# ${\bf NeuraMorph}$

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## Introduction

NeuraMorph is a C library providing structures and functions to implement a neural network.

It uses the PBErr, PBMath, GSet library.

# 1 Definitions

#### 2 Interface

// ======= NEURAMORPH.H =======

```
#ifndef NEURAMORPH_H
#define NEURAMORPH_H
// ======== Include =========
#include <stdlib.h>
#include <stdio.h>
#include <math.h>
#include <string.h>
#include <stdbool.h>
#include "pberr.h"
#include "pbmath.h"
#include "gset.h"
#include "gdataset.h"
// ---- NeuraMorphUnit
// ====== Data structure ========
typedef struct NeuraMorphUnit {
  // Input indices in parent NeuraMorph
  VecLong* iInputs;
  // Output indices in parent NeuraMorph
  VecLong* iOutputs;
  // Lowest and highest values for filtering inputs
  VecFloat* lowFilters;
  VecFloat* highFilters;
  // Lowest and highest values of outputs
  VecFloat* lowOutputs;
  VecFloat* highOutputs;
  // Vector to memorize the output values
  VecFloat* outputs;
  // Transfer function coefficients
  // Seen as (nb output) triangular matrices of size (nb input + 1)
  VecFloat** coeffs;
  // Working variables to avoid reallocation of memory at each Evaluate()
  bool* activeInputs;
  VecFloat* scaledInputs;
} NeuraMorphUnit;
// ========= Functions declaration ==========
// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
  const VecLong* iInputs,
  const VecLong* iOutputs);
// Free the memory used by the NeuraMorphUnit 'that'
void NeuraMorphUnitFree(NeuraMorphUnit** that);
// Get the input indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
```

```
#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that);
// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that);
// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that);
// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
  NeuraMorphUnit* that,
  const VecFloat* inputs);
// ---- NeuraMorph
// ========= Data structure ==========
typedef struct NeuraMorph {
  // Number of inputs and outputs
  long nbInput;
  long nbOutput;
  // Inputs and outputs values
  VecFloat* inputs;
  VecFloat* outputs;
  // Internal values
  VecFloat* hiddens;
  // GSet of NeuraMorphUnit
  GSet units;
} NeuraMorph;
// ====== Functions declaration ========
// Create a new NeuraMorph with 'nbInput' inputs and 'nbOutput' outputs
NeuraMorph* NeuraMorphCreate(
  long nbInput,
  long nbOutput);
// Free the memory used by the NeuraMorph 'that'
void NeuraMorphFree(NeuraMorph** that);
// Get the number of input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
long NMGetNbInput(NeuraMorph* that);
// Get the number of output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
```

```
#endif
long NMGetNbOutput(NeuraMorph* that);
// Get the input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
VecFloat* NMInputs(NeuraMorph* that);
// Get the output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMOutputs(const NeuraMorph* that);
// Get the number of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbHidden(NeuraMorph* that);
// Set the number of hidden values of the NeuraMorph 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void NMSetNbHidden(
  NeuraMorph* that,
        long nb);
// ========= static inliner =========
#if BUILDMODE != 0
#include "neuramorph-inline.c"
#endif
#endif
```

#### 3 Code

#### 3.1 neuramorph.c

```
// NeuraMorphUnit 'that' for the output 'iOutput'
float NMUnitGetCoeff(
  const NeuraMorphUnit* that,
                   long iInputA,
                   long iInputB,
                   long iOutput);
// ====== Functions implementation =========
// Create a new NeuraMorphUnit between the input 'iInputs' and the
// outputs 'iOutputs'
NeuraMorphUnit* NeuraMorphUnitCreate(
  const VecLong* iInputs,
  const VecLong* iOutputs) {
#if BUILDMODE == 0
  if (iInputs == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'iInputs' is null");
    PBErrCatch(NeuraMorphErr);
  if (iOutputs == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'iOutputs' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  // Allocate memory for the NeuraMorphUnit
  NeuraMorphUnit* that =
    PBErrMalloc(
      NeuraMorphErr,
      sizeof(NeuraMorphUnit));
  // Get the number of inputs (including the constant) and outputs
  long nbIn = VecGetDim(iInputs) + 1;
long nbOut = VecGetDim(iOutputs);
  // Init properties
  that->iInputs = VecClone(iInputs);
  that->iOutputs = VecClone(iOutputs);
  that->lowFilters = VecFloatCreate(nbIn);
  that->highFilters = VecFloatCreate(nbIn);
  that->lowOutputs = NULL;
  that->highOutputs = NULL;
  that->outputs = VecFloatCreate(nbOut);
  that->coeffs =
    PBErrMalloc(
      NeuraMorphErr,
      sizeof(VecFloat*) * nbOut);
  long nbCoeff = NMUnitGetNBCoeff(nbIn);
```

```
for (
    long iOut = nbOut;
    that->coeffs[iOut] = VecFloatCreate(nbCoeff));
  // 'nbIn + 1' for the constant
  that->activeInputs =
    PBErrMalloc(
      NeuraMorphErr,
      sizeof(bool) * nbIn);
  that->scaledInputs = VecFloatCreate(nbIn);
  // Set the input value, filters and active flag for the constant
    that->scaledInputs,
    Ο,
    1.0);
  that->activeInputs[0] = true;
  // Return the new NeuraMorphUnit
  return that;
}
// Free the memory used by the NeuraMorphUnit 'that'
{\tt void \ NeuraMorphUnitFree(NeuraMorphUnit**\ that)\ \{}
  // Check the input
  if (that == NULL || *that == NULL) {
    return;
  }
  // Free memory
  long nbOut = VecGetDim((*that)->iOutputs);
  VecFree(&((*that)->iInputs));
  VecFree(&((*that)->iOutputs));
  VecFree(&((*that)->lowFilters));
  VecFree(&((*that)->highFilters));
  if ((*that)->lowOutputs != NULL) {
    VecFree(&((*that)->lowOutputs));
  if ((*that)->highOutputs != NULL) {
    VecFree(&((*that)->highOutputs));
  }
  VecFree(&((*that)->outputs));
  for (
    long iOut = nbOut;
    iOut--;
    VecFree((*that)->coeffs + iOut));
  free((*that)->coeffs);
  free((*that)->activeInputs);
  VecFree(&((*that)->scaledInputs));
  free(*that);
  *that = NULL;
```

```
}
// Return the number of coefficients of a NeuraMorphUnit having 'nbIn' inputs
long NMUnitGetNBCoeff(long nbIn) {
#if BUILDMODE == 0
  if (nbIn <= 0) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'nbIn' is invalid (%ld>0)",
      nbIn);
    PBErrCatch(NeuraMorphErr);
  }
#endif
  // Declare a variable to memorise the result
  long nb = 0;
  /\!/ Calculate the number of values in the triangular matrix of size
  // nbIn
  for (
    long i = nbIn;
    i >= 0;
    nb += (i--));
  // Return the result
  return nb;
}
// Calculate the outputs for the 'inputs' with the NeuraMorphUnit 'that'
// Update 'that->outputs'
void NMUnitEvaluate(
  NeuraMorphUnit* that,
  const VecFloat* inputs) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
  if (VecGetDim(inputs) != VecGetDim(that->iInputs)) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
      NeuraMorphErr->_msg,
      "'inputs' has invalid dimension (%ld!=%ld)", VecGetDim(inputs),
      VecGetDim(that->iInputs));
```

```
PBErrCatch(NeuraMorphErr);
  }
#endif
  // Reset the outputs
  VecSetNull(that->outputs);
  // Update the active flags \, and scaled inputs (skip the constant)
  for (
    long iInput = 1;
    iInput < VecGetDim(that->scaledInputs);
    ++iInput) {
    // Get the input value and its low/high filters
    float val =
      VecGet(
        inputs,
        iInput - 1);
    float low =
      VecGet(
       that->lowFilters,
        iInput);
    float high =
      VecGet(
        that->highFilters,
        iInput);
    // If the value is inside the filter
    if (
      low <= val &&
      val <= high &&
      (high - low) > PBMATH_EPSILON) {
      // Set this value as active
      that->activeInputs[iInput] = true;
      // Scale the value according to the filter
      float scaled = 2.0 * (val - low) / (high - low) - 1.0;
      VecSet(
        that->scaledInputs,
        iInput,
        scaled);
    // Else the value is outside the filter
    } else {
      // Set this value as inactive
      that->activeInputs[iInput] = false;
   }
  }
  // Loop on the pair of active inputs
  for (
    long iInputA = 0;
