

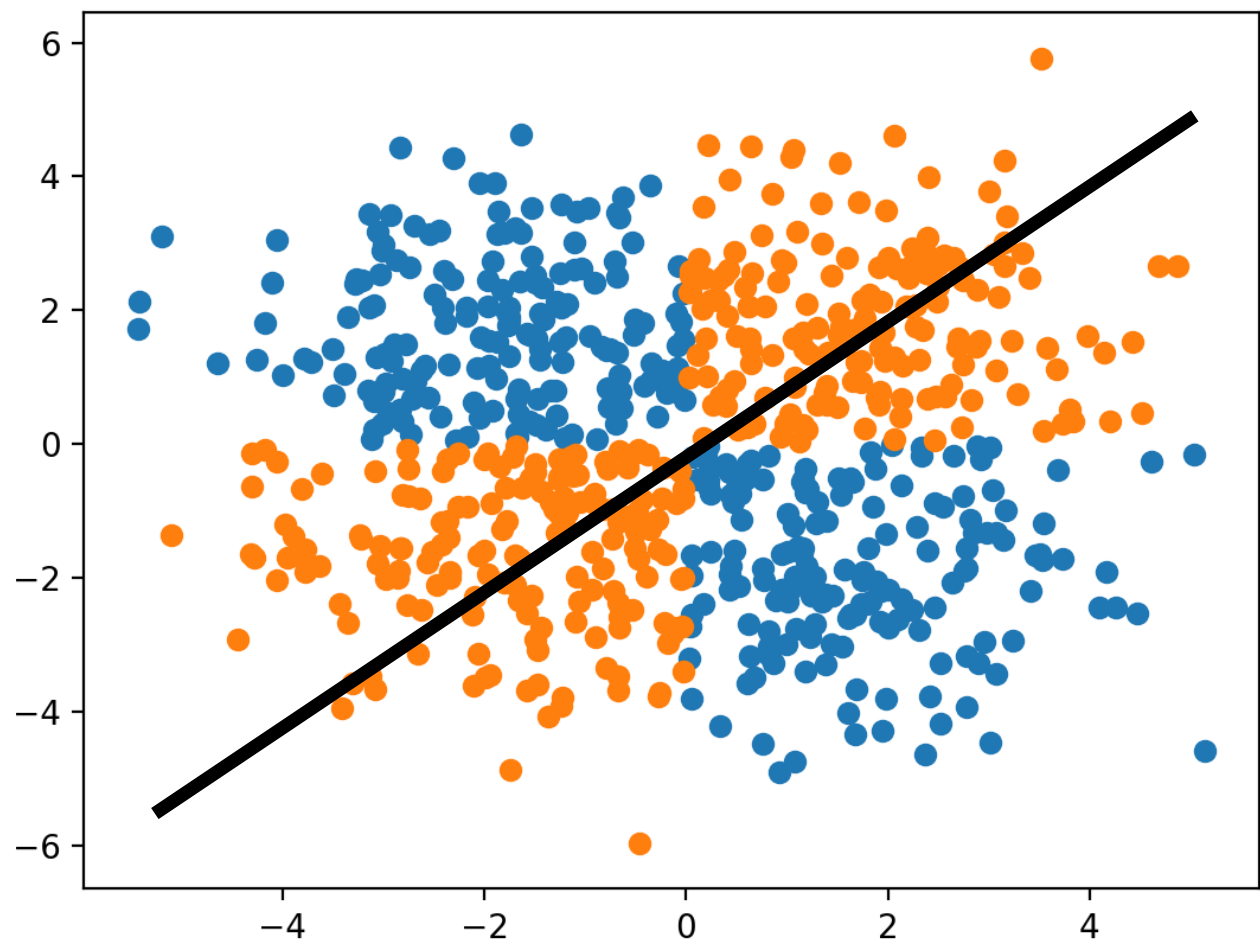
CS 4342: Class 15

Jacob Whitehill

Feature transformations

Linearly inseparable data

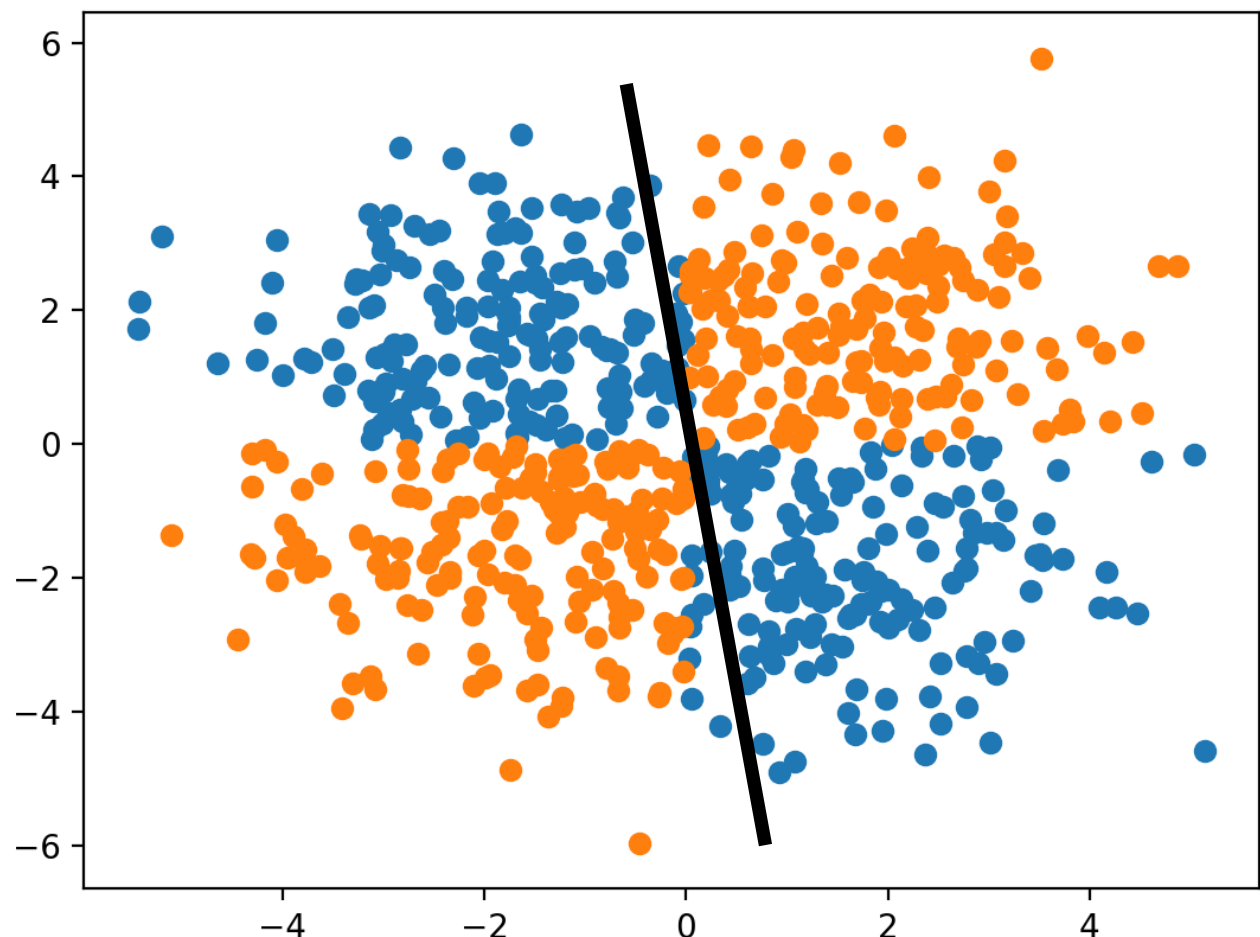
- SVMs use a hyperplane to separate data in two classes.
- But what if the data are **linearly inseparable**, e.g.:
- No matter what \mathbf{w} , b we choose, the SVM will never do a good job of classifying the data.



