Geometric Modeling for Computer Graphics





Mike Bailey

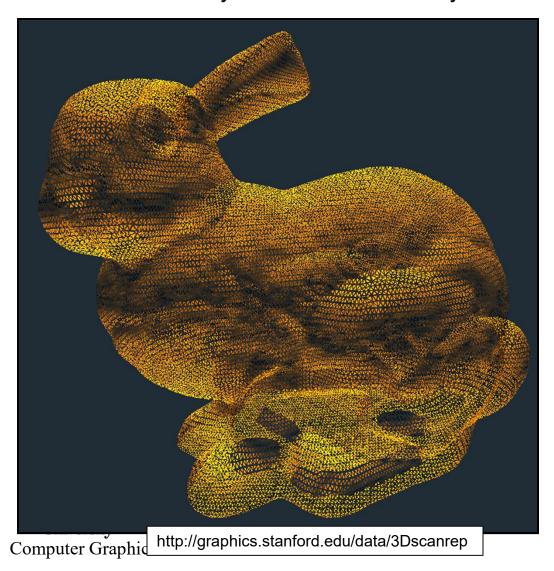
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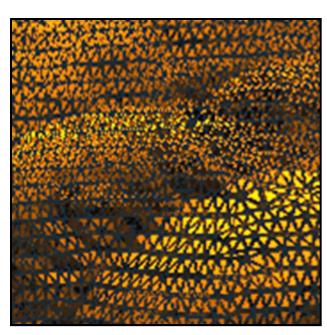
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Explicitly Listing Geometry and Topology

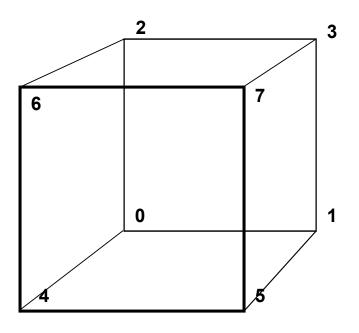
Models can consist of thousands of vertices and faces – we need some way to list them efficiently





This is called a Mesh.

Explicitly Listing Geometry and Topology



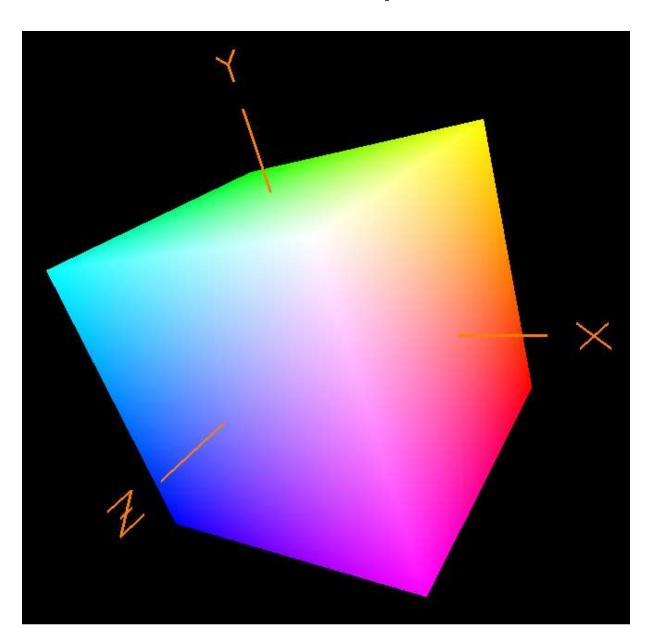
```
static GLfloat CubeColors[][3] =
                   \{0., 0., 0.\}
                   { 1., 0., 0. },
                   { 0., 1., 0. },
                   { 1., 1., 0. },
                   { 0., 0., 1. },
                   { 1., 0., 1. },
                   { 0., 1., 1. },
                   { 1., 1., 1. },
Computer Graphics
```

Ore

```
static GLfloat CubeVertices[][3] =
           { -1., -1., -1. },
           { 1., -1., -1.},
           { -1., 1., -1. },
           { 1., 1., -1.},
           { -1., -1., 1. },
          { 1., -1., 1.},
           { -1., 1., 1. },
          { 1., 1., 1.}
```

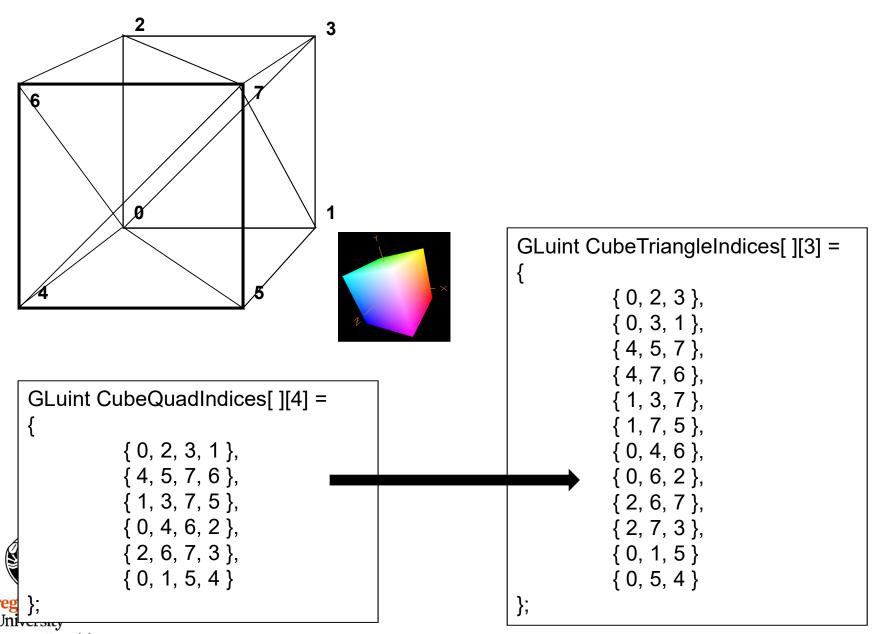
```
static GLuint CubeQuadIndices[][4] =
           { 0, 2, 3, 1 },
           { 4, 5, 7, 6 },
           { 1, 3, 7, 5 },
           { 0, 4, 6, 2 },
          { 2, 6, 7, 3 },
          { 0, 1, 5, 4 }
```

Cube Example



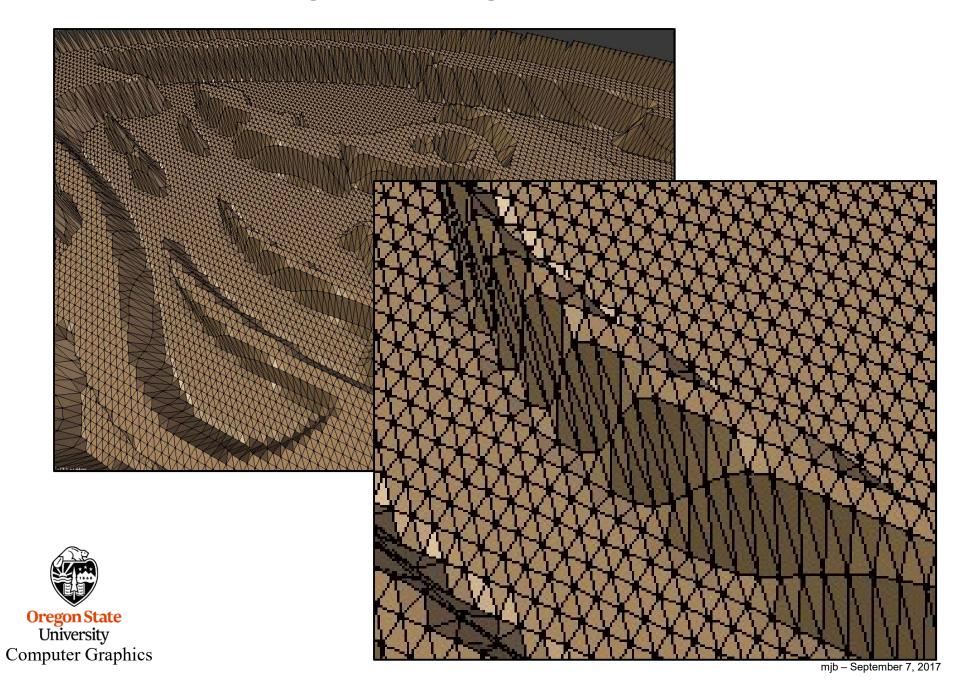


The Cube Can Also Be Defined with Triangles



Computer Graphics

3D Printing uses a Triangular Mesh Data Format



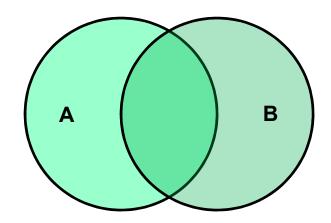
3D Printing uses a Triangular Mesh Data Format



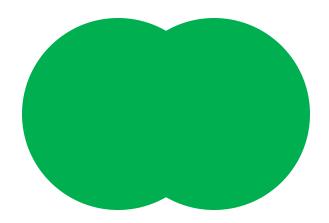
Dessert at the House of Someone Obsessed with OSU and Computer Graphics ©



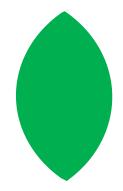
Another way to Model: Remember Venn Diagrams (2D Boolean Operators) from High School?



