NeuraMorph

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Contents

Introduction

NeuraMorph is a C library providing structures and functions to implement a neural network.

It uses the `PBErr`, `PBMath`, `GSet` library.

1 Definitions

2 Interface

```
// ============ NEURAMORPH.H ================
```

```
#ifndef NEURAMORPH_H
#define NEURAMORPH_H

// ================= Include =================

#include <stdlib.h>
#include <stdio.h>
#include <math.h>
#include <string.h>
#include <stdbool.h>
#include "pberr.h"
#include "pbmath.h"
#include "gset.h"
#include "gdataset.h"

// ----- NeuraMorphUnit

// ================= Data structure ===================

typedef struct NeuraMorphUnit {

  // Input indices in parent NeuraMorph
  VecLong* iInputs;

  // Output indices in parent NeuraMorph
  VecLong* iOutputs;

  // Lowest and highest values for filtering inputs
  VecFloat* lowFilters;
  VecFloat* highFilters;

  // Lowest and highest values of outputs
  VecFloat* lowOutputs;
  VecFloat* highOutputs;

  // Vector to memorize the output values
  VecFloat* outputs;

  // Transfer function coefficients
  // Seen as (nb output) triangular matrices of size (nb input + 1)
  VecFloat** coeffs;

  // Working variables to avoid reallocation of memory at each Evaluate()
  bool* activeInputs;
  VecFloat* scaledInputs;

} NeuraMorphUnit;

// ================ Functions declaration ====================

// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
  const VecLong* iInputs,
  const VecLong* iOutputs);

// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that);

// Get the input indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
```

```
#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that);

// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that);

// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that);

// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
  NeuraMorphUnit* that,
  const VecFloat* inputs);

// ----- NeuraMorph

// ================= Data structure ===================

typedef struct NeuraMorph {

  // Number of inputs and outputs
  long nbInput;
  long nbOutput;

  // Inputs and outputs values
  VecFloat* inputs;
  VecFloat* outputs;

  // Internal values
  VecFloat* hiddens;

  // GSet of NeuraMorphUnit
  GSet units;

} NeuraMorph;

// ================ Functions declaration ====================

// Create a new NeuraMorph with 'nbInput' inputs and 'nbOutput' outputs
NeuraMorph* NeuraMorphCreate(
  long nbInput,
  long nbOutput);

// Free the memory used by the NeuraMorph 'that'
void NeuraMorphFree(NeuraMorph** that);

// Get the number of input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbInput(NeuraMorph* that);

// Get the number of output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
```

```
#endif
long NMGetNbOutput(NeuraMorph* that);

// Get the input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
VecFloat* NMInputs(NeuraMorph* that);

// Get the output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMOutputs(const NeuraMorph* that);

// Get the number of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbHidden(NeuraMorph* that);

// Set the number of hidden values of the NeuraMorph 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void NMSetNbHidden(
  NeuraMorph* that,
         long nb);

// Add one NeuraMorphUnit with input and output indices 'iInputs'
// and 'iOutputs' to the NeuraMorph 'that'
// Return the created NeuraMorphUnit
NeuraMorphUnit* NMAddUnit(
     NeuraMorph* that,
  const VecLong* iInputs,
  const VecLong* iOutputs);

// Remove the NeuraMorphUnit 'unit' from the NeuraMorph 'that'
// The NeuraMorphUnit is not freed
void NMRemoveUnit(
      NeuraMorph* that,
