

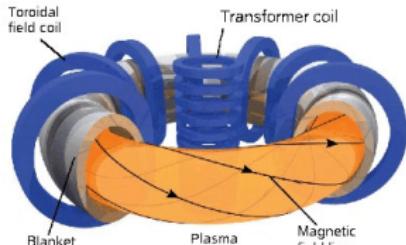
Field-aligned grid generation and enhancements of the guiding-center orbit code GORILLA

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What is the current approach to fusion?

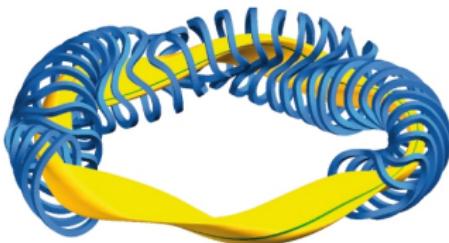


Tokamak^[1]

- Heating of D-T plasma to $\sim 10^8$ K in toroidal magnetic configuration

- Two main types of devices:

- Tokamaks
- Stellarators



Stellarator^[2]

[1] https://upload.wikimedia.org/wikipedia/commons/b/b3/W7X-Spulen_Plasma.blau.gelb.jpg

[2] <https://www.researchgate.net/figure/Schematic-of-a-Tokamak-fusion-reactor/41719279>

Theoretical descriptions of plasmas

- Magnetohydro-dynamics (MHD)

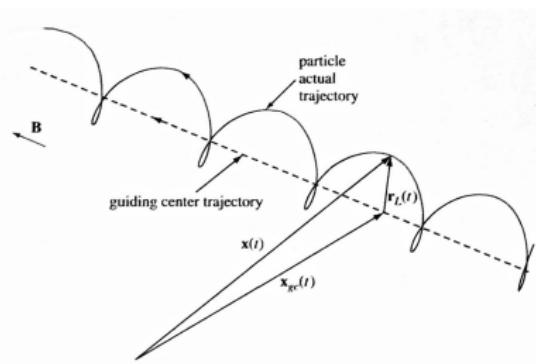
- conducting fluid
- high particle collisionalities

- Kinetic Approach

- distribution function $f(\vec{x}, \vec{v})$

- Gyro-kinetic Approach

- averaging over gyro-motion
- $f(\vec{x}, v_{||}, v_{\perp})$



Guiding center motion^[3]

[3] http://www.thunderbolts.info/eg_draft/images/particle_trajectory_diagram_548x389.jpg

3D geometric integrator **GORILLA**

(Geometric ORbit Integration with Local Linearisation Approach)

Properties:

- **Physically correct long time orbit dynamics**
 - preserved total energy, magnetic moment and phase space volume
- **Insensitive to noise in fields**
- **Computationally efficient**
 - relaxed requirement to orbit shape and time evolution

Guiding-center equations for **GORILLA**

Hamiltonian form of guiding center equations in curvilinear coordinates:

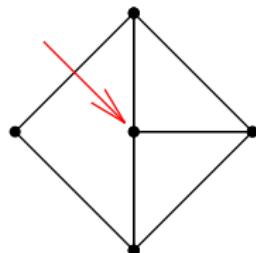
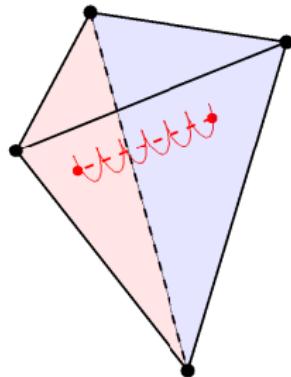
$$\dot{x}^i = \frac{v_{\parallel} \varepsilon^{ijk}}{\sqrt{g} B_{\parallel}^*} \frac{\partial A_k^*}{\partial x^j} \quad A_k^* = A_k + \frac{v_{\parallel}}{\omega_c} B_k \quad (1)$$

$$v_{\parallel} = \sigma \left(\frac{2}{m_{\alpha}} (w - J_{\perp} \omega_c - e_{\alpha} \Phi) \right)^{1/2} \quad (2)$$

Linearization of A_k , B_k/ω_c , ω_c and Φ in spatial cells
 → equations of motion:

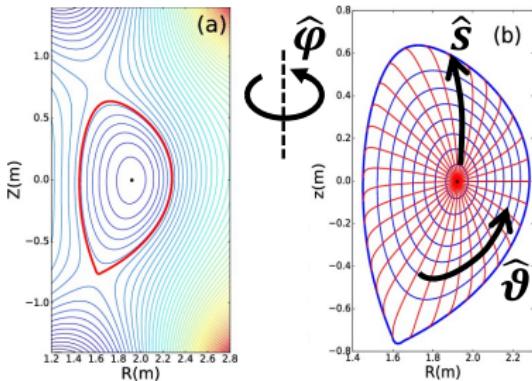
$$\frac{d\mathbf{z}}{d\tau} = \hat{\mathbf{a}}\mathbf{z} + \mathbf{b} \quad (3)$$

Spatial discretization: grid for Gorilla



- Why do we need a grid?
 - linearization of field quantities
 - box counting scheme for distribution function
- Requirements to grid:
 - tetrahedral grid elements
 - no holes or overlaps
 - no hanging nodes

Field-aligned grid in symmetry flux coordinates

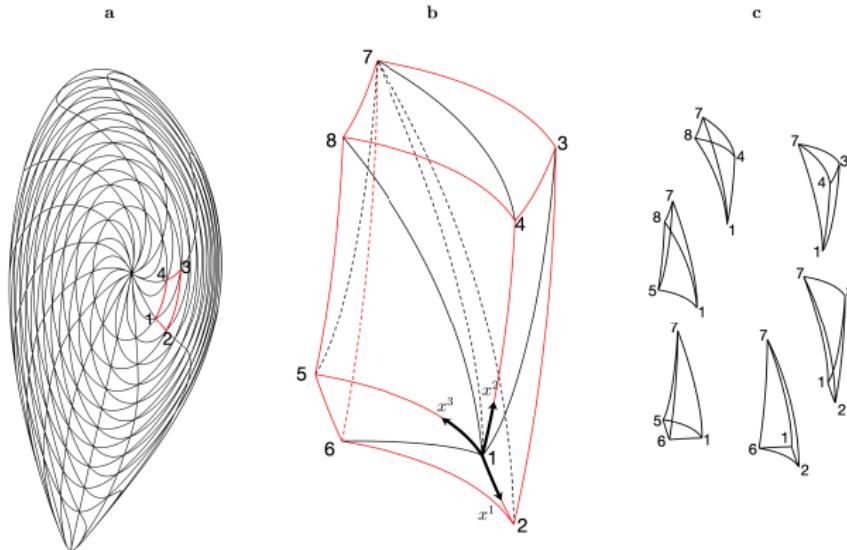


Magnetic field topology^[4]

- coordinates (s, ϑ, φ)
 - $s \rightarrow$ minor-radial coordinate
 - $\vartheta \rightarrow$ poloidal coordinate
 - $\varphi \rightarrow$ toroidal coordinate
- field lines assume straight lines in SFC
- $\mathbf{A} \propto s \cdot \hat{\varphi} \rightarrow$ no error due to linearization

[4] https://www.researchgate.net/profile/Yawei_Hou/publication/335218824/figure/fig1

Field-aligned grid



Poloidal cross-section and grid elements in real space

Computational approach

- Piecewise-constant coefficients of

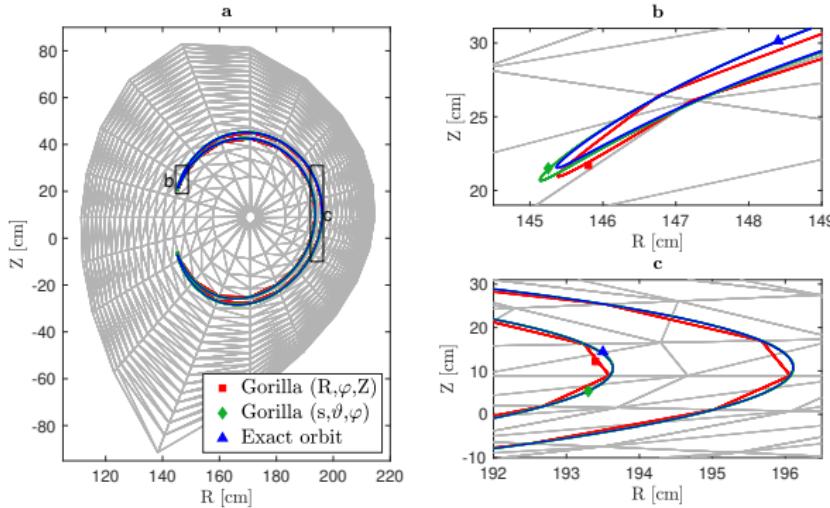
$$\frac{d\mathbf{z}}{d\tau} = \hat{\mathbf{a}}\mathbf{z} + \mathbf{b} \quad (3)$$

