

NeuraMorph

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Contents

1	Definitions	1
2	Interface	1
3	Code	7
3.1	neuramorph.c	7
3.2	neuramorph-inline.c	33
4	Makefile	42
5	Unit tests	43
6	Unit tests output	63

Introduction

NeuraMorph is a C library providing structures and functions to implement a neural network.

It uses the PBErr, PBMath, GSet library.

1 Definitions

2 Interface

```
// ===== NEURAMORPH.H =====
```

```

#ifndef NEURAMORPH_H
#define NEURAMORPH_H

// ===== Include =====

#include <stdlib.h>
#include <stdio.h>
#include <math.h>
#include <string.h>
#include <stdbool.h>
#include "pberr.h"
#include "pbmath.h"
#include "gset.h"
#include "gdataset.h"

// ---- NeuraMorphUnit

// ===== Data structure =====

typedef struct NeuraMorphUnit {

    // Input indices in parent NeuraMorph
    VecLong* iInputs;

    // Output indices in parent NeuraMorph
    VecLong* iOutputs;

    // Lowest and highest values for filtering inputs
    VecFloat* lowFilters;
    VecFloat* highFilters;

    // Lowest and highest values of outputs
    VecFloat* lowOutputs;
    VecFloat* highOutputs;

    // Vector to memorize the output values
    VecFloat* outputs;

    // Transfer function coefficients
    // Seen as (nb output) triangular matrices of size (nb input + 1)
    VecFloat** coeffs;

    // Working variables to avoid reallocation of memory at each Evaluate()
    bool* activeInputs;
    VecFloat* unitInputs;

    // Variable to memorize the value of the unit during training
    float value;

} NeuraMorphUnit;

// ===== Functions declaration =====

// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
    const VecLong* iInputs,
    const VecLong* iOutputs);

// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that);

```

```

// Get the input indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that);

// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that);

// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that);

// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
    NeuraMorphUnit* that,
    const VecFloat* inputs);

// Get the number of input values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbInputs(const NeuraMorphUnit* that);

// Get the number of output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbOutputs(const NeuraMorphUnit* that);

// Get the value of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
float NMUnitGetValue(const NeuraMorphUnit* that);

// Set the value of the NeuraMorphUnit 'that' to 'val'
#if BUILDMODE != 0
static inline
#endif
void NMUnitSetValue(
    NeuraMorphUnit* that,
    float val);

// Print the NeuraMorphUnit 'that' on the 'stream'
void NMUnitPrint(
    const NeuraMorphUnit* that,
    FILE* stream);
#define NMUnitPrintln(T, S) \
    NMUnitPrint(T, S);fprintf(S, "\n")

// ----- NeuraMorph

// ===== Data structure =====

typedef struct NeuraMorph {

```

```

    // Number of inputs and outputs
    long nbInput;
    long nbOutput;

    // Inputs and outputs values
    VecFloat* inputs;
    VecFloat* outputs;

    // Internal values
    VecFloat* hiddens;

    // Lowest and highest values for internal values
    VecFloat* lowHiddens;
    VecFloat* highHiddens;

    // GSet of NeuraMorphUnit
    GSet units;
} NeuraMorph;

// ===== Functions declaration =====

// Create a new NeuraMorph with 'nbInput' inputs and 'nbOutput' outputs
NeuraMorph* NeuraMorphCreate(
    long nbInput,
    long nbOutput);

// Free the memory used by the NeuraMorph 'that'
void NeuraMorphFree(NeuraMorph** that);

// Get the number of input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbInput(const NeuraMorph* that);

// Get the number of output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbOutput(const NeuraMorph* that);

// Get the input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
VecFloat* NMInputs(NeuraMorph* that);

// Get the output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMOutputs(const NeuraMorph* that);

// Get the hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMHiddens(const NeuraMorph* that);

// Get the number of hidden values of the NeuraMorph 'that'

```

```

#if BUILDMODE != 0
static inline
#endif
long NMGetNbHidden(const NeuraMorph* that);

// Set the number of hidden values of the NeuraMorph 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void NMSetNbHidden(
    NeuraMorph* that,
    long nb);

// Add one NeuraMorphUnit with input and output indices 'iInputs'
// and 'iOutputs' to the NeuraMorph 'that'
// Return the created NeuraMorphUnit
NeuraMorphUnit* NMAddUnit(
    NeuraMorph* that,
    const VecLong* iInputs,
    const VecLong* iOutputs);

// Remove the NeuraMorphUnit 'unit' from the NeuraMorph 'that'
// The NeuraMorphUnit is not freed
void NMRemoveUnit(
    NeuraMorph* that,
    NeuraMorphUnit* unit);

// Burry the NeuraMorphUnits in the 'units' set into the
// NeuraMorph 'that'
// 'units' is empty after calling this function
// The NeuraMorphUnits iOutputs must point toward the NeuraMorph
// outputs
// NeuraMorphUnits' iOutputs are redirected toward new hidden values
// 'that->hiddens' is resized as necessary
void NMBurryUnits(
    NeuraMorph* that,
    GSet* units);

// Get a new vector with indices of the outputs in the NeuraMorph 'that'
VecLong* NMGetVecIOutputs(const NeuraMorph* that);

// Evaluate the NeuraMorph 'that' on the 'inputs' values
void NMEvaluate(
    NeuraMorph* that,
    VecFloat* inputs);

// ----- NeuraMorphTrainer

// ===== Data structure =====

typedef struct NeuraMorphTrainer {

    // Trained NeuraMorph
    NeuraMorph* neuraMorph;

    // Training dataset
    GDataSetVecFloat* dataset;

    // Index of the dataset's category used for training
    unsigned int iCatTraining;

    // Depth of the training

```

```

    short depth;

    // Threshold used to discard weakest units during training
    // in [0.0,1.0]
    float weakUnitThreshold;

    // Precomputed values to train the NeuraMorphUnit
    VecFloat** preCompInp;

} NeuraMorphTrainer;

// ===== Functions declaration =====

// Create a static NeuraMorphTrainer for the NeuraMorph 'neuraMorph' and the
// GDataSet 'dataset'
// Default depth: 2
// Default iCatTraining: 0
// Default weakUnitThreshold: 0.9
NeuraMorphTrainer NeuraMorphTrainerCreateStatic(
    NeuraMorph* neuraMorph,
    GDataSetVecFloat* dataset);

// Free the memory used by the static NeuraMorphTrainer 'that'
void NeuraMorphTrainerFreeStatic(NeuraMorphTrainer* that);

// Run the training process for the NeuraMorphTrainer 'that'
void NMTrainerRun(NeuraMorphTrainer* that);

// Get the depth of the NeuraMorphTrainer 'that'
#ifdef BUILDMODE != 0
static inline
#endif
short NMTrainerGetDepth(const NeuraMorphTrainer* that);

// Set the depth of the NeuraMorphTrainer 'that' to 'depth'
#ifdef BUILDMODE != 0
static inline
#endif
void NMTrainerSetDepth(
    NeuraMorphTrainer* that,
    short depth);

// Get the weakness threshold of the NeuraMorphTrainer 'that'
#ifdef BUILDMODE != 0
static inline
#endif
float NMTrainerGetWeakThreshold(const NeuraMorphTrainer* that);

// Set the weakness threshold of the NeuraMorphTrainer 'that'
// to 'iCat'
#ifdef BUILDMODE != 0
static inline
#endif
void NMTrainerSetWeakThreshold(
    NeuraMorphTrainer* that,
    float weakUnitThreshold);

// Get the index of the training category of the NeuraMorphTrainer 'that'
#ifdef BUILDMODE != 0
static inline
#endif
unsigned int NMTrainerGetICatTraining(const NeuraMorphTrainer* that);

```

```

// Set the index of the training category of the NeuraMorphTrainer 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetICatTraining(
    NeuraMorphTrainer* that,
    unsigned int iCatTraining);

// Get the NeuraMorph of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
NeuraMorph* NMTrainerNeuraMorph(const NeuraMorphTrainer* that);

// Get the GDataSet of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
GDataSetVecFloat* NMTrainerDataset(const NeuraMorphTrainer* that);

// ===== static inliner =====

#if BUILDMODE != 0
#include "neuramorph-inline.c"
#endif

#endif

```

3 Code

3.1 neuramorph.c

```

// ===== NEURAMORPH.C =====

// ===== Include =====

#include "neuramorph.h"
#if BUILDMODE == 0
#include "neuramorph-inline.c"
#endif

// ---- NeuraMorphUnit

// ===== Functions declaration =====

// Return the number of coefficients of a NeuraMorphUnit having 'nbIn' inputs
long NMUnitGetNbCoeff(long nbIn);

// Get the coefficient for the pair of inputs 'iInputA', 'iInputB' in the
// NeuraMorphUnit 'that' for the output 'iOutput'
float NMUnitGetCoeff(
    const NeuraMorphUnit* that,
    long iInputA,
    long iInputB,
    long iOutput);