“XOR” problem

Linearly inseparable data

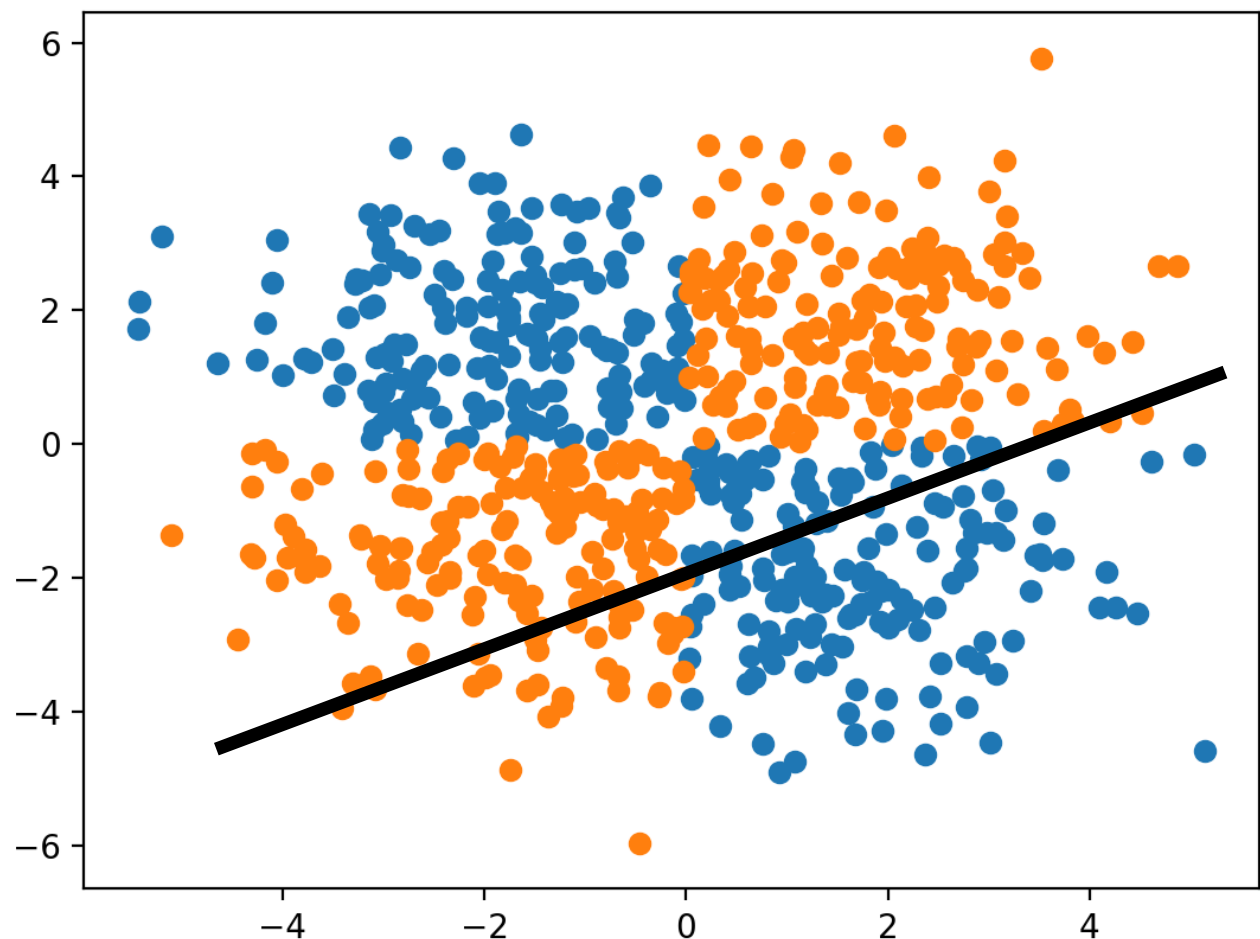
