NeuraMorph

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Introduction

NeuraMorph is a C library providing structures and functions to implement a neural network.

It uses the `PBErr`, `PBMath`, `GSet` library.

1 Definitions

2 Interface

```
// ============ NEURAMORPH.H ================
```

```
#ifndef NEURAMORPH_H
#define NEURAMORPH_H

// ================= Include =================

#include <stdlib.h>
#include <stdio.h>
#include <math.h>
#include <string.h>
#include <stdbool.h>
#include "pberr.h"
#include "pbmath.h"
#include "gset.h"

// ----- NeuraMorphUnit

// ================= Data structure ===================

typedef struct NeuraMorphUnit {

  // Input indices in parent NeuraMorph
  VecLong* iInputs;

  // Output indices in parent NeuraMorph
  VecLong* iOutputs;

  // Lowest and highest values for filtering inputs
  VecFloat* lowFilters;
  VecFloat* highFilters;

  // Vector to memorize the output values
  VecFloat* outputs;

  // Transfer function coefficients
  // Seen as (nb output) triangular matrices of size (nb input + 1)
  VecFloat** coeffs;

  // Working variables to avoid reallocation of memory at each Evaluate()
  bool* activeInputs;
  VecFloat* scaledInputs;

} NeuraMorphUnit;

// ================ Functions declaration ====================

// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
  const VecLong* iInputs,
  const VecLong* iOutputs);

// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that);

// Get the input indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that);

// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
```

```
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that);

// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that);

// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
  NeuraMorphUnit* that,
  const VecFloat* inputs);

// ================ static inliner ====================

#if BUILDMODE != 0
#include "neuramorph-inline.c"
#endif

#endif
```