```

```

// Update the low and high of the hiddens of the NeuraMorph 'that' with
// the low and high of its units
void NMUpdateLowHighHiddens(NeuraMorph* that);

// ===== Functions implementation =====

// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
    const VecLong* iInputs,
    const VecLong* iOutputs) {

#if BUILDMODE == 0

    if (iInputs == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'iInputs' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (iOutputs == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'iOutputs' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    // Allocate memory for the NeuraMorphUnit
    NeuraMorphUnit* that =
        PBErrMalloc(
            NeuraMorphErr,
            sizeof(NeuraMorphUnit));

    // Get the number of inputs (including the constant) and outputs
    long nbIn = VecGetDim(iInputs) + 1;
    long nbOut = VecGetDim(iOutputs);

    // Init properties
    that->iInputs = VecClone(iInputs);
    that->iOutputs = VecClone(iOutputs);
    that->lowFilters = VecFloatCreate(nbIn);
    that->highFilters = VecFloatCreate(nbIn);
    that->lowOutputs = NULL;
    that->highOutputs = NULL;
    that->outputs = VecFloatCreate(nbOut);
    that->coeffs =
        PBErrMalloc(
            NeuraMorphErr,
            sizeof(VecFloat*) * nbOut);
    long nbCoeff = NMUnitGetNbCoeff(nbIn);
    for (
        long iOut = nbOut;
        iOut--;
```



```

        that->coeffs[iOut] = VecFloatCreate(nbCoeff));

// 'nbIn + 1' for the constant
that->activeInputs =
    PBErrMalloc(
        NeuraMorphErr,
        sizeof(bool) * nbIn);
that->unitInputs = VecFloatCreate(nbIn);
that->value = 0.0;

// Set the input value, filters and active flag for the constant
VecSet(
    that->unitInputs,
    0,
    1.0);
that->activeInputs[0] = true;

// Return the new NeuraMorphUnit
return that;
}

// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that) {

    // Check the input
    if (that == NULL || *that == NULL) {

        return;

    }

    // Free memory
    long nbOut = VecGetDim((*that)->iOutputs);
    VecFree(&((*that)->iInputs));
    VecFree(&((*that)->iOutputs));
    VecFree(&((*that)->lowFilters));
    VecFree(&((*that)->highFilters));
    if ((*that)->lowOutputs != NULL) {

        VecFree(&((*that)->lowOutputs));

    }

    if ((*that)->highOutputs != NULL) {

        VecFree(&((*that)->highOutputs));

    }

    VecFree(&((*that)->outputs));
    for (
        long iOut = nbOut;
        iOut--;
        VecFree((*that)->coeffs + iOut));
    free((*that)->coeffs);
    free((*that)->activeInputs);
    VecFree(&((*that)->unitInputs));
    free(*that);
    *that = NULL;
}

```

```

// Return the number of coefficients of a NeuraMorphUnit having 'nbIn' inputs
long NMUnitGetNbCoeff(long nbIn) {

#if BUILDMODE == 0

    if (nbIn <= 0) {

        NeuraMorphErr->_type = PBErrTypeInvalidArg;
        sprintf(
            NeuraMorphErr->_msg,
            "'nbIn' is invalid (%ld>0)",
            nbIn);
        PBErrCatch(NeuraMorphErr);

    }

#endif

    // Declare a variable to memorise the result
    long nb = 0;

    // Calculate the number of values in the triangular matrix of size
    // nbIn
    for (
        long i = nbIn;
        i >= 0;
        nb += (i--));

    // Return the result
    return nb;

}

// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
    NeuraMorphUnit* that,
    const VecFloat* inputs) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (VecGetDim(inputs) != VecGetDim(that->iInputs)) {

        NeuraMorphErr->_type = PBErrTypeInvalidArg;
        sprintf(
            NeuraMorphErr->_msg,
            "'inputs' has invalid dimension (%ld!=%ld)",
            VecGetDim(inputs),
            VecGetDim(that->iInputs));
        PBErrCatch(NeuraMorphErr);

    }

#endif
}

```

```

    }

#endif

    // Reset the outputs
    VecSetNull(that->outputs);

    // Update the active flags and scaled inputs (skip the constant)
    for (
        long iInput = 1;
        iInput < VecGetDim(that->unitInputs);
        ++iInput) {

        // Get the input value and its low/high filters
        float val =
            VecGet(
                inputs,
                iInput - 1);
        float low =
            VecGet(
                that->lowFilters,
                iInput);
        float high =
            VecGet(
                that->highFilters,
                iInput);

        // If the value is inside the filter
        if (
            low <= val &&
            val <= high &&
            (high - low) > PBMath_EPSILON) {

            // Set this value as active
            that->activeInputs[iInput] = true;

            // Set the value in the unit inputs
            VecSet(
                that->unitInputs,
                iInput,
                val);

            // Else the value is outside the filter
        } else {

            // Set this value as inactive
            that->activeInputs[iInput] = false;

        }

    }

}

// Loop on the pair of active inputs
for (
    long iInputA = 0;
    iInputA < VecGetDim(that->unitInputs);
    ++iInputA) {

    if (that->activeInputs[iInputA] == true) {

        for (
            long iInputB = 0;

```

```

        iInputB <= iInputA;
        ++iInputB) {

    if (that->activeInputs[iInputB] == true) {

        // Loop on the outputs
        for (
            long iOutput = 0;
            iOutput < VecGetDim(that->outputs);
            ++iOutput) {

            // Calculate the components for this output and pair of inputs
            float comp =
                VecGet(
                    that->unitInputs,
                    iInputA) *
                VecGet(
                    that->unitInputs,
                    iInputB) *
                NMUnitGetCoeff(
                    that,
                    iInputA,
                    iInputB,
                    iOutput);

            // Add the component to the output
            float cur =
                VecGet(
                    that->outputs,
                    iOutput);
            VecSet(
                that->outputs,
                iOutput,
                cur + comp);

        }

    }

}

}

}

// If the low and high values for outputs don't exist yet
if (that->lowOutputs == NULL) {

    // Create the low and high values by cloning the current output
    that->lowOutputs = VecClone(that->outputs);
    that->highOutputs = VecClone(that->outputs);

    // Else, the low and high values for outputs exist
} else {

    // Loop on the outputs
    for (
        long iOutput = 0;
        iOutput < VecGetDim(that->outputs);
        ++iOutput) {

        // Update the low and high values for this output

```

```

float val =
    VecGet(
        that->outputs,
        iOutput);

float curLow =
    VecGet(
        that->lowOutputs,
        iOutput);
if (curLow > val) {

    VecSet(
        that->lowOutputs,
        iOutput,
        val);

}

float curHigh =
    VecGet(
        that->highOutputs,
        iOutput);
if (curHigh < val) {

    VecSet(
        that->highOutputs,
        iOutput,
        val);

}

}

}

}

// Get the coefficient for the pair of inputs 'iInputA', 'iInputB' in the
// NeuraMorphUnit 'that' for the output 'iOutput'
float NMUnitGetCoeff(
    const NeuraMorphUnit* that,
        long iInputA,
        long iInputB,
        long iOutput) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (
        iInputA < 0 ||
        iInputA >= VecGetDim(that->unitInputs)) {

        NeuraMorphErr->_type = PBErrTypeInvalidArg;

```

```

    sprintf(
        NeuraMorphErr->_msg,
        "'iInputA' is invalid (0<=%ld<%ld)",
        iInputA,
        VecGetDim(that->unitInputs));
    PBErrCatch(NeuraMorphErr);
}

if (
    iInputB < 0 ||
    iInputB >= VecGetDim(that->unitInputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
        NeuraMorphErr->_msg,
        "'iInputB' is invalid (0<=%ld<%ld)",
        iInputB,
        VecGetDim(that->unitInputs));
    PBErrCatch(NeuraMorphErr);
}

if (iInputA < iInputB) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
        NeuraMorphErr->_msg,
        "The pair of indices is invalid (%ld>=%ld)",
        iInputA,
        iInputB);
    PBErrCatch(NeuraMorphErr);
}

if (
    iOutput < 0 ||
    iOutput >= VecGetDim(that->outputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
        NeuraMorphErr->_msg,
        "'iInputB' is invalid (0<=%ld<%ld)",
        iInputB,
        VecGetDim(that->outputs));
    PBErrCatch(NeuraMorphErr);
}

}

#endif

// Calculate the index of the coefficient
long iCoeff = 0;
for (
    long shift = 0;
    shift < iInputA;
    iCoeff += (shift++) + 1);
iCoeff += iInputB;

// Return the coefficient
float coeff =
    VecGet(

```

```

        that->coeffs[iOutput],
        iCoeff);
    return coeff;
}

// Print the NeuraMorphUnit 'that' on the 'stream'
void NMUnitPrint(
    const NeuraMorphUnit* that,
    FILE* stream) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (stream == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'stream' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    VecPrint(
        NMUnitIInputs(that),
        stream);
    fprintf(
        stream,
        " -> ");
    VecPrint(
        NMUnitIOutputs(that),
        stream);
    fprintf(
        stream,
        " (%04.6f)",
        NMUnitGetValue(that));

    }

// ----- NeuraMorph

// ===== Functions implementation =====

// Create a new NeuraMorph with 'nbInput' inputs and 'nbOutput' outputs
NeuraMorph* NeuraMorphCreate(
    long nbInput,
    long nbOutput) {

    // Allocate memory for the NeuraMorph
    NeuraMorph* that =

