Weekly Report

This week

Next week

- Deconvolution Network
- What is DeconvNet
- Apply VGG16 in Keras
- Compare to CAM
- Training 2D-Model for visualization

- Deconvolution Network
- Apply to 2D (our data)
- To improve performance
- Fine tuning (simply)
- Augmentation
- Apply to 1D (our data)

Interesting and new finding

DeconvNet

The aim of this month / Discussion

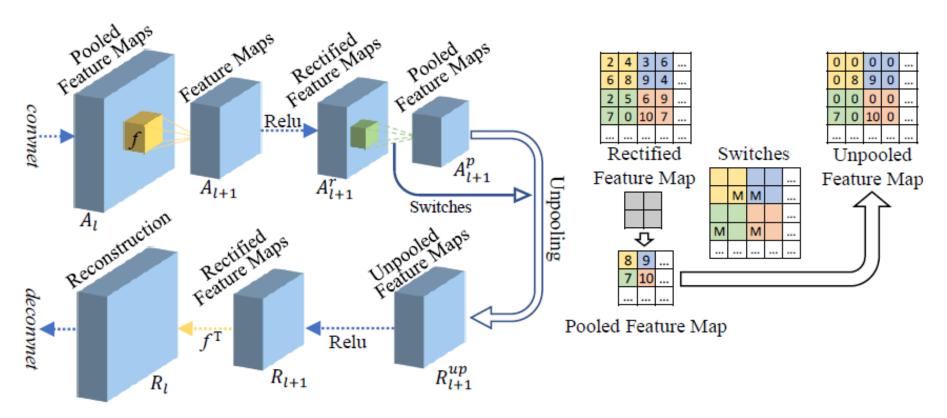
• The aim of this month: To study brain data.





What is DeconNet?

- Visualize each filter or layer (how to see the data)
- To target certain filter(Conv) or certain layer(Dense, Softmax)



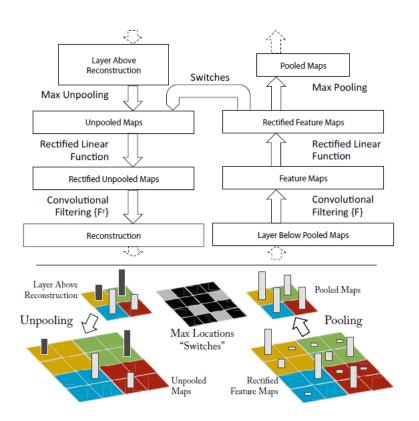
The structure of the Deconvolutional Network





What is DeconNet?

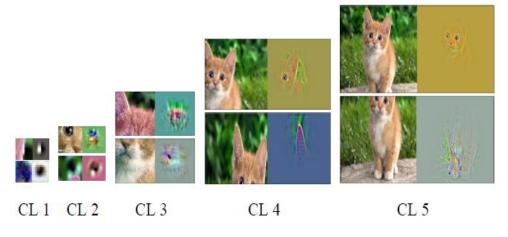
- Visualize each filter or layer (how to see the data)
- To target certain filter(Conv) or certain layer(Dense, Softmax)