3 Code

3.1 neuramorph.c

```
// ============ NEURAMORPH.C ================

// ================= Include =================

#include "neuramorph.h"
#if BUILDMODE == 0
#include "neuramorph-inline.c"
#endif

// ----- NeuraMorphUnit

// ================ Functions declaration ====================

// Return the number of coefficients of a NeuraMorphUnit having 'nbIn' inputs
long NMUnitGetNBCoeff(long nbIn);

// Get the coefficient for the pair of inputs 'iInputA', 'iInputB' in the
// NeuraMorphUnit 'that' for the output 'iOutput'
float NMUnitGetCoeff(
  const NeuraMorphUnit* that,
                  long iInputA,
                  long iInputB,
                  long iOutput);

// ================ Functions implementation ====================

// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
  const VecLong* iInputs,
```

```
  const VecLong* iOutputs) {

#if BUILDMODE == 0

  if (iInputs == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputs' is null");
    PBErrCatch(NeuraMorphErr);

  }

  if (iOutputs == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'iOutputs' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Allocate memory for the NeuraMorphUnit
  NeuraMorphUnit* that =
    PBErrMalloc(
      NeuraMorphErr,
      sizeof(NeuraMorphUnit));

  // Get the number of inputs (including the constant) and outputs
  long nbIn = VecGetDim(iInputs) + 1;
  long nbOut = VecGetDim(iOutputs);

  // Init properties
  that->iInputs = VecClone(iInputs);
  that->iOutputs = VecClone(iOutputs);
  that->lowFilters = VecFloatCreate(nbIn);
  that->highFilters = VecFloatCreate(nbIn);
  that->outputs = VecFloatCreate(nbOut);
  that->coeffs =
    PBErrMalloc(
      NeuraMorphErr,
      sizeof(VecFloat*) * nbOut);
  long nbCoeff = NMUnitGetNBCoeff(nbIn);
  for (
    long iOut = nbOut;
    iOut--;
    that->coeffs[iOut] = VecFloatCreate(nbCoeff));

  // 'nbIn + 1' for the constant
  that->activeInputs =
    PBErrMalloc(
      NeuraMorphErr,
      sizeof(bool) * nbIn);
  that->scaledInputs = VecFloatCreate(nbIn);

  // Set the input value, filters and active flag for the constant
  VecSet(
    that->scaledInputs,
```

```
    0,
    1.0);
  that->activeInputs[0] = true;

  // Return the new NeuraMorphUnit
  return that;

}

// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that) {

  // Check the input
  if (that == NULL || *that == NULL) {

    return;

  }

  // Free memory
  long nbOut = VecGetDim((*that)->iOutputs);
  VecFree(&((*that)->iInputs));
  VecFree(&((*that)->iOutputs));
  VecFree(&((*that)->lowFilters));
  VecFree(&((*that)->highFilters));
  VecFree(&((*that)->outputs));
  for (
    long iOut = nbOut;
    iOut--;
    VecFree((*that)->coeffs + iOut));
  free((*that)->coeffs);
  free((*that)->activeInputs);
  VecFree(&((*that)->scaledInputs));
  free(*that);
  *that = NULL;

}

// Return the number of coefficients of a NeuraMorphUnit having 'nbIn' inputs
long NMUnitGetNBCoeff(long nbIn) {

#if BUILDMODE == 0

  if (nbIn <= 0) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'nbIn' is invalid (%ld>0)",
      nbIn);
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Declare a variable to memorise the result
  long nb = 0;

  // Calculate the number of values in the triangular matrix of size
  // nbIn
  for (
```

```
    long i = nbIn;
    i >= 0;
    nb += (i--));

  // Return the result
  return nb;

}

// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
  NeuraMorphUnit* that,
  const VecFloat* inputs) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

  if (VecGetDim(inputs) != VecGetDim(that->iInputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'inputs' has invalid dimension (%ld!=%ld)",
      VecGetDim(inputs),
      VecGetDim(that->iInputs));
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Reset the outputs
  VecSetNull(that->outputs);

  // Update the active flags  and scaled inputs (skip the constant)
  for (
    long iInput = 1;
    iInput < VecGetDim(that->scaledInputs);
    ++iInput) {

    // Get the input value and its low/high filters
    float val =
      VecGet(
        inputs,
        iInput - 1);
    float low =
      VecGet(
        that->lowFilters,
        iInput);
    float high =
      VecGet(
        that->highFilters,
```

```
      iInput);

  // If the value is inside the filter
  if (
    low <= val &&
    val <= high &&
    (high - low) > PBMATH_EPSILON) {

    // Set this value as active
    that->activeInputs[iInput] = true;

    // Scale the value according to the filter
    float scaled = 2.0 * (val - low) / (high - low) - 1.0;
    VecSet(
      that->scaledInputs,
      iInput,
      scaled);

  // Else the value is outside the filter
  } else {

    // Set this value as inactive
    that->activeInputs[iInput] = false;

  }

}

// Loop on the pair of active inputs
for (
  long iInputA = 0;
  iInputA < VecGetDim(that->scaledInputs);
  ++iInputA) {

  if (that->activeInputs[iInputA] == true) {

    for (
      long iInputB = 0;
      iInputB <= iInputA;
      ++iInputB) {

      if (that->activeInputs[iInputB] == true) {

        // Loop on the outputs
        for (
          long iOutput = 0;
          iOutput < VecGetDim(that->outputs);
          ++iOutput) {

          // Calculate the components for this output and pair of inputs
          float comp =
            VecGet(
              that->scaledInputs,
              iInputA) *
            VecGet(
              that->scaledInputs,
              iInputB) *
            NMUnitGetCoeff(
              that,
              iInputA,
              iInputB,
              iOutput);
```

```
            // Add the component to the output
            float cur =
              VecGet(
                that->outputs,
                iOutput);
            VecSet(
              that->outputs,
              iOutput,
              cur + comp);

          }

        }

      }

    }

  }

}

// Get the coefficient for the pair of inputs 'iInputA', 'iInputB' in the
// NeuraMorphUnit 'that' for the output 'iOutput'
float NMUnitGetCoeff(
  const NeuraMorphUnit* that,
                  long iInputA,
                  long iInputB,
                  long iOutput) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

  if (
    iInputA < 0 ||
    iInputA >= VecGetDim(that->scaledInputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputA' is invalid (0<=%ld<%ld)",
      iInputA,
      VecGetDim(that->scaledInputs));
    PBErrCatch(NeuraMorphErr);

  }

  if (
    iInputB < 0 ||
    iInputB >= VecGetDim(that->scaledInputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
```

```
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputB' is invalid (0<=%ld<%ld)",
      iInputB,
      VecGetDim(that->scaledInputs));
    PBErrCatch(NeuraMorphErr);

  }

  if (iInputA < iInputB) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "The pair of indices is invalid (%ld>=%ld)",
      iInputA,
      iInputB);
    PBErrCatch(NeuraMorphErr);

  }

  if (
    iOutput < 0 ||
    iOutput >= VecGetDim(that->outputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputB' is invalid (0<=%ld<%ld)",
      iInputB,
      VecGetDim(that->outputs));
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Calculate the index of the coefficient
  long iCoeff = 0;
  for (
    long shift = 0;
    shift < iInputA;
    iCoeff += (shift++) + 1);
  iCoeff += iInputB;

  // Return the coefficient
  float coeff =
    VecGet(
      that->coeffs[iOutput],
      iCoeff);
  return coeff;

}
```