```

```

    PBErrMalloc(
        NeuraMorphErr,
        sizeof(NeuraMorph));

    // Init properties
    that->nbInput = nbInput;
    that->nbOutput = nbOutput;
    that->inputs = VecFloatCreate(nbInput);
    that->outputs = VecFloatCreate(nbOutput);
    that->hiddens = NULL;
    that->lowHiddens = NULL;
    that->highHiddens = NULL;
    that->units = GSetCreateStatic();

    // Return the NeuraMorph
    return that;
}

// Free the memory used by the NeuraMorph 'that'
void NeuraMorphFree(NeuraMorph** that) {

    // Check the input
    if (that == NULL || *that == NULL) {

        return;
    }

    // Free memory
    VecFree(&((*that)->inputs));
    VecFree(&((*that)->outputs));
    if ((*that)->hiddens != NULL) {

        VecFree(&((*that)->hiddens));
        VecFree(&((*that)->lowHiddens));
        VecFree(&((*that)->highHiddens));
    }

    while (GSetNbElem(&((*that)->units)) > 0) {

        NeuraMorphUnit* unit = GSetPop(&((*that)->units));
        NeuraMorphUnitFree(&unit);
    }

    free(*that);
    *that = NULL;
}

// Add one NeuraMorphUnit with input and output indices 'iInputs'
// and 'iOutputs' to the NeuraMorph 'that'
// Return the created NeuraMorphUnit
NeuraMorphUnit* NMAddUnit(
    NeuraMorph* that,
    const VecLong* iInputs,
    const VecLong* iOutputs) {

#ifdef BUILDMODE == 0

```



```

if (that == NULL) {

    NeuroMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
        NeuroMorphErr->_msg,
        "'that' is null");
    PBErrCatch(NeuroMorphErr);

}

if (iInputs == NULL) {

    NeuroMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
        NeuroMorphErr->_msg,
        "'iInputs' is null");
    PBErrCatch(NeuroMorphErr);

}

if (iOutputs == NULL) {

    NeuroMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
        NeuroMorphErr->_msg,
        "'iOutputs' is null");
    PBErrCatch(NeuroMorphErr);

}

#endif

// Create the NeuroMorphUnit
NeuroMorphUnit* unit =
    NeuroMorphUnitCreate(
        iInputs,
        iOutputs);

// Append the new NeuroMorphUnit to the set of NeuroMorphUnit
GSetAppend(
    &(that->units),
    unit);

// Return the new unit
return unit;

}

// Remove the NeuroMorphUnit 'unit' from the NeuroMorph 'that'
// The NeuroMorphUnit is not freed
void NMRemoveUnit(
    NeuroMorph* that,
    NeuroMorphUnit* unit) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'that' is null");
    }
}

```

```

        PBErCatch(NeuraMorphErr);

    }

#endif

    // Remove the NeuraMorphUnit from the set of NeuraMorphUnit
    GSetRemoveAll(
        &(that->units),
        unit);

}

// Burry the NeuraMorphUnits in the 'units' set into the
// NeuraMorph 'that'
// 'units' is empty after calling this function
// The NeuraMorphUnits iOutputs must point toward the NeuraMorph
// outputs
// NeuraMorphUnits' iOutputs are redirected toward new hidden values
// 'that->hiddens' is resized as necessary
void NMBurryUnits(
    NeuraMorph* that,
    GSet* units) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErCatch(NeuraMorphErr);

    }

#endif

    // Declare a variable to memorize the number of hidden values
    // to add
    long nbHiddenValues = 0;

    // While there are units to burry
    while (GSetNbElem(units) > 0) {

        // Get the unit
        NeuraMorphUnit* unit = GSetPop(units);

        // Loop on the iOutputs of the unit
        for (
            long iOutput = 0;
            iOutput < VecGetDim(NMUnitIOOutputs(unit));
            ++iOutput) {

            long indice =
                VecGet(
                    NMUnitIOOutputs(unit),
                    iOutput);
            VecSet(
                unit->iOutputs,
                iOutput,
                indice + nbHiddenValues);
        }
    }
}

```

```

    }

    // Append the unit to the set of NeuraMorphUnit
    GSetAppend(
        &(that->units),
        unit);

    // Update the number of new hidden values
    nbHiddenValues += VecGetDim(NMUnitIOutputs(unit));
}

// If there is already hidden values
if (that->hiddens != NULL) {

    // Add the previous number of hidden values
    nbHiddenValues += VecGetDim(that->hiddens);

    // Free memory
    VecFree(&(that->hiddens));
    VecFree(&(that->lowHiddens));
    VecFree(&(that->highHiddens));
}

// If there are hidden values after burrying
if (nbHiddenValues > 0) {

    // Resize the hiddens value vector
    that->hiddens = VecFloatCreate(nbHiddenValues);
    that->lowHiddens = VecFloatCreate(nbHiddenValues);
    that->highHiddens = VecFloatCreate(nbHiddenValues);

    // Update the low and high of the hiddens with the low and high
    // of the units
    NMUpdateLowHighHiddens(that);
}
}

// Get a new vector with indices of the outputs in the NeuraMorph 'that'
VecLong* NMGetVecIOutputs(const NeuraMorph* that) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PErrCatch(NeuraMorphErr);
    }

#endif

    // Allocate memory for the result
    VecLong* iOutputs = VecLongCreate(NMGetNbOutput(that));

```

```

// Loop on indices
for (
    long iOutput = 0;
    iOutput < NMGetNbOutput(that);
    ++iOutput) {

    // Set the indice of this output
    VecSet(
        iOutputs,
        iOutput,
        iOutput + NMGetNbHidden(that));

}

// Return the result
return iOutputs;

}

// Update the low and high of the hiddens of the NeuraMorph 'that' with
// the low and high of its units
void NMUpdateLowHighHiddens(NeuraMorph* that) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PErrCatch(NeuraMorphErr);

    }

#endif

    // Loop on the units
    GSetIterForward iter =
        GSetIterForwardCreateStatic(&(that->units));
    do {

        // Get the unit
        NeuraMorphUnit* unit = GSetIterGet(&iter);

        // Loop on the iOutputs of the unit
        for (
            long iOutput = 0;
            iOutput < VecGetDim(NMUnitIOutputs(unit));
            ++iOutput) {

            // Get the indice
            long indice =
                VecGet(
                    NMUnitIOutputs(unit),
                    iOutput);

            // If the indice points to a hidden value
            if (indice < NMGetNbHidden(that)) {

                // If the low and high exist
                if (

```

```

        unit->lowOutputs != NULL &&
        unit->highOutputs != NULL) {

    // Update the low and high
    float low =
        VecGet(
            unit->lowOutputs,
            iOutput);
    float high =
        VecGet(
            unit->highOutputs,
            iOutput);
    VecSet(
        that->lowHiddens,
        indice,
        low);
    VecSet(
        that->highHiddens,
        indice,
        high);

    }

    }

    }

    } while (GSetIterStep(&iter));
}

// Evaluate the NeuraMorph 'that' on the 'inputs' values
void NMEvaluate(
    NeuraMorph* that,
    VecFloat* inputs) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (inputs == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'inputs' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (VecGetDim(inputs) != VecGetDim(that->inputs)) {

        NeuraMorphErr->_type = PBErrTypeInvalidArg;
        sprintf(

```

```

        NeuraMorphErr->_msg,
        "'inputs' has invalid size (%ld==%ld)",
        VecGetDim(inputs),
        VecGetDim(that->inputs));
    PBErrCatch(NeuraMorphErr);
}

#endif

// Copy the inputs into the internal inputs
VecCopy(
    that->inputs,
    inputs);

// Reset the internal outputs
VecSetNull(that->outputs);

// If there are no units
if (GSetNbElem(&(that->units)) == 0) {

    // Nothing else to do
    return;
}

// Loop on the units
GSetIterForward iter = GSetIterForwardCreateStatic(&(that->units));
do {

    // Get the unit
    NeuraMorphUnit* unit = GSetIterGet(&iter);

    // Allocate memory for inputs sent to the unit
    VecFloat* unitInputs = VecFloatCreate(NMUnitGetNbInputs(unit));

    // Loop on the input indices of the unit
    for (
        long iInput = 0;
        iInput < NMUnitGetNbInputs(unit);
        ++iInput) {

        // Get the input indice
        long indiceInput =
            VecGet(
                NMUnitIInputs(unit),
                iInput);

        // Declare a variable to memorize the input value
        float val = 0.0;

        // If this indice points toward an input
        if (indiceInput < NMGetNbInput(that)) {

            // Get the input value of the NeuraMorph for this indice
            val =
                VecGet(
                    NMInputs(that),
                    indiceInput);

            // Else, the indice points toward a hidden value
        } else {

```

```

        // Get the hidden value of the NeuraMorph for this indice
        val =
            VecGet(
                that->hiddens,
                indiceInput - NMGetNbInput(that));
    }

    // Set the input value for the unit for this indice
    VecSet(
        unitInputs,
        iInput,
        val);
}

// Evaluate the unit
NMUnitEvaluate(
    unit,
    unitInputs);

// Free the memory used by the unit input
VecFree(&unitInputs);

// Loop on the output indices of the unit
for (
    long iOutput = 0;
    iOutput < NMUnitGetNbOutputs(unit);
    ++iOutput) {

    // Get the output value of the unit for this indice
    float val =
        VecGet(
            NMUnitOutputs(unit),
            iOutput);

    // Get the output indice
    long indiceOutput =
        VecGet(
            NMUnitIOutputs(unit),
            iOutput);

    // If the indice points toward a hidden
    if (indiceOutput < NMGetNbHidden(that)) {

        // Set the hidden value of the NeuraMorph for this indice
        VecSet(
            that->hiddens,
            indiceOutput,
            val);

    // Else, the indice points toward an output
    } else {

        // Set the output value of the NeuraMorph for this indice
        VecSet(
            that->outputs,
            indiceOutput - NMGetNbHidden(that),
            val);
    }
}

