Department of Computer Engineering

T.E. (Computer Sem VI) Assignment -1 Artificial Intelligence (CSC604)			
Student Name:	Becky Nadar	Roll No:	9626
CO Addressed:-CSC intelligent systems.	604.1 -To conceptua	llize the basic ic	leas and techniques underlying the design of

Assignment 1:

- 1. Explain the concept of rationality in the context of intelligent agents. How does rationality relate to the behavior of agents in their environments? Provide examples to illustrate your explanation.
- 2. Discuss the nature of environments in which intelligent agents operate. What are the key characteristics that define an environment, and how do they influence the design and behavior of agents? Provide examples of different types of environments and the challenges they present to agents.
- 3. Describe the structure of intelligent agents and the types of agents commonly used in artificial intelligence. What are the components of an agent, and how do they interact to achieve intelligent behavior? Provide examples of different types of agents and their applications in real-world scenarios.
- 4. Outline the process of problem-solving by searching, including the role of problem-solving agents and the formulation of problems. How do problem-solving agents analyze and approach problems, and what methods do they use to search for solutions? Illustrate your explanation with examples of problem-solving tasks and the strategies employed by agents to solve them.

Rubrics for the First Assignments:

Indicator	Average	Good	Excellent	Marks
Organization (2)	Readable with some missing points and structured (1)	Readable with improved points coverage and structured (1)	Very well written and fully structured	
Level of content(4)	All major topics are covered, the information is accurate (2)	Most major and some minor criteria are included. Information is accurate (3)	All major and minor criteria are covered and are accurate (4)	
Depth and breadth of discussion and representation(4)	Minor points/information maybe missing and representation isminimal (1)	Discussion focused on some points and covers themadequately (2)	Information is presented indepth and is accurate (4)	
Total				

Signature of the Teacher

Assignment - 1 011 Explain the concept of rutionality in the context of intelligent agents How does rationality relate to the behaviour of agents in their environment Provide example to illustrate your explanation. -> Rationality: The State of being reasonable, sensible and having a sound sense of judgement is known as rationality. Rationality is concerned with the predicted behaviours and outcomes based on the agents pencephons. An essential aspect of rationality is taking activities invending to collect valuable knowledge Rationality at any given time depends on four things The performance measure that defines the criterion of sucess . The agent's prior Isnowledge of the environment The actions that the agent can perform The agent's percept sequence to date Rational Agent: For each possible percept sequence, a rational agent Should select on action that is expected to maximize its performance measure, given the evidence provided by the percept sequence and whatever buit-in Isnowledge the agent has The behaviour of rational agents is guided by the principle of achieving the best outcome or maximizing expected utility. It involves malsing decisions based on reasonsing, logical inference, and learning from experience . Key componients and the relationships between rationality and the behaviour of agents in their environments - Goals and objectives -> Information and Penception -> Decision - Malsing