are discontinuous at cell boundaries:

→ orbit intersections must be computed accurately

- Runge-Kutta 4 in iterative scheme using a **parabolic estimation** and **Newton's method**

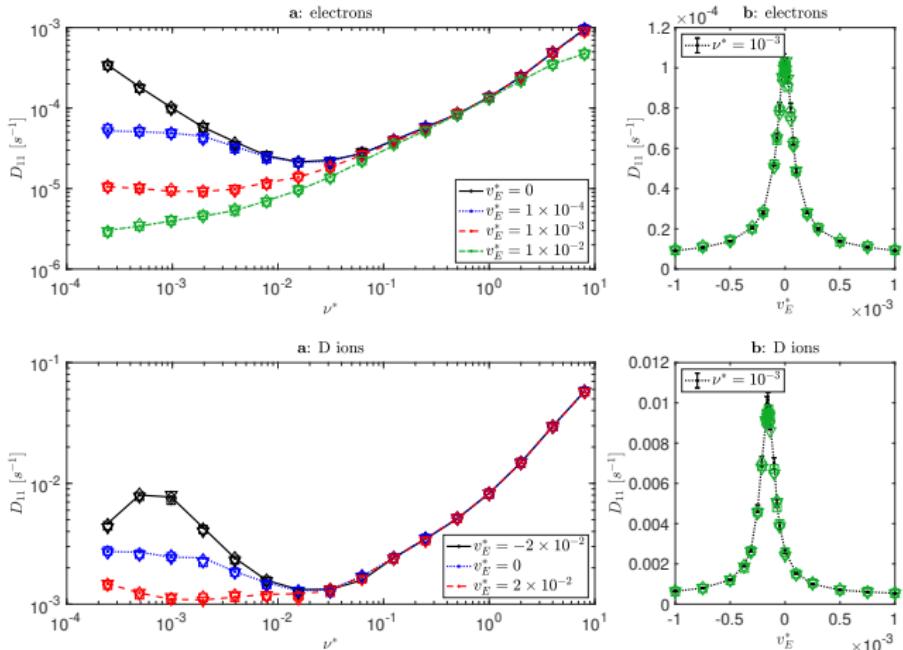
Poincaré plots of guiding center orbits



- Geometric integration: Not exact orbit shape.
- Axisymmetric (2D): Canonical toroidal angular momentum is conserved.

Radial Transport in a Stellarator (Monte Carlo)

Mono-energetic radial diffusion coefficient D_{11}



$$\nu^* = \frac{R_0 \nu_c}{\iota V}$$

$$v_E^* = \frac{E_r}{vB_0}$$

Init. cond.:

$$E = 3 \text{ keV}$$

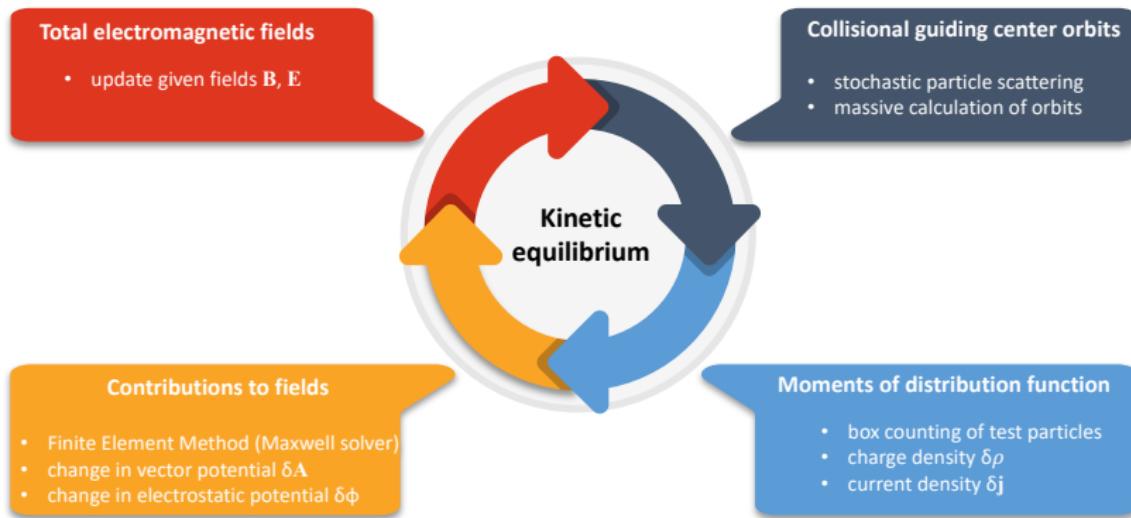
$$s_0 = 0.6$$

Conclusion and Outlook

- Physically correct long time orbit dynamics
- Particle coordinates and velocities are implicitly given at cell boundaries
- Computational efficiency
- Low sensitivity to noise in electromagnetic fields
- Computation of quasi-steady plasma parameters and kinetic equilibria

Thank you for your attention!

Target application: kinetic equilibria



Requirements to integrator:

1. physically correct long time orbit dynamics
2. low sensitivity to noise in fields
3. high computational efficiency

Physically correct long time orbit dynamics

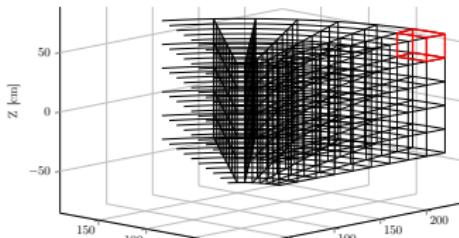
- Linear approximation of field quantities does **not** destroy the **Hamiltonian nature** of the original guiding center equations.
- Non-canonical Hamiltonian form of linear ODE set

$$\frac{dz^i}{d\tau} = \Lambda^{ij} \frac{\partial H}{\partial z^j}, \quad \Lambda^{ij}(\mathbf{z}) = \{z^i, z^j\}_\tau, \quad (4)$$

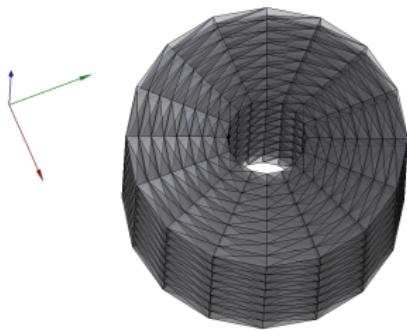
with Hamiltonian $H(\mathbf{z}) = v_{||}^2/2 - U(\mathbf{x})$ and antisymmetric Poisson matrix $\Lambda^{ij}(\mathbf{z})$.

- **Symplecticity:** Phase space volume is conserved.

Previous grid in cylindrical coordinates

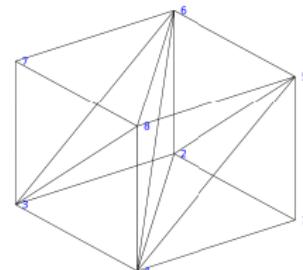


Hexahedra

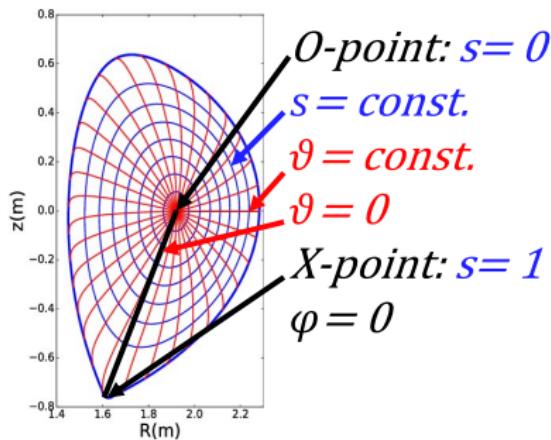


Cylindrical Contour Grid

- vertices lie on contours of cylindrical coordinates (R, φ, Z)
- hexahedra are obtained via indexing
- each hexahedron is cut into six tetrahedra:

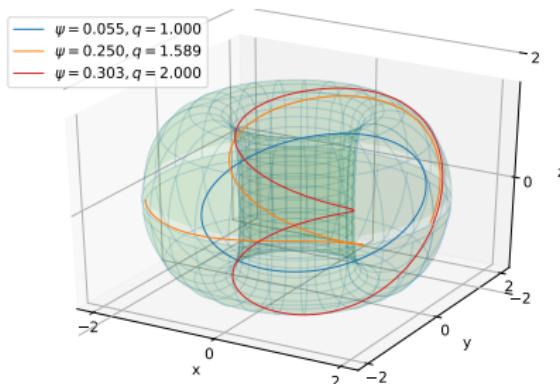


Implementing the field-aligned grid



- find O-point and X-point
- field line integration for coordinate interpolation
- interpolation routine:
 $(s, \vartheta, \varphi) \rightarrow (R, \varphi, Z)$ for evaluation of field quantities
- create 2D grid points
→ extrude to 3D
- connect vertices to tetrahedra with Delaunay condition

Field-line integration



Selected field lines in torus

- Field line equations:

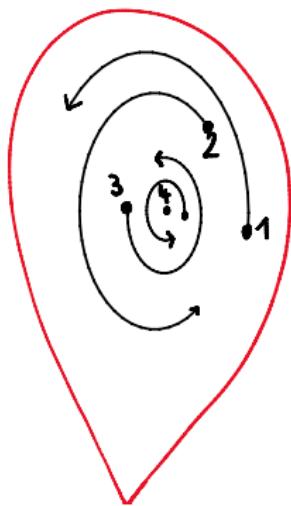
$$\frac{dR}{d\varphi} = \frac{B^R}{B^\varphi}, \quad \frac{dZ}{d\varphi} = \frac{B^Z}{B^\varphi}$$

- Safety factor:

$$q = \frac{B^\varphi}{B^{\vartheta}}, \quad d\varphi = q d\vartheta$$

- if q is irrational, the field line forms a flux surface

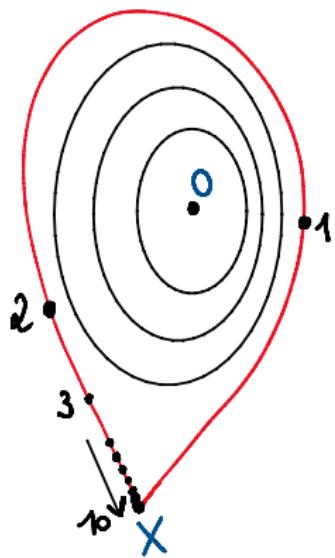
Finding the O -point



Iterative scheme for finding the O – point

- start at point 1, follow \vec{B} for 10 toroidal turns in (R, φ, Z)
- compute average of $(R, Z) \rightarrow$ new starting point for the next iteration
- perform 20 iterations for satisfying accuracy of the magnetic axis

Finding the X-point



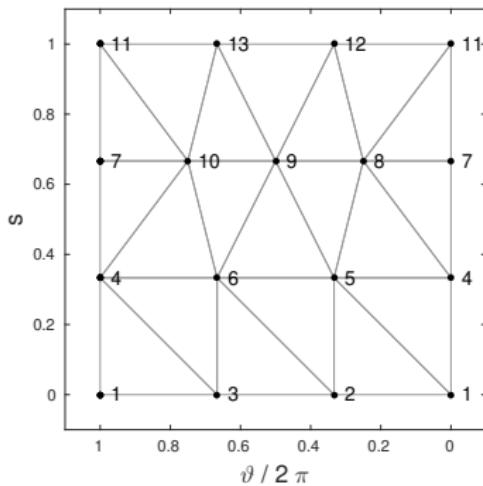
Iterative scheme for finding the *X – point*

- start inside and integrate field line for one poloidal turn
- increase distance to mag. axis and repeat until the field line does not cross → Separatrix
- perform iterative integrations with $\Delta\varphi = 2\pi/10 \rightarrow$ convergence, since $B^{pol} = 0$ at *X*-point