```

```

    }

    } while (GSetIterStep(&iter));
}

// ----- NeuraMorphTrainer

// ===== Functions declaration =====

// Return true if the vector 'v' is a valid indices configuration
// i.e. v[i]<v[j] for all i<j
bool NMTrainerIsValidInputConfig(
    const VecLong* v,
    long iMinInput);

// Train a new NeuraMorphUnit with the interface defined by 'iInputs'
// and 'iOutputs', and add it to the set, sorted on its value
void NMTrainerTrainUnit(
    NeuraMorphTrainer* that,
    GSet* trainedUnits,
    const VecLong* iInputs,
    const VecLong* iOutputs);

// Precompute the hidden values of the NeuraMorph for each sample of the
// GDataset for the NeuraMorphTrainer 'that'
void NMTrainerPrecomputeHiddens(NeuraMorphTrainer* that);

// Free the precomputed hidden values of the NeuraMorphTrainer 'that'
void NMTrainerFreePrecomputed(NeuraMorphTrainer* that);

// ===== Functions implementation =====

// Create a static NeuraMorphTrainer for the NeuraMorph 'neuraMorph' and the
// GDataSet 'dataset'
// Default depth: 2
// Default iCatTraining: 0
// Default weakUnitThreshold: 0.9
NeuraMorphTrainer NeuraMorphTrainerCreateStatic(
    NeuraMorph* neuraMorph,
    GDataSetVecFloat* dataset) {

#ifdef BUILDMODE == 0

    if (neuraMorph == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'neuraMorph' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (dataset == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'dataset' is null");
        PBErrCatch(NeuraMorphErr);

    }

}

```



```

    }

#endif

    // Declare the new NeuraMorphTrainer
    NeuraMorphTrainer that;

    // Init properties
    that.neuraMorph = neuraMorph;
    that.dataset = dataset;
    that.depth = 2;
    that.iCatTraining = 0;
    that.weakUnitThreshold = 0.9;
    that.preCompInp = NULL;

    // Return the NeuraMorphTrainer
    return that;
}

// Free the memory used by the static NeuraMorphTrainer 'that'
void NeuraMorphTrainerFreeStatic(NeuraMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    // Nothing to do
}

// Run the training process for the NeuraMorphTrainer 'that'
void NMTrainerRun(NeuraMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    // Declare a variable to memorize the minimum index needed in the
    // inputs of the new unit to ensure we do not train twice the same
    // unit

```

```

long iMinInput = 0;

// Loop on training depth
for (
    short iDepth = 1;
    iDepth <= NMTrainerGetDepth(that);
    ++iDepth) {

    printf(
        "Depth %d/%d...\n",
        iDepth,
        NMTrainerGetDepth(that));

    // Get the number of available inputs for the new unit
    long nbAvailInputs =
        NMGetNbInput(NMTrainerNeuraMorph(that)) +
        NMGetNbHidden(NMTrainerNeuraMorph(that));

    printf(
        "Nb available inputs: %ld\n",
        nbAvailInputs);

    // Precompute the hidden values to speed up the training
    NMTrainerPrecomputeHiddens(that);

    // Get the output indices
    VecLong* iOutputs = NMGetVecIOutputs(NMTrainerNeuraMorph(that));

    // Declare a set to memorize the trained units
    GSet trainedUnits = GSetCreateStatic();

    // Loop on the number of inputs for the new unit
    // TODO restrain nbUnitInput to a maximum
    for (
        long nbUnitInputs = 1;
        nbUnitInputs <= nbAvailInputs;
        ++nbUnitInputs) {

        printf(
            "Train units with %04ld inputs\n",
            nbUnitInputs);

        // Loop on the possible input configurations for the new units
        VecLong* iInputs = VecLongCreate(nbUnitInputs);
        VecLong* iInputsBound = VecLongCreate(nbUnitInputs);
        VecSetAll(
            iInputsBound,
            nbAvailInputs);
        bool hasStepped = true;
        do {

            bool isValidInputConfig =
                NMTrainerIsValidInputConfig(
                    iInputs,
                    iMinInput);
            if (isValidInputConfig == true) {

                // Train the unit
                NMTrainerTrainUnit(
                    that,
                    &trainedUnits,
                    iInputs,

```

```

        iOutputs);

    }

    // Step to the next input configuration
    hasStepped =
        VecStep(
            iInputs,
            iInputsBound);

} while (hasStepped);

// Free memory
VecFree(&iInputs);
VecFree(&iInputsBound);

}

// If this is the last depth
if (iDepth == NMTrainerGetDepth(that)) {

    // Add the best of all units to the NeuraMorph
    NeuraMorphUnit* bestUnit = GSetDrop(&trainedUnits);
    GSetAppend(
        &(NMTrainerNeuraMorph(that)->units),
        bestUnit);

    printf("Add the last unit\n");
    NMUnitPrintln(
        bestUnit,
        stdout);

    // Discard all other units
    while (GSetNbElem(&trainedUnits) > 0) {

        NeuraMorphUnit* unit = GSetPop(&trainedUnits);
        NeuraMorphUnitFree(&unit);

    }

    // Else, this is not the last depth
} else {

    // Get the value of the weakest and strongest units
    float weakVal = GSetElemGetSortVal(GSetHeadElem(&trainedUnits));
    float strongVal = GSetElemGetSortVal(GSetTailElem(&trainedUnits));

    // Get the threshold to discard the weakest units
    float threshold =
        weakVal + (strongVal - weakVal) *
        NMTrainerGetWeakThreshold(that);

    // Discard the weakest units
    long nbTrainedUnits = GSetNbElem(&trainedUnits);
    while (
        GSetElemGetSortVal(GSetHeadElem(&trainedUnits)) < threshold) {

        NeuraMorphUnit* unit = GSetPop(&trainedUnits);
        NeuraMorphUnitFree(&unit);

    }
}

```

```

printf(
    "Burry %ld out of %ld units\n",
    GSetNbElem(&trainedUnits),
    nbTrainedUnits);
GSetIterForward iter = GSetIterForwardCreateStatic(&trainedUnits);
do {

    NeuraMorphUnit* unit = GSetIterGet(&iter);
    NMUnitPrintln(
        unit,
        stdout);

} while (GSetIterStep(&iter));

// Burry the remaining units
NMBurryUnits(
    NMTrainerNeuraMorph(that),
    &trainedUnits);

}

// Update the minimum index of a valid configuration
iMinInput = nbAvailInputs;

// Free memory
VecFree(&iOutputs);
NMTrainerFreePrecomputed(that);

}

}

// Return true if the vector 'v' is a valid indices configuration
// i.e. v[i]<v[j] for all i<j and there exists i such as
// v[i]>=iMinInput
bool NMTrainerIsValidInputConfig(
    const VecLong* v,
    long iMinInput) {

#ifdef BUILDMODE == 0

    if (v == NULL) {

        NeuraMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'v' is null");
        PErrCatch(NeuraMorphErr);

    }

#endif

    bool noveltyCond = false;
    long a =
        VecGet(
            v,
            0);
    if (a >= iMinInput) {

        noveltyCond = true;
    }

```

```

    }

    for (
        long i = 1;
        i < VecGetDim(v);
        ++i) {

        long b =
            VecGet(
                v,
                i);
        if (a >= b) {

            return false;

        }

        a = b;

        if (a >= iMinInput) {

            noveltyCond = true;

        }

    }

    return noveltyCond;

}

// Train a new NeuraMorphUnit with the interface defined by 'iInputs'
// and 'iOutputs', and add it to the set, sorted on its value
void NMTrainerTrainUnit(
    NeuraMorphTrainer* that,
        GSet* trainedUnits,
        const VecLong* iInputs,
        const VecLong* iOutputs) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PErrCatch(NeuraMorphErr);

    }

    if (trainedUnits == NULL) {

        NeuraMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'trainedUnits' is null");
        PErrCatch(NeuraMorphErr);

    }

    if (iInputs == NULL) {

```

```

        NeuroMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'iInputs' is null");
        PErrCatch(NeuroMorphErr);
    }

    if (iOutputs == NULL) {

        NeuroMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'iOutputs' is null");
        PErrCatch(NeuroMorphErr);
    }

#endif

    // Create the unit
    NeuroMorphUnit* unit =
        NeuroMorphUnitCreate(
            iInputs,
            iOutputs);

    // TODO
    NMUnitSetValue(
        unit,
        rand());

    // Add the unit to the set of trained units
    GSetAddSort(
        trainedUnits,
        unit,
        NMUnitGetValue(unit));
}

// Precompute the hidden values of the NeuroMorph for each sample of the
// GDataset for the NeuroMorphTrainer 'that'
void NMTrainerPrecomputeHiddens(NeuroMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuroMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'that' is null");
        PErrCatch(NeuroMorphErr);
    }

#endif

    // Get the number of samples
    long nbSample =
        GDSGetSizeCat(
            NMTrainerDataset(that),

