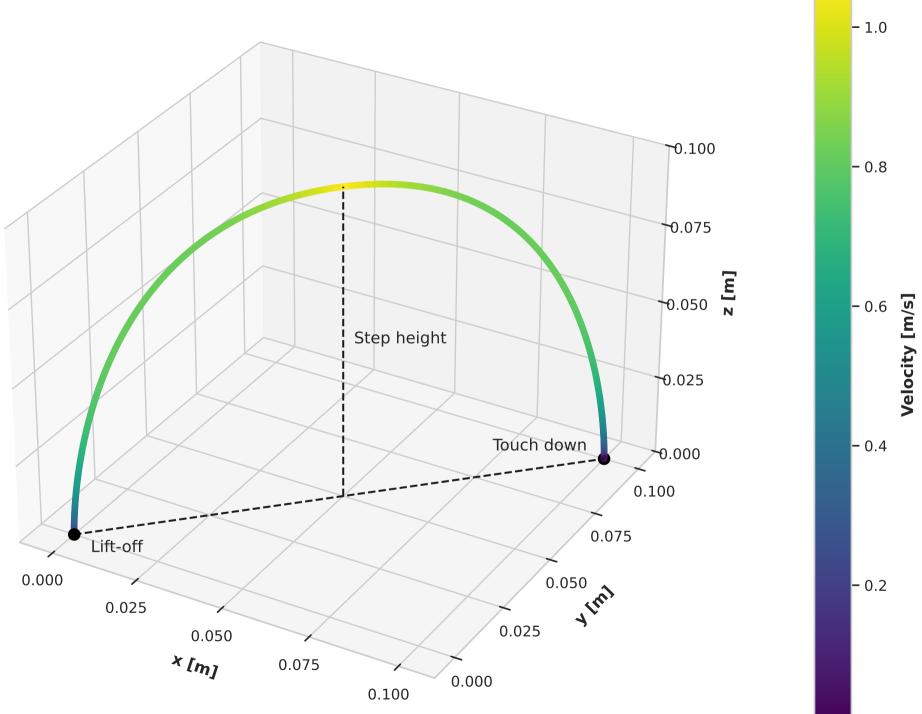
Swing Trajectory



- 0.0