Statistics 360: Advanced R for Data Science Multivariate Adaptive Regression Splines (MARS)

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Terminology of MARS

- MARS stands for Multivariate Adaptive Regression Splines.
- Multivariate: able to generate model based on several input variables (high dimensionality).
- Adaptive: Generates flexible models in passes each time adjusting the model.
- Regression: estimation of relationship among independent and dependent variables.
- Spline: a piecewise defined polynomial function that is smooth (possesses higher order derivatives) where polynomial pieces connect.
- Knot: the point at which two polynomial pieces polynomial pieces connect.

Introduction to MARS

- ▶ MARS is a form of stepwise linear regression.
- ▶ Introduced by Jerome Friedman in 1991.
- ▶ In R, this methods is implemented by package earth
- Suitable for higher dimensional inputs
- Extension of linear model that can model non-linearity.
- MARS models are simpler as compared to other models like random forest or neural networks.

Normal regression vs MARS

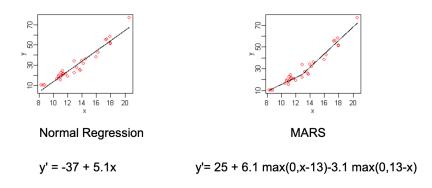


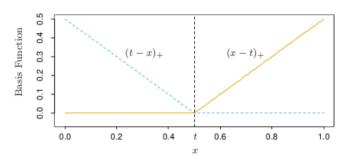
Figure 1: Linear regression vs MARS

In the MARS plot, you could see there is one knot at x=13.

Basis Functions

MARS uses piecewise linear basis functions of the form $(x-t)_+$ and $(t-x)_+$. The + means postive part only. so

$$(x-t)_+ = max(0,x-t), \qquad (t-x)_+ = max(0,t-x)$$



Basis Functions

MARS uses collection of functions comprised of reflected pairs for each input x_j with knots at each observed value x_{ij} of that input

$$C = \{(x_j - t)_+, (t - x_j)_+\}_{t \in \{x_{1j}, x_{2j}, \dots, x_{Nj}\}, j = 1, 2, \dots, p}.$$

- ► If all input values are distinct, then set C contains 2np functions where
 - n = number of observations.
 - ightharpoonup p = number of predictors or input variables.

MARS Model Euqation

MARS model has the general form

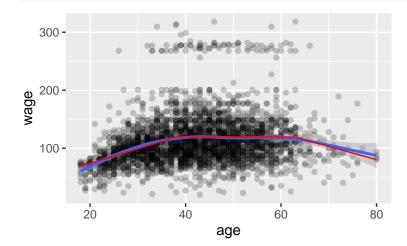
$$f(x) = \beta_0 + \sum_{k=1}^{M} \beta_k h_k(x)$$

- $h_k(x)$ is a function from set C of candidate functions or a product of two or more such functions.
- \triangleright β s are the coefficients estimated by minimizing the residual sum of squares (standard linear regression).
- ► These coefficients can be consider weights that represent the importance of the variable.

Example Data

```
library(tidyverse)
   library(ISLR)
   data(Wage) # help(Wage) for info
   ggplot(Wage,aes(x=age,y=wage)) + geom_point(alpha=.2) + geom_smooth()
      300 -
200 -
     100 -
            20
                            40
                                                          80
                                           60
                                  age
```

```
library(earth)
ee <- earth(wage ~ age, data=Wage)
Wage <- mutate(Wage,pwage = predict(ee))
ggplot(Wage,aes(x=age,y=wage)) + geom_point(alpha=.2) + geom_smooth()+
    geom_line(aes(y=pwage),color="red")</pre>
```



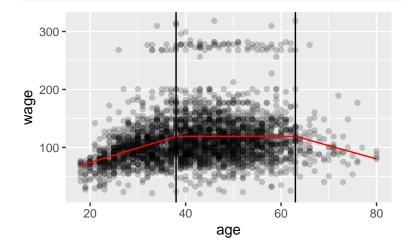
```
summary(ee)
## Call: earth(formula=wage~age, data=Wage)
##
##
              coefficients
## (Intercept) 119.190151
## h(38-age) -2.508377
## h(age-63) -2.289070
##
## Selected 3 of 4 terms, and 1 of 1 predictors
## Termination condition: RSq changed by less than 0.001 at 4 terms
## Importance: age
## Number of terms at each degree of interaction: 1 2 (additive model)
```

GRSq 0.08405764 RSq 0.08649934

RSS 4770379

GCV 1595.44

```
ggplot(Wage,aes(x=age,y=wage)) + geom_point(alpha=.2) +
geom_line(aes(y=pwage),color="red") +
geom_vline(xintercept=38) +
geom_vline(xintercept=63)
```



Hinge functions

- ► The points 38 and 63 are "knots" where the piece-wise linear function changes slope.
- The piece-wise linear fit is a linear model in a constant term (intercept) and two "hinge" functions, h(38-age) and h(age-63), where

$$h(x) = \max(0, x)$$

- ▶ Hinge functions h(x c) and h(c x) are called mirror image.
 - Exercise: Plot two mirror-image hinge functions for x <- seq(from=0,to=50,length=100) and c<-50. Why are they called mirror image?

Fitting

Once we are given the knots and hinge functions, the fit can be obtained by least squares.

```
Wage <- mutate(Wage,h1=pmax(0,38-age),h2=pmax(0,age-63))
ff <- lm(wage ~ h1+h2,data=Wage)
summary(ff)$coefficients</pre>
```

```
## Estimate Std. Error t value Pr(>|t|)
## (Intercept) 119.190151 0.8539353 139.577500 0.000000e+00
## h1 -2.508377 0.1506008 -16.655805 1.216314e-59
## h2 -2.289070 0.5949343 -3.847601 1.217668e-04
```

Questions

- ► How do we choose the knots?
- ► What happens when there are multiple explanatory variables, and we allow for interactions between them?

MARS Model Building Procedure

- 1. Gather data: x input variables with y observations each, giving a total of xy data points.
- 2. Calculate set of candidate functions by generating reflected pairs of basis functions with knows set at observed values.
- 3. Specify constraints; the number of terms in the model and maxium allowable degree of interaction.
- 4. Do foward pass: try out new fucntion products and see which product decreases training error.
- 5. Do backward pass: fix overfit.
- 6. Do generalized cross validation to estimate the optimal number of terms in the model.

MARS Forward Pass

- At each step, MARS adds the basis function which reduces the residual error the most
- Always adds the basis function in "pairs", both sides of knot
- Calculate value for knot and function that fit the data, least squares.
- ► This is greedy algorithm.
- ► The addition of model terms continues until the max number of terms in the model is reached.

MARS Backwards Pass

- Remove one term at a time from the model
- Remove the term which increases the residual error the least
- Continue removing terms until cross validation is statisfied
- Use the Generalized Cross Validation (GCV) function for this purpose.

Reference

- Hastie, Tibshirani, and Friedman. The Elements of Statistical Learning (2nd ed.). Springer, 2009. http://www-stat.stanford.edu/~hastie/pub.htm.
- 2. Jerome H. Friedman. Multivariate Adaptive Regression Splines (with discussion). Annals of Statistics, 1991