# **GDataSet**

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## Introduction

GDataSet is a C library to manipulate generic data sets.

It offers the following functionalities:

- loading a data set from its description file
- splitting the data set into user defined categories (e.g. training, validation, test)
- shuffling the data set

- looping through the samples of the data set.
- centering on the mean, normalizing, getting the covariance of two variables, getting the covariance matrix for dataset of type VecFloat

It provides an unique interface to several implementation supporting various types of dataset. Supported types are: VecFloat and pair of GenBrush (img/mask).

The GDataSet library uses the PBErr, GSet, PBJson, PBMath and PBFileSys libraries.

### 1 Interface

```
// ====== GDATASET_H ========
#ifndef GDATASET H
#define GDATASET_H
// ========= Include =========
#include <stdlib.h>
#include <stdio.h>
#include <stdbool.h>
#include <execinfo.h>
#include <errno.h>
#include <string.h>
#include "pberr.h"
#include "gset.h"
#include "pbmath.h"
#include "pbjson.h"
#include "pbfilesys.h"
#include "neuranet.h"
// Define locally the needed types and functions for libraries that were
// not included to allow the user to include only what's needed for her
// application
#ifndef GENBRUSH_H
typedef struct GenBrush GenBrush;
typedef enum GBScaleMethod {GBScaleMethod_Default} GBScaleMethod;
GenBrush* GBCreateFromFile(const char* const fileName);
GenBrush* GBScale(const GenBrush* const that,
  const VecShort2D* const dim, const GBScaleMethod scaleMethod);
void GBFree(GenBrush** that);
VecShort2D* GBDim(const GenBrush* const that);
void _GDSGenBrushPairRemoveAllSample();
void _GDSGenBrushPairAddSample();
#endif
// ======= Define ========
typedef enum GDataSetType {
  GDataSetType_VecFloat, GDataSetType_GenBrushPair
} GDataSetType;
```

```
// ======= Data structures =========
typedef struct GDataSet {
 // Name of the data set
 char* _name;
 \ensuremath{//} Description of the data set
 char* _desc;
  // Type of set
 GDataSetType _type;
 // Nb of samples
 long _nbSample;
  // Set of samples
 GSet _samples;
  // Dimensions of each sample, they must have all the same dimension
  // e.g.:
 // if samples are VecFloat<3> then _dim = VecShort<1>[3]
  // if samples are GenBrush then _dim = VecShort<2>[width, height]
  VecShort* _sampleDim;
 short _nbInputs;
 short _nbOutputs;
  // Splitting of samples
 VecLong* _split;
  // Sets of splitted samples
 GSet* _categories;
  // Iterators on the sets of splitted samples
 GSetIterForward* _iterators;
} GDataSet;
typedef struct GDataSetVecFloat {
  // Generic GDataSet
 GDataSet _dataSet;
} GDataSetVecFloat;
typedef struct GDataSetGenBrushPair {
 // Generic GDataSet
 GDataSet _dataSet;
 // Format of images
 char* _format;
  // Dimensions of images
 VecShort2D _dim;
 // Nb of mask per img
 int _nbMask;
 // Path to the config file of the data set
 char* _cfgFilePath;
} GDataSetGenBrushPair;
#define GDS_NBMAXMASK 100
typedef struct GDSFilePathPair {
  char* _path[1 + GDS_NBMAXMASK];
} GDSFilePathPair;
typedef struct GDSGenBrushPair {
 GenBrush* _img;
 GenBrush* _mask[GDS_NBMAXMASK];
} GDSGenBrushPair;
typedef struct GDSVecFloatCSVImporter {
  // Size (nb of lines) of the header
 unsigned int _sizeHeader;
 // Separator
 char _sep;
```

```
// Number of column in CSV
  unsigned int _nbCol;
  // Size of the resulting sample
  unsigned int _sizeSample;
  // Field converter function
  void (*_converter)(
    int col,
    char* val,
    VecFloat* sample);
} GDSVecFloatCSVImporter;
// ========= Functions declaration =========
// Create a new GDataSet of type 'type'
GDataSet GDataSetCreateStatic(GDataSetType type);
// Free the memory used by a GDataSet
void GDataSetFreeStatic(GDataSet* const that);
// Load the GDataSet 'that' from the stream 'stream'
// Return true if the GDataSet could be loaded, false else
bool GDataSetLoad(GDataSet* that, FILE* const stream);
bool _GDSLoad(GDataSet* that, FILE* const stream);
// Function which decode from JSON encoding 'json' to 'that'
bool GDataSetDecodeAsJSON(GDataSet* that, const JSONNode* const json);
// Create a new GDataSetVecFloat defined by the file at 'cfgFilePath'
GDataSetVecFloat GDataSetVecFloatCreateStaticFromFile(
  const char* const cfgFilePath);
// Reset the categories of the GDataSet 'that' to one unshuffled
// category
void GDSResetCategories(GDataSet* const that);
// Function which decode from JSON encoding 'json' to 'that'
bool GDataSetVecFloatDecodeAsJSON(GDataSetVecFloat* that,
  const JSONNode* const json);
// Function which return the JSON encoding of 'that'
JSONNode* GDataSetVecFloatEncodeAsJSON(
  const GDataSetVecFloat* const that);
// Function which return the JSON encoding of the category 'iCat'
// of'that'
JSONNode* GDataSetVecFloatEncodeCategoryAsJSON(
  const GDataSetVecFloat* const that,
             const unsigned int iCat);
// Function which decode from JSON encoding 'json' to 'that'
bool GDataSetGenBrushPairDecodeAsJSON(GDataSetGenBrushPair* that,
  const JSONNode* const json);
// Free the memory used by a GDataSetVecFloat
void GDataSetVecFloatFreeStatic(GDataSetVecFloat* const that);
// Create a new GDataSetGenBrushPair defined by the file at 'cfgFilePath'
{\tt GDataSetGenBrushPair\ GDataSetGenBrushPairCreateStaticFromFile} (
  const char* const cfgFilePath);
// Free the memory used by a GDataSetGenBrushPair
void GDataSetGenBrushPairFreeStatic(GDataSetGenBrushPair* const that);
```

```
// Get the total number of samples in the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
long _GDSGetSize(const GDataSet* const that);
// Get the number of input values in one sample of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
short _GDSGetNbInputs(const GDataSet* const that);
// Get the number of output values in one sample of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
short _GDSGetNbOutputs(const GDataSet* const that);
// Set the number of input values in one sample of the GDataSet 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void _GDSSetNbInputs(GDataSet* const that, const short nb);
// Set the number of output values in one sample of the GDataSet 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void _GDSSetNbOutputs(GDataSet* const that, const short nb);
// Get the number of masks in the GDataSet 'that'
int _GDSGetNbMask(const GDataSet* const that);
// Get the number of masks in the GDataSetGenBrushPair 'that'
#if BUILDMODE != 0
static inline
#endif
int GDSGetNbMaskGenBrushPair(const GDataSetGenBrushPair* const that);
// Get the total number of samples in the GDataSet 'that' for the
// category 'iCat'. Return 0 if the category doesn't exists
#if BUILDMODE != 0
static inline
#endif
long _GDSGetSizeCat(const GDataSet* const that, const long iCat);
// Split the samples of the GDataSet 'that' into several categories
// defined by 'cat'. The dimension of 'cat' gives the number of
// categories and the value for each dimension of 'cat' gives the
// number of samples in the corresponding category. For example <3,4>
// would mean 2 categories with 3 samples in the first one and 4
// samples in the second one. There must me at least as many samples
// in the data set as the sum of samples in 'cat'.
// Each category must have at least one sample.
// If 'that' was already splitted the previous splitting is discarded.
void _GDSSplit(GDataSet* const that, const VecLong* const cat);
// Unsplit the GDataSet 'that', i.e. after calling GDataSetUnsplit 'that'
// has only one category containing all the samples
#if BUTLDMODE != 0
static inline
```

```
#endif
void _GDSUnsplit(GDataSet* const that);
// Shuffle the samples of the GDataSet 'that'.
#if BUILDMODE != 0
static inline
#endif
void _GDSShuffle(GDataSet* const that);
// Shuffle the samples of the category 'iCat' of the GDataSet 'that'.
// Reset the iterator of the category
#if BUILDMODE != 0
static inline
#endif
void _GDSShuffleCat(GDataSet* const that, const long iCat);
// Shuffle the samples of all the categories of the GDataSet 'that'.
// Reset the iterator of the categories
#if BUILDMODE != 0
static inline
#endif
void _GDSShuffleAll(GDataSet* const that);
// Get the name of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
const char* _GDSName(const GDataSet* const that);
// Get the description of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
const char* _GDSDesc(const GDataSet* const that);
// Get the type of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
GDataSetType _GDSGetType(const GDataSet* const that);
// Get the number of categories of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
long _GDSGetNbCat(const GDataSet* const that);
// If there is a next sample move to the next sample of the category
\ensuremath{//} 'iCat' and return true, else return false
#if BUILDMODE != 0
static inline
#endif
bool _GDSStepSample(const GDataSet* const that, const long iCat);
// Reset the iterator on category 'iCat' of the GDataSet 'that', i.e.
// the next call to GDataSetGetNextSample will give the first sample of
// the category 'iCat'
#if BUILDMODE != 0
static inline
#endif
void _GDSReset(GDataSet* const that, const long iCat);
```

```
// Reset the iterator on all categories of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
void _GDSResetAll(GDataSet* const that);
// Get the current sample in the category 'iCat' of the GDataSet 'that'
void* _GDSGetSample(
  const GDataSet* const that, const int iCat);
VecFloat* GDSGetSampleVecFloat(
  const GDataSetVecFloat* const that, const int iCat);
GDSGenBrushPair* GDSGetSampleGenBrushPair(
  const GDataSetGenBrushPair* const that, const int iCat);
// Get the inputs of the current sample in the category 'iCat' of
// the GDataSet 'that'
VecFloat* GDSGetSampleInputsVecFloat(
  const GDataSetVecFloat* const that, const int iCat);
// Get the outputs of the current sample in the category 'iCat' of
// the GDataSet 'that'
VecFloat* GDSGetSampleOutputsVecFloat(
  const GDataSetVecFloat* const that, const int iCat);
// Release the memory used by the FilePathPair 'that'
void GDSFilePathPairFree(GDSFilePathPair** const that);
#ifdef GENBRUSH_H
// Release the memory used by the GenBrushPair 'that'
void GDSGenBrushPairFree(GDSGenBrushPair** const that);
// Get the dimensions of the samples of GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
const VecShort* _GDSSampleDim(const GDataSet* const that);
// Get the samples of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
const GSet* _GDSSamples(const GDataSet* const that);
#if BUILDMODE != 0
static inline
#endif
const GSetVecFloat* _GDSVecFloatSamples(
  const GDataSetVecFloat* const that);
#if BUILDMODE != 0
static inline
#endif
const GSet* _GDSGenBrushPairSamples(
  const GDataSetGenBrushPair* const that);
// Center the GDataSet 'that' on its mean
void GDSMeanCenter(GDataSetVecFloat* const that);
// Center the inputs of the GDataSet 'that' on its mean
void GDSMeanCenterInputs(GDataSetVecFloat* const that);
// Normalize the GDataSet 'that', ie normalize each of its vectors
void GDSNormalize(GDataSetVecFloat* const that);
```

```
// Normalize the inputs of GDataSet 'that', ie normalize each of its
// input vectors
void GDSNormalizeInputs(GDataSetVecFloat* const that);
// Get the mean of the GDataSet 'that'
VecFloat* GDSGetMean(const GDataSetVecFloat* const that);
// Get the max of the GDataSet 'that'
VecFloat* GDSGetMax(const GDataSetVecFloat* const that);
// Get a clone of the GDataSet 'that'
// All the data in the GDataSet are cloned except for the splitting
// categories which are reset to one category made of the original data
GDataSetVecFloat GDSClone(const GDataSetVecFloat* const that);
// Get the covariance matrix of the GDataSetVecFloat 'that'
MatFloat* GDSGetCovarianceMatrix(const GDataSetVecFloat* const that);
// Get the covariance matrix of inputs of the GDataSetVecFloat 'that'
MatFloat* GDSGetInpCovarianceMatrix(const GDataSetVecFloat* const that);
// Get the covariance of the variables at 'indices' in the
// GDataSetVecFloat 'that'
float GDSGetCovariance(const GDataSetVecFloat* const that,
  const VecShort2D* const indices);
// Create a GDataSetVecFloat by importing the CSV file 'csvPath' and
// decoding it with the 'importer'
// Return an empty GDatasetVecFloat if the importation failed
GDataSetVecFloat GDataSetCreateStaticFromCSV(
                    const char* const csvPath,
  const GDSVecFloatCSVImporter* const importer);
// Create a CSV importer for a GDataSetVecFloat
GDSVecFloatCSVImporter GDSVecFloatCSVImporterCreateStatic(
  const unsigned int sizeHeader,
          const char sep,
  const unsigned int nbCol,
  const unsigned int sizeSample,
                void (*converter)(
                  int col,
                  char* val,
                  VecFloat* sample));
// Save the GDataSetVecFloat to the stream
// If 'compact' equals true it saves in compact form, else it saves in
// readable form
// Return true upon success else false
bool GDSVecFloatSave(
  const GDataSetVecFloat* const that,
                    FILE* const stream,
                     const bool compact):
// Save the category 'iCat' of the GDataSetVecFloat to the stream
// If 'compact' equals true it saves in compact form, else it saves in
// readable form
// Return true upon success else false
bool GDSVecFloatSaveCategory(
  const GDataSetVecFloat* const that,
                   FILE* const stream,
                     const bool compact,
                      const int iCat);
```

```
// Run the prediction by the NeuraNet 'nn' on each sample of the category
// 'iCat' of the GDataSet 'that'. The index of columns in the samples
// for inputs and outputs are given by 'iInputs' and 'iOutputs'.
// Stop the prediction of samples when the result can't get better
// than 'threshold'
// Return the value of the NeuraNet on the predicted samples, defined
// as sum_samples(||output_sample-output_neuranet||)/nb_sample
// Higher is better, 0.0 is best value
float GDataSetVecFloatEvaluateNN(
  const GDataSetVecFloat* const that,
  const NeuraNet* const nn.
  const int iCat.
  const VecShort* const iInputs,
  const VecShort* const iOutputs,
  const float threshold);
// Create a new GDataSetVecFloat
GDataSetVecFloat GDataSetVecFloatCreateStatic(void);
// Remove all the samples of the GDataSetVecFloat 'that'
#if BUILDMODE != 0
static inline
#endif
void _GDSVecFloatRemoveAllSample(GDataSetVecFloat* const that);
// Remove all the samples of the GDataSetGenBrushPair 'that'
#ifdef GENBRUSH_H
#if BUTLDMODE != 0
static inline
#endif
void _GDSGenBrushPairRemoveAllSample(GDataSetGenBrushPair* const that);
#endif
// Append 'sample' in the GDataSetVecFloat 'that'
#if BUILDMODE != 0
static inline
#endif
void _GDSVecFloatAddSample(
  GDataSetVecFloat* const that,
  VecFloat* sample);
// Append 'sample' in the GDataSetGenBrush 'that'
#ifdef GENBRUSH_H
#if BUTI.DMODE != 0
static inline
#endif
void _GDSGenBrushPairAddSample(
  GDataSetGenBrushPair* const that,
  GDSGenBrushPair* sample);
#endif
// Get the proximity matrix of the samples of category 'iCat' in the
// GDataSetVecFloat 'that'
// M[i,j] = euclidean distance between the i-th sample and the j-th sample
MatFloat* GDSVecFloatGetProxMat(
  const GDataSetVecFloat* that,
             unsigned int iCat);
// Get the nearest (in term of euclidean distance) sample of category
// 'iCat' to 'target' in the GDataSetVecFloat 'that' using the AESA
// nearest neighbour search
```

```
// TODO: should use a lookup table to get VecDist(sample, prevCandidate)
// but it's complicated by the fact I'm loosing the index of samples when
// using GSet
// Also, even if using a lookup table, and even if AESA actually reduces
// efficiently the number of VecDist(candidate, target), the cost of
// VecDist() much be hugely bigger than the one of using a lookup table
// to make AESA relevant. It's probably meaningless on a VecFloat,
// maybe more meaningful on a GenBrush ?
// http://citeseerx.ist.psu.edu/viewdoc/download?
// doi=10.1.1.481.2200&rep=rep1&type=pdf
VecFloat* GDSVecFloatNearestNeighbourAESA(
 const GDataSetVecFloat* that,
         const VecFloat* target,
                     int iCat);
// Get the nearest (in term of euclidean distance) sample of category
// 'iCat' to 'target' in the GDataSetVecFloat 'that' using brute force
VecFloat* GDSVecFloatNearestNeighbourBrute(
  const GDataSetVecFloat* that,
         const VecFloat* target,
                     int iCat):
// Check if the 'iSample'-th sample in the category 'iCat' of the
// GDataSetVecFloat 'that' is an outlier. The outliers are identified as follow.
// For each sample, the nearest (in term of euclidian distance of inputs)
// sample with same output values is searched. Then, the number of nearer
// samples with different output values (called "opponents") is calculated.
// Finally, if there is more than 'nbOpponent' opponents, the sample is
// considered to be an outlier. The lower 'nbOpponent' is the more samples
// will be considered as outliers.
bool GDSVecFloatIsOutlierSampleCat(
  const GDataSetVecFloat* that,
         const VecFloat* sample,
                    long iCat,
             unsigned int nbOpponent);
// ======== Polymorphism =========
#define GDSRemoveAllSample(DataSet) _Generic(DataSet, \
  GDataSetVecFloat*: _GDSVecFloatRemoveAllSample, \
  GDataSetGenBrushPair*: _GDSGenBrushPairRemoveAllSample, \
  default: PBErrInvalidPolymorphism)(DataSet)
#define GDSAddSample(DataSet, Sample) _Generic(DataSet, \
  GDataSetVecFloat*: _GDSVecFloatAddSample, \
  GDataSetGenBrushPair*: _GDSGenBrushPairAddSample, \
  default: PBErrInvalidPolymorphism)(DataSet, Sample)
#define GDSDesc(DataSet) _Generic(DataSet, \
  GDataSet*: _GDSDesc, \
  const GDataSet*: _GDSDesc, \
  GDataSetVecFloat*: _GDSDesc, \
  const GDataSetVecFloat*: _GDSDesc, \
  GDataSetGenBrushPair*: _GDSDesc, \
  const GDataSetGenBrushPair*: _GDSDesc, \
  default: PBErrInvalidPolymorphism)((const GDataSet*)DataSet)
#define GDSGetNbCat(DataSet) _Generic(DataSet, \
  GDataSet*: _GDSGetNbCat, \
  const GDataSet*: _GDSGetNbCat, \
  GDataSetVecFloat*: _GDSGetNbCat, \
  const GDataSetVecFloat*: _GDSGetNbCat, \
```

```
GDataSetGenBrushPair*: _GDSGetNbCat, \
 const GDataSetGenBrushPair*: _GDSGetNbCat, \
 default: PBErrInvalidPolymorphism)((const GDataSet*)DataSet)
#define GDSGetSample(DataSet, ICat) _Generic(DataSet, \
 GDataSet*: _GDSGetSample, \
 const GDataSet*: _GDSGetSample, \
 GDataSetVecFloat*: GDSGetSampleVecFloat, \
 const GDataSetVecFloat*: GDSGetSampleVecFloat, \
 GDataSetGenBrushPair*: GDSGetSampleGenBrushPair, \
 const GDataSetGenBrushPair*: GDSGetSampleGenBrushPair, \
 default: PBErrInvalidPolymorphism)(DataSet, ICat)
#define GDSGetSampleInputs(DataSet, ICat) _Generic(DataSet, \
 GDataSetVecFloat*: GDSGetSampleInputsVecFloat, \
 const GDataSetVecFloat*: GDSGetSampleInputsVecFloat, \
 default: PBErrInvalidPolymorphism)(DataSet, ICat)
#define GDSGetSampleOutputs(DataSet, ICat) _Generic(DataSet, \
 GDataSetVecFloat*: GDSGetSampleOutputsVecFloat, \
 const GDataSetVecFloat*: GDSGetSampleOutputsVecFloat, \
 default: PBErrInvalidPolymorphism)(DataSet, ICat)
#define GDSGetSize(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSGetSize, \
 const GDataSet*: _GDSGetSize, \
 GDataSetVecFloat*: _GDSGetSize, \
 const GDataSetVecFloat*: _GDSGetSize, \
 GDataSetGenBrushPair*: _GDSGetSize, \
 const GDataSetGenBrushPair*: _GDSGetSize, \
 default: PBErrInvalidPolymorphism)((const GDataSet*)DataSet)
#define GDSGetSizeCat(DataSet, ICat) _Generic(DataSet, \
 GDataSet*: _GDSGetSizeCat, \
 const GDataSet*: _GDSGetSizeCat, \
 GDataSetVecFloat*: _GDSGetSizeCat, \
 const GDataSetVecFloat*: _GDSGetSizeCat, \
 GDataSetGenBrushPair*: _GDSGetSizeCat, \
 const GDataSetGenBrushPair*: _GDSGetSizeCat, \
 default: PBErrInvalidPolymorphism)((const GDataSet*)DataSet, ICat)
#define GDSGetType(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSGetType, \
 const GDataSet*: _GDSGetType, \
 GDataSetVecFloat*: _GDSGetType, \
 const GDataSetVecFloat*: _GDSGetType, \
 GDataSetGenBrushPair*: _GDSGetType, \
 const GDataSetGenBrushPair*: _GDSGetType, \
 default: PBErrInvalidPolymorphism)((const GDataSet*)DataSet)
#define GDSName(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSName, \
 const GDataSet*: _GDSName, \
 GDataSetVecFloat*: _GDSName, \
 const GDataSetVecFloat*: _GDSName, \
 GDataSetGenBrushPair*: _GDSName, \
 const GDataSetGenBrushPair*: _GDSName, \
 default: PBErrInvalidPolymorphism)((const GDataSet*)DataSet)
#define GDSGetNbMask(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSGetNbMask, \
 const GDataSet*: _GDSGetNbMask, \
```

```
GDataSetGenBrushPair*: GDSGetNbMaskGenBrushPair, \
 default: PBErrInvalidPolymorphism)(DataSet)
#define GDSReset(DataSet, ICat) _Generic(DataSet, \
 GDataSet*: _GDSReset, \
 const GDataSet*: _GDSReset, \
 GDataSetVecFloat*: _GDSReset, \
 const GDataSetVecFloat*: _GDSReset, \
 GDataSetGenBrushPair*: _GDSReset, \
 const GDataSetGenBrushPair*: _GDSReset, \
 default: PBErrInvalidPolymorphism)((GDataSet*)DataSet, ICat)
#define GDSResetAll(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSResetAll, \
 const GDataSet*: _GDSResetAll, \
 GDataSetVecFloat*: _GDSResetAll, \
 \verb|const GDataSetVecFloat*: \_GDSResetAll, \  \  \setminus \\
 GDataSetGenBrushPair*: _GDSResetAll, \
 const GDataSetGenBrushPair*: _GDSResetAll, \
 default: PBErrInvalidPolymorphism)((GDataSet*)DataSet)
#define GDSSampleDim(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSSampleDim, \
 const GDataSet*: _GDSSampleDim, \
 GDataSetVecFloat*: _GDSSampleDim, \
 const GDataSetVecFloat*: _GDSSampleDim, \
 GDataSetGenBrushPair*: _GDSSampleDim, \
 const GDataSetGenBrushPair*: _GDSSampleDim, \
 default: PBErrInvalidPolymorphism)((const GDataSet*)DataSet)
#define GDSShuffle(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSShuffle, \
 GDataSetVecFloat*: _GDSShuffle, \
 GDataSetGenBrushPair*: _GDSShuffle, \
 default: PBErrInvalidPolymorphism)((GDataSet*)DataSet)
#define GDSShuffleCat(DataSet, ICat) _Generic(DataSet, \
 GDataSet*: _GDSShuffleCat, \
 GDataSetVecFloat*: _GDSShuffleCat, \
 GDataSetGenBrushPair*: _GDSShuffleCat, \
 default: PBErrInvalidPolymorphism)((GDataSet*)DataSet, ICat)
#define GDSShuffleAll(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSShuffleAll, \
 GDataSetVecFloat*: _GDSShuffleAll, \
 GDataSetGenBrushPair*: _GDSShuffleAll, \
 default: PBErrInvalidPolymorphism)((GDataSet*)DataSet)
#define GDSSplit(DataSet, Cat) _Generic(DataSet, \
 GDataSet*: _Generic(Cat, \
   VecLong*: _GDSSplit, \
   const VecLong*: _GDSSplit, \
   VecLong2D*: _GDSSplit, \
   const VecLong2D*: _GDSSplit, \
   VecLong3D*: _GDSSplit, \
 const VecLong3D*: _GDSSplit), \
GDataSetVecFloat*: _Generic(Cat, \
   VecLong*: _GDSSplit, \
   const VecLong*: _GDSSplit, \
   VecLong2D*: _GDSSplit, \
   const VecLong2D*: _GDSSplit, \
```

```
VecLong3D*: _GDSSplit, \
   const VecLong3D*: _GDSSplit), \
 GDataSetGenBrushPair*: _Generic(Cat, \
   VecLong*: _GDSSplit, \
   const VecLong*: _GDSSplit, \
   VecLong2D*: _GDSSplit, \
   const VecLong2D*: _GDSSplit, \
   VecLong3D*: _GDSSplit, \
   const VecLong3D*: _GDSSplit), \
 default: PBErrInvalidPolymorphism)((GDataSet*)DataSet, (const VecLong*)Cat)
\verb|#define GDSStepSample(DataSet, ICat) _Generic(DataSet, \\ \\ \setminus
 GDataSet*: _GDSStepSample, \
 const GDataSet*: _GDSStepSample, \
 GDataSetVecFloat*: _GDSStepSample, \
 const GDataSetVecFloat*: _GDSStepSample, \
 GDataSetGenBrushPair*: _GDSStepSample, \
 const GDataSetGenBrushPair*: _GDSStepSample, \
 default: PBErrInvalidPolymorphism)((const GDataSet*)DataSet, ICat)
#define GDSUnsplit(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSUnsplit, \
 GDataSetVecFloat*: _GDSUnsplit, \
 GDataSetGenBrushPair*: _GDSUnsplit, \
 default: PBErrInvalidPolymorphism)((GDataSet*)DataSet)
#define GDSSamples(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSSamples, \
 const GDataSet*: _GDSSamples, \
 GDataSetVecFloat*: _GDSVecFloatSamples, \
 const GDataSetVecFloat*: _GDSVecFloatSamples, \
 GDataSetGenBrushPair*: _GDSGenBrushPairSamples, \
 const GDataSetGenBrushPair*: _GDSGenBrushPairSamples, \
 default: PBErrInvalidPolymorphism)(DataSet)
#define GDSSave(DataSet, Stream, Compact) _Generic(DataSet, \
 GDataSetVecFloat*: GDSVecFloatSave, \
 const GDataSetVecFloat*: GDSVecFloatSave, \
 default: PBErrInvalidPolymorphism)(DataSet, Stream, Compact)
#define GDSEvaluateNN(GDS, NN, Cat, Inputs, Outputs, Threshold) \
  _Generic(GDS, \
 GDataSetVecFloat*: GDataSetVecFloatEvaluateNN, \
 const GDataSetVecFloat*: GDataSetVecFloatEvaluateNN, \
 default: PBErrInvalidPolymorphism)( \
   GDS, NN, Cat, Inputs, Outputs, Threshold)
#define GDSLoad(DataSet, FP) _Generic(DataSet, \
 GDataSet*: GDataSetLoad, \
 GDataSetVecFloat*: _GDSLoad, \
 GDataSetGenBrushPair*: _GDSLoad, \
 default: PBErrInvalidPolymorphism)((GDataSet*)DataSet, FP)
#define GDSGetProxMat(DataSet, Cat) _Generic(DataSet, \
 GDataSetVecFloat*: GDSVecFloatGetProxMat, \
 const GDataSetVecFloat*: GDSVecFloatGetProxMat, \
 default: PBErrInvalidPolymorphism)(DataSet, Cat)
#define GDSNearestNeighbour(DataSet, Target, ICat) \
 _Generic(DataSet, \
   GDataSetVecFloat*: GDSVecFloatNearestNeighbourBrute, \
   const GDataSetVecFloat*: GDSVecFloatNearestNeighbourBrute, \
```

```
default: PBErrInvalidPolymorphism)(DataSet, Target, ICat)
#define GDSIsOutlierSampleCat(DataSet, ISample, ICat, NbOpponent) \
  _Generic(DataSet, \
   GDataSetVecFloat*: GDSVecFloatIsOutlierSampleCat, \
    const GDataSetVecFloat*: GDSVecFloatIsOutlierSampleCat, \
    default: PBErrInvalidPolymorphism)(DataSet, ISample, ICat, NbOpponent)
#define GDSGetNbInputs(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSGetNbInputs, \
  const GDataSet*: _GDSGetNbInputs, \
 GDataSetVecFloat*: _GDSGetNbInputs, \
  const GDataSetVecFloat*: _GDSGetNbInputs, \
 default: PBErrInvalidPolymorphism)((const GDataSet*)DataSet)
#define GDSGetNbOutputs(DataSet) _Generic(DataSet, \
 GDataSet*: _GDSGetNbOutputs, \
  const GDataSet*: _GDSGetNbOutputs, \
  GDataSetVecFloat*: _GDSGetNbOutputs, \
  const GDataSetVecFloat*: _GDSGetNbOutputs, \
  default: PBErrInvalidPolymorphism)((const GDataSet*)DataSet)
#define GDSSetNbInputs(DataSet, Nb) _Generic(DataSet, \
  GDataSet*: _GDSSetNbInputs, \
  const GDataSet*: _GDSSetNbInputs, \
 GDataSetVecFloat*: _GDSSetNbInputs, \
  const GDataSetVecFloat*: _GDSSetNbInputs, \
  default: PBErrInvalidPolymorphism)((GDataSet*)DataSet, Nb)
#define GDSSetNbOutputs(DataSet, Nb) _Generic(DataSet, \
 GDataSet*: _GDSSetNbOutputs, \
  const GDataSet*: _GDSSetNbOutputs, \
 GDataSetVecFloat*: _GDSSetNbOutputs, \
  const GDataSetVecFloat*: _GDSSetNbOutputs, \
  default: PBErrInvalidPolymorphism)((GDataSet*)DataSet, Nb)
// ======== static inliner ==========
#if BUILDMODE != 0
#include "gdataset-inline.c"
#endif
#endif
```

