NeuraMorph

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Contents

1	Definitions	1
2	Interface	1
3	Code3.1 neuramorph.c3.2 neuramorph-inline.c	9 9 39
4	Makefile	56
5	Unit tests	56
6	Unit tests output	7 9

Introduction

NeuraMorph is a C library providing structures and functions to implement a neural network.

It uses the PBErr, PBMath, GSet library.

1 Definitions

2 Interface

// ====== NEURAMORPH.H =======

```
#ifndef NEURAMORPH_H
#define NEURAMORPH_H
// ======== Include ========
#include <stdlib.h>
#include <stdio.h>
#include <math.h>
#include <string.h>
#include <stdbool.h>
#include "pberr.h"
#include "pbmath.h"
#include "gset.h"
#include "gdataset.h"
#include "bcurve.h"
// ---- NeuraMorphUnit
// ========= Data structure =========
typedef struct NeuraMorphUnit {
  // Input indices in parent NeuraMorph
  VecLong* iInputs;
  // Output indices in parent NeuraMorph
  VecLong* iOutputs;
  // Lowest and highest values for filtering inputs
  VecFloat* lowFilters;
  VecFloat* highFilters;
  // Lowest and highest values of outputs
  VecFloat* lowOutputs;
  VecFloat* highOutputs;
  // Vector to memorize the output values
  VecFloat* outputs;
  // Transfer function
  BBody* transfer;
  // Working variable to avoid reallocation of memory at each Evaluate()
  VecFloat* unitInputs;
  // Variable to memorize the value of the unit during training
  float value;
} NeuraMorphUnit;
// ========= Functions declaration =========
// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
  const VecLong* iInputs,
  const VecLong* iOutputs);
// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that);
// Get the input indices of the NeuraMorphUnit 'that'
```

```
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that);
// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that);
// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that);
// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
  NeuraMorphUnit* that,
  const VecFloat* inputs);
// Get the number of input values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbInputs(const NeuraMorphUnit* that);
// Get the number of output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbOutputs(const NeuraMorphUnit* that);
// Get the number of coefficients in the transfer function of
// the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbCoeffs(const NeuraMorphUnit* that);
// Get the value of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
float NMUnitGetValue(const NeuraMorphUnit* that);
// Set the value of the NeuraMorphUnit 'that' to 'val'
#if BUILDMODE != 0
static inline
#endif
void NMUnitSetValue(
  NeuraMorphUnit* that,
            float val);
// Print the NeuraMorphUnit 'that' on the 'stream'
void NMUnitPrint(
  const NeuraMorphUnit* that,
                 FILE* stream);
#define NMUnitPrintln(T, S) \
  do {NMUnitPrint(T, S);fprintf(S, "\n");} while (false)
```

```
// ---- NeuraMorph
// ======= Data structure ========
typedef struct NeuraMorph {
  // Number of inputs and outputs
  long nbInput;
  long nbOutput;
  // Inputs and outputs values
VecFloat* inputs;
  VecFloat* outputs;
  // Internal values
  VecFloat* hiddens;
  // Lowest and highest values for internal values
  VecFloat* lowHiddens;
  VecFloat* highHiddens;
  // Flag to memorize if the outputs are to be seen as one hot encoding
  bool flagOneHot;
  // GSet of NeuraMorphUnit
  GSet units;
} NeuraMorph;
// ========= Functions declaration ===========
// Create a new NeuraMorph with 'nbInput' inputs and 'nbOutput' outputs
NeuraMorph* NeuraMorphCreate(
  long nbInput,
  long nbOutput);
// Free the memory used by the NeuraMorph 'that'
void NeuraMorphFree(NeuraMorph** that);
// Get the number of input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbInput(const NeuraMorph* that);
// Get the number of output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbOutput(const NeuraMorph* that);
// Get the input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
VecFloat* NMInputs(NeuraMorph* that);
// Get the output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
```

```
const VecFloat* NMOutputs(const NeuraMorph* that);
// Get the hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMHiddens(const NeuraMorph* that);
// Get the lowest bound of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMLowHiddens(const NeuraMorph* that);
// Get the highest bound of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMHighHiddens(const NeuraMorph* that);
// Get the number of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbHidden(const NeuraMorph* that);
// Set the number of hidden values of the NeuraMorph 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void NMSetNbHidden(
  NeuraMorph* that,
         long nb);
// Get the flag for one hot encoding of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
bool NMGetFlagOneHot(const NeuraMorph* that);
// Set the flag for one hot encoding of the NeuraMorph 'that' to 'flag'
#if BUILDMODE != 0
static inline
#endif
void NMSetFlagOneHot(
  NeuraMorph* that,
         bool flag);
// Add one NeuraMorphUnit with input and output indices 'iInputs'
// and 'iOutputs' to the NeuraMorph 'that'
// Return the created NeuraMorphUnit
NeuraMorphUnit* NMAddUnit(
     NeuraMorph* that,
  const VecLong* iInputs,
  const VecLong* iOutputs);
// Remove the NeuraMorphUnit 'unit' from the NeuraMorph 'that'
// The NeuraMorphUnit is not freed
void NMRemoveUnit(
     NeuraMorph* that,
  NeuraMorphUnit* unit);
```

```
// Burry the NeuraMorphUnits in the 'units' set into the
// NeuraMorph 'that'
// 'units' is empty after calling this function
// The NeuraMorphUnits iOutputs must point toward the NeuraMorph
// outputs
// NeuraMorphUnits' iOutputs are redirected toward new hidden values
// 'that->hiddens' is resized as necessary
void NMBurryUnits(
 NeuraMorph* that,
       GSet* units);
// Get a new vector with indices of the outputs in the NeuraMorph 'that'
VecLong* NMGetVecIOutputs(const NeuraMorph* that);
// Evaluate the NeuraMorph 'that' on the 'inputs' values
void NMEvaluate(
 NeuraMorph* that,
   VecFloat* inputs);
// ---- NeuraMorphTrainer
// ======= Data structure =========
typedef struct NeuraMorphTrainer {
  // Trained NeuraMorph
 NeuraMorph* neuraMorph;
  // Training dataset
 GDataSetVecFloat* dataset;
  // Index of the dataset's category used for training and evaluation
 unsigned int iCatTraining;
 unsigned int iCatEval;
  // Depth of the training
 short depth;
  // Order of the transfer function of NeuraMorphUnit
 int order;
  // Maximum number of inputs per NeuraMorphUnit
 int nbMaxInputsUnit;
 // Threshold used to discard weakest units during training
  // in [0.0,1.0]
 float weakUnitThreshold;
  // Maximum number of unit kept at each depth
 int nbMaxUnitDepth;
  // Max level of division of values' range
 short maxLvlDiv;
  // Precomputed values to train the NeuraMorphUnit
 VecFloat** preCompInp;
 VecFloat** preCompOut;
  // Lowest and highest values for input values in the training
  // dataset
 VecFloat* lowInputs;
 VecFloat* highInputs;
```

```
// Variable to store the result of the last evaluation
  VecFloat3D resEval;
} NeuraMorphTrainer;
// ====== Functions declaration ==========
// Create a static NeuraMorphTrainer for the NeuraMorph 'neuraMorph' and the
// GDataSet 'dataset'
// Default depth: 2
// Default iCatTraining: 0
// Default weakUnitThreshold: 0.9
NeuraMorphTrainer NeuraMorphTrainerCreateStatic(
        NeuraMorph* neuraMorph,
  GDataSetVecFloat* dataset);
// Free the memory used by the static NeuraMorphTrainer 'that'
void NeuraMorphTrainerFreeStatic(NeuraMorphTrainer* that);
// Run the training process for the NeuraMorphTrainer 'that'
void NMTrainerRun(NeuraMorphTrainer* that);
// Run the evaluation process for the NeuraMorphTrainer 'that'
void NMTrainerEval(NeuraMorphTrainer* that);
// Get the depth of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
short NMTrainerGetDepth(const NeuraMorphTrainer* that);
// Set the depth of the NeuraMorphTrainer 'that' to 'depth'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetDepth(
  NeuraMorphTrainer* that,
              short depth);
// Get the maxLvlDiv of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
short NMTrainerGetMaxLvlDiv(const NeuraMorphTrainer* that);
// Set the maxLvlDiv of the NeuraMorphTrainer 'that' to 'lvl'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetMaxLvlDiv(
 NeuraMorphTrainer* that,
              short lvl);
// Get the order of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
int NMTrainerGetOrder(const NeuraMorphTrainer* that);
// Set the order of the NeuraMorphTrainer 'that' to 'order'
#if BUILDMODE != 0
```

```
static inline
#endif
void NMTrainerSetOrder(
  NeuraMorphTrainer* that,
                 int order);
// Get the nbMaxUnitDepth of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
int NMTrainerGetNbMaxUnitDepth(const NeuraMorphTrainer* that);
// Set the nbMaxUnitDepth of the NeuraMorphTrainer 'that' to 'nbMaxUnitDepth'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetNbMaxUnitDepth(
  NeuraMorphTrainer* that,
                 int nbMaxUnitDepth);
// Get the nbMaxInputsUnit of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
int NMTrainerGetNbMaxInputsUnit(const NeuraMorphTrainer* that);
// Set the nbMaxInputsUnit of the NeuraMorphTrainer 'that' to 'order'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetNbMaxInputsUnit(
  NeuraMorphTrainer* that,
                 int nbMaxInputsUnit);
// Get the weakness threshold of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
float NMTrainerGetWeakThreshold(const NeuraMorphTrainer* that);
// Set the weakness threshold of the NeuraMorphTrainer 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetWeakThreshold(
  NeuraMorphTrainer* that,
               float weakUnitThreshold);
// Get the index of the training category of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
unsigned int NMTrainerGetICatTraining(const NeuraMorphTrainer* that);
// Set the index of the training category of the NeuraMorphTrainer 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetICatTraining(
  NeuraMorphTrainer* that,
```

```
unsigned int iCatTraining);
// Get the index of the evaluation category of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
unsigned int NMTrainerGetICatEval(const NeuraMorphTrainer* that);
// Set the index of the evaluation category of the NeuraMorphTrainer 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetICatEval(
 NeuraMorphTrainer* that,
       unsigned int iCatEval);
// Get the NeuraMorph of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
NeuraMorph* NMTrainerNeuraMorph(const NeuraMorphTrainer* that);
// Get the GDataSet of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
GDataSetVecFloat* NMTrainerDataset(const NeuraMorphTrainer* that);
// Get the result of the last evaluation of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat3D* NMTrainerResEval(const NeuraMorphTrainer* that);
// ======== static inliner =========
#if BUILDMODE != 0
#include "neuramorph-inline.c"
#endif
#endif
```