    iInputA < VecGetDim(that->scaledInputs);
    ++iInputA) {
    if (that->activeInputs[iInputA] == true) {
```

```
for (
      long iInputB = 0;
      iInputB <= iInputA;</pre>
      ++iInputB) {
      if (that->activeInputs[iInputB] == true) {
        // Loop on the outputs
        for (
          long iOutput = 0;
          iOutput < VecGetDim(that->outputs);
          ++iOutput) {
          // Calculate the components for this output and pair of inputs
          float comp =
            VecGet(
              that->scaledInputs,
              iInputA) *
            VecGet(
              that->scaledInputs,
              iInputB) *
            NMUnitGetCoeff(
              that,
              iInputA,
              iInputB,
              iOutput);
          \ensuremath{//} Add the component to the output
          float cur =
            VecGet(
              that->outputs,
              iOutput);
          VecSet(
            that->outputs,
            iOutput,
            cur + comp);
        }
      }
    }
  }
}
// If the low and high values for outputs don't exist yet
if (that->lowOutputs == NULL) {
  // Create the low and high values by cloning the current output
  that->lowOutputs = VecClone(that->outputs);
  that->highOutputs = VecClone(that->outputs);
\ensuremath{//} Else, the low and high values for outputs exist
} else {
  // Loop on the outputs
  for (
    long iOutput = 0;
    iOutput < VecGetDim(that->outputs);
```

```
++iOutput) {
      \ensuremath{//} Update the low and high values for this output
      float val =
        VecGet(
          that->outputs,
          iOutput);
      float curLow =
        VecGet(
          that->lowOutputs,
          iOutput);
      if (curLow > val) {
        VecSet(
          that->lowOutputs,
          iOutput,
          val);
      }
      float curHigh =
        VecGet(
          that->highOutputs,
      iOutput);
if (curHigh < val) {</pre>
        VecSet(
          that->highOutputs,
          iOutput,
          val);
      }
    }
  }
}
// Get the coefficient for the pair of inputs 'iInputA', 'iInputB' in the
// NeuraMorphUnit 'that' for the output 'iOutput'
float NMUnitGetCoeff(
  const NeuraMorphUnit* that,
                    long iInputA,
                    long iInputB,
                    long iOutput) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
  if (
    iInputA < 0 ||
```

```
iInputA >= VecGetDim(that->scaledInputs)) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
   sprintf(
     NeuraMorphErr->_msg,
     "'iInputA' is invalid (0<=%ld<%ld)",
     iInputA,
     VecGetDim(that->scaledInputs));
   PBErrCatch(NeuraMorphErr);
 }
 if (
    iInputB < 0 ||
   iInputB >= VecGetDim(that->scaledInputs)) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
     NeuraMorphErr->_msg,
      "'iInputB' is invalid (0<=%ld<%ld)",
     iInputB,
     VecGetDim(that->scaledInputs));
   PBErrCatch(NeuraMorphErr);
 }
 if (iInputA < iInputB) {</pre>
   NeuraMorphErr->_type = PBErrTypeInvalidArg;
   sprintf(
     NeuraMorphErr->_msg,
     "The pair of indices is invalid (%ld>=%ld)",
     iInputA,
     iInputB);
   PBErrCatch(NeuraMorphErr);
 }
 if (
    iOutput < 0 ||
    iOutput >= VecGetDim(that->outputs)) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
    sprintf(
     NeuraMorphErr->_msg,
     "'iInputB' is invalid (0<=%ld<%ld)",
     iInputB,
     VecGetDim(that->outputs));
   PBErrCatch(NeuraMorphErr);
 }
#endif
 // Calculate the index of the coefficient
 long iCoeff = 0;
 for (
   long shift = 0;
    shift < iInputA;</pre>
   iCoeff += (shift++) + 1);
 iCoeff += iInputB;
```

```
// Return the coefficient
  float coeff =
    VecGet(
     that->coeffs[iOutput],
     iCoeff);
 return coeff;
}
// ---- NeuraMorph
// ====== Functions implementation ========
// Create a new NeuraMorph with 'nbInput' inputs and 'nbOutput' outputs
NeuraMorph* NeuraMorphCreate(
  long nbInput,
  long nbOutput) {
  // Allocate memory for the NeuraMorph
  NeuraMorph* that =
    PBErrMalloc(
     NeuraMorphErr,
     sizeof(NeuraMorph));
  // Init properties
  that->nbInput = nbInput;
  that->nbOutput = nbOutput;
  that->inputs = VecFloatCreate(nbInput);
  that->outputs = VecFloatCreate(nbOutput);
  that->hiddens = NULL;
  that->units = GSetCreateStatic();
  // Return the NeuraMorph
  return that;
// Free the memory used by the NeuraMorph 'that'
void NeuraMorphFree(NeuraMorph** that) {
  // Check the input
  if (that == NULL || *that == NULL) {
    return;
  }
  // Free memory
  VecFree(&((*that)->inputs));
  VecFree(&((*that)->outputs));
  if ((*that)->hiddens != NULL) {
    VecFree(&((*that)->hiddens));
  }
  while (GSetNbElem(\&((*that)->units)) > 0) {
    NeuraMorphUnit* unit = GSetPop(&((*that)->units));
    NeuraMorphUnitFree(&unit);
  }
```

```
free(*that);
*that = NULL;
}
```

#### 3.2 neuramorph-inline.c

```
// ====== NEURAMORPH-INLINE.C ========
// ---- NeuraMorphUnit
// ====== Functions implementation =======
// Get the input indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIInputs(const NeuraMorphUnit* that) {
#if BUILDMODE == 0
  if (that == NULL) {
   NeuraMorphErr->_type = PBErrTypeNullPointer;
   sprintf(
     NeuraMorphErr->_msg,
      "'that' is null");
   PBErrCatch(NeuraMorphErr);
#endif
  return that->iInputs;
// Get the output indices of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecLong* NMUnitIOutputs(const NeuraMorphUnit* that) {
#if BUILDMODE == 0
  if (that == NULL) {
   NeuraMorphErr->_type = PBErrTypeNullPointer;
   sprintf(
     NeuraMorphErr->_msg,
      "'that' is null");
   PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->iOutputs;
```

```
}
// Get the output values of the NeuraMorphUnit 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMUnitOutputs(const NeuraMorphUnit* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->outputs;
// ---- NeuraMorph
// ====== Functions implementation =========
// Get the number of input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbInput(NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
   "'that' is null");
PBErrCatch(NeuraMorphErr);
  }
#endif
 return that->nbInput;
}
// Get the number of output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbOutput(NeuraMorph* that) {
#if BUILDMODE == 0
```

```
if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->nbOutput;
}
// Get the input values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
VecFloat* NMInputs(NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
     NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->inputs;
}
// Get the output values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
const VecFloat* NMOutputs(const NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  return that->outputs;
```

```
}
// Get the number of hidden values of the NeuraMorph 'that'
#if BUILDMODE != 0
static inline
#endif
long NMGetNbHidden(NeuraMorph* that) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  }
#endif
  long nb = 0;
  if (that->hiddens != NULL) {
    nb = VecGetDim(that->hiddens);
  }
 return nb;
}
// Set the number of hidden values of the NeuraMorph 'that' to 'nb'
#if BUILDMODE != 0
static inline
#endif
void NMSetNbHidden(
  NeuraMorph* that,
         long nb) {
#if BUILDMODE == 0
  if (that == NULL) {
    NeuraMorphErr->_type = PBErrTypeNullPointer;
    sprintf(
      NeuraMorphErr->_msg,
      "'that' is null");
    PBErrCatch(NeuraMorphErr);
  if (nb <= 0) {
    NeuraMorphErr->_type = PBErrTypeInvalidArg;
      NeuraMorphErr->_msg,
      "'nb' is invalid (%ld>0)",
      nb);
    PBErrCatch(NeuraMorphErr);
```

```
}
#endif
if (that->hiddens != NULL) {
    VecFree(&(that->hiddens));
}
that->hiddens = VecFloatCreate(nb);
}
```

#### 4 Makefile

```
# Build mode
# 0: development (max safety, no optimisation)
# 1: release (min safety, optimisation)
# 2: fast and furious (no safety, optimisation)
BUILD_MODE?=0
all: pbmake_wget main
# Automatic installation of the repository PBMake in the parent folder
if [ ! -d ../PBMake ]; then wget https://github.com/BayashiPascal/PBMake/archive/master.zip; unzip master.zip; rm -f
# Makefile definitions
MAKEFILE_INC=../PBMake/Makefile.inc
include $(MAKEFILE_INC)
# Rules to make the executable
repo=neuramorph
$($(repo)_EXENAME): \
(pos)_{EXENAME}.o
$($(repo)_EXE_DEP) \
$($(repo)_DEP)
$(COMPILER) 'echo "$($(repo)_EXE_DEP) $($(repo)_EXENAME).o" | tr ' ' '\n' | sort -u' $(LINK_ARG) $($(repo)_LINK_ARG)
$($(repo)_EXENAME).o: \
((repo)_DIR)/((repo)_EXENAME).c
$($(repo)_INC_H_EXE) \
$($(repo)_EXE_DEP)
$(COMPILER) $(BUILD_ARG) $($(repo)_BUILD_ARG) 'echo "$($(repo)_INC_DIR)" | tr ', ', '\n' | sort -u' -c $($(repo)_DIR)/
```

