

NeuraMorph

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Introduction

NeuraMorph is a C library providing structures and functions to implement a neural network.

It uses the PBErr, PBMath, GSet library.

1 Definitions

2 Interface

```
// ===== NEURAMORPH.H =====
```

```

#ifndef NEURAMORPH_H
#define NEURAMORPH_H

// ===== Include =====

#include <stdlib.h>
#include <stdio.h>
#include <math.h>
#include <string.h>
#include <stdbool.h>
#include "pberr.h"
#include "pbmath.h"
#include "gset.h"
#include "gdataset.h"

// ---- NeuraMorphUnit

// ===== Data structure =====

typedef struct NeuraMorphUnit {

    // Input indices in parent NeuraMorph
    VecLong* iInputs;

    // Output indices in parent NeuraMorph
    VecLong* iOutputs;

    // Lowest and highest values for filtering inputs
    VecFloat* lowFilters;
    VecFloat* highFilters;

    // Lowest and highest values of outputs
    VecFloat* lowOutputs;
    VecFloat* highOutputs;

    // Vector to memorize the output values
    VecFloat* outputs;

    // Transfer function coefficients
    // Seen as (nb output) triangular matrices of size (nb input + 1)
    VecFloat** coeffs;

    // Working variables to avoid reallocation of memory at each Evaluate()
    bool* activeInputs;
    VecFloat* unitInputs;

} NeuraMorphUnit;

// ===== Functions declaration =====

// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
    const VecLong* iInputs,
    const VecLong* iOutputs);

// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that);

// Get the input indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline

```

```

#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that);

// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that);

// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that);

// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
    NeuraMorphUnit* that,
    const VecFloat* inputs);

// Get the number of input values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbInputs(const NeuraMorphUnit* that);

// Get the number of output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbOutputs(const NeuraMorphUnit* that);

// ----- NeuraMorph

// ===== Data structure =====

typedef struct NeuraMorph {

    // Number of inputs and outputs
    long nbInput;
    long nbOutput;

    // Inputs and outputs values
    VecFloat* inputs;
    VecFloat* outputs;

    // Internal values
    VecFloat* hiddens;

    // Lowest and highest values for internal values
    VecFloat* lowHiddens;
    VecFloat* highHiddens;

    // GSet of NeuraMorphUnit
    GSet units;

} NeuraMorph;

// ===== Functions declaration =====

// Create a new NeuraMorph with 'nbInput' inputs and 'nbOutput' outputs

```

```

NeuraMorph* NeuraMorphCreate(
    long nbInput,
    long nbOutput);

// Free the memory used by the NeuraMorph 'that'
void NeuraMorphFree(NeuraMorph** that);

// Get the number of input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbInput(const NeuraMorph* that);

// Get the number of output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbOutput(const NeuraMorph* that);

// Get the input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
VecFloat* NMInputs(NeuraMorph* that);

// Get the output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMOutputs(const NeuraMorph* that);

// Get the number of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbHidden(const NeuraMorph* that);

// Set the number of hidden values of the NeuraMorph 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void NMSetNbHidden(
    NeuraMorph* that,
    long nb);

// Add one NeuraMorphUnit with input and output indices 'iInputs'
// and 'iOutputs' to the NeuraMorph 'that'
// Return the created NeuraMorphUnit
NeuraMorphUnit* NMAddUnit(
    NeuraMorph* that,
    const VecLong* iInputs,
    const VecLong* iOutputs);

// Remove the NeuraMorphUnit 'unit' from the NeuraMorph 'that'
// The NeuraMorphUnit is not freed
void NMRemoveUnit(
    NeuraMorph* that,
    NeuraMorphUnit* unit);

// Burry the NeuraMorphUnits in the 'units' set into the
// NeuraMorph 'that'
// 'units' is empty after calling this function

```

```

// The NeuraMorphUnits iOutputs must point toward the NeuraMorph
// outputs
// NeuraMorphUnits' iOutputs are redirected toward new hidden values
// 'that->hiddens' is resized as necessary
void NMBurryUnits(
    NeuraMorph* that,
    GSet* units);

// Get a new vector with indices of the outputs in the NeuraMorph 'that'
VecLong* NMGetVecIOutputs(const NeuraMorph* that);

// Evaluate the NeuraMorph 'that' on the 'inputs' values
void NMEvaluate(
    NeuraMorph* that,
    VecFloat* inputs);

// ----- NeuraMorphTrainer

// ===== Data structure =====

typedef struct NeuraMorphTrainer {

    // Trained NeuraMorph
    NeuraMorph* neuraMorph;

    // Training dataset
    GDataSetVecFloat* dataset;

    // Index of the dataset's category used for training
    unsigned int iCatTraining;

    // Depth of the training
    short depth;

} NeuraMorphTrainer;

// ===== Functions declaration =====

// Create a static NeuraMorphTrainer for the NeuraMorph 'neuraMorph' and the
// GDataSet 'dataset'
// Default depth: 2
NeuraMorphTrainer NeuraMorphTrainerCreateStatic(
    NeuraMorph* neuraMorph,
    GDataSetVecFloat* dataset);

// Free the memory used by the static NeuraMorphTrainer 'that'
void NeuraMorphTrainerFreeStatic(NeuraMorphTrainer* that);

// Run the training process for the NeuraMorphTrainer 'that'
void NMTrainerRun(NeuraMorphTrainer* that);

// Get the depth of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
short NMTrainerGetDepth(const NeuraMorphTrainer* that);

// Set the depth of the NeuraMorphTrainer 'that' to 'depth'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetDepth(

```

```

        NeuraMorphTrainer* that,
            short depth);

// Get the index of the training category of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
unsigned int NMTrainerGetICatTraining(const NeuraMorphTrainer* that);

// Set the index of the training category of the NeuraMorphTrainer 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetICatTraining(
    NeuraMorphTrainer* that,
    unsigned int iCatTraining);

// Get the NeuraMorph of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
NeuraMorph* NMTrainerNeuraMorph(const NeuraMorphTrainer* that);

// Get the GDataSet of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
GDataSetVecFloat* NMTrainerDataset(const NeuraMorphTrainer* that);

// ===== static inliner =====

#if BUILDMODE != 0
#include "neuramorph-inline.c"
#endif

#endif

```

3 Code

3.1 neuramorph.c

```

// ===== NEURAMORPH.C =====

// ===== Include =====

#include "neuramorph.h"
#if BUILDMODE == 0
#include "neuramorph-inline.c"
#endif

// ----- NeuraMorphUnit

// ===== Functions declaration =====

// Return the number of coefficients of a NeuraMorphUnit having 'nbIn' inputs
long NMUnitGetNbCoeff(long nbIn);

```

```

// Get the coefficient for the pair of inputs 'iInputA', 'iInputB' in the
// NeuraMorphUnit 'that' for the output 'iOutput'
float NMUnitGetCoeff(
    const NeuraMorphUnit* that,
        long iInputA,
        long iInputB,
        long iOutput);

// Update the low and high of the hiddens of the NeuraMorph 'that' with
// the low and high of its units
void NMUpdateLowHighHiddens(NeuraMorph* that);

// ===== Functions implementation =====

// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
    const VecLong* iInputs,
    const VecLong* iOutputs) {

#if BUILDMODE == 0

    if (iInputs == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'iInputs' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (iOutputs == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'iOutputs' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    // Allocate memory for the NeuraMorphUnit
    NeuraMorphUnit* that =
        PBErrMalloc(
            NeuraMorphErr,
            sizeof(NeuraMorphUnit));

    // Get the number of inputs (including the constant) and outputs
    long nbIn = VecGetDim(iInputs) + 1;
    long nbOut = VecGetDim(iOutputs);

    // Init properties
    that->iInputs = VecClone(iInputs);
    that->iOutputs = VecClone(iOutputs);
    that->lowFilters = VecFloatCreate(nbIn);
    that->highFilters = VecFloatCreate(nbIn);
    that->lowOutputs = NULL;
    that->highOutputs = NULL;
    that->outputs = VecFloatCreate(nbOut);

