# Filip B. Bečanović

#### Optimization • Robotics • Biomechanics • Machine Learning

Dr Agostina Neta 66, 11070, Belgrade, Serbia

® (+381) 64 566 24 28 | ☑ filip.becanovic@gmail.com | in filipbecanovic | ☑ beca-filip

## Education \_\_\_\_\_

### **University Paris-Est Créteil**

Paris, France

### Cotutelle Ph.D. in Signal Processing, Imaging, and Control Systems

Nov, 2020 - Feb, 2024

- École Doctorale Mathématiques et Sciences de la Technologie, Information, et Communication.
- Dissertation title: "Uncovering optimal control strategies in human motion through inverse optimal control".
- Dissertation committee: Milica Janković, Željko Đurović, Vincent Bonnet, François Charpillet, Vincent Padois.
- Advisor: Prof. Samer Mohammed.

## M.S. (Erasmus+ Exchange) in Signal Processing, Imaging, and Control Systems

Jan. 2020 - Jul. 2020

- Biometrics module.
- GPA: 16.5 (out of 20).

## University of Belgrade, School of Electrical Engineering Cotutelle Ph.D. in *Electrical Engineering and Computer Science*

Belgrade, Serbia

- elle Ph.D. in *Electrical Engineering and Computer Science*Nov, 2020 Feb, 2024
- Signals and Systems department.
- Dissertation title: "Uncovering optimal control strategies in human motion through inverse optimal control".
- Dissertation committee: Milica Janković, Željko Đurović, Vincent Bonnet, François Charpillet, Vincent Padois
- Advisor: Prof. Kosta Jovanović.

### M.S. in Electrical Engineering and Computer Science

Oct, 2019 - Sep, 2020

- Signals and Systems department.
- GPA: 9.33 (out of 10).

#### B.S. in Electrical Engineering and Computer Science

Oct, 2015 - Sep, 2019

- Signals and Systems department.
- GPA: 9.42 (out of 10).

# Publications \_

## Journal Papers (published)

**1. Bečanović, F.,** Bonnet, V., Dumas, R., Jovanović, K. and Mohammed, S., 2022. Force Sharing Problem During Gait Using Inverse Optimal Control. *IEEE Robotics and Automation Letters*, 8 (2), pp. 872-879. [DOI: 10.1109/LRA.2022.3217398].

## Conference Proceedings (published)

- 1. **Bečanović, F.**, Bonnet, V. and Jovanović, 2024. Reliability of Single-Level Equality-Constrained Inverse Optimal Control. 2024 IEEE-RAS 23<sup>rd</sup> International Conference on Humanoid Robots (Humanoids), pp.623-630. [DOI: 10.1109/Humanoids58906.2024.10769923]
- 2. Klasanović, D., Jugović, L., Ružić, N., **Bečanović, F.** and Knežević, N., 2024. Application and Optimal Design of a Soft Robotic Gripper for Grasping Objects of Arbitrary Shape. *11th International Conference on Electrical, Electronic and Computing Engineering (IcETRAN 2024)*, pp. 77. [DOI: 10.1109/IcETRAN62308.2024.10645079]
- 3. Lukić, B., **Bečanović, F.**, and Radmilović, M., 2024. Human motion estimation application for the marker-based motion capture systems. *11th International Conference on Electrical, Electronic and Computing Engineering (IcETRAN 2024)*, pp. 80. [DOI: 10.1109/IcETRAN62308.2024.10645143]
- 4. Rodić, F., **Bečanović, F.**, Aleksić, J., Mirkov, D. and Jovanović, K., 2024. Synchronization of Motion Capture and Forceplate Data for Analysis of Vertical Jumping. *11th International Conference on Electrical, Electronic and Computing Engineering (IcETRAN 2024)*, pp. 80. [DOI: 10.1109/IcETRAN62308.2024.10645109]
- 5. **Bečanović**, **F.,** Miller, J., Bonnet, V., Jovanović, K. and Mohammed, S., 2022. Assessing the Quality of a Set of Basis Functions for Inverse Optimal Control via Projection onto Global Minimizers. *IEEE 61st Conference on Decision and Control (CDC)*, pp. 7598-7605. [DOI: 10.1109/CDC51059.2022.9993342]