#### 2 Code

### 2.1 gdataset.c

```
// Create a new GDataSet of type 'type'
GDataSet GDataSetCreateStatic(GDataSetType type) {
 // Declare the new GDataSet
 GDataSet that;
  // Set the properties
 that._name = NULL;
  that._desc = NULL;
  that._type = type;
  that._nbSample = 0;
  that._nbInputs = 0;
  that._nbOutputs = 0;
  that._samples = GSetCreateStatic();
  that._sampleDim = NULL;
  that._split = NULL;
  that._categories = NULL;
 that._iterators = NULL;
  // Return the new GDataSet
 return that;
// Load the GDataSet 'that' from the stream 'stream'
// Return true if the GDataSet could be loaded, false else
bool GDataSetLoad(GDataSet* that, FILE* const stream) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
 if (stream == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'stream' is null");
   PBErrCatch(PBImgAnalysisErr);
#endif
  // Load the whole encoded data
  JSONNode* json = JSONCreate();
 if (!JSONLoad(json, stream)) {
   return false;
 // Decode the JSON
  if (!GDataSetDecodeAsJSON(that, json)) {
   return false;
 // Free memory
 JSONFree(&json);
  // Return the success code
 return true;
bool _GDSLoad(GDataSet* that, FILE* const stream) {
#if BUILDMODE == 0
 if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
 if (stream == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'stream' is null");
   PBErrCatch(PBImgAnalysisErr);
```

```
#endif
  // Load the whole encoded data
  JSONNode* json = JSONCreate();
  if (!JSONLoad(json, stream)) \{
    return false;
  // Decode the JSON
  GDataSet dataset = GDataSetCreateStatic(0);
  if (!GDataSetDecodeAsJSON(&dataset, json)) {
   return false;
  if (GDSGetType(&dataset) != GDSGetType(that)) {
    return false;
  } else {
    *that = dataset;
  \ensuremath{//} 
 Decode the samples according to the type of dataset
  switch(GDSGetType(that)) {
    case GDataSetType_VecFloat:
      if (!GDataSetVecFloatDecodeAsJSON((GDataSetVecFloat*)that, json)) {
        return false;
      break;
    case GDataSetType_GenBrushPair:
      if (!GDataSetGenBrushPairDecodeAsJSON(
        (GDataSetGenBrushPair*)that, json)) {
        return false;
      }
      break;
    default:
      return false;
  // Free memory
  JSONFree(&json);
  // Return the success code
 return true;
// Function which decode from JSON encoding 'json' to 'that'
bool GDataSetDecodeAsJSON(GDataSet* that, const JSONNode* const json) {
#if BUILDMODE == 0
  if (that == NULL) {
    PBMathErr->_type = PBErrTypeNullPointer;
    sprintf(PBMathErr->_msg, "'that' is null");
    PBErrCatch(PBMathErr);
  if (json == NULL) {
    PBMathErr->_type = PBErrTypeNullPointer;
    sprintf(PBMathErr->_msg, "'json' is null");
    PBErrCatch(PBMathErr);
#endif
  // Free memory
  GDataSetFreeStatic(that);
  // Decode dataSetType
  JSONNode* prop = JSONProperty(json, "dataSetType");
  if (prop == NULL) {
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg,
      "Invalid description file (dataSetType missing)");
    return false;
  }
```

```
JSONNode* val = JSONValue(prop, 0);
// Create the new data set
*that = GDataSetCreateStatic(atoi(JSONLabel(val)));
// Decode dataSet
prop = JSONProperty(json, "dataSet");
if (prop == NULL) {
  GDataSetErr->_type = PBErrTypeInvalidData;
  sprintf(GDataSetErr->_msg,
    "Invalid description file (dataSet missing)");
 return false;
}
val = JSONValue(prop, 0);
that->_name = PBErrMalloc(GDataSetErr,
 sizeof(char) * (strlen(JSONLabel(val)) + 1));
strcpy(that->_name, JSONLabel(val));
// Decode desc
prop = JSONProperty(json, "desc");
if (prop == NULL) {
  GDataSetErr->_type = PBErrTypeInvalidData;
  sprintf(GDataSetErr->_msg,
    "Invalid description file (desc missing)");
 return false;
}
val = JSONValue(prop, 0);
that->_desc = PBErrMalloc(GDataSetErr,
  sizeof(char) * (strlen(JSONLabel(val)) + 1));
strcpy(that->_desc, JSONLabel(val));
// Decode dim
prop = JSONProperty(json, "dim");
if (prop == NULL) {
  GDataSetErr->_type = PBErrTypeInvalidData;
  sprintf(GDataSetErr->_msg,
    "Invalid description file (dim missing)");
 return false;
that->_sampleDim = NULL;
VecDecodeAsJSON(&(that->_sampleDim), prop);
// Decode nbSample
prop = JSONProperty(json, "nbSample");
if (prop == NULL) {
  GDataSetErr->_type = PBErrTypeInvalidData;
  sprintf(GDataSetErr->_msg,
    "Invalid description file (nbSample missing)");
 return false;
val = JSONValue(prop, 0);
that->_nbSample = atoi(JSONLabel(val));
// Decode nbInputs
prop = JSONProperty(json, "nbInputs");
if (prop == NULL) {
  GDataSetErr->_type = PBErrTypeInvalidData;
  sprintf(GDataSetErr->_msg,
    "Invalid description file (nbInputs missing)");
 return false;
val = JSONValue(prop, 0);
that->_nbInputs = atoi(JSONLabel(val));
// Decode nbOutputs
prop = JSONProperty(json, "nbOutputs");
if (prop == NULL) {
 GDataSetErr->_type = PBErrTypeInvalidData;
  sprintf(GDataSetErr->_msg,
```

```
"Invalid description file (nbOutputs missing)");
   return false;
 val = JSONValue(prop, 0);
  that->_nbOutputs = atoi(JSONLabel(val));
  // Return the success code
 return true;
// Free the memory used by a GDataSet
void GDataSetFreeStatic(GDataSet* const that) {
 if (that == NULL)
   return:
  // Free memory
 if (that->_name)
   free(that->_name);
  if (that->_desc)
   free(that->_desc);
  for (int iCat = GDSGetNbCat(that); iCat--;) {
   GSetFlush(that->_categories + iCat);
 if (that->_categories)
   free(that->_categories);
  if (that->_iterators)
   free(that->_iterators);
  if (that->_split)
    VecFree(&(that->_split));
 if (that->_sampleDim)
    VecFree(&(that->_sampleDim));
// Create a new GDataSetVecFloat defined by the file at 'cfgFilePath'
GDataSetVecFloat GDataSetVecFloatCreateStaticFromFile(
 const char* const cfgFilePath) {
#if BUILDMODE == 0
 if (cfgFilePath == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'cfgFilePath' is null");
   PBErrCatch(PBImgAnalysisErr);
 }
#endif
  // Declare the new GDataSetVecFloat
  GDataSetVecFloat that;
 *(GDataSet*)&that = GDataSetCreateStatic(GDataSetType_VecFloat);
  // Open the file
 FILE* stream = fopen(cfgFilePath, "r");
  // If the description file doesn't exist
  if (stream == NULL) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(GDataSetErr->_msg, "Can't open the configuration file %s",
      cfgFilePath);
   PBErrCatch(GDataSetErr);
 }
  // Load the whole encoded data
  JSONNode* json = JSONCreate();
  if (!JSONLoad(json, stream)) {
    printf("%s\n", GDataSetErr->_msg);
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg, "Can't load the configuration file");
   PBErrCatch(GDataSetErr);
 // Decode the JSON data for the generic GDataSet
```

```
if (!GDataSetDecodeAsJSON((GDataSet*)&that, json)) {
    printf("%s\n", GDataSetErr->_msg);
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg, "Can't decode the configuration file");
    PBErrCatch(GDataSetErr);
  // Check the type
  if (GDSGetType(&that) != GDataSetType_VecFloat) {
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg, "Invalid type");
    PBErrCatch(GDataSetErr);
  // Check the samples' dimension
  if (VecGetDim(GDSSampleDim(&that)) != 1) {
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg, "Invalid sample dimension");
    PBErrCatch(GDataSetErr);
  // Decode the properties of the GDataSetVecFloat
  if (!GDataSetVecFloatDecodeAsJSON(&that, json)) {
    printf("%s\n", GDataSetErr->_msg);
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg, "Can't decode the configuration file");
    PBErrCatch(GDataSetErr);
  // Free memory
  JSONFree(&json);
  fclose(stream);
  // Return the new GDataSetVecFloat
 return that;
// Function which decode from JSON encoding 'json' to 'that'
bool GDataSetVecFloatDecodeAsJSON(GDataSetVecFloat* that,
  const JSONNode* const json) {
#if BUILDMODE == 0
  if (that == NULL) {
    PBMathErr->_type = PBErrTypeNullPointer;
    sprintf(PBMathErr->_msg, "'that' is null");
    PBErrCatch(PBMathErr);
  if (json == NULL) {
    PBMathErr->_type = PBErrTypeNullPointer;
    sprintf(PBMathErr->_msg, "'json' is null");
    PBErrCatch(PBMathErr);
  }
#endif
  // Load the samples
  JSONNode* prop = JSONProperty(json, "samples");
  if (prop == NULL) {
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg,
      "Invalid description file (samples missing)");
   return false;
  if (JSONGetNbValue(prop) != that->_dataSet._nbSample) {
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg,
      "Invalid description file (samples's number != nbSample)");
    return false;
  that->_dataSet._samples = GSetCreateStatic();
```

```
for (int iSample = 0; iSample < GDSGetSize(that); ++iSample) {</pre>
    JSONNode* val = JSONValue(prop, iSample);
    VecFloat* v = NULL;
    VecDecodeAsJSON(&v, val);
   GSetAppend((GSet*)GDSSamples(that), v);
  // Create the initial category
 GDSResetCategories((GDataSet*)that);
 // Return the success code
 return true;
// Reset the categories of the GDataSet 'that' to one unshuffled
// category
void GDSResetCategories(GDataSet* const that) {
#if BUILDMODE == 0
 if (that == NULL) {
   PBMathErr->_type = PBErrTypeNullPointer;
    sprintf(PBMathErr->_msg, "'that' is null");
   PBErrCatch(PBMathErr);
 }
#endif
 if (that->_split)
   VecFree(&(that->_split));
  that->_split = VecLongCreate(1);
 VecSet(that->_split, 0, GDSGetSize(that));
  if (that->_categories) {
   for (int iCat = GDSGetNbCat(that); iCat--;) {
     GSetFlush(that->_categories + iCat);
   free(that->_categories);
 if (that->_iterators)
    free(that->_iterators);
  that->_categories = GSetCreate();
  GSetIterForward iter = GSetIterForwardCreateStatic(GDSSamples(that));
  if (GDSGetSize(that) > 0) {
     void* sample = GSetIterGet(&iter);
     GSetAppend(that->_categories, sample);
   } while (GSetIterStep(&iter));
 that->_iterators = PBErrMalloc(GDataSetErr, sizeof(GSetIterForward));
 that->_iterators[0] = GSetIterForwardCreateStatic(that->_categories);
// Free the memory used by a GDataSetVecFloat
void GDataSetVecFloatFreeStatic(GDataSetVecFloat* const that) {
 if (that == NULL)
    return;
  // Free memory
 while (GSetNbElem(&(((GDataSet*)that)->_samples)) > 0) {
    VecFloat* sample = GSetPop(&(((GDataSet*)that)->_samples));
    VecFree(&sample);
 GDataSetFreeStatic((GDataSet*)that);
// Create a new GDataSetGenBrushPair defined by the file at 'cfgFilePath'
// The random generator must have been initialized before calling
// this function
{\tt GDataSetGenBrushPair\ GDataSetGenBrushPairCreateStaticFromFile()}
```

```
const char* const cfgFilePath) {
#if BUILDMODE == 0
 if (cfgFilePath == NULL) {
   GDataSetErr->_type = PBErrTypeNullPointer;
   sprintf(PBImgAnalysisErr->_msg, "'cfgFilePath' is null");
   PBErrCatch(PBImgAnalysisErr);
#endif
 // Declare the new GDataSetVecFloat
 GDataSetGenBrushPair that;
 *(GDataSet*)&that = GDataSetCreateStatic(GDataSetType_GenBrushPair);
 // Copy the file path
 that._cfgFilePath = PBErrMalloc(GDataSetErr, strlen(cfgFilePath) + 1);
 strcpy(that._cfgFilePath, cfgFilePath);
 // Open the file
 FILE* stream = fopen(cfgFilePath, "r");
 // If the description file doesn't exist
 if (stream == NULL) {
   GDataSetErr->_type = PBErrTypeInvalidArg;
   sprintf(GDataSetErr->_msg, "Can't open the configuration file %s",
     cfgFilePath);
   PBErrCatch(GDataSetErr);
 // Load the whole encoded data
 JSONNode* json = JSONCreate();
 if (!JSONLoad(json, stream)) {
   printf("%s\n", GDataSetErr->_msg);
   GDataSetErr->_type = PBErrTypeInvalidData;
   sprintf(GDataSetErr->_msg, "Can't load the configuration file");
   PBErrCatch(GDataSetErr);
  // Decode the JSON data for the generic GDataSet
 if (!GDataSetDecodeAsJSON((GDataSet*)&that, json)) {
   printf("%s\n", GDataSetErr->_msg);
   GDataSetErr->_type = PBErrTypeInvalidData;
   sprintf(GDataSetErr->_msg, "Can't decode the configuration file");
   PBErrCatch(GDataSetErr);
 // Check the type
 if (GDSGetType(&that) != GDataSetType_GenBrushPair) {
   GDataSetErr->_type = PBErrTypeInvalidData;
   sprintf(GDataSetErr->_msg, "Invalid type");
   PBErrCatch(GDataSetErr);
 // Check the samples' dimension
 if (VecGetDim(GDSSampleDim(&that)) != 2) {
   GDataSetErr->_type = PBErrTypeInvalidData;
   sprintf(GDataSetErr->_msg, "Invalid sample dimension (%1d=2)",
     VecGetDim(GDSSampleDim(&that)));
   PBErrCatch(GDataSetErr);
 // Decode the properties of the GDataSetGenBrushPair
 if (!GDataSetGenBrushPairDecodeAsJSON(&that, json)) {
   printf("%s\n", GDataSetErr->_msg);
   GDataSetErr->_type = PBErrTypeInvalidData;
   sprintf(GDataSetErr->_msg, "Can't decode the configuration file");
   PBErrCatch(GDataSetErr);
 // Free memory
 JSONFree(&json);
 fclose(stream);
 // Return the new GDataSetGenBrushPair
```

```
return that;
}
// Function which decode from JSON encoding 'json' to 'that'
bool GDataSetGenBrushPairDecodeAsJSON(GDataSetGenBrushPair* that,
  const JSONNode* const json) {
#if BUILDMODE == 0
  if (that == NULL) {
    PBMathErr->_type = PBErrTypeNullPointer;
    sprintf(PBMathErr->_msg, "'that' is null");
    PBErrCatch(PBMathErr);
  if (json == NULL) {
    PBMathErr->_type = PBErrTypeNullPointer;
    sprintf(PBMathErr->_msg, "'json' is null");
    PBErrCatch(PBMathErr);
  }
#endif
  // Get the nb of mask
  JSONNode* prop = JSONProperty(json, "nbMask");
  if (prop == NULL) {
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg,
      "Invalid description file (nbMask missing)");
   PBErrCatch(GDataSetErr);
  that->_nbMask = atoi(JSONLblVal(prop));
  if (that->_nbMask >= GDS_NBMAXMASK) {
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg,
      "Invalid description file (invalid nbMask %d>=%d)",
      that->_nbMask, GDS_NBMAXMASK);
    PBErrCatch(GDataSetErr);
  }
  // Load the samples
  prop = JSONProperty(json, "samples");
  if (prop == NULL) {
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg,
      "Invalid description file (samples missing)");
   PBErrCatch(GDataSetErr);
  if (JSONGetNbValue(prop) != GDSGetSize(that)) {
    GDataSetErr->_type = PBErrTypeInvalidData;
    sprintf(GDataSetErr->_msg,
      "Invalid description file (samples's number != nbSample)");
    PBErrCatch(GDataSetErr);
  that->_dataSet._samples = GSetCreateStatic();
  for (int iSample = 0; iSample < GDSGetSize(that); ++iSample) {</pre>
    JSONNode* val = JSONValue(prop, iSample);
    // Allocate memory for the pair image/mask
    GDSFilePathPair* pair = PBErrMalloc(GDataSetErr,
      sizeof(GDSFilePathPair));
    pair->_path[0] = NULL;
    for (int iMask = GDS_NBMAXMASK; iMask--;)
      pair->_path[1 + iMask] = NULL;
    // Decode img
    JSONNode* subProp = JSONProperty(val, "img");
    if (subProp == NULL) {
      GDataSetErr->_type = PBErrTypeUnitTestFailed;
      sprintf(GDataSetErr->_msg,
```

```
"Invalid description file (samples.img missing)");
      PBErrCatch(GDataSetErr);
    JSONNode* subVal = JSONValue(subProp, 0);
    pair->_path[0] = PBErrMalloc(GDataSetErr,
      sizeof(char) * (strlen(JSONLabel(subVal)) + 1));
    strcpy(pair->_path[0], JSONLabel(subVal));
    // Decode mask
    subProp = JSONProperty(val, "mask");
    if (subProp == NULL) {
      GDataSetErr->_type = PBErrTypeUnitTestFailed;
      sprintf(GDataSetErr->_msg,
        "Invalid description file (samples.mask missing)");
      PBErrCatch(GDataSetErr);
    for (int iMask = 0; iMask < that->_nbMask; ++iMask) {
      subVal = JSONValue(subProp, iMask);
      pair->_path[1 + iMask] = PBErrMalloc(GDataSetErr,
        sizeof(char) * (strlen(JSONLabel(subVal)) + 1));
      strcpy(pair->_path[1 + iMask], JSONLabel(subVal));
    // Add the pair to the samples
    GSetAppend((GSet*)GDSSamples(that), pair);
  // Create the initial category
  GDSResetCategories((GDataSet*)that);
  // Return the new GDataSetVecFloat
  return that;
// Free the memory used by a GDataSetGenBrushPair
void GDataSetGenBrushPairFreeStatic(GDataSetGenBrushPair* const that) {
  if (that == NULL)
    return;
  // Free memory
  GDataSetFreeStatic((GDataSet*)that):
  if (that->_cfgFilePath)
    free(that->_cfgFilePath);
  while (GSetNbElem(&(((GDataSet*)that)->_samples)) > 0) {
    GDSFilePathPair* sample = GSetPop(&(((GDataSet*)that)->_samples));
    GDSFilePathPairFree(&sample);
}
// Split the samples of the GDataSet 'that' into several categories
// defined by 'cat'. The dimension of 'cat' gives the number of
// categories and the value for each dimension of 'cat' gives the
// number of samples in the corresponding category. For example <3,4>
// would mean 2 categories with 3 samples in the first one and 4
// samples in the second one. There must me at least as many samples
// in the data set as the sum of samples in 'cat'.
// Each category must have at least one sample.
