

# Package ‘lsmnsd’

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**Title** Classify movement strategies using latent-state model and NSD

**Version** 0.0.0.9000

## Description

This package provides a series of functions to analyse animal movement strategies using a latent-state model and net squared displacement.

References: Bastille-Rousseau, G., Potts, J., Yackulic, C., Frair, J., Ellington, E.H., Blake, S. (In review) Characterizing movement strategies of Galapagos giant tortoises using a Bayesian mixture distribution model and net squared displacement. Movement Ecology

**Depends** R (>= 3.2.3)

**License** GPL (>=3)

**LazyData** true

**RoxygenNote** 5.0.1

**Imports** R2jags

## R topics documented:

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bootNSD	<i>Iterative latent-state model of NSD</i>
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**Description**

Bootstrap latent-state model by changing starting locations

**Usage**

bootNSD(x, y, day, interval = 30, by = 5, n.iter = 20000, ...)

**Arguments**

- |          |   |
|----------|---|
| x,       | y, time, information on locations and time (continuous)   |
| interval | Amount of variation in time to be tested  |
| by       | Time step between each iteration (number of iterations is a function of the interval and time step) |
| n.iter   | number of total iterations per chain (including burn in; default: 5000)                             |

**Value**

A boot.clust object

**Examples**

```
data(Christian)
#May results in low convergence given low number of iterations
boot1<-bootNSD(Christian$x[1:300], Christian$y[1:300], Christian$Time[1:300], interval=20, by=5, n.iter=1000)
summary(boot1)
plot(boot1)
```

---

breaks	<i>Calculating transitions between clusters</i>
--------	---

---

**Description**

Calculating pattern of transitions among cluster

**Usage**

```
breaks(object)
```

**Arguments**

object            an object of class "mov.clust" or "rjags"

**Examples**

```
data(Zelfa_rjags)
breaks(Zelfa_rjags)
```

---

Christian	<i>Christian - daily spatial locations</i>
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---

**Description**

A dataset containing the x, y locations (UTM), and time of Christian, a male giant tortoises inhabiting Alcedo volcano on Isabela Island, Galapagos.

**Usage**

```
Christian
```

**Format**

A data frame with 1536 rows and 3 variables (x, y, time)

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Christian_rjags	<i>Latent-state model applied to Christian</i>
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---

**Description**

The output of clustNSD function applied to Christian.

**Usage**

```
Christian_rjags
```

**Format**

A "rjags" object

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classify	<i>Classify movement strategies</i>
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---

### Description

Extract information to classify movement strategies

### Usage

```
classify(object, grph = F, ...)
```

### Arguments

object	an object of class "mov.clust" or "rjags"
grph	Produce a graph of classification (Default = F)

### Value

A clust.classify object

### Examples

```
data(Christian_rjags)
summary(classify(Christian_rjags))
data(Zelfa_rjags)
summary(classify(Zelfa_rjags))
```

---

clustNSD	<i>Latent-state model of NSD</i>
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---

### Description

Perform latent-state model to characterize movement patterns based on NSD

### Usage

```
clustNSD(data, WAIC = FALSE, n.iter = 5000, n.chains = 3,
  n.burnin = floor(n.iter/2), n.thin = max(1, floor((n.iter -
  n.burnin)/1000)), simplify = FALSE, sigma1.max = 0.1, sigma2.max = 0.1,
  sigma1.min = 0.001, sigma2.min = 0.001, mu1.max = 0.5, mu2.max = 1,
  mu1.min = 0, mu2.min = 0, ...)
```

