

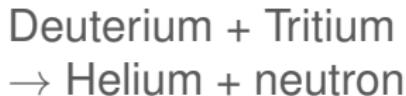
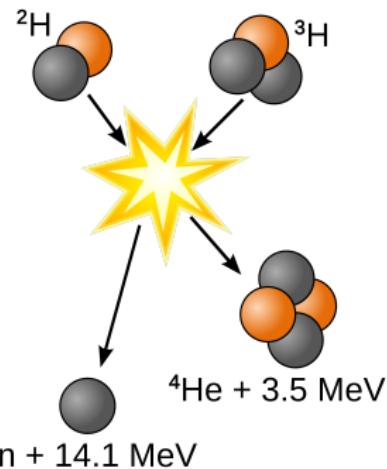
Geometric Integration of Guiding Center Orbits in Magnetically Confined Plasmas and Applications

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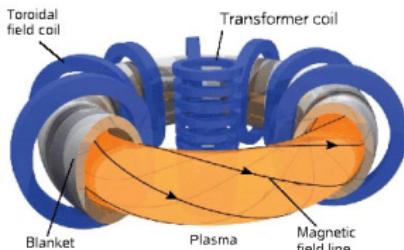
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What is nuclear fusion?

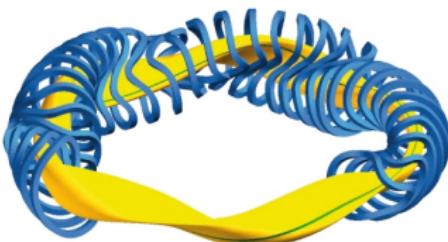


- Two or more atomic nuclei are combined to form one or more different atomic nuclei and subatomic particles
- 17.6 MeV are released as kinetic energy in the case for D+T fusion

What is the current approach to fusion?



Tokamak



Stellarator

- Heating of D-T plasma to $\sim 10^7$ K in toroidal magnetic configuration
- Self sustained reaction according to the Lawson Criterion for the triple product $n\tau T > C$
- Two main types of devices: Tokamaks and Stellarators

Theoretical descriptions of plasmas

■ Magnetohydrodynamics (MHD)

- describes the plasma as an electrically conducting fluid
- only valid at high particle collisionalities
→ velocity distributions are considered to be Maxwellian

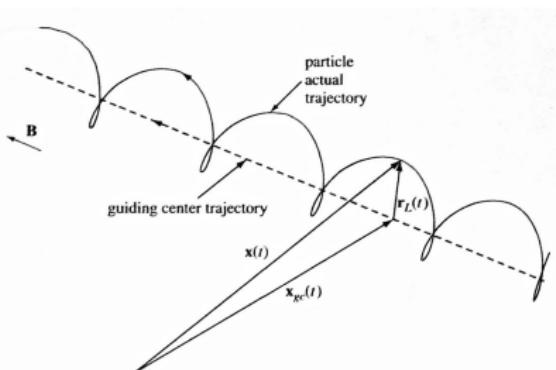
■ Kinetic Approach

- description of plasma through discrete particle distribution functions $f(\vec{x}, \vec{v})$ of phase space
- coupling Vlasov + Maxwell's equations

■ Gyro-kinetic Approach

- averaging over gyrating motion around field lines
- reduced distribution function $f(\vec{x}, v_{\parallel}, v_{\perp})$

Guiding center motion

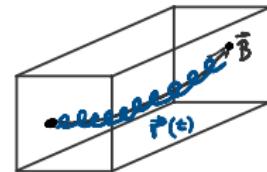


Guiding center motion

- particles gyrate around field lines
- → average over fast gyration
- corrections to motion in form of drifts
- for gyro-kinetic approach many particles need to be traced in boxes

Gorilla guiding center code

- Geometric ORbit Integration with Local Linearisation Approach
- Integration of charged particle guiding center orbits in toroidal fusion devices



Target application - kinetic equilibria

- Kinetic modelling of edge plasmas
- Quasi-steady plasma parameters in 3D toroidal fusion devices
 - Simple (cylindrical) modelling of perturbed tokamak equilibria shows that the problem of shielding of external perturbations is essentially kinetic.
 - 3D equilibria should be computed by using plasma response currents and charges in kinetic approximation.
→ Global Monte Carlo modelling

