OPEN INNOVATION

Problem statement:

To Develop a wearable device that monitors a user's posture using gyroscope and flex sensors with real-time feedback.

Components:

1. Voltage regulator - AP2112K-3.3V.

2. Battery - Li-ion (400mAh, 3.7V).

3. Battery protection - TP4056.4. Gyro - BMI160.

5. Flex
6. Speaker
7. Resistive Flex Sensor.
8. Dynamic Speaker Driver.

7. Audio amplifier - MAX98357A. 8. Mic - SPH0645LM4H.

9. Passive Components - Resistors, Capacitors, Inductors.

10. Controller - Esp-32 pico d4

11.Button, LED

Description:

Using the main controller : esp32-pico-d4 ($7 \text{ mm} \times 7 \text{ mm} \times 0.94 \text{ mm}$) we give power supply and all the inputs to sensors and other components.

Voltage regulator(AP2112K- $2.9~\text{mm} \times 2.9~\text{mm} \times 1.45~\text{mm}$) is used to reduce the voltage to 3.3V when needed for protection.

For power supply we have used Li-ion (400mAh, 3.7V)battery because of less power consumption and it is rechargeable

Gyro (BMI160 $2.5 \times 3.0 \text{ mm}^2 \times 0.8 \text{ mm}$) and flex sensors (2inch) are used to detect posture.

Speaker placed inside earbud to give audio feedback connected with mic and audio amplifier(MAX98357A - 1.345×1.435 mm $\times 0.64$ mm)

Mic for speaking purposes during meetings and calls(SPH0645LM4H - $3.5\times2.65\times0.98~mm$)

Passive Components are used to make your system run smoothly

i.e Resistors = current control flow

Capacitors = Stores current

Inductors = coiled pipes that resist sudden flow changes.

Button is used to on or off, play or pause and led is used to indicate whether on or off.