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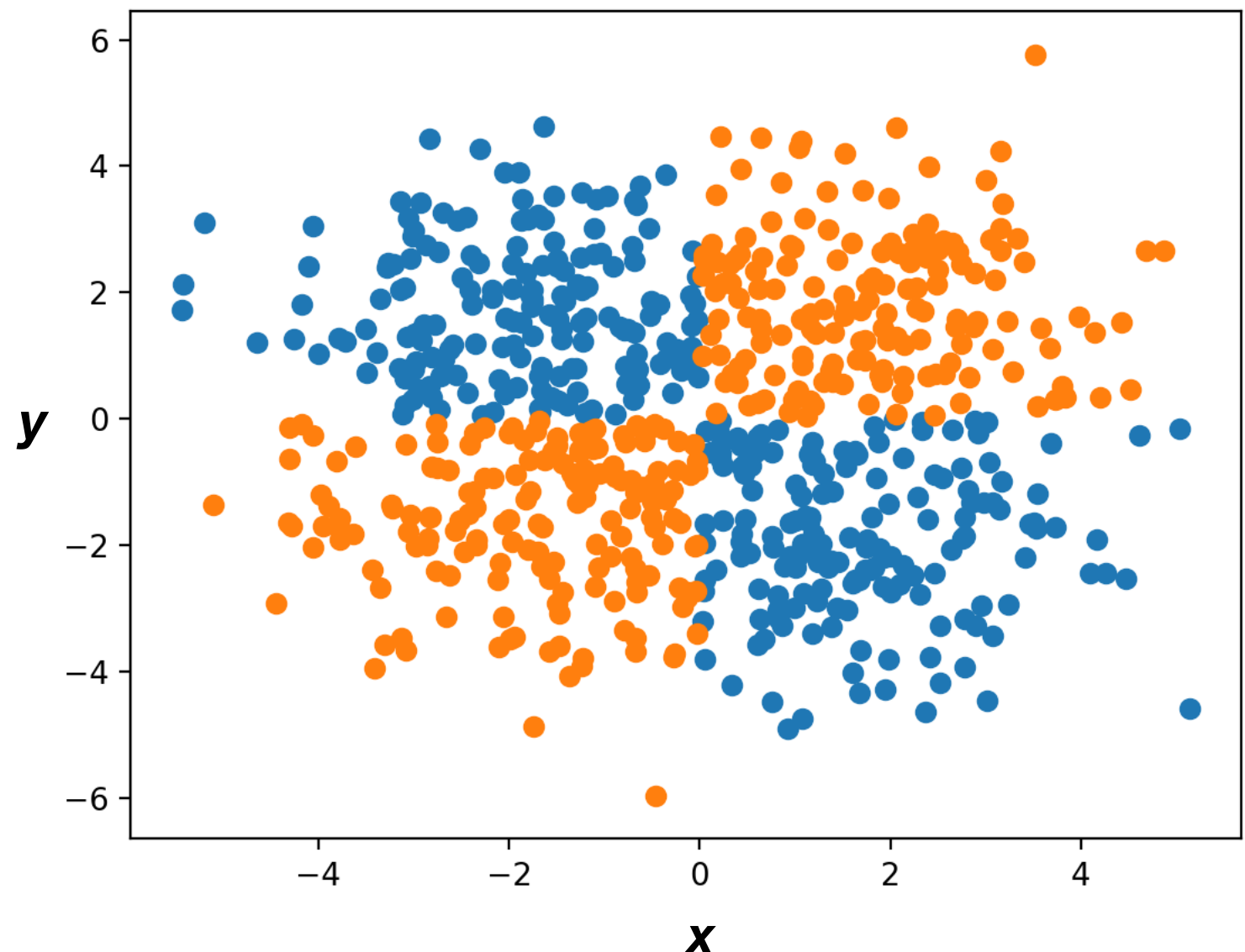