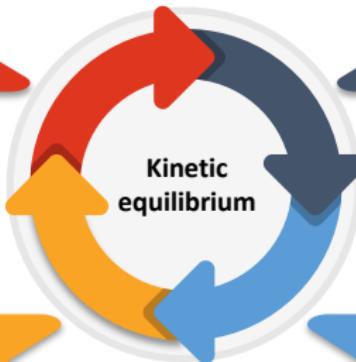
Modelling of kinetic equilibria

Total electromagnetic fields

- update given fields \mathbf{B} , \mathbf{E}

Collisional guiding center orbits

- stochastic particle scattering
- massive calculation of orbits



Contributions to fields

- Finite Element Method (Maxwell solver)
- change in vector potential $\delta\mathbf{A}$
- change in electrostatic potential $\delta\phi$

Moments of distribution function

- box counting of test particles
- charge density $\delta\rho$
- current density $\delta\mathbf{j}$

Requirements to orbit integrator

1. **Physically correct long time orbit dynamics**
2. **Low sensitivity to noise in fields:** Perturbation field from plasma response currents and charges is noisy due to stochasticity of particle collisions (Monte Carlo).
3. **Integrator efficiency:** Millions of orbits should be followed for few collision times at each iteration.
4. **Efficient box counting:** Orbit intersections with boundaries of grid cells should be traced efficiently.

3D geometric integrator properties

- **Physically correct long time orbit dynamics**
 - preserved total energy
 - preserved magnetic moment
 - preserved phase space volume
- **Computationally efficient:** Relaxed requirements to the accuracy of guiding center orbits
 - not exact orbit shape
 - not exact time evolution

Formulation of the geometric integrator

Use the Hamiltonian form of guiding center equations in curvilinear coordinates,

$$\dot{x}^i = \frac{v_{\parallel} \varepsilon^{ijk}}{\sqrt{g} B_{\parallel}^*} \frac{\partial A_k^*}{\partial x^j}, \quad A_k^* = A_k + \frac{v_{\parallel}}{\omega_c} B_k, \quad (1)$$

$$v_{\parallel} = \sigma \left(\frac{2}{m_{\alpha}} (w - J_{\perp} \omega_c - e_{\alpha} \Phi) \right)^{1/2}. \quad (2)$$

Approximate A_k , B_k/ω_c , ω_c and Φ by linear functions in spatial cells with equations of motion

$$\frac{dz^i}{d\tau} = a_k^i z^k + b^i. \quad (3)$$

Physically correct long time orbit dynamics

- Linear approximation of field quantities does **not** destroy the **Hamiltonian nature** of the original guiding center equations.
- Non-canonical Hamiltonian form of linear ODE set

$$\frac{dz^i}{d\tau} = \Lambda^{ij} \frac{\partial H}{\partial z^j}, \quad \Lambda^{ij}(\mathbf{z}) = \{z^i, z^j\}_\tau, \quad (4)$$

with Hamiltonian $H(\mathbf{z}) = v_{||}^2/2 - U(\mathbf{x})$ and antisymmetric Poisson matrix $\Lambda^{ij}(\mathbf{z})$.

- **Symplecticity:** Phase space volume is conserved.

Grid for Gorilla

- Grid necessary for calculations due to
 - linearization of field quantities
 - box counting scheme for distribution function
- guiding center orbits are computed between cell boundaries using a standard *RK4*-integrator

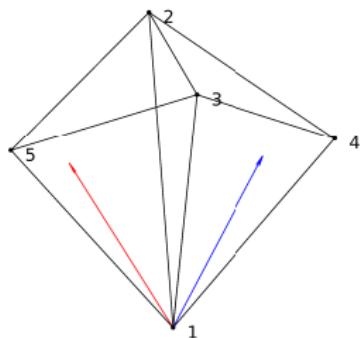
Grid must consist of tetrahedra due to linearization of field quantities

- linear system of equations for $\nabla f = \text{const.}$

$$f(\vec{x}_i) = f(\vec{x}_1) + (\vec{x}_i - \vec{x}_1) \cdot \nabla f, \quad i \in \{1, 2, 3, 4\}$$