```

```

that->coeffs =
    PBErrMalloc(
        NeuraMorphErr,
        sizeof(VecFloat*) * nbOut);
long nbCoeff = NMUnitGetNbCoeff(nbIn);
for (
    long iOut = nbOut;
    iOut--;
    that->coeffs[iOut] = VecFloatCreate(nbCoeff));

// 'nbIn + 1' for the constant
that->activeInputs =
    PBErrMalloc(
        NeuraMorphErr,
        sizeof(bool) * nbIn);
that->unitInputs = VecFloatCreate(nbIn);

// Set the input value, filters and active flag for the constant
VecSet(
    that->unitInputs,
    0,
    1.0);
that->activeInputs[0] = true;

// Return the new NeuraMorphUnit
return that;
}

// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that) {

    // Check the input
    if (that == NULL || *that == NULL) {

        return;
    }

    // Free memory
    long nbOut = VecGetDim((*that)->iOutputs);
    VecFree(&((*that)->iInputs));
    VecFree(&((*that)->iOutputs));
    VecFree(&((*that)->lowFilters));
    VecFree(&((*that)->highFilters));
    if ((*that)->lowOutputs != NULL) {

        VecFree(&((*that)->lowOutputs));
    }

    if ((*that)->highOutputs != NULL) {

        VecFree(&((*that)->highOutputs));
    }

    VecFree(&((*that)->outputs));
    for (
        long iOut = nbOut;
        iOut--;
        VecFree((*that)->coeffs + iOut));
}

```



```

    free((*that)->coeffs);
    free((*that)->activeInputs);
    VecFree(&((*that)->unitInputs));
    free(*that);
    *that = NULL;
}

// Return the number of coefficients of a NeuraMorphUnit having 'nbIn' inputs
long NMUnitGetNbCoeff(long nbIn) {

#if BUILDMODE == 0

    if (nbIn <= 0) {

        NeuraMorphErr->_type = PBErrTypeInvalidArg;
        sprintf(
            NeuraMorphErr->_msg,
            "'nbIn' is invalid (%ld>0)",
            nbIn);
        PBErrCatch(NeuraMorphErr);

    }

#endif

    // Declare a variable to memorise the result
    long nb = 0;

    // Calculate the number of values in the triangular matrix of size
    // nbIn
    for (
        long i = nbIn;
        i >= 0;
        nb += (i--));

    // Return the result
    return nb;
}

// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
    NeuraMorphUnit* that,
    const VecFloat* inputs) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (VecGetDim(inputs) != VecGetDim(that->iInputs)) {

        NeuraMorphErr->_type = PBErrTypeInvalidArg;

```

```

    sprintf(
        NeuraMorphErr->_msg,
        "'inputs' has invalid dimension (%ld!=%ld)",
        VecGetDim(inputs),
        VecGetDim(that->iInputs));
    PBErrCatch(NeuraMorphErr);

}

#endif

// Reset the outputs
VecSetNull(that->outputs);

// Update the active flags and scaled inputs (skip the constant)
for (
    long iInput = 1;
    iInput < VecGetDim(that->unitInputs);
    ++iInput) {

    // Get the input value and its low/high filters
    float val =
        VecGet(
            inputs,
            iInput - 1);
    float low =
        VecGet(
            that->lowFilters,
            iInput);
    float high =
        VecGet(
            that->highFilters,
            iInput);

    // If the value is inside the filter
    if (
        low <= val &&
        val <= high &&
        (high - low) > PBMath_EPSILON) {

        // Set this value as active
        that->activeInputs[iInput] = true;

        // Set the value in the unit inputs
        VecSet(
            that->unitInputs,
            iInput,
            val);

    // Else the value is outside the filter
    } else {

        // Set this value as inactive
        that->activeInputs[iInput] = false;

    }

}

// Loop on the pair of active inputs
for (
    long iInputA = 0;

```

```

iInputA < VecGetDim(that->unitInputs);
++iInputA) {

if (that->activeInputs[iInputA] == true) {

    for (
        long iInputB = 0;
        iInputB <= iInputA;
        ++iInputB) {

        if (that->activeInputs[iInputB] == true) {

            // Loop on the outputs
            for (
                long iOutput = 0;
                iOutput < VecGetDim(that->outputs);
                ++iOutput) {

                // Calculate the components for this output and pair of inputs
                float comp =
                    VecGet(
                        that->unitInputs,
                        iInputA) *
                    VecGet(
                        that->unitInputs,
                        iInputB) *
                    NMUnitGetCoeff(
                        that,
                        iInputA,
                        iInputB,
                        iOutput);

                // Add the component to the output
                float cur =
                    VecGet(
                        that->outputs,
                        iOutput);
                VecSet(
                    that->outputs,
                    iOutput,
                    cur + comp);

            }

        }

    }

}

// If the low and high values for outputs don't exist yet
if (that->lowOutputs == NULL) {

    // Create the low and high values by cloning the current output
    that->lowOutputs = VecClone(that->outputs);
    that->highOutputs = VecClone(that->outputs);

// Else, the low and high values for outputs exist
} else {

```

```

// Loop on the outputs
for (
    long iOutput = 0;
    iOutput < VecGetDim(that->outputs);
    ++iOutput) {

    // Update the low and high values for this output
    float val =
        VecGet(
            that->outputs,
            iOutput);

    float curLow =
        VecGet(
            that->lowOutputs,
            iOutput);
    if (curLow > val) {

        VecSet(
            that->lowOutputs,
            iOutput,
            val);

    }

    float curHigh =
        VecGet(
            that->highOutputs,
            iOutput);
    if (curHigh < val) {

        VecSet(
            that->highOutputs,
            iOutput,
            val);

    }

}

}

}

// Get the coefficient for the pair of inputs 'iInputA', 'iInputB' in the
// NeuraMorphUnit 'that' for the output 'iOutput'
float NMUnitGetCoeff(
    const NeuraMorphUnit* that,
        long iInputA,
        long iInputB,
        long iOutput) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);
    }

```

```

}

if (
    iInputA < 0 ||
    iInputA >= VecGetDim(that->unitInputs)) {

    NeuraMorphErr->_type = PErrTypeInvalidArg;
    sprintf(
        NeuraMorphErr->_msg,
        "'iInputA' is invalid (0<=%ld<%ld)",
        iInputA,
        VecGetDim(that->unitInputs));
    PErrCatch(NeuraMorphErr);

}

if (
    iInputB < 0 ||
    iInputB >= VecGetDim(that->unitInputs)) {

    NeuraMorphErr->_type = PErrTypeInvalidArg;
    sprintf(
        NeuraMorphErr->_msg,
        "'iInputB' is invalid (0<=%ld<%ld)",
        iInputB,
        VecGetDim(that->unitInputs));
    PErrCatch(NeuraMorphErr);

}

if (iInputA < iInputB) {

    NeuraMorphErr->_type = PErrTypeInvalidArg;
    sprintf(
        NeuraMorphErr->_msg,
        "The pair of indices is invalid (%ld>=%ld)",
        iInputA,
        iInputB);
    PErrCatch(NeuraMorphErr);

}

if (
    iOutput < 0 ||
    iOutput >= VecGetDim(that->outputs)) {

    NeuraMorphErr->_type = PErrTypeInvalidArg;
    sprintf(
        NeuraMorphErr->_msg,
        "'iInputB' is invalid (0<=%ld<%ld)",
        iInputB,
        VecGetDim(that->outputs));
    PErrCatch(NeuraMorphErr);

}

#endif

// Calculate the index of the coefficient
long iCoeff = 0;
for (
    long shift = 0;