// If 'that' was already splitted the previous splitting is discarded.
void _GDSSplit(GDataSet* const that, const VecLong* const cat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  long nb = 0;
  for (long iCat = VecGetDim(cat); iCat--;)
```

```
nb += VecGet(cat, iCat);
  if (nb > GDSGetSize(that)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(PBImgAnalysisErr->_msg,
      "Not enough samples for the requested splitting (%ld<%ld)",
       nb, GDSGetSize(that));
   PBErrCatch(PBImgAnalysisErr);
 }
#endif
  // Free the current splitting if necessary
 if (that->_categories != NULL) {
   if (that->_split != NULL) {
      for (int iCat = GDSGetNbCat(that); iCat--;) {
        GSetFlush(that->_categories + iCat);
   free(that->_categories);
 }
  if (that->_iterators)
    free(that->_iterators);
  VecFree(&(that->_split));
  // Get the number of categories
  long nbCat = VecGetDim(cat);
  // Allocate memory for the categories
  that->_categories = PBErrMalloc(GDataSetErr, sizeof(GSet) * nbCat);
  for (long iCat = nbCat; iCat--;) {
    that->_categories[iCat] = GSetCreateStatic();
  // Copy the splitting
 that->_split = VecClone(cat);
  // Declare an iterator on the samples
  GSetIterForward iter = GSetIterForwardCreateStatic(&(that->_samples));
  // Loop on categories
  for (long iCat = 0; iCat < nbCat; ++iCat) {</pre>
    // Get the nb of samples for this category
    long nbSample = VecGet(cat, iCat);
    // Loop on the sample
    for (long iSample = 0; iSample < nbSample; ++iSample) {</pre>
      // Get the sample
      void* sample = GSetIterGet(&iter);
      // Add the sample to the category
     GSetAppend(that->_categories + iCat, sample);
      // Move to the next sample
     GSetIterStep(&iter);
  // Allocate memory for the iterators
 that->_iterators = PBErrMalloc(GDataSetErr,
   sizeof(GSetIterForward) * nbCat);
 for (long iCat = nbCat; iCat--;) {
    that->_iterators[iCat] =
     GSetIterForwardCreateStatic(that->_categories + iCat);
 }
// Get the current sample in the category 'iCat' of the GDataSet 'that'
void* _GDSGetSample(
  const GDataSet* const that, const int iCat) {
  // Call the appropriate function according to the type
 switch (GDSGetType(that)) {
    case GDataSetType_VecFloat:
     return GDSGetSampleVecFloat((GDataSetVecFloat*)that, iCat);
```

```
break;
    {\tt case \ GDataSetType\_GenBrushPair:}
     return GDSGetSampleGenBrushPair((GDataSetGenBrushPair*)that, iCat);
    default:
     return NULL;
     break;
 }
// Get the number of masks in the GDataSet 'that'
int _GDSGetNbMask(const GDataSet* const that) {
  // Call the appropriate function according to the type
 switch (GDSGetType(that)) {
    case GDataSetType_GenBrushPair:
     return GDSGetNbMaskGenBrushPair((GDataSetGenBrushPair*)that);
     break;
    default:
      return 0;
     break;
 }
VecFloat* GDSGetSampleVecFloat(
 const GDataSetVecFloat* const that, const int iCat) {
#if BUILDMODE == 0
 if (that == NULL) {
   GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
 if (iCat < 0 || iCat >= GDSGetNbCat(that)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(PBImgAnalysisErr->\_msg, \ "'iCat' is invalid \ (0<=\%d<\%ld)",
      iCat, GDSGetNbCat(that));
   PBErrCatch(PBImgAnalysisErr);
 }
#endif
 VecFloat* sample = GSetIterGet(((GDataSet*)that)->_iterators + iCat);
 return VecClone(sample);
// Get the inputs of the current sample in the category 'iCat' of
// the GDataSet 'that'
VecFloat* GDSGetSampleInputsVecFloat(
 const GDataSetVecFloat* const that, const int iCat) {
#if BUILDMODE == 0
 if (that == NULL) {
   GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
 if (iCat < 0 || iCat >= GDSGetNbCat(that)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(PBImgAnalysisErr->_msg, "'iCat' is invalid (0<=%d<%ld)",
      iCat, GDSGetNbCat(that));
   PBErrCatch(PBImgAnalysisErr);
 7
#endif
 VecFloat* sample = GSetIterGet(((GDataSet*)that)->_iterators + iCat);
 VecFloat* inputs = VecFloatCreate(GDSGetNbInputs(that));
 for (short i = GDSGetNbInputs(that); i--;) {
```

```
VecSet(inputs, i, VecGet(sample, i));
 return inputs;
// Get the outputs of the current sample in the category 'iCat' of
// the GDataSet 'that'
VecFloat* GDSGetSampleOutputsVecFloat(
  const GDataSetVecFloat* const that, const int iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  if (iCat < 0 || iCat >= GDSGetNbCat(that)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(PBImgAnalysisErr->\_msg, "'iCat' is invalid (0<=\%d<\%ld)",\\
      iCat, GDSGetNbCat(that));
    PBErrCatch(PBImgAnalysisErr);
  }
#endif
  VecFloat* sample = GSetIterGet(((GDataSet*)that)->_iterators + iCat);
  VecFloat* outputs = VecFloatCreate(GDSGetNbOutputs(that));
  for (short i = GDSGetNbOutputs(that); i--;) {
    VecSet(outputs, i, VecGet(sample, i + GDSGetNbInputs(that)));
  }
 return outputs;
GDSGenBrushPair* GDSGetSampleGenBrushPair(
  const GDataSetGenBrushPair* const that, const int iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  if (iCat < 0 || iCat >= GDSGetNbCat(that)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(PBImgAnalysisErr->\_msg, "'iCat' is invalid (0<=\%d<\%ld)",\\
      iCat, GDSGetNbCat(that));
    PBErrCatch(PBImgAnalysisErr);
  }
#endif
  GDSFilePathPair* pairFile =
    GSetIterGet(((GDataSet*)that)->_iterators + iCat);
  GDSGenBrushPair* pairSample = PBErrMalloc(GDataSetErr,
   sizeof(GDSGenBrushPair));
  for (int iMask = 0; iMask < GDS_NBMAXMASK; ++iMask)</pre>
    pairSample->_mask[iMask] = NULL;
  char* root = PBFSGetRootPath(that->_cfgFilePath);
  char* path = PBFSJoinPath(root, pairFile->_path[0]);
  GenBrush* gb = GBCreateFromFile(path);
  \ensuremath{//} Rescale the sample if needed to always provide to the user
  // the dimensions defined in the configuration file of the data set
  if (gb != NULL && !VecIsEqual(GBDim(gb), GDSSampleDim(that))) {
    pairSample->_img = GBScale(gb,
      (const VecShort2D*)GDSSampleDim(that), GBScaleMethod_Default);
    GBFree(&gb);
  } else {
    pairSample->_img = gb;
```

```
free(path);
  for (int iMask = 0; iMask < GDSGetNbMask(that); ++iMask) {</pre>
    path = PBFSJoinPath(root, pairFile->_path[1 + iMask]);
    gb = GBCreateFromFile(path);
    if (gb != NULL && !VecIsEqual(GBDim(gb), GDSSampleDim(that))) {
      pairSample->_mask[iMask] = GBScale(gb,
        (const VecShort2D*)GDSSampleDim(that), GBScaleMethod_Default);
      GBFree(&gb);
    } else {
      pairSample->_mask[iMask] = gb;
    free(path);
  free(root);
  return pairSample;
// Release the memory used by the FilePathPair 'that'
void GDSFilePathPairFree(GDSFilePathPair** const that) {
  if (that == NULL || *that == NULL)
    return;
  for (int iMask = GDS_NBMAXMASK + 1; iMask--;)
    if ((*that)->_path[iMask] != NULL)
      free((*that)->_path[iMask]);
  free(*that);
  *that = NULL;
// Release the memory used by the GenBrushPair 'that'
void GDSGenBrushPairFree(GDSGenBrushPair** const that) {
  if (that == NULL || *that == NULL)
   return;
  GBFree(&((*that)->_img));
  for (int iMask = GDS_NBMAXMASK; iMask--;)
    GBFree(&((*that)->_mask[iMask]));
  free(*that):
  *that = NULL;
}
// Center the GDataSet 'that' on its mean
{\tt void \;GDSMeanCenter(GDataSetVecFloat*\;const\;that)} \; \{
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
  // Get the mean of the dataset
  VecFloat* mean = GDSGetMean(that);
  \ensuremath{//} Translate all the data by the mean of the data set
  if (GDSGetSize(that) > 0) {
    GSetIterForward iter = GSetIterForwardCreateStatic(GDSSamples(that));
      VecFloat* sample = GSetIterGet(&iter);
      VecOp(sample, 1.0, mean, -1.0);
    } while (GSetIterStep(&iter));
  // Free memory
  VecFree(&mean);
```

```
// Center the inputs of the GDataSet 'that' on its mean
void GDSMeanCenterInputs(GDataSetVecFloat* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
  // Get the mean of the dataset
  VecFloat* mean = GDSGetMean(that);
  // Translate all the data by the mean of the data set
  if (GDSGetSize(that) > 0) {
    GSetIterForward iter = GSetIterForwardCreateStatic(GDSSamples(that));
    do {
      VecFloat* sample = GSetIterGet(&iter);
      VecFloat* inputs = VecGetOp(sample, 1.0, mean, -1.0);
      for (int i = GDSGetNbInputs(that); i--;)
        VecSet(sample, i, VecGet(inputs, i));
      VecFree(&inputs);
   } while (GSetIterStep(&iter));
  // Free memory
  VecFree(&mean);
// Normalize the GDataSet 'that', ie normalize each of its vectors
void GDSNormalize(GDataSetVecFloat* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
  // Normalize all the data of the data set
  if (GDSGetSize(that) > 0) {
    GSetIterForward iter = GSetIterForwardCreateStatic(GDSSamples(that));
      VecFloat* sample = GSetIterGet(&iter);
      VecNormalise(sample);
    } while (GSetIterStep(&iter));
// Normalize the inputs of GDataSet 'that', ie normalize each of its
// input vectors
void GDSNormalizeInputs(GDataSetVecFloat* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
 }
#endif
  // Normalize all the data of the data set
  if (GDSGetSize(that) > 0) {
    GSetIterForward iter = GSetIterForwardCreateStatic(GDSSamples(that));
    do {
      VecFloat* sample = GSetIterGet(&iter);
      VecFloat* inputs = VecGetNewDim(sample, GDSGetNbInputs(that));
```

```
VecNormalise(inputs);
      for (int i = GDSGetNbInputs(that); i--;)
        VecSet(sample, i, VecGet(inputs, i));
      VecFree(&inputs);
    } while (GSetIterStep(&iter));
 }
// Get the mean of the GDataSet 'that'
VecFloat* GDSGetMean(const GDataSetVecFloat* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
  // Get the dimension of the samples
  const VecShort* dim = GDSSampleDim(that);
  // Create a vector to calculate the mean
  VecFloat* mean = VecFloatCreate(VecGet(dim, 0));
  // Calculate the mean
  if (GDSGetSize(that) > 0) {
    GSetIterForward iter =
      GSetIterForwardCreateStatic(GDSSamples(that));
    do {
      VecFloat* v = GSetIterGet(&iter);
      VecOp(mean, 1.0, v, 1.0);
    } while(GSetIterStep(&iter));
    VecScale(mean, 1.0 / (float)GDSGetSize(that));
  }
  // Return the result
 return mean;
}
// Get the max of the GDataSet 'that'
VecFloat* GDSGetMax(const GDataSetVecFloat* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
  // Get the dimension of the samples
  const VecShort* dim = GDSSampleDim(that);
  // Create a vector to calculate the max
  int d = VecGet(dim, 0);
  VecFloat* max = VecFloatCreate(d);
  // Calculate the mx
  if (GDSGetSize(that) > 0) {
    GSetIterForward iter =
      GSetIterForwardCreateStatic(GDSSamples(that));
    VecFloat* v = GSetIterGet(&iter);
    VecCopy(max, v);
    do {
      v = GSetIterGet(&iter);
      for (int i = d; i--;)
        if (VecGet(max, i) < VecGet(v, i))</pre>
          VecSet(max, i, VecGet(v, i));
   } while(GSetIterStep(&iter));
```

```
// Return the result
 return max;
// Get a clone of the GDataSet 'that'
// All the data in the GDataSet are cloned except for the splitting
// categories which are reset to one category made of the original data
GDataSetVecFloat GDSClone(const GDataSetVecFloat* const that) {
#if BUILDMODE == 0
 if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
#endif
  // Declare the result dataset
 GDataSetVecFloat dataset;
  // Create a pointer to the GDataSet for convenience
  GDataSet* tho = &(dataset._dataSet);
  // Clone or initialize the properties
  tho->_name = PBErrMalloc(GDataSetErr,
   sizeof(char) * (1 + strlen(that->_dataSet._name)));
  strcpy(tho->_name, that->_dataSet._name);
  tho->_desc = PBErrMalloc(GDataSetErr,
   sizeof(char) * (1 + strlen(that->_dataSet._desc)));
  strcpy(tho->_desc, that->_dataSet._desc);
  tho->_type = that->_dataSet._type;
  tho->_nbSample = that->_dataSet._nbSample;
  tho->_nbInputs = that->_dataSet._nbInputs;
  tho->_nbOutputs = that->_dataSet._nbOutputs;
  tho->_sampleDim = VecClone(that->_dataSet._sampleDim);
  tho->_samples = GSetCreateStatic();
  if (GDSGetSize(that) > 0) {
    GSetIterForward iter = GSetIterForwardCreateStatic(GDSSamples(that));
     VecFloat* v = GSetIterGet(&iter);
     GSetAppend(&(tho->_samples), VecClone(v));
   } while (GSetIterStep(&iter));
  tho->_split = NULL;
  tho->_categories = NULL;
  tho->_iterators = NULL;
  tho->_split = VecLongCreate(1);
  VecSet(tho->_split, 0, tho->_nbSample);
  tho->_categories = PBErrMalloc(GDataSetErr, sizeof(GSet));
  tho->_categories[0] = GSetCreateStatic();
  if (GDSGetSize(that) > 0) {
    GSetIterForward iter =
     GSetIterForwardCreateStatic(&(tho->_samples));
      void* sample = GSetIterGet(&iter);
     GSetAppend(tho->_categories, sample);
   } while (GSetIterStep(&iter));
 tho->_iterators =
   PBErrMalloc(GDataSetErr, sizeof(GSetIterForward));
  tho->_iterators[0] =
    GSetIterForwardCreateStatic(tho->_categories);
  // Return the result dataset
 return dataset;
```

```
// Get the covariance matrix of the GDataSetVecFloat 'that'
MatFloat* GDSGetCovarianceMatrix(const GDataSetVecFloat* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  }
#endif
  // Get the dimension of the samples
  const VecShort* dim = GDSSampleDim(that);
  // Allocate memory for the covariance matrix;
  VecShort2D dimMat = VecShortCreateStatic2D();
  VecSet(&dimMat, 0, VecGet(dim, 0));
  VecSet(&dimMat, 1, VecGet(dim, 0));
  MatFloat* res = MatFloatCreate(&dimMat);
  // Loop on the matrix to set the covariances
  VecShort2D i = VecShortCreateStatic2D();
    // The matrix is symmetric, avoid calculating twice the same value
    if (VecGet(&i, 0) > VecGet(&i, 1)) {
      VecShort2D j = VecShortCreateStatic2D();
      VecSet(&j, 0, VecGet(&i, 1));
      VecSet(&j, 1, VecGet(&i, 0));
      MatSet(res, &i, MatGet(res, &j));
    } else {
      float covar = GDSGetCovariance(that, &i);
      MatSet(res, &i, covar);
  } while(VecStep(&i, &dimMat));
  // Return the covariance matrix
  return res;
// Get the covariance matrix of inputs of the GDataSetVecFloat 'that'
MatFloat* GDSGetInpCovarianceMatrix(const GDataSetVecFloat* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
#endif
  // Get the dimension of the inputksamples
  int dim = GDSGetNbInputs(that);
  // Allocate memory for the covariance matrix;
  VecShort2D dimMat = VecShortCreateStatic2D();
  VecSetAll(&dimMat, dim);
  MatFloat* res = MatFloatCreate(&dimMat);
  // Loop on the matrix to set the covariances
  VecShort2D i = VecShortCreateStatic2D();
  do {
    // The matrix is symmetric, avoid calculating twice the same value
    if (VecGet(&i, 0) > VecGet(&i, 1)) {
      VecShort2D j = VecShortCreateStatic2D();
      VecSet(&j, 0, VecGet(&i, 1));
      VecSet(&j, 1, VecGet(&i, 0));
      MatSet(res, &i, MatGet(res, &j));
      float covar = GDSGetCovariance(that, &i);
      MatSet(res, &i, covar);
```

```
} while(VecStep(&i, &dimMat));
  // Return the covariance matrix
  return res;
// Get the covariance of the variables at 'indices' in the
// GDataSetVecFloat 'that'
float GDSGetCovariance(const GDataSetVecFloat* const that,
  const VecShort2D* const indices) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  if (indices == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'indices' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
  // Declare a variable to memorize the result
  float res = 0.0;
  if (GDSGetSize(that) > 0) {
    // Get the means of the dataset
    VecFloat* means = GDSGetMean(that);
    // Calculate the covariance
    GSetIterForward iter = GSetIterForwardCreateStatic(GDSSamples(that));
    do {
      VecFloat* sample = GSetIterGet(&iter);
      res += (VecGet(sample, VecGet(indices, 0)) -
        VecGet(means, VecGet(indices, 0))) *
        (VecGet(sample, VecGet(indices, 1)) -
        VecGet(means, VecGet(indices, 1)));
    } while (GSetIterStep(&iter));
    res /= (float)GDSGetSize(that);
    // Free memory
    VecFree(&means);
  // Return the covariance
 return res;
// Create a GDataSetVecFloat by importing the CSV file 'csvPath' and
// decoding it with the 'importer'
// Return an empty GDatasetVecFloat if the importation failed
GDataSetVecFloat GDataSetCreateStaticFromCSV(
                    const char* const csvPath,
  const GDSVecFloatCSVImporter* const importer) {
#if BUILDMODE == 0
  if (csvPath == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'csvPath' is null");
    PBErrCatch(PBImgAnalysisErr);
  if (importer == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'importer' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
  // Declare the result GDataSetVecFloat
```

```
GDataSetVecFloat dataset;
GDataSet* that = (GDataSet*)&dataset;
*that = GDataSetCreateStatic(GDataSetType_VecFloat);
// Initialise the properties
that->_name = strdup(csvPath);