Construct conversion routine from field line data

- parametrize line segment from O -point to X -point
- integrate field lines in equidistant steps for one poloidal turn
- save (R, Z) data $\rightarrow s$ is constant, ϑ is equidistant
- interpolate data for coordinate conversion
 - periodic splines in ϑ
 - lagrange polynomials in s

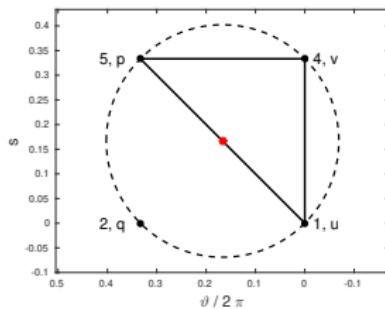
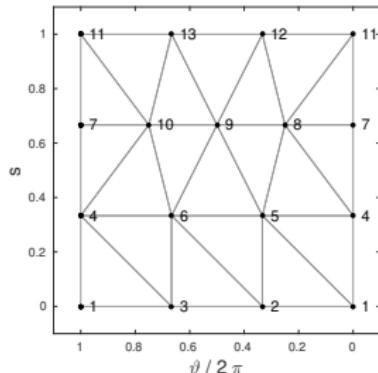
Generate grid vertices



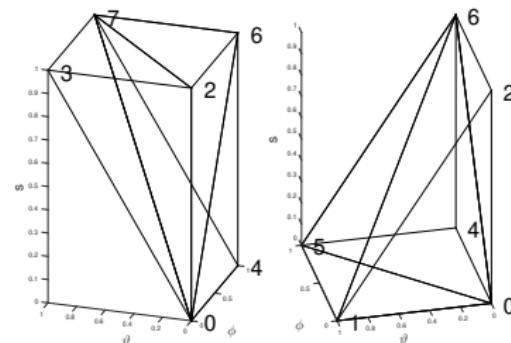
2D grid vertices

- Generate the vertex positions in poloidal plane
 - set number of points per ring
 - scale point distributions according to scaling functions for s, ϑ
- Extrude vertex coordinates toroidally $(s, \vartheta, \varphi = 0) \rightarrow (s, \vartheta, \varphi)$

Mesh tetrahedra using Delaunay condition

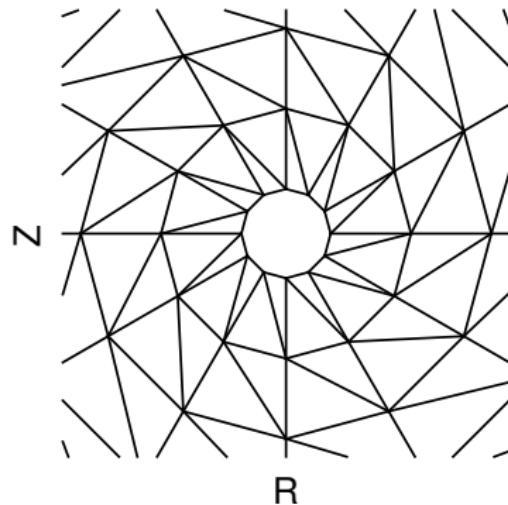
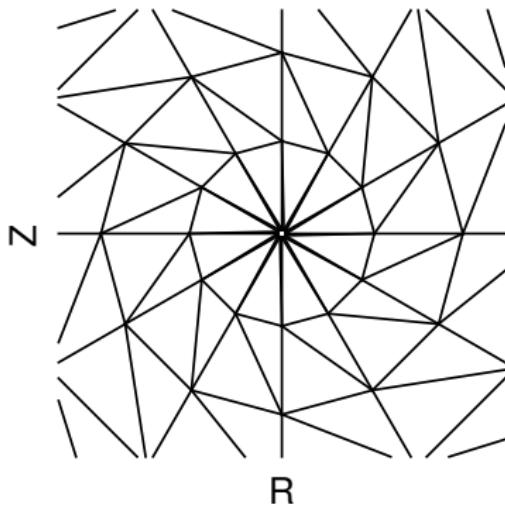


