view_frames Result

Recorded at time: 256.242

world

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.92
Most recent transform: 256.225
Oldest transform: 251.305

camera2_link

camera_link

link1

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.92
Most recent transform: 256.225
Oldest transform: 251.305

camera2_link_optical

camera_link_optical

link2

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.92
Most recent transform: 256.225
Oldest transform: 251.305

link3

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.92
Most recent transform: 256.225
Oldest transform: 251.305

link4

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.92
Most recent transform: 256.225
Oldest transform: 251.305

link5

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.92
Most recent transform: 256.225
Oldest transform: 251.305

gripper_connector

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.92
Most recent transform: 256.225
Oldest transform: 251.305

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.92
Most recent transform: 256.225
Oldest transform: 251.305

gripper_left

gripper_right