

Graph (V)

Matthew Chau {happychau} 2023-05-27

Introduction

Sometimes there are tree problems that can be solved efficiently by certain properties.

In today's lecture, we will take a look at Centroid Decomposition and Heavy-light Decomposition, algorithms that will allow us to break down the trees for our own convenience.

Our Powerful Weapons

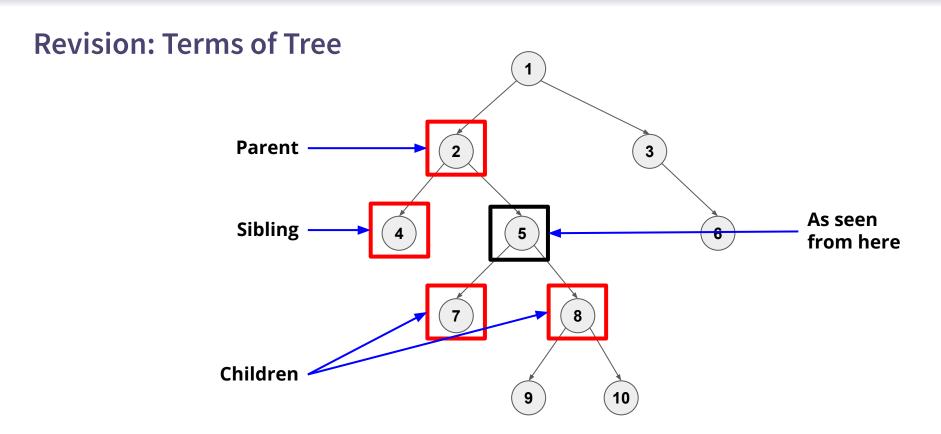
Still DFS!

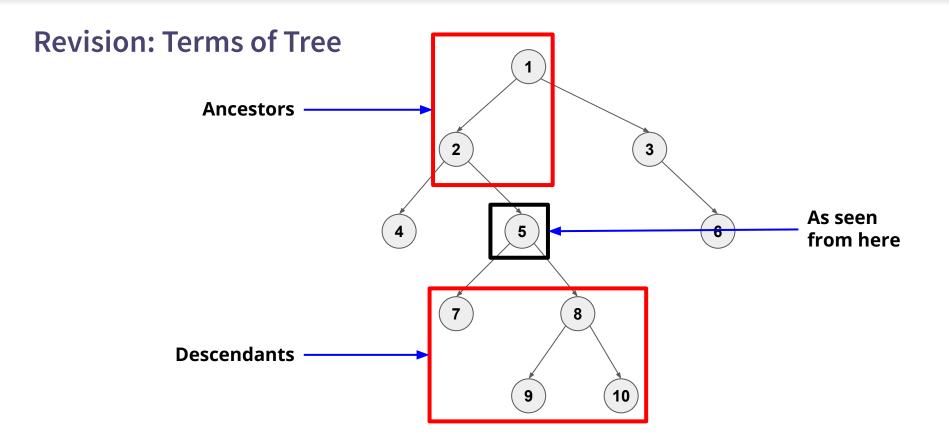


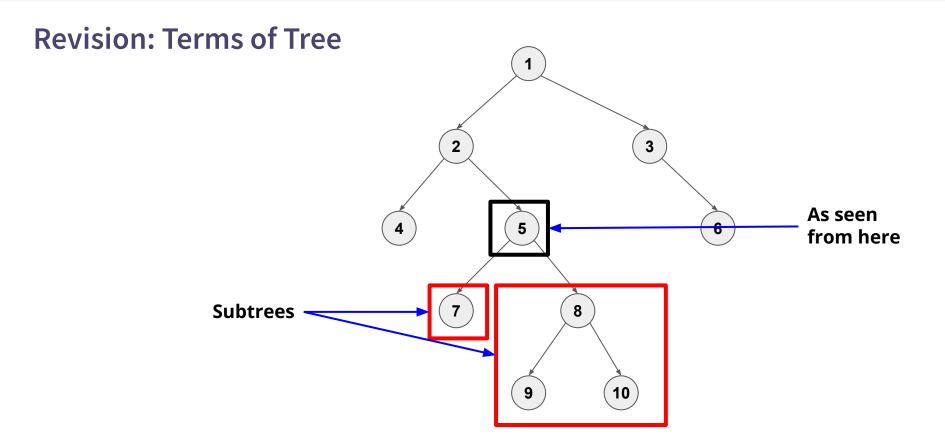
Revision: Terms of Tree

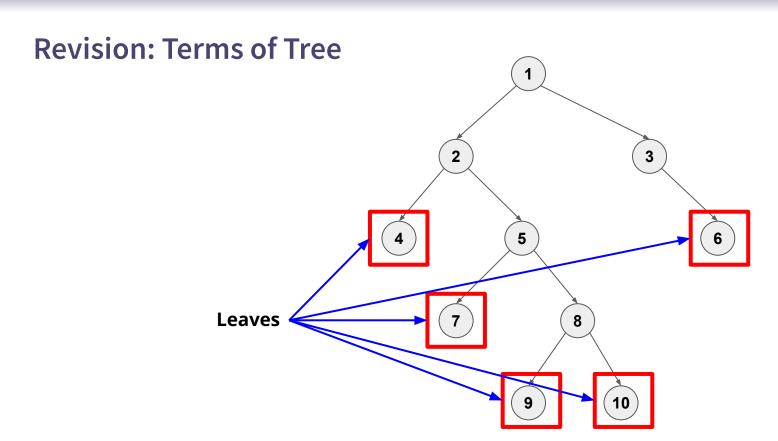
Refer to Graph (IV) (2023)

https://assets.hkoi.org/training2023/g-iv.pdf









Revision: DFS

```
vector<vector<int>> G; // Adjacency List
vector<bool> vis;
void dfs(int u) {
  vis[u] = true;
 for (int v : G[u])
  if (!vis[v])
      dfs(v);
```

Centroid Decomposition

Centroid on tree

A **centroid** of a tree is defined as:

• a node such that when the tree is rooted at it, no other nodes have a subtree of size greater than N/2.

Centroid on tree

A visual example: which is centroid?

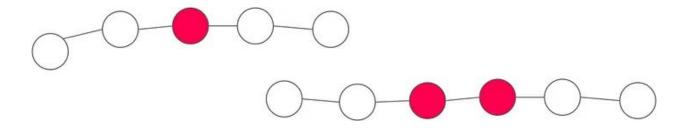
Centroid on tree

Answer:

Centroid vs Center

Centroid is different from the **center** of a tree:

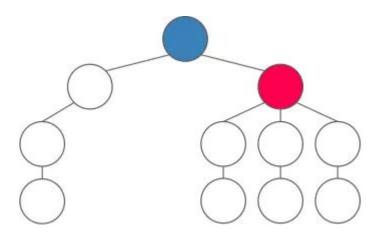
• the middle nodes (either 1 or 2) in every longest path along the tree.



Centroid vs Center

Example:

The red node is the centroid but the blue node is the center.



Why?

It may be unintuitive why we would need centroid decomposition.

Let's take a look at CF342E: https://codeforces.com/problemset/problem/342/E

E. Xenia and Tree

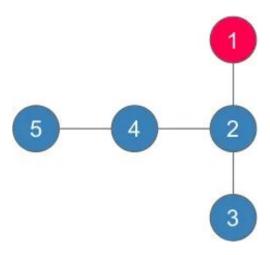
time limit per test: 5 seconds
memory limit per test: 256 megabytes
input: standard input
output: standard output

Problem statement:

- Consider a tree with nodes indexed from 1 to n.
- The first node is initially painted red, and the other nodes painted blue.
- Two types of operation:
 - a. Update(u): Paint blue node u red
 - b. Query(u): Find the distance to the closest red node for node u
- n, # of queries $\leq 10^5$

Example:

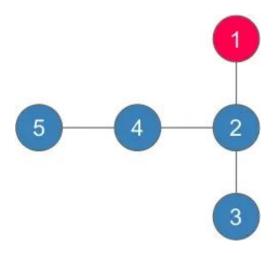
n = 5 as follow



Example:

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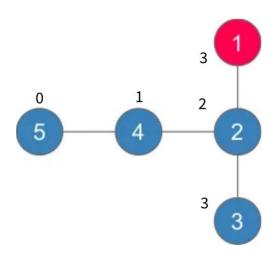
query(5) = ?



Example:

n = 5 as follow

query(5) = 3



How do we approach this problem?

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1. BFS/DFS on query

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```
int query(int u, int p) {
  if (colour[u] == 1) return 0;
  int mn = INF;
  for (auto v : tree[u])
    if (v != p)
       mn = min(mn, query(v, u));
  return mn + 1;
}

void update(int a) {
  colour[a] = 1;
}
```

How do we approach this problem?

- 1. BFS/DFS on query
 - a. Update: O(1)
 - b. Query: O(n)

This surely will TLE

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- 1. BFS/DFS on query
 - a. Update: O(1)
 - b. Query: O(n)
- 2. BFS/DFS on update

```
int query(int u) {
   return ans[u];
}

void update(int u, int p, int d) {
   ans[u] = min(ans[u], d);
   for (auto v : tree[u])
       if (v != p)
            update(v, u, d + 1);
}
```

How do we approach this problem?

- 1. BFS/DFS on query
 - a. Update: O(1)
 - b. Query: O(n)
- 2. BFS/DFS on update
 - a. Update: O(n)
 - b. Query: O(1)

This will also TLE

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}
```

Is it possible to balance the two operations?

