# MArefSetup

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2017

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# **Test**

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# 1 Quadratic equations

A quadratic equation is an equation with the form  $ax^2 + bx + c = 0$  where x represents an unknown and a, b and c are known numbers with  $a \neq 0$ .

# 1.1 Solutions to a quadratic equation

A solution to a quadratic equation is a value of x such that the equation balances. The solutions to quadratic equations can be found by using the quadratic formula:

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.\tag{1}$$

# Example.

For instance, the solutions to  $x^2 + 2x - 3 = 0$  are:

$$x = \frac{-2 \pm \sqrt{2^2 - 4 \times 1 \times -3}}{2 \times 1}$$

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$$= \frac{-2 \pm \sqrt{4 + 12}}{2}$$
$$= \frac{-2 \pm \sqrt{16}}{2}$$
$$= \frac{-2 \pm 4}{2}$$

Hence, x = 1 or x = -3.

### 1.2 The discriminant

**Definition 1.1** (Discriminant).

The **discriminant** of a quadratic equation with coefficients  $a,b,c\in\mathbb{R}$  is:

$$\Delta = b^2 - 4ac.$$

#### Remark 1.2.

**Note that** this is the expression beneath the square root symbol in the quadratic formula (1).

We can use the discriminant to determine the number of real roots of a quadratic equation. The number depends on the value of  $\Delta$  as in table 1.

Figure 1 shows an example of each possibility<sup>1</sup>.

<sup>&</sup>lt;sup>1</sup>The image is due to Olin, CC-BY-AS 3.0 downloaded from Wikimedia Commons

Value of $\Delta$	Real roots
$\Delta > 0$	Two, distinct
$\Delta = 0$	One, repeated
$\Delta < 0$	Zero

Table 1: Number of real roots of a quadratic equation, given the discriminant

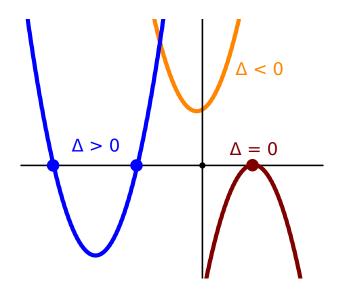


Figure 1: Examples of quadratic functions with zero, one and two real roots.

# 2 The scalar product

Consider two vectors  ${\bf a}$  and  ${\bf b}$  drawn so their tails are at the same point.

We define the scalar product of  $\mathbf{a}$  and  $\mathbf{b}$  as follows.

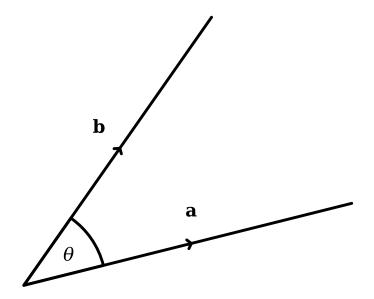


Figure 2: Two vectors with angle between them.

Definition 2.1 (Scalar product).

The scalar product of a and b is

$$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta$$

where

- ullet  $|\mathbf{a}|$  is the modulus of  $\mathbf{a}$ ,
- ullet  $|\mathbf{b}|$  is the modulus of  $\mathbf{b}$ , and
- $\theta$  is the angle between a and b.

#### Remark 2.2.

It is important to use the dot symbol for the scalar product (also called the dot product). You must not use a  $\times$  symbol

as this denotes the vector product which is defined differently.

### Example 2.3.

Let

$$\mathbf{a} = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$$
 and  $\mathbf{b} = \begin{pmatrix} 4 \\ 0 \end{pmatrix}$ .

The angle between these vectors is  $\,\theta=45^\circ$  . Then  $\,|{\bf a}|=\sqrt{8}\,$  and  $\,|{\bf b}|=4$  . So,

$$\mathbf{a} \cdot \mathbf{b} = \begin{pmatrix} 2 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 0 \end{pmatrix} = |\mathbf{a}| |\mathbf{b}| \cos \theta$$
$$= \sqrt{8} \times 4 \times \cos 45^{\circ}$$
$$= 4\sqrt{8} \times \frac{1}{\sqrt{2}} = 4\frac{\sqrt{8}}{\sqrt{2}} = 4\sqrt{4} = 8.$$

Note that the result is a scalar, not a vector.

### 2.1 Vectors in cartesian form

When vectors are given in cartesian form there is an alternative formula for calculating the scalar product.

## **Proposition 2.4.**

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If  $\mathbf{a} = a_1 \mathbf{i} + a_2 \mathbf{j}$  and  $\mathbf{b} = b_1 \mathbf{i} + b_2 \mathbf{j}$  then

$$\mathbf{a} \cdot \mathbf{b} = a_1 b_1 + a_2 b_2.$$

**Proof.** Consider the vector  $\mathbf{b} - \mathbf{a} = \begin{pmatrix} b_1 - a_1 \\ b_2 - a_2 \end{pmatrix}$ . The modulus of this is

$$|\mathbf{b} - \mathbf{a}| = \sqrt{(b_1 - a_2)^2 + (b_2 - a_2)^2}.$$

Note from figure 3 that the vectors  ${\bf a}$ ,  ${\bf b}$  and  ${\bf b}-{\bf a}$  form a triangle:

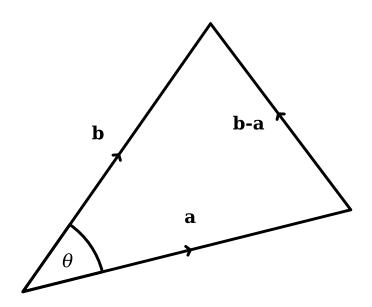


Figure 3: A triangle is formed by two vectors and their difference.

Let  $\theta$  denote the angle between a and b. Then, the cosine

rule yields:

$$|\mathbf{b} - \mathbf{a}|^2 = |\mathbf{a}|^2 + |\mathbf{b}|^2 - 2|\mathbf{a}||\mathbf{b}|\cos\theta.$$
 (2)

Substituting the definition of the scalar product of a and b into equation 2 gives:

$$|\mathbf{b} - \mathbf{a}|^2 = |\mathbf{a}|^2 + |\mathbf{b}|^2 - 2(\mathbf{a} \cdot \mathbf{b}).$$

Rearranging:

$$(\mathbf{a} \cdot \mathbf{b}) = \frac{1}{2} (|\mathbf{a}|^2 + |\mathbf{b}|^2 - |\mathbf{b} - \mathbf{a}|^2).$$

Writing this in terms of components produces:

$$(\mathbf{a} \cdot \mathbf{b}) = \frac{1}{2} \left( a_1^2 + a_2^2 + b_1^2 + b_2^2 - (b_1 - a_1)^2 - (b_2 - a_2)^2 \right)$$

$$= \frac{1}{2} \left( a_1^2 + a_2^2 + b_1^2 + b_2^2 - b_1^2 + 2b_1 a_1 - a_1^2 - b_2^2 + 2b_2 a_2 - a_2^2 \right)$$

$$= \frac{1}{2} \left( 2b_1 a_1 + 2b_2 a_2 \right)$$

$$= a_1 b_1 + a_2 b_2$$

as required.

### Example 2.5.

Consider again the vectors

$$\mathbf{a} = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$$
 and  $\mathbf{b} = \begin{pmatrix} 4 \\ 0 \end{pmatrix}$ .

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Calculating the scalar product using the components:

$$\mathbf{a} \cdot \mathbf{b} = a_1 b_1 + a_2 b_2 = 2 \times 4 + 2 \times 0 = 8.$$

Note that if we are given vectors in this form, the scalar product may be used to calculate the angle between them. Since  $\mathbf{a} \cdot \mathbf{b} = 8$  and we have:

$$|\mathbf{a}| = \sqrt{8}$$

$$|\mathbf{b}| = 4.$$

Hence,

$$8 = \mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta$$
$$= 4\sqrt{8} \cos \theta.$$

Rearranging:

$$\theta = \cos^{-1}\left(\frac{8}{4\sqrt{8}}\right) = 45^{\circ}.$$

# 3 Using Matlab

Two calculate the scalar product in Matlab the dot function is used.

Create two vectors:

$$> A = [4 -1 2];$$
  
 $> B = [2 -2 -1];$ 

Calculate the scalar product:

$$> C = dot(A,B)$$

$$C = 8$$