This week	Next week
<ul> <li>Fine Tuning</li> <li>Change activation function to tanh</li> <li>Try large filter size</li> <li>He initializer</li> </ul>	<ul> <li>Fine Tuning</li> <li>Change tanh model's channel</li> <li>Change activation function to RLelu</li> <li>Filter initializer</li> </ul>
	<ul> <li>Visualization</li> <li>The other model(tanh, long filter)</li> <li>The other label</li> <li>Activation Maximization</li> <li>CAM(Class Activation Map)</li> </ul>

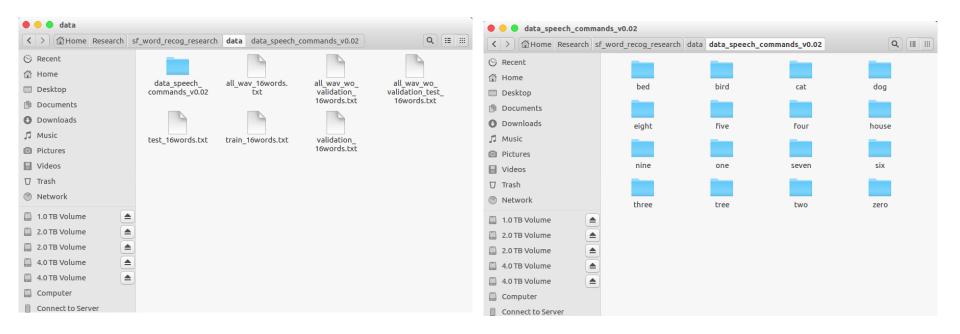
#### Interesting and new finding

- Fine Tuning
- Visualization

#### The aim of this month / Discussion

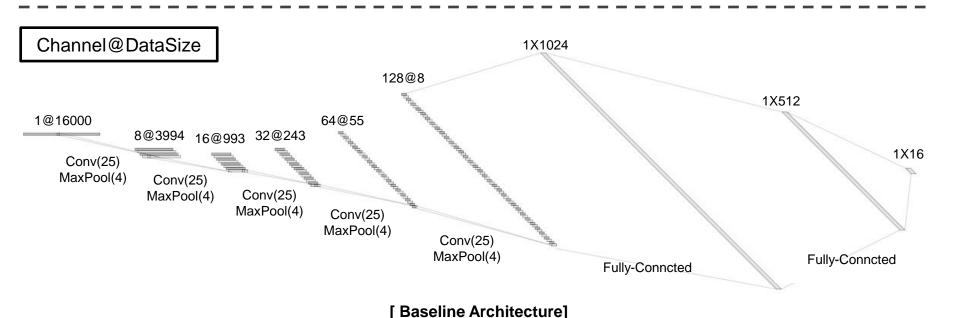
• The aim of this month: To investigate about CNN and visualization.

- Data is low-waveform.
  - sec: 1, sampling rate: 16000, type: float32, channel: mono
- 16 class data.
  - 'zero', 'one', 'two', 'three', 'four', 'five', 'six', 'seven', 'eight', 'nine', 'bed', 'bird', 'tree', 'cat', 'house', 'dog'
- Train: 40851(≒80%), Validation: 4796(≒10%), Test: 5297(≒10%)





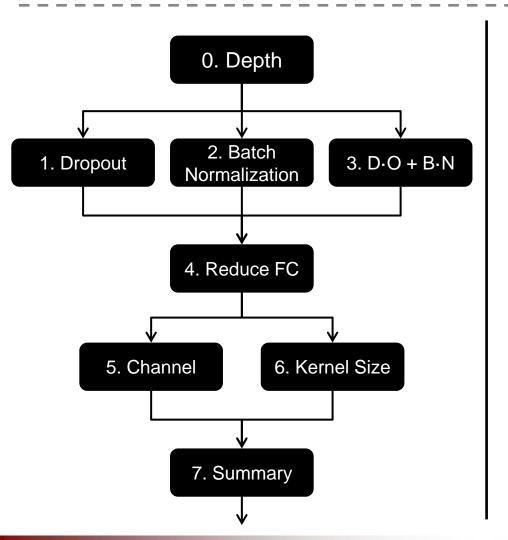
- For example, '5Conv, 2FC' baseline model's detail.
- It just flatten 2D model. (5X5 filter->1X25 filter, 2X2 stride->1X4 stride)
- Input: 16000X1 low waveform.
- Output:1x16 labeled one hot vector. ('zero', ..., 'eight', ..., 'house', 'dog')
- Loss: cross entropy loss
- Obtimizer: Adam

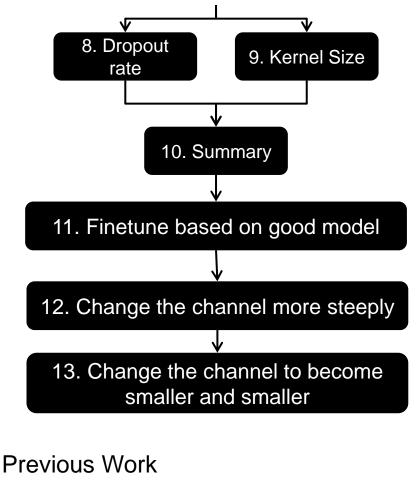






Fine tuning task in 1D-CNN







This is SOTA(State Of The Art) in current research.

	<b>Architecture (i = 0,1,2)</b>	1D DO(0.5)	1D BN	1D DO+BN	Params		
	baseline						
base model	5 Conv(25, 8*2 <sup>i</sup> ), 5 Pool(4), 2 FC	0.9090	0.9072	0.9240	1,855,056		
	Accurac	y and Num	ber of para	meters			
Custom channel 32 DO(0.75)	8 CONV(5, 64)	0.9533	0.9285	0.9391	94,768		
Custom channel 64 DO(0.75)	8 CONV(5, 128)	0.9589	X	0.9497	363,600		
Custom VGG style DO(0.75)	16 CONV(3, 128), 8 Pool	0.9620	0.9423	0.9136	470,736		
		Only Ac	curacy				
Custom channel 128 DO(0.25)+BN	9 CONV(5, 512)	0.9535	X	0.9701	2,071,184		



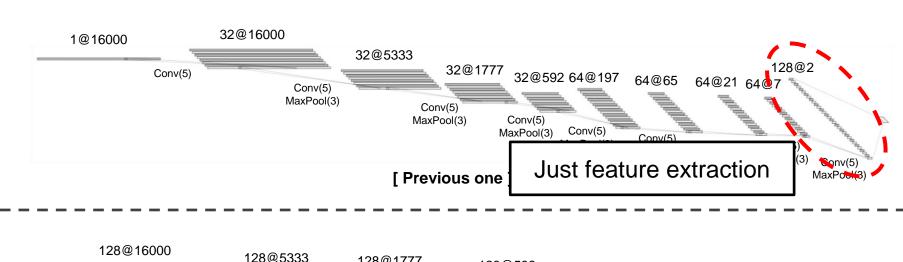
- To validate the model, We can use measure such as precision, recall, f1-score.
- We find out that It does not confuse between 'three' and 'tree'.
- It just confuses 'tree' as 'three'.
- And It also confuse between 'Bed' and 'Bird'.