< The architecture >

Left: input image

Right: visualization of each filter



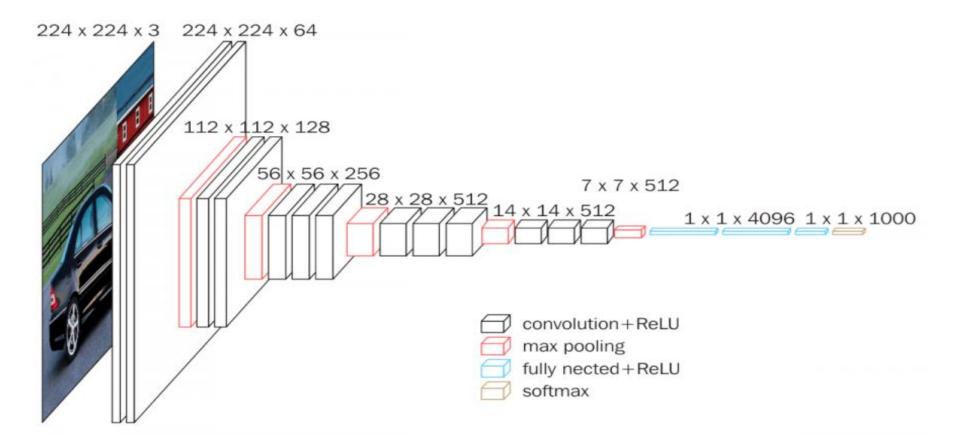
< Visualization of Convolution layer >





Apply VGG16 in Keras

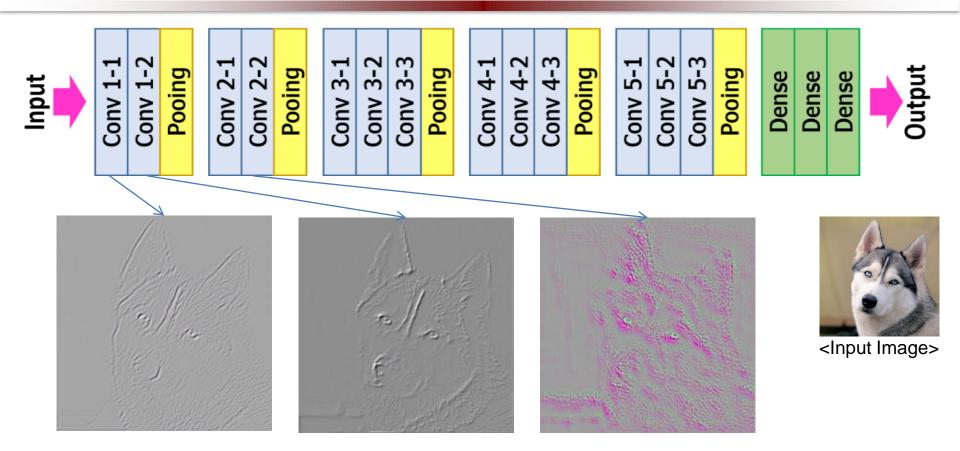
- It's hard to validate whether DeconvNet is implemented well in 1D-CNN Because we can not understand the result of DeconvNet visually
- So, Test in 2D-Model first (Target model: pretrained VGG16 provided by Keras)







Apply VGG16 in Keras (based on 0th filter)

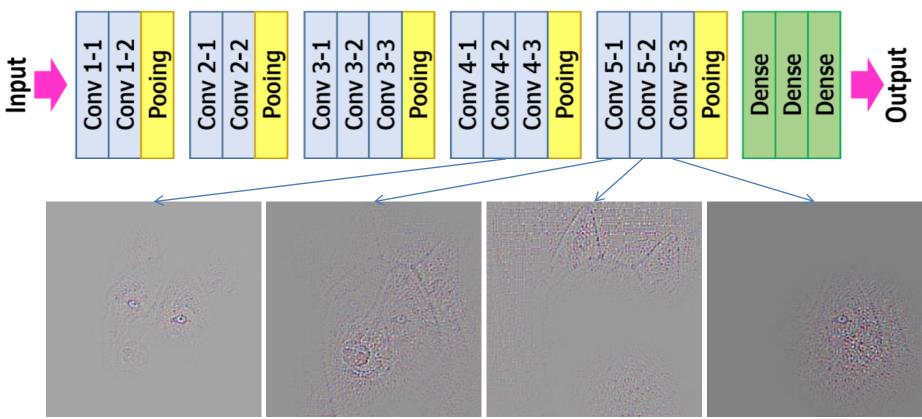


- In the 0th filter of the front layer, the model focus on the edge or texture
- Although there is no exist in the slide, each filter focus on individual feature.
- Front layer see the data entirely





Apply VGG16 in Keras (based on 0th filter)



- But, In the 0th filter of the backward layer,
 the model focus on certain area(eyes, nose, ear)
- Backward layer see the data partially



