

# Multiple-type, two-dimensional finite bin packing problem

This is a mini project for Fundamental of  
Optimization course of SOICT – HUST

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**Introduction**



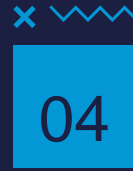
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# Introduction

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# Problem

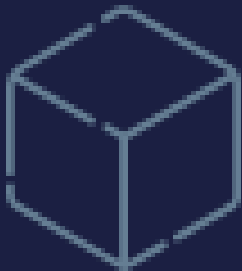
There are  $K$  trucks  $1, 2, \dots, K$  for transporting  $N$  packages of  $1, 2, \dots, N$ . Trucks have a container size of  $W_k * L_k$ . Each package  $i$  has size  $w_i * l_i$ .



Packages that are placed in same container must not overlap. Assume that the number  $K$  can be large, leading to a large number of trucks that are not being used. The cost of using truck  $k$  is  $c_k$ .



Find a way to put these package in the trucks so that the total cost is minimal.





# Exact solutions

CP and MIP models



02

# Denotation

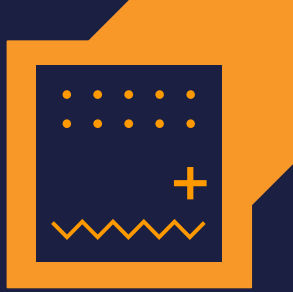
**N\_items** is the number of items given

Item  $i$  has width  $w_i$  and height  $h_i$

**N\_bins** is the number of bins given

Bin  $j$  has width  $W_j$ , height  $H_j$  and cost  $C_j$

# Decision variable



\*  $X_{ij} = 1$ : item  $i$  packed in bin  $j$

$$\Rightarrow \sum_{i=1}^{N\_items} X_{ij} \geq 1 \iff Z_j = 1: \text{bin } j \text{ has been used}$$

\*  $R_i = 1$ : item  $i$  rotated 90 degree



# Item's Coordinate

$l_i, r_i, b_i, t_i$ : left, right, bottom and top coordinates of item  $i$

\* First way to approach:

- if item  $i$  not rotated:  $R_i = 0$

$$\Rightarrow \begin{cases} r_i = l_i + w_i \\ t_i = b_i + h_i \end{cases}$$

- if item  $i$  rotated:  $R_i = 1$

$$\Rightarrow \begin{cases} r_i = l_i + h_i \\ t_i = b_i + w_i \end{cases}$$

\* Another way to approach:

- if item  $i$  not rotated:  $R_i = 0$

$$\Rightarrow \begin{cases} w_i = w_i \\ h_i = h_i \end{cases}$$

- if item  $i$  rotated:  $R_i = 1$

$$\Rightarrow \begin{cases} w_i = h_i \\ h_i = w_i \end{cases}$$



# CP model - Constraints

Each item has to be packed in exactly 1 bin

$$\sum_{j=1}^{N\_bins} X_{ij} = 1 \text{ for } i \text{ in } N\_items$$

No two items overlap

if  $X_{i_1j} = X_{i_2j} = 1$

$$r_{i_1} \leq l_{i_2} \text{ or } r_{i_2} \leq l_{i_1} \text{ or } t_{i_1} \leq b_{i_2} \text{ or } t_{i_2} \leq b_{i_1}$$

Items cannot exceed the bin

if  $X_{ij} = 1$

$$\Rightarrow \begin{cases} w_i \leq r_i \leq W_j \\ h_i \leq t_i \leq H_j \end{cases}$$

# MIP model - Constraints

Each item has to be packed in exactly 1 bin

$$\sum_{j=1}^{N\_bins} X_{ij} = 1 \text{ for } i \text{ in } N\_items$$

No two items overlap

if  $X_{i_1j} = X_{i_2j} = 1$

$$r_{i_1} \leq l_{i_2} \text{ or } r_{i_2} \leq l_{i_1} \text{ or } t_{i_1} \leq b_{i_2} \text{ or } t_{i_2} \leq b_{i_1}$$