3 Code

3.1 neuramorph.c

```
// ========= Functions declaration ==========
// Update the low and high of the hiddens of the NeuraMorph 'that' with
// the low and high of its units
void NMUpdateLowHighHiddens(NeuraMorph* that);
// ====== Functions implementation =========
// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
 const VecLong* iInputs,
const VecLong* iOutputs) {
#if BUILDMODE == 0
 if (iInputs == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
     NeuraMorphErr->_msg,
      "'iInputs' is null");
   PBErrCatch(NeuraMorphErr);
  if (iOutputs == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
     NeuraMorphErr->_msg,
      "'iOutputs' is null");
    PBErrCatch(NeuraMorphErr);
 }
#endif
  // Allocate memory for the NeuraMorphUnit
 NeuraMorphUnit* that =
   PBErrMalloc(
     NeuraMorphErr,
      sizeof(NeuraMorphUnit));
  // Get the number of inputs (including the constant) and outputs
  long nbIn = VecGetDim(iInputs);
 long nbOut = VecGetDim(iOutputs);
  // Init properties
  that->iInputs = VecClone(iInputs);
  that->iOutputs = VecClone(iOutputs);
 that->lowFilters = VecFloatCreate(nbIn);
  that->highFilters = VecFloatCreate(nbIn);
  that->lowOutputs = NULL;
  that->highOutputs = NULL;
  that->outputs = VecFloatCreate(nbOut);
  VecShort2D dim = VecShortCreateStatic2D();
 VecSet(
   &dim,
   Ο,
   nbIn):
 VecSet(
```

```
&dim,
    1,
    nbOut);
  that->transfer = NULL;
  that->unitInputs = VecFloatCreate(nbIn);
  that->value = 0.0;
  // Return the new NeuraMorphUnit
  return that;
}
// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that) {
  // Check the input
  if (that == NULL || *that == NULL) {
    return;
  }
  // Free memory
  VecFree(&((*that)->iInputs));
  VecFree(&((*that)->iOutputs));
  VecFree(&((*that)->lowFilters));
  VecFree(&((*that)->highFilters));
  if ((*that)->lowOutputs != NULL) {
    VecFree(&((*that)->lowOutputs));
  }
  if ((*that)->highOutputs != NULL) {
    VecFree(&((*that)->highOutputs));
  VecFree(&((*that)->outputs));
  BBodyFree(&((*that)->transfer));
  VecFree(&((*that)->unitInputs));
  free(*that);
  *that = NULL;
}
// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
  NeuraMorphUnit* that,
  const VecFloat* inputs) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
```

```
}
  if (VecGetDim(inputs) != VecGetDim(that->iInputs)) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'inputs' has invalid dimension (%ld!=%ld)",
      VecGetDim(inputs),
      VecGetDim(that->iInputs));
    PBErrCatch(NeuraMorphErr);
  }
#endif
  // Reset the outputs
  VecFree(&(that->outputs));
  // Update the scaled inputs
  for (
   long iInput = 0;
    iInput < VecGetDim(that->unitInputs);
    ++iInput) {
    // Get the input value and its low/high filters
    float val =
      VecGet(
        inputs,
        iInput);
    float low =
      VecGet(
        that->lowFilters,
        iInput);
    float high =
      VecGet(
        that->highFilters,
        iInput);
    // Set the value in the unit inputs
    VecSet(
      that->unitInputs,
      iInput,
      (val - low) / (high - low));
  }
  // Apply the transfer function
  that->outputs =
    BBodyGet(
      that->transfer,
      that->unitInputs);
  \ensuremath{//} If the low and high values for outputs don't exist yet
  if (that->lowOutputs == NULL) {
    // Create the low and high values by cloning the current output
    that->lowOutputs = VecClone(that->outputs);
    that->highOutputs = VecClone(that->outputs);
  // Else, the low and high values for outputs exist
```

```
} else {
    \ensuremath{//} Loop on the outputs
    for (
      long iOutput = 0;
      iOutput < VecGetDim(that->outputs);
      ++iOutput) {
      // Update the low and high values for this output
      float val =
        VecGet(
          that->outputs,
          iOutput);
      float curLow =
        VecGet(
          that->lowOutputs,
          iOutput);
      if (curLow > val) {
        VecSet(
          that->lowOutputs,
          iOutput,
          val);
      }
      float curHigh =
        VecGet(
          that->highOutputs,
          iOutput);
      if (curHigh < val) {
        VecSet(
          that->highOutputs,
          iOutput,
          val);
      }
    }
  }
}
// Print the NeuraMorphUnit 'that' on the 'stream'
void NMUnitPrint(
  const NeuraMorphUnit* that,
                  FILE* stream) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
```

```
if (stream == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'stream' is null");
    PBErrCatch(NeuraMorphErr);
#endif
  VecPrint(
    NMUnitIInputs(that),
    stream);
  fprintf(
    stream,
    " -> ");
  VecPrint(
    NMUnitIOutputs(that),
    stream);
  fprintf(
    stream,
    " (%04.6f)",
    NMUnitGetValue(that));
// ---- NeuraMorph
// ====== Functions implementation =========
// Create a new NeuraMorph with 'nbInput' inputs and 'nbOutput' outputs
NeuraMorph* NeuraMorphCreate(
  long nbInput,
  long nbOutput) {
  // Allocate memory for the NeuraMorph
  NeuraMorph* that =
   PBErrMalloc(
      NeuraMorphErr,
      sizeof(NeuraMorph));
  // Init properties
  that->nbInput = nbInput;
  that->nbOutput = nbOutput;
  that->inputs = VecFloatCreate(nbInput);
  that->outputs = VecFloatCreate(nbOutput);
  that->hiddens = NULL;
  that->lowHiddens = NULL;
  that->highHiddens = NULL;
  that->units = GSetCreateStatic();
  that->flagOneHot = false;
  // Return the NeuraMorph
  return that;
}
// Free the memory used by the NeuraMorph 'that'
void NeuraMorphFree(NeuraMorph** that) {
```

```
// Check the input
  if (that == NULL || *that == NULL) {
    return;
  }
  // Free memory
  VecFree(&((*that)->inputs));
  VecFree(&((*that)->outputs));
  if ((*that)->hiddens != NULL) {
    VecFree(&((*that)->hiddens));
    VecFree(&((*that)->lowHiddens));
    VecFree(&((*that)->highHiddens));
  }
  while (GSetNbElem(&((*that)->units)) > 0) {
    NeuraMorphUnit* unit = GSetPop(&((*that)->units));
    NeuraMorphUnitFree(&unit);
  free(*that);
  *that = NULL;
}
// Add one NeuraMorphUnit with input and output indices 'iInputs'
// and 'iOutputs' to the NeuraMorph 'that'
// Return the created NeuraMorphUnit
NeuraMorphUnit* NMAddUnit(
    NeuraMorph* that,
  const VecLong* iInputs,
  const VecLong* iOutputs) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
  if (iInputs == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputs' is null");
    PBErrCatch(NeuraMorphErr);
  }
  if (iOutputs == NULL) {
```

```
NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'iOutputs' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  // Create the NeuraMorphUnit
  NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
      iInputs,
      iOutputs);
  // Append the new NeuraorphUnit to the set of NeuraMorphUnit
  GSetAppend(
    &(that->units),
    unit);
  // Return the new unit
  return unit;
// Remove the NeuraMorphUnit 'unit' from the NeuraMorph 'that'
// The NeuraMorphUnit is not freed
void NMRemoveUnit(
      NeuraMorph* that,
  NeuraMorphUnit* unit) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  // Remove the NeuraorphUnit from the set of NeuraMorphUnit
  GSetRemoveAll(
    &(that->units),
    unit);
}
// Burry the NeuraMorphUnits in the 'units' set into the
// NeuraMorph 'that'
// 'units' is empty after calling this function
// The NeuraMorphUnits iOutputs must point toward the NeuraMorph
// NeuraMorphUnits' iOutputs are redirected toward new hidden values // 'that->hiddens' is resized as necessary
void NMBurryUnits(
```

```
NeuraMorph* that,
       GSet* units) {
#if BUILDMODE == 0
 if (that == NULL) {
   NeuraMorphErr->_type = PBErrTypeNullPointer;
   sprintf(
     NeuraMorphErr->_msg,
     "'that' is null");
   PBErrCatch(NeuraMorphErr);
 }
#endif
  // Declare a variable to memorize the number of hidden values
 long nbHiddenValues = 0;
  // While there are units to burry
 while (GSetNbElem(units) > 0) {
    // Get the unit
   NeuraMorphUnit* unit = GSetPop(units);
    // Loop on the iOutputs of the unit
   for (
     long iOutput = 0;
     iOutput < VecGetDim(NMUnitIOutputs(unit));</pre>
     ++iOutput) {
     long indice =
        VecGet(
         NMUnitIOutputs(unit),
          iOutput);
      VecSet(
       unit->iOutputs,
        iOutput,
       indice + nbHiddenValues);
    // Append the unit to the set of NeuraMorphUnit
    GSetAppend(
     &(that->units),
     unit);
    // Update the number of new hidden values
   nbHiddenValues += VecGetDim(NMUnitIOutputs(unit));
 }
 // If there is already hidden values
 if (that->hiddens != NULL) {
    // Add the previous number of hidden values
   nbHiddenValues += VecGetDim(that->hiddens);
    // Free memory
    VecFree(&(that->hiddens));
```

```
VecFree(&(that->lowHiddens));
    VecFree(&(that->highHiddens));
  }
  // If there are hidden values after burrying
  if (nbHiddenValues > 0) {
    // Resize the hiddens value vector
    that->hiddens = VecFloatCreate(nbHiddenValues);
    that->lowHiddens = VecFloatCreate(nbHiddenValues);
    that->highHiddens = VecFloatCreate(nbHiddenValues);
    // Update the low and high of the hiddens with the low and high
    // of the units
    NMUpdateLowHighHiddens(that);
  }
}
// Get a new vector with indices of the outputs in the NeuraMorph 'that'
VecLong* NMGetVecIOutputs(const NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  // Allocate memory for the result
  VecLong* iOutputs = VecLongCreate(NMGetNbOutput(that));
  // Loop on indices
  for (
    long iOutput = 0;
    iOutput < NMGetNbOutput(that);</pre>
    ++iOutput) {
    // Set the indice of this output
    VecSet(
      iOutputs,
      iOutput,
      iOutput + NMGetNbHidden(that));
  }
  // Return the result
  return iOutputs;
// Update the low and high of the hiddens of the NeuraMorph 'that' with
// the low and high of its units
```

```
void NMUpdateLowHighHiddens(NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  // Loop on the units
  GSetIterForward iter =
    GSetIterForwardCreateStatic(&(that->units));
  do {
    // Get the unit
    NeuraMorphUnit* unit = GSetIterGet(&iter);
    // Loop on the iOutputs of the unit
      long iOutput = 0;
      iOutput < VecGetDim(NMUnitIOutputs(unit));</pre>
      ++iOutput) {
      // Get the indice
      long indice =
        VecGet(
          NMUnitIOutputs(unit),
          iOutput);
      \ensuremath{//} If the indice points to a hidden value
      if (indice < NMGetNbHidden(that)) {</pre>
        // If the low and high exist
        if (
          unit->lowOutputs != NULL &&
          unit->highOutputs != NULL) {
          // Update the low and high
          float low =
            VecGet(
              unit->lowOutputs,
              iOutput);
          float high =
            VecGet(
              unit->highOutputs,
              iOutput);
          VecSet(
            that->lowHiddens,
            indice,
            low);
          VecSet(
            that->highHiddens,
            indice,
            high);
```

```
}
      }
    }
  } while (GSetIterStep(&iter));
// Evaluate the NeuraMorph 'that' on the 'inputs' values
void NMEvaluate(
  NeuraMorph* that,
    VecFloat* inputs) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  if (inputs == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'inputs' is null");
    PBErrCatch(NeuraMorphErr);
  if (VecGetDim(inputs) != VecGetDim(that->inputs)) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'inputs' has invalid size (%ld==%ld)",
      VecGetDim(inputs),
      VecGetDim(that->inputs));
    PBErrCatch(NeuraMorphErr);
  }
#endif
  // Copy the inputs into the internal inputs
  VecCopy(
    that->inputs,
    inputs);
  // Reset the internal outputs
  VecSetNull(that->outputs);
  // If there are no units
  if (GSetNbElem(&(that->units)) == 0) {
```

```
// Nothing else to do
  return;
}
// Loop on the units
GSetIterForward iter = GSetIterForwardCreateStatic(&(that->units));
do {
  // Get the unit
  NeuraMorphUnit* unit = GSetIterGet(&iter);
  // Allocate memory for inputs sent to the unit
  VecFloat* unitInputs = VecFloatCreate(NMUnitGetNbInputs(unit));
  // Loop on the input indices of the unit
  for (
    long iInput = 0;
    iInput < NMUnitGetNbInputs(unit);</pre>
    ++iInput) {
    // Get the input indice
    long indiceInput =
      VecGet(
        NMUnitIInputs(unit),
        iInput);
    // Declare a variable to memorize the input value
    float val = 0.0;
    \ensuremath{//} If this indice points toward an input
    if (indiceInput < NMGetNbInput(that)) {</pre>
      // \ensuremath{\mathsf{Get}} the input value of the NeuraMorph for this indice
      val =
        VecGet(
          NMInputs(that),
          indiceInput);
    // Else, the indice points toward a hidden value
    } else {
      // Get the hidden value of the NeuraMorph for this indice
      val =
        VecGet(
          that->hiddens,
          indiceInput - NMGetNbInput(that));
    // Set the input value for the unit for this indice
    VecSet(
      unitInputs,
      iInput,
      val);
  // Evaluate the unit
  NMUnitEvaluate(
    unit.
    unitInputs);
```

```
// Free the memory used by the unit input
  VecFree(&unitInputs);
  // Loop on the output indices of the unit
  for (
    long iOutput = 0;
    iOutput < NMUnitGetNbOutputs(unit);</pre>
    ++iOutput) {
    // Get the output value of the unit for this indice
    float val =
      VecGet(
        NMUnitOutputs(unit),
        iOutput);
    // Get the output indice
    long indiceOutput =
      VecGet(
        NMUnitIOutputs(unit),
        iOutput);
    // If the indice points toward a hidden
    if (indiceOutput < NMGetNbHidden(that)) {</pre>
      // Set the hidden value of the NeuraMorph for this indice
      VecSet(
        that->hiddens,
        indiceOutput,
        val);
    // Else, the indice points toward an output
    } else {
      // Set the output value of the NeuraMorph for this indice
      VecSet(
        that->outputs,
        indiceOutput - NMGetNbHidden(that),
        val);
    }
  }
} while (GSetIterStep(&iter));
// If the NeuraMorph is a one hot encoder
if (NMGetFlagOneHot(that) == true) {
  // Get the one hot
  long oneHot = VecGetIMaxVal(that->outputs);
  // Convert the output values
  VecSetAll(
    that->outputs,
    -1.0);
  VecSet(
    that->outputs,
    oneHot,
    1.0);
```