-> Ada ptation and learning

-> Consistency and coherence

Expected utility FOR EDUCATIONAL USE

Trade-offs and constraints. FOR EDUCATIONAL USE

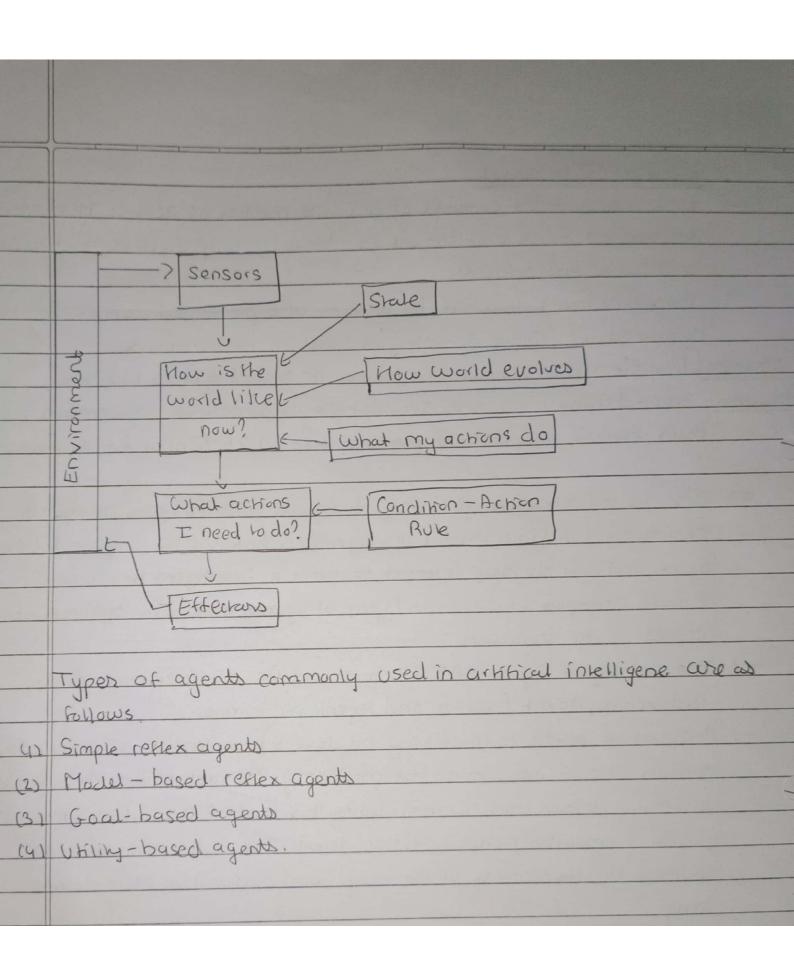
23	Simple vaccoum-cleaner agent that moves to the other Square if not, Be the performance measure is, what is what sensors and actuators the agent	there we need	to say mad what
		B	
	A		
		2 0	
	Fig: A vaccum - cleaner	o o	thua lacabine
	Percept Sequence	Achien	
	[A, Clean]	Right	
	TA, Dirty]	Suck	
	[B, clean]	Left	
	[B, Dirty]	Suck	
	[A, Clean], [A, Clean]	Right	
	D, Clean J, [A, Dicty]	Such	
	, , , , , , ,	Right	
	[A clean], [A clean], [A, clean]	4	
	TA, clean], [A, clean], [A, Diry]	Sucre	
		The second second	A second

