(\mathbf{x} - \mu)}$ to each class C_k using a training dataset X^p and classifies test datapoint \mathbf{x}^p as the class C_k with largest posterior probability $p(C_k|\mathbf{x}) = \frac{p(\mathbf{x}|C_k)p(C_k)}{p(\mathbf{x})}$. Our KNN method assigns class membership under majority voting among the K-nearest neighbours to \mathbf{x}^p , where votes are weighted by the inverse of the distance of the neighbour to \mathbf{x}^p . This weighted voting method avoids classification indecision that would result from a possible tie between two or more classes among the K nearest neighbours of \mathbf{x}^p within an non-weighted voting system. MLP is a neural network with 2 hidden layers comprising 40 units each with hyperbolic tangent activation functions. It uses the generalized delta rule with backward propagation to adjust network weights, as well as L2 loss $E = \frac{1}{2} \sum_i (\mathbf{y}_i^p - \mathbf{V}_i^{\mathbf{M}})^2$ as an error measure, where y^p is the desired network output for training example \mathbf{x}^p and $\mathbf{V}^{\mathbf{M}}$ is the predicted output. For MB, since our feature space is 64-dimensional, N bins per dimension would require a minimum of N^{64} datapoints for the algorithm to be implemented. However, we only have 64,000 datapoints where $N^{64} \gg 64,000$ for $N \geq 2$, $N \in \mathbb{N}$, hence \mathbf{MB} is rejected.

The dataset was visualized following a brute-force approach where class-specific empirical distributions were plotted for each feature to identify class-specific trends (1) and assess class separability (2) to guide our choice of classification pipeline (3). We observe (1) that class 1 is generally multi-modal while other classes follow a skewed Gaussian or Poisson distribution (Table 1), hence we expect poor generalization of GG for class 1 as we are fitting a unimodal model to multimodal data. This may be mitigated by the generally good separability (2) of classes 1 and 2: their distribution, across features 1 to 60 (esp. 2, 5-6, 10, 13-14, 56, 58-60), rarely overlap with the distribution of any other class, while conversely classes 4 and 5 often overlap. Besides, we note that features 61 to 64 are poorly informative since datapoints are normally distributed around the same mean irrespective of the class. We therefore choose to discard these features in our classification pipeline as they result in additional system noise. Similarly, we can here note that if model simplicity and computational time were primary design objectives, we may consider ignoring the following redundant classes, for which the magnitude of the correlation coefficient with another feature exceeds 0.9: 4, 5, 6, 7, 10, 13, 18, 27, 30, 42.

Two pre-processing stages are applied to the training data (3): feature normalization and class balancing, defined here with special relevance to each classifier. Feature normalization is performed by **z-scoring** the training data, such that for each feature the mean value across training examples is 0 and standard deviation is 1, using $x_{out} = \frac{x_{in} - \mu_{in}}{\sigma_{in}}$, where μ_{in} and σ_{in} are stored and applied to the test data through the same transformation, such as to not introduce any bias. Centering all features on 0 prevents potentially unstable large bias terms in MLP, while scaling by the standard deviation prevents numerical explosion of the weights. It also ensures that all features contribute equally to the classification output in the case of KNN, given that the distance from a test data point to another training example is a priori of the same scale across all features/dimensions, and ensures numerical stability in the case of GG, since the exponential term in the expression of a multivariate Gaussian $p(x|C_k) = a \exp(\mathbf{x} - \mu)^T \Sigma_k^{-1}(\mathbf{x} - \mu)$ aggressively pushes $p(x|C_k)$ to ∞ or 0 if the term in the exponential is of large magnitude (which z-scoring avoids). More generally, scaling renders the features unit-independent.

Class balancing ensures that the training dataset contains equal number of datapoints for each class, which limits classification bias. Notably, Σ_k varies with sample size in GG, and similarly as K approaches the number of training examples belonging to class k, the bias in assigning membership to k with KNN becomes increasingly biased against this class. Class balancing was performed by extracting the number of training datapoints N_t for the least represented class and under-sampling the training dataset such that each class would be represented by N_t datapoints. This technique is fast and easy to implement, however in the unlikely case where

one class would be represented by exactly 1 datapoint, the Gaussian generative approach would fail, since extraction of a covariance matrix requires at least 2 datapoints (if K < 5, where 5 is the number of classes, then KNN would also fail). In the case of the KNN, we have chosen to implement class-balancing via a weighting of the vote of each datapoint by a class-dependant factor α_k reflecting class imbalance, such that α_k equals the ratio of the number of training datapoints for the most represented class to the number of training datapoints for class C_k .

Class	1	2	3	4	5			
Shape (% features)	Multimodal (89%)	Gaussian (76%)	Gaussian (90%)	Gaussian (94%)	Gaussian (94%)			
Separability (relative)	Excellent	Excellent	Good	Poor	Poor			

Table 1: Preliminary analysis of class-specific empirical trends in the unprocessed dataset

- 2. GG, KNN and MLP classifiers (described in the first paragraph of Question 1) were implemented, along with a GUI allowing for the selection of pre-processing steps (see appendix). Training algorithms were implemented for the parametric approaches: GG (class-specific mean μ_k and covariance Σ_k are trained) and MLP (weight matrix w and biases B are trained).
- 3. The classifiers were tested and validated using 10-fold cross-validation, using mean and standard deviation in test accuracy as performance parameters, along with the confusion matrix. During every 1 of the 10 validation tests 90% of the available data is used as training, such as to ensure good generalization properties, and the classifier performance is evaluated on the remaining 10% of the dataset, such as to limit bias in the estimation of classification error probability. We hence slightly value generalization over accuracy estimation bias.

The **choice of hyperparameters** was determined experimentally, taking maximization of mean accuracy and reduction of accuracy variability as performance parameters, leading to the choice K=5 for KNN. Although higher mean accuracy was observed for K<5, reducing K sacrifices resistance to outliers noise, hence we have chosen to settle for the plateau region at K=5 to ensure good generalization on noisy datasets (Figure 1). In addition, this ensures that the algorithm would not fail even in the unlikely scenario where the training dataset would contain only one example of each class. Similarly, we select $\eta=0.002$ and $\beta=0.6$ for the learning rate and activation gain of the units in MLP as they maximize test accuracy (Figure 2 and 3). The classifier performance was not improved when using a time-dependant learning rate in the form $\eta(t)=\frac{\eta_0}{t}$, where t is the number of epochs (classification accuracy under 10-fold cross-validation for $\eta_0=0.002$ of 94.1417 ± 0.9395 , compare against Table 2).