}

```
}
// ---- NeuraMorphTrainer
// ======= Functions declaration =========
// Return true if the vector 'v' is a valid indices configuration
// i.e. v[i] < v[j] for all i < j
bool NMTrainerIsValidInputConfig(
  const VecLong* v,
           long iMinInput);
// Train a new NeuraMorphUnit with the interface defined by 'iInputs'
\ensuremath{//} and 'iOutputs', and add it to the set, sorted on its value
// If 'lastUnit' is true, the NeuraMorphUnit will be the last one in
// its NeuraMorph
void NMTrainerTrainUnit(
  NeuraMorphTrainer* that,
              GSet* trainedUnits,
      const VecLong* iInputs,
     // Precompute the values of the NeuraMorph for each sample of the
// GDataset for the NeuraMorphTrainer 'that'
void NMTrainerPrecomputeValues(NeuraMorphTrainer* that);
// Free the precomputed values of the NeuraMorphTrainer 'that'
void NMTrainerFreePrecomputed(NeuraMorphTrainer* that);
// ====== Functions implementation =========
// Create a static NeuraMorphTrainer for the NeuraMorph 'neuraMorph' and the
// GDataSet 'dataset'
// Default depth: 2
// Default iCatTraining: 0
// Default weakUnitThreshold: 0.9
NeuraMorphTrainer NeuraMorphTrainerCreateStatic(
       NeuraMorph* neuraMorph,
  GDataSetVecFloat* dataset) {
#if BUILDMODE == 0
  if (neuraMorph == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
     NeuraMorphErr->_msg,
      "'neuraMorph' is null");
    PBErrCatch(NeuraMorphErr);
  }
  if (dataset == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'dataset' is null");
    PBErrCatch(NeuraMorphErr);
```

```
}
#endif
  // Declare the new NeuraMorphTrainer
  NeuraMorphTrainer that;
  // Init properties
  that.neuraMorph = neuraMorph;
  that.dataset = dataset;
  that.depth = 2;
  that.order = 1;
  that.nbMaxUnitDepth = 2;
  that.maxLvlDiv = 2;
  that.nbMaxInputsUnit =
    MAX(
      GDSGetNbOutputs(dataset),
      2);
  that.iCatTraining = 0;
  that.iCatEval = 1;
  that.weakUnitThreshold = 0.9;
  that.preCompInp = NULL;
  that.lowInputs = NULL;
  that.highInputs = NULL;
  that.resEval = VecFloatCreateStatic3D();
  // Return the NeuraMorphTrainer
  return that;
}
// Free the memory used by the static NeuraMorphTrainer 'that'
void NeuraMorphTrainerFreeStatic(NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
     NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  VecFree(&(that->lowInputs));
  VecFree(&(that->highInputs));
// Run the training process for the NeuraMorphTrainer 'that'
void NMTrainerRun(NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
```

```
NeuraMorphErr->_msg,
     "'that' is null");
    PBErrCatch(NeuraMorphErr);
 }
#endif
  // Declare a variable to memorize the minimum index needed in the
  // inputs of the new unit to ensure we do not train twice the same
 // unit
 long iMinInput = 0;
  // Loop on training depth
 for (
    short iDepth = 1;
   iDepth <= NMTrainerGetDepth(that);</pre>
    ++iDepth) {
   printf(
      "Depth %d/%d...\n",
      iDepth,
     NMTrainerGetDepth(that));
    // Get the number of available inputs for the new unit
    long nbAvailInputs =
      NMGetNbInput(NMTrainerNeuraMorph(that)) +
     NMGetNbHidden(NMTrainerNeuraMorph(that));
    printf(
      "Nb available inputs: ld\n",
     nbAvailInputs);
    // Precompute the values to speed up the training
    NMTrainerPrecomputeValues(that);
    // Get the output indices
    VecLong* iOutputs = NMGetVecIOutputs(NMTrainerNeuraMorph(that));
    // Declare a set to memorize the trained units
    GSet trainedUnits = GSetCreateStatic();
    // Set a flag to memorize if we are at the last depth
    bool isLastDepth = (iDepth == NMTrainerGetDepth(that));
    // Get the number of inputs per unit
    long nbMaxInputsUnit =
     MIN(
       nbAvailInputs,
        NMTrainerGetNbMaxInputsUnit(that));
    // Loop on the number of inputs for the new unit
    for (
     long nbUnitInputs = 1;
     nbUnitInputs <= nbMaxInputsUnit;</pre>
     ++nbUnitInputs) {
     printf(
        "Train units with %04ld input(s)\n",
       nbUnitInputs);
     // Loop on the possible input configurations for the new units
```

```
VecLong* iInputs = VecLongCreate(nbUnitInputs);
 VecLong* iInputsBound = VecLongCreate(nbUnitInputs);
 VecSetAll(
   iInputsBound,
    nbAvailInputs);
 bool hasStepped = true;
 do {
   bool isValidInputConfig =
      {\tt NMTrainerIsValidInputConfig(}
        iInputs,
        iMinInput);
    if (isValidInputConfig == true) {
      // Train the unit
      NMTrainerTrainUnit(
        that,
        &trainedUnits,
        iInputs,
        iOutputs,
        isLastDepth);
      }
    // Step to the next input configuration
   hasStepped =
      VecStep(
        iInputs,
        iInputsBound);
 } while (hasStepped);
 // Free memory
 VecFree(&iInputs);
 VecFree(&iInputsBound);
}
// If this is the last depth
if (isLastDepth == true) {
  // Add the best of all units to the NeuraMorph
 NeuraMorphUnit* bestUnit = GSetDrop(&trainedUnits);
 GSetAppend(
    &(NMTrainerNeuraMorph(that)->units),
   bestUnit);
 printf("Add the last unit\n");
 NMUnitPrintln(
   bestUnit,
    stdout);
  // Discard all other units
 while (GSetNbElem(&trainedUnits) > 0) {
    NeuraMorphUnit* unit = GSetPop(&trainedUnits);
   NeuraMorphUnitFree(&unit);
// Else, this is not the last depth
} else {
```

```
// \ensuremath{\mathsf{Get}} the value of the weakest and strongest units
      float weakVal = GSetElemGetSortVal(GSetHeadElem(&trainedUnits));
      float strongVal = GSetElemGetSortVal(GSetTailElem(&trainedUnits));
      // Get the threshold to discard the weakest units
      float threshold =
        weakVal + (strongVal - weakVal) *
        NMTrainerGetWeakThreshold(that);
      // Discard the weakest units
      long nbTrainedUnits = GSetNbElem(&trainedUnits);
      while (
        GSetElemGetSortVal(GSetHeadElem(&trainedUnits)) < threshold
        || GSetNbElem(&trainedUnits) > NMTrainerGetNbMaxUnitDepth(that)) {
        NeuraMorphUnit* unit = GSetPop(&trainedUnits);
        NeuraMorphUnitFree(&unit);
      }
      // Displayed the burried units
      printf(
        "Burry %ld out of %ld unit(s)\n",
        GSetNbElem(&trainedUnits),
        nbTrainedUnits);
      GSetIterForward iter = GSetIterForwardCreateStatic(&trainedUnits);
        NeuraMorphUnit* unit = GSetIterGet(&iter);
        NMUnitPrintln(
          unit,
          stdout);
      } while (GSetIterStep(&iter));
      // Burry the remaining units
      NMBurryUnits(
        NMTrainerNeuraMorph(that),
        &trainedUnits);
    }
    // Update the minimum index of a valid configuration
    iMinInput = nbAvailInputs;
    // Free memory
    VecFree(&iOutputs);
    NMTrainerFreePrecomputed(that);
// Return true if the vector 'v' is a valid indices configuration
// i.e. v[i] < v[j] for all i<j and there exists i such as
// v[i]>=iMinInput
bool NMTrainerIsValidInputConfig(
  const VecLong* v,
            long iMinInput) {
#if BUILDMODE == 0
```