“XOR” problem

XOR problem

- We can use a non-linear transformation to make these data linearly separable, e.g.:

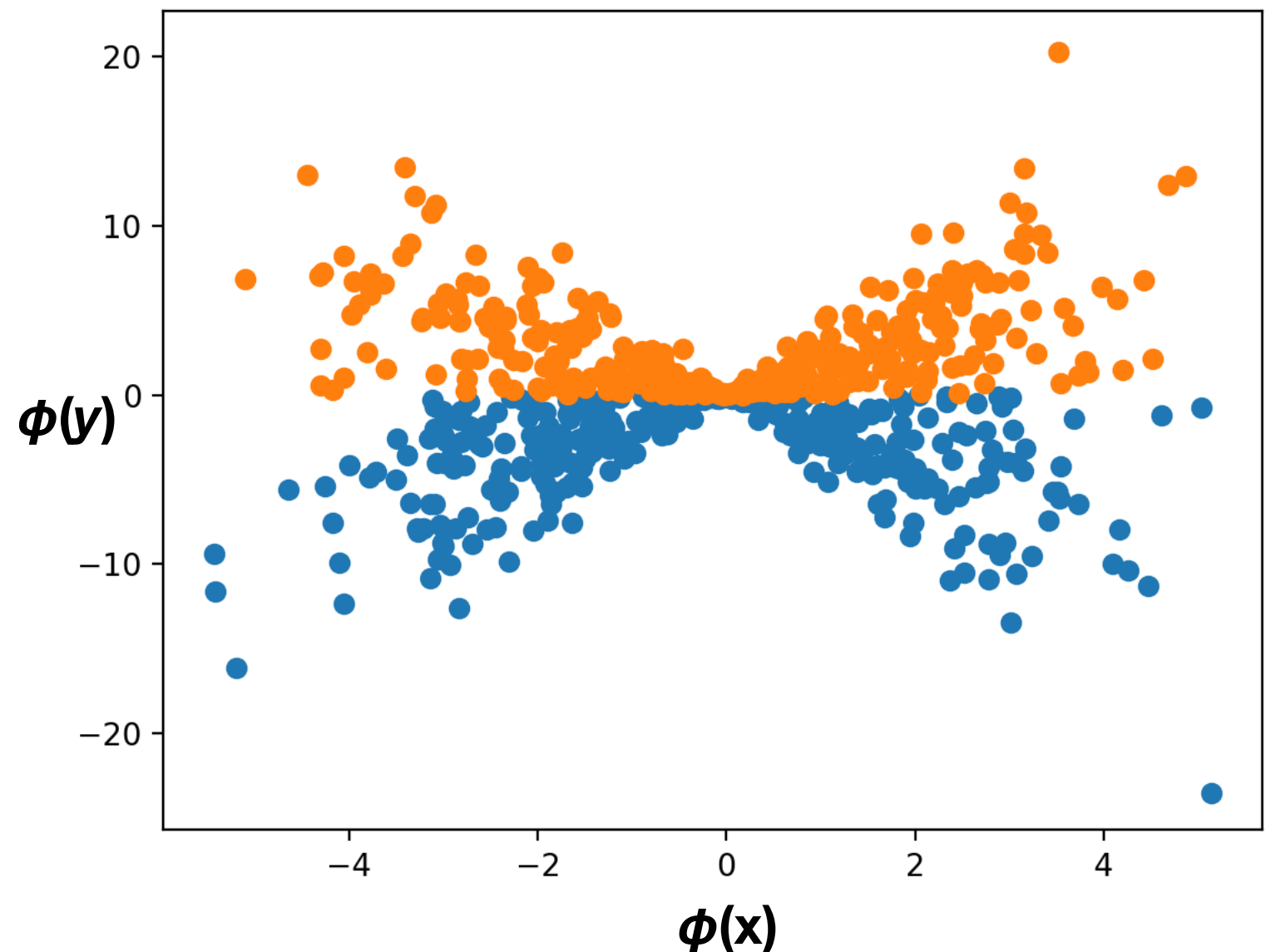
$$\phi(x, y) = \begin{bmatrix} x \\ xy \end{bmatrix}$$



XOR problem

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XOR problem

- There are many other transformations we could use. While not visualizable in 2-D, we could use:

$$\phi \left(\begin{bmatrix} x \\ y \end{bmatrix} \right) = \begin{bmatrix} 1 \\ \sqrt{2}x \\ \sqrt{2}y \\ \sqrt{2}xy \\ x^2 \\ y^2 \end{bmatrix}$$

**(6-dimensional
plot goes here)**

XOR problem

- It turns out that, through a process known as **kernelization** (more next week), these transformations ϕ can be computed **implicitly**.

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(6-dimensional
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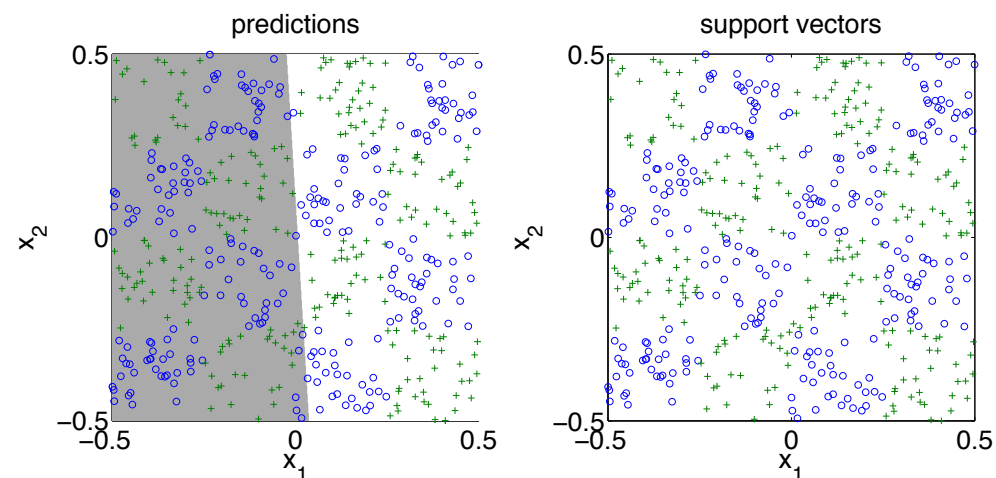
Equivalent to a polynomial
kernel of degree 2.

Kernelization

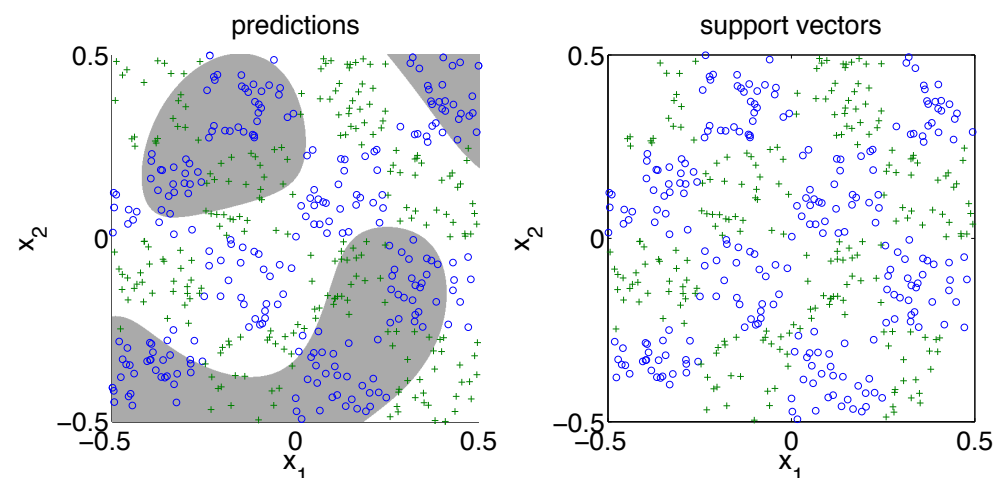
- SVMs **always** try to separate the positive from the negative examples using a **hyperplane** — a linear decision boundary.
- But the hyperplane might exist in a very different (transformed) space than the raw input data.
- In the original input space, the decision boundary can be non-linear.