- 6. Radmilović, M., Urukalo, D., Petrović, M., Bečanović, F. and Jovanović, K., 2021. Influence of muscle co-contraction indicators for different task conditions. 8th International Conference on Electrical, Electronic and Computing Engineering (IcETRAN 2021), pp. 584-590. [ISBN 978-86-7466-894-8]
- 7. Bečanović, F., Bonnet, V., Mohammed, S. and Jovanović, K., 2021. Pronalazak Optimizacione Funkcije Kretanja iz Simulirane Demonstracije Pokreta Čučnja. 65<sup>th</sup> Conference on Electrical, Electronic and Computing Engineering (ETRAN 2021), pp. 551-555. [ISBN 978-86-7466-894-8]

# Experience \_\_\_\_\_

University of Belgrade, School of Electrical Engineering Research Associate (i.e. Postdoctoral Researcher), Robotics Laboratory Research Assistant (i.e. Ph.D. Student Researcher), Robotics Laboratory Laboratory for Analysis and Architecture of Systems (LAAS-CNRS) Visiting Ph.D. Student, Humanoid Robotics, Gepetto Team Visiting Ph.D. Student, Humanoid Robotics, Gepetto Team Microsoft Development Center Serbia (MDCS) Mathematical Data Labelling Associate, Math Team University of Belgrade, School of Electrical Engineering Lab Assistant, Electrical Engineering Laboratory

Belgrade, Serbia Sep. 2024 - Present Apr, 2021 - Sep, 2024 Toulouse, France Jan, 2023 – May, 2023 Jan, 2022 - May, 2022 Belgrade, Serbia Feb, 2019 - Jun, 2019 Belgrade, Serbia Feb 2019 - May 2019

# Teaching \_\_\_\_\_

University of Belgrade, School of Electrical Engineering Teaching Assistant

• 13E054BMH Biomechanics **University Paris-Est Créteil** Teaching Assistant

• (License SPI - Synthèse SPI) Engineering Sciences Synthesis

Belgrade, Serbia Autumn, 2023, 2024

Paris, France

# **Project Participation**

Horizon Europe Projects (Funding Body: EU Commission)

MUSAE: A Human - Centered Factory for a Future Technological Sustainable

Sep, 2023 - Present Development Driven by Arts (MUSAE)

- Acronym: MUSAE.
- Call: HORIZON-CL4-2021-HUMAN-01.
- Grant ID: 101070421.
- Role: Researcher, Administrative staff.
- Institution: University of Belgrade, School of Electrical Engineering.

### **Nationally Funded Projects**

Multi-SENSor SysteM and ARTificial intelligence in service of heart failure Sep, 2023 - Dec, 2023 diagnosis (SensSmart)

- Acronym: SensSmart.
- Funding body: Science Fund of the Republic of Serbia.
- Call: IDEAS Programme.
- Grant ID: 7754338.
- Role: Researcher, Administrative staff.
- Representing institution: University of Belgrade, School of Electrical Engineering.

# Scholarships \_\_\_\_\_

Cotutelle Ph.D. Scholarship

Nov, 2020 - Nov, 2023

Funded by the French government's agency Campus France. 36-month long. Supported by the French Institute in Serbia and the French Embassy in Serbia

**ERASMUS+ KA1 Scholarship** 

Jan, 2020 - Jul, 2020

Funded by the European Union's ERASMUS+ program. 6-month long.

**Exceptional Academic Performance Scholarship** 

Oct, 2017 - Sep, 2020

Funded by the Serbian government's Ministry of Science, Technological Development and Innovation.

# Continuous Learning and Certifications \_\_\_\_\_

Certificate of Proficiency in English (C2)

Jan. 2025

Cambridge University Press & Assessment

English C2 CEFR level exam.

10<sup>th</sup> Practical Seminar in Machine Learning (PSIML10)

Jul, 2024

Among selected 20 applicants (out of 200+). Received accommodation and travel grant. 10-day-long. Organized by Serbian science and engineering center PFE. Sponsored by Microsoft Development Center Serbia.

Eastern European Machine Learning Summer School (EEML2024)

Jul, 2024

Among selected 150 applicants (out of 700+). Received accommodation and travel grant. Week-long. Organized by Google DeepMind researchers. Sponsored by Google DeepMind.

## Professional Service \_\_\_\_\_

#### Peer-review

**Journals** 

IEEE Robotics and Automation Letters 2024-2025

Conferences

IEEE Control and Decision Conference2023-2024International Conference on Robotics in Alpe-Adria-Danube Region2025

International Conference on Electrical, Electronic and Computing Engineering 2021-2025