that->_desc = strdup(csvPath);
that->_sampleDim = VecShortCreate(1);
VecSet(that->_sampleDim, 0, importer->_sizeSample);
that->_samples = GSetCreateStatic();
// Open the csv file
FILE* csvFile = fopen(csvPath, "r");
// If we could open the file
if (csvFile != NULL) {
  // Skip the header
  unsigned int nbSkip = 0;
  while (nbSkip < importer->_sizeHeader &&
    !feof(csvFile)) {
    char buffer;
   buffer = fgetc(csvFile);
   if (buffer == '\n')
      ++nbSkip;
  // Load the samples line by line
  while (!feof(csvFile)) {
    // Allocate memory for a new sample
   VecFloat* sample = VecFloatCreate(importer->_sizeSample);
    // Decode each column
    for (unsigned int iCol = 0;
      iCol < importer->_nbCol && !feof(csvFile); ++iCol) {
      // Read the value
      char buffer[1024];
      unsigned int iChar = 0;
     do {
       buffer[iChar] = fgetc(csvFile);
      } while (buffer[iChar] != importer->_sep &&
        buffer[iChar] != '\n' &&
        ++iChar && iChar < sizeof(buffer) && !feof(csvFile));
     buffer[iChar] = '\0';
      // Decode the value and set it into the sample
     if (importer->_converter != NULL) {
        importer->_converter(iCol, buffer, sample);
      } else {
        VecSet(sample, iCol, atof(buffer));
     }
   // If we haven't reached the end of the file
   if (!feof(csvFile)) {
      // Add the sample to the dataset
      GSetAppend((GSet*)GDSSamples(that), sample);
    // Else, we are at the end of the file
   } else {
```

```
// Free the memory
        VecFree(&sample);
      }
    }
    // Update the number of samples
    that->_nbSample = GSetNbElem(GDSSamples(that));
    // Close the csv file
    fclose(csvFile);
  // Initialise the categories
  GDSResetCategories(that);
  // Return the dataset
 return dataset;
// Create a CSV importer for a GDataSetVecFloat
{\tt GDSVecFloatCSVImporter~GDSVecFloatCSVImporterCreateStatic(}
  const unsigned int sizeHeader,
         const char sep,
  const unsigned int nbCol,
  const unsigned int sizeSample,
                 void (*converter)(
                   int col,
                   char* val.
                   VecFloat* sample)) {
  GDSVecFloatCSVImporter importer = {
    ._sizeHeader=sizeHeader,
    ._sep=sep,
    ._nbCol=nbCol,
    ._sizeSample=sizeSample,
    ._converter=converter
 return importer;
// Function which return the JSON encoding of 'that'
JSONNode* GDataSetVecFloatEncodeAsJSON(
  const GDataSetVecFloat* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
 }
#endif
  // Create the JSON structure
  JSONNode* json = JSONCreate();
  // Declare a buffer to convert value into string
  char val[100];
  // Encode the properties
  JSONAddProp(json, "dataSet", that->_dataSet._name);
  sprintf(val, "%d", that->_dataSet._type);
JSONAddProp(json, "dataSetType", val);
JSONAddProp(json, "desc", that->_dataSet._desc);
  sprintf(val, "%ld", GDSGetSize(that));
```

```
JSONAddProp(json, "nbSample", val);
  sprintf(val, "%d", GDSGetNbInputs(that));
  JSONAddProp(json, "nbInputs", val);
sprintf(val, "%d", GDSGetNbOutputs(that));
  JSONAddProp(json, "nbOutputs", val);
  JSONAddProp(json, "dim", VecEncodeAsJSON(that->_dataSet._sampleDim));
JSONArrayStruct samples = JSONArrayStructCreateStatic();
  GSetIterForward iter = GSetIterForwardCreateStatic(GDSSamples(that));
  do {
    VecFloat* sample = GSetIterGet(&iter);
    JSONArrayStructAdd(&samples,
      VecEncodeAsJSON(sample));
  } while (GSetIterStep(&iter));
  JSONAddProp(json, "samples", &samples);
  JSONArrayStructFlush(&samples);
  // Return the created JSON
 return json;
// Function which return the JSON encoding of the category 'iCat'
// of'that'
JSONNode* GDataSetVecFloatEncodeCategoryAsJSON(
  const GDataSetVecFloat* const that,
              const unsigned int iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  }
#endif
  // Create the JSON structure
  JSONNode* json = JSONCreate();
  // Declare a buffer to convert value into string
  char val[100];
  // Encode the properties
  JSONAddProp(json, "dataSet", that->_dataSet._name);
  sprintf(val, "%d", that->_dataSet._type);

JSONAddProp(json, "dataSetType", val);

JSONAddProp(json, "desc", that->_dataSet._desc);
  sprintf(val, "%ld", GDSGetSizeCat(that, iCat));
JSONAddProp(json, "nbSample", val);
  JSONAddProp(json, "dim", VecEncodeAsJSON(that->_dataSet._sampleDim));
  sprintf(val, "%d", GDSGetNbInputs(that));
JSONAddProp(json, "nbInputs", val);
  sprintf(val, "%d", GDSGetNbOutputs(that));
  JSONAddProp(json, "nbOutputs", val);
  JSONArrayStruct samples = JSONArrayStructCreateStatic();
  GDSReset(that, iCat);
  do {
    VecFloat* sample = GDSGetSample(that, iCat);
    JSONArrayStructAdd(&samples,
      VecEncodeAsJSON(sample));
    VecFree(&sample);
  } while (GDSStepSample(that, iCat));
  JSONAddProp(json, "samples", &samples);
  JSONArrayStructFlush(&samples);
  // Return the created JSON
```

```
return json;
}
// Save the GDataSetVecFloat to the stream
// If 'compact' equals true it saves in compact form, else it saves in
// readable form
// Return true upon success else false
bool GDSVecFloatSave(
  const GDataSetVecFloat* const that,
                    FILE* const stream,
                     const bool compact) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(GDataSetErr->_msg, "'that' is null");
    PBErrCatch(GDataSetErr);
  if (stream == NULL) \{
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(GDataSetErr->_msg, "'stream' is null");
    PBErrCatch(GDataSetErr);
#endif
  // \ensuremath{\mathsf{Get}} the JSON encoding
  JSONNode* json = GDataSetVecFloatEncodeAsJSON(that);
  // Save the JSON
  if (!JSONSave(json, stream, compact)) {
   return false;
  // Free memory
  JSONFree(&json);
  // Return success code
 return true;
}
// Save the category 'iCat' of the GDataSetVecFloat to the stream
// If 'compact' equals true it saves in compact form, else it saves in
// readable form
// Return true upon success else false
bool GDSVecFloatSaveCategory(
  const GDataSetVecFloat* const that,
                    FILE* const stream,
                     const bool compact,
                      const int iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(GDataSetErr->_msg, "'that' is null");
    PBErrCatch(GDataSetErr);
  if (stream == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(GDataSetErr->_msg, "'stream' is null");
    PBErrCatch(GDataSetErr);
  }
#endif
  // Get the JSON encoding
  JSONNode* json = GDataSetVecFloatEncodeCategoryAsJSON(
    iCat);
  // Save the JSON
  if (!JSONSave(json, stream, compact)) {
```

```
return false;
  }
  // Free memory
  JSONFree(&json);
  // Return success code
 return true;
// Run the prediction by the NeuraNet 'nn' on each sample of the category
// 'iCat' of the GDataSet 'that'. The index of columns in the samples
// for inputs and outputs are given by 'iInputs' and 'iOutputs'.
// Stop the prediction of samples when the result can't get better
// than 'threshold'
// Return the value of the NeuraNet on the predicted samples, defined
// as sum_samples(||output_sample-output_neuranet||)/nb_sample
// Higher is better, 0.0 is best value
float GDataSetVecFloatEvaluateNN(
  const GDataSetVecFloat* const that,
  const NeuraNet* const nn,
  const int iCat,
  const VecShort* const iInputs,
  const VecShort* const iOutputs,
  const float threshold) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(GDataSetErr->_msg, "'that' is null");
    PBErrCatch(GDataSetErr);
  if (nn == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(GDataSetErr->_msg, "'nn' is null");
    PBErrCatch(GDataSetErr);
  if (iInputs == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(GDataSetErr->_msg, "'iInputs' is null");
    PBErrCatch(GDataSetErr);
  if (iOutputs == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(GDataSetErr->_msg, "'iOutputs' is null");
    PBErrCatch(GDataSetErr);
  if (VecGetDim(iInputs) != NNGetNbInput(nn)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(GDataSetErr->_msg,
      "Dim of 'iInputs' is invalid (%ld==%d)",
      VecGetDim(iInputs),
      NNGetNbInput(nn));
    PBErrCatch(GDataSetErr);
  if (VecGetDim(iOutputs) != NNGetNbOutput(nn)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(GDataSetErr->_msg,
      "Dim of 'iOutputs' is invalid (%ld==%d)",
      VecGetDim(iOutputs),
      NNGetNbOutput(nn));
    PBErrCatch(GDataSetErr);
#endif
```

```
// Declare a variable to memorize the result
float value = 0.0;
// Declare a variable to memorize the nb of predicted samples
long nbPredSample = 0;
// Declare a variable to manage the threshold
bool flag = true;
// Declare variables for the input and output of the NeuraNet and
// for the correct output of the NeuraNet
VecFloat* inputNN = VecFloatCreate(NNGetNbInput(nn));
VecFloat* outputNN = VecFloatCreate(NNGetNbOutput(nn));
VecFloat* outputSample = VecFloatCreate(NNGetNbOutput(nn));
// Reset the iterator on samples
GDSReset(that, iCat);
// Loop on the samples of the requested category
do {
  // Get a clone of the sample
  VecFloat* sample = GDSGetSample(that, iCat);
  // Create the input of the NeuraNet from the sample
  for (int iInput = NNGetNbInput(nn); iInput--;) {
   VecSet(inputNN, iInput,
      VecGet(sample, VecGet(iInputs, iInput)));
  // Run the prediction
  NNEval(nn, inputNN, outputNN);
  // Create the correct output of the NeuraNet from the sample
  for (int iOutput = NNGetNbOutput(nn); iOutput--;) {
    VecSet(outputSample, iOutput,
      VecGet(sample, VecGet(iOutputs, iOutput)));
  }
  // Calculate the value on this sample
  VecFloat* diff = VecGetOp(outputNN, 1.0, outputSample, -1.0);
  float sampleValue = VecNorm(diff);
  VecFree(&diff);
  // Update the total value
  value += sampleValue;
  // Check against the threshold
  float bestPossible = -1.0 * value / (float)GDSGetSizeCat(that, iCat);
  if (bestPossible <= threshold) {</pre>
    flag = false;
  // Free memory
  VecFree(&sample);
  // Increment the nb of predicted samples
  ++nbPredSample;
} while (flag && GDSStepSample(that, iCat));
// Update the total value
value /= (float)nbPredSample;
```

```
// Free memory
  VecFree(&inputNN);
  VecFree(&outputNN);
  VecFree(&outputSample);
  // Return the value of the NeuraNet on the samples
  return value * -1.0;
// Create a new GDataSetVecFloat
GDataSetVecFloat GDataSetVecFloatCreateStatic(void) {
  // Declare the result GDataSetVecFloat
  GDataSetVecFloat that;
  // Initialise properties
  that._dataSet = GDataSetCreateStatic(GDataSetType_VecFloat);
  // Return the dataset
 return that;
}
// Get the proximity matrix of the samples of category 'iCat' in the
// GDataSetVecFloat 'that'
// M[i,j] = euclidean distance between the i-th sample and the j-th sample
MatFloat* GDSVecFloatGetProxMat(
  const GDataSetVecFloat* that,
             unsigned int iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
      GDataSetErr->_msg,
      "'that' is null");
    PBErrCatch(GDataSetErr);
  }
#endif
  // Allocate memory for the result matrix
  long nbSamples =
    GDSGetSizeCat(
      that,
      iCat);
  VecShort2D v = VecShortCreateStatic2D();
  VecSet(
    &v,
    Ο,
    nbSamples);
  VecSet(
    &ν,
    1,
   nbSamples);
  MatFloat* proxMat = MatFloatCreate(&v);
  // Declare another vector used to manipulate the matrix
  VecShort2D w = VecShortCreateStatic2D();
```

```
// Declare two variables to memorize the indices of samples
long iSample = 0;
long jSample = 0;
// Loop on the samples of the category
GDSReset(
  that.
  iCat);
bool flagStepI = true;
bool flagStepJ = true;
do {
  // Get the sample
  VecFloat* sampleI = GSetIterGet(((GDataSet*)that)->_iterators + iCat);
  // Update the index to manipulate the matrix
  VecSet(
    &v,
    Ο,
    iSample);
  VecSet(
    &w,
    1,
    iSample);
  // Create a temporary iterator to loop on the following sample % \frac{1}{2}\left( \frac{1}{2}\right) =\frac{1}{2}\left( \frac{1}{2}\right) 
  GSetIterForward iterJ = ((GDataSet*)that)->_iterators[iCat];
  jSample = iSample;
  // Loop on the following samples
  do {
    // Get the following sample
    VecFloat* sampleJ = GSetIterGet(&iterJ);
    // Get the distance between the sample and the following sample
    float dist = 0.0;
    if (iSample != jSample) {
      dist =
        VecDist(
          sampleI,
           sampleJ);
    // Update the index to manipulate the matrix
    VecSet(
      &ν,
      1,
      jSample);
    VecSet(
      &w,
      Ο,
      jSample);
    // Update the proximity matrix
    MatSet(
      proxMat,
      ων,
      dist);
    MatSet(
```

```
proxMat,
        &w,
        dist);
      // Step to the next following sample
      flagStepJ = GSetIterStep(&iterJ);
      ++jSample;
    } while (flagStepJ);
    // Step to the next sample
    flagStepI =
      GDSStepSample(
        that,
        iCat):
    ++iSample;
  } while (flagStepI);
  // Return the proximity matrix
  return proxMat;
}
// Get the nearest (in term of euclidean distance) sample of category
// 'iCat' to 'target' in the GDataSetVecFloat 'that' using the AESA
// nearest neighbour search
// TODO: should use a lookup table to get VecDist(sample, prevCandidate)
// but it's complicated by the fact I'm loosing the index of samples when
// using GSet
// Also, even if using a lookup table, and even if AESA actually reduces
// efficiently the number of VecDist(candidate, target), the cost of
// VecDist() much be hugely bigger than the one of using a lookup table
// to make AESA relevant. It's probably meaningless on a VecFloat,
// maybe more meaningful on a GenBrush ?
// http://citeseerx.ist.psu.edu/viewdoc/download?
// doi=10.1.1.481.2200&rep=rep1&type=pdf
VecFloat* GDSVecFloatNearestNeighbourAESA(
  const GDataSetVecFloat* that,
          const VecFloat* target,
                      int iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(
      GDataSetErr->_msg,
      "'that' is null");
    PBErrCatch(GDataSetErr);
  }
  if (target == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(
      GDataSetErr->_msg,
    "'target' is null");
PBErrCatch(GDataSetErr);
```

```
}
#endif
 // Declare the pointer to the result sample
 VecFloat* nearestNeighbour = NULL;
 // Declare a variable to store the best distance
 float bestDist = -1.0;
 // Create the set of examined samples
 GSet done = GSetCreateStatic();
 // Create the set of not yet examined samples
 GSet todo = GSetCreateStatic();
 GDSReset(
   that,
   iCat);
 bool flagStep = true;
 do {
   VecFloat* sample = GSetIterGet(((GDataSet*)that)->_iterators + iCat);
   GSetAppend(
     &todo,
     sample);
   flagStep =
     GDSStepSample(
       that,
        iCat);
 } while(flagStep);
 // Declare the pointer to the candidate sample and initialise it
 // to the first sample not yet examined
 VecFloat* candidate = GSetPop(&todo);
 // While there is a candidate to examined
 while(candidate != NULL) {
   // Get the distance from the candidate to the target
   float distCandidate =
     VecDist(
       candidate,
       target);
   // Add the candidate to the set of examined samples sorted on
   // their distance to the target
   GSetAddSort(
     &done,
     candidate,
     distCandidate);
   // If there is no current best or the distance is less than the
   // current best
   if (
     bestDist < 0.0 ||
     distCandidate < bestDist) {</pre>
     // Update the current best
     bestDist = distCandidate;
     nearestNeighbour = candidate;
```

```
}
  // Create a temporary set to update the lower bound
  GSet update = GSetCreateStatic();
  // For each sample not yet examined
  while(GSetNbElem(&todo) > 0) {
    // Get the sample
    VecFloat* sample = GSetPop(&todo);
    // Get the lower bound of the sample
    float lowerBound = 0.0;
    GSetIterForward iter = GSetIterForwardCreateStatic(&done);
    do {
      VecFloat* prevCandidate = GSetIterGet(&iter);
      const GSetElem* elem = GSetIterGetElem(&iter);
      float 1 =
        GSetElemGetSortVal(elem) -
        VecDist(
          sample,
          prevCandidate);
      if (1 > lowerBound) {
        lowerBound = 1;
      }
    } while(
      GSetIterStep(&iter) &&
      lowerBound < bestDist);</pre>
    \ensuremath{//} Add the sample to the updated set if its lower bound is below
    // the current best distance
    if (lowerBound < bestDist) {</pre>
      GSetAddSort(
        &update,
        sample,
        lowerBound);
    }
  }
  // Swap the todo and update sets
  todo = update;
  // Get the next candidate as the one with lowest bound in the list of
  // not yet examined samples
  candidate = GSetPop(&todo);
// Free memory
GSetFlush(&done);
// Return the nearest neighbour
return nearestNeighbour;
```

}

```
// Get the nearest (in term of euclidean distance) sample of category
// 'iCat' to 'target' in the GDataSetVecFloat 'that' using brute force VecFloat* GDSVecFloatNearestNeighbourBrute(
  const GDataSetVecFloat* that,
          const VecFloat* target,
                       int iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
      GDataSetErr->_msg,
      "'that' is null");
    PBErrCatch(GDataSetErr);
  if (target == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(
      GDataSetErr->_msg,
    "'target' is null");
PBErrCatch(GDataSetErr);
  }
#endif
  // Declare the pointer to the result
  VecFloat* nearest = NULL;
  // Declare a variable to memorize the best distance
  float bestDist = 0.0;
  // Loop on samples
  do {
    // Get the sample
    VecFloat* sample =
      GDSGetSample(
        that.
        iCat);
    // Get the distance to the target
    float dist =
      VecDist(
        target,
        sample);
    // If there is no nearest yet or the distance is better
    if (
      nearest == NULL ||
      dist < bestDist) {</pre>
         // Free memory used by the copy of the current best sample
        VecFree(&nearest);
        // Update the nearest sample
```

```
bestDist = dist;
        nearest = sample;
    // Else, it is farther than the current best
    } else {
      // Free memory used by the copy of the sample
      VecFree(&sample);
  } while(GDSStepSample(that, iCat));
  // Return the result
  return nearest:
// Check if the 'sample' in the category 'iCat' of the
// GDataSetVecFloat 'that' is an outlier. The outliers are identified as follow.
// For each sample, the nearest (in term of euclidian distance of inputs)
// sample with same output values is searched. Then, the number of nearer
// samples with different output values (called "opponents") is calculated.
// Finally, if there is more than 'nbOpponent' opponents, the sample is
// considered to be an outlier. The lower 'nbOpponent' is the more samples
// will be considered as outliers.
bool GDSVecFloatIsOutlierSampleCat(
  const GDataSetVecFloat* that,
          const VecFloat* sample,
                    long iCat,
             unsigned int nbOpponent) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
     GDataSetErr->_msg,
      "'that' is null");
    PBErrCatch(GDataSetErr);
  if (iCat >= GDSGetNbCat(that)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(
      GDataSetErr->_msg,
      "'iCat' is invalid (%ld<=%ld)",
      GDSGetNbCat(that));
    PBErrCatch(GDataSetErr);
  if (iSample >= GDSGetSizeCat(that, iCat))) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(
      GDataSetErr->_msg,
      "'iSample' is invalid (%ld<=%ld)",
```

```
iSample,
     GDSGetSizeCat(that, iCat));
   PBErrCatch(GDataSetErr);
 if (GDSGetNbInputs(that) <= 0) {</pre>
   GDataSetErr->_type = PBErrTypeInvalidArg;
   sprintf(
     GDataSetErr->_msg,
      "No inputs in the sample");
   PBErrCatch(GDataSetErr);
 }
 if (GDSGetNbOutputs(that) <= 0) {</pre>
   GDataSetErr->_type = PBErrTypeInvalidArg;
   sprintf(
     GDataSetErr->_msg,
      "No outputs in the sample");
   PBErrCatch(GDataSetErr);
 }
#endif
 // If there is no sample in the category
 if (GDSGetSizeCat(that, iCat) == 0) {
   return false;
 // Variable to memorise the nearest distance
 double nearestDist = -1.0;
 // Get the inputs and outputs of the checked sample
 VecFloat* inputs = VecFloatCreate(GDSGetNbInputs(that));
 for (short i = GDSGetNbInputs(that); i--;) {
   VecSet(inputs, i, VecGet(sample, i));
 VecFloat* outputs = VecFloatCreate(GDSGetNbOutputs(that));
 for (short i = GDSGetNbOutputs(that); i--;) {
   VecSet(outputs, i, VecGet(sample, i + GDSGetNbInputs(that)));
 // Create an iterator to loop on the samples of the category
 GSetIterForward iter = ((GDataSet*)that)->_iterators[iCat];
 GSetIterReset(&iter);
 // Loop on the samples
 do {
   // Get the sample
   const VecFloat* sampleIter = GSetIterGet(&iter);
   // Get the sample outputs
   VecFloat* outputsIter = VecFloatCreate(GDSGetNbOutputs(that));
   for (short i = GDSGetNbOutputs(that); i--;) {
     VecSet(outputsIter, i, VecGet(sampleIter, i + GDSGetNbInputs(that)));
   // Get the distance to the checked sample
   float dist =
     VecDist(
```

```
outputsIter,
      outputs);
  // If it's the same output
  if (ISEQUALF(dist, 0.0)) {
    // Get the sample inputs
    VecFloat* inputsIter = VecFloatCreate(GDSGetNbInputs(that));
   for (short i = GDSGetNbInputs(that); i--;) {
      VecSet(inputsIter, i, VecGet(sampleIter, i));
    // Get the distance to the checked sample
   dist =
      VecDist(
        inputsIter,
        inputs);
    // If it's nearer that the actual nearest
    if (dist > PBMATH_EPSILON && (nearestDist < 0.0 || nearestDist > dist)) {
     // Update the nearest dist
     nearestDist = dist;
    // Free memory
    VecFree(&inputsIter);
  // Free memory
  VecFree(&outputsIter);
} while (GSetIterStep(&iter));
// Declare a variable to count the opponents
long nb = 0;
// Reset the iterator
GSetIterReset(&iter);
// Loop on the samples
do {
  // Get the sample
  const VecFloat* sampleIter = GSetIterGet(&iter);
  // Get the sample outputs
  VecFloat* outputsIter = VecFloatCreate(GDSGetNbOutputs(that));
  for (short i = GDSGetNbOutputs(that); i--;) {
    VecSet(outputsIter, i, VecGet(sampleIter, i + GDSGetNbInputs(that)));
  // Get the distance to the checked sample
  float dist =
    VecDist(
      outputsIter,
      outputs);
  // If it's not the same output
  if (!ISEQUALF(dist, 0.0)) {
    // Get the sample inputs
   VecFloat* inputsIter = VecFloatCreate(GDSGetNbInputs(that));
   for (short i = GDSGetNbInputs(that); i--;) {
      VecSet(inputsIter, i, VecGet(sampleIter, i));
    // Get the distance to the checked sample
   dist =
     VecDist(
        inputsIter,
        inputs);
    // If it's nearerer than the nearest non opponent
    if (nearestDist > dist) {
      // Increment the number of opponents
      ++nb;
   }
```

```
// Free memory
   VecFree(&inputsIter);
}
// Free memory
VecFree(&outputsIter);
} while (GSetIterStep(&iter));

// Free memory
VecFree(&inputs);
VecFree(&outputs);

// Return the result
if (nb > nbOpponent) {
   return true;
} else {
   return false;
}
```