⇒ To MIP:

$$\begin{cases} r_{i_1} \leq l_{i_2} + M * (1 - (r_{i_1} \leq l_{i_2})) \\ r_{i_2} \leq l_{i_1} + M * (1 - (r_{i_2} \leq l_{i_1})) \\ t_{i_1} \leq b_{i_2} + M * (1 - (t_{i_1} \leq b_{i_2})) \\ t_{i_2} \leq b_{i_1} + M * (1 - (t_{i_2} \leq b_{i_1})) \\ (r_{i_1} \leq l_{i_2}) + (r_{i_2} \leq l_{i_1}) + (t_{i_1} \leq b_{i_2}) + (t_{i_2} \leq b_{i_1}) + (1 - (X_{i_1j} == X_{i_2j})) * M \geq 1 \\ (r_{i_1} \leq l_{i_2}) + (r_{i_2} \leq l_{i_1}) + (t_{i_1} \leq b_{i_2}) + (t_{i_2} \leq b_{i_1}) \leq (X_{i_1j} == X_{i_2j}) * M \end{cases}$$

Items cannot exceed the bin

if  $X_{ij} = 1$

$$\Rightarrow \begin{cases} w_i \leq r_i \leq W_j \\ h_i \leq t_i \leq H_j \end{cases}$$

⇒ To MIP:

$$\begin{cases} r_i \leq (1 - X_{ij}) * M + W_j \\ t_i \leq (1 - X_{ij}) * M + H_j \end{cases}$$



# Heuristic

03

# The heuristic algorithm

## Sorting

Bins by “density” (cost/area), in descending order

Items by longer side in descending order

## Destination Bin

Bin First Fit rule – pack the item into the bin with the lowest index (after the process of sorting bins from 1); in other words, pack in the first bin that the item fits

## Destination Free Rectangle of a Bin

Best Short Side Fit rule – choose a free rectangle where the shorter remainder side after insertion is minimized; in other words, minimize the length of the shorter leftover side, ties broken with best longer side (longer leftover side is minimized)

# Packing process

Concept of free rectangles: A list of free rectangles represents the free space of the bin. In the Guillotine algorithm, these rectangles are pairwise disjoint

Heuristic algorithms: Combine two algorithms, including Guillotine and Maximal Rectangles

# Guilotine

- Pack the item into the first free rectangle of the bin, which means the bin itself, starting with its bottom-left corner.

- For each insertion, split the initial free rectangle into smaller free rectangle(s), which are tracked in a list.

- Whenever a new item is inserted into the bin, choose a free rectangle (with rule II.2) and place the item into its bottom-left corner, then split the chosen rectangle using the Guillotine split rule to produce at most two new rectangles.

- Merge some free rectangles into larger ones if possible.

- \* Splitting rule: Best Short Side rule - split by horizontal axis if the free rectangle's width is less than its height; otherwise, split by vertical axis.

- \* Rectangle merging: if there exists a pair of neighboring rectangles  $F_i$  and  $F_j$  such that  $F_i \cup F_j$  can be exactly represented by a single bigger rectangle, merge these two into one.




# Maximal Rectangles



- Rather than choosing one of the two split axes like in the Guillotine algorithm, the Maximal Rectangles algorithm picks both split axes at the same time to ensure that the largest possible rectangular areas are present in the list of free rectangles.
- Because the free rectangles are no longer pairwise disjoint like in the Guillotine algorithm, any free rectangle that intersects the area occupied by the newly inserted item is split to remove the intersection.
- Delete every free rectangle which is fully overlapped by others in the list.



# Statistics



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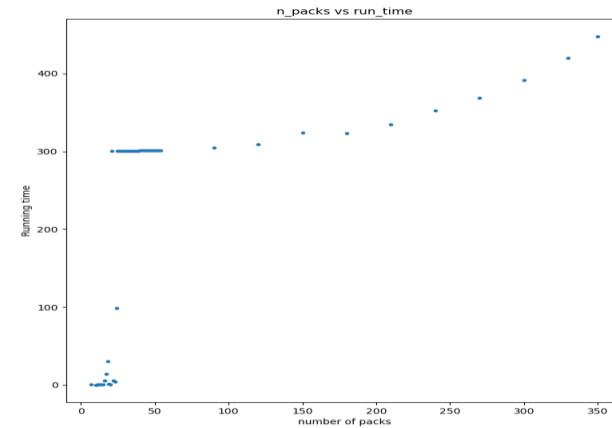
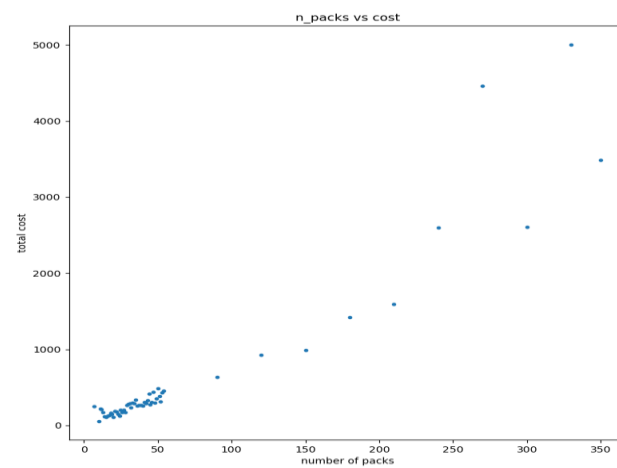
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# CP model