} }

```
if (v == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
       "'v' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  bool noveltyCond = false;
  long a =
    VecGet(
      ν,
      0);
  if (a >= iMinInput) {
    noveltyCond = true;
  }
  for (
    long i = 1;
    i < VecGetDim(v);</pre>
    ++i) {
    long b =
      VecGet(
        v,
        i);
    if (a >= b) \{
      return false;
    a = b;
    if (a >= iMinInput) {
      noveltyCond = true;
    }
  return noveltyCond;
// Train a new NeuraMorphUnit with the interface defined by 'iInputs'
// and 'iOutputs', and add it to the set, sorted on its value
// If 'lastUnit' is true, the NeuraMorphUnit will be the last one in
// its NeuraMorph
void NMTrainerTrainUnit(
  NeuraMorphTrainer* that,
      GSet* trainedUnits, const VecLong* iInputs,
      const VecLong* iOutputs,
```

```
bool lastUnit) {
#if BUILDMODE == 0
 if (that == NULL) {
   NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
     NeuraMorphErr->_msg,
      "'that' is null");
   PBErrCatch(NeuraMorphErr);
 }
 if (trainedUnits == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'trainedUnits' is null");
   PBErrCatch(NeuraMorphErr);
 }
 if (iInputs == NULL) {
   NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
     NeuraMorphErr->_msg,
      "'iInputs' is null");
   PBErrCatch(NeuraMorphErr);
 if (iOutputs == NULL) {
   NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
     NeuraMorphErr->_msg,
     "'iOutputs' is null");
   PBErrCatch(NeuraMorphErr);
 }
#endif
  // Get the number of inputs
 long nbInputs = VecGetDim(iInputs);
 // Loop on the division levels
  // (None for the last unit)
 VecShort* curDivLvl = VecShortCreate(nbInputs);
 VecShort* divLvlBound = VecShortCreate(nbInputs);
 if (lastUnit == true) {
   VecSetAll(
     divLvlBound,
     0);
 } else {
    VecSetAll(
```

```
divLvlBound,
    NMTrainerGetMaxLvlDiv(that));
}
bool flagStepDivLvl = true;
do {
  // Get the bounds for the number of division for each input
  // at current levels
  VecShort* divBound = VecShortCreate(nbInputs);
    long iInput = nbInputs;
    iInput--;) {
    short lvl =
      VecGet(
        curDivLvl,
        iInput);
    short bound =
      powi(
        2,
        lv1);
    VecSet(
      divBound,
      iInput,
      bound);
  }
  // Loop on the combination of divisions
  VecShort* curDiv = VecShortCreate(nbInputs);
  bool flagStepDiv = true;
  do {
    // Create the unit
    NeuraMorphUnit* unit =
      NeuraMorphUnitCreate(
        iInputs,
        iOutputs);
    \ensuremath{//} Loop on the inputs of the unit
    for (
      long iInput = nbInputs;
      iInput--;) {
      // Get the indice of this input in the NeuraMorph
      short jInput =
        VecGet(
          NMUnitIInputs(unit),
          iInput);
      // Declare variables to memorize the lowest and highest
      // values for this input
      float low = 0.0;
      float high = 0.0;
      // If this input is an input in the NeuraMorph
      if (jInput < NMGetNbInput(NMTrainerNeuraMorph(that))) {</pre>
        low =
          VecGet(
```

```
that->lowInputs,
        jInput);
    high =
      VecGet(
        that->highInputs,
        jInput);
  // Else, this input is an hidden value in the NeuraMorph
  } else {
    low =
      VecGet(
        NMLowHiddens(NMTrainerNeuraMorph(that)),
        jInput - NMGetNbInput(NMTrainerNeuraMorph(that)));
    high =
      VecGet(
        NMHighHiddens(NMTrainerNeuraMorph(that)),
        jInput - NMGetNbInput(NMTrainerNeuraMorph(that)));
 }
  // Get the filter values for the current division
  float lowFilter =
    low + (high - low) *
    (float)VecGet(
      curDiv,
      iInput) /
    (float)VecGet(
      divBound,
      iInput);
  float highFilter =
    low + (high - low) *
    (float)(VecGet(
      curDiv,
      iInput) + 1) /
    (float)VecGet(
      divBound,
      iInput);
  // Set the filter values in the unit
  VecSet(
    unit->lowFilters,
    iInput,
    lowFilter);
  VecSet(
    unit->highFilters,
    iInput,
    highFilter);
// Declare two GSets to extract the filtered samples
GSetVecFloat trainingInputs = GSetVecFloatCreateStatic();
GSetVecFloat trainingOutputs = GSetVecFloatCreateStatic();
// Loop on the samples of the dataset
long nbSample =
  GDSGetSizeCat(
    NMTrainerDataset(that),
    NMTrainerGetICatTraining(that));
for (
  long iSample = 0;
```

}

```
iSample < nbSample;</pre>
++iSample) {
// Create the sample's inputs for this unit
VecFloat* sampleInputs = VecFloatCreate(nbInputs);
\ensuremath{//} If all the input values are within the bound of the unit
bool flag = true;
for (
  long iInput = nbInputs;
  flag && iInput--;) {
  float low =
    VecGet(
      unit->lowFilters,
      iInput);
  float high =
    VecGet(
      unit->highFilters,
     iInput);
  short jInput =
    VecGet(
      iInputs,
      iInput);
  float val =
    VecGet(
      that->preCompInp[iSample],
 jInput);
if (
    val < low ||
    val > high) {
    flag = false;
  // Simultaneously, scale the inputs values toward the unit
  // input space
  val = (val - low) / (high - low);
  VecSet(
    sampleInputs,
    iInput,
    val);
}
if (flag) {
  // Add this sample to the training set for the current unit
  {\tt GSetAppend(}
    &trainingInputs,
    sampleInputs);
  GSetAppend(
    &trainingOutputs,
    that->preCompOut[iSample]);
} else {
  // Free memory
  VecFree(&sampleInputs);
}
```

```
}
 \ensuremath{//} If we have enough samples to train the unit on the current
  // combination of divisions
 if (GSetNbElem(&trainingInputs) >= NMUnitGetNbInputs(unit)) {
    // Calculate the transfer function
    float bias = 0.0;
    unit->transfer =
      BBodyFromPointCloud(
        NMTrainerGetOrder(that),
        &trainingInputs,
        &trainingOutputs,
        &bias);
    // If we could calculate the transfer function
    if (unit->transfer != NULL) {
      // Set the value of the unit
      float corrRange =
        (float)GSetNbElem(&trainingInputs) /
        (float)GDSGetSizeCat(
          NMTrainerDataset(that),
          NMTrainerGetICatTraining(that));
      {\tt NMUnitSetValue}(
        unit,
        -1.0 * bias / corrRange);
      // Add the unit to the set of trained units
      GSetAddSort(
        trainedUnits,
        unit,
        NMUnitGetValue(unit));
    // Else, we couldn't calculate the transfer function
    } else {
      // Free memory
      NeuraMorphUnitFree(&unit);
   }
 }
 // Free memory
 while (GSetNbElem(&trainingInputs) > 0) {
    VecFloat* v = GSetPop(&trainingInputs);
    VecFree(&v);
 GSetFlush(&trainingOutputs);
  \ensuremath{//} Move to the next combination of divisions
 flagStepDiv =
    VecStep(
      curDiv,
      divBound);
} while (flagStepDiv);
```

```
// Free memory
    VecFree(&curDiv);
    VecFree(&divBound);
    // Move to the next division level
    flagStepDivLvl =
      VecStep(
        curDivLvl,
        divLvlBound);
  } while (flagStepDivLvl);
  // Free memory
  VecFree(&curDivLvl);
  VecFree(&divLvlBound);
}
// Precompute the values of the NeuraMorph for each sample of the
// GDataset for the NeuraMorphTrainer 'that'
void NMTrainerPrecomputeValues(NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  // Get the number of samples
  long nbSample =
    GDSGetSizeCat(
      NMTrainerDataset(that),
      NMTrainerGetICatTraining(that));
  // Allocate memory
  that->preCompInp =
    PBErrMalloc(
      NeuraMorphErr,
      nbSample * sizeof(VecFloat*));
  that->preCompOut =
    PBErrMalloc(
      NeuraMorphErr,
      nbSample * sizeof(VecFloat*));
  // Reset the low and high values for input
  VecFree(&(that->lowInputs));
  VecFree(&(that->highInputs));
  // Get the size of the precomputed vector
  long sizeInp =
    NMGetNbInput(NMTrainerNeuraMorph(that)) +
    NMGetNbHidden(NMTrainerNeuraMorph(that));
```

```
// Loop on the samples
long iSample = 0;
bool flagStep = true;
GDSReset(
  NMTrainerDataset(that),
  NMTrainerGetICatTraining(that));
do {
 // Get a clone of the sample's inputs
VecFloat* inputs =
    {\tt GDSGetSampleInputs(}
      NMTrainerDataset(that),
      NMTrainerGetICatTraining(that));
  \ensuremath{//} Update the low and high input values
  if (that->lowInputs == NULL) {
    that->lowInputs = VecClone(inputs);
    that->highInputs = VecClone(inputs);
  } else {
    for (
      long iInput = 0;
      iInput < VecGetDim(inputs);</pre>
      ++iInput) {
      float val =
        VecGet(
          inputs,
          iInput);
      float curLow =
        VecGet(
          that->lowInputs,
          iInput);
      if (curLow > val) {
        VecSet(
          that->lowInputs,
          iInput,
          val);
      }
      float curHigh =
        VecGet(
          that->highInputs,
          iInput);
      if (curHigh < val) {</pre>
        VecSet(
          that->highInputs,
          iInput,
          val);
      }
    }
  }
```

```
// Get a clone of the sample's outputs
  that->preCompOut[iSample] =
    GDSGetSampleOutputs(
      NMTrainerDataset(that),
      NMTrainerGetICatTraining(that));
  // Run the NeuraMorph on the sample
  NMEvaluate(
    NMTrainerNeuraMorph(that),
    inputs);
  // Allocate memory for the precomputed vector
  that->preCompInp[iSample] = VecFloatCreate(sizeInp);
  // Copy the inputs and hidden values into the precomputed vector
    long i = NMGetNbInput(NMTrainerNeuraMorph(that));
    i--;) {
    float val =
      VecGet(
        NMInputs(NMTrainerNeuraMorph(that)),
    VecSet(
      that->preCompInp[iSample],
      i,
      val);
  }
  for (
    long i = NMGetNbHidden(NMTrainerNeuraMorph(that));
    i--;) {
    float val =
      VecGet(
        NMHiddens(NMTrainerNeuraMorph(that)),
        i);
    VecSet(
      that->preCompInp[iSample],
      i + NMGetNbInput(NMTrainerNeuraMorph(that)),
  }
  // Free memory
  VecFree(&inputs);
  // Move to the next sample
  ++iSample;
  flagStep =
    GDSStepSample(
      NMTrainerDataset(that),
      NMTrainerGetICatTraining(that));
} while (flagStep);
\ensuremath{//} Finally, update the hiddens bound if any
if (NMGetNbHidden(NMTrainerNeuraMorph(that)) > 0) {
  NMUpdateLowHighHiddens(NMTrainerNeuraMorph(that));
```

```
}
}
// Free the precomputed hidden values of the NeuraMorphTrainer 'that'
void NMTrainerFreePrecomputed(NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  // If the hidden values are not precomputed
  if (that->preCompInp == NULL) {
    // Stop here
    return;
  // Get the number of samples
  long nbSample =
    {\tt GDSGetSizeCat}(
      NMTrainerDataset(that),
      NMTrainerGetICatTraining(that));
  // Free memory
  for (
    long iSample = nbSample;
    iSample--;) {
    VecFree(that->preCompInp + iSample);
    VecFree(that->preCompOut + iSample);
  }
  free(that->preCompInp);
  that->preCompInp = NULL;
  free(that->preCompOut);
  that->preCompOut = NULL;
}
// Run the evaluation process for the NeuraMorphTrainer 'that'
void NMTrainerEval(NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
```

```
"'that' is null");
   PBErrCatch(NeuraMorphErr);
 }
#endif
  // Declare a variable to calculate the result of evaluation
 float minBias = 0.0;
 float avgBias = 0.0;
 float maxBias = 0.0;
  // Loop on the evaluation samples
 long iSample = 0;
 bool flagStep = true;
 GDSReset(
   NMTrainerDataset(that),
   NMTrainerGetICatEval(that));
 do {
    // Get a clone of the sample's inputs and outputs
    VecFloat* inputs =
     GDSGetSampleInputs(
       NMTrainerDataset(that),
       NMTrainerGetICatEval(that));
    VecFloat* outputs =
     GDSGetSampleOutputs(
       NMTrainerDataset(that),
        NMTrainerGetICatEval(that));
    // Run the NeuraMorph on the sample
   NMEvaluate(
     NMTrainerNeuraMorph(that),
     inputs);
   // Display the result
    printf(
      "%021d ",
     iSample);
    VecPrint(
     inputs,
     stdout);
   printf(" -> ");
    VecPrint(
     outputs,
     stdout);
    printf(" : ");
    VecPrint(
     NMOutputs(NMTrainerNeuraMorph(that)),
     stdout);
   printf(" ");
   float bias =
     VecDist(
        outputs,
       NMOutputs(NMTrainerNeuraMorph(that)));
    printf(
     "%f\n",
     bias);
    // Update the result of evaluation
   avgBias += bias;
    if (iSample == 0) {
```

```
minBias = bias;
   maxBias = bias;
 } else {
   minBias =
     MIN(
       bias,
       minBias);
   maxBias =
     MAX(
       bias,
       maxBias);
 }
  // Free memory
  VecFree(&inputs);
 VecFree(&outputs);
 // Move to the next sample
  ++iSample;
 flagStep =
   GDSStepSample(
     NMTrainerDataset(that),
     NMTrainerGetICatEval(that));
} while (flagStep);
// Memorize the result of evaluation
avgBias /=
  (float)GDSGetSizeCat(
   NMTrainerDataset(that),
   NMTrainerGetICatEval(that));
VecSet(
 &(that->resEval),
 Ο,
 minBias);
VecSet(
 &(that->resEval),
 avgBias);
VecSet(
 &(that->resEval),
 2,
 maxBias);
```