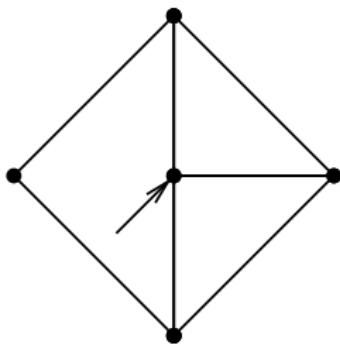
- this system is uniquely defined as the number of unknowns (=4) is equal to the number of values for f
 \rightarrow no fitting for the case of tetrahedra

Linearization leads to continuous f



- influence of points $\{4,5\}$ vanishes on the plane spanned by $\{1,2,3\}$
 $\rightarrow f$ is continuous at cell boundaries
- but: piece-wise constant gradients remain discontinuous at cell boundaries

No hanging nodes

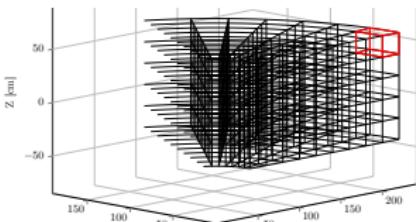


- adjacent tetrahedral faces must share three common vertices for linearized fields to be continuous
→ no hanging nodes!

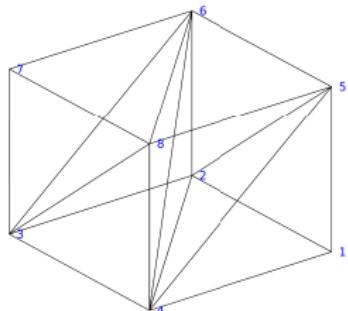
Further requirements

- whole domain must be unambiguously covered by tetrahedra → no holes or overlaps in grid
- tetrahedra must be uniquely indexed, also the corresponding neighboring tetrahedra and the faces through which they are connected
- periodic boundaries must be taken into account due to coordinate jump

Initial grid: cylindrical contour grid



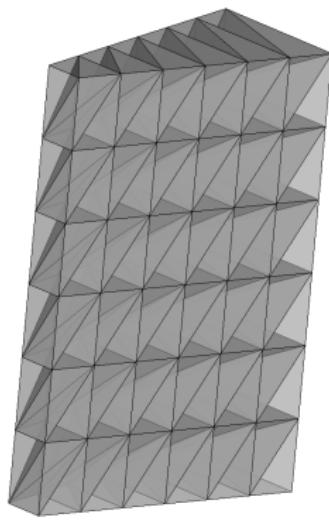
Hexahedra



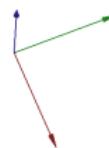
Tetrahedra

- vertices lie on contours of cylindrical coordinates (R, φ, Z)
- hexahedra are obtained by indexing vertices
- each hexahedron is cut into six tetrahedra
- neighboring tetrahedra need to be indexed for logics

Cylindrical contour grid

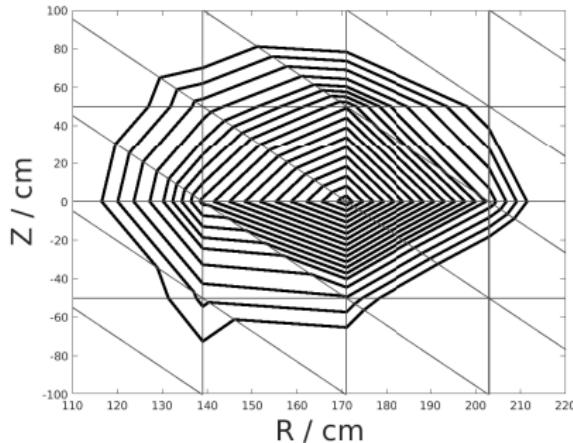


toroidal grid slice



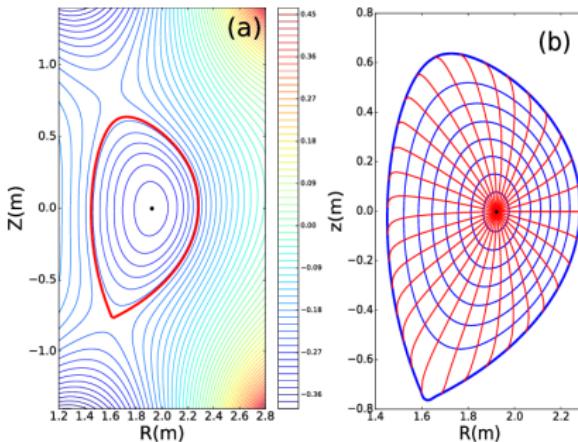
full cylindrical contour grid

Poincaré plots of guiding center orbits



- intersections of orbits with $\varphi = 0$ plane are marked with points
- points lie on well-defined contours
- polygonal shape due to linearization