  NeuraMorphUnit* unit);

// Burry the NeuraMorphUnits in the 'units' set into the
// NeuraMorph 'that'
// 'units' is empty after calling this function
// The NeuraMorphUnits iOutputs must point toward the NeuraMorph
// outputs
// NeuraMorphUnits' iOutputs are redirected toward new hidden values
// 'that->hiddens' is resized as necessary
void NMBurryUnits(
  NeuraMorph* that,
        GSet* units);

// ================ static inliner ====================

#if BUILDMODE != 0
#include "neuramorph-inline.c"
#endif

#endif
```

3 Code

3.1 neuramorph.c

```
// ============ NEURAMORPH.C ================

// ================ Include =================

#include "neuramorph.h"
#if BUILDMODE == 0
#include "neuramorph-inline.c"
#endif

// ----- NeuraMorphUnit

// ================ Functions declaration ====================

// Return the number of coefficients of a NeuraMorphUnit having 'nbIn' inputs
long NMUnitGetNBCoeff(long nbIn);

// Get the coefficient for the pair of inputs 'iInputA', 'iInputB' in the
// NeuraMorphUnit 'that' for the output 'iOutput'
float NMUnitGetCoeff(
  const NeuraMorphUnit* that,
                  long iInputA,
                  long iInputB,
                  long iOutput);

// ================ Functions implementation ====================

// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
  const VecLong* iInputs,
  const VecLong* iOutputs) {

#if BUILDMODE == 0

  if (iInputs == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputs' is null");
    PBErrCatch(NeuraMorphErr);

  }

  if (iOutputs == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'iOutputs' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Allocate memory for the NeuraMorphUnit
```

```
  NeuraMorphUnit* that =
    PBErrMalloc(
      NeuraMorphErr,
      sizeof(NeuraMorphUnit));

  // Get the number of inputs (including the constant) and outputs
  long nbIn = VecGetDim(iInputs) + 1;
  long nbOut = VecGetDim(iOutputs);

  // Init properties
  that->iInputs = VecClone(iInputs);
  that->iOutputs = VecClone(iOutputs);
  that->lowFilters = VecFloatCreate(nbIn);
  that->highFilters = VecFloatCreate(nbIn);
  that->lowOutputs = NULL;
  that->highOutputs = NULL;
  that->outputs = VecFloatCreate(nbOut);
  that->coeffs =
    PBErrMalloc(
      NeuraMorphErr,
      sizeof(VecFloat*) * nbOut);
  long nbCoeff = NMUnitGetNBCoeff(nbIn);
  for (
    long iOut = nbOut;
    iOut--;
    that->coeffs[iOut] = VecFloatCreate(nbCoeff));

  // 'nbIn + 1' for the constant
  that->activeInputs =
    PBErrMalloc(
      NeuraMorphErr,
      sizeof(bool) * nbIn);
  that->scaledInputs = VecFloatCreate(nbIn);

  // Set the input value, filters and active flag for the constant
  VecSet(
    that->scaledInputs,
    0,
    1.0);
  that->activeInputs[0] = true;

  // Return the new NeuraMorphUnit
  return that;

}

// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that) {

  // Check the input
  if (that == NULL || *that == NULL) {

    return;

  }

  // Free memory
  long nbOut = VecGetDim((*that)->iOutputs);
  VecFree(&((*that)->iInputs));
  VecFree(&((*that)->iOutputs));
  VecFree(&((*that)->lowFilters));
  VecFree(&((*that)->highFilters));
```

```
  if ((*that)->lowOutputs != NULL) {

    VecFree(&((*that)->lowOutputs));

  }

  if ((*that)->highOutputs != NULL) {

    VecFree(&((*that)->highOutputs));

  }

  VecFree(&((*that)->outputs));
  for (
    long iOut = nbOut;
    iOut--;
    VecFree((*that)->coeffs + iOut));
  free((*that)->coeffs);
  free((*that)->activeInputs);
  VecFree(&((*that)->scaledInputs));
  free(*that);
  *that = NULL;

}

// Return the number of coefficients of a NeuraMorphUnit having 'nbIn' inputs
long NMUnitGetNBCoeff(long nbIn) {

#if BUILDMODE == 0

  if (nbIn <= 0) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'nbIn' is invalid (%ld>0)",
      nbIn);
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Declare a variable to memorise the result
  long nb = 0;

  // Calculate the number of values in the triangular matrix of size
  // nbIn
  for (
    long i = nbIn;
    i >= 0;
    nb += (i--));

  // Return the result
  return nb;

}

// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
  NeuraMorphUnit* that,
```

```
  const VecFloat* inputs) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

  if (VecGetDim(inputs) != VecGetDim(that->iInputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'inputs' has invalid dimension (%ld!=%ld)",
      VecGetDim(inputs),
      VecGetDim(that->iInputs));
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Reset the outputs
  VecSetNull(that->outputs);

  // Update the active flags  and scaled inputs (skip the constant)
  for (
    long iInput = 1;
    iInput < VecGetDim(that->scaledInputs);
    ++iInput) {

    // Get the input value and its low/high filters
    float val =
      VecGet(
        inputs,
        iInput - 1);
    float low =
      VecGet(
        that->lowFilters,
        iInput);
    float high =
      VecGet(
        that->highFilters,
        iInput);

    // If the value is inside the filter
    if (
      low <= val &&
      val <= high &&
      (high - low) > PBMATH_EPSILON) {

      // Set this value as active
      that->activeInputs[iInput] = true;

      // Scale the value according to the filter
      float scaled = 2.0 * (val - low) / (high - low) - 1.0;
```

```
    VecSet(
      that->scaledInputs,
      iInput,
      scaled);

  // Else the value is outside the filter
  } else {

    // Set this value as inactive
    that->activeInputs[iInput] = false;

  }

}

// Loop on the pair of active inputs
for (
  long iInputA = 0;
  iInputA < VecGetDim(that->scaledInputs);
  ++iInputA) {

  if (that->activeInputs[iInputA] == true) {

    for (
      long iInputB = 0;
      iInputB <= iInputA;
      ++iInputB) {

      if (that->activeInputs[iInputB] == true) {

        // Loop on the outputs
        for (
          long iOutput = 0;
          iOutput < VecGetDim(that->outputs);
          ++iOutput) {

          // Calculate the components for this output and pair of inputs
          float comp =
            VecGet(
              that->scaledInputs,
              iInputA) *
            VecGet(
              that->scaledInputs,
              iInputB) *
            NMUnitGetCoeff(
              that,
              iInputA,
              iInputB,
              iOutput);

          // Add the component to the output
          float cur =
            VecGet(
              that->outputs,
              iOutput);
          VecSet(
            that->outputs,
            iOutput,
            cur + comp);

        }
```

```
      }

    }

  }

  // If the low and high values for outputs don't exist yet
  if (that->lowOutputs == NULL) {

    // Create the low and high values by cloning the current output
    that->lowOutputs = VecClone(that->outputs);
    that->highOutputs = VecClone(that->outputs);

  // Else, the low and high values for outputs exist
  } else {

    // Loop on the outputs
    for (
      long iOutput = 0;
      iOutput < VecGetDim(that->outputs);
      ++iOutput) {

      // Update the low and high values for this output
      float val =
        VecGet(
          that->outputs,
          iOutput);

      float curLow =
        VecGet(
          that->lowOutputs,
          iOutput);
      if (curLow > val) {

        VecSet(
          that->lowOutputs,
          iOutput,
          val);

      }

      float curHigh =
        VecGet(