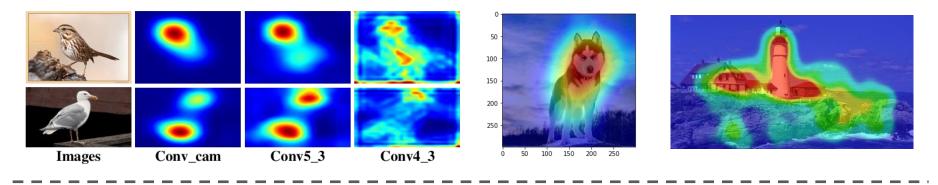
<Input Image>



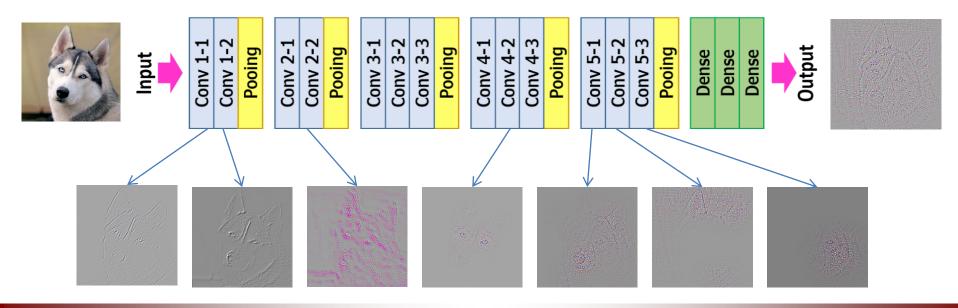


Compare to CAM(Class Activation Map)

CAM visualize the model where to see



DeconvNet visualize the model how to see







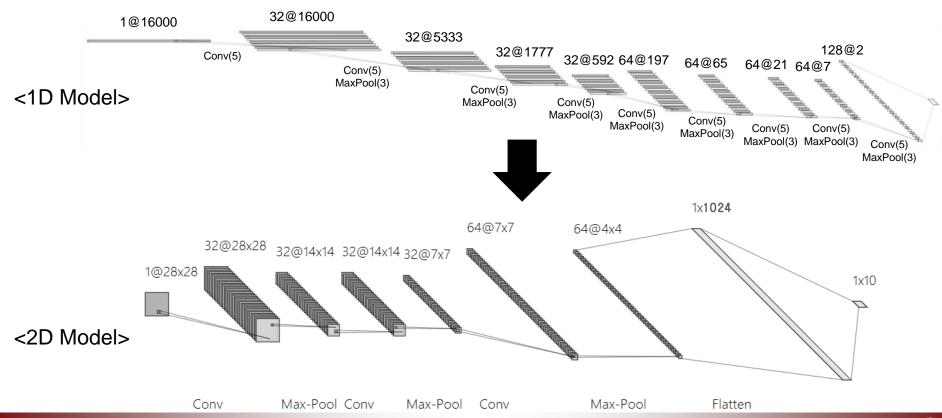
Training 2D-Model for visualization (MNIST)

Change (Because of input data's shape)

Input: $16000X1 \rightarrow 28X28X1$, Output: $16 \rightarrow 10 (0 \sim 9)$

filter size: $1X5 \rightarrow 3X3$, pool size: $1X3 \rightarrow 2X2$, number of conv layer: $8 \rightarrow 3$

Train: 40000, Val: 20000, Test:10000



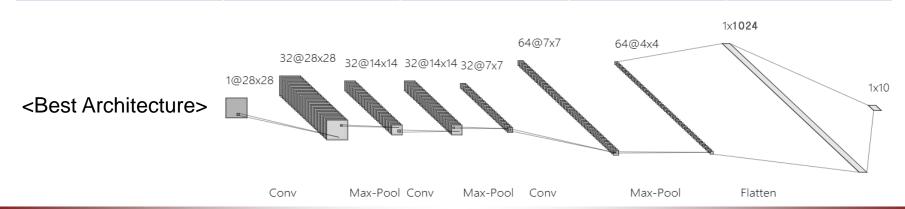




Training 2D-Model for visualization (MNIST)

- To find best fit model, Tuning the start channel(16, 32) and dropout rate(0.5, 0.75)
- When the number of convolution filter is 3, performance is best.

Architecture	CH16+DO0.5	CH16+DO0.75	CH32+DO0.5	CH32+DO0.75
1 CONV(3X3)	0.9835	0.9828	0.9837	0.9839
2 CONV(3X3)	0.9893	0.9875	0.9891	0.9901
3 CONV(3X3)	0.9901	0.9902	0.9921	0.9934
4 CONV(3X3)	0.9892	0.9891	0.9917	0.9900
5 CONV(3X3)	0.9863	0.9910	0.9901	0.9904



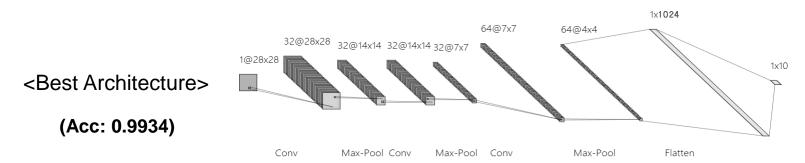




Training 2D-Model for visualization (MNIST)

- In the best architecture, It seems that the model classify well
- So, I will visualize this as DeconvNet in next week.