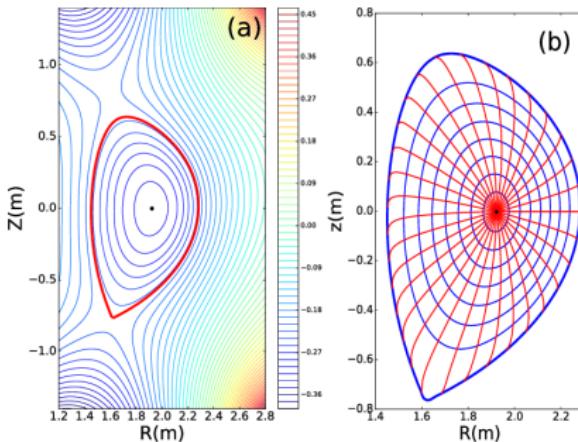
Idea: symmetry flux coordinates



Magnetic field topology

- coordinates (s, ϑ, φ)
 - $s \rightarrow$ minor-radial coordinate
 - $\vartheta \rightarrow$ poloidal coordinate
 - $\varphi \rightarrow$ toroidal coordinate
- field lines assume straight lines in SFC
- $\vec{A} \propto s \rightarrow$ no interpolation error due to linearization

Idea: symmetry flux coordinates

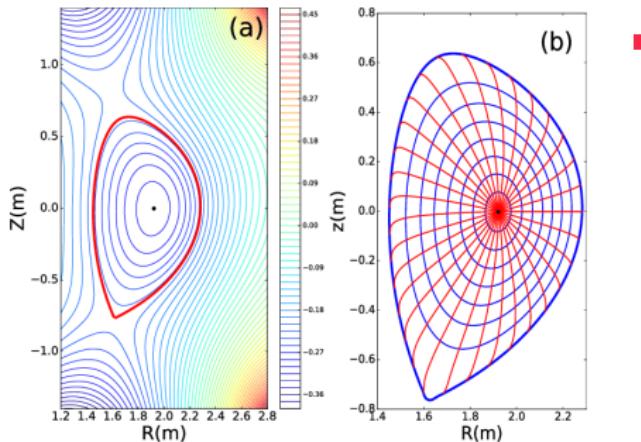


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Problem with CCG: incompatible with SFC

Implementing a field aligned grid



Magnetic field topology

Computational method - efficiency

- Piecewise-constant coefficients of

$$\frac{dz^i}{d\tau} = a_k^i z^k + b^i$$

are discontinuous at cell boundaries.

- Orbit intersections with tetrahedra faces must be computed exactly when integrating particle trajectories.
- The ODE set is numerically solved via **Runge-Kutta 4** in an iterative scheme.
- Iterative scheme uses **Newton's method** and a parabolic analytic estimation for the initial step length.

Error of the RK 4 method

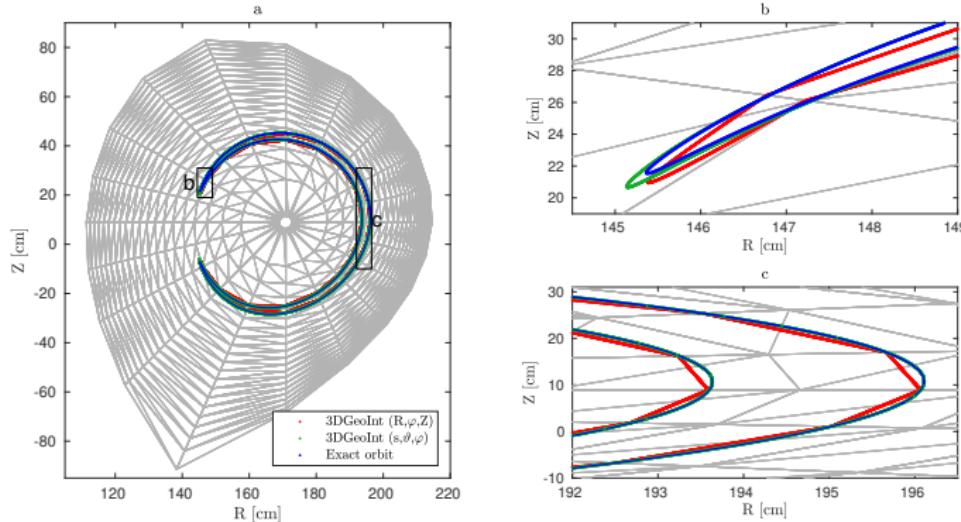
- The relative integration error of a single step between cell boundaries strongly **scales with the Larmor radius ρ** .
- The error is in the order of