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Centroid Decomposition

Recall the definition of **centroid**:

 a node such that when the tree is rooted at it, no other nodes have a subtree of size greater than N/2.

How to find the centroid with program?

Consider a node u:

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- If all of its neighbor nodes have subtree size <= N/2:
 - Centroid

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- Otherwise:
 - there will only be one neighbor node with subtree size > N/2

Therefore we propose an algorithm:

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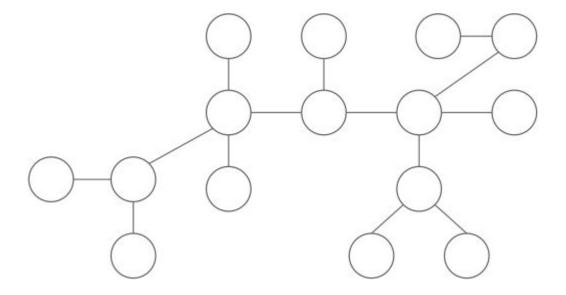
- 1. Arbitrarily take a node as root
- 2. Calculate the subtree sizes

Therefore we propose an algorithm:

- 1. Arbitrarily take a node as root
- 2. Calculate the subtree sizes
- 3. Start considering from root node:
 - a. If a neighbor node have subtree size > N/2: consider such node
 - b. Otherwise the current node is centroid

Visualization:

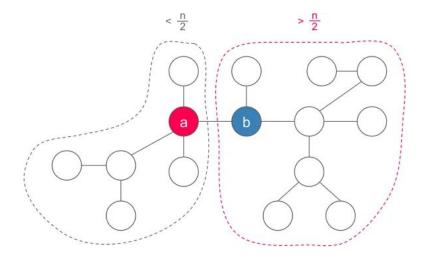
- 1. Arbitrarily root a node
- 2. Calculate the subtree sizes
- 3. Start considering from root node:
 - a. If a neighbor node have subtree size > N/2: consider such node
 - b. Otherwise the current node is centroid



Finding centroid

Some idea on why this work:

- it doesn't visit a visited node (it doesn't go back from b to a).
 - \circ If it does, it will visit a node with subtree size < N/2.



Finding centroid

Let's code this out

- 1. Precompute a. DFS!
- 2. Search

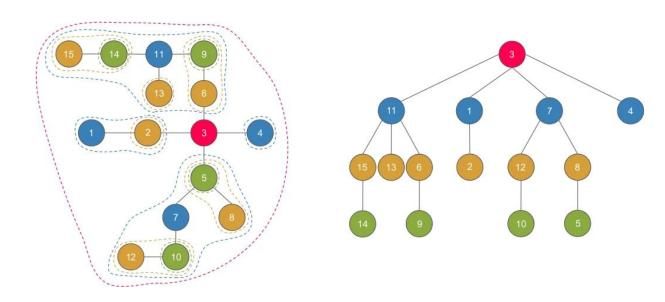
```
int dfs(int u, int p) {
   for (auto v : tree[u])
      if (v != p) sub[u] += dfs(v, u);
   return sub[u] + 1;
}

int centroid(int u, int p) {
   for (auto v : tree[u])
      if (v != p and sub[v] > n/2) return centroid(v, u);
   return u;
}
```

The centroid decomposition of a tree is another tree defined recursively as:

- Its root is the centroid of the original tree.
- Its children are the centroid of each tree resulting from the removal of the centroid from the original tree.

Visualization:



To code that: apply the definitions

```
void build(int u, int p) {
   int n = dfs(u, p); // find the size of each subtree
   int cent = centroid(u, p); // find the centroid
   if (p == -1) p = cent; // dad of root is the root itself
   dad[cent] = p;

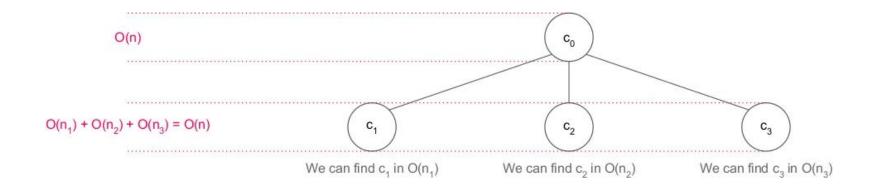
   // for each tree resulting from the removal of the centroid
   for (auto v : tree[cent])
        tree[cent].erase(v), // remove the edge to disconnect
        tree[v].erase(cent), // the component from the tree
        build(v, cent);
}
```

