Probabilistic Machine Learning with Julia

Lecture 3 | Probabilistic Programs

Amirabbas Asadi

amir.asadi78@sharif.edu

2025

About the Course

Probabilistic Machine Learning with Julia

Exploring Julia ecosystem for probabilistic modeling and inference focused on probabilistic programming

Course page: bayesianrl.github.io/pml2025

Lecturer: Amirabbas Asadi (amir.asadi78@sharif.edu)





Course Outline

- Intoroduction to Julia
- Introduction to Probabilistic Programming
- Probabilistic Modeling
 - Parametric Probabilistic Models
 - Basic Latent Variable Models [Turing.jl]
 - Bayesian Deep Learning [Turing.jl, Lux.jl]
 - Bayesian Differential Equations [DifferentialEquations.jl]
 - Nonparametric Probabilistic Models [GaussianProcesses.jl]
- Inference
 - Markov Chain Monte Carlo [AdvancedMH.jl, AdvancedHMC.jl]
 - Parametric Variational Inference [AdvancedVI.jl]
 - Nonparametric Variational Inference [Nonparametric VI.jl]
 - Reactive Message Passing [RxInfer.jl]
- Applications
 - Probabilistic Time Series Modeling
 - Bayesian Optimization
 - Bayesian Reinforcement Learning
 - Active Inference



Probabilistic Programs

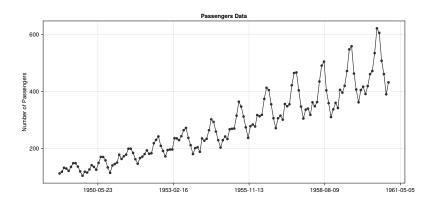
The meeting of grammars and stochastic processes





https://yuu6883.github.io/MarkovJuniorWeb/

A Simple Time Series Example





Let's denote the number of passengers at time au by $Y_{ au}$

$$Y_1,Y_2,Y_3,\cdots Y_T$$

Our goal is to design a probabilistic model:

$$p(Y_1 = y_1, Y_2 = y_2, Y_3 = y_3, \cdots, Y_T = y_T)$$

$$Y_1,Y_2,Y_3,\cdots,Y_T$$

In our very first example, we assume Y_i are i.i.d !!!

$$p(y_1,y_2,\cdots,y_T) = p(y_1)p(y_2)\cdots p(y_T)$$

We further assume they follow a Poisson distribution:

$$p(Y_\tau=k;\lambda)=\frac{\lambda^k e^{-\lambda}}{k!}$$



The two main functions in any probabilistic programming language are:

- sample : Generating a random variable from a distribution
- observe : Conditioning on observed data

The two main functions in any probabilistic programming language are:

- **sample**: Generating a random variable from a distribution
- observe : Conditioning on observed data

For example this program only includes sampling and defines a joint density

```
Qmodel function p() \lambda \sim \text{Exponential}(300.0) y \sim \text{Poisson}(\lambda) end
```

$$p(\lambda, y)$$



$$p(\lambda,y)$$

So far we haven't see anything more than simulation. The main feature of probabilistic programs is conditioning the model on observed data.

$$p(\lambda, y)$$

So far we haven't see anything more than simulation. The main feature of probabilistic programs is conditioning the model on observed data.

$$\widetilde{p(\lambda|y)} = \frac{\overbrace{p(y|\lambda)}^{\text{pikelihood Prior}}}{\underbrace{p(y|\lambda)}_{\text{evidence}}}$$

$$p(\lambda, y)$$

So far we haven't see anything more than simulation. The main feature of probabilistic programs is conditioning the model on observed data.

$$\underbrace{\widetilde{p(\lambda|y)}}_{\text{posterior}} = \underbrace{\frac{\widetilde{p(y|\lambda)}}{\widetilde{p(y)}}}_{\substack{\widetilde{p(y)} \\ \text{evidence}}}$$

$$p(\lambda|y) \propto p(y|\lambda)p(\lambda)$$



Observing a variable simply means conditioning. We usually pass observations as arguments to the model:

```
Qmodel function p(y_obs)

\lambda \sim Exponential(300.0)

y_obs \sim Poisson(\lambda)

end
```

$$p(\lambda|y_{\rm obs})$$

Unobserved variables like λ here are called latent variable. We need to specify a prior for each latent variable like Exponential in the above example.