```

```

        NMTrainerGetICatTraining(that));

// Allocate memory
that->preCompInp =
    PBErrMalloc(
        NeuraMorphErr,
        nbSample * sizeof(VecFloat*));

// Get the size of the precomputed vector
long sizeInp =
    NMGetNbInput(NMTrainerNeuraMorph(that)) +
    NMGetNbHidden(NMTrainerNeuraMorph(that));

// Loop on the samples
long iSample = 0;
bool flagStep = true;
GDSReset(
    NMTrainerDataset(that),
    NMTrainerGetICatTraining(that));
do {

    // Get a clone of the sample
    VecFloat* inputs =
        GDSGetSampleInputs(
            NMTrainerDataset(that),
            NMTrainerGetICatTraining(that));

    // Run the NeuraMorph on the sample
    NMEvaluate(
        NMTrainerNeuraMorph(that),
        inputs);

    // Allocate memory for the precomputed vector
    that->preCompInp[iSample] = VecFloatCreate(sizeInp);

    // Copy the inputs and hidden values into the precomputed vector
    for (
        long i = NMGetNbInput(NMTrainerNeuraMorph(that));
        i--;) {

        float val =
            VecGet(
                NMInputs(NMTrainerNeuraMorph(that)),
                i);
        VecSet(
            that->preCompInp[iSample],
            i,
            val);

    }

    for (
        long i = NMGetNbHidden(NMTrainerNeuraMorph(that));
        i--;) {

        float val =
            VecGet(
                NMHiddens(NMTrainerNeuraMorph(that)),
                i);
        VecSet(
            that->preCompInp[iSample],
            i + NMGetNbInput(NMTrainerNeuraMorph(that)),

```

```

        val);

    }

    // Free memory
    VecFree(&inputs);

    // Move to the next sample
    ++iSample;
    flagStep =
        GDSStepSample(
            NMTrainerDataset(that),
            NMTrainerGetICatTraining(that));

    } while (flagStep);
}

// Free the precomputed hidden values of the NeuraMorphTrainer 'that'
void NMTrainerFreePrecomputed(NeuraMorphTrainer* that) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    // If the hidden values are not precomputed
    if (that->preCompInp == NULL) {

        // Stop here
        return;

    }

    // Get the number of samples
    long nbSample =
        GDSSGetSizeCat(
            NMTrainerDataset(that),
            NMTrainerGetICatTraining(that));

    // Free memory
    for (
        long iSample = nbSample;
        iSample--;) {

        VecFree(that->preCompInp + iSample);

    }

    free(that->preCompInp);
    that->preCompInp = NULL;

}

```


3.2 neuramorph-inline.c

```
// ===== NEURAMORPH-INLINE.C =====

// ----- NeuroMorphUnit

// ===== Functions implementation =====

// Get the input indices of the NeuroMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIInputs(const NeuroMorphUnit* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuroMorphErr);

    }

#endif

    return that->iInputs;

}

// Get the output indices of the NeuroMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitOOutputs(const NeuroMorphUnit* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuroMorphErr);

    }

#endif

    return that->oOutputs;

}

// Get the output values of the NeuroMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuroMorphUnit* that) {
```

```

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->outputs;

}

// Get the number of input values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbInputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return VecGetDim(that->iInputs);

}

// Get the number of output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbOutputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

}

```

```

    return VecGetDim(that->iOutputs);
}

// Get the value of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
float NMUnitGetValue(const NeuraMorphUnit* that) {

    #if BUILDMODE == 0

        if (that == NULL) {

            NeuraMorphErr->_type = PBErrTypeNullPointer;
            sprintf(
                NeuraMorphErr->_msg,
                "'that' is null");
            PBErrCatch(NeuraMorphErr);

        }

    #endif

    return that->value;
}

// Set the value of the NeuraMorphUnit 'that' to 'val'
#if BUILDMODE != 0
static inline
#endif
void NMUnitSetValue(
    NeuraMorphUnit* that,
    float val) {

    #if BUILDMODE == 0

        if (that == NULL) {

            NeuraMorphErr->_type = PBErrTypeNullPointer;
            sprintf(
                NeuraMorphErr->_msg,
                "'that' is null");
            PBErrCatch(NeuraMorphErr);

        }

    #endif

    that->value = val;
}

// ----- NeuraMorph

// ===== Functions implementation =====

// Get the number of input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif

```

```

long NMGetNbInput(const NeuraMorph* that) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->nbInput;

}

// Get the number of output values of the NeuraMorph 'that'
#ifdef BUILDMODE != 0
static inline
#endif
long NMGetNbOutput(const NeuraMorph* that) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->nbOutput;

}

// Get the input values of the NeuraMorph 'that'
#ifdef BUILDMODE != 0
static inline
#endif
VecFloat* NMInputs(NeuraMorph* that) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

```

```

#endif

    return that->inputs;

}

// Get the output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMOutputs(const NeuraMorph* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->outputs;

}

// Get the hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMHiddens(const NeuraMorph* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->hiddens;

}

// Get the number of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbHidden(const NeuraMorph* that) {

#if BUILDMODE == 0

```

```

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    long nb = 0;
    if (that->hiddens != NULL) {

        nb = VecGetDim(that->hiddens);

    }

    return nb;

}

// Set the number of hidden values of the NeuraMorph 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void NMSetNbHidden(
    NeuraMorph* that,
    long nb) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (nb <= 0) {

        NeuraMorphErr->_type = PBErrTypeInvalidArg;
        sprintf(
            NeuraMorphErr->_msg,
            "'nb' is invalid (%ld>0)",
            nb);
        PBErrCatch(NeuraMorphErr);

    }

#endif

    if (that->hiddens != NULL) {

        VecFree(&(that->hiddens));

    }

}

```

```

        that->hiddens = VecFloatCreate(nb);
    }

    // ----- NeuraMorphTrainer

    // ===== Functions implementation =====

    // Get the depth of the NeuraMorphTrainer 'that'
    #if BUILDMODE != 0
    static inline
    #endif
    short NMTrainerGetDepth(const NeuraMorphTrainer* that) {

    #if BUILDMODE == 0

        if (that == NULL) {

            NeuraMorphErr->_type = PBErrTypeNullPointer;
            sprintf(
                NeuraMorphErr->_msg,
                "'that' is null");
            PBErrCatch(NeuraMorphErr);

        }

    #endif

        return that->depth;

    }

    // Set the depth of the NeuraMorphTrainer 'that' to 'depth'
    #if BUILDMODE != 0
    static inline
    #endif
    void NMTrainerSetDepth(
        NeuraMorphTrainer* that,
        short depth) {

    #if BUILDMODE == 0

        if (that == NULL) {

            NeuraMorphErr->_type = PBErrTypeNullPointer;
            sprintf(
                NeuraMorphErr->_msg,
                "'that' is null");
            PBErrCatch(NeuraMorphErr);

        }

        if (depth < 1) {

            NeuraMorphErr->_type = PBErrTypeInvalidArg;
            sprintf(
                NeuraMorphErr->_msg,
                "'depth' is invalid (%d>=1)",
                depth);
            PBErrCatch(NeuraMorphErr);

        }

    #endif

```

```

#endif

    that->depth = depth;

}

// Get the NeuraMorph of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
NeuraMorph* NMTrainerNeuraMorph(const NeuraMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PErrCatch(NeuraMorphErr);

    }

#endif

    return that->neuraMorph;

}

// Get the GDataSet of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
GDataSetVecFloat* NMTrainerDataset(const NeuraMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PErrCatch(NeuraMorphErr);

    }

#endif

    return that->dataset;

}

// Get the index of the training category of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
unsigned int NMTrainerGetICatTraining(const NeuraMorphTrainer* that) {

#if BUILDMODE == 0

```



```

    if (that == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuroMorphErr);

    }

#endif

    return that->iCatTraining;

}

// Set the index of the training category of the NeuroMorphTrainer 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetICatTraining(
    NeuroMorphTrainer* that,
    unsigned int iCatTraining) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuroMorphErr);

    }

#endif

    that->iCatTraining = iCatTraining;

}

// Get the weakness threshold of the NeuroMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
float NMTrainerGetWeakThreshold(const NeuroMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuroMorphErr);

    }

#endif

```

```

#endif

    return that->weakUnitThreshold;

}

// Set the weakness threshold of the NeuraMorphTrainer 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetWeakThreshold(
    NeuraMorphTrainer* that,
    float weakUnitThreshold) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    that->weakUnitThreshold = weakUnitThreshold;

}

```

4 Makefile

```

# Build mode
# 0: development (max safety, no optimisation)
# 1: release (min safety, optimisation)
# 2: fast and furious (no safety, optimisation)
BUILD_MODE?=0

all: pbmake_wget main

# Automatic installation of the repository PBMake in the parent folder
pbmake_wget:
if [ ! -d ../PBMake ]; then wget https://github.com/BayashiPascal/PBMake/archive/master.zip; unzip master.zip; rm -f

# Makefile definitions
MAKEFILE_INC=../PBMake/Makefile.inc
include $(MAKEFILE_INC)

# Rules to make the executable
repo=neuramorph
$($(repo)_EXENAME): \
$($(repo)_EXENAME).o \
$($(repo)_EXE_DEP) \
$($(repo)_DEP)
$(COMPILER) 'echo "$($(repo)_EXE_DEP) $($(repo)_EXENAME).o" | tr ' ' '\n' | sort -u' $(LINK_ARG) $($(repo)_LINK_ARG)