$$\frac{\delta R(\Delta\tau)}{a} \sim \frac{\rho^3}{q^4 R^3} \Delta\varphi^5, \quad (5)$$

with R , a , q and $\Delta\varphi$ denoting major radius, plasma radius, safety factor and toroidal cell length.

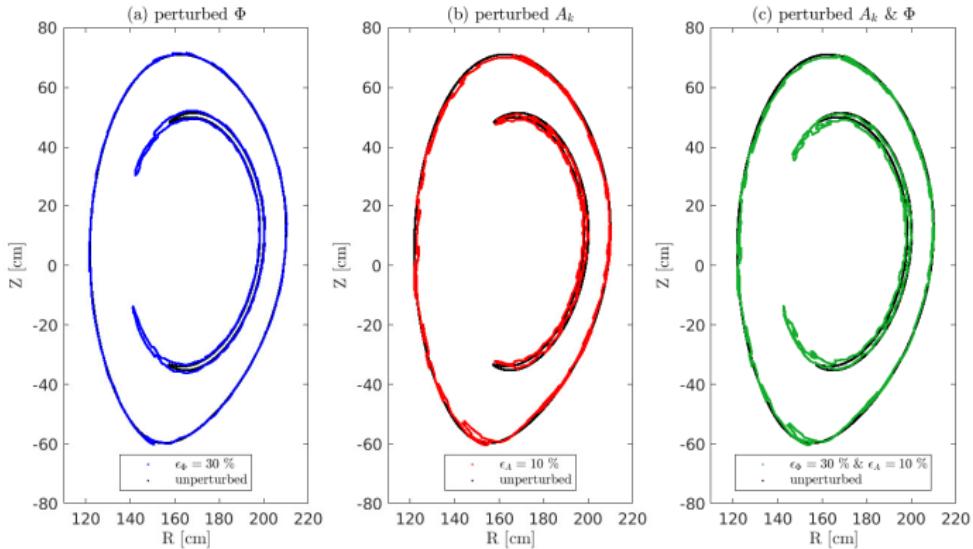
- The **error of the RK4 method** can be brought **below computer accuracy**.

Poincare plots of guiding center orbits



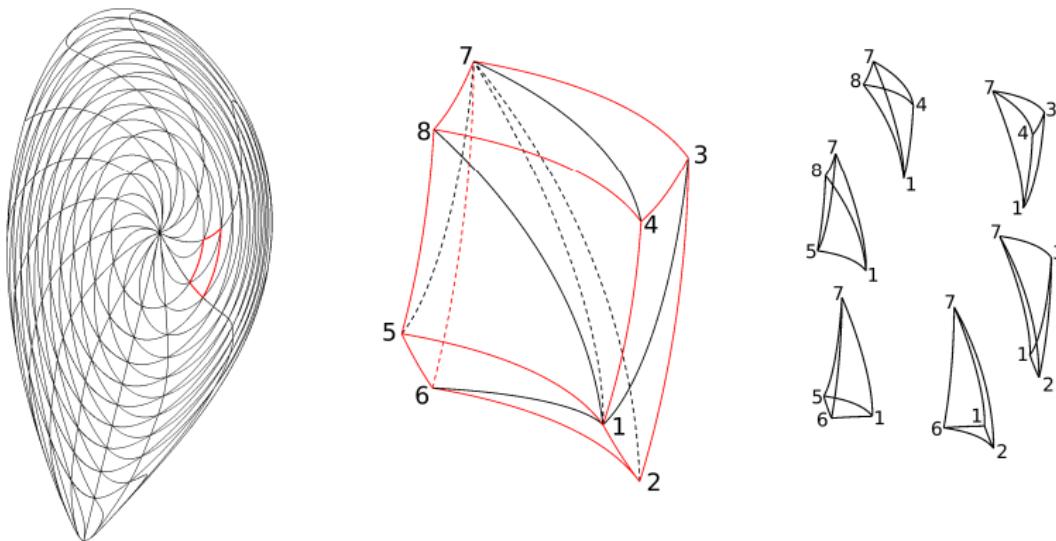
- Geometric integration: Not exact orbit shape.
- Axisymmetric (2D): Canonical toroidal angular momentum is preserved.