3.2 neuramorph-inline.c

}

```
static inline
#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->iInputs;
// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->iOutputs;
// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
```

```
}
#endif
  return that->outputs;
// Get the number of input values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbInputs(const NeuraMorphUnit* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return VecGetDim(that->iInputs);
// Get the number of output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbOutputs(const NeuraMorphUnit* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return VecGetDim(that->iOutputs);
}
// Get the number of coefficients in the transfer function of
// the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbCoeffs(const NeuraMorphUnit* that) {
```

```
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return BBodyGetNbCtrl(that->transfer);
}
// Get the value of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
float NMUnitGetValue(const NeuraMorphUnit* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->value;
// Set the value of the NeuraMorphUnit 'that' to 'val'
#if BUILDMODE != 0
static inline
#endif
void NMUnitSetValue(
  NeuraMorphUnit* that,
            float val) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
```

```
#endif
  that->value = val;
// ---- NeuraMorph
// ====== Functions implementation ========
// Get the number of input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbInput(const NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
     NeuraMorphErr->_msg,
     "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
 return that->nbInput;
}
// Get the number of output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbOutput(const NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
     NeuraMorphErr->_msg,
     "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->nbOutput;
}
// Get the input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
```

```
#endif
VecFloat* NMInputs(NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->inputs;
// Get the output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMOutputs(const NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
      NeuraMorphErr->_msg,
    "'that' is null");
PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->outputs;
// Get the hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMHiddens(const NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
```

```
#endif
  return that->hiddens;
// Get the number of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbHidden(const NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
      NeuraMorphErr->_msg,
"'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  long nb = 0;
if (that->hiddens != NULL) {
    nb = VecGetDim(that->hiddens);
 return nb;
}
// Set the number of hidden values of the NeuraMorph 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void NMSetNbHidden(
  NeuraMorph* that,
         long nb) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  if (nb <= 0) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
```

```
NeuraMorphErr->_msg,
      "'nb' is invalid (%ld>0)",
      nb);
   PBErrCatch(NeuraMorphErr);
  }
#endif
  if (that->hiddens != NULL) {
    VecFree(&(that->hiddens));
  that->hiddens = VecFloatCreate(nb);
}
// Get the lowest bound of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMLowHiddens(const NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->lowHiddens;
// Get the highest bound of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMHighHiddens(const NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
```

```
return that->highHiddens;
}
// Get the flag for one hot encoding of the NeuraMorph 'that' \mbox{\tt\#if} BUILDMODE != 0
static inline
#endif
bool NMGetFlagOneHot(const NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->flagOneHot;
// Set the flag for one hot encoding of the NeuraMorph 'that' to 'flag'
#if BUILDMODE != 0
static inline
#endif
void NMSetFlagOneHot(
  NeuraMorph* that,
         bool flag) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
      NeuraMorphErr->_msg,
"'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  that->flagOneHot = flag;
// ---- NeuraMorphTrainer
// ====== Functions implementation =========
// Get the depth of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
```

```
#endif
short NMTrainerGetDepth(const NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->depth;
}
// Set the depth of the NeuraMorphTrainer 'that' to 'depth'
#if BUILDMODE != 0
static inline
#endif
\verb"void NMTrainerSetDepth" (
  NeuraMorphTrainer* that,
               short depth) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
  if (depth < 1) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'depth' is invalid (%d>=1)",
      depth);
    PBErrCatch(NeuraMorphErr);
  }
#endif
  that->depth = depth;
// Get the maxLvlDiv of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
```

```
short NMTrainerGetMaxLvlDiv(const NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
 return that->maxLvlDiv;
// Set the maxLvlDiv of the NeuraMorphTrainer 'that' to 'lvl'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetMaxLvlDiv(
 NeuraMorphTrainer* that,
               short lvl) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
   PBErrCatch(NeuraMorphErr);
  }
  if (lvl < 0) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'lvl' is invalid (%d>=0)",
     lvl);
    PBErrCatch(NeuraMorphErr);
  }
#endif
  that->maxLvlDiv = lvl;
}
// Get the order of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
int NMTrainerGetOrder(const NeuraMorphTrainer* that) {
```

```
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->order;
}
// Set the order of the NeuraMorphTrainer 'that' to 'order'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetOrder(
  NeuraMorphTrainer* that,
                 int order) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  if (order < 1) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
      NeuraMorphErr->_msg,
"'order' is invalid (%d>=1)",
    PBErrCatch(NeuraMorphErr);
  }
#endif
  that->order = order;
// Get the nbMaxInputsUnit of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
int NMTrainerGetNbMaxInputsUnit(const NeuraMorphTrainer* that) {
```

```
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->nbMaxInputsUnit;
// Set the nbMaxInputsUnit of the NeuraMorphTrainer 'that' to 'order'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetNbMaxInputsUnit(
  NeuraMorphTrainer* that,
                 int nbMaxInputsUnit) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
  if (nbMaxInputsUnit < 2) {</pre>
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'nbMaxInputsUnit' is invalid (%d>=2)",
      nbMaxInputsUnit);
    PBErrCatch(NeuraMorphErr);
  }
#endif
  that->nbMaxInputsUnit = nbMaxInputsUnit;
// Get the NeuraMorph of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
NeuraMorph* NMTrainerNeuraMorph(const NeuraMorphTrainer* that) {
#if BUILDMODE == 0
```

```
if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
 return that->neuraMorph;
// Get the GDataSet of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
GDataSetVecFloat* NMTrainerDataset(const NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
 return that->dataset;
// Get the index of the training category of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
unsigned int NMTrainerGetICatTraining(const NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->iCatTraining;
```

```
}
// Set the index of the training category of the NeuraMorphTrainer 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetICatTraining(
  NeuraMorphTrainer* that,
        unsigned int iCatTraining) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  that->iCatTraining = iCatTraining;
}
// Get the index of the evaluation category of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
unsigned int NMTrainerGetICatEval(const NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->iCatEval;
}
// Set the index of the evaluation category of the {\tt NeuraMorphTrainer} 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetICatEval(
  NeuraMorphTrainer* that,
        unsigned int iCatEval) {
```

```
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  that->iCatEval = iCatEval;
}
// Get the weakness threshold of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
{\tt float\ NMTrainerGetWeakThreshold(const\ NeuraMorphTrainer*\ that)\ \{}
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->weakUnitThreshold;
// Set the weakness threshold of the NeuraMorphTrainer 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetWeakThreshold(
  NeuraMorphTrainer* that,
               float weakUnitThreshold) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
```

```
}
#endif
  that->weakUnitThreshold = weakUnitThreshold;
// Get the nbMaxUnitDepth of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
int NMTrainerGetNbMaxUnitDepth(const NeuraMorphTrainer* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
   PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->nbMaxUnitDepth;
// Set the nbMaxUnitDepth of the NeuraMorphTrainer 'that' to 'nbMaxUnitDepth'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetNbMaxUnitDepth(
  NeuraMorphTrainer* that,
                 int nbMaxUnitDepth) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
     NeuraMorphErr->_msg,
      "'that' is null");
   PBErrCatch(NeuraMorphErr);
  }
#endif
  that->nbMaxUnitDepth = nbMaxUnitDepth;
// Get the result of the last evaluation of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
```

```
const VecFloat3D* NMTrainerResEval(const NeuraMorphTrainer* that) {
#if BUILDMODE == 0

if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
         NeuraMorphErr->_msg,
         "'that' is null");
    PBErrCatch(NeuraMorphErr);
}
#endif
return &(that->resEval);
```

4 Makefile

```
# Build mode
# 0: development (max safety, no optimisation)
# 1: release (min safety, optimisation)
# 2: fast and furious (no safety, optimisation)
BUILD_MODE?=0
all: pbmake_wget main
# Automatic installation of the repository PBMake in the parent folder
if [ ! -d ../PBMake ]; then wget https://github.com/BayashiPascal/PBMake/archive/master.zip; unzip master.zip; rm -f
# Makefile definitions
MAKEFILE_INC=../PBMake/Makefile.inc
include $(MAKEFILE_INC)
# Rules to make the executable
repo=neuramorph
$($(repo)_EXENAME): \
$($(repo)_EXENAME).o \
$($(repo)_EXE_DEP) \
$($(repo)_DEP)
$(COMPILER) 'echo "$($(repo)_EXE_DEP) $($(repo)_EXENAME).o" | tr ' ', '\n' | sort -u' $(LINK_ARG) $($(repo)_LINK_ARG)
$($(repo)_EXENAME).o: \
$($(repo)_DIR)/$($(repo)_EXENAME).c \
(\text{repo}_INC_H_EXE) \
$($(repo)_EXE_DEP)
$(COMPILER) $(BUILD_ARG) $($(repo)_BUILD_ARG) 'echo "$($(repo)_INC_DIR)" | tr ', '\n' | sort -u' -c $($(repo)_DIR)/
```