Two Overlapping Shapes



Union: A∪B



Intersection: A∩B

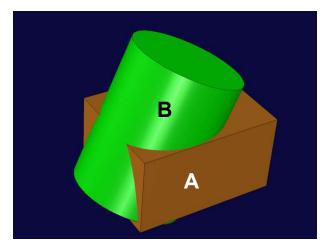
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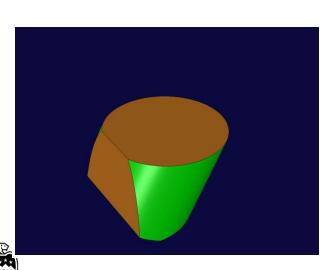


Difference: A-B

Solid Modeling Using 3D Boolean Operators



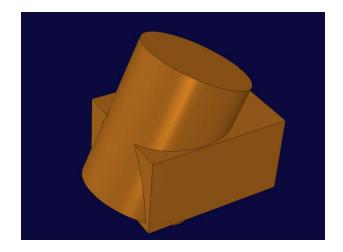
Two Overlapping Solids



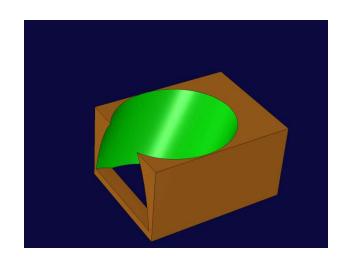
Intersection: A∩B

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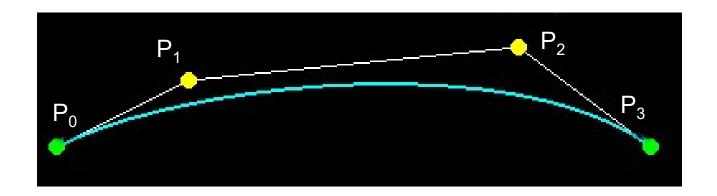
Union: A∪B



Difference: A-B

This is often called **Constructive Solid Geometry**, or CSG

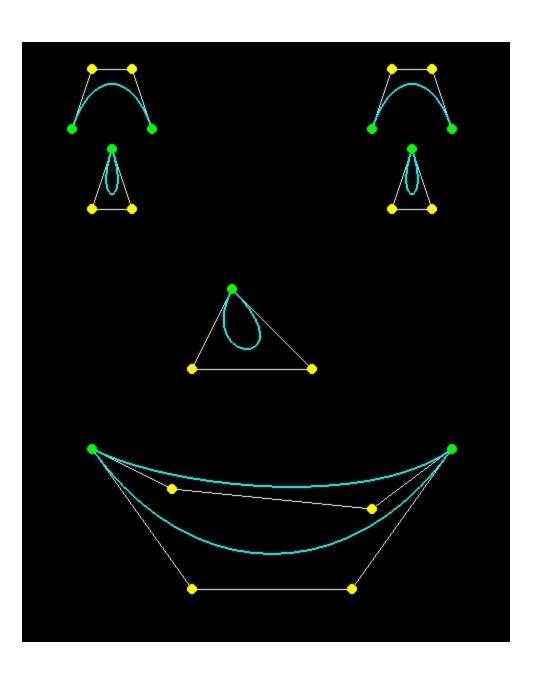
Another way to Model: Curve Sculpting – Bezier Curve Sculpting



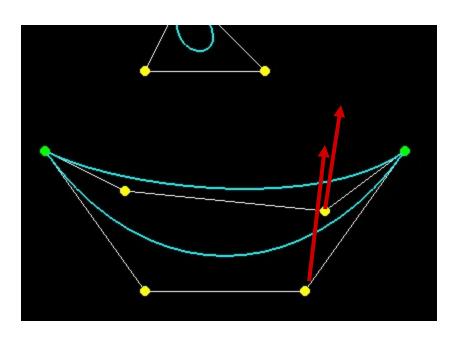
$$P(t) = (1-t)^{3} P_{0} + 3t(1-t)^{2} P_{1} + 3t^{2} (1-t) P_{2} + t^{3} P_{3}$$
$$0. \le t \le 1.$$

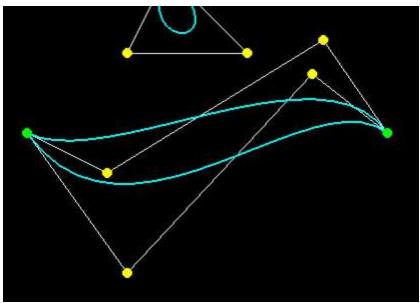


where *P* represents $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$





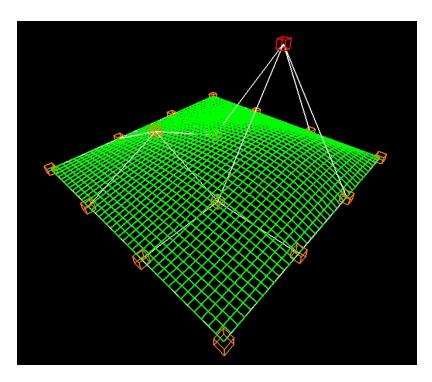


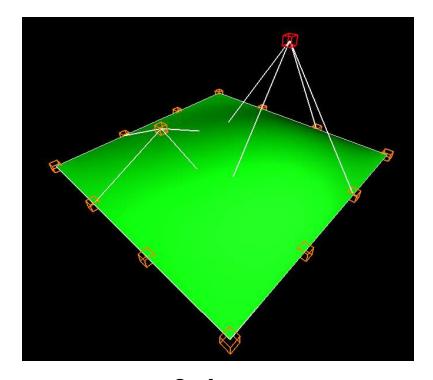




Moving a single point moves an entire curve

Another way to Model: Surface Sculpting



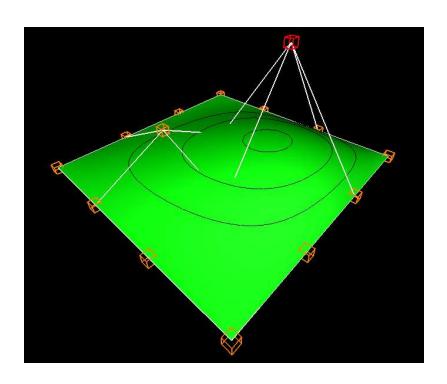


Wireframe

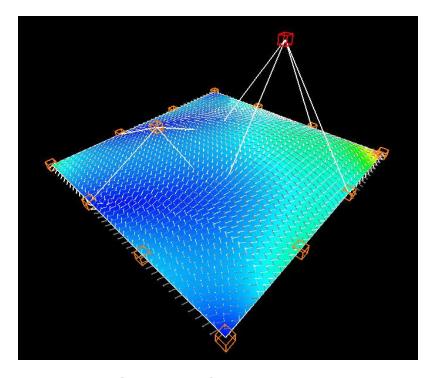
Surface



Moving a single point moves an entire surface

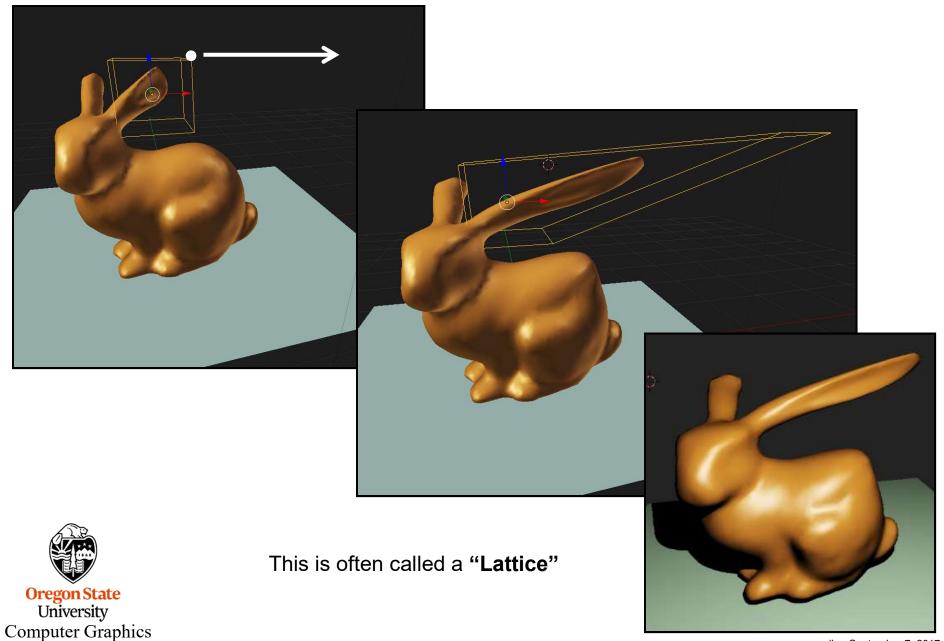


With Contour Lines

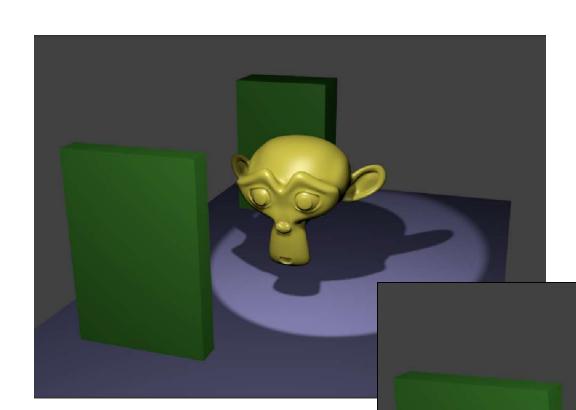


Showing Curvature

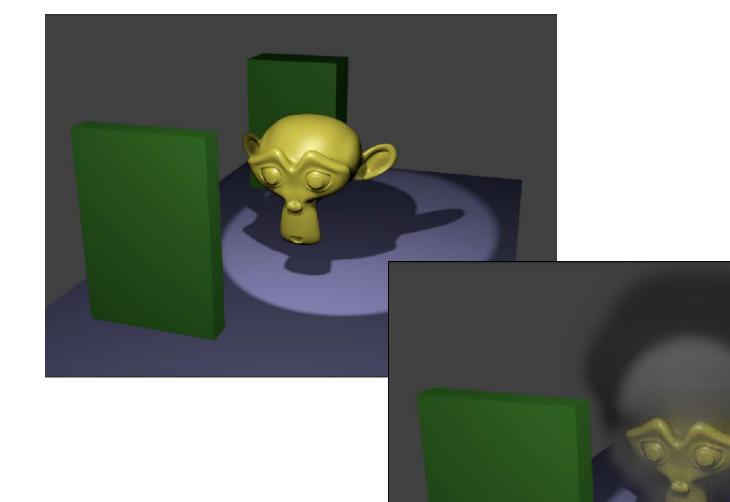




mjb - September 7, 2017



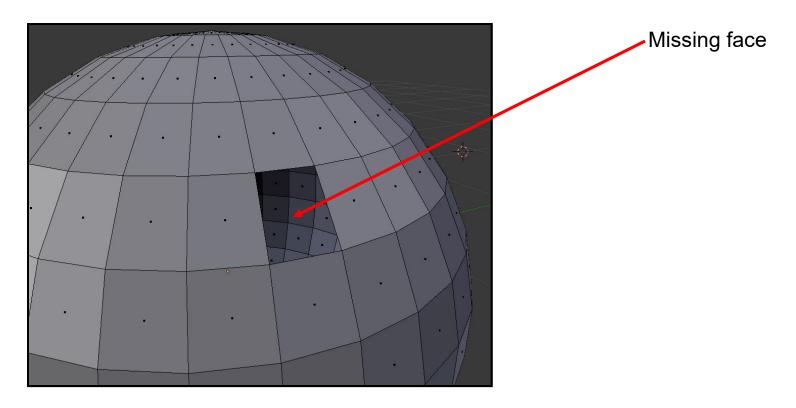