Axisymmetric noise of electrostatic and vector potential



- Similar orbit shape (compared to unperturbed orbit)
- Canonical toroidal angular momentum is preserved.

3D field aligned grid: tetrahedral cells



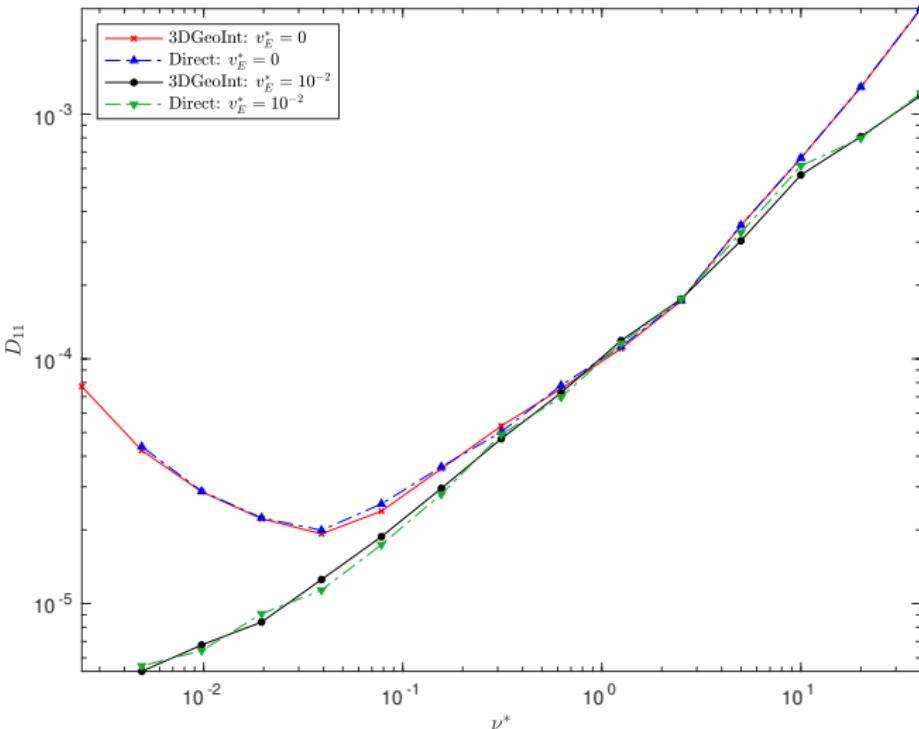
Application: Mono-energetic radial transport coefficient

- Mono-energetic radial transport coefficient as a function of collisionality is evaluated with the Monte Carlo method.
- Collisions are realized by pitch angle scattering (Lorentz scattering operator).

$$\frac{\partial f}{\partial t} = \frac{1}{s(\psi)} \frac{\partial}{\partial \psi} s D \frac{\partial f}{\partial \psi} \quad (6)$$

$$D = D(E, \psi) = \langle \frac{1}{2t} (\psi(t) - \psi(t_0))^2 \rangle \quad (7)$$

Radial Transport in HYDRA (stellarator)



$$\nu^* = \frac{R_0 \nu_c}{\iota V}$$

$$v_E^* = \frac{E_r}{vB_0}$$

Conclusion

Advantages:

- Physically correct long time orbit dynamics
- Particle coordinates and velocities are implicitly given at cell boundaries.
- Low sensitivity to noise in electromagnetic fields
- Computational efficiency

Limitations:

- Artificial numerical diffusion is induced by piecewise linear field quantities.

Thank you for your attention!