view_frames Result

Recorded at time: 1709553396.35

map Broadcaster: /slam_gmapping Average rate: 20.202 Buffer length: 4.95 Most recent transform: 1709553396.37 Oldest transform: 1709553391.41 odom Broadcaster: /autolabor_driver Average rate: 100.218 Buffer length: 4.989 Most recent transform: 1709553396.33 Oldest transform: 1709553391.34 base_link Broadcaster: /robot_state_publisher` Broadcaster: /autolabor_driver Average rate: 10000.0 Average rate: 100.218 Buffer length: 0.0 Buffer length: 4.989 Most recent transform: 0.0 Most recent transform: 1709553396.33 Oldest transform: 0.0 Oldest transform: 1709553391.34 lidar real_map