3.2 neuramorph-inline.c

```
// ============ NEURAMORPH-INLINE.C ================

// ----- NeuraMorphUnit
```

```
// ================ Functions implementation ====================

// Get the input indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  return that->iInputs;

}

// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  return that->iOutputs;

}

// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
```

```
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  return that->outputs;

}
```

4 Makefile

```
# Build mode
# 0: development (max safety, no optimisation)
# 1: release (min safety, optimisation)
# 2: fast and furious (no safety, optimisation)
BUILD_MODE?=0

all: pbmake_wget main

# Automatic installation of the repository PBMake in the parent folder
pbmake_wget:
if [ ! -d ../PBMake ]; then wget https://github.com/BayashiPascal/PBMake/archive/master.zip; unzip master.zip; rm -f

# Makefile definitions
MAKEFILE_INC=../PBMake/Makefile.inc
include $(MAKEFILE_INC)

# Rules to make the executable
repo=neuramorph
$($(repo)_EXENAME): \
$($(repo)_EXENAME).o \
$($(repo)_EXE_DEP) \
$($(repo)_DEP)
$(COMPILER) `echo "$($(repo)_EXE_DEP) $($(repo)_EXENAME).o" | tr ' ' '\n' | sort -u` $(LINK_ARG) $($(repo)_LINK_ARG)

$($(repo)_EXENAME).o: \
$($(repo)_DIR)/$($(repo)_EXENAME).c \
$($(repo)_INC_H_EXE) \
$($(repo)_EXE_DEP)
$(COMPILER) $(BUILD_ARG) $($(repo)_BUILD_ARG) `echo "$($(repo)_INC_DIR)" | tr ' ' '\n' | sort -u` -c $($(repo)_DIR)/$
```