#### 5 Unit tests

```
#include <stdlib.h>
#include <stdio.h>
#include <time.h>
#include <string.h>
#include <time.h>
#include <unistd.h>
#include <sys/time.h>
#include "neuramorph.h"
```

```
void UnitTestNeuraMorphUnitCreateFree() {
 VecLong* iIn = VecLongCreate(3);
 VecSet(
   iIn,
   Ο,
   0);
 VecSet(
   iIn,
   1,
   1);
 VecSet(
   iIn,
   2,
   2);
 VecLong* iOut = VecLongCreate(2);
 VecSet(
    iOut,
   Ο,
   0);
 VecSet(
   iOut,
   1);
 NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
     iIn,
     iOut);
 if (
    VecGetDim(unit->coeffs[0]) != 10 ||
   VecGetDim(unit->outputs) != 2 ||
    VecGetDim(unit->lowFilters) != 4 ||
   VecGetDim(unit->highFilters) != 4 ||
   VecGetDim(unit->scaledInputs) != 4 ||
   unit->lowOutputs != NULL ||
   unit->highOutputs != NULL) {
   NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NeuraMorphUnitCreate failed (1)");
   PBErrCatch(NeuraMorphErr);
 }
 bool isSame =
    VecIsEqual(
     unit->iInputs,
      iIn);
 if (isSame == false) {
   NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
   sprintf(
     NeuraMorphErr->_msg,
      "NeuraMorphUnitCreate failed (2)");
   PBErrCatch(NeuraMorphErr);
 }
 isSame =
   VecIsEqual(
```

```
unit->iOutputs,
      iOut);
  if (isSame == false) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphUnitCreate failed (3)");
    PBErrCatch(NeuraMorphErr);
  }
  NeuraMorphUnitFree(&unit);
  if (unit != NULL) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphUnitFree failed");
    PBErrCatch(NeuraMorphErr);
  VecFree(&iIn);
  VecFree(&iOut);
  printf("UnitTestNeuraMorphUnitCreateFree \ OK\n");\\
}
void UnitTestNeuraMorphUnitGetSet() {
  VecLong* iIn = VecLongCreate(3);
  VecLong* iOut = VecLongCreate(2);
  NeuraMorphUnit* unit =
    NeuraMorphUnitCreate(
      iIn,
      iOut);
  if (NMUnitIInputs(unit) != unit->iInputs) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMUnitIInputs failed");
    PBErrCatch(NeuraMorphErr);
  }
  if (NMUnitIOutputs(unit) != unit->iOutputs) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMUnitIOutputs failed");
    PBErrCatch(NeuraMorphErr);
  if (NMUnitOutputs(unit) != unit->outputs) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
```

```
NeuraMorphErr->_msg,
     "NMUnitOutputs failed");
   PBErrCatch(NeuraMorphErr);
 NeuraMorphUnitFree(&unit);
 VecFree(&iIn);
 VecFree(&iOut);
 printf("UnitTestNeuraMorphUnitGetSet OK\n");
void UnitTestNeuraMorphUnitEvaluate() {
 VecLong* iIn = VecLongCreate(3);
 VecLong* iOut = VecLongCreate(2);
 NeuraMorphUnit* unit =
   NeuraMorphUnitCreate(
     iIn,
     iOut);
 for (
   long iInput = 3;
   iInput--;) {
   VecSet(
     unit->lowFilters,
     iInput + 1,
     0.0);
   VecSet(
     unit->highFilters,
     iInput + 1,
     2.0);
 // iOutput == 0 -> 1.0+x+y+z+x^2+xy+xz+y^2+yz+z^2
 // iOutput == 1 -> x^2-xy+2xz+3y^2-4yz+5z^2
 float coeffs[2][10] = {
   };
 for (
   long iOutput = 2;
   iOutput--;) {
   for (
     long iCoeff = 10;
     iCoeff--;) {
     VecSet(
       unit->coeffs[iOutput],
       iCoeff,
       coeffs[iOutput][iCoeff]);
   }
 }
```

```
VecFloat* inputs = VecFloatCreate(3);
VecSet(
  inputs,
 0,
1.0);
VecSet(
  inputs,
 3.0);
VecSet(
 inputs,
 2,
1.5);
NMUnitEvaluate(
  unit,
  inputs);
float check[2];
float x = 2.0 * (1.0 - 0.0) / (2.0 - 0.0) - 1.0;
float y = 0.0; //2.0 * (3.0 - 0.0) / (2.0 - 0.0) - 1.0;
float z = 2.0 * (1.5 - 0.0) / (2.0 - 0.0) - 1.0;

check[0] = 1.0 + x + y + z + x * x + x * y + x * z + y * y + y * z + z * z;
