Vignette movescape

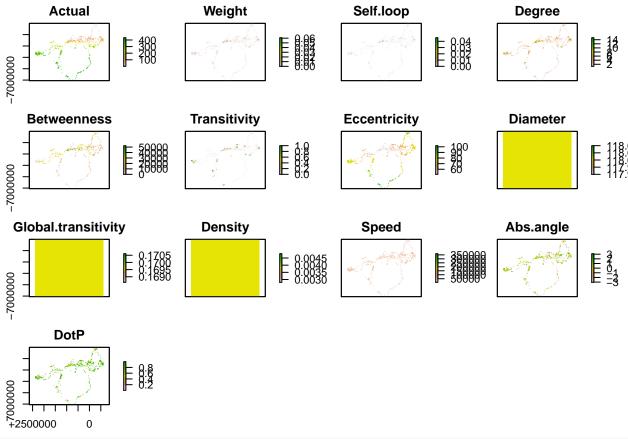
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This vignette presents a simple workflow to extract the movescape of GPS tracked individuals. We recommend interest readers read the documentation associated to the moveNT package.

A- Data preparation

For simplification, we initiate the analysis with a simple trajectory object of class ltraj. This trajectory object is freely available in the adehabitatLT package and contains the GPS locations of 6 albatross. We will first use the loop function in moveNT, which is a wrapper function extracting the movement metrics for each individual. We then use the function $table_grid$ to convert the loop object into a data.frame.

```
library(moveNT)
##
## Attaching package: 'moveNT'
## The following objects are masked _by_ '.GlobalEnv':
##
##
       adj2stack, clustnet, graphmet, interpolation, loop,
##
       mosaic_network, quant, sim_mov, traj2adj, val
data(albatross)
grid<-loop(albatross, 35000)</pre>
    balise.11378
   balise.11380
##
  balise.16256
## balise.25070
##
   balise.8196
  balise.8337
##
#Stack showing all metrics calculated for the first albatros
plot(grid[[1]])
```



table_grid<-table_cluster(albatross, grid)
#Showing the first few rows of the table created.
head(table_grid)</pre>

```
##
       Actual
                    Weight
                             Self.loop Degree Betweenness Transitivity
            1 0.001090513 0.000000000
                                             2
## 75
                                                       2531
                                                                        0
## 76
            2 0.004362050 0.001090513
                                             6
                                                       3692
                                                                        0
            3 0.009814613 0.008724100
                                             5
                                                        382
                                                                        0
##
  77
                                             2
            4 0.001090513 0.000000000
                                                                        0
  78
                                                          0
##
##
            5 0.001090513 0.000000000
                                             2
                                                                        0
  160
                                                       2516
            6 0.002181025 0.001090513
                                             4
                                                       3707
                                                                        0
##
   162
##
       Eccentricity Diameter Global.transitivity
                                                        Density
                                                                   Speed
## 75
                  87
                          118
                                         0.1696113 0.003803168 50784.60
## 76
                  88
                                         0.1696113 0.003803168 32739.75
                          118
##
  77
                  89
                          118
                                         0.1696113 0.003803168 15622.52
## 78
                  90
                          118
                                         0.1696113 0.003803168 26281.46
  160
                  86
                          118
                                         0.1696113 0.003803168 40014.98
  162
                  89
                          118
                                         0.1696113 0.003803168 24601.32
##
                        DotP
##
        Abs angle
       -2.0312774 0.9703201
##
                              balise.11378
  75
       -0.4432067 0.6445507
  76
                              balise.11378
## 77
        0.1772387 0.6329915
                              balise.11378
## 78
        3.0051036 0.7281993
                              balise.11378
## 160 -1.5583292 0.8902292
                              balise.11378
## 162 0.2959155 0.9960083
                              balise.11378
```

B- Individual-level clustering

The first step of the analysis is to apply the clustering to each individual. ind_clust apply a mixture model to each individual. It is possible to specify the maximum number of clusters (here 8) and also the covariates to use for the clustering, but the function automatically selects the optimal number of clusters (based on BIC). In our case, 2 individuals had 6 clusters, 2 had seven, and 2 had eight clusters. ls_ind simply return a list object with each element representing a single individual.

```
ls_ind<-ind_clust(table_grid, max.n.clust=8)

## [1] "mclust is loaded correctly"

## [1] " balise.11378"

## [1] " balise.11380"

## [1] " balise.16256"

## [1] " balise.25070"

## [1] " balise.8196"

## [1] " balise.8337"

#Showing the number of individuals with 6, 7, and 8 clusters

# (i.e. no individual had less than 6 clusters)

table(unlist(lapply(ls_ind, function(x) x$G)))

##

## 6 7 8

## 2 2 2</pre>
```

