## The max-min-hill-climbing algorithm

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M.Sc. Comp. Science

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### MMPC

```
Algorithm 1 MMPC Algorithm
 1: procedure \overline{MMPC} (T,D)
       Input: target variable T; data D
       Output: the parents and children of T in any Bayesian
       network faithfully representing the data distribution
       %Phase I: Forward
       CPC = \emptyset
2:
 3:
       repeat
           \langle F, assocF \rangle = MaxMinHeuristic(T; CPC)
          if assocF \neq 0 then
              CPC = CPC \cup F
 6:
7:
          end if
       until CPC has not changed
8:
       %Phase II: Backward
       for all X \in \mathbf{CPC} do
 9:
          if \exists S \subseteq CPC, s.t. Ind(X;T|S) then
10:
              CPC = CPC \setminus \{X\}
11:
12:
          end if
13:
       end for
       return CPC
14:
15: end procedure
16: procedure MaxMinHeuristic(T.CPC)
       Input: target variable T; subset of variables CPC
       Output: the maximum over all variables of the minimum asso-
       ciation with T relative to CPC, and the variable that achieves
       the maximum
       assocF = \max_{X \in V} MinAssoc(X; T|CPC)
17:
       F = \arg \max_{X \in V} MinAssoc(X; T|CPC)
18:
19:
       return \langle F, assocF \rangle
20: end procedure
```

We define the minimum association of X and T relative to a feature subset  $\mathbf{Z}$ , as

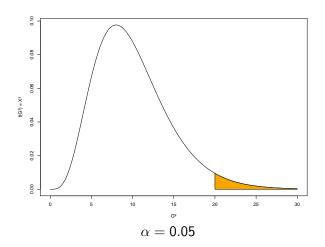
$$MinAssoc(X; T|\mathbf{Z}) = \min_{\mathbf{S} \subseteq \mathbf{Z}} Assoc(X; T|\mathbf{S}). \tag{1}$$

## Definition

We calculate the  $G^2$  value under the nullhypothesis of the conditional independence of  $Ind_P(X_i, X_j | \mathbf{X}_k)$  holding. Then, the  $G^2$  value is defined as:

$$G^{2} := 2 * \sum_{a,b,c} S_{ijk}^{abc} * In \left( \frac{S_{ijk}^{abc} * S_{k}^{c}}{S_{ik}^{ac} * S_{jk}^{bc}} \right), \tag{2}$$

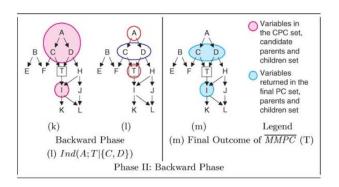
where  $S_{ijk}^{abc}$  is the number of times in the data where  $X_i = a$ ,  $X_j = b$  and  $\mathbf{X}_k = \mathbf{c}$ . We define in a similar fashion  $S_{ik}^{ac}$ ,  $S_{jk}^{bc}$  and  $S_k^c$ , respectively.



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# The last goal:

