



$$\textcircled{1} g(r, \theta) = \int_{z_1(r, \theta)}^{z_2(r, \theta)} f(x(r, \theta), y(r, \theta), z) \, dz$$

$$\begin{aligned} \textcircled{2} h(\theta) &= \int_0^{r(\theta)} g(r, \theta) \, r \, dr \\ &= \int_0^{r(\theta)} \left[\int_{z_1(r, \theta)}^{z_2(r, \theta)} f(x(r, \theta), y(r, \theta), z) \, dz \right] r \, dr \end{aligned}$$

$$\begin{aligned} \textcircled{3} \iiint_{\Omega} f(x, y, z) \, dx \, dy \, dz &= \int_0^{2\pi} h(\theta) \, d\theta \\ &= \int_0^{2\pi} \left[\int_0^{r(\theta)} \left[\int_{z_1(r, \theta)}^{z_2(r, \theta)} f(x(r, \theta), y(r, \theta), z) \, dz \right] r \, dr \right] d\theta \\ &= \int_0^{2\pi} d\theta \int_0^{r(\theta)} \left[\int_{z_1(r, \theta)}^{z_2(r, \theta)} f(x(r, \theta), y(r, \theta), z) \, dz \right] r \, dr \end{aligned}$$