# EEDG 6370: DESIGN AND ANALYSIS OF RECONFIGURABLE COMPUTING SYSTEMS

Assignment 3: GCD Hardware Design

**Group Name – BSS** 

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#### **Objective:**

To design and implement hardware for calculating the greatest common divisor (GCD) between two positive 16-bit integers.

#### **Design and analysis of the GCD function:**

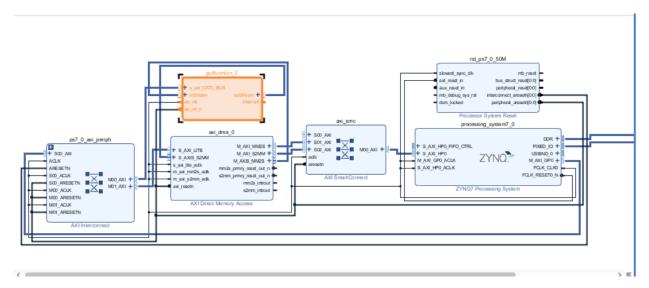
The C++ code for the GCD function was written in Vivado HLS and simulated to check the correctness of the GCD function. The test bench was also written in CPP which was used in the simulation process to send sets of inputs and get the outputs. Synthesis of the design was done where the CPP code was converted to an RTL Code. The RTL was exported as an IP to use in Vivado. A block design was created in Vivado where the IP was connected to the zynq processing system and the Direct memory access (DMA) through the AXI bus. Synthesis, Implementation and generation of bitstream were done. Also, the HDL Wrapper code was generated and the hardware was exported along with the bitstream to launch the Xilinx SDK. In the SDK, The FPGA board was first configured with the bitstream. Two different codes were written in SDK- one to implement the design on the ARM Core(Software) and one to implement the design on the programmable logic where the processor is interfaced with the IP through the AXI DMA. A few sets of inputs were used for each of the codes to test the functionality of the design. To Speed up the design, the modulo operation in the CPP Code was replaced by a straightforward statement that performed the same operation.

#### **Screenshot of C Simulation in Vivado HLS:**

# **Screenshot of Synthesis Report:**



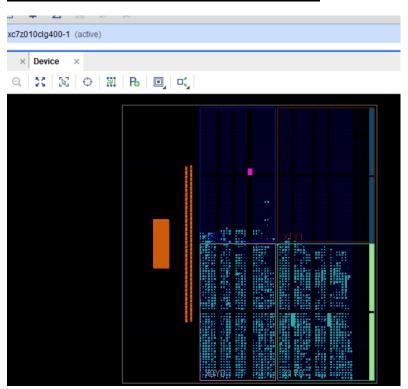
# Screenshot of Block design in Vivado:



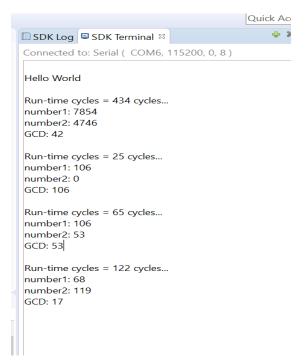
# **Screenshot of Cosimulation report(C/RTL):**



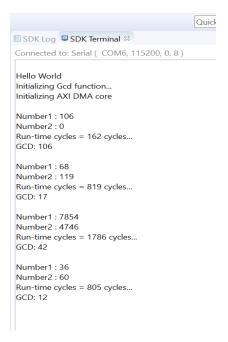
# **Screenshot of implemented Design:**



### **Screenshot of SDK output for ARM core implementation:**



### **Screenshot of SDK Output for FPGA Implementation:**



Thus, the GCD function was implemented in the Zybo FPGA Board where it was implemented on both the ARM Core as well as the programmable logic. The clock cycles required to run both the designs were also reported.					