

# Statistics 360: Advanced R for Data Science

## MARS, part II

Becky Lin

## Revisit: MARS model

- ▶ MARS model has the general form

$$f(x) = \beta_0 + \sum_{k=1}^M \beta_k h_k(x)$$

- ▶  $h_k(x)$  is a function from set  $C$  of candidate functions or a product of two or more such basis functions. Where

Hinge function:  $h(x) = \max(0, x)$

Also note that Note that  $h(x-t)$  and  $h(t-x)$  are mirror images.

$$C = \{(x_j - t)_+, (t - x_j)_+\}_{t \in \{x_{1j}, x_{2j}, \dots, x_{Nj}\}, j=1, 2, \dots, p.}$$

- ▶  $\beta$ s are the coefficients estimated by minimizing the residual sum of squares (standard linear regression).
- ▶ These coefficients can be consider weights that represent the importance of the variable.

## Revisit: MARS Model Building Procedure

1. Gather data:  $p$  input variables with  $n$  observations each, giving a total of  $np$  data points.
2. Calculate set of candidate functions by generating reflected pairs of basis functions with knots set at observed values.
3. Specify constraints; the number of terms in the model and maximum allowable degree of interaction.
4. **Do forward pass: try out new pair of basis function or function product and see which product decreases training error.**
5. Do backward pass: fix overfit.
6. Do generalized cross validation to estimate the optimal number of terms in the model.

## Recursive partitioning

- ▶ In the week 4 exercises we will implement the forward part of an algorithm called recursive partitioning.
- ▶ Friedman (1991) recasts recursive partitioning in terms of a forward stepwise regression procedure that selects products of mirror-image step functions  $I((x_v - t) \geq 0) = I(x_v \geq t)$  and  $I(-(x_v - t) \geq 0) = I(x_v \leq t)$ .
- ▶ Exercise: draw these two step functions to see why they are mirror image.
- ▶ Note: I think the first mirror-image step function should be  $I(x_v > t)$ , but will not make any changes to the discussion in the paper.

# Region splitting as a product of step functions

- ▶ Take the case of two covariates and a region  
 $R = [a_1, b_1] \times [a_2, b_2]$ .
- ▶ Claim:  $R$  is the set of points  $(x_1, x_2)$  such that the basis function

$$B_R(x) = I(x_1 \geq a_1) \times I(x_1 \leq b_1) \times I(x_2 \geq a_2) \times I(x_2 \leq b_2) > 0$$

- ▶ Splitting  $R$  on variable  $x_v$  at point  $t \in [a_v, b_v]$  means removing a “parent” basis function  $B_R(x)$  from the model and replacing it with two “children” basis functions  $B_R(x)I(x_v \leq t)$  and  $B_R(x)I(x_v \geq t)$ .

# Recursive partitioning forward algorithm (paper page 11)

## Algorithm 1 (recursive partitioning)

```
 $B_1(\mathbf{x}) \leftarrow 1$ 
For  $M = 2$  to  $M_{\max}$  do:  $\text{lof}^* \leftarrow \infty$ 
  For  $m = 1$  to  $M - 1$  do:
    For  $v = 1$  to  $n$  do:
      For  $t \in \{x_{vj} | B_m(\mathbf{x}_j) > 0\}$ 
         $g \leftarrow \sum_{i \neq m} a_i B_i(\mathbf{x}) + a_m B_m(\mathbf{x}) H[(x_v - t)] + a_M B_M(\mathbf{x}) H[-(x_v - t)]$ 
         $\text{lof} \leftarrow \min_{a_1, \dots, a_M} \text{LOF}(g)$ 
        if  $\text{lof} < \text{lof}^*$ , then  $\text{lof}^* \leftarrow \text{lof}$ ;  $m^* \leftarrow m$ ;  $v^* \leftarrow v$ ;  $t^* \leftarrow t$  end if
      end for
    end for
  end for
   $B_{M^*}(\mathbf{x}) \leftarrow B_{m^*}(\mathbf{x}) H[-(x_{v^*} - t^*)]$ 
   $B_{m^*}(\mathbf{x}) \leftarrow B_{m^*}(\mathbf{x}) H[(x_{v^*} - t^*)]$ 
end for
end algorithm
```

- ▶ Outer loop 1 over the number of model terms ( $M$ ), from 1 to a specified maximum number of basis functions.
- ▶ Outer loop 2 over parent basis functions to replace by splitting
- ▶ Inner loops to choose variables  $v$ , splits  $t$  in the region where  $B_R(x) > 0$ , and coefficients for  $B_R(x)I(x_v \leq t)$  and  $B_R(x)I(x_v \geq t)$  to minimize a LOF criterion. (This is like our recursive partitioning.)