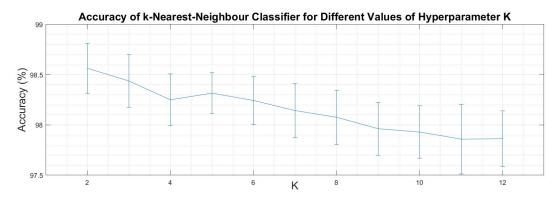


Figure 1: KNN accuracy under 10-fold cross-validation against K, highlighting optimal trade-off between smoothing effect of high K, minimal variance and maximal mean accuracy at K=5

The classifiers were evaluated to settle our choice of preferred classifier. Overall, KNN exhibits highest mean test accuracy (owing to large size of the training dataset) and lowest accuracy variance. In addition, KNN exhibits robustness to noise in training data resulting from the "smoothing" effect of increasing K, and benefits from the high quality of the available feature set which offers good class separability. Its computational cost is however high (n distance computation in 64-dimensions per test datapoint \mathbf{x} , where n is the number of training datapoints).

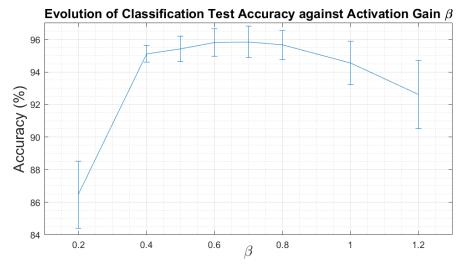


Figure 2: MLP accuracy under 10-fold cross-validation against β for $\eta = 0.002$, highlighting optimal trade-off between minimal accuracy variance and maximal mean accuracy at $\beta = 0.6$

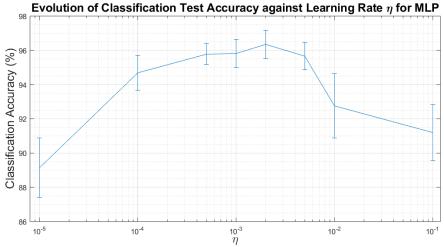


Figure 3: MLP accuracy under 10-fold cross-validation against η for $\beta = 0.6$, highlighting optimal trade-off between minimal accuracy variance and maximal mean accuracy at $\eta = 0.002$

Conversely, GG benefits in the classification step from independence of computational cost on n, however it generalizes more poorly than KNN due to the generally multimodal distribution of class 1 datapoints across features. Lastly, MLP benefits from increased model flexibility with two hidden layers enabling for fine tuning of nonlinear decision boundaries, which comes at the cost of highest computational load. MLP is expected to perform better than KNN/GG in the case of poorly separable classes, however owing to the advantageous feature set available for this classification problem, we observe that it is outperformed by KNN and GG. Besides,the confusion matrices indicate that MLP performs poorly on classification of class 5, with an error rate of 15.6379%. Overall, the error rate across classifiers is higher for classes 4 and 5, which is a consequence of the poor separability observed for these classes and discussed in Question 1. Consequently, KNN is selected as our preferred classifier, since it optimizes our design parameters of computational time minimization and generalization maximization expressed through the mean classification test accuracy.

Algorithm	GG					KNN					MLP						
Accuracy (%)	96.9625 ± 0.2549						98.2167 ± 0.2892					96.6042 ± 0.5275					
	99.9824	0.0176	0	0	0	[99	9.2167	0.8095	0	0	0	99.7921	0.1906	0	0.0173	0	
	0	.7658	0.2342	0	0	0	0.1946	99.4487	0.2757	0	0.0811	0.0486	99.4820	0.3885	0.0162	0.0647	
Confusion matrix (%)	0.0549	3.0569	96.6502	0.1098	0.1281	0	0.0725	0.7254	97.5517	0.8524	0.7980	0.2359	1.1432	97.3508	0.7984	0.4718	
	2.3035	0.2612	1.7098	91.948	4.6307		0	0	0	96.7383	3.2617	0	0	0.1656	95.3366	4.4978	
	0.0748	2.8432	1.1223	4.2649	91.6947	ΙL	0	0	0	3.2447	96.7553	0	0	0.0343	15.6036	84.3621	

Table 2: Comparison of generative Gaussian (GG), k-nearest neighbours (KNN) and multilayer perceptron (MLP) classifiers showing classification accuracy and confusion matrices, evaluated through 10-fold cross-validation