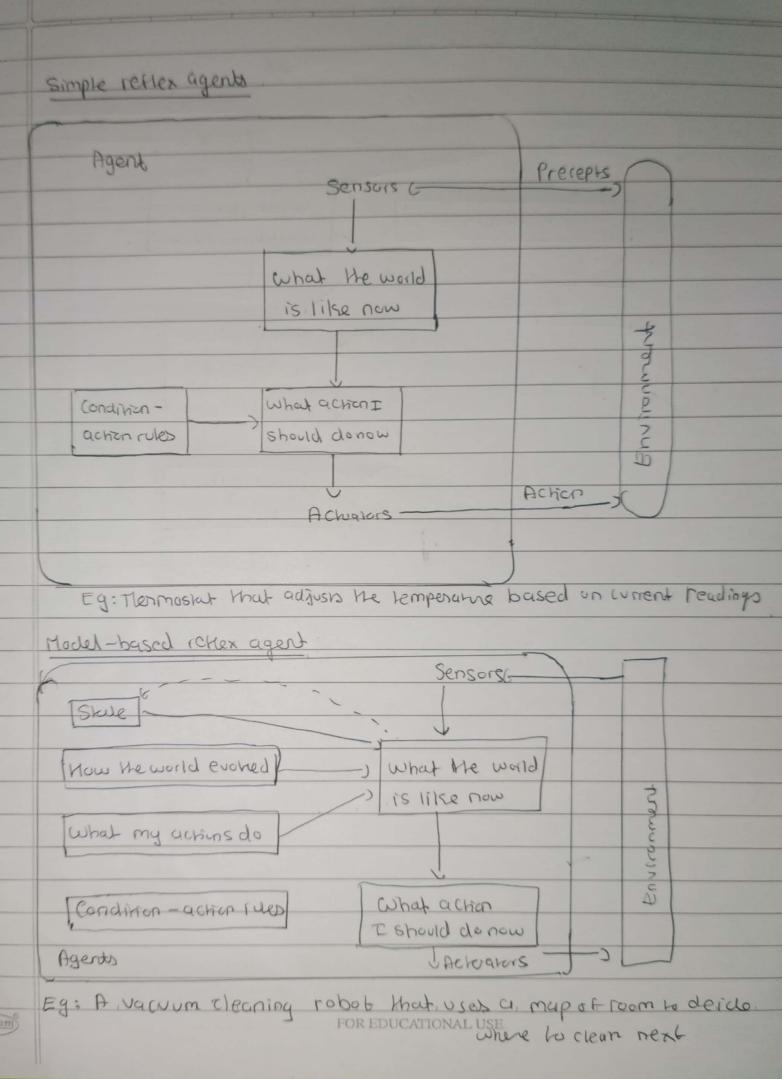
621	Discuss the nature of environments in which intelligent agents operate.
	What are the key characteris that define an environment, and how
	do Hey influence the design and behavior of agents? Provide examples
	of different types of environments and the challenges they piesent to agents?
->	An environment in AI is the surrounding of the agent. The agent takes
W. VIII.	input from the environment through sensors and delivers the output
	to the environment through actuators. There are several types of
	environment.
13	Full observable vs Partially observable.
	When an agent is capable to sense or acress the complete stute of an
	agent at each point in time, it is said to be a fully absertable environment
-3	when the agent how limited or incomplete information about the
	current state
Examp	ie: these - the board is folly observable, and so are the opponent's moves
	Driving - The environment is partially observable because what is
	around the comes is not known.
	Deterministic Vs Stochastic
-)	When a uniqueness in the agent's current state completely determines
	the next state of the agent, the environment is said to be "deterministic"
-3	the "stochashz environment" is random in nature which is not
	unique and cannot be completely determined by the agent.
Example	e: - Chess - There would be only a few possible moves from a coin at the
	correct state and these moves can be determined.
	Self-Driving Cars - The actions of a Self-driving car are not unique,
	it varies hime to hime.
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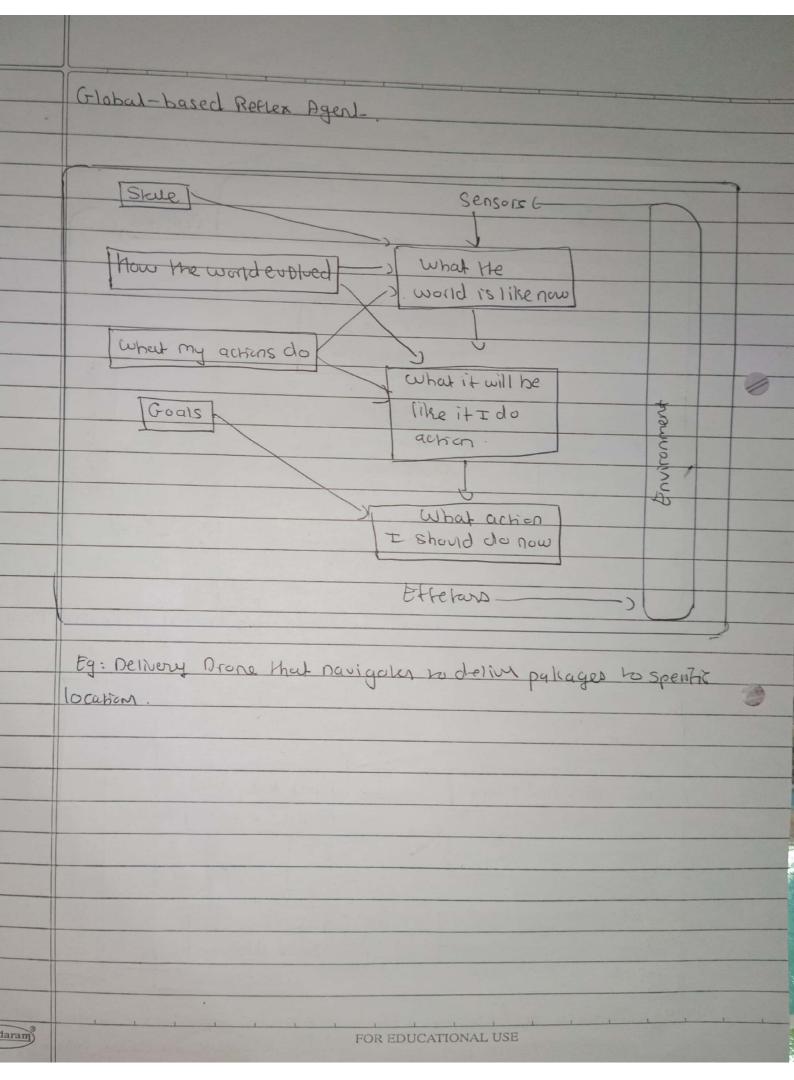
31	Competitive VS Collaborative
	An agent is said to be in a "comparitive environment" when it
	completes against another agent to ophimize the output
->	An agent is said to be in a "collaborative en vironment" when
	multiple agents cooperate to produce the desired output.
Examp	le : Financial markets, where traders compelete to maximize profits
	potentially at the expense of others.
Example	: Team-hased projects in business, where members collaborate to
	achieve project objectives.
41	Single-Agent VS Multi-Agent.
-5	An environment consisting of only one agent is said to be usingle agent
	environment