```

```

        shift < iInputA;
        iCoeff += (shift++) + 1);
iCoeff += iInputB;

// Return the coefficient
float coeff =
    VecGet(
        that->coeffs[iOutput],
        iCoeff);
return coeff;
}

// ----- NeuraMorph

// ===== Functions implementation =====

// Create a new NeuraMorph with 'nbInput' inputs and 'nbOutput' outputs
NeuraMorph* NeuraMorphCreate(
    long nbInput,
    long nbOutput) {

    // Allocate memory for the NeuraMorph
    NeuraMorph* that =
        PBErrMalloc(
            NeuraMorphErr,
            sizeof(NeuraMorph));

    // Init properties
    that->nbInput = nbInput;
    that->nbOutput = nbOutput;
    that->inputs = VecFloatCreate(nbInput);
    that->outputs = VecFloatCreate(nbOutput);
    that->hiddens = NULL;
    that->lowHiddens = NULL;
    that->highHiddens = NULL;
    that->units = GSetCreateStatic();

    // Return the NeuraMorph
    return that;
}

// Free the memory used by the NeuraMorph 'that'
void NeuraMorphFree(NeuraMorph** that) {

    // Check the input
    if (that == NULL || *that == NULL) {

        return;
    }

    // Free memory
    VecFree(&((*that)->inputs));
    VecFree(&((*that)->outputs));
    if ((*that)->hiddens != NULL) {

        VecFree(&((*that)->hiddens));
        VecFree(&((*that)->lowHiddens));
        VecFree(&((*that)->highHiddens));
    }
}

```

```

}

while (GSetNbElem(&((*that)->units)) > 0) {

    NeuroMorphUnit* unit = GSetPop(&((*that)->units));
    NeuroMorphUnitFree(&unit);

}

free(*that);
*that = NULL;

}

// Add one NeuroMorphUnit with input and output indices 'iInputs'
// and 'iOutputs' to the NeuroMorph 'that'
// Return the created NeuroMorphUnit
NeuroMorphUnit* NMAddUnit(
    NeuroMorph* that,
    const VecLong* iInputs,
    const VecLong* iOutputs) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuroMorphErr);

    }

    if (iInputs == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'iInputs' is null");
        PBErrCatch(NeuroMorphErr);

    }

    if (iOutputs == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'iOutputs' is null");
        PBErrCatch(NeuroMorphErr);

    }

#endif

    // Create the NeuroMorphUnit
    NeuroMorphUnit* unit =
        NeuroMorphUnitCreate(
            iInputs,
            iOutputs);

```

```

// Append the new NeuraorphUnit to the set of NeuraMorphUnit
GSetAppend(
    &(that->units),
    unit);

// Return the new unit
return unit;
}

// Remove the NeuraMorphUnit 'unit' from the NeuraMorph 'that'
// The NeuraMorphUnit is not freed
void NMRemoveUnit(
    NeuraMorph* that,
    NeuraMorphUnit* unit) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

// Remove the NeuraorphUnit from the set of NeuraMorphUnit
GSetRemoveAll(
    &(that->units),
    unit);
}

// Burry the NeuraMorphUnits in the 'units' set into the
// NeuraMorph 'that'
// 'units' is empty after calling this function
// The NeuraMorphUnits iOutputs must point toward the NeuraMorph
// outputs
// NeuraMorphUnits' iOutputs are redirected toward new hidden values
// 'that->hiddens' is resized as necessary
void NMBurryUnits(
    NeuraMorph* that,
    GSet* units) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif
}

```



```

// Declare a variable to memorize the number of hidden values
// to add
long nbHiddenValues = 0;

// While there are units to burry
while (GSetNbElem(units) > 0) {

    // Get the unit
    NeuraMorphUnit* unit = GSetPop(units);

    // Loop on the iOutputs of the unit
    for (
        long iOutput = 0;
        iOutput < VecGetDim(NMUnitIOOutputs(unit));
        ++iOutput) {

        long indice =
            VecGet(
                NMUnitIOOutputs(unit),
                iOutput);
        VecSet(
            unit->iOutputs,
            iOutput,
            indice + nbHiddenValues);

    }

    // Append the unit to the set of NeuraMorphUnit
    GSetAppend(
        &(that->units),
        unit);

    // Update the number of new hidden values
    nbHiddenValues += VecGetDim(NMUnitIOOutputs(unit));

}

// If there is already hidden values
if (that->hiddens != NULL) {

    // Add the previous number of hidden values
    nbHiddenValues += VecGetDim(that->hiddens);

    // Free memory
    VecFree(&(that->hiddens));
    VecFree(&(that->lowHiddens));
    VecFree(&(that->highHiddens));

}

// If there are hidden values after burrying
if (nbHiddenValues > 0) {

    // Resize the hiddens value vector
    that->hiddens = VecFloatCreate(nbHiddenValues);
    that->lowHiddens = VecFloatCreate(nbHiddenValues);
    that->highHiddens = VecFloatCreate(nbHiddenValues);

    // Update the low and high of the hiddens with the low and high
    // of the units
    NMUpdateLowHighHiddens(that);
}

```

```

    }

}

// Get a new vector with indices of the outputs in the NeuraMorph 'that'
VecLong* NMGetVecIOutputs(const NeuraMorph* that) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    // Allocate memory for the result
    VecLong* iOutputs = VecLongCreate(NMGetNbOutput(that));

    // Loop on indices
    for (
        long iOutput = 0;
        iOutput < NMGetNbOutput(that);
        ++iOutput) {

        // Set the indice of this output
        VecSet(
            iOutputs,
            iOutput,
            iOutput + NMGetNbHidden(that));

    }

    // Return the result
    return iOutputs;

}

// Update the low and high of the hiddens of the NeuraMorph 'that' with
// the low and high of its units
void NMUpdateLowHighHiddens(NeuraMorph* that) {

#ifdef BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    // Loop on the units

```

```

GSetIterForward iter =
    GSetIterForwardCreateStatic(&(that->units));
do {

    // Get the unit
    NeuraMorphUnit* unit = GSetIterGet(&iter);

    // Loop on the iOutputs of the unit
    for (
        long iOutput = 0;
        iOutput < VecGetDim(NMUnitIOOutputs(unit));
        ++iOutput) {

        // Get the indice
        long indice =
            VecGet(
                NMUnitIOOutputs(unit),
                iOutput);

        // If the indice points to a hidden value
        if (indice < NMGetNbHidden(that)) {

            // If the low and high exist
            if (
                unit->lowOutputs != NULL &&
                unit->highOutputs != NULL) {

                // Update the low and high
                float low =
                    VecGet(
                        unit->lowOutputs,
                        iOutput);
                float high =
                    VecGet(
                        unit->highOutputs,
                        iOutput);
                VecSet(
                    that->lowHiddens,
                    indice,
                    low);
                VecSet(
                    that->highHiddens,
                    indice,
                    high);

            }

        }

    }

} while (GSetIterStep(&iter));

}

// Evaluate the NeuraMorph 'that' on the 'inputs' values
void NMEvaluate(
    NeuraMorph* that,
    VecFloat* inputs) {

#ifdef BUILDMODE == 0