1 APPENDIX 4

1 Appendix

The fully annotated source code which generated the results discussed above is included below. This includes, in order: the function LookatData.m used to visualize the class-specific distribution of the dataset for each features (press any key to progress to the next feature), the GUI Main.m, used to select pre-processing steps as well as classifiers to be implemented, and computing classification accuracy for each trial through n-fold cross-validation as well as the confusion matrix accumulated over the n trials, and finally the training and classifying functions for GG, MLP and KNN, respectively named TrainsClassifierGCA.m, TrainsClassifierMLP, TrainClassifierX.m ClassifyGCA.m, ClassifyMLP and ClassifyX.m. Please note that only Main.m has to be run to access all training functions and classifiers.

```
%% COURSEWORK 2: HUMAN ACTIVITY RECOGNITION
%%% This is a function for preliminary visualization of the dataset.
%%% Bastien CABA, MEng Y4, CID: 01060785
%% IMPORT DATA
clearvars; clc; close all; load('data.mat'); %Clear workspace and command ✓
window, load data
                                                %Matrix containing features ∠
labels raw = data(:,1);
(columns) of datapoints (rows)
features raw = data(:,2:length(data(1,:))); %Column vector containing label of ✓
datapoints (rows)
%% SEPARATE FEATURE VALUES OF DATASET INTO INTO CLASSES AND PLOT CLASS-DEPENDANT 🗸
HISTOGRAM FOR EACH FEATURE
for feat = 1:64 %Iterate over features
    for i = 1:5 %Iterate over classes
        %Select datapoints belonging to this class
        X{i} = features raw((labels raw == i), feat);
    end
    fprintf('Press any key to progress to the next feature.');
    figure;
    %Display class-specific distribution for each feature
   histogram(X{1}); hold on;
   histogram (X\{2\}); histogram (X\{3\});
   histogram(X{4}); histogram(X{5});
    legend('Class 1', 'Class 2', 'Class 3', 'Class 4', 'Class 5');
    xlabel('Feature value'); ylabel('Number of occurences');
    title(['Class-specific data distributions for feature ', num2str(feat)]);
    clc;
end
pause;
fprintf('All features have been visualized.');
clc; close all;
```

```
%% COURSEWORK 2: HUMAN ACTIVITY RECOGNITION
%%% This is a GUI guiding through the classification pipeline.
%%% Bastien CABA, MEng Y4, CID: 01060785
%% IMPORT AND CROP DATA
clearvars; clc; close all; load('data.mat'); %Clear workspace and command ✓
window, load data
                                                 %Matrix containing features ∠
labels raw = data(:,1);
(columns) of datapoints (rows)
features raw = data(:,2:length(data(1,:))); %Column vector containing label of ✓
datapoints (rows)
%% SPLIT DATA IN TRAINING AND TESTING SETS FOR N-FOLD VALIDATION
% Get user input for k-cross validation
fprintf('The complete dataset will first be divided into a training subset and a <math>\checkmark
testing subset.\n');
prompt = 'Select K for K-fold cross-validation > ';
n = input(prompt);
clear prompt;
% Split the data
[data subsets] = split data(features raw, labels raw, n);
fprintf('The input data has been randomly partitioned into %d subsets in variable 🗸
data subsets.\n', n);
%% SELECT WHICH CODE TO RUN
% KNN
prompt = '\nDo you wish to run KNN (0:NO, 1:YES)? > ';
knn ctrl = input(prompt);
% GG
prompt = 'Do you wish to run GG (0:NO, 1:YES)? > ';
gg ctrl = input(prompt);
prompt = 'Do you wish to run MLP (0:NO, 1:YES)? > ';
mlp ctrl = input(prompt);
%% SELECT HYPERPARAMETER K for KNN (not applied since here to fit the classifier 🗸
format expected)
% if(knn ctrl == 1)
응
     % Get user input
응
     prompt = '\nSelect K for K-nearest-neighbour > ';
응
     k knn = input(prompt);
응
90
     % Pre-processing pipeline
9
     prompt = 'Do you wish to z-score the training data for KNN (0:NO, 1:YES)? > ✓
٠,
      standard knn = input(prompt);
응
00
      prompt = 'Do you wish to balance the training data for KNN (0:NO, 1:YES)? > ✓
١;
응
      balance knn = input(prompt);
% end
```

```
%% PRE-PROCESSING for GG
if(gg ctrl == 1)
    prompt = '\nDo you wish to z-score the training data for GG (0:NO, 1:YES)? > ';
    standard gg = input(prompt);
    prompt = 'Do you wish to balance the training data for GG (0:NO, 1:YES)? > ';
    balance gg = input(prompt);
    fprintf('The parameters for generative approach will now be trained.\n');
    fprintf('A Gaussian model is assumed for each class.\n');
end
%% PRE-PROCESSING for MLP
if(mlp ctrl == 1)
   prompt = '\nDo you wish to z-score the training data for MLP (0:NO, 1:YES)? > ✔
١;
    standard mlp = input(prompt);
    prompt = 'Do you wish to balance the training data for MLP (0:NO, 1:YES)? > ';
    balance mlp = input(prompt);
end
%% N-FOLD CROSS VALIDATION
for i = 1:n
    %% RESET TRAINING SETS
    train_input = []; train_output = [];
    %% SELECT TRAINING AND TEST DATASETS
    for j = 1:n
       if(j == i)
            test input = data subsets{j,1}; %One of the n subsets becomes the r
new test set
            test output = data subsets{j,2}; %Associate corresponding true ✓
labels
        else
            train input = [train input; data subsets{j,1}]; %Other subsets are *\'
training sets
            train output = [train output; data subsets{j,2}]; %Associate 
corresponding labels
        end
    end
    %% TRAIN THE CLASSIFIERS AND CLASSIFY THE TEST INPUT
    %% Generative Gaussian
    if(gg ctrl == 1)
        % Train the parameters (class mean and class covariance matrix)
        parametersGCA = TrainsClassifierGCA(train input, train output, standard gg, ✔
balance gg);
        % Classify the test dataset
        classGG = ClassifyGCA(test input, parametersGCA);
```

```
% Compute classification accuracy and confusion matrix
        [accuracyGG(i), confGG{i}] = accuracy(classGG, test output);
    end
    %% Multilayer Perceptron
    if(mlp ctrl == 1)
        % Train the parameters (weigths and bias in network)
        parametersMLP = TrainsClassifierMLP(train input, train output, ✓
standard mlp, balance mlp);
        % Classify the test dataset
        classMLP = ClassifyMLP(test input, parametersMLP);
        % Compute classification accuracy and confusion matrix
        [accuracyMLP(i), confMLP{i}] = accuracy(classMLP, test output);
    end
    %% K-nearest neighbours
    if(knn ctrl == 1)
        % Train the parameters for KNN
        parametersKNN = TrainClassifierX(train input, train output);
        % Classify the test dataset
        classKNN = ClassifyX(test input, parametersKNN);
        % Compute classification accuracy and confusion matrix