5 Unit tests

```
#include <stdlib.h>
#include <stdio.h>
#include <time.h>
#include <string.h>
#include <time.h>
#include <unistd.h>
#include <sys/time.h>
#include "neuramorph.h"

void UnitTestNeuraMorphUnitCreateFree() {
```

```
VecLong* iIn = VecLongCreate(3);
VecSet(
  iIn,
  0,
  0);
VecSet(
  iIn,
  1,
  1);
VecSet(
  iIn,
  2,
  2);
VecLong* iOut = VecLongCreate(2);
VecSet(
  iOut,
  0,
  0);
VecSet(
  iOut,
  1,
  1);
NeuraMorphUnit* unit =
  NeuraMorphUnitCreate(
    iIn,
    iOut);
if (
  VecGetDim(unit->coeffs[0]) != 10 ||
  VecGetDim(unit->outputs) != 2 ||
  VecGetDim(unit->lowFilters) != 4 ||
  VecGetDim(unit->highFilters) != 4 ||
  VecGetDim(unit->scaledInputs) != 4) {

  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
    NeuraMorphErr->_msg,
    "NeuraMorphUnitCreate failed (1)");
  PBErrCatch(NeuraMorphErr);

}

bool isSame =
  VecIsEqual(
    unit->iInputs,
    iIn);
if (isSame == false) {

  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
    NeuraMorphErr->_msg,
    "NeuraMorphUnitCreate failed (2)");
  PBErrCatch(NeuraMorphErr);

}

isSame =
  VecIsEqual(
    unit->iOutputs,
    iOut);
if (isSame == false) {
```

```
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphUnitCreate failed (3)");
    PBErrCatch(NeuraMorphErr);

  }

  NeuraMorphUnitFree(&unit);
  if (unit != NULL) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphUnitFree failed");
    PBErrCatch(NeuraMorphErr);

  }

  VecFree(&iIn);
  VecFree(&iOut);
  printf("UnitTestNeuraMorphUnitCreateFree OK\n");

}

void UnitTestNeuraMorphUnitGetSet() {

  VecLong* iIn = VecLongCreate(3);
  VecLong* iOut = VecLongCreate(2);
  NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
      iIn,
      iOut);

  if (NMUnitIInputs(unit) != unit->iInputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMUnitIInputs failed");
    PBErrCatch(NeuraMorphErr);

  }

  if (NMUnitIOutputs(unit) != unit->iOutputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMUnitIOutputs failed");
    PBErrCatch(NeuraMorphErr);

  }

  if (NMUnitOutputs(unit) != unit->outputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMUnitOutputs failed");
    PBErrCatch(NeuraMorphErr);
```

```
  }

  NeuraMorphUnitFree(&unit);
  VecFree(&iIn);
  VecFree(&iOut);
  printf("UnitTestNeuraMorphUnitGetSet OK\n");

}

void UnitTestNeuraMorphUnitEvaluate() {

  VecLong* iIn = VecLongCreate(3);
  VecLong* iOut = VecLongCreate(2);
  NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
      iIn,
      iOut);

  for (
    long iInput = 3;
    iInput--;) {

    VecSet(
      unit->lowFilters,
      iInput + 1,
      0.0);
    VecSet(
      unit->highFilters,
      iInput + 1,
      2.0);

  }

  // iOutput == 0 -> 1.0+x+y+z+x^2+xy+xz+y^2+yz+z^2
  // iOutput == 1 -> x^2-xy+2xz+3y^2-4yz+5z^2
  float coeffs[2][10] = {

    { 1.0, 1.0,  1.0, 1.0,  1.0,  1.0, 1.0,  1.0,  1.0, 1.0},
    { 0.0, 0.0,  1.0, 0.0, -1.0,  3.0, 0.0,  2.0, -4.0, 5.0}

  };
  for (
    long iOutput = 2;
    iOutput--;) {

    for (
      long iCoeff = 10;
      iCoeff--;) {

      VecSet(
        unit->coeffs[iOutput],
        iCoeff,
        coeffs[iOutput][iCoeff]);

    }

  }

  VecFloat* inputs = VecFloatCreate(3);
  VecSet(
    inputs,
    0,
```

```
    1.0);
  VecSet(
    inputs,
    1,
    3.0);
  VecSet(
    inputs,
    2,
    1.5);

  NMUnitEvaluate(
    unit,
    inputs);

  float check[2];
  float x = 2.0 * (1.0 - 0.0) / (2.0 - 0.0) - 1.0;
  float y = 0.0; //2.0 * (3.0 - 0.0) / (2.0 - 0.0) - 1.0;
  float z = 2.0 * (1.5 - 0.0) / (2.0 - 0.0) - 1.0;
  check[0] = 1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z;
  check[1] =
    x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z;
  for (
    long iOutput = 2;
    iOutput--;) {

    float v =
      VecGet(
        unit->outputs,
        iOutput);
    bool same =
      ISEQUALF(
        v,
        check[iOutput]);
    if (same == false) {

      NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
      sprintf(
        NeuraMorphErr->_msg,
        "NMUnitEvaluate failed");
      PBErrCatch(NeuraMorphErr);

    }

  }

  NeuraMorphUnitFree(&unit);
  VecFree(&iIn);
  VecFree(&iOut);
  VecFree(&inputs);
  printf("UnitTestNeuraMorphUnitEvaluate OK\n");

}

void UnitTestNeuraMorphUnit() {

  UnitTestNeuraMorphUnitCreateFree();
  UnitTestNeuraMorphUnitGetSet();
  UnitTestNeuraMorphUnitEvaluate();
  printf("UnitTestNeuraMorphUnit OK\n");

}
```

```
void UnitTestAll() {

  UnitTestNeuraMorphUnit();
  printf("UnitTestAll OK\n");

}

int main() {

  UnitTestAll();

  // Return success code
  return 0;

}
```

6 Unit tests output