5 Unit tests

```
#include <stdlib.h>
#include <stdio.h>
```

```
#include <time.h>
#include <string.h>
#include <time.h>
#include <unistd.h>
#include <sys/time.h>
#include "neuramorph.h"
void UnitTestNeuraMorphUnitCreateFree() {
  VecLong* iIn = VecLongCreate(3);
  VecSet(
    iIn,
    Ο,
   0);
  VecSet(
   iIn,
    1,
   1);
  VecSet(
   iIn,
    2,
    2);
  VecLong* iOut = VecLongCreate(2);
  VecSet(
    iOut,
    Ο,
    0);
  VecSet(
    iOut,
    1,
    1);
  NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
      iIn,
      iOut);
  bool isSame =
    ISEQUALF(
      unit->value,
      0.0);
  if (
    VecGetDim(unit->outputs) != 2 ||
    VecGetDim(unit->lowFilters) != 3 ||
    VecGetDim(unit->highFilters) != 3 ||
    VecGetDim(unit->unitInputs) != 3 ||
    isSame != true ||
    unit->lowOutputs != NULL ||
    unit->highOutputs != NULL) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphUnitCreate failed (1)");
    PBErrCatch(NeuraMorphErr);
  }
  isSame =
    VecIsEqual(
      unit->iInputs,
      iIn);
  if (isSame == false) {
```

```
NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NeuraMorphUnitCreate failed (2)");
   PBErrCatch(NeuraMorphErr);
 }
 isSame =
   VecIsEqual(
     unit->iOutputs,
     iOut);
 if (isSame == false) {
   NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NeuraMorphUnitCreate failed (3)");
   PBErrCatch(NeuraMorphErr);
 }
 NeuraMorphUnitFree(&unit);
 if (unit != NULL) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
     NeuraMorphErr->_msg,
      "NeuraMorphUnitFree failed");
   PBErrCatch(NeuraMorphErr);
 }
 VecFree(&iIn);
 VecFree(&iOut);
 printf("UnitTestNeuraMorphUnitCreateFree OK\n");
void UnitTestNeuraMorphUnitGetSetPrint() {
 VecLong* iIn = VecLongCreate(3);
 VecLong* iOut = VecLongCreate(2);
 NeuraMorphUnit* unit =
   NeuraMorphUnitCreate(
     iIn,
     iOut);
 if (NMUnitIInputs(unit) != unit->iInputs) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NMUnitIInputs failed");
   PBErrCatch(NeuraMorphErr);
 if (NMUnitIOutputs(unit) != unit->iOutputs) {
   NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
```

```
NeuraMorphErr->_msg,
   "NMUnitIOutputs failed");
 PBErrCatch(NeuraMorphErr);
}
if (NMUnitOutputs(unit) != unit->outputs) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
    "NMUnitOutputs failed");
 PBErrCatch(NeuraMorphErr);
}
if (NMUnitGetNbInputs(unit) != 3) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
 sprintf(
   NeuraMorphErr->_msg,
    "NMUnitGetNbInputs failed");
 PBErrCatch(NeuraMorphErr);
}
if (NMUnitGetNbOutputs(unit) != 2) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
 sprintf(
   NeuraMorphErr->_msg,
    "NMUnitGetNbOutputs failed");
 PBErrCatch(NeuraMorphErr);
bool isSame =
  ISEQUALF(
   NMUnitGetValue(unit),
   0.0);
if (isSame != true) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
   "NMUnitGetValue failed");
 PBErrCatch(NeuraMorphErr);
NMUnitSetValue(
 unit,
 0.5);
isSame =
 ISEQUALF(
   NMUnitGetValue(unit),
   0.5);
if (isSame != true) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
```

```
"NMUnitSetValue failed");
    PBErrCatch(NeuraMorphErr);
  }
  NMUnitPrintln(
    unit,
    stdout);
  NeuraMorphUnitFree(&unit);
  VecFree(&iIn);
  VecFree(&iOut);
  printf("UnitTestNeuraMorphUnitGetSetPrint OK\n");
}
void UnitTestNeuraMorphUnitEvaluate() {
  VecLong* iIn = VecLongCreate(3);
  VecLong* iOut = VecLongCreate(2);
  NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
      iIn,
      iOut);
  for (
    long iInput = 3;
    iInput--;) {
    VecSet(
     unit->lowFilters,
      iInput,
      0.0);
    VecSet(
      unit->highFilters,
      iInput,
      2.0);
  }
  VecShort2D dim = VecShortCreateStatic2D();
  VecSet(
    &dim,
    Ο,
    3);
  VecSet(
    &dim,
   2);
  unit->transfer =
    BBodyCreate(
      1,
     &dim);
  unit->transfer->_ctrl[0]->_val[0] = 1.0;
  unit->transfer->_ctrl[0]->_val[1] = 2.0;
  VecFloat* inputs = VecFloatCreate(3);
  VecSet(
    inputs,
    Ο,
    1.0);
  VecSet(
```

```
inputs,
 1,
 3.0);
VecSet(
 inputs,
 2,
 1.5);
NMUnitEvaluate(
 unit,
  inputs);
float check[2];
check[0] = -0.0625;
check[1] = -0.125;
VecFloat2D checkHigh = VecFloatCreateStatic2D();
VecSet(
 &checkHigh,
 check[0]);
VecSet(
 &checkHigh,
 check[1]);
VecFloat2D checkLow = checkHigh;
for (
 long iOutput = 2;
 iOutput--;) {
 float v =
   VecGet(
     unit->outputs,
     iOutput);
 bool same =
   ISEQUALF(
      check[iOutput]);
  if (same == false) {
   NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
   sprintf(
     NeuraMorphErr->_msg,
      "NMUnitEvaluate failed (1)");
   PBErrCatch(NeuraMorphErr);
 }
}
bool sameLow =
  VecIsEqual(
   &checkLow,
   unit->lowOutputs);
bool sameHigh =
 VecIsEqual(
   &checkHigh,
   unit->highOutputs);
if (
  sameLow == false ||
 sameHigh == false) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
```

```
sprintf(
      NeuraMorphErr->_msg,
      "NMUnitEvaluate failed (2)");
    PBErrCatch(NeuraMorphErr);
  NeuraMorphUnitFree(&unit);
  VecFree(&iIn);
  VecFree(&iOut);
  VecFree(&inputs);
  printf("UnitTestNeuraMorphUnitEvaluate OK\n");
void UnitTestNeuraMorphUnit() {
  UnitTestNeuraMorphUnitCreateFree();
  UnitTestNeuraMorphUnitGetSetPrint();
  UnitTestNeuraMorphUnitEvaluate();
  printf("UnitTestNeuraMorphUnit\ OK\n");\\
}
void UnitTestNeuraMorphCreateFree() {
  NeuraMorph* nm =
    NeuraMorphCreate(
      3,
      2);
  if (
    nm->nbInput != 3 ||
    nm->nbOutput != 2 ||
    nm->flagOneHot != false ||
    VecGetDim(nm->inputs) != 3 ||
    VecGetDim(nm->outputs) != 2 ||
    nm->hiddens != NULL ||
    GSetNbElem(&(nm->units)) != 0) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphCreate failed");
    PBErrCatch(NeuraMorphErr);
  }
  NeuraMorphFree(&nm);
  if (nm != NULL) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphFree failed");
    PBErrCatch(NeuraMorphErr);
  printf("UnitTestNeuraMorphCreateFree OK\n");
}
```

```
void UnitTestNeuraMorphGetSet() {
 NeuraMorph* nm =
   NeuraMorphCreate(
     3,
     2);
 if (NMGetNbInput(nm) != 3) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NMGetNbInput failed");
   PBErrCatch(NeuraMorphErr);
 }
 if (NMGetNbOutput(nm) != 2) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
   sprintf(
     NeuraMorphErr->_msg,
      "NMGetNbOutput failed");
   PBErrCatch(NeuraMorphErr);
 }
 if (NMGetNbHidden(nm) != 0) {
   NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
   sprintf(
     NeuraMorphErr->_msg,
      "NMGetNbHidden failed");
   PBErrCatch(NeuraMorphErr);
 if (NMGetFlagOneHot(nm) != false) {
   NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NMGetFlagOneHot failed");
   PBErrCatch(NeuraMorphErr);
 NMSetNbHidden(
   nm,
   5);
 if (NMGetNbHidden(nm) != 5) {
   NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NMSetNbHidden failed");
   PBErrCatch(NeuraMorphErr);
 }
 NMSetFlagOneHot(
   nm,
   true);
```

```
if (NMGetFlagOneHot(nm) != true) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
 sprintf(
   NeuraMorphErr->_msg,
    "NMSetFlagOneHot failed");
 PBErrCatch(NeuraMorphErr);
VecLong* iOuts = NMGetVecIOutputs(nm);
VecLong2D checkOuts =
  VecLongCreateStatic2D();
VecSet(
 &checkOuts,
 Ο,
 5);
VecSet(
 &checkOuts,
 1,
 6);
bool isSame =
 VecIsEqual(
   &checkOuts,
   iOuts);
if (isSame == false) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
    "NMGetVecIOutputs failed");
 PBErrCatch(NeuraMorphErr);
}
VecFree(&iOuts);
if (NMInputs(nm) != nm->inputs) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
 sprintf(
   NeuraMorphErr->_msg,
    "NMInputs failed");
 PBErrCatch(NeuraMorphErr);
}
if (NMOutputs(nm) != nm->outputs) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
   "NMOutputs failed");
 PBErrCatch(NeuraMorphErr);
}
if (NMHiddens(nm) != nm->hiddens) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
```

```
"NMHiddens failed");
    PBErrCatch(NeuraMorphErr);
  }
  if (NMLowHiddens(nm) != nm->lowHiddens) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMLowHiddens failed");
    PBErrCatch(NeuraMorphErr);
  if (NMHighHiddens(nm) != nm->highHiddens) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
      NeuraMorphErr->_msg,
      "NMHighHiddens failed");
    PBErrCatch(NeuraMorphErr);
  NeuraMorphFree(&nm);
  printf("UnitTestNeuraMorphGetSet OK\n");
}
void UnitTestNeuraMorphAddRemoveUnit() {
  VecLong3D iInputs = VecLongCreateStatic3D();
  VecSet(
    &iInputs,
    Ο,
    0);
  VecSet(
    &iInputs,
    1,
    1);
  VecSet(
    &iInputs,
    2,
  VecLong2D iOutputs = VecLongCreateStatic2D();
  VecSet(
    &iOutputs,
    Ο,
    0);
  VecSet(
    &iOutputs,
    1);
  NeuraMorph* nm =
    {\tt NeuraMorphCreate} (
      2);
  NeuraMorphUnit* unit =
```

```
NMAddUnit(
      nm,
      (VecLong*)&iInputs,
      (VecLong*)&iOutputs);
  bool isSameA =
    VecIsEqual(
      &iInputs,
      unit->iInputs);
  bool isSameB =
    VecIsEqual(
      \&iOutputs,
      unit->iOutputs);
  if (
    GSetNbElem(&(nm->units)) != 1 ||
    GSetHead(&(nm->units)) != unit ||
    isSameA == false ||
    isSameB == false) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMAddUnit failed");
    PBErrCatch(NeuraMorphErr);
  NeuraMorphFree(&nm);
    NeuraMorphCreate(
      3,
      2);
  unit =
    NMAddUnit(
      nm,
      (VecLong*)&iInputs,
      (VecLong*)&iOutputs);
  NMRemoveUnit(
    nm,
    unit);
  if (GSetNbElem(&(nm->units)) != 0) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMRemoveUnit failed");
    PBErrCatch(NeuraMorphErr);
  }
  NeuraMorphUnitFree(&unit);
  NeuraMorphFree(&nm);
  \verb|printf("UnitTestNeuraMorphAddRemoveUnit OK\n");|\\
void UnitTestNeuraMorphBurryUnitsEvaluate() {
```