C- Population-level clustering

After performing the individual clustering, a second clustering is applied via pop_clust . This second clustering takes the ouptut of ind_clust and will identify which individual clusters could be considered as one population-level clusters. The function automatically selects the optimal number of clusters (based on BIC). It is possible for two clusters from the same individual to be in the same population-level cluster. Likewise, it is possible that a population level cluster does not have all individuals. Here, 3 different population clusters were calculated. The second line extract the center (mean) of each cluster which is helpful in interpreting their meaning. The first cluster was heavily used (weight), well connected (degree), and important for connectivity (betweenness), but albatross were moving slowly and not linearly in them. The second cluster was a cluster with intermediate use, not important for connectivity and still with meandering movement. The third cluster was important for connectivity and albatross were moving fast and linearly in it. We also extract the proportion of each cluster.

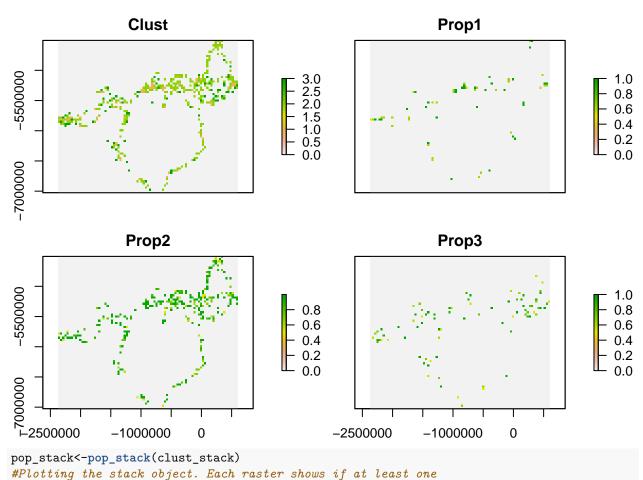
```
pop<-pop_clust(albatross, ls_ind)</pre>
#Paremeters associated to each cluster (i.e. center)
pop[[1]]$parameters$mean
##
                      [,1]
                                  [,2]
                                              [,3]
## Weight
                2.0414281
                            0.07588085 -0.2203643
                2.1634587
                            0.70690604 -0.5993716
## Degree
## Betweenness
                0.5743463 -0.13990333
                                        0.3104720
## Speed
               -0.3411859 -0.39086569
                                        0.7518956
## DotP
               -0.1277000 -0.16974009
                                       0.6275062
#Proportion of each cluster (how frequent it is spatially)
pop[[1]]$parameters$pro
## [1] 0.2868044 0.5703384 0.1428571
```

D- Mapping and results export

After performing the population level cluster, the function <code>clust_stack</code> recombines the individual and population level clustering and produce a <code>stack</code> object for each individual albatross showing the most likely cluster, and also the probability of observing each cluster (uncertainty) in any given pixel. This individual level data (but which contains the population level clustering) can be used in a regression based analysis as presented in the manuscript or simply mapped. We developed two functions to produce these maps. <code>pop_stack</code> generate for each population cluster, rasters showing if at least one individual is using this pixel for this specific cluster. <code>pop_overl</code> display for each pixel all potential use observed, for example a pixel having the value <code>123</code> will have at least one individual using this pixel as cluster 1, another individual using it as 2, and another individual as 3. We show how frequent each combination are using the <code>table</code> function. These object can be exported to be used in other software using the <code>writeRaster</code> function.

```
clust_stack<-clust_stack(grid, pop, ls_ind, table_grid)</pre>
```

```
## [1] " balise.11378"
## [1] " balise.16256"
## [1] " balise.25070"
## [1] " balise.8196"
## [1] " balise.8337"
#Plotting the stack for the first individual
plot(clust_stack[[1]])
```



```
# individual is using the pixel as a specific cluster.
plot(pop_stack)
```