 x * x - x * y + 2.0 * x * z + 3.0 * y * y - 4.0 * y * z + 5.0 * z * z;
VecFloat2D checkHigh = VecFloatCreateStatic2D();
VecSet(
  &checkHigh,
  Ο,
 check[0]);
VecSet(
  &checkHigh,
  1,
  check[1]);
VecFloat2D checkLow = checkHigh;
for (
  long iOutput = 2;
  iOutput--;) {
  float v =
    VecGet(
      unit->outputs,
      iOutput);
  bool same =
    ISEQUALF(
      check[iOutput]);
  if (same == false) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMUnitEvaluate failed (1)");
    PBErrCatch(NeuraMorphErr);
  }
}
bool sameLow =
  VecIsEqual(
    &checkLow,
```

```
unit->lowOutputs);
 bool sameHigh =
    VecIsEqual(
     &checkHigh,
     unit->highOutputs);
    sameLow == false ||
    sameHigh == false) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
      "NMUnitEvaluate failed (2)");
    PBErrCatch(NeuraMorphErr);
 NeuraMorphUnitFree(&unit);
 VecFree(&iIn);
 VecFree(&iOut);
 VecFree(&inputs);
 printf("UnitTestNeuraMorphUnitEvaluate OK\n");
void UnitTestNeuraMorphUnit() {
 UnitTestNeuraMorphUnitCreateFree();
 UnitTestNeuraMorphUnitGetSet();
 UnitTestNeuraMorphUnitEvaluate();
 printf("UnitTestNeuraMorphUnit OK\n");
void UnitTestNeuraMorphCreateFree() {
 NeuraMorph* nm =
    NeuraMorphCreate(
     3,
     2);
 if (
   nm->nbInput != 3 ||
   nm->nbOutput != 2 ||
    VecGetDim(nm->inputs) != 3 ||
   VecGetDim(nm->outputs) != 2 ||
   nm->hiddens != NULL ||
   GSetNbElem(&(nm->units)) != 0) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphCreate failed");
   PBErrCatch(NeuraMorphErr);
 }
 NeuraMorphFree(&nm);
 if (nm != NULL) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
     NeuraMorphErr->_msg,
```

```
"NeuraMorphFree failed");
    PBErrCatch(NeuraMorphErr);
  }
  printf("UnitTestNeuraMorphCreateFree OK\n");
}
void UnitTestNeuraMorphGetSet() {
  NeuraMorph* nm =
    {\tt NeuraMorphCreate(}
      3,
      2):
  if (NMGetNbInput(nm) != 3) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
      NeuraMorphErr->_msg,
      "NMGetNbInput failed");
    PBErrCatch(NeuraMorphErr);
  if (NMGetNbOutput(nm) != 2) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMGetNbOutput failed");
    PBErrCatch(NeuraMorphErr);
  }
  if (NMGetNbHidden(nm) != 0) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMGetNbHidden failed");
    PBErrCatch(NeuraMorphErr);
  NMSetNbHidden(
    nm,
    5);
  if (NMGetNbHidden(nm) != 5) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
      NeuraMorphErr->_msg,
      "NMSetNbHidden failed");
    PBErrCatch(NeuraMorphErr);
  if (NMInputs(nm) != nm->inputs) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
```

```
NeuraMorphErr->_msg,
      "NMInputs failed");
    PBErrCatch(NeuraMorphErr);
  if (NMOutputs(nm) != nm->outputs) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NMOutputs failed");
    PBErrCatch(NeuraMorphErr);
  }
  NeuraMorphFree(&nm);
  if (nm != NULL) {
    NeuraMorphErr->_type = PBErrTypeUnitTestFailed;
    sprintf(
      NeuraMorphErr->_msg,
      "NeuraMorphFree failed");
    PBErrCatch(NeuraMorphErr);
  printf("UnitTestNeuraMorphCreateFree OK\n");
void UnitTestNeuraMorph() {
  UnitTestNeuraMorphCreateFree();
  UnitTestNeuraMorphGetSet();
  printf("UnitTestNeuraMorph OK\n");
void UnitTestAll() {
  UnitTestNeuraMorphUnit();
  UnitTestNeuraMorph();
  printf("UnitTestAll OK\n");
}
int main() {
  UnitTestAll();
  // Return success code
  return 0;
}
```

# 6 Unit tests output

UnitTestNeuraMorphUnitCreateFree OK

UnitTestNeuraMorphUnitGetSet OK UnitTestNeuraMorphUnitEvaluate OK UnitTestNeuraMorphUnit OK UnitTestAll OK