## Week 6 lab (lab 4)

- ▶ Re-implement recursive partitioning with the forward stepwise regression algorithm outlined above.
- ▶ A more detailed breakdown of the tasks will follow.

# MARS generalization

- ▶ Replace the step functions with hinge functions  $h(t - x_v)$  and  $h(x_v - t)$ , where  $h(x) = \max(0, x)$ .
- ▶ Do not remove a parent basis function, just add pairs of children.
- ▶ Restrict the product that defines a basis function to distinct variables; i.e., no variable appears twice in the product.



## Revisit: MARS Forward Pass

- ▶ At each step, MARS adds the basis function which reduces the residual error the most
- ▶ Always adds the basis function in “pairs”, both sides of knot
- ▶ Calculate value for knot and function that fit the data, least squares.
- ▶ This is greedy algorithm.
- ▶ The addition of model terms continues until the max number of terms in the model is reached.

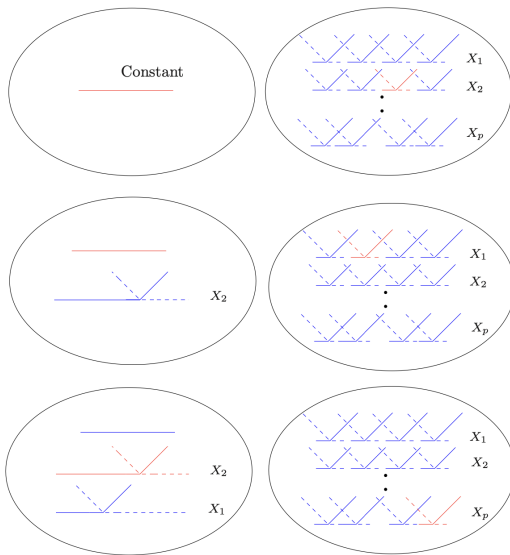


Figure 1: MARS forward pass (picture credit: ESL)

The first three steps in MARS forward model-building procedure.

# MARS forward algorithm (MARS paper page 17)

## Algorithm 2 (MARS—forward stepwise)

```
 $B_1(\mathbf{x}) \leftarrow 1; M \leftarrow 2$ 
Loop until  $M > M_{\max}$ :  $\text{lof}^* \leftarrow \infty$ 
  For  $m = 1$  to  $M - 1$  do:
    For  $v \notin \{v(k, m) | 1 \leq k \leq K_m\}$ 
      For  $t \in \{x_{vj} | B_m(\mathbf{x}_j) > 0\}$ 
         $g \leftarrow \sum_{i=1}^{M-1} a_i B_i(\mathbf{x}) + a_M B_m(\mathbf{x})[+(x_v - t)]_+ + a_{M+1} B_m(\mathbf{x})[-(x_v - t)]_+$ 
         $\text{lof} \leftarrow \min_{a_1, \dots, a_{M+1}} \text{LOF}(g)$ 
        if  $\text{lof} < \text{lof}^*$ , then  $\text{lof}^* \leftarrow \text{lof}$ ;  $m^* \leftarrow m$ ;  $v^* \leftarrow v$ ;  $t^* \leftarrow t$  end if
      end for
    end for
  end for
   $B_M(\mathbf{x}) \leftarrow B_{m^*}(\mathbf{x})[+(x_{v^*} - t^*)]_+$ 
   $B_{M+1}(\mathbf{x}) \leftarrow B_{m^*}(\mathbf{x})[-(x_{v^*} - t^*)]_+$ 
   $M \leftarrow M + 2$ 
end loop
end algorithm
```

Figure 2: Algorithm 2-MARS forward

- ▶ Outer loop 1 over the number of model terms,  $M$ , from 1 to some maximum number
  - ▶ Outer loop 2 over parent basis functions  $B_m$  to generate children
    - ▶ Inner loops over variables  $v$  not part of  $B_m$ , splits  $t$  such that  $B_m$  is positive for  $x_v = t$  and coefficients for the child basis functions to minimize a LOF criterion.