Non-linear decision boundaries

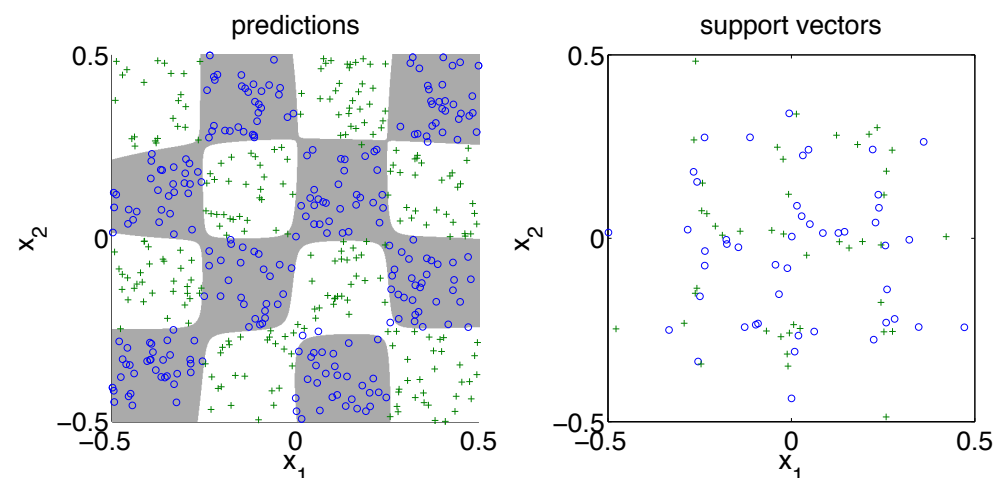
Dataset B, $c = 10^5$, $k(\mathbf{x}, \mathbf{v}) = 1 + \mathbf{x} \cdot \mathbf{v}$.



Dataset B, $c = 10^5$, $k(\mathbf{x}, \mathbf{v}) = (1 + \mathbf{x} \cdot \mathbf{v})^5$.

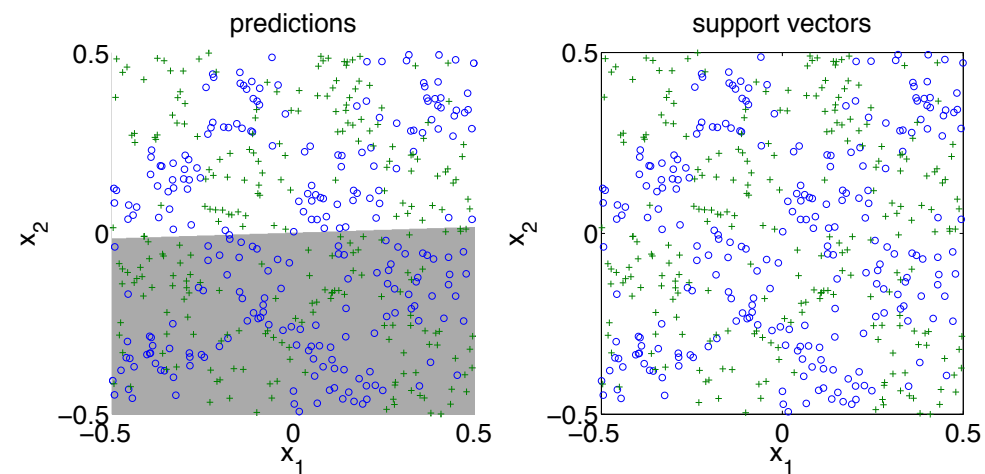


Dataset B, $c = 10^5$, $k(\mathbf{x}, \mathbf{v}) = (1 + \mathbf{x} \cdot \mathbf{v})^{10}$.