}

```
VecLong3D iInputs = VecLongCreateStatic3D();
VecSet(
  &iInputs,
  Ο,
 0);
VecSet(
  &iInputs,
  1,
  1);
VecSet(
  &iInputs,
  2,
  2);
VecLong2D iOutputs = VecLongCreateStatic2D();
VecSet(
  &iOutputs,
  Ο,
  0);
VecSet(
  &iOutputs,
  1,
  1);
NeuraMorph* nm =
  {\tt NeuraMorphCreate(}
    2);
NeuraMorphUnit* unitA =
  NeuraMorphUnitCreate(
    (VecLong*)&iInputs,
    (VecLong*)&iOutputs);
NeuraMorphUnit* unitB =
  NeuraMorphUnitCreate(
    (VecLong*)&iInputs,
    (VecLong*)&iOutputs);
for (
 long iInput = 3;
iInput--;) {
  VecSet(
    unitA->lowFilters,
    iInput,
   0.0);
  VecSet(
    unitA->highFilters,
    iInput,
    2.0);
  VecSet(
    unitB->lowFilters,
    iInput,
    0.0);
  VecSet(
    unitB->highFilters,
   iInput,
    2.0);
}
```

```
VecShort2D dim = VecShortCreateStatic2D();
VecSet(
  &dim,
  Ο,
  3);
VecSet(
  &dim,
  1,
 2);
unitA->transfer =
  BBodyCreate(
    1,
    &dim);
unitA->transfer->_ctrl[0]->_val[0] = 1.0;
unitA->transfer->_ctrl[0]->_val[1] = 2.0;
unitB->transfer =
 BBodyCreate(
    1,
    &dim);
unitB->transfer->_ctrl[0]->_val[0] = 2.0;
unitB->transfer->_ctrl[0]->_val[1] = 1.0;
float x = 1.0;
float y = 0.5;
float z = 1.5;
VecFloat* evalInputs = VecFloatCreate(3);
VecSet(
  evalInputs,
  Ο,
 x);
VecSet(
  evalInputs,
  1,
 у);
VecSet(
  evalInputs,
  2,
 z);
{\tt NMUnitEvaluate(}
  unitA,
  evalInputs);
NMUnitEvaluate(
 unitB,
  evalInputs);
GSet units = GSetCreateStatic();
GSetAppend(
  &units,
  unitA);
GSetAppend(
  &units,
  unitB);
{\tt NMBurryUnits(}
  nm,
  &units);
if (
  GSetNbElem(&units) != 0 ||
  nm->hiddens == NULL ||
  VecGetDim(nm->hiddens) != 4) {
```

```
NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
    "NMBurryUnits failed (1)");
 PBErrCatch(NeuraMorphErr);
}
VecLong2D checkA = VecLongCreateStatic2D();
 &checkA,
 Ο,
 0);
VecSet(
 &checkA,
 1,
 1);
VecLong2D checkB = VecLongCreateStatic2D();
VecSet(
 &checkB,
 Ο,
 2);
VecSet(
 &checkB,
 3);
bool isSameA =
 VecIsEqual(
   &checkA,
   unitA->iOutputs);
bool isSameB =
 VecIsEqual(
   &checkB,
   unitB->iOutputs);
if (
  isSameA == false ||
 isSameB == false) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
 sprintf(
   NeuraMorphErr->_msg,
    "NMBurryUnits failed (2)");
 PBErrCatch(NeuraMorphErr);
}
float checkLowAa =
 VecGet(
   unitA->lowOutputs,
   0);
checkLowAa -=
  VecGet(
   nm->lowHiddens,
   0);
bool isSameLowAa =
 ISEQUALF(
    checkLowAa,
   0.0);
float checkLowAb =
 VecGet(
```

```
unitA->lowOutputs,
   1);
checkLowAb -=
 VecGet(
   nm->lowHiddens,
   1);
bool isSameLowAb =
 ISEQUALF(
   checkLowAb,
   0.0);
float checkLowBa =
 VecGet(
   unitB->lowOutputs,
   0);
checkLowBa -=
 VecGet(
   nm->lowHiddens,
   2);
bool isSameLowBa =
 ISEQUALF(
   checkLowBa,
   0.0);
float checkLowBb =
 VecGet(
   unitB->lowOutputs,
   1);
checkLowBb -=
 VecGet(
   nm->lowHiddens,
   3);
bool isSameLowBb =
 ISEQUALF(
   checkLowBb,
   0.0);
float checkHighAa =
 VecGet(
   unitA->lowOutputs,
   0);
checkHighAa -=
 VecGet(
   nm->lowHiddens,
   0);
bool isSameHighAa =
 ISEQUALF(
   checkHighAa,
   0.0);
float checkHighAb =
 VecGet(
   unitA->lowOutputs,
   1);
checkHighAb -=
 VecGet(
   nm->lowHiddens,
   1);
bool isSameHighAb =
 ISEQUALF(
   checkHighAb,
   0.0);
float checkHighBa =
 VecGet(
   unitB->lowOutputs,
   0);
```

```
checkHighBa -=
  VecGet(
    nm->lowHiddens,
    2);
bool isSameHighBa =
  ISEQUALF(
    checkHighBa,
    0.0);
float checkHighBb =
  VecGet(
    unitB->lowOutputs,
    1);
checkHighBb -=
  VecGet(
    nm->lowHiddens,
    3);
bool isSameHighBb =
  ISEQUALF(
    checkHighBb,
    0.0);
if (
  isSameLowAa == false ||
  isSameLowAb == false ||
  isSameLowBa == false ||
  isSameLowBb == false ||
  isSameHighAa == false ||
  isSameHighAb == false ||
 isSameHighBa == false ||
isSameHighBb == false) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
    NeuraMorphErr->_msg,
"NMBurryUnits failed (3)");
  PBErrCatch(NeuraMorphErr);
}
VecSet(
  &iInputs,
  Ο,
  3);
VecSet(
  &iInputs,
  1,
  4);
VecSet(
  &iInputs,
  2,
  5);
VecSet(
  &iOutputs,
 Ο,
  4);
VecSet(
  &iOutputs,
  1,
  5);
NeuraMorphUnit* unitC =
  NMAddUnit(
    nm,
    (VecLong*)&iInputs,
```

```
(VecLong*)&iOutputs);
for (
 long iInput = 3;
 iInput--;) {
 VecSet(
   unitC->lowFilters,
   iInput,
   0.0);
 VecSet(
   unitC->highFilters,
   iInput,
   20.0);
}
unitC->transfer =
 BBodyCreate(
   1,
   &dim);
unitC->transfer->_ctrl[0]->_val[0] = -1.0;
unitC->transfer->_ctrl[0]->_val[1] = -2.0;
NMEvaluate(
 evalInputs);
float checkAout[2];
checkAout[0] =
 0.09375 -
 VecGet(
   nm->hiddens,
   0);
checkAout[1] =
 0.1875 -
 VecGet(
   nm->hiddens,
   1);
float checkBout[2];
checkBout[0] =
 0.1875 -
 VecGet(
   nm->hiddens,
   2);
checkBout[1] =
 0.09375 -
 VecGet(
   nm->hiddens,
   3);
bool isSameAa =
 ISEQUALF(
   checkAout[0],
   0.0);
bool isSameAb =
 ISEQUALF(
   checkAout[1],
   0.0);
bool isSameBa =
 ISEQUALF(
   checkBout[0],
   0.0);
```

```
bool isSameBb =
 ISEQUALF(
    checkBout[1],
   0.0);
if (
  isSameAa == false ||
 isSameAb == false ||
 isSameBa == false ||
 isSameBb == false) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
 sprintf(
   NeuraMorphErr->_msg,
   "NMEvaluate failed (1)");
 PBErrCatch(NeuraMorphErr);
  VecGet(
   nm->hiddens,
   0);
 VecGet(
   nm->hiddens,
   1);
 VecGet(
   nm->hiddens,
   2);
float checkCout[2];
checkCout[0] =
 -0.976738 -
 VecGet(
   unitC->outputs,
   0);
checkCout[1] =
  -1.953476 -
  VecGet(
   unitC->outputs,
   1);
bool isSameCa =
 ISEQUALF(
   checkCout[0],
   0.0);
bool isSameCb =
 ISEQUALF(
   checkCout[1],
   0.0);
bool isSameCc =
 VecIsEqual(
   unitC->outputs,
   nm->outputs);
if (
 isSameCa == false ||
 isSameCb == false ||
 isSameCc == false) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
 sprintf(
   NeuraMorphErr->_msg,
```

```
"NMEvaluate failed (2)");
    PBErrCatch(NeuraMorphErr);
  }
  VecFree(&evalInputs);
  NeuraMorphFree(&nm);
  printf("UnitTestNeuraMorphBurryUnitsEvaluate OK\n");
}
void UnitTestNeuraMorph() {
  UnitTestNeuraMorphCreateFree();
  UnitTestNeuraMorphGetSet();
  UnitTestNeuraMorphAddRemoveUnit();
  UnitTestNeuraMorphBurryUnitsEvaluate();
  printf("UnitTestNeuraMorph OK\n");
}
void UnitTestNeuraMorphTrainerCreateFree() {
  GDataSetVecFloat dataset =
    GDataSetVecFloatCreateStaticFromFile("./Datasets/iris.json");
  NeuraMorph* nm =
    NeuraMorphCreate(
      GDSGetNbInputs(&dataset),
      GDSGetNbOutputs(&dataset));
  NeuraMorphTrainer trainer =
    NeuraMorphTrainerCreateStatic(
      nm,
      &dataset);
  bool isSame
    ISEQUALF(
      trainer.weakUnitThreshold,
  if (
    trainer.neuraMorph != nm ||
    trainer.depth != 2 ||
    trainer.order != 1 ||
    trainer.nbMaxUnitDepth != 2 ||
    trainer.maxLvlDiv != 2 ||
    trainer.nbMaxInputsUnit != GDSGetNbOutputs(&dataset) ||
    isSame != true ||
    trainer.iCatTraining != 0 ||
    trainer.iCatEval != 1 ||
    trainer.dataset != &dataset) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphTrainerCreateStatic failed");
    PBErrCatch(NeuraMorphErr);
  NeuraMorphTrainerFreeStatic(&trainer);
  NeuraMorphFree(&nm);
  GDataSetVecFloatFreeStatic(&dataset);
```

```
printf("UnitTestNeuraMorphTrainerCreateFree OK\n");
}
void UnitTestNeuraMorphTrainerGetSet() {
 GDataSetVecFloat dataset =
    GDataSetVecFloatCreateStaticFromFile("./Datasets/iris.json");
 NeuraMorph* nm =
   NeuraMorphCreate(
     GDSGetNbInputs(&dataset),
     GDSGetNbOutputs(&dataset));
 NeuraMorphTrainer trainer =
    NeuraMorphTrainerCreateStatic(
     nm,
     &dataset);
  if (NMTrainerGetDepth(&trainer) != 2) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NeuraMorphTrainerGetDepth failed");
   PBErrCatch(NeuraMorphErr);
 }
  if (NMTrainerGetOrder(&trainer) != 1) {
   NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NeuraMorphTrainerGetOrder failed");
   PBErrCatch(NeuraMorphErr);
 if (NMTrainerGetNbMaxUnitDepth(&trainer) != 2) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NeuraMorphTrainerGetNbMaxUnitDepth failed");
   PBErrCatch(NeuraMorphErr);
 if (NMTrainerGetMaxLvlDiv(&trainer) != 2) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphTrainerGetMaxLvlDiv failed");
   PBErrCatch(NeuraMorphErr);
 }
  if (NMTrainerGetNbMaxInputsUnit(&trainer) != GDSGetNbOutputs(&dataset)) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NeuraMorphTrainerGetNbMaxInputsUnit failed");
```

```
PBErrCatch(NeuraMorphErr);
}
if (NMTrainerGetICatTraining(&trainer) != 0) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
    "NeuraMorphTrainerGetICatTraining failed");
 PBErrCatch(NeuraMorphErr);
}
if (NMTrainerGetICatEval(&trainer) != 1) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
    NeuraMorphErr->_msg,
    "NeuraMorphTrainerGetICatEval failed");
 PBErrCatch(NeuraMorphErr);
}
bool isSame =
  ISEQUALF(
   NMTrainerGetWeakThreshold(&trainer),
   0.9);
if (isSame != true) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
    "NeuraMorphTrainerGetWeakThreshold failed");
 PBErrCatch(NeuraMorphErr);
}
NMTrainerSetDepth(
  &trainer,
if (NMTrainerGetDepth(&trainer) != 3) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
    "NeuraMorphTrainerSetDepth failed");
 PBErrCatch(NeuraMorphErr);
NMTrainerSetNbMaxUnitDepth(
 &trainer,
if (NMTrainerGetNbMaxUnitDepth(&trainer) != 3) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
 sprintf(
   NeuraMorphErr->_msg,
    "NeuraMorphTrainerSetNbMaxUnitDepth failed");
 PBErrCatch(NeuraMorphErr);
```

```
NMTrainerSetOrder(
 &trainer,
if (NMTrainerGetOrder(&trainer) != 3) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
    "NeuraMorphTrainerSetOrder failed");
 PBErrCatch(NeuraMorphErr);
NMTrainerSetNbMaxInputsUnit(
 &trainer,
  GDSGetNbOutputs(&dataset) + 1);
if (NMTrainerGetNbMaxInputsUnit(&trainer) != GDSGetNbOutputs(&dataset) + 1) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
    "NeuraMorphTrainerSetNbMaxInputsUnit failed");
 PBErrCatch(NeuraMorphErr);
}
NMTrainerSetICatTraining(
 &trainer,
if (NMTrainerGetICatTraining(&trainer) != 3) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
   NeuraMorphErr->_msg,
    "NeuraMorphTrainerSetICatTraining failed");
  PBErrCatch(NeuraMorphErr);
NMTrainerSetICatEval(
  &trainer,
 4);
if (NMTrainerGetICatEval(&trainer) != 4) {
 NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
    "NeuraMorphTrainerSetICatEval failed");
 PBErrCatch(NeuraMorphErr);
}
NMTrainerSetMaxLvlDiv(
 &trainer,
if (NMTrainerGetMaxLvlDiv(&trainer) != 3) {
  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
   NeuraMorphErr->_msg,
```

```
"NeuraMorphTrainerSetMaxLvlDiv failed");
    PBErrCatch(NeuraMorphErr);
  }
  NMTrainerSetWeakThreshold(
    &trainer,
    0.5);
  isSame =
    ISEQUALF(
      NMTrainerGetWeakThreshold(&trainer),
      0.5);
  if (isSame != true) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphTrainerSetWeakThreshold failed");
    PBErrCatch(NeuraMorphErr);
  }
  NeuraMorphTrainerFreeStatic(&trainer);
  NeuraMorphFree(&nm);
  GDataSetVecFloatFreeStatic(&dataset);
  printf("UnitTestNeuraMorphTrainerGetSet OK\n");
}
void UnitTestNeuraMorphTrainerRun() {
  GDataSetVecFloat dataset =
    GDataSetVecFloatCreateStaticFromFile("./Datasets/iris.json");
  GDSShuffle(&dataset);
  VecShort2D split = VecShortCreateStatic2D();
  VecSet(
    &split,
    Ο,
    130);
  VecSet(
    &split,
    1,
    20);
  GDSSplit(
    &dataset,
    (VecShort*)&split);
  NeuraMorph* nm =
    NeuraMorphCreate(
      GDSGetNbInputs(&dataset),
      GDSGetNbOutputs(&dataset));
  {\tt NMSetFlagOneHot}(
    nm,
    true);
  NeuraMorphTrainer trainer =
    NeuraMorphTrainerCreateStatic(
      nm,
      &dataset);
  NMTrainerSetWeakThreshold(
    &trainer,
```

```
0.99);
  {\tt NMTrainerSetDepth(}
    &trainer,
    3);
  NMTrainerSetMaxLvlDiv(
    &trainer,
    1);
  NMTrainerSetNbMaxInputsUnit(
    &trainer,
    GDSGetNbInputs(&dataset));
  NMTrainerSetOrder(
    &trainer,
    1);
  NMTrainerRun(&trainer);
  NMTrainerEval(&trainer);
  printf("Bias (min/avg/max): ");
  VecPrint(
    NMTrainerResEval(&trainer),
    stdout);
  printf("\n");
  NeuraMorphTrainerFreeStatic(&trainer);
  NeuraMorphFree(&nm);
  GDataSetVecFloatFreeStatic(&dataset);
  printf("UnitTestNeuraMorphTrainerRun\ OK\n");\\
}
void UnitTestNeuraMorphTrainer() {
  UnitTestNeuraMorphTrainerCreateFree();
  UnitTestNeuraMorphTrainerGetSet();
  UnitTestNeuraMorphTrainerRun();
  printf("UnitTestNeuraMorphTrainer OK\n");
}
void UnitTestAll() {
  UnitTestNeuraMorphUnit();
  UnitTestNeuraMorph();
  UnitTestNeuraMorphTrainer();
  printf("UnitTestAll OK\n");
}
int main() {
  UnitTestAll();
  // Return success code
  return 0;
}
```