Out of 58 tests, the model can solve 56, with a 300-second time limitation

The objective values (costs) of solved instances are excellent in general

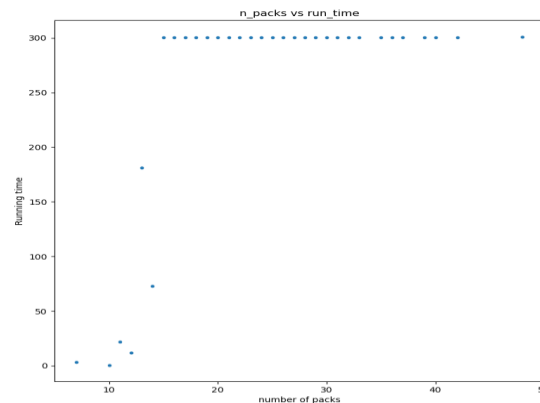
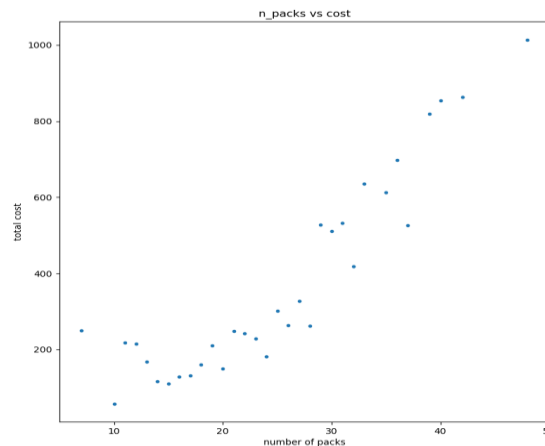




# MIP model

Out of 58 tests, the model can solve 32, with a 300-second time limitation

The objective values (costs) of solved instances are quite good in general

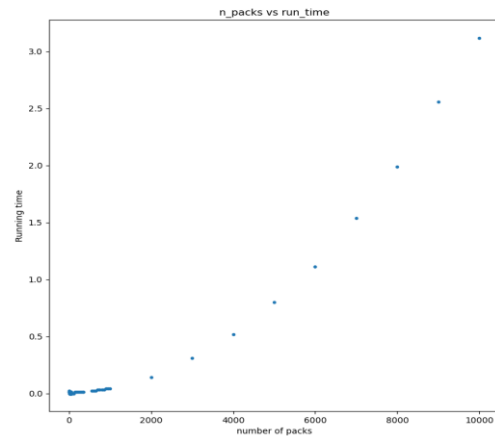
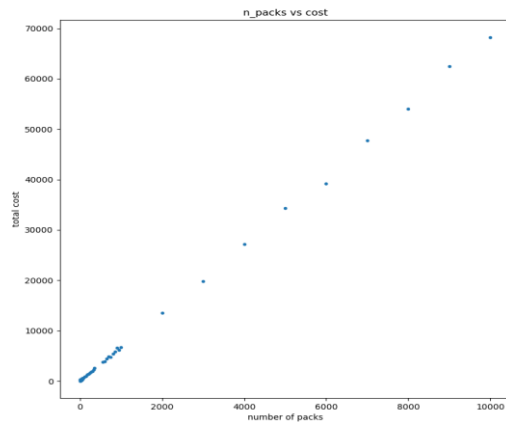


# Heuristic

It can solve all **75** tests without a time limitation

The objective values (costs) of instances are good

The running time form an exponential curve with the number of rectangles (test size)



# MEET THE TEAM



Phan Dinh  
Nhat



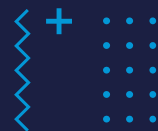
Nguyen Huu  
Duan



Chu Minh  
Ha



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Minh





**CYBER SECURITY**

# Thanks for attention!

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