        [accuracyKNN(i), confKNN(i)] = accuracy(classKNN, test_output);
    end
end
%% NORMALIZE THE CONFUSION MATRICES
%% Generative Gaussian
if(gg ctrl == 1)
    %Display test classification accuracy
    fprintf('\nThe mean classification accuracy on test data for the generative &
Gaussian approach evaluated through %d-fold cross-validation is of %f, with %f ∠
standard deviation.', n, mean(accuracyGG), std(accuracyGG));
    % Initialize an empty confusion matrix of correct dimensions
    confusionGG = zeros(length(confGG\{1\}(:,1)), length(confGG\{1\}(1,:)));
    % Sum confusion matrices over all cross-validation trials
    for i = 1:n
        confusionGG = confusionGG + confGG{i};
    end
    % Normalize each term over total number of actual occurences
    for j = 1: length(confGG\{1\}(:,1))
        norm = sum(confusionGG(j,:));
        confusionGG(j,:) = (confusionGG(j,:)/norm)*100;
    end
    % Display confusion matrix
```

```
fprintf('\nThe confusion matrix accumulated over all trials of cross-validation ♥
for GG is given below: \n');
    confusionGG
end
%% K-nearest neighbours
if(knn ctrl == 1)
    %Display test classification accuracy
    fprintf('\nThe mean classification accuracy on test data for the k-nearest ¥
neighbours approach evaluated through %d-fold cross-validation is of %f, with %f 🗸
standard deviation.', n, mean(accuracyKNN), std(accuracyKNN));
    % Initialize an empty confusion matrix of correct dimensions
    confusionKNN = zeros(length(confKNN{1}(:,1)), length(confKNN{1}(1,:)));
    % Sum confusion matrices over all cross-validation trials
    for i = 1:n
        confusionKNN = confusionKNN + confKNN{i};
    end
    % Normalize each term over total number of actual occurences
    for j = 1: length(confKNN\{1\}(:,1))
       norm = sum(confusionKNN(j,:));
        confusionKNN(j,:) = (confusionKNN(j,:)/norm)*100;
    end
    % Display confusion matrix
    fprintf('\nThe confusion matrix accumulated over all trials of cross-validation ¥
for KNN is given below: \n');
    confusionKNN
end
%% Multilayer perceptron
if(mlp ctrl == 1)
    %Display test classification accuracy
    fprintf('\nThe mean classification accuracy on test data for the multi-layer &
perceptron approach evaluated through %d-fold cross-validation is of %f, with %f ✓
standard deviation.', n, mean(accuracyMLP), std(accuracyMLP));
    % Initialize an empty confusion matrix of correct dimensions
    confusionMLP = zeros(length(confMLP{1}(:,1)), length(confMLP{1}(1,:)));
    % Sum confusion matrices over all cross-validation trials
    for i = 1:n
        confusionMLP = confusionMLP + confMLP{i};
    end
    % Normalize each term over total number of actual occurences
    for j = 1:length(confMLP{1}(:,1))
        norm = sum(confusionMLP(j,:));
        confusionMLP(j,:) = (confusionMLP(j,:)/norm)*100;
    end
```

```
% Display confusion matrix
    fprintf('\nThe\ confusion\ matrix\ accumulated\ over\ all\ trials\ of\ cross-validation\ {\it v}
for MLP is given below: \n');
    confusionMLP
end
%% LIST OF SUB-FUNCTIONS
%% SPLITTING DATA IN N EQUALLY-SIZED SUBSETS
function [list_subsets] = split_data(data_input, data_output, n)
%% INITIALIZATION OF SUBSET LENGTH
len in = length(data input);
                                    %Number of datapoints in complete set
set_size = floor(len_in/n);
                                %Number of datapoints needed in each subset %Randomly shuffle data indices
elems = randperm(len in)';
%% CREATE N INDICES SUBSETS
for i = 1:n
    temp lim = (i-1)*set size+1:i*set size; %Boundaries element indices for ✓
each subset
    data list{i} = elems(temp lim);
                                         %List of elements in each of the n ∠
subsets
end
%% APPEND REMAINING INDICES TO LAST SUBSET
data list\{n\} = [data list\{n\}; elems\{n*set size+1:length\{data input\}\};
%% CREATE N DATA SUBSETS
for i = 1:n
    list subsets{i,1} = data input(data list{i},:);
    list subsets{i,2} = data output(data list{i},:);
end
end
%% CLASSIFICATION TEST ACCURACY COMPUTATION
function [performance, conf] = accuracy(actual, predicted)
% Initialize variables
count = 0; conf = [];
% Count number of correct predictions
for i = 1:length(actual)
    if(actual(i) == predicted(i))
        count = count + 1;
    end
end
% Compute percentage of correct predictions and confusion matrix
performance = (count/length(predicted))*100;
conf = confmat(actual, predicted);
end
%% CONFUSION MATRIX COMPUTATION
function [confusion] = confmat(vec actual, vec predicted)
% Indentify classes present in predicted and actual vectors
```

```
classes_actual = unique(vec_actual);
classes predicted = unique(vec predicted);
% Initialize confusion matrix
confusion = zeros(length(classes_actual), length(classes_predicted));
% Compute number of actual/predicted class occurences
for i = 1:length(vec_predicted)
     \texttt{confusion}\,(\texttt{vec\_actual}\,(\texttt{i})\,,\,\,\texttt{vec\_predicted}\,(\texttt{i})\,)\,\,=\,\,\texttt{confusion}\,(\texttt{vec\_actual}\,(\texttt{i})\,,\,\, \checkmark\,\,
vec_predicted(i)) + 1;
end
end
```

```
%% TRAINING PARAMETERS FOR GCA (generative classification approach)
    %%% We define one class probability distribution model per class (Gaussian {m arepsilon}
model assumed)
       %%% Each class probability distribution model has 2 parameters (mean and 🗸
covariance)
% IN: "inputs" is a matrix containing features (columns) of datapoints (rows)
% IN: "outputs" is a column vector containing the class of each data point (rows)
% IN: "standard" is a boolean control determining whether data should be z-scored
% IN: "balance" is a boolean control determining whether the testing set should be oldsymbol{arepsilon}
class-balanced
function parameters = TrainsClassifierGCA(inputs, outputs, standard, balance)
%% STEP 0: REMOVE NON-INFORMATIVE FEATURES
inputs = inputs(:,1:60); %Remove features 61 to 64
%% EXTRACT DATA INFO
info = data info(inputs, outputs);
num classes = info{3};
                          %Number of classes in test set
num features = info{2}; %Number of features in datapoints from test set
num_datapoints = info{1};  %Number of datapoints in test set
%% Z-SCORING (PRE-PROCESSING STEP)
if(standard == 1)
    [inputs, param z] = z standard(inputs);
    fprintf('The data was z-scored.\n');
else
    fprintf('The data was not z-scored.\n');
    [temp, param z] = z standard(inputs);
    clear temp;
end
%% BALANCING (PRE-PROCESSING STEP)
if(balance == 1)
    [inputs, outputs, num datapoints] = balances(inputs, outputs, info);