          that->highOutputs,
          iOutput);
      if (curHigh < val) {

        VecSet(
          that->highOutputs,
          iOutput,
          val);

      }

    }

  }

}
```

```
// Get the coefficient for the pair of inputs 'iInputA', 'iInputB' in the
// NeuraMorphUnit 'that' for the output 'iOutput'
float NMUnitGetCoeff(
  const NeuraMorphUnit* that,
                  long iInputA,
                  long iInputB,
                  long iOutput) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

  if (
    iInputA < 0 ||
    iInputA >= VecGetDim(that->scaledInputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputA' is invalid (0<=%ld<%ld)",
      iInputA,
      VecGetDim(that->scaledInputs));
    PBErrCatch(NeuraMorphErr);

  }

  if (
    iInputB < 0 ||
    iInputB >= VecGetDim(that->scaledInputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputB' is invalid (0<=%ld<%ld)",
      iInputB,
      VecGetDim(that->scaledInputs));
    PBErrCatch(NeuraMorphErr);

  }

  if (iInputA < iInputB) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "The pair of indices is invalid (%ld>=%ld)",
      iInputA,
      iInputB);
    PBErrCatch(NeuraMorphErr);

  }

  if (
    iOutput < 0 ||
```

```
    iOutput >= VecGetDim(that->outputs)) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputB' is invalid (0<=%ld<%ld)",
      iInputB,
      VecGetDim(that->outputs));
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Calculate the index of the coefficient
  long iCoeff = 0;
  for (
    long shift = 0;
    shift < iInputA;
    iCoeff += (shift++) + 1);
  iCoeff += iInputB;

  // Return the coefficient
  float coeff =
    VecGet(
      that->coeffs[iOutput],
      iCoeff);
  return coeff;

}

// ----- NeuraMorph

// ================ Functions implementation ====================

// Create a new NeuraMorph with 'nbInput' inputs and 'nbOutput' outputs
NeuraMorph* NeuraMorphCreate(
  long nbInput,
  long nbOutput) {

  // Allocate memory for the NeuraMorph
  NeuraMorph* that =
    PBErrMalloc(
      NeuraMorphErr,
      sizeof(NeuraMorph));

  // Init properties
  that->nbInput = nbInput;
  that->nbOutput = nbOutput;
  that->inputs = VecFloatCreate(nbInput);
  that->outputs = VecFloatCreate(nbOutput);
  that->hiddens = NULL;
  that->units = GSetCreateStatic();

  // Return the NeuraMorph
  return that;

}

// Free the memory used by the NeuraMorph 'that'
void NeuraMorphFree(NeuraMorph** that) {
```

```
  // Check the input
  if (that == NULL || *that == NULL) {

    return;

  }

  // Free memory
  VecFree(&((*that)->inputs));
  VecFree(&((*that)->outputs));
  if ((*that)->hiddens != NULL) {

    VecFree(&((*that)->hiddens));

  }

  while (GSetNbElem(&((*that)->units)) > 0) {

    NeuraMorphUnit* unit = GSetPop(&((*that)->units));
    NeuraMorphUnitFree(&unit);

  }

  free(*that);
  *that = NULL;

}

// Add one NeuraMorphUnit with input and output indices 'iInputs'
// and 'iOutputs' to the NeuraMorph 'that'
// Return the created NeuraMorphUnit
NeuraMorphUnit* NMAddUnit(
     NeuraMorph* that,
  const VecLong* iInputs,
  const VecLong* iOutputs) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

  if (iInputs == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputs' is null");
    PBErrCatch(NeuraMorphErr);

  }

  if (iOutputs == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
```

```
      NeuraMorphErr->_msg,
      "'iOutputs' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Create the NeuraMorphUnit
  NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
      iInputs,
      iOutputs);

  // Append the new NeuraorphUnit to the set of NeuraMorphUnit
  GSetAppend(
    &(that->units),
    unit);

  // Return the new unit