**Arguments**

data	a maxtrix with x,y, and time columns
WAIC	save log-likelihood of every iteration to allow calculations of WAIC, default=FALSE
n.iter	number of total iterations per chain (including burn in; default: 5000)
n.chains	number of Markov chains (default: 3)
n.burnin	length of burn in, i.e. number of iterations to discard at the beginning. Default is n.iter/2, that is, discarding the first half of the simulations. If n.burnin is 0, jags() will run 100 iterations for adaption.
n.thin	thinning rate. Must be a positive integer. Set n.thin > 1 to save memory and computation time if n.iter is large. Default is max(1, floor(n.chains * (n.iter - n.burnin) / 1000)) which will only thin if there are at least 2000 simulations.
simplify	Convert output to mov.clust object. Default=FALSE. See simple.clust for details
sigma1.max	Upper limit of uniform prior for SD of first normal distribution (Default=0.1)
sigma2.max	Upper limit of uniform prior for SD of second normal distribution (Default=0.1)
sigma1.min	Lower limit of uniform prior for SD of first normal distribution (Default=0.001)
sigma2.min	Lower limit of uniform prior for SD of second normal distribution (Default=0.001)
mu1.max	Upper limit of uniform prior for mean of first normal distribution (Default=0.5)
mu2.max	Upper limit of uniform prior for difference between mean of first and second normal distribution (Default=1)
mu1.min	Lower limit of uniform prior for mean of first normal distribution (Default=0.001)
mu2.min	Lower limit of uniform prior for difference between mean of first and second normal distribution (Default=0)

**Value**

A rjags or mov.clust object

**Examples**

```
data(Christian)
nsd1<-NSD_fct(Christian$x, Christian$y)
Christian_rjags<-clustNSD(cbind(range01(nsd1), Christian$Time), n.iter=10000, WAIC=T, simplify=F)
summary(simple.clust(Christian_rjags))
data(Zelfa)
nsd2<-NSD_fct(Zelfa$x, Zelfa$y)
Zelfa_rjags<-clustNSD(cbind(range01(nsd2), Zelfa$Time), n.iter=10000, WAIC=F, simplify=F)
summary(simple.clust(Zelfa_rjags))
```

---

colVars

---

*Posterior variances*


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**Description**

Function to calculate posterior variances from simulation. Based on script initially written by Andrew Gelman

**Usage**

```
colVars(a)
```

**Arguments**

a                      A matrix

**Examples**

```
mat<-matrix(rnorm(20), nrow=10, ncol=2)
```

---

Dist_fct	<i>Calculate euclidean distance</i>
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---

**Description**

This function calculates euclidean distance between spatial locations

**Usage**

```
Dist_fct(x, y)
```

**Arguments**

x, y                      Spatial locations

**Examples**

```
data(Christian)
hist(Dist_fct(Christian$x, Christian$y))
```

---

lsmnsd	<i>lsmnsd: A package for classifying animal movement strategies based on latent-space model and net squared displacement.</i>
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**Description**

The lsmnsd package provides four categories of important functions: clustNSD, simple.clust, classify, bootNSD.

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Mode	<i>Mode</i>
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---

**Description**

This function finds the mode of a vector

**Usage**

```
Mode(x)
```

**Arguments**

x	A vector
---	----------

**Examples**

```
v<-c(1,2,2,3,4,4,4,4,5,6)
Mode(v)
```

---

NSD_fct	<i>Calculate NSD</i>
---------	----------------------

---

**Description**

This function calculates NSD from a time-series of spatial locations

**Usage**

```
NSD_fct(x, y)
```

**Arguments**

x, y	Spatial locations
------	-------------------

**Examples**

```
data(Christian)
ts.plot(NSD_fct(Christian$x, Christian$y))
```

---

plot.boot.clust	<i>Plotting boot.clust object</i>
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---

**Description**

plot method for class "boot.clust"

**Usage**

```
## S3 method for class 'boot.clust'  
plot(object)
```

**Arguments**

object            an object of class "boot.clust"

**Examples**

```
#plot(boot1)
```

---

plot.mov.clust	<i>Plot mov.clust object</i>
----------------	------------------------------

---

**Description**

plotting method for class "mov.clust"

**Usage**

```
## S3 method for class 'mov.clust'  
plot(object)
```

**Arguments**

object            an object of class "mov.clust"

**Examples**

```
data(Zelfa_rjags)  
plot(simple.clust(Zelfa_rjags))
```



---

print.mov.clust	<i>Print mov.clust object</i>
-----------------	-------------------------------

---

**Description**

printing method for class "mov.clust"

**Usage**

```
## S3 method for class 'mov.clust'
print(object)
```

**Arguments**

object            an object of class "mov.clust"

**Examples**

```
data(Zelfa_rjags)
simple.clust(Zelfa_rjags)
```

---

range01	<i>Range standardisation (0,1)</i>
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---

**Description**

This function standardises a vector between 0 and 1

**Usage**

```
range01(x)
```

**Arguments**

x                    A vector

**Examples**

```
v<-c(1,2,2,3,4,4,5,6)
range01(v)
```

---

rerun	<i>Rerun clustNSD</i>
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---