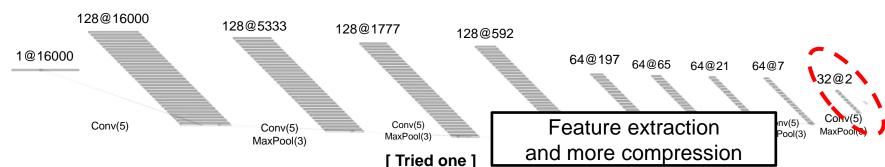
	Actual class	Precision	Recall	F1-score	Support
	Zero [[369 0 5 1 3 0 1 4 0 1 0 0 1 0 0 0] zero One [ 1 347 0 0 4 1 1 0 0 7 2 0 0 1 0 0]	0.95	0.96	0.95	385
	i one	0.96	0.95	0.95	364
	Two [8 0 369 2 0 0 0 0 1 0 0 0 2 2 0 0] two	0.95	0.96	0.95	384
	Three [ 1 0 2 356 0 1 1 2 6 0 0 0 0 0 0 8] three	0.93	0.94	0.94	377
	Fore [ 2 2 1 1 359 2 0 0 0 0 0 1 0 0 0] four	0.96	0.98	0.97	368
	Five [ 0 6 0 3 4 386 0 2 1 3 0 1 2 0 0 0] five	0.98	0.95	0.96	408
ب	Six [ 0 0 0 3 1 0 366 1 2 0 1 0 0 0 0 0 ] six	0.98	0.98	0.98	374
<u>:</u>	Seven [ 3 0 0 0 1 0 2 367 0 0 3 0 0 0 0 0] seven	0.97	0.98	0.97	376
Predict	eight [ 1 0 1 2 1 0 0 0 367 0 2 0 1 0 0 1]	0.95	0.98	0.96	376
7	Nine [ 0 6 0 0 0 3 0 0 0 364 3 1 0 0 0 0]	0.96	0.97	0.96	377
	bed [ 1 0 2 0 0 0 0 0 0 100 0 2 1 0 0] bed	0.89	0.91	0.90	183
	Bird [ 0 1 1 1 0 0 2 0 0 2 7 137 0 2 0 0] bird	0.95	0.90	0.92	153
	Cat [ 0 0 0 0 0 0 0 1 0 0 1 0161 4 1 0] cat	0.91	0.96	0.93	168
	Dog [ 0 1 5 0 0 0 0 0 1 1 0 2182 0 0] dog	0.94	0.95	0.95	192
	House [ 0 0 2 0 0 1 1 0 0 1 0 0 5 1156 0] house	0.99	0.93	0.96	167
	Tree [ 2 0 2 15 0 0 1 0 4 1 0 0 0 0 0 138]] tree	0.94	0.85	0.89	163
	Custom channel 32 (Acc: 0.9533) weighted avg DO(0.75)	0.95	0.95	0.95	4815





- I think this try is very meaningful.
- Because this model focus on the feature compression than previous model.
- Like autoencoder. ( 16000 → 64(=2\*32channel) )
- This model is better when use other classifiers after extract the feature from CNN.

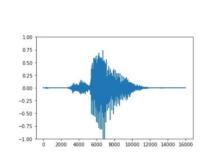


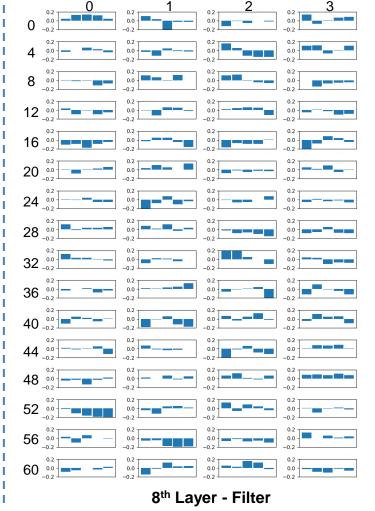


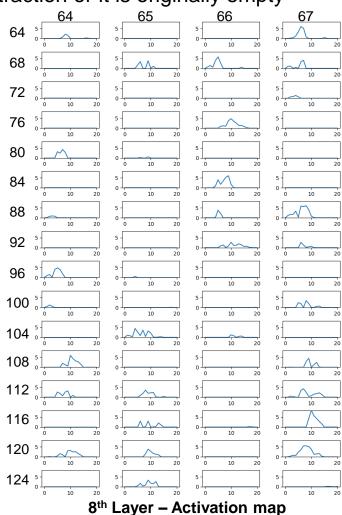




- About half is gone away...
- I don't know whether each label has a place for feature extraction or it is originally empty



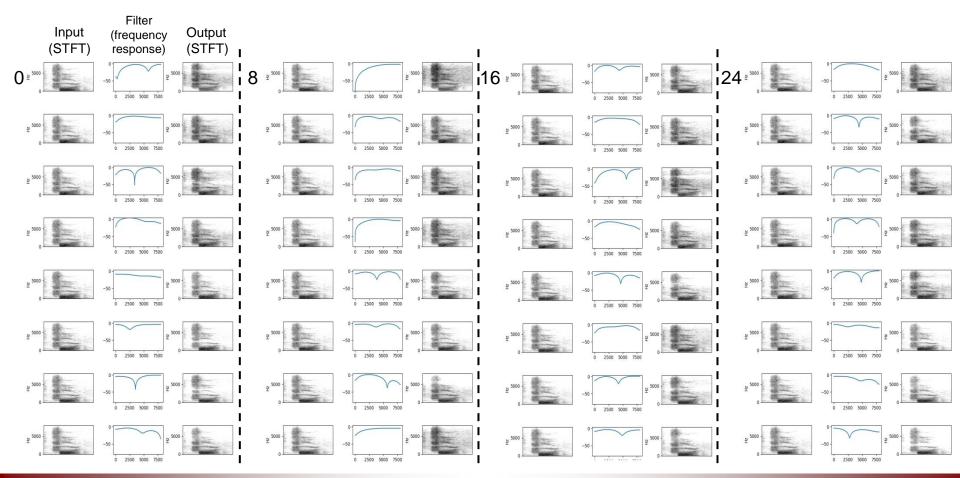




**Original input** 



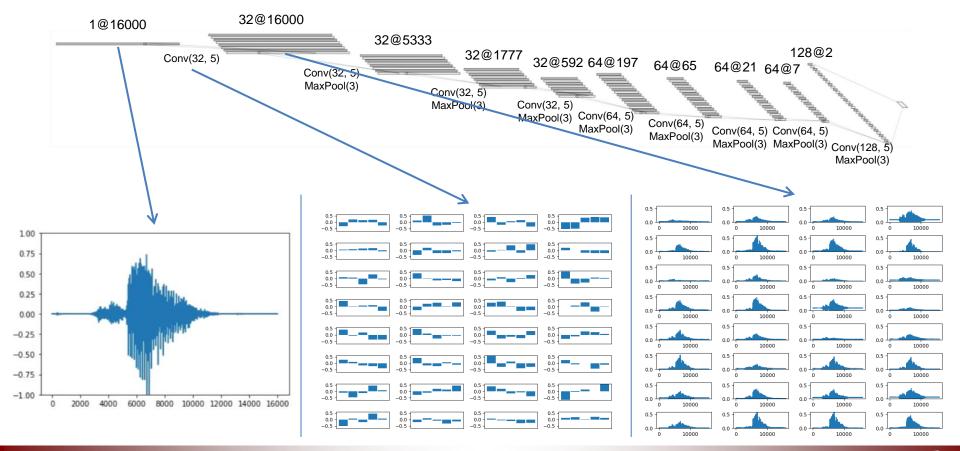
- So I created spectrogram by Short Time Fourier Transform (STFT).
- Window Size: 512, Stride: 128
- We can see that it is applied to the shape of frequency response.







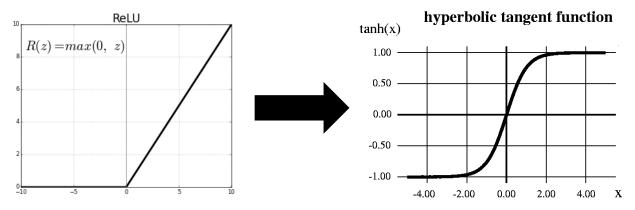
- Visualize the filter map. (Custom channel 32 DO(0.75) Model)
- Less than zero of the waveform is removed because of 'Relu'
- Because of this problem, it is difficult to analysis from the point of view of Signal Processing.
- So, I consider to use 'tanh' function.







- Less than zero of the waveform is removed because of 'Relu'
- So, I tried to change 'Relu' to 'tanh'



- First of all, It is impossible to apply all of my previous task.
  - Dropout
  - Batch Normalization
  - Dropout + Batch Normalization
  - VGG style
  - Droptout rate
  - Channel size (First, I fix the base channel size to 64)
  - **-** etc... (Maybe next time...)
- So, I tried a few task to see the results as soon as possible.





First, I applied the 'custom CH64' model.

Architecture	DO(0.5)	BN	DO+BN	Params
1 CONV(5, 64)	0.0953	0.0976	0.1111	16,384,400
2 CONV(5, 64)	0.3421	0.2517	0.2675	5,481,936
3 CONV(5, 64)	0.5001	0.5076	0.5350	1,861,136
4 CONV(5, 64)	0.6370	0.5518	0.6422	668,240
5 CONV(5, 128)	0.7423	0.6066	0.7082	506,576
6 CONV(5, 128)	0.8455	0.7583	0.7859	318,288
7 CONV(5, 128)	0.9192	0.8827	0.8687	310,224
8 CONV(5, 128)	0.9433	0.9269	0.9252	363,600
9 CONV(5, 256)	0.9477	0.9377	0.9479	521,552



- Second, I tune the dropout's rate
- As with previous results, high dropout rate model has a good performance.
- The high dropout rate contribute to the generalization of the model.

Architecture	DO(0.25)	DO(0.25)+BN	DO(0.75)	DO(0.75)+BN
1 CONV(5, 64)	0.1051	0.1020	0.1040	0.1011
2 CONV(5, 64)	0.3429	0.3246	0.3524	0.2569
3 CONV(5, 64)	0.4987	0.4295	0.5088	0.5624
4 CONV(5, 64)	0.6278	0.6079	0.7148	0.6550
5 CONV(5, 128)	0.7310	0.6947	0.7707	0.7146
6 CONV(5, 128)	0.8582	0.8150	0.8417	0.7763
7 CONV(5, 128)	0.9215	0.8922	0.9111	0.8617
8 CONV(5, 128)	0.9441	0.9169	0.9485	0.9229
9 CONV(5, 256)	0.9472	0.9439	0.9543	0.9441



3th, I tried VGG style

Architecture	DO(0.5)	BN	DO+BN	Params
2 CONV(3, 64), 1 Pool	0.1001	0.1047	0.1032	16,396,624
4 CONV(3, 64), 2 Pool	0.3421	0.2692	0.2721	5,498,320
6 CONV(3, 64) ,3 Pool	0.5333	0.3192	0.3927	1,881,680
8 CONV(3, 64), 4 Pool	0.6908	0.5333	0.5952	692,944
10 CONV(3, 128) , 5 Pool	0.7659	0.5034	0.7481	564,176
12 CONV(3, 128), 6 Pool	0.8627	0.7570	0.7666	392,400
14 CONV(3, 128) , 7 Pool	0.9246	0.8839	0.8681	400,848
16 CONV(3, 128), 8 Pool	0.9487	0.9406	0.9364	470,736
18 CONV(3, 256), 9 Pool	0.9516	0.9464	0.9439	760,016