Time complexity: O(n log(n))

- Similar to merge sort, the maximum depth for decomposition is log n.
- Each level contains less than n nodes in total

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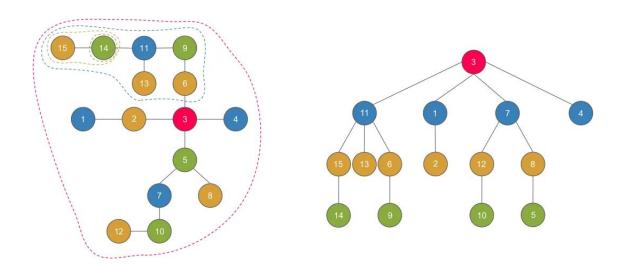


What can we do with the results?

Property 1: A vertex belongs to the component of all its ancestors.

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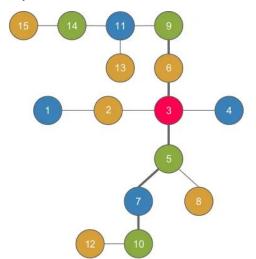
• The node 14 belongs to the component of 14, 15, 11 and 3.

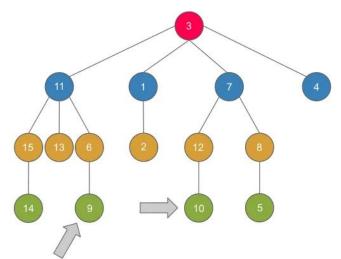


Property 2: the path from a to b can be decomposed into the path from a to lca(a,b) and the path from lca(a,b) to b.

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• The path from 9 to 10 in the original tree can be decomposed into the path from 9 to 3 and the path from 3 to 10.





Property 2: the path from a to b can be decomposed into the path from a to lca(a,b) and the path from lca(a,b) to b.

Proof:

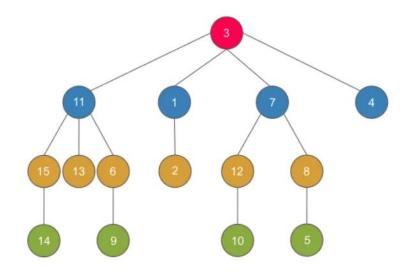
 Both a and b belong to the component where the node lca(a,b) is the centroid.

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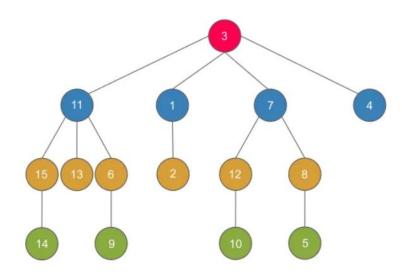
- Both a and b belong to the component where the node lca(a,b) is the centroid.
 - i.e. removal of lca(a,b) will split them into different components.

Property 3: Each one of the n² paths of the original tree is the concatenation of two paths in a set of O(n log(n)) paths from a node to all its ancestors in the centroid decomposition.

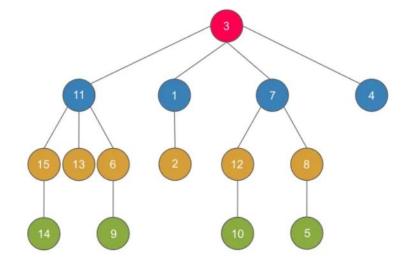


Take node 14 as example, to reach node a:

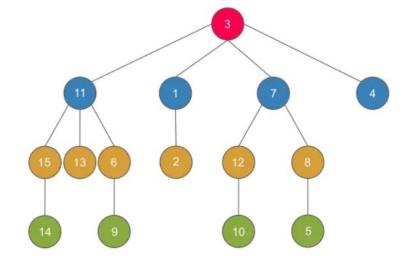
• $\alpha = \{14\}: (14, 14) + (14, \alpha)$



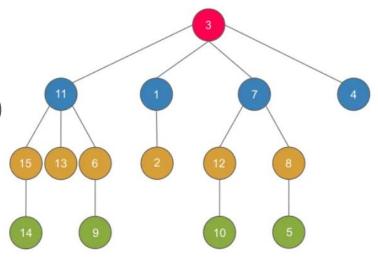
- $\alpha = \{14\}: (14, 14) + (14, \alpha)$
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- $a = \{14\}: (14, 14) + (14, a)$
- $a = \{15\}$: (14, 15) + (15, a)
- $a = \{6, 9, 13\}$: (14, 11) + (11, a)