```

```

if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
        NeuraMorphErr->_msg,
        "'that' is null");
    PBErrCatch(NeuraMorphErr);

}

if (inputs == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
        NeuraMorphErr->_msg,
        "'inputs' is null");
    PBErrCatch(NeuraMorphErr);

}

if (VecGetDim(inputs) != VecGetDim(that->inputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
        NeuraMorphErr->_msg,
        "'inputs' has invalid size (%ld==%ld)",
        VecGetDim(inputs),
        VecGetDim(that->inputs));
    PBErrCatch(NeuraMorphErr);

}

#endif

// Copy the inputs into the internal inputs
VecCopy(
    that->inputs,
    inputs);

// Reset the internal outputs
VecSetNull(that->outputs);

// Loop on the units
GSetIterForward iter = GSetIterForwardCreateStatic(&(amp;that->units));
do {

    // Get the unit
    NeuraMorphUnit* unit = GSetIterGet(&iter);

    // Allocate memory for inputs sent to the unit
    VecFloat* unitInputs = VecFloatCreate(NMUnitGetNbInputs(unit));

    // Loop on the input indices of the unit
    for (
        long iInput = 0;
        iInput < NMUnitGetNbInputs(unit);
        ++iInput) {

        // Get the input indice
        long indiceInput =
            VecGet(
                NMUnitIInputs(unit),

```

```

        iInput);

// Declare a variable to memorize the input value
float val = 0.0;

// If this indice points toward an input
if (indiceInput < NMGetNbInput(that)) {

    // Get the input value of the NeuraMorph for this indice
    val =
        VecGet(
            NMInputs(that),
            indiceInput);

// Else, the indice points toward a hidden value
} else {

    // Get the hidden value of the NeuraMorph for this indice
    val =
        VecGet(
            that->hiddens,
            indiceInput - NMGetNbInput(that));

}

// Set the input value for the unit for this indice
VecSet(
    unitInputs,
    iInput,
    val);

}

// Evaluate the unit
NMUnitEvaluate(
    unit,
    unitInputs);

// Free the memory used by the unit input
VecFree(&unitInputs);

// Loop on the output indices of the unit
for (
    long iOutput = 0;
    iOutput < NMUnitGetNbOutputs(unit);
    ++iOutput) {

    // Get the output value of the unit for this indice
    float val =
        VecGet(
            NMUnitOutputs(unit),
            iOutput);

    // Get the output indice
    long indiceOutput =
        VecGet(
            NMUnitIOOutputs(unit),
            iOutput);

    // If the indice points toward a hidden
    if (indiceOutput < NMGetNbHidden(that)) {

```

```

        // Set the hidden value of the NeuraMorph for this indice
        VecSet(
            that->hiddens,
            indiceOutput,
            val);

    // Else, the indice points toward an output
    } else {

        // Set the output value of the NeuraMorph for this indice
        VecSet(
            that->outputs,
            indiceOutput - NMGetNbHidden(that),
            val);

    }

}

} while (GSetIterStep(&iter));
}

// ----- NeuraMorphTrainer

// ===== Functions declaration =====

// Return true if the vector 'v' is a valid indices configuration
// i.e. v[i]<v[j] for all i<j
bool NMTrainerIsValidInputConfig(
    const VecLong* v,
    long iMinInput);

// ===== Functions implementation =====

// Create a static NeuraMorphTrainer for the NeuraMorph 'neuraMorph' and the
// GDataSet 'dataset'
// Default depth: 2
NeuraMorphTrainer NeuraMorphTrainerCreateStatic(
    NeuraMorph* neuraMorph,
    GDataSetVecFloat* dataset) {

#ifdef BUILDMODE == 0

    if (neuraMorph == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'neuraMorph' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (dataset == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'dataset' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif
}

```

```

    }

#endif

    // Declare the new NeuroMorphTrainer
    NeuroMorphTrainer that;

    // Init properties
    that.neuraMorph = neuraMorph;
    that.dataset = dataset;
    that.depth = 2;
    that.iCatTraining = 0;

    // Return the NeuroMorphTrainer
    return that;
}

// Free the memory used by the static NeuroMorphTrainer 'that'
void NeuroMorphTrainerFreeStatic(NeuroMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuroMorphErr);

    }

#endif

    // Nothing to do

}

// Run the training process for the NeuroMorphTrainer 'that'
void NMTrainerRun(NeuroMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuroMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuroMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuroMorphErr);

    }

#endif

    // Declare a variable to memorize the minimum index needed in the
    // inputs of the new unit to ensure we do not train twice the same
    // unit
    long iMinInput = 0;

    // Loop on training depth

```

```

for (
    short iDepth = 1;
    iDepth <= NMTrainerGetDepth(that);
    ++iDepth) {

    printf(
        "Depth %d/%d...\n",
        iDepth,
        NMTrainerGetDepth(that));

    // Get the number of available inputs for the new unit
    long nbAvailInputs =
        NMGetNbInput(NMTrainerNeuraMorph(that)) +
        NMGetNbHidden(NMTrainerNeuraMorph(that));

    printf(
        "Nb available inputs: %ld\n",
        nbAvailInputs);

    // Get the output indices
    VecLong* iOutputs = NMGetVecIOutputs(NMTrainerNeuraMorph(that));

    // Declare a set to memorize the trained units
    GSet trainedUnits = GSetCreateStatic();

    // Loop on the number of inputs for the new unit
    // TODO restrain nbUnitInput to a maximum
    for (
        long nbUnitInputs = 1;
        nbUnitInputs <= nbAvailInputs;
        ++nbUnitInputs) {

        printf(
            "Train units with %ld inputs\n",
            nbUnitInputs);

        // Loop on the possible input configurations for the new units
        VecLong* iInputs = VecLongCreate(nbUnitInputs);
        VecLong* iInputsBound = VecLongCreate(nbUnitInputs);
        VecSetAll(
            iInputsBound,
            nbAvailInputs);
        bool hasStepped = true;
        do {

            bool isValidInputConfig =
                NMTrainerIsValidInputConfig(
                    iInputs,
                    iMinInput);
            if (isValidInputConfig == true) {

                printf("Train units with configuration ");
                VecPrint(
                    iInputs,
                    stdout);
                printf(" -> ");
                VecPrint(
                    iOutputs,
                    stdout);
                printf("\n");

            }

        }
    }
}

```



```

        // Create the unit
        NeuroMorphUnit* unit =
            NeuroMorphUnitCreate(
                iInputs,
                iOutputs);

        // TODO Train the unit
        GSetAppend(
            &trainedUnits,
            unit);

        // Step to the next input configuration
        hasStepped =
            VecStep(
                iInputs,
                iInputsBound);

    } while (hasStepped);

    // Free memory
    VecFree(&iInputs);
    VecFree(&iInputsBound);
}

// If this is the last depth
if (iDepth == NMTrainerGetDepth(that)) {

    // TODO Add the best of all units to the NeuroMorph
    NeuroMorphUnit* bestUnit = GSetDrop(&trainedUnits);
    GSetAppend(
        &(NMTrainerNeuroMorph(that)->units),
        bestUnit);

    // Discard all other units
    while (GSetNbElem(&trainedUnits) > 0) {

        NeuroMorphUnit* unit = GSetPop(&trainedUnits);
        NeuroMorphUnitFree(&unit);

    }

    // Else, this is not the last depth
} else {

    // TODO Discard the weakest units
    while (GSetNbElem(&trainedUnits) > 0) {

        NeuroMorphUnit* unit = GSetPop(&trainedUnits);
        NeuroMorphUnitFree(&unit);

    }

    // Burry the remaining units

}

// Update the minimum index of a valid configuration
iMinInput = nbAvailInputs;

// Free memory