    fprintf('The data was balanced.\n');
else
    fprintf('The data was not balanced.\n');
clear balance;
%% INITIALIZE PARAMETERS
parameters{1} = zeros(num classes, num features);
                                                                  %Feature means≰
(column) per class (row)
parameters{2} = zeros(num features, num features, num classes);
                                                                   %Inverse∠
covariance per class
parameters{3} = class names;
                                                                   %Class names
parameters{4} = zeros(1, num classes);
                                                                   %Class prior ∠
probabilities
parameters{5} = repmat(inv(cov(inputs)),[1 1 num_classes]);
                                                                  %Covariance∠
matrix computed over all input data
                                                                   %Indicates if ∠
parameters(6) = standard;
```

```
inputs were z-scored
                                                                        %Parameters for∠
parameters{7} = param z;
z-score
p class = zeros(1, num classes);
                                                                        %Temporary ∠
class probability
means temp = zeros(num classes, num features);
                                                                        %Temporary ∠
invcov temp = zeros(num features, num features, num classes);
                                                                        %Temporary ∠
inverse covariance
%% COMPUTE MEAN AND COVARIANCE
                       %Iterate over classes
for i = 1:num classes
    %Select datapoints belonging to this class
    X = inputs((outputs == class names(i)),:);
    fprintf('The training dataset contains %d points that belong to class %d.\n', &
length(X), class names(i));
    %Compute class mean and inverse covariance for feature across datapts
    means temp(i,:) = mean(X);
                                         %Mean
    invcov_temp(:,:,i) = inv(cov(X)); %Inverse covariance
    %Probability of observing each class
    p class(i) = length(X)/num datapoints;
end
%% SET PARAMETERS
parameters{1} = means_temp; %Class-specific mean across features
parameters{2} = invcov_temp; %Class-specific inverse covariance matrix
                                %Prior probability of each class
parameters{4} = p class;
end
function [info] = data info(inputs, outputs)
%% EXTRACT BASIC DATA INFO
[num datapts, num features] = size(inputs);
                                                      %Number of datapoints and ✓
number of features
class names = unique(outputs)';
                                                       %Name of classes
num class = length(class names);
                                                       %Number of classes
%% DISPLAY DATA INFO
fprintf('The complete dataset contains %d data points with %d features.\n', \script
num datapts, num features);
class string = sprintf('%d', class names);
fprintf('There are %d different classes observed in the training dataset, which can ¥
be: %s\n\n', num_class, class_string);
%Return an array with information on data
info = {num datapts, num features, num class, class names};
end
%% FUNCTION TO Z-SCORE DATA
```

```
function [feat z, param z] = z standard(inputs)
%% Z-SCORE DATA, STORE PARAMETERS
[feat z, mu, sigma] = zscore(inputs);
param z = [mu; sigma];
end
%% FUNCTION TO CLASS-BALANCE A SET
function [feat bal, label bal, num datapts bal] = balances(inputs, outputs, info)
%% BALANCE INPUTS SO EACH CLASS IS EQUALLY REPRESENTED
class names = info{4};
num class = info{3};
original length = length(outputs); %Original length of test dataset
for i = 1:num class
   temp = inputs((outputs == class names(i)),:);
   count class(i) = length(temp);
end
%% SELECT NUM OF ELEM IN LEAST REPRESENTED CLASS AND BALANCE INPUTS
min_length = min(count_class); %Number of elements in least represented class
bal inputs = []; bal outputs = []; %Initialize new empty sets
for i = 1:num class %Iterate over classes
   order inputs = inputs((outputs == class names(i)),:);
                                                           %Select inputs ¥
with that class
   min length datapoints of that class
   bal outputs = [bal outputs; class names(i) *ones(min length,1)]; %Associate ▶
corresponding labels
end
                                   %OUTPUT: Original dataset cropped so that ∠
feat bal = bal inputs;
every class has as many datapoints as the least represented class
                                 %OUTPUT: Corresponding labels
label bal = bal outputs;
num datapts bal = length(label bal); %New size of the training set
%% DISPLAY NEW INFORMATION
fprintf('The training dataset now contains %d datapoints, reduced from the original ₹
%d.\n', num datapts bal, original length);
```

```
%% Training Perceptron Learning
%%% This function trains the parameters for multilayer perceptron classification
%%% The parameters are network weights which best separate the training data into {m arphi}
classes
%%% The input variable "inputs" is a matrix containing features (second dimension) {m \ell}
of data points (first dimension)
%%% The input variable "outputs" is a column vector containing the class of each {m arepsilon}
data point
function parameters = TrainsClassifierMLP(inputs, outputs, standard, balance)
%% STEP 0: REMOVE NON-INFORMATIVE FEATURES
inputs = inputs(:,1:60); %Remove features 61 to 64
%% EXTRACT DATA INFO
info = data info(inputs, outputs);
class names = info{4}; %Vector containing name of classes
num datapoints = info{1};  %Number of datapoints in training set
%% SELECT IF DATA MUST BE BALANCED AND/OR Z-SCORED
fprintf('The parameters for multilayer perceptron learning will now be trained. &
\n');
if(standard == 1)
    [inputs, param z] = z standard(inputs);
    fprintf('The data was z-scored.\n');
else
    fprintf('The data was not z-scored.\n');
    [temp, param z] = z standard(inputs);
    clear temp;
end
if(balance == 1)
    [inputs, outputs, num datapoints] = balances(inputs, outputs, info);
    fprintf('The data was balanced.\n');
else
    fprintf('The data was not balanced.\n');
end
clear balance;
%% INITIALIZE HYPERPARAMETERS
nabla = 0.002; %Learning rate (not called eta to limit chances of mistaking it \mathbf{r}
with beta)
               %Activation gain
beta = 0.6;
nbrOfNodes = [num_features, 40, 40, num_classes]; %Nodes per layer
nbrOfLayers = length(nbrOfNodes);