-)	An environment involving more than one agent is a multi-agent
	Environment.
Examp	e: A person left alone in a maze is an example of the "single-agent"
	System.
Examp	le. The game of football is multi-agent as it minualves " players
	in each ream.
	Sharp Us Dynamic
->	An idle environment with no change in its skule is called a skutic
=3	An environment that keeps constantly changing itself when He agent
3	is up with Some action is said to be dynamic.
tix ampa	An empty house is skurk as More's no change in the surrounding when
Evalute	an agent eners
Example	A coller coaster ride is dynamic as it is set in motion and the
Draining	environment keeps changing every instant.
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6	Discrete vs Continous.
	typ an environment consists of a finite number of actions that can be
	deliberated in the environment to obtain the output, it is said to be
	the environment in which He actions was performed connot be
	The environment in which he generals as a portained
~i.	numbered i-e is not discrete, is said to be commons.
Exam	pre: Discrete grid worlds in robotics or board games like these
Examp	e. Self-driving cors are an example of continuus environment as
0	their actions are driving, parking, etc which cannot be numbered
03	Describe the Structure of intelligent agents and the types of agents
ر می	commonly used in artifical intelligence. What are the components of an
	agent, and how do they interact to achieve intelligent behaviour?
	agent, and now do read interact is actived their applications
	Provide examples of different types of agents and their applications
-)	in real-world scenarions. The tokelligent Agent (IA? Smuchure consists of three main parts:
	Architecture, Agent Function and Agent programme.
	Architecture refers to machinary or devices that consist of achieves and
-3	sensors. The 1A executes on this machinary. The tool allows the adjusting
	Sensors. The 1th executes of this traditional the control of chair affect detail
	of image derails and clarities. Using this tool we can obtain great derail
	or get a smooker picture with less detail. This is the main tool to
	increase the concontrast of the image and visualize more details of the
	îmage.