```

```

    VecFree(&iOutputs);

}

}

// Return true if the vector 'v' is a valid indices configuration
// i.e. v[i]<v[j] for all i<j and there exists i such as
// v[i]>=iMinInput
bool NMTrainerIsValidInputConfig(
    const VecLong* v,
    long iMinInput) {

#ifdef BUILDMODE == 0

    if (v == NULL) {

        NeuraMorphErr->_type = PErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'v' is null");
        PErrCatch(NeuraMorphErr);

    }

#endif

    bool noveltyCond = false;
    long a =
        VecGet(
            v,
            0);
    if (a >= iMinInput) {

        noveltyCond = true;

    }

    for (
        long i = 1;
        i < VecGetDim(v);
        ++i) {

        long b =
            VecGet(
                v,
                i);
        if (a >= b) {

            return false;

        }

        a = b;

        if (a >= iMinInput) {

            noveltyCond = true;

        }

    }

}

```

```

    return noveltyCond;
}

```

3.2 neuramorph-inline.c

```

// ===== NEURAMORPH-INLINE.C =====

// ----- NeuraMorphUnit

// ===== Functions implementation =====

// Get the input indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->iInputs;

}

// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->iOutputs;

}

```

```

// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->outputs;

}

// Get the number of input values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbInputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return VecGetDim(that->iInputs);

}

// Get the number of output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
long NMUnitGetNbOutputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,

```

```

        "'that' is null");
        PBErCatch(NeuraMorphErr);

    }

#endif

    return VecGetDim(that->iOutputs);

}

// ----- NeuraMorph

// ===== Functions implementation =====

// Get the number of input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbInput(const NeuraMorph* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErCatch(NeuraMorphErr);

    }

#endif

    return that->nbInput;

}

// Get the number of output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbOutput(const NeuraMorph* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErCatch(NeuraMorphErr);

    }

#endif

    return that->nbOutput;

}

```

```

// Get the input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
VecFloat* NMInputs(NeuraMorph* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->inputs;

}

// Get the output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMOutputs(const NeuraMorph* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->outputs;

}

// Get the number of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbHidden(const NeuraMorph* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,

```

```

        "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    long nb = 0;
    if (that->hiddens != NULL) {

        nb = VecGetDim(that->hiddens);

    }

    return nb;

}

// Set the number of hidden values of the NeuraMorph 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void NMSetNbHidden(
    NeuraMorph* that,
    long nb) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (nb <= 0) {

        NeuraMorphErr->_type = PBErrTypeInvalidArg;
        sprintf(
            NeuraMorphErr->_msg,
            "'nb' is invalid (%ld>0)",
            nb);
        PBErrCatch(NeuraMorphErr);

    }

#endif

    if (that->hiddens != NULL) {

        VecFree(&(that->hiddens));

    }

    that->hiddens = VecFloatCreate(nb);

}

// ----- NeuraMorphTrainer

```

```

// ===== Functions implementation =====

// Get the depth of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
short NMTrainerGetDepth(const NeuraMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->depth;

}

// Set the depth of the NeuraMorphTrainer 'that' to 'depth'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetDepth(
    NeuraMorphTrainer* that,
    short depth) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

    if (depth < 1) {

        NeuraMorphErr->_type = PBErrTypeInvalidArg;
        sprintf(
            NeuraMorphErr->_msg,
            "'depth' is invalid (%d>=1)",
            depth);
        PBErrCatch(NeuraMorphErr);

    }

#endif

    that->depth = depth;
}

```



```

}

// Get the NeuraMorph of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
NeuraMorph* NMTrainerNeuraMorph(const NeuraMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->neuraMorph;

}

// Get the GDataSet of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
GDataSetVecFloat* NMTrainerDataset(const NeuraMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->dataset;

}

// Get the index of the training category of the NeuraMorphTrainer 'that'
#if BUILDMODE != 0
static inline
#endif
unsigned int NMTrainerGetICatTraining(const NeuraMorphTrainer* that) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;

```

```

        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    return that->iCatTraining;

}

// Set the index of the training category of the NeuraMorphTrainer 'that'
// to 'iCat'
#if BUILDMODE != 0
static inline
#endif
void NMTrainerSetICatTraining(
    NeuraMorphTrainer* that,
    unsigned int iCatTraining) {

#if BUILDMODE == 0

    if (that == NULL) {

        NeuraMorphErr->_type = PBErrTypeNullPointer;
        sprintf(
            NeuraMorphErr->_msg,
            "'that' is null");
        PBErrCatch(NeuraMorphErr);

    }

#endif

    that->iCatTraining = iCatTraining;

}

```

4 Makefile

```

# Build mode
# 0: development (max safety, no optimisation)
# 1: release (min safety, optimisation)
# 2: fast and furious (no safety, optimisation)
BUILD_MODE?=0

all: pbmake_wget main

# Automatic installation of the repository PBMake in the parent folder
pbmake_wget:
if [ ! -d ../PBMake ]; then wget https://github.com/BayashiPascal/PBMake/archive/master.zip; unzip master.zip; rm -f

# Makefile definitions
MAKEFILE_INC=../PBMake/Makefile.inc
include $(MAKEFILE_INC)

```

```

# Rules to make the executable
repo=neuramorph
$$$(repo)_EXENAME): \
$$$(repo)_EXENAME).o \
$$$(repo)_EXE_DEP) \
$$$(repo)_DEP)
$(COMPILER) 'echo "$$(repo)_EXE_DEP) $$(repo)_EXENAME).o" | tr ' ' '\n' | sort -u' $(LINK_ARG) $$(repo)_LINK_ARG)

$$$(repo)_EXENAME).o: \
$$$(repo)_DIR)/$$(repo)_EXENAME).c \
$$$(repo)_INC_H_EXE) \
$$$(repo)_EXE_DEP)
$(COMPILER) $(BUILD_ARG) $$(repo)_BUILD_ARG) 'echo "$$(repo)_INC_DIR)" | tr ' ' '\n' | sort -u' -c $$(repo)_DIR)/

```

5 Unit tests

```

#include <stdlib.h>
#include <stdio.h>
#include <time.h>
#include <string.h>
#include <time.h>
#include <unistd.h>
#include <sys/time.h>
#include "neuramorph.h"

void UnitTestNeuraMorphUnitCreateFree() {

    VecLong* iIn = VecLongCreate(3);
    VecSet(
        iIn,
        0,
        0);
    VecSet(
        iIn,
        1,
        1);
    VecSet(
        iIn,
        2,
        2);
    VecLong* iOut = VecLongCreate(2);
    VecSet(
        iOut,
        0,
        0);
    VecSet(
        iOut,
        1,
        1);
    NeuraMorphUnit* unit =
        NeuraMorphUnitCreate(
            iIn,
            iOut);
    if (
        VecGetDim(unit->coeffs[0]) != 10 ||
        VecGetDim(unit->outputs) != 2 ||
        VecGetDim(unit->lowFilters) != 4 ||

```

```

    VecGetDim(unit->highFilters) != 4 ||
    VecGetDim(unit->unitInputs) != 4 ||
    unit->lowOutputs != NULL ||
    unit->highOutputs != NULL) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NeuraMorphUnitCreate failed (1)");
    PBErrCatch(NeuraMorphErr);

}

bool isSame =
    VecIsEqual(
        unit->iInputs,
        iIn);
if (isSame == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NeuraMorphUnitCreate failed (2)");
    PBErrCatch(NeuraMorphErr);

}

isSame =
    VecIsEqual(
        unit->iOutputs,
        iOut);
if (isSame == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NeuraMorphUnitCreate failed (3)");
    PBErrCatch(NeuraMorphErr);

}

NeuraMorphUnitFree(&unit);
if (unit != NULL) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NeuraMorphUnitFree failed");
    PBErrCatch(NeuraMorphErr);

}

VecFree(&iIn);
VecFree(&iOut);
printf("UnitTestNeuraMorphUnitCreateFree OK\n");

}

void UnitTestNeuraMorphUnitGetSet() {

    VecLong* iIn = VecLongCreate(3);
    VecLong* iOut = VecLongCreate(2);