                                                  %Number of layers
tol = 0.0001; error = tol + 1; %Tolerance in the network output error
epoch = 0; max epoch = 200; %Max epochs if weights have not converged
%%% Initialize random weight matrices with small magnitude terms
%%% Weights are all between -1 and +1
%%% E.G. Weight matrix 1 connects layer 1 to 2
```

```
for m = 1:(nbrOfLayers-1)
   w{m} = rand(nbrOfNodes(m+1), nbrOfNodes(m)) - rand(nbrOfNodes(m+1), nbrOfNodes ♥
   B{m} = rand(nbrOfNodes(m+1),1) - rand(nbrOfNodes(m+1),1);
%% FORWARD AND BACKWARD PASS FOR EACH TRAINING POINT
while((error>tol)&&(epoch<max epoch)) %Check for weights convergence and number ⊌
of epochs
   LayerInput{1} = inputs(training,:)'; %Input to the first layer is a new ✓
test datapoint
       ActualOutput = outputs(training); %Associate corresponding label
       % Compute desired network output
       TargetOut = zeros(num classes, 1); %Initialiwe desired output
       for class = 1:num classes
          if(class == ActualOutput)
              TargetOut(class) = 0.95; %Network should output close to +1 for ✔
the neuron associated with the correct class
          else
              TargetOut(class) = -0.95; %Network should output clsoe to -1 for \checkmark
the neurons associated with any other class
          end
       end
       %% FORWARD PASS
       for layer = 1:(nbr0fLayers-1) %Iterate over layers
          input = LayerInput{layer};  %Select input to that layer
          the next
          u{layer+1} = weights*input + B{layer};
                                                             %Compute∠
activity of next layer
          LayerOutput{layer+1} = activation(u{layer+1}, beta); %Compute 
activation of next layer
          LayerInput{layer+1} = LayerOutput{layer+1};
                                                             %Activation of ∠
one layer is input to the next
       end
       %% COMPUTE ERROR
       output = LayerOutput{nbrOfLayers};
                                                  %Network output is the ∠
output of the last layer
       error = (1/2) * (sum((TargetOut - output).^2)); %Compute L2 loss between ▶
predicted and actual output
       %% BACKWARD PASS (Generalized delta rule)
       Delta{nbrOfLayers} = deriv activation(u{nbrOfLayers}, beta).*(TargetOut- \( \mu \)
output); %COmpute deltas for output layer
      for layer = (nbr0fLayers-1):-1:2
                                                              %Iterate over∠
layers backwards
          gradient = deriv_activation(u{layer}, beta);
                                                              %Compute∠
activation function gradient at the unit activity for each layer
```

```
Delta{layer} = gradient.*(Delta{layer+1}'*w{layer})'; %Back-propagate \( \varphi \)
errors
        end
        %% UPDATE WEIGHTS
        for Layer = 1:nbrOfLayers-1
            w{layer} = w{layer} + nabla*(Delta{layer+1}*LayerInput{layer}');
            B{layer} = B{layer} + nabla*Delta{layer+1};
    end
end
%% Parameters
                                 %Weight matrix
parameters{1} = w;
parameters{2} = class_names; %Vector of class names
parameters{3} = param z; %Parameters for z-scor
parameters{3} = param z;
                                  %Parameters for z-scoring
parameters{4} = standard;
                                %Control indicating whether test data should be z- ¥
scored
parameters{5} = nbrOfLayers; %Number of network layers
                                 %Activation gain beta
parameters{6} = beta;
                                  %Network biases
parameters{7} = B;
end
%% NEURON ACTIVATION FUNCTION
function [output] = activation(input, beta)
output = tanh((beta/2)*input);
end
%% GRADIENT OF NEURON ACTIVATION FUNCTION
function [output] = deriv activation(input, beta)
output = (beta/2) * (1 - (tanh ((beta/2) * input) .^2));
%% PREPROCESSING FUNCTIONS
function [info] = data info(inputs, outputs)
%% EXTRACT BASIC DATA INFO
[num datapts, num features] = size(inputs);
                                                       %Number of datapoints and ∠
number of features
class names = unique(outputs)';
                                                       %Name of classes
num class = length(class names);
                                                       %Number of classes
%% DISPLAY DATA INFO
fprintf('The complete dataset contains %d data points with %d features.\n', 
✓
num datapts, num features);
class string = sprintf('%d', class names);
fprintf('There are %d different classes observed in the training dataset, which can <math>oldsymbol{arepsilon}
be: %s\n\n', num class, class string);
info = {num datapts, num features, num class, class names};
end
```

```
function [feat z, param z] = z standard(inputs)
%% Z-SCORE DATA, STORE PARAMETERS
[feat z, mu, sigma] = zscore(inputs);
param_z = [mu; sigma];
%% FUNCTION TO CLASS-BALANCE A SET
function [feat bal, label bal, num datapts bal] = balances(inputs, outputs, info)
%% BALANCE INPUTS SO EACH CLASS IS EQUALLY REPRESENTED
class names = info{4};
num class = info{3};
original length = length(outputs); %Original length of test dataset
for i = 1:num class
   temp = inputs((outputs == class names(i)),:);
   count class(i) = length(temp);
end
%% SELECT NUM OF ELEM IN LEAST REPRESENTED CLASS AND BALANCE INPUTS
min length = min(count class); %Number of elements in least represented class
bal inputs = []; bal outputs = []; %Initialize new empty sets
for i = 1:num class %Iterate over classes
   order inputs = inputs((outputs == class names(i)),:);
                                                        %Select inputs≰
with that class
   min length datapoints of that class
   bal outputs = [bal outputs; class names(i) *ones(min length,1)]; %Associate ▶
corresponding labels
end
feat_bal = bal inputs;
                             %OUTPUT: Original dataset cropped so that ∠
every class has as many datapoints as the least represented class
num datapts bal = length(label bal); %New size of the training set
%% DISPLAY NEW INFORMATION
fprintf('The training dataset now contains %d datapoints, reduced from the original ✓
%d.\n', num datapts bal, original length);
end
```

```
%% TRAINING PARAMETERS KNN (k-nearest-neighbour)
%%% 1. PRE-PROCESSING: Remove non-informative features 61-64
%%% 2. PRE-PROCESSING: Z-score the training data
%%% 3. PRE-PROCESSING: Store mean and standard deviation to Z-score the testing {m \ell}
data in the same way
%%% 4. PRE-PROCESSING: Compute coefficient alpha accounting for class imbalance
