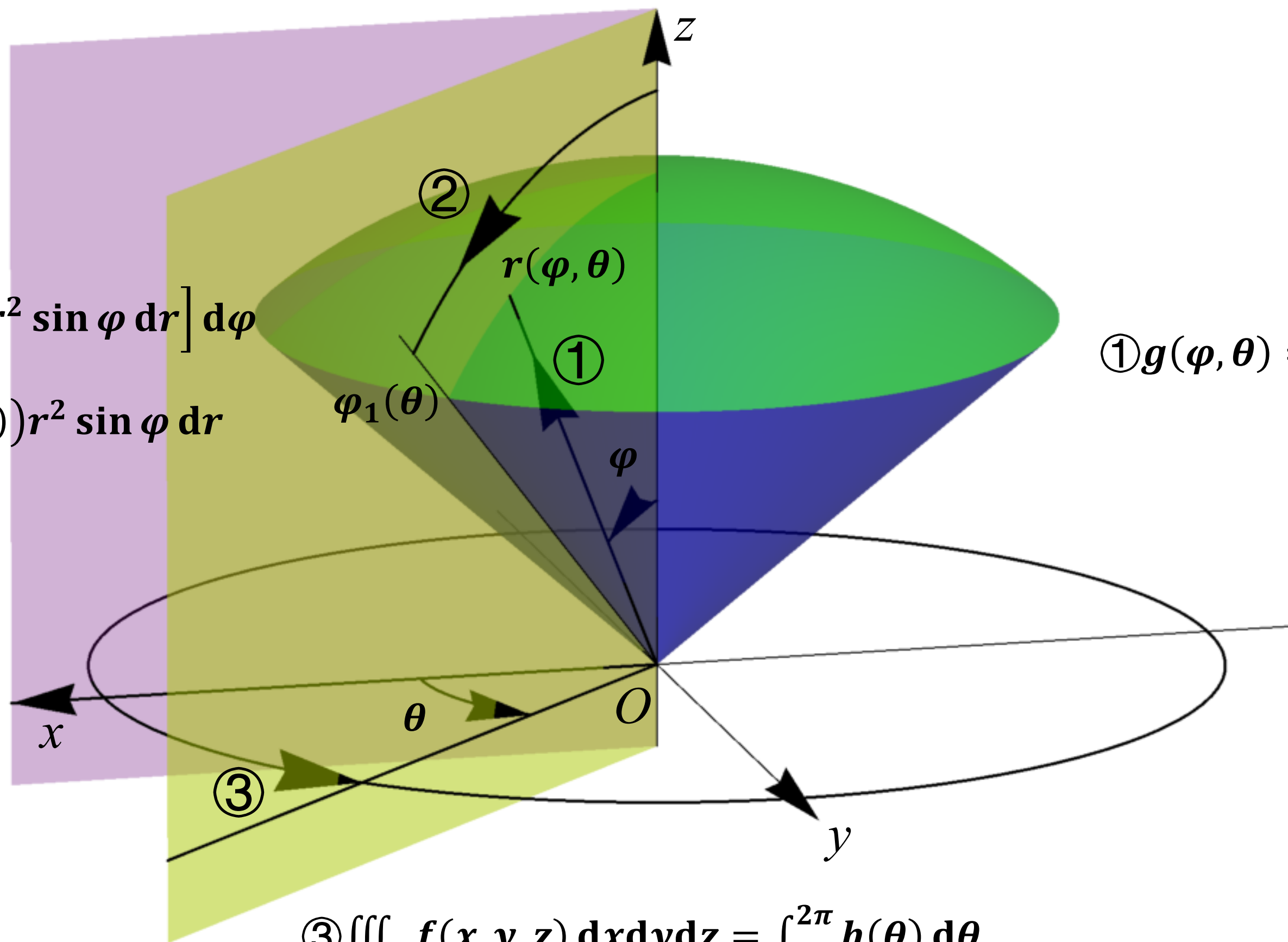


$$\textcircled{2} h(\theta) = \int_0^{\varphi_1(\theta)} g(\varphi, \theta) d\varphi$$

$$= \int_0^{\varphi_1(\theta)} \left[\int_0^{r(\varphi, \theta)} f(x(r, \varphi, \theta), y(r, \varphi, \theta), z(r, \varphi, \theta)) r^2 \sin \varphi dr \right] d\varphi$$

$$= \int_0^{\varphi_1(\theta)} d\varphi \int_0^{r(\varphi, \theta)} f(x(r, \varphi, \theta), y(r, \varphi, \theta), z(r, \varphi, \theta)) r^2 \sin \varphi dr$$

$$\textcircled{1} g(\varphi, \theta) = \int_0^{r(\varphi, \theta)} f(x(r, \varphi, \theta), y(r, \varphi, \theta), z(r, \varphi, \theta)) r^2 \sin \varphi dr$$



$$\textcircled{3} \iiint_{\Omega} f(x, y, z) dx dy dz = \int_0^{2\pi} h(\theta) d\theta$$

$$= \int_0^{2\pi} \left[\int_0^{\varphi(\theta)} d\varphi \int_0^{r(\varphi, \theta)} f(x(r, \varphi, \theta), y(r, \varphi, \theta), z(r, \varphi, \theta)) r^2 \sin \varphi dr \right] d\theta$$

$$= \int_0^{2\pi} d\theta \int_0^{\varphi(\theta)} d\varphi \int_0^{r(\varphi, \theta)} f(x(r, \varphi, \theta), y(r, \varphi, \theta), z(r, \varphi, \theta)) r^2 \sin \varphi dr$$