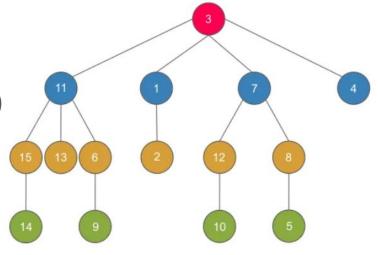
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- $a = \{6, 9, 13\}$: (14, 11) + (11, a)
- $a = \{1, 2, 4, 5, 6, 7, 10, 12\}$: (14, 3) + (3, a)



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- $a = \{6, 9, 13\}$: (14, 11) + (11, a)
- $\alpha = \{1, 2, 4, 5, 6, 7, 10, 12\}$: $(14, 3) + (3, \alpha)$

As we can see, they can all be expressed as two paths, where one of them passes through 14's four ancestors.



Property 3: Each one of the n² paths of the original tree is the concatenation of two paths in a set of O(n log(n)) paths from a node to all its ancestors in the centroid decomposition.

 As each node contains at most log(n) ancestors, the total number of paths is n*log(n).

Back to the problem.

How do we optimize the problem with centroid decomposition?

Define ans[a] as the distance to the closest red node to a in the component where node a is centroid.

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For update:

- Assume node a becomes red now
- It will only affect the ancestor of a
 => ans[b] = min(ans[b], dist(a, b)) for all ancestor b of a

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log(n) ancestor * log(n) dist calculation = $O(log(n)^2)$

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For query:

- We can consider all nodes by ancestors of a
- ans = min(dist(a,b) + ans(b)) for all ancestor b of a
 - o ans[b]: answer from b to other nodes c that lca(a,c) = b

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log(n) ancestor * log(n) dist calculation = $O(log(n)^2)$ as well

Through centroid decomposition, we can split every possible paths into two paths that are easier to manage.

Related problems

- <u>IOI'11 Race</u>
- 321C Ciel the Commander
- 766E Mahmoud and a xor trip
- <u>716E Digit Tree</u>
- <u>161D Distance in Tree</u>
- 776F Sherlock's bet to Moriarty
- 379F New Year Tree
- 342E Xenia and Tree
- 293E Close Vertices
- <u>150E Freezing with Style</u>
- 348E Pilgrims
- Codechef Prime Distance On Tree

Reference

https://medium.com/carpanese/an-illustrated-introduction-to-centroid-decomposition-8c1989 d53308

Questions?

break;

Heavy-light Decomposition

Heavy Light Decomposition

- A way to split a tree into several paths
- Each node can reach the root node through at most log(n) paths



Why

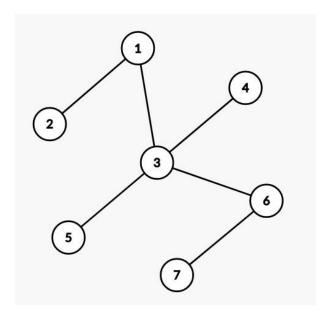
It would allows us to effectively solve many problems that require queries on a tree .

Given a tree with n node. Initially, all edges are "light edge".

There are two types of operations:

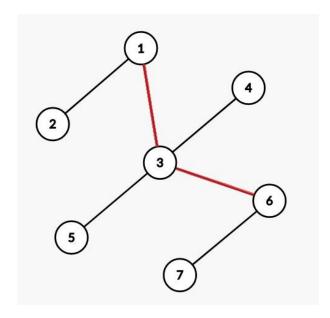
- update(a,b): for all node x on the path from a to b, first assign all connected edges of x as "light edge", then assign the path from node a to node b as "heavy edge".
- 2. query(a,b): count how many edges from node a to node b are "heavy edge".

Example: consider the following tree:



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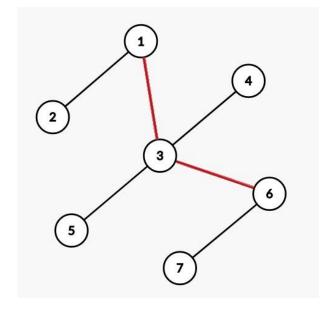
update(1,6);



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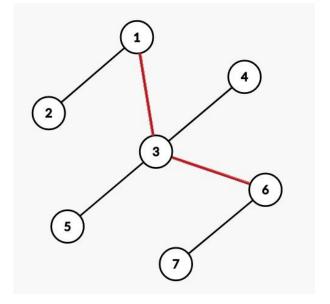
query(2,4) = ?