6 Unit tests output

UnitTestNeuraMorphUnitCreateFree OK

```
<0,0,0> -> <0,0> (0.500000)
UnitTestNeuraMorphUnitGetSetPrint OK
UnitTestNeuraMorphUnitEvaluate OK
UnitTestNeuraMorphUnit OK
UnitTestNeuraMorphCreateFree OK
UnitTestNeuraMorphGetSet OK
UnitTestNeuraMorphAddRemoveUnit OK
UnitTestNeuraMorphBurryUnitsEvaluate OK
UnitTestNeuraMorph OK
UnitTestNeuraMorphTrainerCreateFree OK
UnitTestNeuraMorphTrainerGetSet OK
Depth 1/3...
Nb available inputs: 4
Train units with 0001 input(s)
Train units with 0002 input(s)
Train units with 0003 input(s)
Train units with 0004 input(s)
Burry 1 out of 15 unit(s)
<0,1,2,3> -> <0,1,2> (-3.347140)
Depth 2/3...
Nb available inputs: 7
Train units with 0001 input(s)
Train units with 0002 input(s)
Train units with 0003 input(s)
Train units with 0004 input(s)
Burry 1 out of 78 unit(s)
<2,3,5,6> -> <3,4,5> (-2.053272)
Depth 3/3...
Nb available inputs: 10
Train units with 0001 input(s)
Train units with 0002 input(s)
Train units with 0003 input(s)
Train units with 0004 input(s)
Add the last unit
<4,6,8,9> -> <6,7,8> (-1.552779)
00 < 4.900, 2.500, 4.500, 1.700 > > < -1.000, -1.000, 1.000 > : < -1.000, -1.000, 1.000 > 0.000000
01 <5.100,3.800,1.600,0.200> -> <1.000,-1.000,-1.000> : <1.000,-1.000,-1.000> 0.000000
02 <5.400,3.000,4.500,1.500> -> <-1.000,1.000,-1.000> : <-1.000,1.000,-1.000> 0.000000
03 <4.900,3.100,1.500,0.200> -> <1.000,-1.000> : <1.000,-1.000> 0.000000
04 < 7.000, 3.200, 4.700, 1.400 > -> < -1.000, 1.000, -1.000 > : < -1.000, 1.000, -1.000 > 0.000000
05 <5.000,2.300,3.300,1.000> -> <-1.000,1.000,-1.000> : <-1.000,1.000,-1.000> 0.000000
06 < 6.400, 2.900, 4.300, 1.300 > - < -1.000, 1.000, -1.000 > : < -1.000, 1.000, -1.000 > 0.000000
07 <7.700,3.800,6.700,2.200> -> <-1.000,-1.000,1.000> : <-1.000,-1.000,1.000> 0.000000
08 <6.000,2.700,5.100,1.600> -> <-1.000,1.000,-1.000> : <-1.000,-1.000,1.000> 2.828427
09 < 7.100, 3.000, 5.900, 2.100 > -> < -1.000, -1.000, 1.000 > : < -1.000, -1.000, 1.000 > 0.000000
10 <6.400,2.800,5.600,2.100> -> <-1.000,-1.000,1.000> : <-1.000,-1.000,1.000> 0.000000
11 <5.800,4.000,1.200,0.200> -> <1.000,-1.000,-1.000> : <1.000,-1.000,-1.000> 0.000000
12 <5.800,2.700,5.100,1.900> -> <-1.000,-1.000,1.000> : <-1.000,-1.000,1.000> 0.000000
13 <5.300,3.700,1.500,0.200> -> <1.000,-1.000,-1.000> : <1.000,-1.000,-1.000> 0.000000
14 <5.600,2.500,3.900,1.100> -> <-1.000,1.000,-1.000> : <-1.000,1.000,-1.000> 0.000000
15 <6.300,2.500,5.000,1.900> -> <-1.000,-1.000,1.000> : <-1.000,-1.000,1.000> 0.000000
16 <5.100,3.500,1.400,0.300> -> <1.000,-1.000,-1.000> : <1.000,-1.000,-1.000> 0.000000
17 <4.800,3.000,1.400,0.300> -> <1.000,-1.000,-1.000> : <1.000,-1.000,-1.000> 0.000000
18 <5.400,3.700,1.500,0.200> -> <1.000,-1.000,-1.000> : <1.000,-1.000,-1.000> 0.000000
19 <6.300,2.700,4.900,1.800> -> <-1.000,-1.000,1.000> : <-1.000,-1.000,1.000> 0.000000
Bias (min/avg/max): <0.000,0.141,2.828>
UnitTestNeuraMorphTrainerRun OK
UnitTestNeuraMorphTrainer OK
UnitTestAll OK
```