Actual class precision recall f1-score support 0] 0] 1133 0 0.99 0.99 0.99 980 1.00 1.00 1.00 1135 1] 0 1028 0.99 1.00 0.99 1032 0 1008 0] 0 **Predict** 1.00 1.00 1.00 1010 6] 982 0.99 0.99 0.99 892 0.99 0.99 0.99 887 0] 0.99 0.99 958 1.00 946 0] 0.99 0.99 0.99 1028 11 0 0 1019 0.99 0.99 0.99 974 3] 0.99 0.99 0.99 1009 969 0 994]] weighted avg 10000 0.99 0.99 0.99







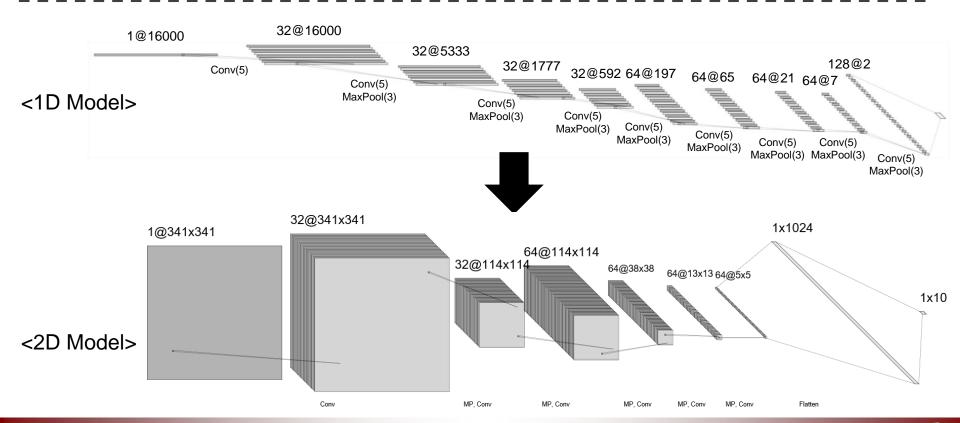
Training 2D-Model for visualization (Imagenet)

Change (Because of input data's shape)

Input: $16000X1 \rightarrow 341X341X3$, Output: $16 \rightarrow 6$ ('bed', 'bird', 'cat', 'dog', 'house', 'tree')

filter size: $1X5 \rightarrow 5X5$, pool size: $1X3 \rightarrow 3X3$, number of conv layer: $8 \rightarrow 5$

Train: 4680(60%), Val: 1560(20%), Test: 1560(20%)

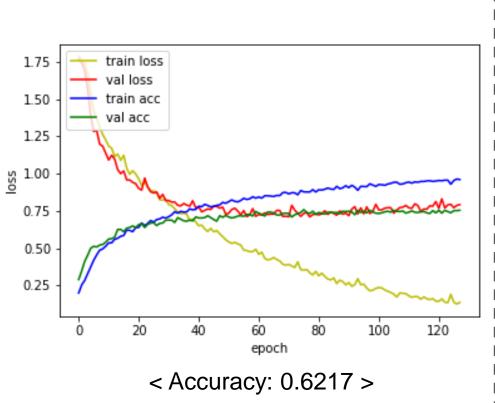


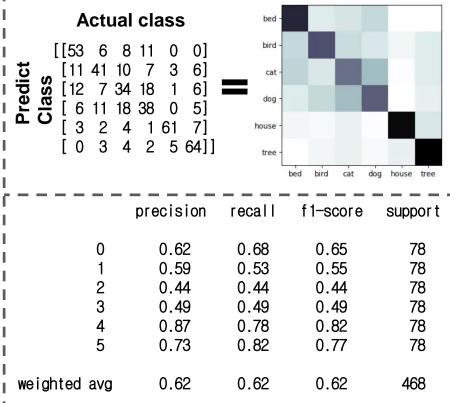




Training 2D-Model for visualization (Imagenet)

- It is still training now... For the report, I use only 30% of each set.
 - Train: 1404(20%), Val: 468(6%), Test: 468(6%)
- Despite val loss increase, It seems that val accuracy increase.
- Maybe It is caused by a lack of data. I will try again as more data.









Any Question?

Thank you