%%% IN: "input" is a matrix containing the training datapoints as rows
%%% IN: "label" is a vector containing the class of each training datapoint
%%% OUT: "parameters" is an array containg trained parameters for KNN 🗸
classification
function [parameters] = TrainClassifierX(input, label)
%% STEP 0: REMOVE NON-INFORMATIVE FEATURES
input = input(:,1:60);
                                  %Remove features 61 to 64
%% STEP 1: EXTRACT DATA INFO
info = data info(input, label); %Extracts/displays training dataset information
%% STEP 2: DATA PREPROCESSING
% Z-SCORING TRAINING SET AND STORING PARAMETERS
[input, param z] = standardize(input);
clear standard; fprintf('The data was z-scored.\n');
% COMPUTING ALPHA COEFFICIENTS FOR CLASS-BALANCING
[alpha] = balances(input, label, info);
fprintf('The data was class-balanced.\n');
% RE-COMPUTING DATA INFO
info = data info(input, label);
                               %Extracts/displays training dataset information
%% STEP 3: ASSIGNING PARAMETERS
parameters{1} = input; %Pass on pre-processed training set
%Pass on data information
parameters{4} = info;
parameters{5} = label; %Pass on training dataset labels
end
%% THIS FUNCTION EXTRACTS BASIC INFORMATION ON A DATASET
function [info] = data info(inputs, outputs)
[num datapts, num features] = size(inputs); %Number of datapoints and number of \checkmark
features
class_names = unique(outputs)';
                                              %Name of classes
num class = length(class names);
                                              %Number of classes
%% DISPLAY DATA INFO
fprintf('The complete dataset contains %d data points with %d features.\n', \mu
num datapts, num features);
class string = sprintf('%d', class names);
```

```
fprintf('There are %d different classes observed in the training dataset, which can ¥
be: %s\n\n', num class, class string);
info = {num datapts, num features, num class, class names};
end
%% THIS FUNCTION Z-SCORES DATA, STORE PARAMETERS MEAN AND STD
function [feat_z, param_z] = standardize(inputs)
[feat z, mu, sigma] = zscore(inputs);
param z = [mu; sigma];
end
%% THIS FUNCTION COMPUTES COEFFICIENTS ALPHA REFLECTING CLASS IMBALANCE
function [alpha] = balances(inputs, outputs, info)
%% EXTRACT INFORMATION ON DATASET
class names = info{4};
                                                     Class names (1, 2, 3, 4, 5)
                                                     %Number of classes (5)
num class = info{3};
%% COUNT NUMBER OF ELEMENTS PER CLASS
                                                     %Initialize vector of number of ∠
count class = zeros(1, num class);
datapoints per class
for i = 1:num class
                                                     %Iterate over classes
    temp = inputs((outputs == class names(i)),:);
                                                    %Select all training datapoints ¥
from that class
   count class(i) = length(temp);
                                                     %Count number of elements per ∠
class
end
%% COMPUTE ALPHAS
alpha = zeros(1, num class);
                                                     %Initialize vector of alpha ✔
coefficient per class
maxElements = max(count class);
                                                     %Compute number of elements in ∠
most represented class
for i = 1:num class
                                                     %Iterate over classes
    alpha(i) = maxElements/count class(i);
                                                     %Ratio of number of elements in ∠
most represented class to number of elements in that class
end
end
```

```
%% CLASSIFIER GCA (generative classification approach, using trained parameters)
%%% Define 1 class probability distribution model per class (Gaussian model 🗸
assumed)
%%% Compute posterior probability of point "input" to belong to class Ck
%%% Classification rule: classify "input" with class with largest posterior ¥
priority
%%% IN: "input" is a row vector containing features of one data point
%%% IN: "parameters" is an array containing trained parameters
function [class] = ClassifyGCA(input, parameters)
%% STEP 0: REMOVE NON-INFORMATIVE FEATURES
input = input(:,1:60);
                                  %Remove features 61 to 64
%% EXTRACT PARAMETERS
means = parameters{1};
                                    %MEANS
inv cov class = parameters{2};
                                  %INVERSE COVARIANCE (PER CLASS)
class names = parameters{3};
                                    %CLASS NAMES
p class = parameters{4};
                                   %PRIOR CLASS PROBABILITIES
inv_cov_global = parameters{5}; %INVERSE COVARIANCE (GLOBAL)
standard = parameters{6};
                                   %SHOULD DATA BE Z-SCORED
param z = parameters{7};
                                   %PARAMETERS FOR Z-SCORE
%% SELECT COVARIANCE
cov = 0;
if(cov == 1)
    inv cov = inv cov global;
    fprintf('The global covariance will be used.\n');
else
    inv_cov = inv_cov_class;
    fprintf('The covariance per class will be used.\n');
clear cov;
%% EVALUATE EACH CLASS-SPECIFIC GAUSSIAN AT TEST DATAPOINT
[num class, num features] = size(means);
for test = 1:length(input) %Iterate over test datapoints
    %% Z-SCORING
    if(standard == 1)
        input(test,:) = (input(test,:) - param_z(1,:))./(param_z(2,:));
    end
    %% COMPUTE PRIOR P(input|Ck)
    px_given_class = zeros(1,num_class);
    for c = 1:num_class %Iterate over classes
        px given class(c) = \exp((-1/2)*(input(test,:)-means(c,:))*inv cov(:,:,c)*
(input(test,:)-means(c,:))'); %Gaussian model assumption
        % NOTE : the exponential agressively pushes large magnitude number to 0 or \checkmark
+infinity
        % Also p(x|Ck) is interpreted for one class with respect to others and \mathbf{k}'
exponential is monotonic
```

```
end
```

```
%% NORMALISATION
px_given_class = px_given_class/sum(px_given_class);

%% POSTERIOR PROBABILITY
% We ignore marginal p(x) since it will be the same across classes
pclass_given_x = px_given_class.*p_class;

% Class which maximizes posterior probability
[max_p, idx] = max(pclass_given_x); % Assign class according to highest \( \mu \)
posterior probability of belonging to that class
DoB = max_p/sum(pclass_given_x); % Normalised degree of belief
class(test) = class_names(idx);
fprintf('This datapoint was classified with %.2f percent certainty as belonging \( \mu \)
to class %d.\n', DoB*100, class(test));
end
class = class';
end
```

```
%% CLASSIFIER MLP (multi-layer perceptron)