```

```

NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
        iIn,
        iOut);

if (NMUnitIInputs(unit) != unit->iInputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitIInputs failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMUnitIOutputs(unit) != unit->iOutputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitIOutputs failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMUnitOutputs(unit) != unit->outputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitOutputs failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMUnitGetNbInputs(unit) != 3) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitGetNbInputs failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMUnitGetNbOutputs(unit) != 2) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitGetNbOutputs failed");
    PBErrCatch(NeuraMorphErr);

}

NeuraMorphUnitFree(&unit);
VecFree(&iIn);
VecFree(&iOut);
printf("UnitTestNeuraMorphUnitGetSet OK\n");

}

```

```

void UnitTestNeuraMorphUnitEvaluate() {

    VecLong* iIn = VecLongCreate(3);
    VecLong* iOut = VecLongCreate(2);
    NeuraMorphUnit* unit =
        NeuraMorphUnitCreate(
            iIn,
            iOut);

    for (
        long iInput = 3;
        iInput--;) {

        VecSet(
            unit->lowFilters,
            iInput + 1,
            0.0);
        VecSet(
            unit->highFilters,
            iInput + 1,
            2.0);

    }

    // iOutput == 0 -> 1.0+x+y+z+x^2+xy+xz+y^2+yz+z^2
    // iOutput == 1 -> x^2-xy+2xz+3y^2-4yz+5z^2
    float coeffs[2][10] = {

        { 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0},
        { 0.0, 0.0, 1.0, 0.0, -1.0, 3.0, 0.0, 2.0, -4.0, 5.0}

    };

    for (
        long iOutput = 2;
        iOutput--;) {

        for (
            long iCoeff = 10;
            iCoeff--;) {

            VecSet(
                unit->coeffs[iOutput],
                iCoeff,
                coeffs[iOutput][iCoeff]);

        }

    }

    VecFloat* inputs = VecFloatCreate(3);
    VecSet(
        inputs,
        0,
        1.0);
    VecSet(
        inputs,
        1,
        3.0);
    VecSet(
        inputs,
        2,
        1.5);
}

```

```

NMUnitEvaluate(
    unit,
    inputs);

float check[2];
float x = 1.0;
float y = 0.0;
float z = 1.5;
check[0] = 1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z;
check[1] =
    x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z;
VecFloat2D checkHigh = VecFloatCreateStatic2D();
VecSet(
    &checkHigh,
    0,
    check[0]);
VecSet(
    &checkHigh,
    1,
    check[1]);
VecFloat2D checkLow = checkHigh;
for (
    long iOutput = 2;
    iOutput--;) {

    float v =
        VecGet(
            unit->outputs,
            iOutput);
    bool same =
        ISEQUALF(
            v,
            check[iOutput]);
    if (same == false) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NMUnitEvaluate failed (1)");
        PBErrCatch(NeuraMorphErr);

    }

}

bool sameLow =
    VecIsEqual(
        &checkLow,
        unit->lowOutputs);
bool sameHigh =
    VecIsEqual(
        &checkHigh,
        unit->highOutputs);
if (
    sameLow == false ||
    sameHigh == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMUnitEvaluate failed (2)");

```

```

        PBErriCatch(NeuraMorphErr);

    }

    NeuraMorphUnitFree(&unit);
    VecFree(&iIn);
    VecFree(&iOut);
    VecFree(&inputs);
    printf("UnitTestNeuraMorphUnitEvaluate OK\n");

}

void UnitTestNeuraMorphUnit() {

    UnitTestNeuraMorphUnitCreateFree();
    UnitTestNeuraMorphUnitGetSet();
    UnitTestNeuraMorphUnitEvaluate();
    printf("UnitTestNeuraMorphUnit OK\n");

}

void UnitTestNeuraMorphCreateFree() {

    NeuraMorph* nm =
        NeuraMorphCreate(
            3,
            2);
    if (
        nm->nbInput != 3 ||
        nm->nbOutput != 2 ||
        VecGetDim(nm->inputs) != 3 ||
        VecGetDim(nm->outputs) != 2 ||
        nm->hiddens != NULL ||
        GSetNbElem(&(nm->units)) != 0) {

        NeuraMorphErr->_type = PBErriTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NeuraMorphCreate failed");
        PBErriCatch(NeuraMorphErr);

    }

    NeuraMorphFree(&nm);
    if (nm != NULL) {

        NeuraMorphErr->_type = PBErriTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NeuraMorphFree failed");
        PBErriCatch(NeuraMorphErr);

    }

    printf("UnitTestNeuraMorphCreateFree OK\n");

}

void UnitTestNeuraMorphGetSet() {

    NeuraMorph* nm =
        NeuraMorphCreate(

```



```

        3,
        2);
if (NMGetNbInput(nm) != 3) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMGetNbInput failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMGetNbOutput(nm) != 2) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMGetNbOutput failed");
    PBErrCatch(NeuraMorphErr);

}

if (NMGetNbHidden(nm) != 0) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMGetNbHidden failed");
    PBErrCatch(NeuraMorphErr);

}

NMSetNbHidden(
    nm,
    5);
if (NMGetNbHidden(nm) != 5) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMSetNbHidden failed");
    PBErrCatch(NeuraMorphErr);

}

VecLong* iOuts = NMGetVecIOutputs(nm);
VecLong2D checkOuts =
    VecLongCreateStatic2D();
VecSet(
    &checkOuts,
    0,
    5);
VecSet(
    &checkOuts,
    1,
    6);
bool isSame =
    VecIsEqual(
        &checkOuts,
        iOuts);
if (isSame == false) {

```

```

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMGetVecIOutputs failed");
    PBErrCatch(NeuraMorphErr);
}

VecFree(&iOuts);

if (NMInputs(nm) != nm->inputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMInputs failed");
    PBErrCatch(NeuraMorphErr);
}

if (NMOutputs(nm) != nm->outputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMOutputs failed");
    PBErrCatch(NeuraMorphErr);
}

NeuraMorphFree(&nm);

printf("UnitTestNeuraMorphGetSet OK\n");
}

void UnitTestNeuraMorphAddRemoveUnit() {

    VecLong3D iInputs = VecLongCreateStatic3D();
    VecSet(
        &iInputs,
        0,
        0);
    VecSet(
        &iInputs,
        1,
        1);
    VecSet(
        &iInputs,
        2,
        2);
    VecLong2D iOutputs = VecLongCreateStatic2D();
    VecSet(
        &iOutputs,
        0,
        0);
    VecSet(
        &iOutputs,
        1,
        1);

    NeuraMorph* nm =

```

```

NeuraMorphCreate(
    3,
    2);

NeuraMorphUnit* unit =
    NMAddUnit(
        nm,
        (VecLong*)&iInputs,
        (VecLong*)&iOutputs);

bool isSameA =
    VecIsEqual(
        &iInputs,
        unit->iInputs);
bool isSameB =
    VecIsEqual(
        &iOutputs,
        unit->iOutputs);
if (
    GSetNbElem(&(nm->units)) != 1 ||
    GSetHead(&(nm->units)) != unit ||
    isSameA == false ||
    isSameB == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMAddUnit failed");
    PBErrCatch(NeuraMorphErr);

}

NeuraMorphFree(&nm);

nm =
    NeuraMorphCreate(
        3,
        2);

unit =
    NMAddUnit(
        nm,
        (VecLong*)&iInputs,
        (VecLong*)&iOutputs);

NMRemoveUnit(
    nm,
    unit);

if (GSetNbElem(&(nm->units)) != 0) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMRemoveUnit failed");
    PBErrCatch(NeuraMorphErr);

}

NeuraMorphUnitFree(&unit);
NeuraMorphFree(&nm);