We use Turing.jl to define a probabilistic program:

using Turing

To create a probabilistic program with Turing wrap a function in <code>Qmodel</code> macro

@model function naive_model(y)

end

Here y is a vector of observed data.



```
We use Turing.jl to define a probabilistic program:
```

using Turing

We use operator ~ to sample a variable:

@model function naive_model(y)

 $\lambda \sim \text{Exponential}(300.0)$

end

Exponential is defined in Distributions.jl package.



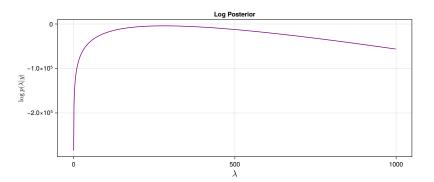
```
We use Turing. jl to define a probabilistic program:
using Turing
We can use usual control flows (while, for, if, ...) inside a probabilistic program:
@model function naive_model(y)
     \lambda \sim \text{Exponential}(300.0)
     for \tau \in eachindex(y)
          y[\tau] \sim Poisson(\lambda)
     end
end
```

Note that we have used ~ for both sampling latent variables and observing data.

```
@model function naive_model(y)
     \lambda \sim \text{Exponential}(300.0)
     for \tau \in eachindex(y)
          y[\tau] \sim Poisson(\lambda)
     end
end
Once the model is defined, we can generate samples from prior:
rand(naive_model(y))
# output
(\lambda = 205.46898514251205,)
```

We can also evaluate the unnormalized posterior:

logjoint(naive_model(y), $(\lambda=\lambda_0)$)



We can compute **Maximum a Posterior** estimation using Optim.jl package.

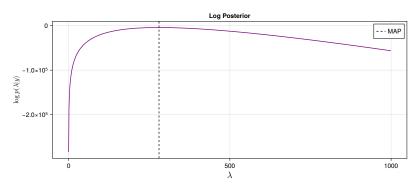
$$\lambda_{\mathrm{MAP}} = \mathrm{argmax}_{\lambda} \, p(\lambda|y)$$

using Optim
optimize(naive_model(y), MAP(), LBFGS())

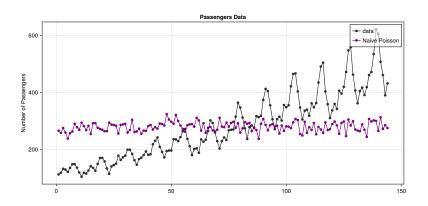
We can compute **Maximum a Posterior** estimation using Optim.jl package.

$$\lambda_{\mathrm{MAP}} = \mathrm{argmax}_{\lambda} \, p(\lambda|y)$$

using Optim
optimize(naive_model(y), MAP(), LBFGS())







To make the model realistic, we can assume λ changes over time.

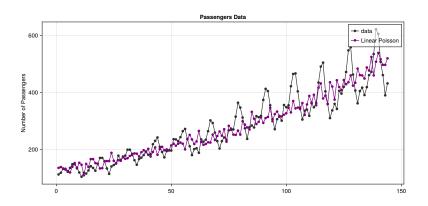
$$Y_{\tau} \sim \text{Poisson}(\lambda_{\tau})$$

This model is known as **Poisson Regression** where $\log \lambda_{\tau}$ changes linearly over time.

$$\log \lambda_\tau = \alpha \tau + \beta$$



```
\label{eq:continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous_continuous
```