**Description**

This function uses the autojags function to rerun the function clustNSD to facilitate convergence

**Usage**

```
rerun(rjags, n.update = 3, inc.fact = 1)
```

**Arguments**

rjags	Output from clustNSD
n.update	the max number of updates, default =3
inc.fact	Factor by which the number of iterations will be increased, default=1 (no increase)

**Examples**

```
# DO NOT RUN - TAKE A LONG TIME
#data(Christian_rjags)
#rerun(Christian_rjags, n.update=2, inc.fact=1)
```

---

simple.clust	<i>Convert to mov.clust class</i>
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---

**Description**

This function simplifies a rjags output from clustNSD to a mov.clust object

**Usage**

```
simple.clust(out)
```

**Arguments**

out	Output of clustNSD function
-----	-----------------------------

**Value**

A mov.clust object

**Examples**

```
data(Christian_rjags)
summary(simple.clust(Christian_rjags))
plot(simple.clust(Christian_rjags))
data(Zelfa_rjags)
summary(simple.clust(Zelfa_rjags))
plot(simple.clust(Zelfa_rjags))
```

---

summary.boot.clust	<i>Summarizing boot.clust object</i>
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---

**Description**

summary method for class "boot.clust"

**Usage**

```
## S3 method for class 'boot.clust'  
summary(object)
```

**Arguments**

object	an object of class "boot.clust"
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**Examples**

```
summary(boot1)
```

---

summary.clust.classify	<i>Summarizing clust.classify object</i>
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---

**Description**

summary method for class "clust.classify"

**Usage**

```
## S3 method for class 'clust.classify'  
summary(object)
```

**Arguments**

object	an object of class "clust.classify"
--------	-------------------------------------

**Examples**

```
data(Christian_rjags)  
summary(classify(Christian_rjags))
```

---

summary.mov.clust	<i>Summarizing mov.clust object</i>
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---

### Description

summary method for class "mov.clust"

### Usage

```
## S3 method for class 'mov.clust'
summary(object)
```

### Arguments

object                    an object of class "mov.clust"

### Examples

```
data(Christian_rjags)
summary(simple.clust(Christian_rjags))
```

---

switch.matrix	<i>Switching probabilities matrix</i>
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---

### Description

Extrac matrix of switching probabilities

### Usage

```
switch.matrix(object)
```

### Arguments

object                    an object of class "mov.clust" or "rjags"

### Examples

```
data(Zelfa_rjags)
switch.matrix(Zelfa_rjags)
```

---

t.plot

*Diagnostics plots*


---

### Description

This function used the traceplot to display a plot of iterations vs. sampled values for each variable in the chain, with a separate plot per variable.

### Usage

```
## S3 method for class 'plot'
t(out)
```

### Arguments

out                      Output from clustNSD

### Examples

```
data(Christian_rjags)
t.plot(Christian_rjags)
```

---

time.spent

*Calculating time-spent in cluster*


---

### Description

Calculating pattern of time spent in each cluster

### Usage

```
## S3 method for class 'spent'
time(object)
```

### Arguments

object                      an object of class "mov.clust" or "rjags"

### Examples

```
data(Zelfa_rjags)
time.spent(Zelfa_rjags)
```

---

waic	<i>WAIC calculation</i>
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---

**Description**

This function calculates WAIC from clustNSD output. Based on script initially written by Andrew Gelman

**Usage**

```
waic(jagsfit)
```

**Arguments**

jagsfit	Output of a clustNSD call
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**Examples**

```
data(Christian_rjags)
waic(Christian_rjags)
```

---

Zelfa	<i>Zelfa - daily spatial locations</i>
-------	--

---

**Description**

A dataset containing the x, y locations (UTM), and time of Zelfa, a female giant tortoises inhabiting Espanola Island, Galapagos.

**Usage**

```
Zelfa
```

**Format**

A data frame with 1537 rows and 3 variables (x, y, time)

---

Zelfa_rjags	<i>Latent-state model applied to Zelfa</i>
-------------	--

---

**Description**

The output of clustNSD function applied to Zelfa.

**Usage**

```
Zelfa_rjags
```

**Format**

A "rjags" object

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