Object Modeling Rules for 3D Printing

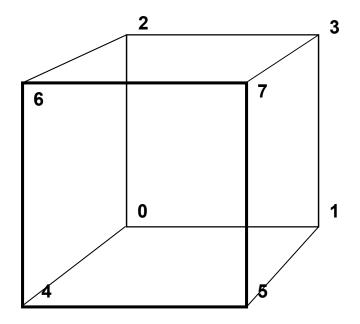
The object must be a legal solid. It must have a definite inside and a definite outside. It can't have any missing face pieces.





"Definite inside and outside" is sometimes called "Two-manifold" or "Watertight"

*sometimes called the Euler-Poincaré formula



$$F - E + V = 2$$

F FacesE EdgesV Vertices

For a cube, 6 - 12 + 8 = 2

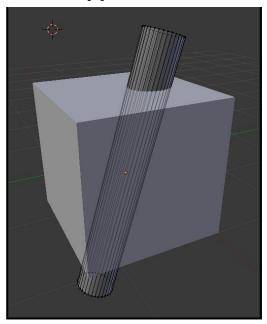
The full formula is:



Object Modeling Rules for 3D Printing

Objects cannot pass through other objects. If you want two shapes together, do a Boolean union on them so that they become one complete object.

Overlapped in 3D -- bad





Boolean union -- good

