

# Package ‘moveNT’

July 3, 2018

**Title** An R package for the analysis of movement data using network theory

**Version** 0.0.0.9000

**Description**

This package provides a series of functions to analyse movement data using network theory.

**Depends** R (>= 3.3.2), raster, sp, adehabitatLT

**License** GPL (>=3)

**Encoding** UTF-8

**LazyData** true

**RoxygenNote** 6.0.1.9000

**Imports** igraph, mclust, moveHMM, uuid

## R topics documented:

adj2stack . . . . .	1
clustnet . . . . .	2
dot . . . . .	3
graphmet . . . . .	3
interpolation . . . . .	4
loop . . . . .	5
mosaic_network . . . . .	5
quant . . . . .	6
sim_mov . . . . .	7
traj2adj . . . . .	8
val . . . . .	8
<b>Index</b>	<b>10</b>

---

adj2stack	<i>Calculation of network metrics</i>
-----------	---------------------------------------

---

**Description**

Transform an adjacency matrix to a series of network metrics at the node-level (weight, degree, betweenness, transitivity, eccentricity) and graph level (diameter, transitivity, density, and modularity)

**Usage**

```
adj2stack(adjmov, grph = T, mode = "directed", weighted = T, ...)
```

**Arguments**

adjmov	Adjacency matrix, need to be an object produced by function traj2adj
grph	Whether node level metrics are to be plotted
mode	Whether the graph should be "directed" or "undirected". Default="directed". See "graph_from_adjacency_matrix" from package "igraph"
weighted	Whether the graph should be weighted (=TRUE) or unweighted (=NULL). Default is weighted. See "graph_from_adjacency_matrix" from package "igraph"

**Value**

A raster stack object

**Examples**

```
traj1<-sim_mov(type="OU", npatches=3, grph=T)
stck<-adj2stack(traj2adj(traj1, res=100), grph=T)
```

---

clustnet

*Normal mixture model for clustering of node level metrics*


---

**Description**

Apply a normal mixture model to a node-level metric

**Usage**

```
clustnet(stack, id = 2, nclust = 2, grph = T)
```

**Arguments**

stack	An object produce by the function adj2stack
id	Metric to be used (2=Weight, 3=Degree, 4=Betweenness, 5=Transitivity, 6=Ec-centricity)
grph	Whether resulting classification should be plotted

**Value**

A list object containing a Mclust object and a raster object

**Examples**

```
traj1<-sim_mov(type="OU", npatches=3, grph=T)
stck<-adj2stack(traj2adj(traj1, res=100), grph=T)
cl<-clustnet(stck, id=2, nclust=2, grph=T)
summary(cl[[1]])
```

---

dot	<i>dot product</i>
-----	--------------------

---

**Description**

dot product

**Usage**

dot(x, ...)

---

graphmet	<i>Summarize graph-level metrics</i>
----------	--------------------------------------

---

**Description**

Summarize graph-level metrics from an object generated by adj2stack

**Usage**

graphmet(grid)

**Arguments**

grid	An object generated by the function adj2stack
id	Metric to be used (2=Weight, 3=Degree, 4=Betweenness, 5=Transitivity, 6=Eccentricity)

**Value**

A vector

**Examples**

```
traj1<-sim_mov(type="OU", npatches=3, grph=T)
stck<-adj2stack(traj2adj(traj1, res=quant(traj1)), grph=T)
graphmet(stck)
```

---

interpolation

*Interpolation based on movement steps for all individuals*


---

## Description

Use movement steps to interpolate raster. User can extract the mean or max when multiple steps overlap in a single pixel. Function need to be applied followign the loop function. This process is very slow

## Usage

```
interpolation(traj, ls, wei = mean, deg = mean, bet = max,
  spe = mean, dt = dot)
```

## Arguments

traj	An object produce by the function adj2stack
ls	An object produced by the loop
wei	Whether mean or max should be used for weight (default = mean)
deg	Whether mean or max should be used for degree (default = mean)
bet	Whether mean or max should be used for betweenness (default = max)
spe	Whether mean or max should be used for speed (default = mean)
dt	Whether mean, max, or dot produc should be used for turning angle (default = dot)

## Value

A list object containing a raster stack object for each individual

## Examples

```
data(puechabonsp)
locs <- puechabonsp$relocs
xy <- coordinates(locs)
df <- as.data.frame(locs)
da <- as.character(df$Date)
da <- as.POSIXct(strptime(as.character(df$Date),"%y%m%d", tz="Europe/Paris"))
litr <- as.ltraj(xy, da, id = id)
out1<-loop(litr)
out2<-interpolation(litr, out1)
```

---

loop	<i>Looping over all individuals</i>
------	-------------------------------------

---

**Description**

Extract adjacency matrix and calculate network metrics for all individuals in a trajectory object. Also calculate mean speed, mean direction, and dot product.

**Usage**

```
loop(traj, res = 100)
```

**Arguments**

traj	An object produce by the function adj2stack
res	Grid size

**Value**

A list object containing a raster stack object for each individual

**Examples**

```
data(puechabonsp)
locs <- puechabonsp$relocs
xy <- coordinates(locs)
df <- as.data.frame(locs)
da <- as.character(df$Date)
da <- as.POSIXct(strptime(as.character(df$Date), "%y%m%d", tz="Europe/Paris"))
litr <- as.ltraj(xy, da, id = id)
out1<-loop(litr)
```

---

mosaic_network	<i>Mosaic individuals together for a given variable</i>
----------------	---

---

**Description**

Use output of loop or interpolation and combine all individuals (mosaic) together using the mean or max values.