```

```

$$($(repo)_EXENAME).o: \
$$($(repo)_DIR)/$$($(repo)_EXENAME).c \
$$($(repo)_INC_H_EXE) \
$$($(repo)_EXE_DEP)
$(COMPILER) $(BUILD_ARG) $$($(repo)_BUILD_ARG) 'echo "$$(repo)_INC_DIR" | tr ' ' '\n' | sort -u' -c $$($(repo)_DIR)/

```

5 Unit tests

```

#include <stdlib.h>
#include <stdio.h>
#include <time.h>
#include <string.h>
#include <time.h>
#include <unistd.h>
#include <sys/time.h>
#include "neuramorph.h"

void UnitTestNeuraMorphUnitCreateFree() {

    VecLong* iIn = VecLongCreate(3);
    VecSet(
        iIn,
        0,
        0);
    VecSet(
        iIn,
        1,
        1);
    VecSet(
        iIn,
        2,
        2);
    VecLong* iOut = VecLongCreate(2);
    VecSet(
        iOut,
        0,
        0);
    VecSet(
        iOut,
        1,
        1);
    NeuraMorphUnit* unit =
        NeuraMorphUnitCreate(
            iIn,
            iOut);
    bool isSame =
        ISEQUALF(
            unit->value,
            0.0);
    if (
        VecGetDim(unit->coeffs[0]) != 10 ||
        VecGetDim(unit->outputs) != 2 ||
        VecGetDim(unit->lowFilters) != 4 ||
        VecGetDim(unit->highFilters) != 4 ||
        VecGetDim(unit->unitInputs) != 4 ||
        isSame != true ||
        unit->lowOutputs != NULL ||
        unit->highOutputs != NULL) {

```

```

        NeuroMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuroMorphErr->_msg,
            "NeuraMorphUnitCreate failed (1)");
        PBErrCatch(NeuraMorphErr);
    }

    isSame =
        VecIsEqual(
            unit->iInputs,
            iIn);
    if (isSame == false) {

        NeuroMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuroMorphErr->_msg,
            "NeuraMorphUnitCreate failed (2)");
        PBErrCatch(NeuraMorphErr);
    }

    isSame =
        VecIsEqual(
            unit->iOutputs,
            iOut);
    if (isSame == false) {

        NeuroMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuroMorphErr->_msg,
            "NeuraMorphUnitCreate failed (3)");
        PBErrCatch(NeuraMorphErr);
    }

    NeuroMorphUnitFree(&unit);
    if (unit != NULL) {

        NeuroMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuroMorphErr->_msg,
            "NeuraMorphUnitFree failed");
        PBErrCatch(NeuraMorphErr);
    }

    VecFree(&iIn);
    VecFree(&iOut);
    printf("UnitTestNeuraMorphUnitCreateFree OK\n");
}

void UnitTestNeuraMorphUnitGetSetPrint() {

    VecLong* iIn = VecLongCreate(3);
    VecLong* iOut = VecLongCreate(2);
    NeuroMorphUnit* unit =
        NeuroMorphUnitCreate(
            iIn,
            iOut);

```

```

if (NMUnitIInputs(unit) != unit->iInputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitIInputs failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMUnitIOutputs(unit) != unit->iOutputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitIOutputs failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMUnitOutputs(unit) != unit->outputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitOutputs failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMUnitGetNbInputs(unit) != 3) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitGetNbInputs failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMUnitGetNbOutputs(unit) != 2) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitGetNbOutputs failed");
    PBErrCatch(NeuraMorphErr);

}

bool isSame =
    ISEQUALF(
        NMUnitGetValue(unit),
        0.0);
if (isSame != true) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitGetValue failed");
    PBErrCatch(NeuraMorphErr);
}

```

```

}

NMUnitSetValue(
    unit,
    0.5);
isSame =
    ISEQUALF(
        NMUnitGetValue(unit),
        0.5);
if (isSame != true) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitSetValue failed");
    PBErrCatch(NeuraMorphErr);

}

NMUnitPrintln(
    unit,
    stdout);

NeuraMorphUnitFree(&unit);
VecFree(&iIn);
VecFree(&iOut);
printf("UnitTestNeuraMorphUnitGetSetPrint OK\n");

}

void UnitTestNeuraMorphUnitEvaluate() {

    VecLong* iIn = VecLongCreate(3);
    VecLong* iOut = VecLongCreate(2);
    NeuraMorphUnit* unit =
        NeuraMorphUnitCreate(
            iIn,
            iOut);

    for (
        long iInput = 3;
        iInput--;) {

        VecSet(
            unit->lowFilters,
            iInput + 1,
            0.0);
        VecSet(
            unit->highFilters,
            iInput + 1,
            2.0);

    }

    // iOutput == 0 -> 1.0+x+y+z+x^2+xy+xz+y^2+yz+z^2
    // iOutput == 1 -> x^2-xy+2xz+3y^2-4yz+5z^2
    float coeffs[2][10] = {

        { 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0},
        { 0.0, 0.0, 1.0, 0.0, -1.0, 3.0, 0.0, 2.0, -4.0, 5.0}
    }

```

```

};
for (
    long iOutput = 2;
    iOutput--;) {

    for (
        long iCoeff = 10;
        iCoeff--;) {

        VecSet(
            unit->coeffs[iOutput],
            iCoeff,
            coeffs[iOutput][iCoeff]);

    }

}

VecFloat* inputs = VecFloatCreate(3);
VecSet(
    inputs,
    0,
    1.0);
VecSet(
    inputs,
    1,
    3.0);
VecSet(
    inputs,
    2,
    1.5);

NMUnitEvaluate(
    unit,
    inputs);

float check[2];
float x = 1.0;
float y = 0.0;
float z = 1.5;
check[0] = 1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z;
check[1] =
    x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z;
VecFloat2D checkHigh = VecFloatCreateStatic2D();
VecSet(
    &checkHigh,
    0,
    check[0]);
VecSet(
    &checkHigh,
    1,
    check[1]);
VecFloat2D checkLow = checkHigh;
for (
    long iOutput = 2;
    iOutput--;) {

    float v =
        VecGet(
            unit->outputs,
            iOutput);
    bool same =

```

```

ISEQUALF(
    v,
    check[iOutput]);
if (same == false) {

    NeuroMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuroMorphErr->_msg,
        "NMUnitEvaluate failed (1)");
    PBErrCatch(NeuroMorphErr);

}

}

bool sameLow =
    VecIsEqual(
        &checkLow,
        unit->lowOutputs);
bool sameHigh =
    VecIsEqual(
        &checkHigh,
        unit->highOutputs);
if (
    sameLow == false ||
    sameHigh == false) {

    NeuroMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuroMorphErr->_msg,
        "NMUnitEvaluate failed (2)");
    PBErrCatch(NeuroMorphErr);

}

NeuroMorphUnitFree(&unit);
VecFree(&iIn);
VecFree(&iOut);
VecFree(&inputs);
printf("UnitTestNeuroMorphUnitEvaluate OK\n");

}

void UnitTestNeuroMorphUnit() {

    UnitTestNeuroMorphUnitCreateFree();
    UnitTestNeuroMorphUnitGetSetPrint();
    UnitTestNeuroMorphUnitEvaluate();
    printf("UnitTestNeuroMorphUnit OK\n");

}

void UnitTestNeuroMorphCreateFree() {

    NeuroMorph* nm =
        NeuroMorphCreate(
            3,
            2);
    if (
        nm->nbInput != 3 ||
        nm->nbOutput != 2 ||
        VecGetDim(nm->inputs) != 3 ||

```



```

    VecGetDim(nm->outputs) != 2 ||
    nm->hiddens != NULL ||
    GSetNbElem(&(nm->units)) != 0) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NeuraMorphCreate failed");
    PBErrCatch(NeuraMorphErr);

}

NeuraMorphFree(&nm);
if (nm != NULL) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NeuraMorphFree failed");
    PBErrCatch(NeuraMorphErr);

}

printf("UnitTestNeuraMorphCreateFree OK\n");
}

void UnitTestNeuraMorphGetSet() {

    NeuraMorph* nm =
        NeuraMorphCreate(
            3,
            2);
    if (NMGetNbInput(nm) != 3) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NMGetNbInput failed");
        PBErrCatch(NeuraMorphErr);

    }

    if (NMGetNbOutput(nm) != 2) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NMGetNbOutput failed");
        PBErrCatch(NeuraMorphErr);

    }

    if (NMGetNbHidden(nm) != 0) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NMGetNbHidden failed");
        PBErrCatch(NeuraMorphErr);

    }

}

