



YANDAMURI BALA BRAHMARSH

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SUMMARY

Final-year Electronics and Communication Engineering undergraduate with strong foundations in digital logic design, computer architecture, and embedded systems. Experience translating system requirements into hardware-aware implementations, with exposure to RTL-level thinking, performance optimization, and verification concepts. Actively building skills in Verilog/SystemVerilog, ASIC design flow, and hardware verification with a strong interest in large-scale data center accelerators.

EDUCATION

B.Tech Electronics and Communication Engineering, SRM IST-Ramapuram 2026
CGPA-8.21/10

Class XII- CBSE, SRI KRISH INTERNATIONAL SCHOOL 2022
Percentage-57.6%

Class X - CBSE, NARAYANA E-TECHNO SCHOOL 2020
Percentage - 61%

SKILLS

Embedded Systems: Microcontrollers, Sensor Interfacing, Embedded C, IoT Systems

Digital Design & Architecture: Digital Logic Design, FSMs, Timing Analysis, Computer Architecture | Fundamentals

HDL & Hardware Design: Verilog, RTL Design Concepts, HLS (conceptual)

Programming & Scripting: C, Python, C++ (Basic)

Operating Systems: Linux (Basic)

Tools & Platforms: Linux, Raspberry Pi / RP2040, Git

Version Control: Git (Basic)

Debugging & Analysis: GDB (basic), logic debugging

WORK EXPERIENCE

NIDEC CONTROL TECHNIQUES, INTERNSHIP IMPLANT TRAINEE 12/2024 – 12/2024 | Chennai, india

- Exposed to industrial embedded drive systems used in windmill and automation applications.
- Observed hardware reliability, performance constraints, and system-level trade-offs in industrial drive systems.
- Assisted R&D teams in understanding system behavior, reliability, and performance considerations.

V.I MICROSYSTEMS, INTERNSHIP 07/2023 – 07/2023 | Chennai, india

- Acquired extensive experience in embedded systems and Internet of Things (IoT) using Raspberry Pi 2040 microcontroller.
- Designed and implemented practical projects emphasizing system integration and sensor interfacing.
- Focused on IoT protocols to strengthen technical expertise in modern embedded technologies.
- Strengthened understanding of hardware-software interaction and system timing behavior.

PROJECTS

TETRABOT (QUADRAPLE MECHANISED ROBOT) 01/2025 – 08/2025

- Designed FSM-based control logic for coordinated motor control.
- Implemented timing-critical control paths with real-time sensor feedback.
- Analyzed latency, execution timing, and resource usage.
- Debugged concurrency and signal interaction issues.

TRAFFIC ANALYSIS USING MACHINE LEARNING 08/2024 – 11/2024

- Processed real-time and historical sensor data for traffic congestion analysis.
- Worked on data preprocessing pipelines and performance-aware Python implementations.
- Built data preprocessing pipelines with an emphasis on computational efficiency.
- Gained exposure to system-level thinking involving sensors, data flow, and computation efficiency.

IR PROXIMITY SENSOR 01/2024 – 02/2024

- Designed and implemented an IR proximity sensing system using op-amps and comparators.
- Studied thresholding, noise margins, and signal reliability.

- Strengthened understanding of hardware interfacing and low-level signal behavior.

EMSLS (Electromagnetic space launch system)

07/2023 – 11/2023

An electromagnetic space launch system utilizes magnetic fields to accelerate spacecraft along a predetermined track, thereby reducing fuel dependency. It uses linear motors or coil guns to achieve high velocity. This aims to offer a sustainable, reusable, and rapid launch method, making it more efficient for satellite and cargo.

TECHNICAL INTERESTS

- ASIC Design & Verification
- Data Center Accelerators
- Low-Power Digital Design
- Hardware Performance Optimization.

COURSES

Digital Business Services Job Simulation, HSBC	03/2025
PYTHON FOR DATA SCIENCE, NPTEL	02/2025
GEO DATA Processing using Python, ISRO	08/2024
orCAD PSpice, LIVEWIRE	05/2023

LANGUAGES

ENGLISH: Professional Working Proficiency

TELUGU: Native Speaker

HINDI: Fluent

TAMIL: Fluent

VOLUNTEERING

Design Head	11/2024
Volunteer	06/2024
Volunteer	02/2023

LINKS

LinkedIN

GitHub