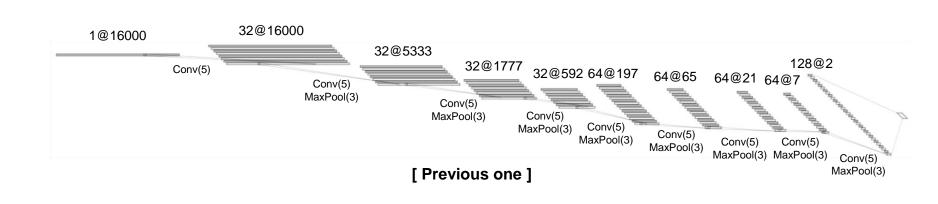


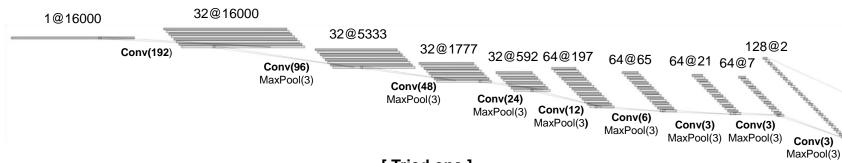
- 4<sup>th</sup>, I tune the dropout's rate
- In this result, 'custom' model is better than 'VGG like' model
- Compared to Relu, overall performance dropped by 1-2%.

Architecture	DO(0.25)	DO(0.25)+BN	DO(0.75)	DO(0.75)+BN
2 CONV(3, 64), 1 Pool	X	X	X	X
4 CONV(3, 64), 2 Pool	Χ	X	X	X
6 CONV(3, 64) ,3 Pool	0.5157	0.4347	0.5736	0.5753
8 CONV(3, 64), 4 Pool	0.6474	0.6565	0.7410	0.7279
10 CONV(3, 128) , 5 Pool	0.7564	0.7248	0.7848	0.7607
12 CONV(3, 128), 6 Pool	0.8677	0.7780	0.8696	0.7896
14 CONV(3, 128) , 7 Pool	0.9277	0.9001	0.9304	0.8924
16 CONV(3, 128), 8 Pool	0.9487	0.9304	0.9404	0.9269
18 CONV(3, 256), 9 Pool	0.9475	0.9489	0.9522	0.9448



- I tune the filter size more bigger.
- Filter size:  $192 \rightarrow 96 \rightarrow 48 \rightarrow 24 \rightarrow 12 \rightarrow 6 \rightarrow 3 \rightarrow \dots$





[ Tried one ]





- I didn't try early case because the results were probably not good.
- Start channel size: 32

Architecture	DO(0.5)	BN	DO+BN	Params
1 CONV(192, 32)	X	X	X	X
2 CONV(96, 32)	X	X	X	X
3 CONV(48, 32)	0.7765	0.5678	0.7506	1,063,536
4 CONV(24, 32)	0.8249	0.7329	0.8424	481,424
5 CONV(12, 64)	0.8758	0.8042	0.8856	404,688
6 CONV(6, 64)	0.9213	0.8785	0.9302	294,160
7 CONV(3, 64)	0.9340	0.9115	0.9385	261,456
8 CONV(3, 64)	0.9483	0.9292	0.9468	259,472
9 CONV(3, 128)	0.9445	0.9466	0.9398	281,104



- Start channel size: 64
- If filter size is more bigger, model become more heavy.
- It take a lot of time... So, I will prepare the other case until the next time.

Architecture	DO(0.5)	BN	DO+BN	Params
1 CONV(192, 64)	X	X	X	X
2 CONV(96, 64)	X	X	X	X
3 CONV(48, 64)	0.7886	0.5346	0.7117	2,421,968
4 CONV(24, 64)	0.8482	0.7423	0.8656	1,306,896
5 CONV(12, 128)	0.8760	0.8258	0.9094	1,202,576
6 CONV(6, 128)	0.9225	0.9088	0.9202	1,030,672
7 CONV(3, 128)	0.9350	0.9321	0.9524	989,840
8 CONV(3, 128)	0.9489	0.9472	0.9535	1,010,448
9 CONV(3, 256)	0.9479	0.9516	0.9570	1,102,864



- In last lab seminar, we know that 'he\_uniform initializer' has good performance
- So, I found the paper of 'he initializer'
- 'He initializer' is improvement of 'xavier initializer'.
- They said, If we use 'relu' function, it is more better than 'xavier initializer'.

$$\sigma = \frac{1}{\sqrt{n_{
m in}}} \longrightarrow \sigma = \frac{\sqrt{2}}{\sqrt{n_{
m in}}}$$
  $n_{in}$ : Number of neurons feeding into given neuron

#### Xavier:

Glorot, Xavier, and Yoshua Bengio. "Understanding the difficulty of training deep feedforward neural networks." Proceedings of the thirteenth international conference on artificial intelligence and statistics. 2010.