```

```

    printf("UnitTestNeuraMorphAddRemoveUnit OK\n");
}

void UnitTestNeuraMorphBurryUnitsEvaluate() {

    VecLong3D iInputs = VecLongCreateStatic3D();
    VecSet(
        &iInputs,
        0,
        0);
    VecSet(
        &iInputs,
        1,
        1);
    VecSet(
        &iInputs,
        2,
        2);
    VecLong2D iOutputs = VecLongCreateStatic2D();
    VecSet(
        &iOutputs,
        0,
        0);
    VecSet(
        &iOutputs,
        1,
        1);

    NeuraMorph* nm =
        NeuraMorphCreate(
            3,
            2);

    NeuraMorphUnit* unitA =
        NeuraMorphUnitCreate(
            (VecLong*)&iInputs,
            (VecLong*)&iOutputs);

    NeuraMorphUnit* unitB =
        NeuraMorphUnitCreate(
            (VecLong*)&iInputs,
            (VecLong*)&iOutputs);

    for (
        long iInput = 3;
        iInput--;) {

        VecSet(
            unitA->lowFilters,
            iInput + 1,
            0.0);
        VecSet(
            unitA->highFilters,
            iInput + 1,
            2.0);
        VecSet(
            unitB->lowFilters,
            iInput + 1,
            0.0);
        VecSet(
            unitB->highFilters,

```

```

        iInput + 1,
        2.0);
}

float coeffsA[2][10] = {

    { 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0},
    { 0.0, 0.0, 1.0, 0.0, -1.0, 3.0, 0.0, 2.0, -4.0, 5.0}

};

float coeffsB[2][10] = {

    { 0.0, 0.0, 1.0, 0.0, -1.0, 3.0, 0.0, 2.0, -4.0, 5.0},
    { 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0}

};

for (
    long iOutput = 2;
    iOutput--;) {

    for (
        long iCoeff = 10;
        iCoeff--;) {

        VecSet(
            unitA->coeffs[iOutput],
            iCoeff,
            coeffsA[iOutput][iCoeff]);

        VecSet(
            unitB->coeffs[iOutput],
            iCoeff,
            coeffsB[iOutput][iCoeff]);

    }

}

float x = 1.0;
float y = 0.5;
float z = 1.5;
VecFloat* evalInputs = VecFloatCreate(3);
VecSet(
    evalInputs,
    0,
    x);
VecSet(
    evalInputs,
    1,
    y);
VecSet(
    evalInputs,
    2,
    z);

NMUnitEvaluate(
    unitA,
    evalInputs);
NMUnitEvaluate(
    unitB,
    evalInputs);

```

```

GSet units = GSetCreateStatic();
GSetAppend(
    &units,
    unitA);
GSetAppend(
    &units,
    unitB);

NMBurryUnits(
    nm,
    &units);

if (
    GSetNbElem(&units) != 0 ||
    nm->hiddens == NULL ||
    VecGetDim(nm->hiddens) != 4) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMBurryUnits failed (1)");
    PBErrCatch(NeuraMorphErr);

}

VecLong2D checkA = VecLongCreateStatic2D();
VecSet(
    &checkA,
    0,
    0);
VecSet(
    &checkA,
    1,
    1);
VecLong2D checkB = VecLongCreateStatic2D();
VecSet(
    &checkB,
    0,
    2);
VecSet(
    &checkB,
    1,
    3);

bool isSameA =
    VecIsEqual(
        &checkA,
        unitA->iOutputs);
bool isSameB =
    VecIsEqual(
        &checkB,
        unitB->iOutputs);
if (
    isSameA == false ||
    isSameB == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMBurryUnits failed (2)");
    PBErrCatch(NeuraMorphErr);
}

```

```

}

float checkLowAa =
    VecGet(
        unitA->lowOutputs,
        0);
checkLowAa -=
    VecGet(
        nm->lowHiddens,
        0);
bool isSameLowAa =
    ISEQUALF(
        checkLowAa,
        0.0);
float checkLowAb =
    VecGet(
        unitA->lowOutputs,
        1);
checkLowAb -=
    VecGet(
        nm->lowHiddens,
        1);
bool isSameLowAb =
    ISEQUALF(
        checkLowAb,
        0.0);
float checkLowBa =
    VecGet(
        unitB->lowOutputs,
        0);
checkLowBa -=
    VecGet(
        nm->lowHiddens,
        2);
bool isSameLowBa =
    ISEQUALF(
        checkLowBa,
        0.0);
float checkLowBb =
    VecGet(
        unitB->lowOutputs,
        1);
checkLowBb -=
    VecGet(
        nm->lowHiddens,
        3);
bool isSameLowBb =
    ISEQUALF(
        checkLowBb,
        0.0);
float checkHighAa =
    VecGet(
        unitA->lowOutputs,
        0);
checkHighAa -=
    VecGet(
        nm->lowHiddens,
        0);
bool isSameHighAa =
    ISEQUALF(
        checkHighAa,

```

```

        0.0);
float checkHighAb =
    VecGet(
        unitA->lowOutputs,
        1);
checkHighAb -=
    VecGet(
        nm->lowHiddens,
        1);
bool isSameHighAb =
    ISEQUALF(
        checkHighAb,
        0.0);
float checkHighBa =
    VecGet(
        unitB->lowOutputs,
        0);
checkHighBa -=
    VecGet(
        nm->lowHiddens,
        2);
bool isSameHighBa =
    ISEQUALF(
        checkHighBa,
        0.0);
float checkHighBb =
    VecGet(
        unitB->lowOutputs,
        1);
checkHighBb -=
    VecGet(
        nm->lowHiddens,
        3);
bool isSameHighBb =
    ISEQUALF(
        checkHighBb,
        0.0);
if (
    isSameLowAa == false ||
    isSameLowAb == false ||
    isSameLowBa == false ||
    isSameLowBb == false ||
    isSameHighAa == false ||
    isSameHighAb == false ||
    isSameHighBa == false ||
    isSameHighBb == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMBurryUnits failed (3)");
    PBErrCatch(NeuraMorphErr);

}

VecSet(
    &iInputs,
    0,
    3);
VecSet(
    &iInputs,
    1,

```



```

    4);
VecSet(
    &iInputs,
    2,
    5);
VecSet(
    &iOutputs,
    0,
    4);
VecSet(
    &iOutputs,
    1,
    5);
NeuraMorphUnit* unitC =
    NMAddUnit(
        nm,
        (VecLong*)&iInputs,
        (VecLong*)&iOutputs);

for (
    long iInput = 3;
    iInput--;) {

    VecSet(
        unitC->lowFilters,
        iInput + 1,
        0.0);
    VecSet(
        unitC->highFilters,
        iInput + 1,
        20.0);

}

float coeffsC[2][10] = {

    { 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0},
    { 0.0, 0.0, 1.0, 0.0, -1.0, 3.0, 0.0, 2.0, -4.0, 5.0}

};

for (
    long iOutput = 2;
    iOutput--;) {

    for (
        long iCoeff = 10;
        iCoeff--;) {

        VecSet(
            unitC->coeffs[iOutput],
            iCoeff,
            coeffsC[iOutput][iCoeff]);

    }

}

NMEvaluate(
    nm,
    evalInputs);

float checkAout[2];

```

```

checkAout[0] =
    1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z -
    VecGet(
        nm->hiddens,
        0);
checkAout[1] =
    x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z -
    VecGet(
        nm->hiddens,
        1);
float checkBout[2];
checkBout[0] =
    x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z -
    VecGet(
        nm->hiddens,
        2);
checkBout[1] =
    1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z -
    VecGet(
        nm->hiddens,
        3);

bool isSameAa =
    ISEQUALF(
        checkAout[0],
        0.0);
bool isSameAb =
    ISEQUALF(
        checkAout[1],
        0.0);
bool isSameBa =
    ISEQUALF(
        checkBout[0],
        0.0);
bool isSameBb =
    ISEQUALF(
        checkBout[1],
        0.0);
if (
    isSameAa == false ||
    isSameAb == false ||
    isSameBa == false ||
    isSameBb == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMEvaluate failed (1)");
    PBErrCatch(NeuraMorphErr);

}

x =
    VecGet(
        nm->hiddens,
        0);
y =
    VecGet(
        nm->hiddens,
        1);
z =
    VecGet(