Example: consider the following tree:

update(1,6);

query(2,4) = 1

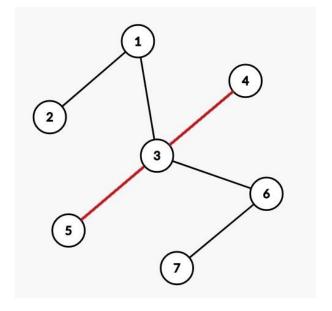


Example: consider the following tree:

update(1,6);

query(2,4) = 1

update(4,5);



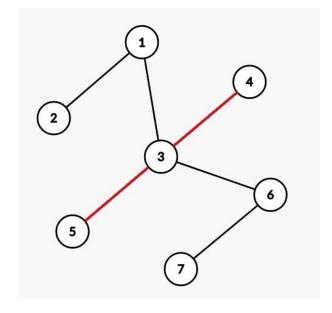
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update(1,6);

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update(4,5);

query(2,4) = ?



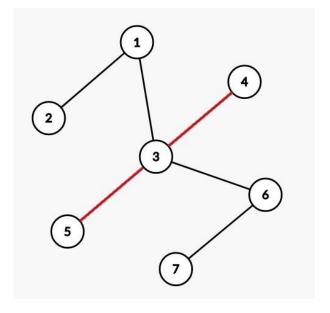
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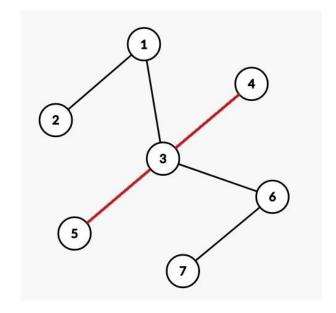
query(2,4) = 1



Naive solution: update the paths accordingly.

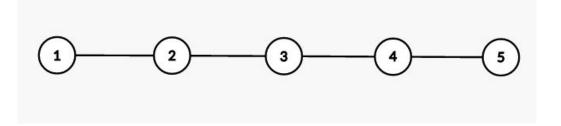
Time complexity: O(n)

TLE:(



This looks hard, let's figure out how to solve it on a simpler problem.

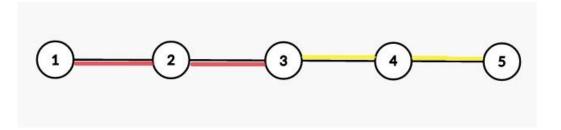
Consider a chain:



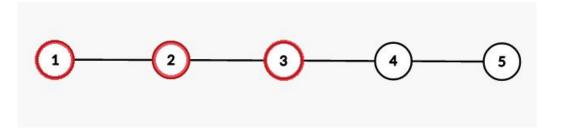
update(1,3)

update(3,5)

How can we handle them?



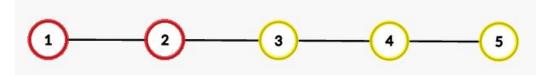
Instead of updating edges, consider colouring the nodes: update(1,3);



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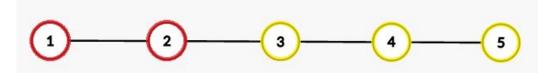
update(3,5);

Number of heavy edges becomes: number of adjacent nodes with same colour



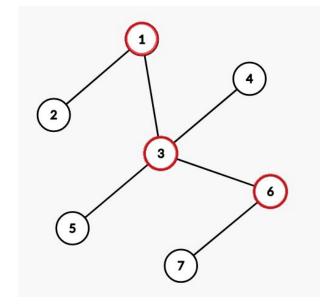
This can be solved with segment tree.

Time complexity = O(log(n))



But how do we solve this problem on tree?

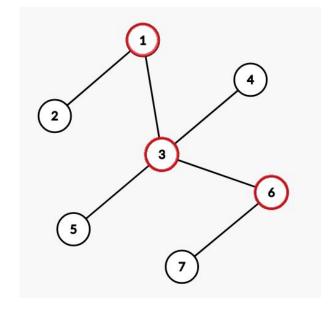
Can we divide the paths into segments of chains?



But how do we solve this problem on tree?

Can we divide the paths into segments of chains?

Yes!



This is why we need heavy-light decomposition.

Recall what it does:

- Split a tree into several paths
- Each node can reach the root node through at most log(n) paths

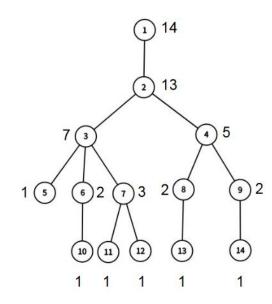
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To understand how it works, let's start with some definitions:

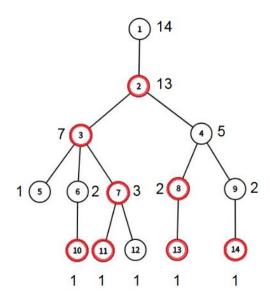
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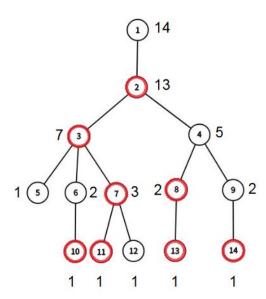
 Heavy edge: the edge to the child with the largest subtree size.