#### He:

He, Kaiming, et al. "Delving deep into rectifiers: Surpassing human-level performance on imagenet classification." Proceedings of the IEEE international conference on computer vision. 2015.

- In tensorflow, Conv1D 's default initializer is 'xavier initializer'.
- So I tried 'he initializer' to my model.





- Compare to previous result.
- The Most of case is improved a little.
- I think 'He initializer' is little better than 'Xavier initializer'.

Architecture	DO(0.5)	BN	DO+BN	DO(0.5)	BN	DO+BN
1 CONV(5, 64)	X	X	X	X	X	Χ
2 CONV(5, 64)	X	X	X	X	X	Χ
3 CONV(5, 64)	0.5844	0.4893	0.5726	0.5904	0.4773	0.6033
4 CONV(5, 64)	0.7128	0.6291	0.7333	0.7221	0.6145	0.7329
5 CONV(5, 128)	0.7732	0.7022	0.8073	0.7859	0.6872	0.8019
6 CONV(5, 128)	0.8901	0.8233	0.8818	0.8928	0.8087	0.8802
7 CONV(5, 128)	0.9400	0.9061	0.9302	0.9433	0.9126	0.9252
8 CONV(5, 128)	0.9560	0.9508	0.9458	0.9587	0.9383	0.9531
9 CONV(5, 256)	0.9537	0.9464	0.9470	0.9541	0.9524	0.9529

< custom model >

< Xavier >

< He >



- Compare to previous result.
- It works well for a few cases, but in some cases it is not effective.
- Is it effective when the filter size is large?

Architecture	DO(0.5)	BN	DO+BN	DO(0.5)	BN	DO+BN
2 CONV(3, 64), 1 Pool	X	X	X	X	X	Χ
4 CONV(3, 64), 2 Pool	X	X	X	X	X	Χ
6 CONV(3, 64) ,3 Pool	0.5844	0.4893	0.5726	0.5680	0.5047	0.5755
8 CONV(3, 64), 4 Pool	0.7128	0.6291	0.7333	0.6793	0.6442	0.7080
10 CONV(3, 128) , 5 Pool	0.7732	0.7022	0.8073	0.7759	0.6947	0.8027
12 CONV(3, 128), 6 Pool	0.8901	0.8233	0.8818	0.8831	0.8368	0.8939
14 CONV(3, 128) , 7 Pool	0.9400	0.9061	0.9302	0.9458	0.9178	0.9418
16 CONV(3, 128), 8 Pool	0.9581	0.9508	0.9458	0.9593	0.9398	0.9543
18 CONV(3, 256), 9 Pool	0.9537	0.9464	0.9470	0.9533	0.9387	0.9506

< VGG like model >

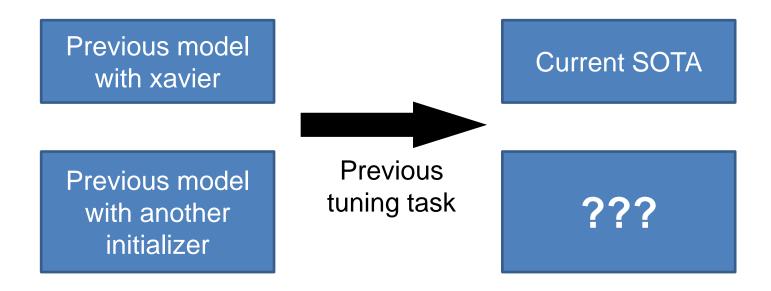
< Xavier >

< He >





- There is a more initializer (ex. xavier\_normal, he\_normal, etc)
- What if I apply another initializer at the same previous task?
- Because 'he initializer' shown such better performance, I expect about it.





## **Any Question?**

# Thank you