### 2.2 gdataset-inline.c

```
// ======= GDATASET_static inline.C ==========
// ======= Functions implementation ==========
// Get the total number of samples in the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
long _GDSGetSize(const GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
#endif
 return that->_nbSample;
// Get the total number of samples in the GDataSet 'that' for the
// category 'iCat'. Return 0 if the category doesn't exists
#if BUILDMODE != 0
static inline
long _GDSGetSizeCat(const GDataSet* const that, const long iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
  if (that->_split == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that->_split' is null");
    PBErrCatch(PBImgAnalysisErr);
  if (iCat < 0 || iCat >= GDSGetNbCat(that)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
```

```
sprintf(PBImgAnalysisErr->_msg, "'iCat' is invalid (0<=%ld<%ld)",
      iCat, GDSGetNbCat(that));
    PBErrCatch(PBImgAnalysisErr);
 }
#endif
 return (that->_split ? VecGet(that->_split, iCat) : 0);
// Unsplit the GDataSet 'that', i.e. after calling GDataSetUnsplit 'that'
// has only one category containing all the samples
#if BUILDMODE != 0
static inline
#endif
void _GDSUnsplit(GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
  // Unsplitting is equivalent to splitting in one category with all the
  // samples
  VecLong* split = VecLongCreate(1);
  VecSet(split, 0, GDSGetSize(that));
  GDSSplit(that, split);
  VecFree(&split);
// Shuffle the samples of the GDataSet 'that'.
#if BUILDMODE != 0
static inline
#endif
void _GDSShuffle(GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
 }
#endif
  // Shuffle the samples
  GSetShuffle(&(that->_samples));
// Shuffle the samples of the category 'iCat' of the GDataSet 'that'.
// Reset the iterator of the category
#if BUILDMODE != 0
static inline
#endif
void _GDSShuffleCat(GDataSet* const that, const long iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
  if (that->_categories == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that->_categories' is null");
    PBErrCatch(PBImgAnalysisErr);
```

```
if (iCat < 0 || iCat >= GDSGetNbCat(that)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(PBImgAnalysisErr->\_msg, "'iCat' is invalid (0<=\%ld<\%ld)",
      iCat, GDSGetNbCat(that));
    PBErrCatch(PBImgAnalysisErr);
#endif
  // Shuffle the GSet of the category
  if (that->_categories)
    GSetShuffle(that->_categories + iCat);
  // Reset the iterator
 GDSReset(that, iCat);
// Shuffle the samples of all the categories of the GDataSet 'that'.
// Reset the iterator of the categories
#if BUILDMODE != 0
static inline
#endif
void _GDSShuffleAll(GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
#endif
  // Loop on categories
  for (int iCat = GDSGetNbCat(that); iCat--;)
    // Shuffle the category
    GDSShuffleCat(that, iCat);
}
// Get the name of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
const char* _GDSName(const GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  }
#endif
 return that->_name;
}
// Get the description of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
const char* _GDSDesc(const GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
  }
#endif
 return that->_desc;
```

```
// Get the type of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
GDataSetType _GDSGetType(const GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
 return that->_type;
}
// Get the number of categories of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
long _GDSGetNbCat(const GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  }
#endif
 return (that->_split ? VecGetDim(that->_split) : 0);
// If there is a next sample move to the next sample of the category
// 'iCat' and return true, else return false
#if BUILDMODE != 0
static inline
#endif
bool _GDSStepSample(const GDataSet* const that, const long iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  if (that->_iterators == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that->_iterators' is null");
   PBErrCatch(PBImgAnalysisErr);
  if (iCat < 0 || iCat >= GDSGetNbCat(that)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(PBImgAnalysisErr->_msg, "'iCat' is invalid (0<=%ld<%ld)",</pre>
      iCat, GDSGetNbCat(that));
   PBErrCatch(PBImgAnalysisErr);
#endif
  return (that->_iterators ?
    GSetIterStep(that->_iterators + iCat) : false);
// Reset the iterator on category 'iCat' of the GDataSet 'that', i.e.
// the next call to GDataSetGetNextSample will give the first sample of
// the category 'iCat'
```

```
#if BUILDMODE != 0
static inline
#endif
void _GDSReset(GDataSet* const that, const long iCat) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  if (that->_iterators == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that->_iterators' is null");
    PBErrCatch(PBImgAnalysisErr);
  if (iCat < 0 || iCat >= GDSGetNbCat(that)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(PBImgAnalysisErr->_msg, "'iCat' is invalid (0<=%ld<%ld)",</pre>
      iCat, GDSGetNbCat(that));
    PBErrCatch(PBImgAnalysisErr);
  }
#endif
  if (that->_iterators)
    GSetIterReset(that->_iterators + iCat);
// Reset the iterator on all categories of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
void _GDSResetAll(GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  }
#endif
  // Loop on categories
  for (int iCat = GDSGetNbCat(that); iCat--;)
    // Reset the category
    GDSReset(that, iCat);
// Get the dimensions of the samples of GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
const VecShort* _GDSSampleDim(const GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
 }
#endif
 return that->_sampleDim;
// Get the number of masks in the GDataSetGenBrushPair 'that'
#if BUILDMODE != 0
static inline
```

```
#endif
int GDSGetNbMaskGenBrushPair(const GDataSetGenBrushPair* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  }
#endif
 return that->_nbMask;
// Get the samples of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
const GSet* _GDSSamples(const GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
 }
#endif
 return &(that->_samples);
#if BUILDMODE != 0
static inline
#endif
const GSetVecFloat* _GDSVecFloatSamples(
  const GDataSetVecFloat* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  }
#endif
 return (GSetVecFloat*)&(that->_dataSet._samples);
#if BUILDMODE != 0
static inline
const GSet* _GDSGenBrushPairSamples(
  const GDataSetGenBrushPair* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
  return &(that->_dataSet._samples);
// Remove all the samples of the GDataSetVecFloat 'that'
#if BUILDMODE != 0
static inline
#endif
void _GDSVecFloatRemoveAllSample(GDataSetVecFloat* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
```

```
GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
 }
#endif
 while (GSetNbElem(GDSSamples(that)) > 0) {
    VecFloat* sample = GSetPop((GSet*)GDSSamples(that));
    VecFree(&sample);
 that->_dataSet._nbSample = 0;
 GDSUnsplit(that);
// Remove all the samples of the GDataSetGenBrushPair 'that'
#ifdef GENBRUSH H
#if BUILDMODE != 0
static inline
#endif
void _GDSGenBrushPairRemoveAllSample(GDataSetGenBrushPair* const that) {
#if BUILDMODE == 0
 if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
#endif
  while (GSetNbElem(GDSSamples(that)) > 0) {
   GDSGenBrushPair* sample = GSetPop((GSet*)GDSSamples(that));
   GDSGenBrushPairFree(&sample);
 that->_dataSet._nbSample = 0;
 GDSUnsplit(that);
#endif
// Append 'sample' in the GDataSetVecFloat 'that'
#if BUILDMODE != 0
static inline
#endif
void _GDSVecFloatAddSample(
 GDataSetVecFloat* const that,
 VecFloat* sample) {
#if BUILDMODE == 0
 if (that == NULL) {
   GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
   PBErrCatch(PBImgAnalysisErr);
 if (sample == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'sample' is null");
   PBErrCatch(PBImgAnalysisErr);
  if (VecGetDim(sample) != VecGet(GDSSampleDim(that), 0)) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(PBImgAnalysisErr->_msg,
      "'sample' has invalid dimensions (%ld!=%d)",
      VecGetDim(sample), VecGet(GDSSampleDim(that), 0));
   PBErrCatch(PBImgAnalysisErr);
#endif
 GSetAppend((GSet*)GDSSamples(that), sample);
```

```
that->_dataSet._nbSample += 1;
}
// Append 'sample' in the GDataSetGenBrush 'that'
#ifdef GENBRUSH H
#if BUILDMODE != 0
static inline
#endif
void _GDSGenBrushPairAddSample(
  GDataSetGenBrushPair* const that,
  GDSGenBrushPair* sample) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
  if (sample == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'sample' is null");
    PBErrCatch(PBImgAnalysisErr);
  if (VecIsEqual(GBDim(sample), GDSSampleDim(&dataset)) == FALSE) {
    GDataSetErr->_type = PBErrTypeInvalidArg;
    sprintf(PBImgAnalysisErr->_msg,
      "'sample' has invalid dimensions ((%ld,%ld)!=(%ld,%ld))",
      VecGet(GBDim(sample), 0),
      VecGet(GBDim(sample), 1),
      VecGet(GDSSampleDim(&dataset), 0),
      VecGet(GDSSampleDim(&dataset), 1));
    PBErrCatch(PBImgAnalysisErr);
#endif
  GSetAppend((GSet*)GDSSamples(that), sample);
  that->_dataSet._nbSample += 1;
#endif
// Get the number of input values in one sample of the GDataSet 'that'
#if BUILDMODE != 0
static inline
#endif
short _GDSGetNbInputs(const GDataSet* const that) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
 }
#endif
 return that->_nbInputs;
// Get the number of output values in one sample of the GDataSet 'that'
#if BUILDMODE != 0
static inline
short _GDSGetNbOutputs(const GDataSet* const that) {
#if BUILDMODE == 0
 if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
```

```
PBErrCatch(PBImgAnalysisErr);
  }
#endif
 return that->_nbOutputs;
// Set the number of input values in one sample of the GDataSet 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void _GDSSetNbInputs(GDataSet* const that, const short nb) {
#if BUILDMODE == 0
  if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
 }
#endif
 that->_nbInputs = nb;
// Set the number of output values in one sample of the GDataSet 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void _GDSSetNbOutputs(GDataSet* const that, const short nb) {
#if BUILDMODE == 0
 if (that == NULL) {
    GDataSetErr->_type = PBErrTypeNullPointer;
    sprintf(PBImgAnalysisErr->_msg, "'that' is null");
    PBErrCatch(PBImgAnalysisErr);
#endif
  that->_nbOutputs = nb;
```