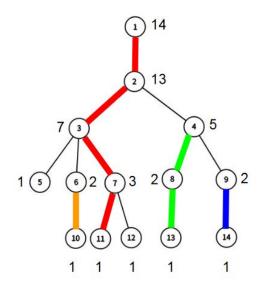
To understand how it works, let's start with some definitions:

Assume the tree is rooted and we know every subtree sizes, then for a node u:

- Heavy edge: the edge to the child with the largest subtree size.
- Light edge: edges that are not heavy.

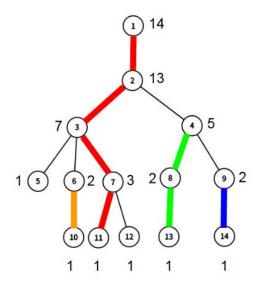


These are all the heavy edges labelled.



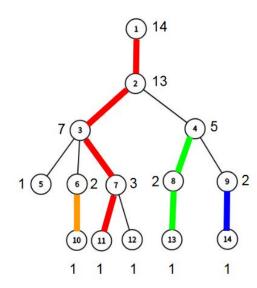
These are all the heavy edges labelled.

DFS on the tree with heavy edges first: 1 2 3 7 11 12 6 10 5 4 8 13 9 14

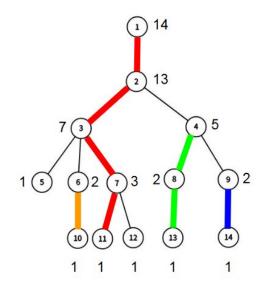


Consider visiting nodes from root:

How many light edge will we go through?

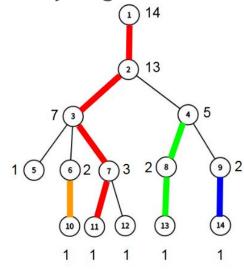


Observe that a light edge must connect to a node with subtree size halve that of the parent node.



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Otherwise it will be the heavy edge.



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Therefore every simple path from root at most will go through log(n) light edges.

Let's try and code that out:

Compute the subtree sizes: DFS

```
void calc_size(int id) {
    size[id] = 1;
    for (int i = 0; i < edge[id].size(); ++i) if (edge[id][i] != parent[id]) {
        parent[edge[id][i]] = id;
        calc_size(edge[id][i]);
        size[id] += size[edge[id][i]];
        if (size[edge[id][i]] > size[edge[id][0]]) swap(edge[id][i],edge[id][0]);
    }
}
```

Let's try and code that out:

Compute the subtree sizes: DFS

We also mark the heavy edges for convenience.

```
void calc_size(int id) {
    size[id] = 1;
    for (int i = 0; i < edge[id].size(); ++i) if (edge[id][i] != parent[id]) {
        parent[edge[id][i]] = id;
        calc_size(edge[id][i]);
        size[id] += size[edge[id][i]];
        if (size[edge[id][i]] > size[edge[id][0]]) swap(edge[id][i],edge[id][0]);
    }
}
```

Let's try and code that out:

Decompose the tree into an array: DFS by heavy edges first

Save the order we visit the nodes into an array

```
void hld(int id) {
    a[++cnt] = id;
    st[id] = cnt;
    for (int i = 0; i < edge[id].size(); ++i) if (edge[id][i] != parent[id]) {
        head[edge[id][i]] = i == 0 ? head[id] : edge[id][i];
        hld(edge[id][i]);
    }
    ed[id] = cnt;
}</pre>
```

Let's try and code that out:

Decompose the tree into an array: DFS by heavy edges first

- Save the order we visit the nodes into an array
- Save the starting and ending position of each heavy paths

```
void hld(int id) {
    a[++cnt] = id;
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    for (int i = 0; i < edge[id].size(); ++i) if (edge[id][i] != parent[id]) {
        head[edge[id][i]] = i == 0 ? head[id] : edge[id][i];
        hld(edge[id][i]);
    }
    ed[id] = cnt;
}</pre>
```

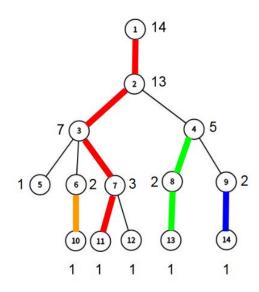
Let's try and code that out:

Decompose the tree into an array: DFS by heavy edges first

- Save the order we visit the nodes into an array
- Save the starting and ending position of each heavy paths
- Mark the parent node of each starting node into head[]

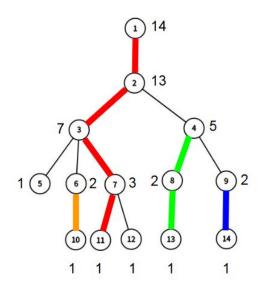
```
void hld(int id) {
    a[++cnt] = id;
    st[id] = cnt;
    for (int i = 0; i < edge[id].size(); ++i) if (edge[id][i] != parent[id]) {
        head[edge[id][i]] = i == 0 ? head[id] : edge[id][i];
        hld(edge[id][i]);
    }
    ed[id] = cnt;
}</pre>
```

Now we have decomposed the tree, and every path to ancestors can be expressed in several heavy paths:



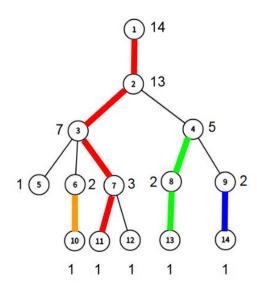
Now we have decomposed the tree, and every path to ancestors can be expressed in several heavy paths:

- 7 2: 7 2
- 10 2: 10 6, 3 2
- 14 1: 14 9, 4 4, 2 1



Paths to other nodes can also be expressed into 2 paths to their lca.

- 7 10: 7 3 + 3 10
 - 0 7 3: 7 3
 - 10 3: 10 6, 3 3



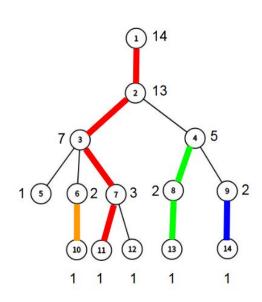
Paths to other nodes can also be expressed into 2 paths to their lca.

Time complexity:

- Lca: O(log(n))
- Retrieving path to ancestor: O(log(n))

Overall: O(log(n))

Implementation is somewhat long and will be left as exercise for readers.

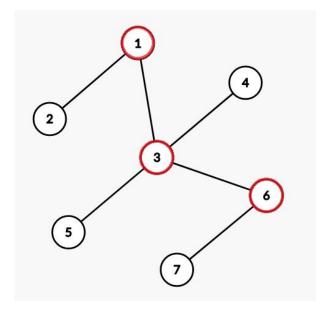


Back to the problem.

We can now split each update and query into log(n) continuous segments.

Which can then be handled by segment tree.

Time complexity: $O(log(n)^2)$



Sometimes although a task can be solved by heavy light decomposition, it actually can be solved using some simpler ways.

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Example: Given a tree

- Update: Change the value of a node
- Query: Find the sum of the values on the path between two nodes

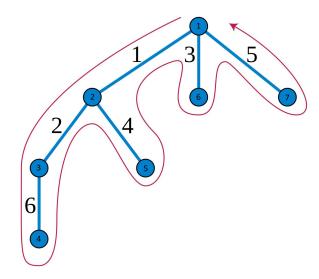
Sometimes although a task can be solved by heavy light decomposition, it actually can be solved using some simpler ways.

Example: Given a tree

- Update: Change the value of a node
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 - Additionally store the the value in negative when leaving the node
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Modified Euler tour = 1, 2, 6, -6, -2, 4, -4, -1, 3, -3, 5, -5

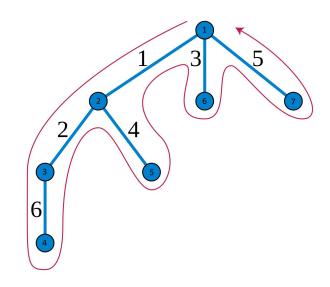


- Store the value of the nodes in Euler tour
- Additionally store the the value in negative when leaving the node
- Use segment tree to query or update

Modified Euler tour = 1, 2, 6, -6, -2, 4, -4, -1, 3, -3, 5, -5

$$(2, 6) = (1, 2) + (1, 6) = (1) + (1, 2, 6, -6, -2, 4, -4, -1, 3)$$

= 4



Related Problems

- <u>Path Queries</u> (CSES)
- QTREE (SPOJ): allows you to test modifications for edges
- GRASSPLA (SPO); original source is USACO but the judge doesn't work for that problem)
- GSS7 (SPOJ)
- <u>QRYLAND</u> (CodeChef)
- MONOPLOY (CodeChef)
- QUERY (CodeChef)
- <u>BLWHTREE</u> (CodeChef)
- Milk Visits (USACO)
- <u>Max Flow</u> (USACO)
- <u>Exercise Route</u> (USACO)

Questions?

end.