  return unit;

}

// Remove the NeuraMorphUnit 'unit' from the NeuraMorph 'that'
// The NeuraMorphUnit is not freed
void NMRemoveUnit(
      NeuraMorph* that,
  NeuraMorphUnit* unit) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Remove the NeuraorphUnit from the set of NeuraMorphUnit
  GSetRemoveAll(
    &(that->units),
    unit);

}

// Burry the NeuraMorphUnits in the 'units' set into the
// NeuraMorph 'that'
// 'units' is empty after calling this function
// The NeuraMorphUnits iOutputs must point toward the NeuraMorph
// outputs
// NeuraMorphUnits' iOutputs are redirected toward new hidden values
// 'that->hiddens' is resized as necessary
void NMBurryUnits(
  NeuraMorph* that,
        GSet* units) {
```

```
#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  // Declare a variable to memorize the number of hidden values
  // to add
  long nbHiddenValues = 0;

  // While there are units to burry
  while (GSetNbElem(units) > 0) {

    // Get the unit
    NeuraMorphUnit* unit = GSetPop(units);

    // Loop on the iOutputs of the unit
    for (
      long iOutput = 0;
      iOutput < VecGetDim(NMUnitIOutputs(unit));
      ++iOutput) {

      long indice =
        VecGet(
          NMUnitIOutputs(unit),
          iOutput);
      VecSet(
        unit->iOutputs,
        iOutput,
        indice + nbHiddenValues);

    }

    // Append the unit to the set of NeuraMorphUnit
    GSetAppend(
      &(that->units),
      unit);

    // Update the number of new hidden values
    nbHiddenValues += VecGetDim(NMUnitIOutputs(unit));

  }

  // Resize the hiddens value vector
  if (that->hiddens != NULL) {

    nbHiddenValues += VecGetDim(that->hiddens);
    VecFree(&(that->hiddens));

  }

  if (nbHiddenValues > 0) {

    that->hiddens = VecFloatCreate(nbHiddenValues);
```

```
  }

}
```

3.2 neuramorph-inline.c

```
// ============ NEURAMORPH-INLINE.C ================

// ----- NeuraMorphUnit

// ================ Functions implementation ====================

// Get the input indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  return that->iInputs;

}

// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  return that->iOutputs;

}
```

```
// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  return that->outputs;

}

// ----- NeuraMorph

// ================ Functions implementation ====================

// Get the number of input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbInput(NeuraMorph* that) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  return that->nbInput;

}

// Get the number of output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbOutput(NeuraMorph* that) {

#if BUILDMODE == 0

  if (that == NULL) {
```

```
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  return that->nbOutput;

}

// Get the input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
VecFloat* NMInputs(NeuraMorph* that) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  return that->inputs;

}

// Get the output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMOutputs(const NeuraMorph* that) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  return that->outputs;

}
```

```
// Get the number of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbHidden(NeuraMorph* that) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

#endif

  long nb = 0;
  if (that->hiddens != NULL) {

    nb = VecGetDim(that->hiddens);

  }

  return nb;

}

// Set the number of hidden values of the NeuraMorph 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void NMSetNbHidden(
  NeuraMorph* that,
         long nb) {

#if BUILDMODE == 0

  if (that == NULL) {

    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);

  }

  if (nb <= 0) {