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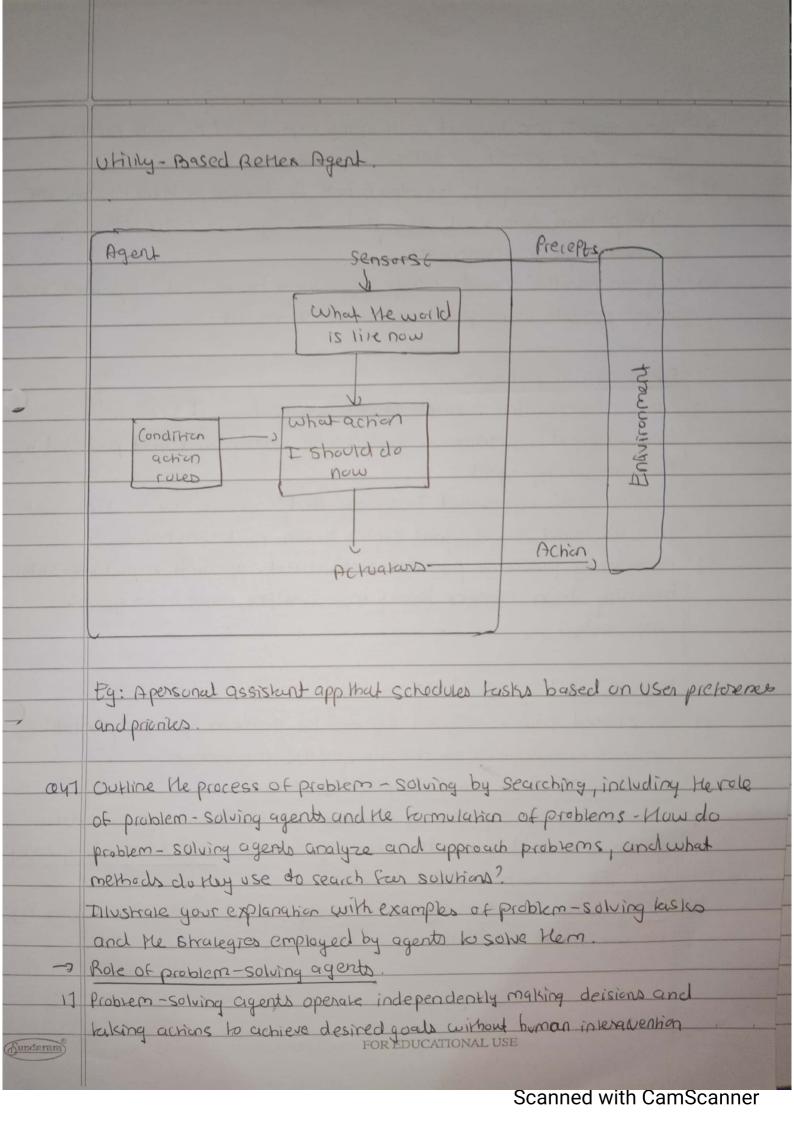
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23	These agents are designed to efficiently explore and navigate problem spaces to find ophmal or substactory solutions.
31	Roblem-Solving agents can adopt to changes in their environment or ptol problem domain adjusting their strategies to accompate new
	information or new constraints.
43	Simple puzzels to complex real-world scenarioss.
	Formulation of Problems
1]	Problem formulation involves abstracting real-world scenarious into a formula representation that can be understood and processed by
	Problem-Salving agents.
2]	Problems are represented in away that captures essential elements
	Such as initial States, goal States action and constraints.
31	Formularing Problems provided a shuckured approach to problem-solving, breaking down complex issues into smaller, more manageable
	Components.
	Methods used for searching solutions:
11	Uninformed search: Agents explain the problem space systematicaly
٦	without consideration of domain specific (moutedge.
	Eg: Breadth First search, depth-first search.
27	Informed search Agents use domain specific Ispowledge or heuristicus to
	guide He search bowards promising solutions Eq: At sparch, greedy
31	best - First Search Local search agents - Agents iteratively improve candidak Solution by
	maising small modifications.
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43	Examples: "
17	Routing Planning: - In novigation systems, problem-solving agents, search for the Shortest part between two locations and they analyze the road network consider traffic conditions and employ algorithms like As to find approval rough.
	Puzzle Solving: - In games like Sudokun or Rubik's rube agents aim to find Solviens satisfying (estain constraints they analyze the puzzels inited state explore possible moves and begave strategies like consent propagation or back tracking to solve the fuzzle Automated planning: - In rabetics or automated systems problem solving agents plan sequences of actions to action desired outcomes they analyze the environment consider (anstraints and employ planning algorithms like Post to generate action sequences