```

```

NMSetNbHidden(
    nm,
    5);
if (NMGetNbHidden(nm) != 5) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMSetNbHidden failed");
    PBErrCatch(NeuraMorphErr);

}

VecLong* iOuts = NMGetVecIOutputs(nm);
VecLong2D checkOuts =
    VecLongCreateStatic2D();
VecSet(
    &checkOuts,
    0,
    5);
VecSet(
    &checkOuts,
    1,
    6);
bool isSame =
    VecIsEqual(
        &checkOuts,
        iOuts);
if (isSame == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMGetVecIOutputs failed");
    PBErrCatch(NeuraMorphErr);

}

VecFree(&iOuts);

if (NMInputs(nm) != nm->inputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMInputs failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMOutputs(nm) != nm->outputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMOutputs failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMHiddens(nm) != nm->hiddens) {

```

```

    NeuroMorphErr->_type = PErrTypeUnitTestFailed;
    sprintf(
        NeuroMorphErr->_msg,
        "NMHiddens failed");
    PErrCatch(NeuroMorphErr);

}

NeuraMorphFree(&nm);

printf("UnitTestNeuraMorphGetSet OK\n");

}

void UnitTestNeuraMorphAddRemoveUnit() {

    VecLong3D iInputs = VecLongCreateStatic3D();
    VecSet(
        &iInputs,
        0,
        0);
    VecSet(
        &iInputs,
        1,
        1);
    VecSet(
        &iInputs,
        2,
        2);
    VecLong2D iOutputs = VecLongCreateStatic2D();
    VecSet(
        &iOutputs,
        0,
        0);
    VecSet(
        &iOutputs,
        1,
        1);

    NeuroMorph* nm =
        NeuroMorphCreate(
            3,
            2);

    NeuroMorphUnit* unit =
        NMAddUnit(
            nm,
            (VecLong*)&iInputs,
            (VecLong*)&iOutputs);

    bool isSameA =
        VecIsEqual(
            &iInputs,
            unit->iInputs);
    bool isSameB =
        VecIsEqual(
            &iOutputs,
            unit->iOutputs);
    if (
        GSetNbElem(&(nm->units)) != 1 ||
        GSetHead(&(nm->units)) != unit ||

```

```

    isSameA == false ||
    isSameB == false) {

    NeuroMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuroMorphErr->_msg,
        "NMAddUnit failed");
    PBErrCatch(NeuroMorphErr);

}

NeuraMorphFree(&nm);

nm =
    NeuroMorphCreate(
        3,
        2);

unit =
    NMAddUnit(
        nm,
        (VecLong*)&iInputs,
        (VecLong*)&iOutputs);

NMRemoveUnit(
    nm,
    unit);

if (GSetNbElem(&(nm->units)) != 0) {

    NeuroMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuroMorphErr->_msg,
        "NMRemoveUnit failed");
    PBErrCatch(NeuroMorphErr);

}

NeuraMorphUnitFree(&unit);
NeuraMorphFree(&nm);

printf("UnitTestNeuraMorphAddRemoveUnit OK\n");

}

void UnitTestNeuraMorphBurryUnitsEvaluate() {

    VecLong3D iInputs = VecLongCreateStatic3D();
    VecSet(
        &iInputs,
        0,
        0);
    VecSet(
        &iInputs,
        1,
        1);
    VecSet(
        &iInputs,
        2,
        2);
    VecLong2D iOutputs = VecLongCreateStatic2D();
    VecSet(

```

```

        &iOutputs,
        0,
        0);
VecSet(
    &iOutputs,
    1,
    1);

NeuraMorph* nm =
    NeuraMorphCreate(
        3,
        2);

NeuraMorphUnit* unitA =
    NeuraMorphUnitCreate(
        (VecLong*)&iInputs,
        (VecLong*)&iOutputs);

NeuraMorphUnit* unitB =
    NeuraMorphUnitCreate(
        (VecLong*)&iInputs,
        (VecLong*)&iOutputs);

for (
    long iInput = 3;
    iInput--;) {

    VecSet(
        unitA->lowFilters,
        iInput + 1,
        0.0);
    VecSet(
        unitA->highFilters,
        iInput + 1,
        2.0);
    VecSet(
        unitB->lowFilters,
        iInput + 1,
        0.0);
    VecSet(
        unitB->highFilters,
        iInput + 1,
        2.0);

}

float coeffsA[2][10] = {

    { 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0},
    { 0.0, 0.0, 1.0, 0.0, -1.0, 3.0, 0.0, 2.0, -4.0, 5.0}

};

float coeffsB[2][10] = {

    { 0.0, 0.0, 1.0, 0.0, -1.0, 3.0, 0.0, 2.0, -4.0, 5.0},
    { 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0}

};

for (
    long iOutput = 2;
    iOutput--;) {

```

```

for (
    long iCoeff = 10;
    iCoeff--;) {

    VecSet(
        unitA->coeffs[iOutput],
        iCoeff,
        coeffsA[iOutput][iCoeff]);

    VecSet(
        unitB->coeffs[iOutput],
        iCoeff,
        coeffsB[iOutput][iCoeff]);

}

}

float x = 1.0;
float y = 0.5;
float z = 1.5;
VecFloat* evalInputs = VecFloatCreate(3);
VecSet(
    evalInputs,
    0,
    x);
VecSet(
    evalInputs,
    1,
    y);
VecSet(
    evalInputs,
    2,
    z);

NMUnitEvaluate(
    unitA,
    evalInputs);
NMUnitEvaluate(
    unitB,
    evalInputs);

GSet units = GSetCreateStatic();
GSetAppend(
    &units,
    unitA);
GSetAppend(
    &units,
    unitB);

NMBurryUnits(
    nm,
    &units);

if (
    GSetNbElem(&units) != 0 ||
    nm->hiddens == NULL ||
    VecGetDim(nm->hiddens) != 4) {

    NeuraMorphErr->_type = PErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,

```

```

        "NMBurryUnits failed (1)");
    PBErrCatch(NeuraMorphErr);
}

VecLong2D checkA = VecLongCreateStatic2D();
VecSet(
    &checkA,
    0,
    0);
VecSet(
    &checkA,
    1,
    1);
VecLong2D checkB = VecLongCreateStatic2D();
VecSet(
    &checkB,
    0,
    2);
VecSet(
    &checkB,
    1,
    3);

bool isSameA =
    VecIsEqual(
        &checkA,
        unitA->iOutputs);
bool isSameB =
    VecIsEqual(
        &checkB,
        unitB->iOutputs);
if (
    isSameA == false ||
    isSameB == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMBurryUnits failed (2)");
    PBErrCatch(NeuraMorphErr);
}

float checkLowAa =
    VecGet(
        unitA->lowOutputs,
        0);
checkLowAa -=
    VecGet(
        nm->lowHiddens,
        0);
bool isSameLowAa =
    ISEQUALF(
        checkLowAa,
        0.0);
float checkLowAb =
    VecGet(
        unitA->lowOutputs,
        1);
checkLowAb -=
    VecGet(

```

```

        nm->lowHiddens,
        1);
bool isSameLowAb =
    ISEQUALF(
        checkLowAb,
        0.0);
float checkLowBa =
    VecGet(
        unitB->lowOutputs,
        0);
checkLowBa -=
    VecGet(
        nm->lowHiddens,
        2);
bool isSameLowBa =
    ISEQUALF(
        checkLowBa,
        0.0);
float checkLowBb =
    VecGet(
        unitB->lowOutputs,
        1);
checkLowBb -=
    VecGet(
        nm->lowHiddens,
        3);
bool isSameLowBb =
    ISEQUALF(
        checkLowBb,
        0.0);
float checkHighAa =
    VecGet(
        unitA->lowOutputs,
        0);
checkHighAa -=
    VecGet(
        nm->lowHiddens,
        0);
bool isSameHighAa =
    ISEQUALF(
        checkHighAa,
        0.0);
float checkHighAb =
    VecGet(
        unitA->lowOutputs,
        1);
checkHighAb -=
    VecGet(
        nm->lowHiddens,
        1);
bool isSameHighAb =
    ISEQUALF(
        checkHighAb,
        0.0);
float checkHighBa =
    VecGet(
        unitB->lowOutputs,
        0);
checkHighBa -=
    VecGet(
        nm->lowHiddens,
        2);

```



```

bool isSameHighBa =
    ISEQUALF(
        checkHighBa,
        0.0);
float checkHighBb =
    VecGet(
        unitB->lowOutputs,
        1);
checkHighBb -=
    VecGet(
        nm->lowHiddens,
        3);
bool isSameHighBb =
    ISEQUALF(
        checkHighBb,
        0.0);
if (
    isSameLowAa == false ||
    isSameLowAb == false ||
    isSameLowBa == false ||
    isSameLowBb == false ||
    isSameHighAa == false ||
    isSameHighAb == false ||
    isSameHighBa == false ||
    isSameHighBb == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMBurryUnits failed (3)");
    PBErrCatch(NeuraMorphErr);

}

VecSet(
    &iInputs,
    0,
    3);
VecSet(
    &iInputs,
    1,
    4);
VecSet(
    &iInputs,
    2,
    5);
VecSet(
    &iOutputs,
    0,
    4);
VecSet(
    &iOutputs,
    1,
    5);
NeuraMorphUnit* unitC =
    NMAddUnit(
        nm,
        (VecLong*)&iInputs,
        (VecLong*)&iOutputs);

for (
    long iInput = 3;