- index vertices to prism face of correct type
→ Delaunay condition



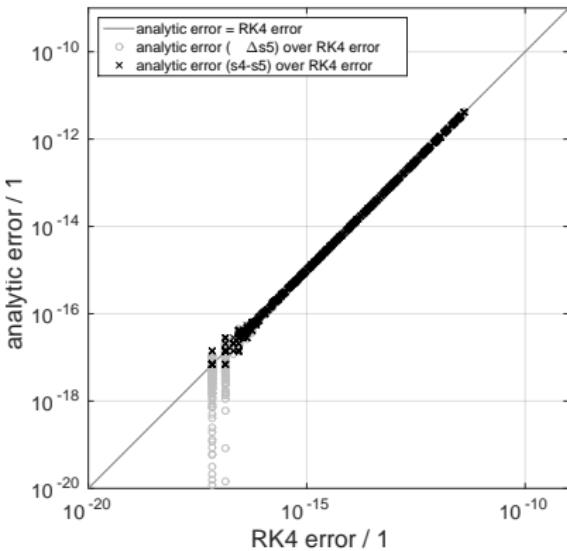
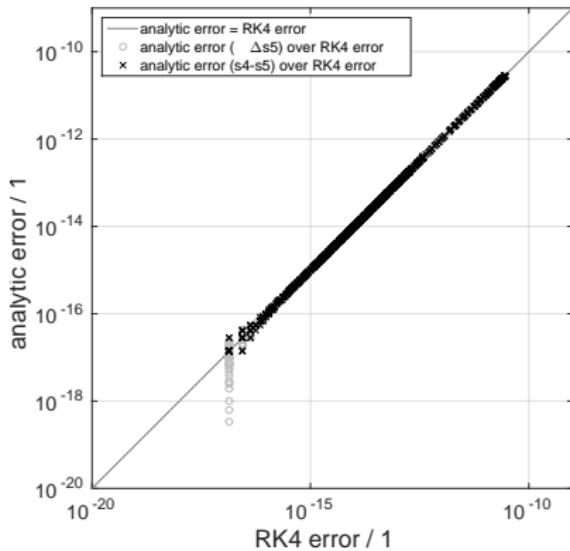
Prism types used for tetrahedra indexing

One compromise: there is a hole



Center region of the grid with annulus

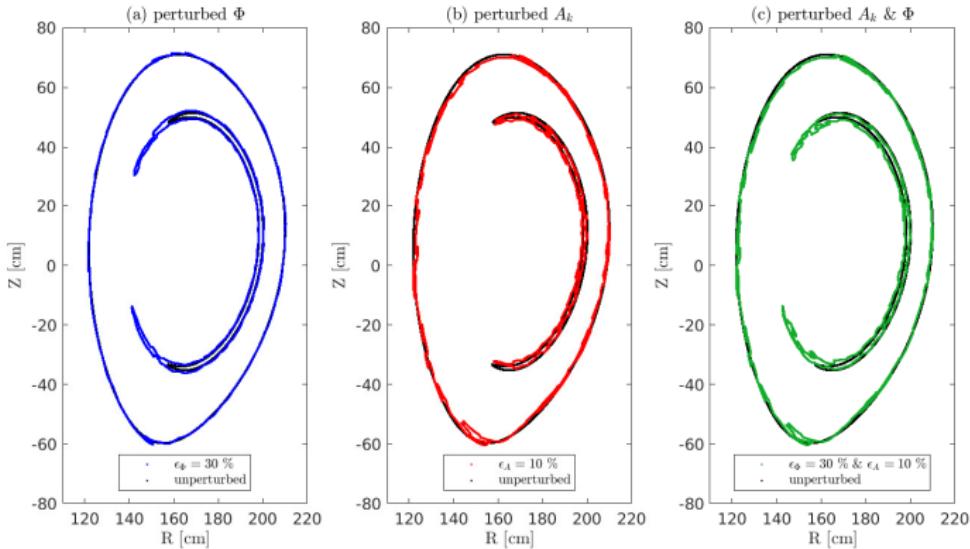
Evaluating the *RK4* error



$$(N_s, N_\vartheta, N_\varphi) = 5 \times 5 \times 5$$

$$(N_s, N_\vartheta, N_\varphi) = 12 \times 12 \times 12$$

Axisymmetric noise of electrostatic and vector potential



- Similar orbit shape (compared to unperturbed orbit)
- Canonical toroidal angular momentum is preserved.