    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'nb' is invalid (%ld>0)",
      nb);
    PBErrCatch(NeuraMorphErr);

  }
```

```
#endif

  if (that->hiddens != NULL) {

    VecFree(&(that->hiddens));

  }

  that->hiddens = VecFloatCreate(nb);

}
```

4 Makefile

```
# Build mode
# 0: development (max safety, no optimisation)
# 1: release (min safety, optimisation)
# 2: fast and furious (no safety, optimisation)
BUILD_MODE?=0

all: pbmake_wget main

# Automatic installation of the repository PBMake in the parent folder
pbmake_wget:
if [ ! -d ../PBMake ]; then wget https://github.com/BayashiPascal/PBMake/archive/master.zip; unzip master.zip; rm -f

# Makefile definitions
MAKEFILE_INC=../PBMake/Makefile.inc
include $(MAKEFILE_INC)

# Rules to make the executable
repo=neuramorph
$($(repo)_EXENAME): \
$($(repo)_EXENAME).o \
$($(repo)_EXE_DEP) \
$($(repo)_DEP)
$(COMPILER) `echo "$($(repo)_EXE_DEP) $($(repo)_EXENAME).o" | tr ' ' '\n' | sort -u` $(LINK_ARG) $($(repo)_LINK_ARG)

$($(repo)_EXENAME).o: \
$($(repo)_DIR)/$($(repo)_EXENAME).c \
$($(repo)_INC_H_EXE) \
$($(repo)_EXE_DEP)
$(COMPILER) $(BUILD_ARG) $($(repo)_BUILD_ARG) `echo "$($(repo)_INC_DIR)" | tr ' ' '\n' | sort -u` -c $($(repo)_DIR)/$
```

5 Unit tests

```
#include <stdlib.h>
#include <stdio.h>
#include <time.h>
#include <string.h>
#include <time.h>
#include <unistd.h>
#include <sys/time.h>
#include "neuramorph.h"
```

```
void UnitTestNeuraMorphUnitCreateFree() {

  VecLong* iIn = VecLongCreate(3);
  VecSet(
    iIn,
    0,
    0);
  VecSet(
    iIn,
    1,
    1);
  VecSet(
    iIn,
    2,
    2);
  VecLong* iOut = VecLongCreate(2);
  VecSet(
    iOut,
    0,
    0);
  VecSet(
    iOut,
    1,
    1);
  NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
      iIn,
      iOut);
  if (
    VecGetDim(unit->coeffs[0]) != 10 ||
    VecGetDim(unit->outputs) != 2 ||
    VecGetDim(unit->lowFilters) != 4 ||
    VecGetDim(unit->highFilters) != 4 ||
    VecGetDim(unit->scaledInputs) != 4 ||
    unit->lowOutputs != NULL ||
    unit->highOutputs != NULL) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphUnitCreate failed (1)");
    PBErrCatch(NeuraMorphErr);

  }

  bool isSame =
    VecIsEqual(
      unit->iInputs,
      iIn);
  if (isSame == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphUnitCreate failed (2)");
    PBErrCatch(NeuraMorphErr);

  }

  isSame =
    VecIsEqual(
      unit->iOutputs,
```

```
      iOut);
  if (isSame == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphUnitCreate failed (3)");
    PBErrCatch(NeuraMorphErr);

  }

  NeuraMorphUnitFree(&unit);
  if (unit != NULL) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphUnitFree failed");
    PBErrCatch(NeuraMorphErr);

  }

  VecFree(&iIn);
  VecFree(&iOut);
  printf("UnitTestNeuraMorphUnitCreateFree OK\n");

}

void UnitTestNeuraMorphUnitGetSet() {

  VecLong* iIn = VecLongCreate(3);
  VecLong* iOut = VecLongCreate(2);
  NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
      iIn,
      iOut);

  if (NMUnitIInputs(unit) != unit->iInputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMUnitIInputs failed");
    PBErrCatch(NeuraMorphErr);

  }

  if (NMUnitIOutputs(unit) != unit->iOutputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMUnitIOutputs failed");
    PBErrCatch(NeuraMorphErr);

  }

  if (NMUnitOutputs(unit) != unit->outputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
```

```
      "NMUnitOutputs failed");
    PBErrCatch(NeuraMorphErr);

  }

  NeuraMorphUnitFree(&unit);
  VecFree(&iIn);
  VecFree(&iOut);
  printf("UnitTestNeuraMorphUnitGetSet OK\n");

}

void UnitTestNeuraMorphUnitEvaluate() {

  VecLong* iIn = VecLongCreate(3);
  VecLong* iOut = VecLongCreate(2);
  NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
      iIn,
      iOut);

  for (
    long iInput = 3;
    iInput--;) {

    VecSet(
      unit->lowFilters,
      iInput + 1,
      0.0);
    VecSet(
      unit->highFilters,
      iInput + 1,
      2.0);

  }

  // iOutput == 0 -> 1.0+x+y+z+x^2+xy+xz+y^2+yz+z^2
  // iOutput == 1 -> x^2-xy+2xz+3y^2-4yz+5z^2
  float coeffs[2][10] = {

    { 1.0, 1.0,  1.0, 1.0,  1.0,  1.0, 1.0,  1.0,  1.0, 1.0},
    { 0.0, 0.0,  1.0, 0.0, -1.0,  3.0, 0.0,  2.0, -4.0, 5.0}

  };
  for (
    long iOutput = 2;
    iOutput--;) {

    for (
      long iCoeff = 10;
      iCoeff--;) {

      VecSet(
        unit->coeffs[iOutput],
        iCoeff,
        coeffs[iOutput][iCoeff]);

    }

  }

  VecFloat* inputs = VecFloatCreate(3);
```

```
VecSet(
  inputs,
  0,
  1.0);
VecSet(
  inputs,
  1,
  3.0);
VecSet(
  inputs,
  2,
  1.5);

NMUnitEvaluate(
  unit,
  inputs);

float check[2];
float x = 2.0 * (1.0 - 0.0) / (2.0 - 0.0) - 1.0;
float y = 0.0; //2.0 * (3.0 - 0.0) / (2.0 - 0.0) - 1.0;
float z = 2.0 * (1.5 - 0.0) / (2.0 - 0.0) - 1.0;
check[0] = 1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z;
check[1] =
  x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z;
VecFloat2D checkHigh = VecFloatCreateStatic2D();
VecSet(
  &checkHigh,
  0,
  check[0]);
VecSet(
  &checkHigh,
  1,
  check[1]);
VecFloat2D checkLow = checkHigh;
for (
  long iOutput = 2;
  iOutput--;) {

  float v =
    VecGet(
      unit->outputs,
      iOutput);
  bool same =
    ISEQUALF(
      v,
      check[iOutput]);
  if (same == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMUnitEvaluate failed (1)");
    PBErrCatch(NeuraMorphErr);

  }

}

bool sameLow =
  VecIsEqual(
    &checkLow,
    unit->lowOutputs);
```

```
  bool sameHigh =
    VecIsEqual(
      &checkHigh,
      unit->highOutputs);
  if (
    sameLow == false ||
    sameHigh == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMUnitEvaluate failed (2)");
    PBErrCatch(NeuraMorphErr);

  }

  NeuraMorphUnitFree(&unit);
  VecFree(&iIn);
  VecFree(&iOut);
  VecFree(&inputs);
  printf("UnitTestNeuraMorphUnitEvaluate OK\n");

}

void UnitTestNeuraMorphUnit() {

  UnitTestNeuraMorphUnitCreateFree();
  UnitTestNeuraMorphUnitGetSet();
  UnitTestNeuraMorphUnitEvaluate();
  printf("UnitTestNeuraMorphUnit OK\n");

}

void UnitTestNeuraMorphCreateFree() {

  NeuraMorph* nm =
    NeuraMorphCreate(
      3,
      2);
  if (
    nm->nbInput != 3 ||
    nm->nbOutput != 2 ||
    VecGetDim(nm->inputs) != 3 ||
    VecGetDim(nm->outputs) != 2 ||
    nm->hiddens != NULL ||
    GSetNbElem(&(nm->units)) != 0) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphCreate failed");
    PBErrCatch(NeuraMorphErr);

  }

  NeuraMorphFree(&nm);
  if (nm != NULL) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphFree failed");
```

```
    PBErrCatch(NeuraMorphErr);

  }

  printf("UnitTestNeuraMorphCreateFree OK\n");

}

void UnitTestNeuraMorphGetSet() {

  NeuraMorph* nm =
    NeuraMorphCreate(
      3,
      2);
  if (NMGetNbInput(nm) != 3) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMGetNbInput failed");
    PBErrCatch(NeuraMorphErr);

  }

  if (NMGetNbOutput(nm) != 2) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMGetNbOutput failed");
    PBErrCatch(NeuraMorphErr);

  }

  if (NMGetNbHidden(nm) != 0) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMGetNbHidden failed");
    PBErrCatch(NeuraMorphErr);

  }

  NMSetNbHidden(
    nm,
    5);
  if (NMGetNbHidden(nm) != 5) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMSetNbHidden failed");
    PBErrCatch(NeuraMorphErr);

  }

  if (NMInputs(nm) != nm->inputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
```

```
      "NMInputs failed");