```

```

    iInput--;) {

    VecSet(
        unitC->lowFilters,
        iInput + 1,
        0.0);
    VecSet(
        unitC->highFilters,
        iInput + 1,
        20.0);

}

float coeffsC[2][10] = {

    { 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0},
    { 0.0, 0.0, 1.0, 0.0, -1.0, 3.0, 0.0, 2.0, -4.0, 5.0}

};

for (
    long iOutput = 2;
    iOutput--;) {

    for (
        long iCoeff = 10;
        iCoeff--;) {

        VecSet(
            unitC->coeffs[iOutput],
            iCoeff,
            coeffsC[iOutput][iCoeff]);

    }

}

NMEvaluate(
    nm,
    evalInputs);

float checkAout[2];
checkAout[0] =
    1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z -
    VecGet(
        nm->hiddens,
        0);
checkAout[1] =
    x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z -
    VecGet(
        nm->hiddens,
        1);
float checkBout[2];
checkBout[0] =
    x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z -
    VecGet(
        nm->hiddens,
        2);
checkBout[1] =
    1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z -
    VecGet(
        nm->hiddens,
        3);

```

```

bool isSameAa =
    ISEQUALF(
        checkAout[0],
        0.0);
bool isSameAb =
    ISEQUALF(
        checkAout[1],
        0.0);
bool isSameBa =
    ISEQUALF(
        checkBout[0],
        0.0);
bool isSameBb =
    ISEQUALF(
        checkBout[1],
        0.0);
if (
    isSameAa == false ||
    isSameAb == false ||
    isSameBa == false ||
    isSameBb == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMEvaluate failed (1)");
    PBErrCatch(NeuraMorphErr);

}

x =
    VecGet(
        nm->hiddens,
        0);
y =
    VecGet(
        nm->hiddens,
        1);
z =
    VecGet(
        nm->hiddens,
        2);
float checkCout[2];
checkCout[0] =
    1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z -
    VecGet(
        unitC->outputs,
        0);
checkCout[1] =
    x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z -
    VecGet(
        unitC->outputs,
        1);

bool isSameCa =
    ISEQUALF(
        checkCout[0],
        0.0);
bool isSameCb =
    ISEQUALF(
        checkCout[1],

```

```

    0.0);
    bool isSameCc =
        VecIsEqual(
            unitC->outputs,
            nm->outputs);
    if (
        isSameCa == false ||
        isSameCb == false ||
        isSameCc == false) {

        NeuroMorphErr->_type = PErrTypeUnitTestFailed;
        sprintf(
            NeuroMorphErr->_msg,
            "NMEvaluate failed (2)");
        PErrCatch(NeuroMorphErr);

    }

    VecFree(&evalInputs);
    NeuroMorphFree(&nm);

    printf("UnitTestNeuraMorphBurryUnitsEvaluate OK\n");
}

void UnitTestNeuraMorph() {

    UnitTestNeuraMorphCreateFree();
    UnitTestNeuraMorphGetSet();
    UnitTestNeuraMorphAddRemoveUnit();
    UnitTestNeuraMorphBurryUnitsEvaluate();
    printf("UnitTestNeuraMorph OK\n");

}

void UnitTestNeuraMorphTrainerCreateFree() {

    GDataSetVecFloat dataset =
        GDataSetVecFloatCreateStaticFromFile("./Datasets/iris.json");
    NeuroMorph* nm =
        NeuroMorphCreate(
            GDSGetNbInputs(&dataset),
            GDSGetNbOutputs(&dataset));
    NeuroMorphTrainer trainer =
        NeuroMorphTrainerCreateStatic(
            nm,
            &dataset);
    bool isSame =
        ISEQUALF(
            trainer.weakUnitThreshold,
            0.9);
    if (
        trainer.neuraMorph != nm ||
        trainer.depth != 2 ||
        isSame != true ||
        trainer.iCatTraining != 0 ||
        trainer.dataset != &dataset) {

        NeuroMorphErr->_type = PErrTypeUnitTestFailed;
        sprintf(
            NeuroMorphErr->_msg,
            "NeuraMorphTrainerCreateStatic failed");
    }
}

```

```

        PBErCatch(NeuraMorphErr);
    }

    NeuraMorphTrainerFreeStatic(&trainer);
    NeuraMorphFree(&nm);
    GDataSetVecFloatFreeStatic(&dataset);

    printf("UnitTestNeuraMorphTrainerCreateFree OK\n");
}

void UnitTestNeuraMorphTrainerGetSet() {

    GDataSetVecFloat dataset =
        GDataSetVecFloatCreateStaticFromFile("./Datasets/iris.json");
    NeuraMorph* nm =
        NeuraMorphCreate(
            GDSGetNbInputs(&dataset),
            GDSGetNbOutputs(&dataset));
    NeuraMorphTrainer trainer =
        NeuraMorphTrainerCreateStatic(
            nm,
            &dataset);
    if (NMTrainerGetDepth(&trainer) != 2) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NeuraMorphTrainerGetDepth failed");
        PBErCatch(NeuraMorphErr);
    }

    if (NMTrainerGetICatTraining(&trainer) != 0) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NeuraMorphTrainerGetICatTraining failed");
        PBErCatch(NeuraMorphErr);
    }

    bool isSame =
        ISEQUALF(
            NMTrainerGetWeakThreshold(&trainer),
            0.9);
    if (isSame != true) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NeuraMorphTrainerGetWeakThreshold failed");
        PBErCatch(NeuraMorphErr);
    }

    NMTrainerSetDepth(
        &trainer,
        3);
    if (NMTrainerGetDepth(&trainer) != 3) {

```

```

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NeuraMorphTrainerSetDepth failed");
        PBErrCatch(NeuraMorphErr);
    }

    NMTrainerSetICatTraining(
        &trainer,
        3);
    if (NMTrainerGetICatTraining(&trainer) != 3) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NeuraMorphTrainerSetICatTraining failed");
        PBErrCatch(NeuraMorphErr);
    }

    NMTrainerSetWeakThreshold(
        &trainer,
        0.5);
    isSame =
        ISEQUALF(
            NMTrainerGetWeakThreshold(&trainer),
            0.5);
    if (isSame != true) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NeuraMorphTrainerSetWeakThreshold failed");
        PBErrCatch(NeuraMorphErr);
    }

    NeuraMorphTrainerFreeStatic(&trainer);
    NeuraMorphFree(&nm);
    GDataSetVecFloatFreeStatic(&dataset);

    printf("UnitTestNeuraMorphTrainerGetSet OK\n");
}

void UnitTestNeuraMorphTrainerRun() {

    GDataSetVecFloat dataset =
        GDataSetVecFloatCreateStaticFromFile("./Datasets/iris.json");
    NeuraMorph* nm =
        NeuraMorphCreate(
            GDSGetNbInputs(&dataset),
            GDSGetNbOutputs(&dataset));
    NeuraMorphTrainer trainer =
        NeuraMorphTrainerCreateStatic(
            nm,
            &dataset);

    NMTrainerRun(&trainer);
}

```

```

    NeuraMorphTrainerFreeStatic(&trainer);
    NeuraMorphFree(&nm);
    GDataSetVecFloatFreeStatic(&dataset);

    printf("UnitTestNeuraMorphTrainerRun OK\n");
}

void UnitTestNeuraMorphTrainer() {

    UnitTestNeuraMorphTrainerCreateFree();
    UnitTestNeuraMorphTrainerGetSet();
    UnitTestNeuraMorphTrainerRun();
    printf("UnitTestNeuraMorphTrainer OK\n");
}

void UnitTestAll() {

    UnitTestNeuraMorphUnit();
    UnitTestNeuraMorph();
    UnitTestNeuraMorphTrainer();
    printf("UnitTestAll OK\n");
}

int main() {

    UnitTestAll();

    // Return success code
    return 0;
}

```

6 Unit tests output

```

UnitTestNeuraMorphUnitCreateFree OK
<0,0,0> -> <0,0> (0.500000)
UnitTestNeuraMorphUnitGetSetPrint OK
UnitTestNeuraMorphUnitEvaluate OK
UnitTestNeuraMorphUnit OK
UnitTestNeuraMorphCreateFree OK
UnitTestNeuraMorphGetSet OK
UnitTestNeuraMorphAddRemoveUnit OK
UnitTestNeuraMorphBurrryUnitsEvaluate OK
UnitTestNeuraMorph OK
UnitTestNeuraMorphTrainerCreateFree OK
UnitTestNeuraMorphTrainerGetSet OK
Depth 1/2...
Nb available inputs: 4
Train units with 0001 inputs
Train units with 0002 inputs
Train units with 0003 inputs
Train units with 0004 inputs
Burrry 2 out of 15 units
<0,1> -> <0,1,2> (1957747840.000000)
<0,1,2,3> -> <0,1,2> (2044897792.000000)
Depth 2/2...

```

```
Nb available inputs: 10
Train units with 0001 inputs
Train units with 0002 inputs
Train units with 0003 inputs
Train units with 0004 inputs
Train units with 0005 inputs
Train units with 0006 inputs
Train units with 0007 inputs
Train units with 0008 inputs
Train units with 0009 inputs
Train units with 0010 inputs
Add the last unit
<4,7,9> -> <6,7,8> (2147469824.000000)
UnitTestNeuraMorphTrainerRun OK
UnitTestNeuraMorphTrainer OK
UnitTestAll OK
```