%%% 1. Forward-propagate test datapoint through the network using trained weights m{arepsilon}
and biases
%%% 2. The softmax function is applied to the network output
%%% 3. The neuron with the highest probability of datapoint belonging to its
%%% corresponding class is selected to assign class membership of test datapoint
%%% IN: "inputs" is a list of test datapoints (vectors of values among features)
%%% IN: "parameters" is an array containing parameters trained using TrainsMLP()
function [class, p max] = ClassifyMLP(inputs, parameters)
%% STEP 0: REMOVE NON-INFORMATIVE FEATURES
inputs = inputs(:,1:60);
                               %Remove features 61 to 64
%% Extract and assign trained parameters
W = parameters{1};
                      %Network weights
NameOfClasses = parameters{2}; %Vector containing names of classes
MeanAndStdZ = parameters{3}; %Mean and standard deviation of training dataset ✓
used to z-score the test dataset
should be z-scored
nbrOfLayers = parameters{5}; %Number of network layers
beta = parameters{6}; %Activation gain beta
B = parameters{7};
                               %Networks biases
%% Z-SCORE TEST DATASET (PRE-PROCESSING)
for i = 1:length(inputs) %Iterate over the full test dataset
    %% Z-SCORE
    if(standardize == 1)
        inputs(i,:) = (inputs(i,:) - MeanAndStdZ(1,:))./(MeanAndStdZ(2,:));
    end
    %% FORWARD PASS
    LayerInput{1} = inputs(i,:)'; %Layer input is one test datapoint
    for layer = 1:(nbrOfLayers-1) %Iterate over network layers
       input = LayerInput{layer}; %Assign input to that layer
                                  %Assign weight connecting that layer to next
        weights = W{layer};
       u{layer+1} = weights*input + B{layer};
                                                              %Compute layer≰
activity
        LayerOutput{layer+1} = activation(u{layer+1}, beta); %Compute layer ✓
activation
                                                              %Output of one ∠
       LayerInput{layer+1} = LayerOutput{layer+1};
layer is input to the next
   end
    %% CLASS ASSIGNMENT
    output = exp(u{nbrOfLayers})./sum(exp(u{nbrOfLayers}));
                                                              %Softmax operator

✓
(convert data over range [-1:+1] to range [0:1])
                                                               %Neuron with∠
    [p \max(i), class(i)] = \max(output);
highest activation assigns class membership of test datapoint
end
class = class';
end
```

```
%% NEURON ACTIVATION FUNCTION
function [output] = activation(input, beta)
output = tanh((beta/2)*input);
end
```

```
%% CLASSIFIER KNN (k-nearest-neighbour)
%%% 1. Extract parameters trained through TrainClassifierX
%%% 2. Pre-process the test data through z-scoring with trained parameters
%%% 3. Identify k training datapoints that are closest to test data point
%%% 4. Vote of each neighbour is weighted by inverse square distance to the test m{arepsilon}
datapoint
%%% 5. Assign class according to voting majority class membership among the k {m \prime}
neighbours
%%% NOTE: We use euclidian distance as metric
%%% IN: "input" is a matrix containing test datapoint as rows
%%% IN: "parameters" is a set of trained parameters from TrainClassifierX
%%% OUT: "label" is a vector containing the predicted class of each test datapoint
function [label] = ClassifyX(input, parameters)
%% STEP 0: REMOVE NON-INFORMATIVE FEATURES
                      %Remove features 61 to 64
input = input(:,1:60);
%% STEP 1: EXTRACT PARAMETERS
                                %Pre-processed training set %Parameters for z-scoring test datapoints
training set = parameters{1};
param z = parameters{2};
%SET HYPERPARAMETER K
K = 5;
%Extract basic informations about training dataset
nbrOfTrainDatapoints = info{1}; %Number of training examples
                         %Size of feature space
%Number of possible classes
nbrOfFeatures = info{2};
nbrOfClasses = info{3};
                                 %Names of classes
ClassNames = info{4};
%% STEP 2: CLASSIFIER
%% STEP 2.1: PREPROCESSING (z-score test datapoint with parameters learnt on ✓
training set)
   input(test,:) = (input(test,:) - param z(1,:))./(param z(2,:));
   %% STEP 2.2: COMPUTE DISTANCE OF TEST DATAPOINT TO ALL TRAINING DATAPOINTS
   distance = zeros(1,nbrOfTrainDatapoints);
                                                                %Initialize∠
vector of distances of test datapoint to all training datapoints
   for i = 1:nbrOfTrainDatapoints
                                                                %Iterate over∠
training datapoints
       distance(i) = norm(input(test,:) - training_set(i,:)); %Euclidian ✔
distance
   end
    [dist order, idx] = sort(distance, 'ascend');
                                                                %Organize∠
distances in ascending order
    %% STEP 2.3: IDENTIFY CLASS OF K-NEAREST NEIGHBOURS
    class neighbours = zeros(2,K);
                                                         %Initialize vector of ¥
```

```
class name and vote weight (first and second rows) for each neighbour (columns)
    for j = 1:K
                                                           %Iterate over∠
neighbours
       class_neighbours(1,j) = training_labels(idx(j));
                                                          %Store class of ∠
neighbour
       %Store weight of neighbour vote including alpha and distance criteria
       class neighbours(2,j) = alpha(class neighbours(1,j))/dist order(j);
   end
    %% STEP 2.4: COMPUTE VOTE PER CLASS
   NeighboursClasses = unique(class neighbours(1,:)); %Classes expressed amongst ¥
neighbours
   vote = zeros(2,length(NeighboursClasses));
                                                       %Intialize vote per class
   for elem = 1:length(NeighboursClasses)
                                                       %Iterate over classes ¥
represented amonst neighours
      vote(1,elem) = NeighboursClasses(elem); %Accumulate weighted votes ✓
for each class
       for i = 1:length(class neighbours)
                                                      %Iterate among K-nearest- 🗸
neighbours
           if(class_neighbours(1,i) == NeighboursClasses(elem))
               %Aggregate vote for each class among K-nearest neighbours
               vote(2,elem) = vote(2,elem) + class neighbours(2,elem);
           end
       end
    end
    %% ASSIGN CLASS BASED ON MAJORITY VOTING
    [val, idx max] = max(vote(2,:)); clear val;
    label(test) = vote(1, idx max);
end
label = label';
end
```