## 3 Makefile

\$(\$(repo)\_EXENAME).o \

```
# Build mode
# 0: development (max safety, no optimisation)
# 1: release (min safety, optimisation)
# 2: fast and furious (no safety, optimisation)
BUILD_MODE?=1
all: pbmake_wget main
# Automatic installation of the repository PBMake in the parent folder
pbmake_wget:
if [ ! -d ../PBMake ]; then wget https://github.com/BayashiPascal/PBMake/archive/master.zip; unzip master.zip; rm -f
# Makefile definitions
MAKEFILE_INC=../PBMake/Makefile.inc
include $(MAKEFILE_INC)
# Rules to make the executable
repo=gdataset
$($(repo)_EXENAME): \
```

```
$($(repo)_EXE_DEP) \
$($(repo)_DEP)
$(COMPILER) 'echo "$($(repo)_EXE_DEP) $($(repo)_EXENAME).o" | tr ' ' '\n' | sort -u' $(LINK_ARG) $($(repo)_LINK_ARG)
$($(repo)_EXENAME).o: \
$($(repo)_DIR)/$($(repo)_EXENAME).c \
$($(repo)_INC_H_EXE) \
$($(repo)_EXE_DEP)
$(COMPILER) $(BUILD_ARG) $($(repo)_BUILD_ARG) 'echo "$($(repo)_INC_DIR)" | tr ' ' '\n' | sort -u' -c $($(repo)_DIR)/$
```

# 4 Dataset configuration file

#### 4.1 VecFloat

```
testGDataSetVecFloat.json:
```

```
"dataSet": "testGDataSet",
"dataSetType": "0",
"desc": "UnitTestGDataSetCreateFree",
"dim": {
 "_dim":"1",
  "_val":["2"]
"nbInputs":"1",
"nbOutputs":"1",
"nbSample": "3",
"samples": [
   "_dim":"2",
    "_val":["0.0","1.0"]
  },
  {
    "_dim":"2",
    "_val":["2.0","3.0"]
    "_dim":"2",
    "_val":["4.0","5.0"]
  testGDataSetVecFloatCovariance.json:
"dataSet": "testGDataSet",
"dataSetType": "0",
"desc": "UnitTestGDataSetVecFloatCovariance",
"dim": {
 "_dim":"1".
  "_val":["3"]
"nbSample": "3",
"nbInputs":"2",
"nbOutputs":"1",
"samples": [
  {
```

```
"_dim":"3",
      "_val":["1.0","2.0","3.0"]
    {
      "_dim":"3",
      "_val":["6.0","5.0","4.0"]
      "_dim":"3",
      "_val":["7.0","8.0","9.0"]
}
    testGDataSetVecFloat.json:
  "dataSet": "testGDataSet",
  "dataSetType": "0",
  "desc": "UnitTestGDataSetVecFloatNormalize",
    "_dim":"1",
    "_val":["3"]
  "nbInputs":"2",
  "nbOutputs":"1",
  "nbSample": "3",
  "samples": [
    {
      "_dim":"3",
      "_val":["1.0","2.0","3.0"]
    },
    {
      "_dim":"3",
      "_val":["6.0","5.0","4.0"]
      "_dim":"3",
      "_val":["7.0","8.0","9.0"]
}
```

## 4.2 Pair of GenBrush

```
{
  "dataSet": "dataset-002-001",
  "dataSetType": "1",
  "desc": "unitTest",
  "dim": {
      "_dim": "2",
      "_val": [
      "10",
      "20"
  ]
},
  "nbInputs":"2",
  "nbOutputs":"1",
  "format": "tga",
  "nbMask": "2",
```

```
"nbSample": "3",
"samples": [
  {
    "img": "img000.tga",
    "mask": [
      "mask000-000.tga",
      "mask000-001.tga"
    ]
  },
    "img": "img001.tga",
    "mask": [
      "mask001-000.tga",
      "mask001-001.tga"
    ٦
  {
    "img": "img002.tga",
    "mask": [
      "mask002-000.tga",
      "mask002-001.tga"
  }
]
```