**Usage**

```
mosaic_network(ls, index = 2, sc = T, fun = mean)
```

**Arguments**

ls	An object produced by the loop or interpolate functions
index	Index indicating which layer to take in the stack
sc	Whether to scale all individual rasters (default = TRUE)
fun	Whether mean or max should be used as the mosaic function (default = mean)

**Value**

A list object containing a raster stack object for each individual

**Examples**

```
data(puechabonsp)
locs <- puechabonsp$relocs
xy <- coordinates(locs)
df <- as.data.frame(locs)
da <- as.character(df$Date)
da <- as.POSIXct(strptime(as.character(df$Date), "%y%m%d", tz="Europe/Paris"))
litr <- as.ltraj(xy, da, id = id)
out1<-loop(litr)
mean_weight<-mosaic_network(out1, index=2, sc=T, fun=mean) #Perform mean weight (not-interpolated)
plot(mean_weight)
```

---

quant

*Sample quantile of distance for ltraj object*


---

**Description**

Wrapper function that extract the sample quantile of distance

**Usage**

```
quant(x, p = 0.5)
```

**Arguments**

x	A ltraj object
p	Probability, default=0.5 (median)

**Value**

A vector of length p

**Examples**

```
traj1<-sim_mov(type="OU", npatches=3, grph=T)
stck<-adj2stack(traj2adj(traj1, res=quant(traj1)), grph=T)
```

sim\_mov

*Simulation of patch-based movement trajectory***Description**

Simulate a movement trajectory with user defined number of patches and interpatch movement

**Usage**

```
sim_mov(type = c("2states", "OU"), npatches = 5, ratio = 5,
        nswitch = 150, ncore = 200, spacecore = 200,
        seq_visit = sample(1:npatches, nswitch, replace = T),
        stepDist = "gamma", angleDist = "vm", stepPar = c(0.5, 3, 1, 5),
        anglePar = c(pi, 0, 0.5, 2), s = diag(40, 2), grph = F)
```

**Arguments**

type	whether movement within patches should be based on a 2states process (from package moveHMM) or a Bivariate Ornstein-Uhlenbeck process (OU) (from package adehabitatLT)
npatches	Number of patches, default=5
ratio	Ratio (in percent) of locations associated to interpatch movement, default=5
nswitch	Number of switch/depart from patches, default=150
ncore	Number of locations within a patch per visit, default=200
spacecore	Minimum distance between center of patches, default=200
seq_visit	Specify the sequence of visit among patches, default is random sequence
stepDist	Distribution for step length if 2states specified in type, see simData of moveHMM package
angleDist	Distribution for turn angle if 2states specified in type, see simData of moveHMM package
stepPar	Parameters for step length distribution if 2states specified in type, see simData of moveHMM package
anglePar	Parameters for turn angle distribution if 2states specified in type, see simData of moveHMM package
s	Parameters for the OU process, see simm.mou of adehabitatLT package
grph	Whether a graph of the trajectory should be produced, default=F

**Value**

A ltraj (adehabitatLT) object

**Examples**

```
traj1<-sim_mov(type="OU", npatches=3, grph=T)
traj2<-sim_mov(type="2states", npatches=2, grph=T)
```

---

traj2adj	<i>Generation of adjacency matrix from movement data</i>
----------	--

---

### Description

Transform an ltraj object to an adjacency matrix using a user-specified grid size

### Usage

```
traj2adj(mov, res = 100, grid = NULL)
```

### Arguments

mov	Movement trajectory, need to be a ltraj object
res	Grid size
grid	User specified grid (a raster), needs to have a larger extent than the movement trajectory

### Value

A list of object containing the adjacency matrix, the grid use, and patch/corridor identification (only useful if sim\_mov was used)

### Examples

```
traj1<-sim_mov(type="OU", npatches=3, grph=T)
adj<-traj2adj(traj1, res=100)
```

---

val	<i>Extract occupied cells in a raster object</i>
-----	--

---

### Description

Extract only occupied cells in a raster object,

### Usage

```
val(grid, id)
```

### Arguments

grid	An object generated by the function adj2stack
id	Metric to be used (2=Weight, 3=Degree, 4=Betweenness, 5=Transitivity, 6=Ec-centricity)

### Value

A vector



**Examples**

```
traj1<-sim_mov(type="OU", npatches=3, grph=T)
stck<-adj2stack(traj2adj(traj1, res=quant(traj1)), grph=T)
mean(val(stck, 2))
```

# Index

- \*Topic **Mclust**
  - clustnet, [2](#)
- \*Topic **adj2stack**
  - clustnet, [2](#)
  - graphmet, [3](#)
  - interpolation, [4](#)
  - loop, [5](#)
  - mosaic\_network, [5](#)
  - sim\_mov, [7](#)
  - traj2adj, [8](#)
  - val, [8](#)
- \*Topic **loop**
  - interpolation, [4](#)
  - mosaic\_network, [5](#)
- \*Topic **ltraj**
  - quant, [6](#)
- \*Topic **traj2adj**
  - adj2stack, [1](#)
  - clustnet, [2](#)
  - interpolation, [4](#)
  - loop, [5](#)
  - mosaic\_network, [5](#)
  - sim\_mov, [7](#)
- adj2stack, [1](#)
- clustnet, [2](#)
- dot, [3](#)
- graphmet, [3](#)
- interpolation, [4](#)
- loop, [5](#)
- mosaic\_network, [5](#)
- quant, [6](#)
- sim\_mov, [7](#)
- traj2adj, [8](#)
- val, [8](#)