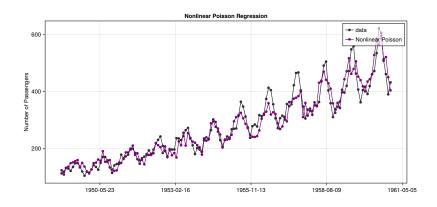


$$\log \lambda_{\tau} = \alpha \tau + \beta$$

One can add a nonlinear component to handle seasonality

$$\log \lambda_\tau = \alpha \tau + \nu \cos(\pi \omega (\tau - \phi)) + \beta$$

```
@model function poisson_nonlinear_model(y)
     \alpha \sim Normal(0.0, 2.0)
     \beta \sim Normal(0.0, 2.0)
     \nu \sim Normal(0.0, 2.0)
     \phi \sim Normal(0.0, 2.0)
     \omega \sim Normal(0.0, 2.0)
     for τ in 1:length(v)
           log_{\lambda} = \alpha * \tau + \nu * cos(\pi * \omega * (\tau - \phi)) + \beta
           y[\tau] \sim Poisson(exp(log_{\lambda}))
     end
end
```



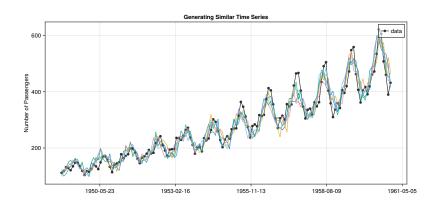


Examples

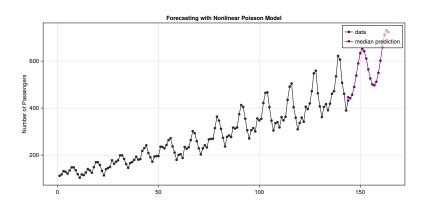
What else can we do with this probabilistic model?



Example: Data Generation

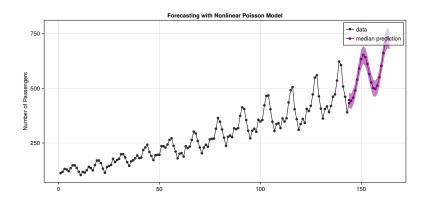


Example: Forecasting





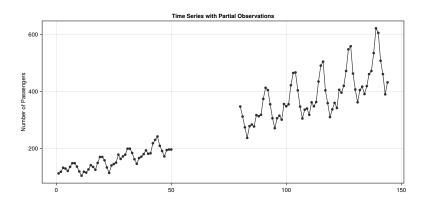
Example: Probabilistic Forecasting



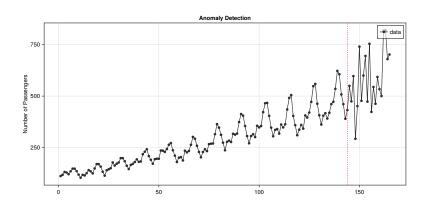
Note that the predicted interval does not look great, Why?



Example: Interpolation

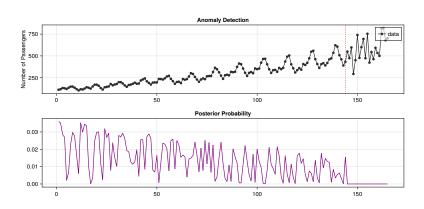


Example: Anomaly Detection





Example: Anomaly Detection





Classification of Probabilistic Programming Languages

All of the probabilistic programs which we have seen so far are called **First-Order Probabilistic Programs** because no **stochastic branching** happens and runtime flow is deterministic.

Classification of Probabilistic Programming Languages

All of the probabilistic programs which we have seen so far are called **First-Order Probabilistic Programs** because no **stochastic branching** happens and runtime flow is deterministic.

```
@model function program_with_stochastic_branch()
   N ~ Poisson(10)
   S = 0
   for i in 1:N
       S += 1
   end
```

end

The representation power of First-Order Probabilistic Programming Languages (FOPLs) is equal to Probabilistic Graphical Models'!



Next Session

In the next session, we will discuss alternative models for our time series problem:

- Bayesian Differential Equation
- State-Space Models
- Bayesian Neural Networks
- Nonparametric Models