## 5 Unit tests

```
#include <stdlib.h>
#include <stdlib.h>
#include <stdio.h>
#include <time.h>
#include <string.h>
#include <math.h>
#include "genbrush.h"
#include "gdataset.h"
void UnitTestGDataSetVecFloatCreateFreeClone() {
  srandom(1);
  char* cfgFilePath = "testGDataSetVecFloat.json";
  GDataSetVecFloat gdataset =
    GDataSetVecFloatCreateStaticFromFile(cfgFilePath);
  GDataSet* g = (GDataSet*)(&gdataset);
  if (GSetGet(g\rightarrow\_categories, 0) != GSetGet(\&(g\rightarrow\_samples), 0) ||
    GSetGet(g->_categories, 1) != GSetGet(&(g->_samples), 1) ||
GSetGet(g->_categories, 2) != GSetGet(&(g->_samples), 2)) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDataSetCreateStatic failed");
    PBErrCatch(GDataSetErr);
  GDataSetVecFloat clone = GDSClone(&gdataset);
  GDataSet* f = (GDataSet*)(&clone);
  if (GSetGet(f->_categories, 0) != GSetGet(&(f->_samples), 0) ||
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSClone failed");
    PBErrCatch(GDataSetErr);
```

```
GDataSetVecFloatFreeStatic(&clone);
  GDataSetVecFloatFreeStatic(&gdataset);
 printf("UnitTestGDataSetVecFloatCreateFreeClone OK\n");
void UnitTestGDataSetVecFloatGet() {
  srandom(1);
  char* cfgFilePath = "testGDataSetVecFloat.json";
 GDataSetVecFloat gdataset =
    GDataSetVecFloatCreateStaticFromFile(cfgFilePath);
  if (strcmp(GDSDesc(&gdataset), "UnitTestGDataSetCreateFree") != 0) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSDesc failed");
   PBErrCatch(GDataSetErr);
 if (strcmp(GDSName(&gdataset), "testGDataSet") != 0) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSName failed");
   PBErrCatch(GDataSetErr);
 }
  if (GDSGetType(&gdataset) != GDataSetType_VecFloat) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSGetType failed");
   PBErrCatch(GDataSetErr);
  if (GDSGetNbCat(&gdataset) != 1) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSGetNbCat failed");
    PBErrCatch(GDataSetErr);
  if (GDSGetSize(&gdataset) != 3) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSGetSize failed");
    PBErrCatch(GDataSetErr);
  if (GDSGetSizeCat(&gdataset, 0) != 3) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSGetSizeCat failed");
    PBErrCatch(GDataSetErr);
  if ((GSet*)GDSSamples(&gdataset) != &(gdataset._dataSet._samples)) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSSamples failed");
   PBErrCatch(GDataSetErr);
  VecShort* dim = VecShortCreate(1);
  VecSet(dim, 0, 2);
  if (VecIsEqual(GDSSampleDim(&gdataset), dim) != true) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSSampleDim failed");
   PBErrCatch(GDataSetErr);
 }
  VecFree(&dim);
  VecFloat* mean = GDSGetMean(&gdataset);
  VecFloat2D checkMean = VecFloatCreateStatic2D();
  VecSet(&checkMean, 0, 2.0);
  VecSet(&checkMean, 1, 3.0);
  if (!VecIsEqual(mean, &checkMean)) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSGetMean failed");
    PBErrCatch(GDataSetErr);
```

```
VecFree(&mean);
  VecFloat* max = GDSGetMax(&gdataset);
  VecFloat2D checkMax = VecFloatCreateStatic2D();
  VecSet(&checkMax, 0, 4.0);
  VecSet(&checkMax, 1, 5.0);
  if (!VecIsEqual(max, &checkMax)) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSGetMax failed");
    PBErrCatch(GDataSetErr);
  VecFree(&max);
  GDSMeanCenter(&gdataset);
  VecFloat2D checkMeanCenter[3];
  for (int i = 0; i < GDSGetSize(&gdataset); ++i) {</pre>
    checkMeanCenter[i] = VecFloatCreateStatic2D();
    VecSet(checkMeanCenter + i, 0, -2.0 + (float)i * 2.0);
    VecSet(checkMeanCenter + i, 1, -2.0 + (float)i * 2.0);
  GSetIterForward iter = GSetIterForwardCreateStatic(
    GDSSamples(&gdataset));
  int i = 0;
  do {
    VecFloat* sample = GSetIterGet(&iter);
    if (!VecIsEqual(sample, checkMeanCenter + i)) {
      GDataSetErr->_type = PBErrTypeUnitTestFailed;
      sprintf(GDataSetErr->_msg, "GDSMeanCenter failed");
      PBErrCatch(GDataSetErr);
  } while (GSetIterStep(&iter) && ++i);
  GDataSetVecFloatFreeStatic(&gdataset);
 printf("UnitTestGDataSetVecFloatGet OK\n");
}
void UnitTestGDataSetVecFloatSplitUnsplit() {
  srandom(1):
  char* cfgFilePath = "testGDataSetVecFloat.json";
  GDataSetVecFloat gdataset =
    GDataSetVecFloatCreateStaticFromFile(cfgFilePath);
  VecLong* split = VecLongCreate(2);
  VecSet(split, 0, 1);
  VecSet(split, 1, 2);
  GDSSplit(&gdataset, split);
  if (GDSGetNbCat(&gdataset) != 2) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSSplit failed");
    PBErrCatch(GDataSetErr);
  if (GDSGetSizeCat(&gdataset, 0) != 1 ||
    GDSGetSizeCat(&gdataset, 1) != 2) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSSplit failed");
    PBErrCatch(GDataSetErr);
  if (GDSGetSizeCat(&gdataset, 0) != GSetNbElem(gdataset._dataSet._categories) ||
    GDSGetSizeCat(&gdataset, 1) != GSetNbElem(gdataset._dataSet._categories + 1)) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSSplit failed");
    PBErrCatch(GDataSetErr);
  GDSUnsplit(&gdataset);
```

```
if (GDSGetNbCat(&gdataset) != 1) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSUnsplit failed");
   PBErrCatch(GDataSetErr);
  VecFree(&split);
 GDataSetVecFloatFreeStatic(&gdataset);
 printf("UnitTestGDataSetVecFloatSplitUnsplit OK\n");
void UnitTestGDataSetVecFloatShuffle() {
  srandom(1);
  char* cfgFilePath = "testGDataSetVecFloat.json";
  GDataSetVecFloat gdataset =
    GDataSetVecFloatCreateStaticFromFile(cfgFilePath);
  GDSShuffleCat(&gdataset, 0);
  GDataSet* g = (GDataSet*)(&gdataset);
  if (GSetGet(g->_categories, 0) != GSetGet(&(g->_samples), 1)/* ||
    GSetGet(g->_categories, 1) != GSetGet(&(g->_samples), 0) ||
    GSetGet(g->_categories, 2) != GSetGet(&(g->_samples), 1)*/) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSShuffleCat failed");
   PBErrCatch(GDataSetErr);
 GDataSetVecFloatFreeStatic(&gdataset);
 printf("UnitTestGDataSetVecFloatShuffle OK\n");
void UnitTestGDataSetVecFloatStepSampleGetSample() {
 srandom(1);
  char* cfgFilePath = "testGDataSetVecFloat.json";
  GDataSetVecFloat gdataset =
    GDataSetVecFloatCreateStaticFromFile(cfgFilePath);
  int iSample = 0;
  float check[6] = \{0.0, 1.0, 2.0, 3.0, 4.0, 5.0\};
  do {
    VecFloat* sample = GDSGetSample(&gdataset, 0);
    if (ISEQUALF(VecGet(sample, 0), check[iSample * 2]) == false ||
      ISEQUALF(VecGet(sample, 1), check[iSample * 2 + 1]) == false) {
     GDataSetErr->_type = PBErrTypeUnitTestFailed;
     sprintf(GDataSetErr->_msg, "GDSGetSample failed");
     PBErrCatch(GDataSetErr);
    VecFree(&sample);
    VecFloat* inputs = GDSGetSampleInputs(&gdataset, 0);
    VecFloat* outputs = GDSGetSampleOutputs(&gdataset, 0);
    if (ISEQUALF(VecGet(inputs, 0), check[iSample * 2]) == false) {
     GDataSetErr->_type = PBErrTypeUnitTestFailed;
     sprintf(GDataSetErr->_msg, "GDSGetSampleInputs failed");
     PBErrCatch(GDataSetErr);
    if (ISEQUALF(VecGet(outputs, 0), check[iSample * 2 + 1]) == false) {
     GDataSetErr->_type = PBErrTypeUnitTestFailed;
      sprintf(GDataSetErr->_msg, "GDSGetSampleOutputs failed");
     PBErrCatch(GDataSetErr);
    VecFree(&inputs);
    VecFree(&outputs);
  } while (GDSStepSample(&gdataset, 0));
  GDataSetVecFloatFreeStatic(&gdataset);
  printf("UnitTestGDataSetVecFloatStepSampleGetSample OK\n");
```

```
void UnitTestGDataSetVecFloatCovariance() {
  srandom(1):
  char* cfgFilePath = "testGDataSetVecFloatCovariance.json";
  GDataSetVecFloat gdataset =
    GDataSetVecFloatCreateStaticFromFile(cfgFilePath);
  MatFloat* covariance = GDSGetCovarianceMatrix(&gdataset);
 float v[9] = {
   6.888888, 6.0, 5.111111,
    6.0, 6.0, 6.0,
   5.111111, 6.0, 6.888888};
  VecShort2D i = VecShortCreateStatic2D();
  VecShort2D dim = VecShortCreateStatic2D();
  VecSet(&dim, 0, 3);
 VecSet(&dim, 1, 3);
 int j = 0;
 do {
    if (!ISEQUALF(MatGet(covariance, &i), v[j])) {
     GDataSetErr->_type = PBErrTypeUnitTestFailed;
      sprintf(GDataSetErr->_msg, "GDSGetCovarianceMatrix failed");
     PBErrCatch(GDataSetErr);
   }
   ++j;
 } while (VecStep(&i, &dim));
 MatFree(&covariance);
 GDataSetVecFloatFreeStatic(&gdataset);
 printf("UnitTestGDataSetVecFloatCovariance OK\n");
void UnitTestGDataSetVecFloatNormalize() {
  char* cfgFilePath = "testGDataSetVecFloatNormalize.json";
  GDataSetVecFloat gdataset =
    GDataSetVecFloatCreateStaticFromFile(cfgFilePath);
  GDSNormalize(&gdataset);
 GSetIterForward iter =
    GSetIterForwardCreateStatic(GDSSamples(&gdataset));
  float check[9] = {
     0.267261,0.534522,0.801784,
     0.683763,0.569803,0.455842,
     0.502571,0.574367,0.646162
   };
 int i = 0;
  do {
    VecFloat* v = GSetIterGet(&iter);
    if (!ISEQUALF(VecGet(v, 0), check[i * 3]) ||
      !ISEQUALF(VecGet(v, 1), check[i * 3 + 1]) \ | \ |
      !ISEQUALF(VecGet(v, 2), check[i * 3 + 2])) {
     GDataSetErr->_type = PBErrTypeUnitTestFailed;
      sprintf(GDataSetErr->_msg, "GDSNormalize failed");
     PBErrCatch(GDataSetErr);
   }
    ++i;
 } while(GSetIterStep(&iter));
 GDataSetVecFloatFreeStatic(&gdataset);
 printf("UnitTestGDataSetVecFloatNormalize OK\n");
void VecFloatCSVImporter(
 int col,
 char* val,
```

```
VecFloat* sample) {
  if (col == 0) {
    if (*val == 'A') {
     VecSet(sample, col, 10.0);
    } else if (*val == 'B') {
      VecSet(sample, col, 20.0);
   }
 } else {
   VecSet(sample, col, atof(val));
 }
void UnitTestGDataSetVecFloatCreateFromCSVSave() {
 char* csvPath = "./unitTestVecFloatCSV.csv";
 GDSVecFloatCSVImporter importer =
    GDSVecFloatCSVImporterCreateStatic(
     1,
      ,,,,
     3,
     3.
     &VecFloatCSVImporter);
  GDataSetVecFloat dataset =
   GDataSetCreateStaticFromCSV(csvPath, &importer);
  if (GDSGetSize(&dataset) != 3 ||
    GDSGetNbCat(&dataset) != 1) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDataSetCreateStaticFromCSV failed");
   PBErrCatch(GDataSetErr);
 float check[] = {
    10.0,1.0,2.0,
    10.0,3.0,4.0,
   20.0,5.0,6.0};
  for (int iSample = 0; iSample < GDSGetSize(&dataset); ++iSample) {</pre>
    for (unsigned int iCol = 0; iCol < importer._nbCol; ++iCol) {</pre>
      if (ISEQUALF(check[iSample * importer._nbCol + iCol],
        VecGet(GSetGet(GDSSamples(&dataset), iSample), iCol)) == false) {
        GDataSetErr->_type = PBErrTypeUnitTestFailed;
        sprintf(GDataSetErr->_msg, "GDataSetCreateStaticFromCSV failed");
        PBErrCatch(GDataSetErr);
   }
 FILE* stream = fopen("./unitTestVecFloatSave.json", "w");
  if (GDSSave(&dataset, stream, false) == false) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDataSetVecFloatSave failed");
   PBErrCatch(GDataSetErr);
 fclose(stream);
  GDataSetVecFloat load =
    GDataSetVecFloatCreateStaticFromFile("./unitTestVecFloatSave.json");
  for (int iSample = 0; iSample < GDSGetSize(&dataset); ++iSample) {</pre>
    for (unsigned int iCol = 0; iCol < importer._nbCol; ++iCol) {</pre>
      if (ISEQUALF(check[iSample * importer._nbCol + iCol],
        VecGet(GSetGet(GDSSamples(&load), iSample), iCol)) == false) {
        GDataSetErr->_type = PBErrTypeUnitTestFailed;
        sprintf(GDataSetErr->_msg, "GDataSetVecFloatSave failed");
        PBErrCatch(GDataSetErr);
   }
 }
```

```
GDataSetVecFloatFreeStatic(&dataset);
 GDataSetVecFloatFreeStatic(&load);
 printf("UnitTestGDataSetVecFloatCreateFromCSVSave OK\n");
void UnitTestGDataSetVecFloatSaveCategory() {
  char* csvPath = "./unitTestVecFloatCSV.csv";
  GDSVecFloatCSVImporter importer =
    GDSVecFloatCSVImporterCreateStatic(
     1,
      ,,,
     3,
     3.
     &VecFloatCSVImporter);
  GDataSetVecFloat dataset =
    GDataSetCreateStaticFromCSV(
     csvPath,
     &importer);
  VecLong2D split = VecLongCreateStatic2D();
  VecSet(&split, 0, 1);
  VecSet(&split, 1, 2);
  GDSSplit(&dataset, &split);
 FILE* stream = fopen("./unitTestVecFloatSaveCategory.json", "w");
  GDSVecFloatSaveCategory(
    &dataset,
    stream,
    true,
   1);
  fclose(stream);
  GDataSetVecFloat load =
    GDataSetVecFloatCreateStaticFromFile(
      "./unitTestVecFloatSaveCategory.json");
  float check[] = {
    10.0,3.0,4.0,
    20.0,5.0,6.0};
  for (int iSample = 0; iSample < GDSGetSize(&load); ++iSample) {</pre>
    for (unsigned int iCol = 0; iCol < importer._nbCol; ++iCol) {</pre>
      if (ISEQUALF(check[iSample * importer._nbCol + iCol],
        VecGet(GSetGet(GDSSamples(&load), iSample), iCol)) == false) {
        GDataSetErr->_type = PBErrTypeUnitTestFailed;
        sprintf(GDataSetErr->_msg, "GDataSetVecFloatSaveCategory failed");
       PBErrCatch(GDataSetErr);
   }
 GDataSetVecFloatFreeStatic(&dataset);
 GDataSetVecFloatFreeStatic(&load);
 printf("UnitTestGDataSetVecFloatSaveCategory OK\n");
void UnitTestGDataSetVecFloatAddRemoveSample() {
 char* cfgFilePath = "testGDataSetVecFloatNormalize.json";
 GDataSetVecFloat dataset =
    GDataSetVecFloatCreateStaticFromFile(cfgFilePath);
  VecLong2D split = VecLongCreateStatic2D();
  VecSet(&split, 0, 1);
  VecSet(&split, 1, 2);
  GDSSplit(&dataset, &split);
  GDSRemoveAllSample(&dataset);
  if (GDSGetNbCat(&dataset) != 1 ||
    GDSGetSize(&dataset) != 0) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
```

```
sprintf(GDataSetErr->_msg, "GDSVecFloatRemoveAllSample failed");
   PBErrCatch(GDataSetErr);
 VecFloat* sample = VecFloatCreate(3);
  GDSAddSample(&dataset, sample);
  if (GDSGetNbCat(&dataset) != 1 ||
    GDSGetSize(&dataset) != 1) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSVecFloatAddSample failed");
   PBErrCatch(GDataSetErr);
 GDataSetVecFloatFreeStatic(&dataset);
 printf("UnitTestGDataSetVecFloatAddRemoveSample OK\n");
void UnitTestGDataSetVecFloatProxMatNearestNeighbour() {
 char* cfgFilePath = "testGDataSetVecFloat.json";
  GDataSetVecFloat dataset =
    GDataSetVecFloatCreateStaticFromFile(cfgFilePath);
  MatFloat* proxMat = GDSGetProxMat(&dataset, 0);
  \verb|float check[3][3] = \{\{0.0, 2.828427, 5.656854\}, \{2.828427, 0.0, 2.828427\}, \{5.656854, 2.828427, 0.0\}\}; \\
  VecShort2D v = VecShortCreateStatic2D();
  do {
    if (!ISEQUALF(check[VecGet(&v, 0)][VecGet(&v, 1)],
     MatGet(proxMat, &v))) {
     GDataSetErr->_type = PBErrTypeUnitTestFailed;
      sprintf(GDataSetErr->_msg, "GDSGetProxMat failed");
     PBErrCatch(GDataSetErr);
 } while(VecStep(&v, MatDim(proxMat)));
  VecFloat2D target = VecFloatCreateStatic2D();
  VecSet(&target, 0, 6.0);
  VecSet(&target, 1, 1.5);
  VecFloat* nearest =
    GDSNearestNeighbour(&dataset, (VecFloat*)&target, 0);
  VecFloat2D checkb = VecFloatCreateStatic2D();
  VecSet(&checkb, 0, 4.0);
  VecSet(&checkb, 1, 5.0);
  if (!VecIsEqual(nearest, &checkb)) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSNearestNeighbour failed");
   PBErrCatch(GDataSetErr);
  VecFree(&nearest):
 MatFree(&proxMat);
  GDataSetVecFloatFreeStatic(&dataset);
  srandom(time(NULL));
  for (int size = 100; size < 10000; size *= 2) {
    dataset = GDataSetVecFloatCreateStatic();
    dataset._dataSet._sampleDim = VecShortCreate(1);
    VecSet(dataset._dataSet._sampleDim, 0, 3);
    for (int iSample = size; iSample--;) {
      VecFloat* sample = VecFloatCreate(3);
      VecSet(sample, 0, (0.5 - rnd()) * 100.0);
     VecSet(sample, 1, (0.5 - rnd()) * 100.0);
      VecSet(sample, 2, (0.5 - rnd()) * 100.0);
     GDSAddSample(&dataset, sample);
    VecLong* split = VecLongCreate(1);
    VecSet(split, 0, size);
    GDSSplit(&dataset, split);
```

```
VecFree(&split);
    float delayAESA = 0.0;
    float delayBruteForce = 0.0;
    for (int iCheck = 10; iCheck--;) {
      VecFloat3D target3d = VecFloatCreateStatic3D();
      VecSet(&target3d, 0, (0.5 - rnd()) * 100.0);
VecSet(&target3d, 1, (0.5 - rnd()) * 100.0);
      VecSet(&target3d, 2, (0.5 - rnd()) * 100.0);
      GDSResetAll(&dataset);
      clock_t clockBefore = clock();
      VecFloat* checkNearest = GDSVecFloatNearestNeighbourBrute(
        &dataset, (VecFloat*)&target3d, 0);
      clock_t clockAfter = clock();
      delayBruteForce += ((double)(clockAfter - clockBefore)) /
        CLOCKS_PER_SEC * 1000.0;
      clockBefore = clock();
      nearest = GDSVecFloatNearestNeighbourAESA(
        &dataset, (VecFloat*)&target3d, 0);
      clockAfter = clock();
      delayAESA += ((double)(clockAfter - clockBefore)) /
        CLOCKS_PER_SEC * 1000.0;
      if (!VecIsEqual(nearest, checkNearest)) {
        GDataSetErr->_type = PBErrTypeUnitTestFailed;
        sprintf(GDataSetErr->_msg, "GDSNearestNeighbour failed");
        PBErrCatch(GDataSetErr);
      VecFree(&checkNearest);
    printf("size: %d, ratio bruteForce/AESA: %f\n",
      size, delayBruteForce / delayAESA);
    GDataSetVecFloatFreeStatic(&dataset);
printf("UnitTestGDataSetVecFloatProxMatNearestNeighbour OK\n");
}
void UnitTestGDataSetVecFloat() {
  UnitTestGDataSetVecFloatCreateFreeClone();
  UnitTestGDataSetVecFloatGet();
  UnitTestGDataSetVecFloatSplitUnsplit();
  UnitTestGDataSetVecFloatShuffle();
  UnitTestGDataSetVecFloatStepSampleGetSample();
  UnitTestGDataSetVecFloatCovariance();
  UnitTestGDataSetVecFloatNormalize();
  UnitTestGDataSetVecFloatCreateFromCSVSave();
  UnitTestGDataSetVecFloatSaveCategory();
  UnitTestGDataSetVecFloatAddRemoveSample();
  UnitTestGDataSetVecFloatProxMatNearestNeighbour();
void UnitTestGDataSetGenBrushPair() {
  char* cfgFilePath = "testGDataSetGenBrushPair.json";
  GDataSetGenBrushPair gdataset =
    GDataSetGenBrushPairCreateStaticFromFile(cfgFilePath);
  if (GDSGetNbMask(&gdataset) != 2) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSGetSample<GenBrushPair> failed");
    PBErrCatch(GDataSetErr);
```

```
int iCat = 0;
  do {
    GDSGenBrushPair* sample = GDSGetSample(&gdataset, iCat);
    if (VecIsEqual(GBDim(sample->_img),
      GDSSampleDim(&gdataset)) == false ||
      VecIsEqual(GBDim(sample->_mask[0]),
     GDSSampleDim(&gdataset)) == false ||
      VecIsEqual(GBDim(sample->_mask[1]),
     GDSSampleDim(&gdataset)) == false) {
     GDataSetErr->_type = PBErrTypeUnitTestFailed;
      sprintf(GDataSetErr->_msg, "GDSGetSample<GenBrushPair> failed");
     PBErrCatch(GDataSetErr);
   GDSGenBrushPairFree(&sample);
  } while (GDSStepSample(&gdataset, iCat));
 GDataSetGenBrushPairFreeStatic(&gdataset);
 printf("UnitTestGDataSetGenBrushPair OK\n");
void UnitTestSDSIA() {
 srandom(1);
  char* cfgFilePath = "../SDSIA/UnitTestOut/002/001/dataset.json";
  GDataSetGenBrushPair gdataset =
    GDataSetGenBrushPairCreateStaticFromFile(cfgFilePath);
  int iCat = 0;
  do {
    GDSGenBrushPair* sample = GDSGetSample(&gdataset, iCat);
    if (VecIsEqual(GBDim(sample->_img),
     GDSSampleDim(&gdataset)) == false ||
      VecIsEqual(GBDim(sample->_mask[0]),
     GDSSampleDim(&gdataset)) == false ||
      VecIsEqual(GBDim(sample->_mask[1]),
      GDSSampleDim(&gdataset)) == false) {
     GDataSetErr->_type = PBErrTypeUnitTestFailed;
      sprintf(GDataSetErr->_msg, "GDSGetSample<GenBrushPair> failed");
     PBErrCatch(GDataSetErr);
    GDSGenBrushPairFree(&sample);
  } while (GDSStepSample(&gdataset, iCat));
 GDataSetGenBrushPairFreeStatic(&gdataset);
 printf("UnitTestSDSIA OK\n");
void UnitTestNNEvalCSVImporter(
       int col.
      char* val,
  VecFloat* sample) {
  if (col == 0) {
    if (*val == 'M') {
     VecSet(sample, 0, 1.0);
     VecSet(sample, 1, 0.0);
     VecSet(sample, 2, 0.0);
    } else if (*val == 'F') {
      VecSet(sample, 0, 0.0);
      VecSet(sample, 1, 1.0);
     VecSet(sample, 2, 0.0);
    } else if (*val == 'I') {
      VecSet(sample, 0, 0.0);
      VecSet(sample, 1, 0.0);
      VecSet(sample, 2, 1.0);
   }
 } else {
```

```
VecSet(sample, col + 2, atof(val));
 }
void UnitTestGDataSetNNEval() {
 char* csvPath = "./unitTestNNEval.csv";
 GDSVecFloatCSVImporter importer =
    GDSVecFloatCSVImporterCreateStatic(
     Ο,
     9,
     11.
     &UnitTestNNEvalCSVImporter);
  GDataSetVecFloat dataset =
   GDataSetCreateStaticFromCSV(csvPath, &importer);
  NeuraNet* nn = NULL;
 FILE* fp = fopen("./unitTestNNEval.json", "r");
  (void)NNLoad(&nn, fp);
  fclose(fp);
 VecShort* inputs = VecShortCreate(10);
 for (int i = 10; i--;)
   VecSet(inputs, i, i);
  VecShort* outputs = VecShortCreate(1);
 VecSet(outputs, 0, 10);
 int iCat = 0;
 float threshold = -1000.0;
  float val = GDSEvaluateNN(
   &dataset,
   nn,
   iCat,
   inputs,
    outputs,
   threshold);
  if (!ISEQUALF(val, -1.672186)) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSEvaluateNN failed");
   PBErrCatch(GDataSetErr);
 VecFree(&inputs);
 VecFree(&outputs);
 NeuraNetFree(&nn);
 GDataSetVecFloatFreeStatic(&dataset);
 printf("UnitTestNNEval OK\n");
void UnitTestGDataSetOutliers() {
  srandom(1);
 char* cfgFilePath = "testGDataSetVecFloatOutlier.json";
 GDataSetVecFloat dataset =
    GDataSetVecFloatCreateStaticFromFile(cfgFilePath);
 bool isOutlier =
   GDSIsOutlierSampleCat(
     &dataset,
     GDSGetSample(&dataset, 0),
     0);
  if (!isOutlier) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSIsOutlierSampleCat failed (1)");
   PBErrCatch(GDataSetErr);
```

```
isOutlier =
    {\tt GDSIsOutlierSampleCat} (
      &dataset,
      GDSGetSample(&dataset, 0),
      1);
  if (isOutlier) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSIsOutlierSampleCat failed (2)");
    PBErrCatch(GDataSetErr);
  GDSStepSample(&dataset, 0);
  isOutlier =
    GDSIsOutlierSampleCat(
      &dataset,
      GDSGetSample(&dataset, 0),
      0,
      0);
  if (isOutlier) {
    GDataSetErr->_type = PBErrTypeUnitTestFailed;
    sprintf(GDataSetErr->_msg, "GDSIsOutlierSampleCat failed (3)");
    PBErrCatch(GDataSetErr);
  GDataSetVecFloatFreeStatic(&dataset);
 printf("UnitTestGDataSetOutliers OK\n");
void UnitTestAll() {
  UnitTestGDataSetVecFloat();
  UnitTestGDataSetGenBrushPair();
  UnitTestGDataSetNNEval();
  UnitTestGDataSetOutliers();
  UnitTestSDSIA();
int main(void) {
  //UnitTestAll();
  UnitTestGDataSetOutliers();
 return 0;
```

## 6 Unit test output

```
UnitTestGDataSetVecFloatCreateFreeClone OK
UnitTestGDataSetVecFloatGet OK
UnitTestGDataSetVecFloatSplitUnsplit OK
UnitTestGDataSetVecFloatShuffle OK
UnitTestGDataSetVecFloatStepSampleGetSample OK
UnitTestGDataSetVecFloatCovariance OK
UnitTestGDataSetVecFloatNormalize OK
UnitTestGDataSetVecFloatCreateFromCSVSave OK
UnitTestGDataSetVecFloatSaveCategory OK
UnitTestGDataSetVecFloatAddRemoveSample OK
size: 100, ratio bruteForce/AESA: 0.102083
size: 200, ratio bruteForce/AESA: 0.049669
```

size: 400, ratio bruteForce/AESA: 0.033159 size: 800, ratio bruteForce/AESA: 0.028277 size: 1600, ratio bruteForce/AESA: 0.004135 size: 3200, ratio bruteForce/AESA: 0.001605 size: 6400, ratio bruteForce/AESA: 0.000488

 ${\tt UnitTestGDataSetVecFloatProxMatNearestNeighbour\ OK}$ 

 ${\tt UnitTestGDataSetGenBrushPair\ OK}$ 

UnitTestNNEval OK
UnitTestSDSIA OK