    PBErrCatch(NeuraMorphErr);

  }

  if (NMOutputs(nm) != nm->outputs) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMOutputs failed");
    PBErrCatch(NeuraMorphErr);

  }

  NeuraMorphFree(&nm);

  printf("UnitTestNeuraMorphGetSet OK\n");

}

void UnitTestNeuraMorphAddRemoveUnit() {

  VecLong3D iInputs = VecLongCreateStatic3D();
  VecSet(
    &iInputs,
    0,
    0);
  VecSet(
    &iInputs,
    1,
    1);
  VecSet(
    &iInputs,
    2,
    2);
  VecLong2D iOutputs = VecLongCreateStatic2D();
  VecSet(
    &iOutputs,
    0,
    0);
  VecSet(
    &iOutputs,
    1,
    1);

  NeuraMorph* nm =
    NeuraMorphCreate(
      3,
      2);

  NeuraMorphUnit* unit =
    NMAddUnit(
      nm,
      (VecLong*)&iInputs,
      (VecLong*)&iOutputs);

  bool isSameA =
    VecIsEqual(
      &iInputs,
      unit->iInputs);
  bool isSameB =
```

```
    VecIsEqual(
      &iOutputs,
      unit->iOutputs);
  if (
    GSetNbElem(&(nm->units)) != 1 ||
    GSetHead(&(nm->units)) != unit ||
    isSameA == false ||
    isSameB == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMAddUnit failed");
    PBErrCatch(NeuraMorphErr);

  }

  NeuraMorphFree(&nm);

  nm =
    NeuraMorphCreate(
      3,
      2);

  unit =
    NMAddUnit(
      nm,
      (VecLong*)&iInputs,
      (VecLong*)&iOutputs);

  NMRemoveUnit(
    nm,
    unit);

  if (GSetNbElem(&(nm->units)) != 0) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMRemoveUnit failed");
    PBErrCatch(NeuraMorphErr);

  }

  NeuraMorphUnitFree(&unit);
  NeuraMorphFree(&nm);

  printf("UnitTestNeuraMorphAddRemoveUnit OK\n");

}

void UnitTestNeuraMorphBurryUnits() {

  VecLong3D iInputs = VecLongCreateStatic3D();
  VecSet(
    &iInputs,
    0,
    0);
  VecSet(
    &iInputs,
    1,
    1);
```

```
VecSet(
  &iInputs,
  2,
  2);
VecLong2D iOutputs = VecLongCreateStatic2D();
VecSet(
  &iOutputs,
  0,
  0);
VecSet(
  &iOutputs,
  1,
  1);

NeuraMorph* nm =
  NeuraMorphCreate(
    3,
    2);

NeuraMorphUnit* unitA =
  NeuraMorphUnitCreate(
    (VecLong*)&iInputs,
    (VecLong*)&iOutputs);

NeuraMorphUnit* unitB =
  NeuraMorphUnitCreate(
    (VecLong*)&iInputs,
    (VecLong*)&iOutputs);

GSet units = GSetCreateStatic();
GSetAppend(
  &units,
  unitA);
GSetAppend(
  &units,
  unitB);

NMBurryUnits(
  nm,
  &units);

if (
  GSetNbElem(&units) != 0 ||
  nm->hiddens == NULL ||
  VecGetDim(nm->hiddens) != 4) {

  NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
  sprintf(
    NeuraMorphErr->_msg,
    "NMBurryUnits failed");
  PBErrCatch(NeuraMorphErr);

}

VecLong2D checkA = VecLongCreateStatic2D();
VecSet(
  &checkA,
  0,
  0);
VecSet(
  &checkA,
  1,
```

```
    1);
  VecLong2D checkB = VecLongCreateStatic2D();
  VecSet(
    &checkB,
    0,
    2);
  VecSet(
    &checkB,
    1,
    3);

  bool isSameA =
    VecIsEqual(
      &checkA,
      unitA->iOutputs);
  bool isSameB =
    VecIsEqual(
      &checkB,
      unitB->iOutputs);
  if (
    isSameA == false ||
    isSameB == false) {

    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMBurryUnits failed");
    PBErrCatch(NeuraMorphErr);

  }

  NeuraMorphFree(&nm);

  printf("UnitTestNeuraMorphBurryUnits OK\n");

}

void UnitTestNeuraMorph() {

  UnitTestNeuraMorphCreateFree();
  UnitTestNeuraMorphGetSet();
  UnitTestNeuraMorphAddRemoveUnit();
  UnitTestNeuraMorphBurryUnits();
  printf("UnitTestNeuraMorph OK\n");

}

void UnitTestAll() {

  UnitTestNeuraMorphUnit();
  UnitTestNeuraMorph();
  printf("UnitTestAll OK\n");

}

int main() {

  UnitTestAll();

  // Return success code
  return 0;
```

```
}
```

6 Unit tests output

```
UnitTestNeuraMorphUnitCreateFree OK
UnitTestNeuraMorphUnitGetSet OK
UnitTestNeuraMorphUnitEvaluate OK
UnitTestNeuraMorphUnit OK
UnitTestAll OK
```