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实验日期	7月1号	教师签字_		成绩	

实验报告

【实验名称】	<u>冬</u>
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【实验目的】

掌握图的两种储存方式: 邻接矩阵表示法借助二维数组来表示元素之间的关系; 邻接表属于链式存储结构。

图的两种遍历: 深度优先遍历和广度优先遍历。

最小生成树算法: 普里姆算法和克鲁斯卡算法。

【实验原理】

邻接矩阵表示法借助二维数组来表示元素之间的关系;邻接表属于链式存储结构,通过链表表示顶点元素和边之间的关系。

图的深度优先遍历 (DFS)

最小生成树算法 (普里姆算法)

【实验内容】

使用邻接矩阵表示一个如图所示无向有权权图,增加顶点,增加边,输出图中的所有顶点和边

使用邻接链表表示一个有向有权图,增加顶点,增加有向弧,输出图中的所有顶点和弧

使用 DFS 遍历题目 1 所生成的图

使用 Prim 算法生成题目 1 的最小生成树

```
#include <iostream>
using namespace std;
#define OK 1
#define ERROR 0
#define OVERFLOW -2
#define MVNum 100
#define MAXINT 32767
typedef int Status;
typedef int VerTexType;
typedef int ArcType;
typedef struct
     VerTexType vexs[MVNum];
     ArcType arcs[MVNum][MVNum];
     int vexnum, arcnum;
}AMGraph;
bool visited[MVNum * MVNum] = { false };
int LocateVex_AM(AMGraph G, int v)
```

```
for (int i = 0; i < G.vexnum; i++)
                                    if (G.vexs[i] == v) return i;
                  return MAXINT;
}
Status CreateUDN(AMGraph& G)
                  cin >> G.vexnum >> G.arcnum;
                  for (int i = 0; i < G.vexnum; ++i)
                                   cin >> G.vexs[i];
                  for (int i = 0; i < G.vexnum; ++i)
                                    for (int j = 0; j < G.vexnum; ++j)
                                                      G.arcs[i][j] = MAXINT;
                  for (int k = 0; k < G.arcnum; ++k)
                  {
                                    int v1, v2, w;
                                    cin >> v1 >> v2 >> w;
                                    int i = LocateVex_AM(G, v1);
                                    int j = LocateVex\_AM(G, v2);
                                    G.arcs[i][j] = w;
                                    G.arcs[j][i] = w;
                  return OK;
void Print_AMGraph(AMGraph G)
                  for (int i = 0; i < G.vexnum; i++)
                  {
                                    cout << G.vexs[i] << endl;</pre>
                                    for (int j = 0; j < G.vexnum; j++)
                                                      if (G.arcs[i][j] != MAXINT) \ cout << G.vexs[i] << "->" << G.vexs[j] << '' << G.arcs[i][j] << '' >< G.arcs[i][j] << G.arcs[i][j] << '' >< G.arcs[i][j] << 
endl;
typedef int OtherInfo;
typedef struct ArcNode
                  int adjvex;
                  struct ArcNode* nextarc;
                  OtherInfo info;
};
typedef struct VNode
                  VerTexType data;
                  ArcNode* firstarc;
}VNode, AdjList[MVNum];
```

```
typedef struct
     AdjList vertices;
     int vexnum, arcnum;
}ALGraph;
int LocateVex_AL(ALGraph G, int v)
     for (int i = 0; i < G.vexnum; i++)
           if (G.vertices[i].data == v) return i;
     return MAXINT;
Status CreatDG(ALGraph& G)
     cin >> G.vexnum >> G.arcnum;
     for (int i = 0; i < G.vexnum; i++)
           cin >> G.vertices[i].data;
           G.vertices[i].firstarc = NULL;
     for (int k = 0; k < G.arcnum; k++)
           int v1, v2, w, i, j;
           cin >> v1 >> v2>>w;
           i = LocateVex\_AL(G, v1);
           j = LocateVex\_AL(G, v2);
           ArcNode* p1 = new ArcNode;
           p1->adjvex = j;
           p1->info = w;
           p1->nextarc = G.vertices[i].firstarc;
           G.vertices[i].firstarc = p1;
     }
     return OK;
void Print_ALGraph(ALGraph G)
     for (int i = 0; i < G.vexnum; i++)
           cout << G.vertices[i].data << endl;</pre>
           ArcNode* p;
           p = G.vertices[i].firstarc;
           while (p)
                cout << G.vertices[i].data << "->" << p->adjvex << ' ' << p->info << endl;
                p = p->nextarc;
           }
```

```
}
void DFS_AM(AMGraph G, int v)
                 cout << G.vexs[v]<<' ';
                 visited[v] = true;
                 for (int w = 0; w < G.vexnum; w++)
                                   if ((G.arcs[v][w] != MAXINT) && (!visited[w])) DFS_AM(G, w);
}
struct
                  VerTexType adjvex;
                 ArcType lowcost;
}closedge[MVNum];
int Min(int num)
                  int k = -1;
                 for (int i = 0; i < num; ++i)
                                   if (((closedge[i].lowcost!=0) \&\&(k==-1))||((closedge[i].lowcost != 0) \&\& (closedge[i].lowcost 
<closedge[k].lowcost))) k = i;
                  return k;
void MiniSpanTree_Prim(AMGraph G, VerTexType u)
                  int k = LocateVex\_AM(G, u);
                 for (int j = 0; j < G.vexnum; ++j)
                                   if (j != k) closedge[j] = \{ u,G.arcs[k][j] \};
                 for (int i = 1; i < G.vexnum; ++i)
                  {
                                   k = Min(G.vexnum);
                                   int u0 = closedge[k].adjvex;
                                   int v0 = G.vexs[k];
                                   cout << u0 <<"->" << v0 <<"
                                                                                                                                             " << closedge[k].lowcost << '\t';
                                   closedge[k].lowcost = 0;
                                   for (int j = 0; j < G.vexnum; ++j)
                                                    if (G.arcs[k][j] < closedge[j].lowcost)</pre>
                                                                      closedge[j] = \{ G.vexs[k], G.arcs[k][j] \};
                  }
int main()
                  AMGraph AMG;
                  ALGraph ALG;
                 CreateUDN(AMG);
                  Print_AMGraph(AMG);
```

```
CreatDG(ALG);
    Print_ALGraph(ALG);
    DFS_AM(AMG, 0);
    cout << endl;
    MiniSpanTree_Prim(AMG, 1);
    cout << endl;
    return 0;
}
/*
6 10
123456
136
129
143
245
258
359
467
564
365
432
68
0\,1\,2\,3\,4\,5
0 5 100
0 4 30
0\,2\,10
125
2350
4 3 20
3510
4 5 60
*/
```

【小结或讨论】

通过该次实验我掌握了图的基本算法,包括图的创建邻接矩阵创建 无向带权图和邻接表创建有向有权图,并能够应用深度优先算法搜 索图,能运用普里姆算法生成最小生成树等。