```

```

        nm->hiddens,
        2);
float checkCout[2];
checkCout[0] =
    1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z -
    VecGet(
        unitC->outputs,
        0);
checkCout[1] =
    x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z -
    VecGet(
        unitC->outputs,
        1);

bool isSameCa =
    ISEQUALF(
        checkCout[0],
        0.0);
bool isSameCb =
    ISEQUALF(
        checkCout[1],
        0.0);
bool isSameCc =
    VecIsEqual(
        unitC->outputs,
        nm->outputs);
if (
    isSameCa == false ||
    isSameCb == false ||
    isSameCc == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NMEvaluate failed (2)");
    PBErrCatch(NeuraMorphErr);

}

VecFree(&evalInputs);
NeuraMorphFree(&nm);

printf("UnitTestNeuraMorphBurryUnitsEvaluate OK\n");
}

void UnitTestNeuraMorph() {

    UnitTestNeuraMorphCreateFree();
    UnitTestNeuraMorphGetSet();
    UnitTestNeuraMorphAddRemoveUnit();
    UnitTestNeuraMorphBurryUnitsEvaluate();
    printf("UnitTestNeuraMorph OK\n");

}

void UnitTestNeuraMorphTrainerCreateFree() {

    GDataSetVecFloat dataset =
        GDataSetVecFloatCreateStaticFromFile("./Datasets/iris.json");
    NeuraMorph* nm =
        NeuraMorphCreate(

```

```

        GDSGetNbInputs(&dataset),
        GDSGetNbOutputs(&dataset));
NeuraMorphTrainer trainer =
    NeuraMorphTrainerCreateStatic(
        nm,
        &dataset);
if (
    trainer.neuraMorph != nm ||
    trainer.depth != 2 ||
    trainer.iCatTraining != 0 ||
    trainer.dataset != &dataset) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
        NeuraMorphErr->_msg,
        "NeuraMorphTrainerCreateStatic failed");
    PBErrCatch(NeuraMorphErr);

}

NeuraMorphTrainerFreeStatic(&trainer);
NeuraMorphFree(&nm);
GDataSetVecFloatFreeStatic(&dataset);

printf("UnitTestNeuraMorphTrainerCreateFree OK\n");

}

void UnitTestNeuraMorphTrainerGetSet() {

    GDataSetVecFloat dataset =
        GDataSetVecFloatCreateStaticFromFile("./Datasets/iris.json");
    NeuraMorph* nm =
        NeuraMorphCreate(
            GDSGetNbInputs(&dataset),
            GDSGetNbOutputs(&dataset));
    NeuraMorphTrainer trainer =
        NeuraMorphTrainerCreateStatic(
            nm,
            &dataset);
    if (NMTrainerGetDepth(&trainer) != 2) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NeuraMorphTrainerGetDepth failed");
        PBErrCatch(NeuraMorphErr);

    }

    if (NMTrainerGetICatTraining(&trainer) != 0) {

        NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuraMorphErr->_msg,
            "NeuraMorphTrainerGetICatTraining failed");
        PBErrCatch(NeuraMorphErr);

    }

    NMTrainerSetDepth(
        &trainer,

```

```

    3);
    if (NMTrainerGetDepth(&trainer) != 3) {

        NeuroMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuroMorphErr->_msg,
            "NeuraMorphTrainerSetDepth failed");
        PBErrCatch(NeuraMorphErr);

    }

    NMTrainerSetICatTraining(
        &trainer,
        3);
    if (NMTrainerGetICatTraining(&trainer) != 3) {

        NeuroMorphErr->_type = PBErrTypeUnitTestFailed;
        sprintf(
            NeuroMorphErr->_msg,
            "NeuraMorphTrainerSetICatTraining failed");
        PBErrCatch(NeuraMorphErr);

    }

    NeuroMorphTrainerFreeStatic(&trainer);
    NeuroMorphFree(&nm);
    GDataSetVecFloatFreeStatic(&dataset);

    printf("UnitTestNeuraMorphTrainerGetSet OK\n");

}

void UnitTestNeuraMorphTrainerRun() {

    GDataSetVecFloat dataset =
        GDataSetVecFloatCreateStaticFromFile("../Datasets/iris.json");
    NeuroMorph* nm =
        NeuroMorphCreate(
            GDSGetNbInputs(&dataset),
            GDSGetNbOutputs(&dataset));
    NeuroMorphTrainer trainer =
        NeuroMorphTrainerCreateStatic(
            nm,
            &dataset);

    NMTrainerRun(&trainer);

    NeuroMorphTrainerFreeStatic(&trainer);
    NeuroMorphFree(&nm);
    GDataSetVecFloatFreeStatic(&dataset);

    printf("UnitTestNeuraMorphTrainerRun OK\n");

}

void UnitTestNeuraMorphTrainer() {

    UnitTestNeuraMorphTrainerCreateFree();
    UnitTestNeuraMorphTrainerGetSet();
    UnitTestNeuraMorphTrainerRun();
    printf("UnitTestNeuraMorphTrainer OK\n");
}

```

```

}

void UnitTestAll() {

    UnitTestNeuraMorphUnit();
    UnitTestNeuraMorph();
    UnitTestNeuraMorphTrainer();
    printf("UnitTestAll OK\n");

}

int main() {

    UnitTestAll();

    // Return success code
    return 0;

}

```

6 Unit tests output

```

UnitTestNeuraMorphUnitCreateFree OK
UnitTestNeuraMorphUnitGetSet OK
UnitTestNeuraMorphUnitEvaluate OK
UnitTestNeuraMorphUnit OK
UnitTestNeuraMorphCreateFree OK
UnitTestNeuraMorphGetSet OK
UnitTestNeuraMorphAddRemoveUnit OK
UnitTestNeuraMorphBurryUnitsEvaluate OK
UnitTestNeuraMorph OK
UnitTestNeuraMorphTrainerCreateFree OK
UnitTestNeuraMorphTrainerGetSet OK
Depth 1/2...
Nb available inputs: 4
Train units with 1 inputs
Train units with configuration <0> -> <0,1,2>
Train units with configuration <1> -> <0,1,2>
Train units with configuration <2> -> <0,1,2>
Train units with configuration <3> -> <0,1,2>
Train units with 2 inputs
Train units with configuration <0,1> -> <0,1,2>
Train units with configuration <0,2> -> <0,1,2>
Train units with configuration <0,3> -> <0,1,2>
Train units with configuration <1,2> -> <0,1,2>
Train units with configuration <1,3> -> <0,1,2>
Train units with configuration <2,3> -> <0,1,2>
Train units with 3 inputs
Train units with configuration <0,1,2> -> <0,1,2>
Train units with configuration <0,1,3> -> <0,1,2>
Train units with configuration <0,2,3> -> <0,1,2>
Train units with configuration <1,2,3> -> <0,1,2>
Train units with 4 inputs
Train units with configuration <0,1,2,3> -> <0,1,2>
Depth 2/2...
Nb available inputs: 4
Train units with 1 inputs
Train units with 2 inputs
Train units with 3 inputs

```

```
Train units with 4 inputs
UnitTestNeuraMorphTrainerRun OK
UnitTestNeuraMorphTrainer OK
UnitTestAll OK
```