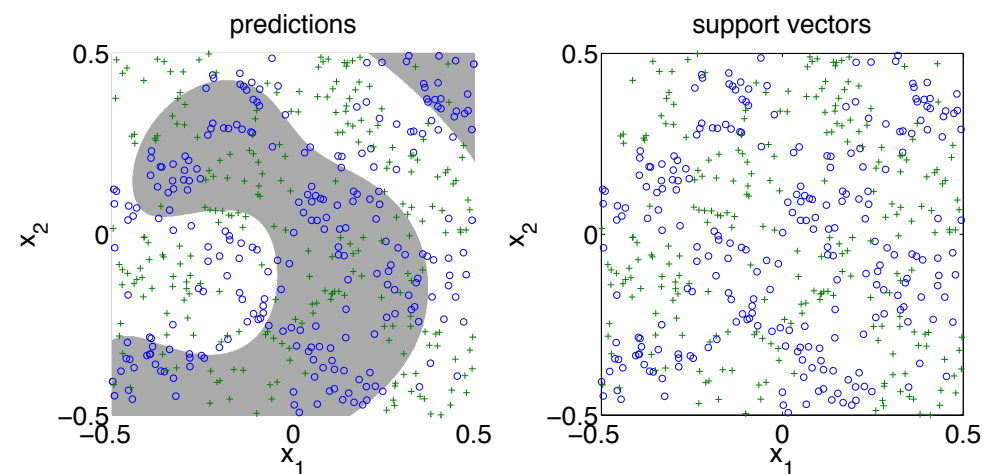


Non-linear decision boundaries

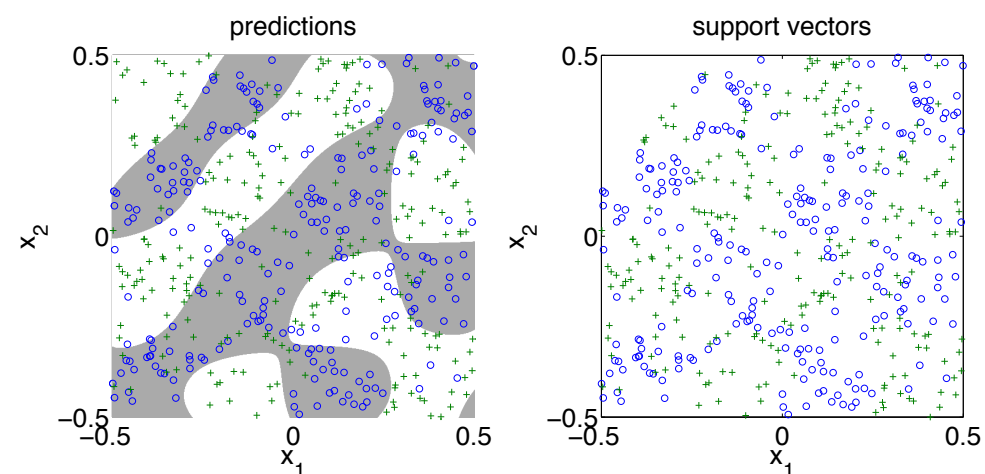
Dataset C (dataset B with noise), $c = 10^5$, $k(\mathbf{x}, \mathbf{v}) = 1 + \mathbf{x} \cdot \mathbf{v}$.



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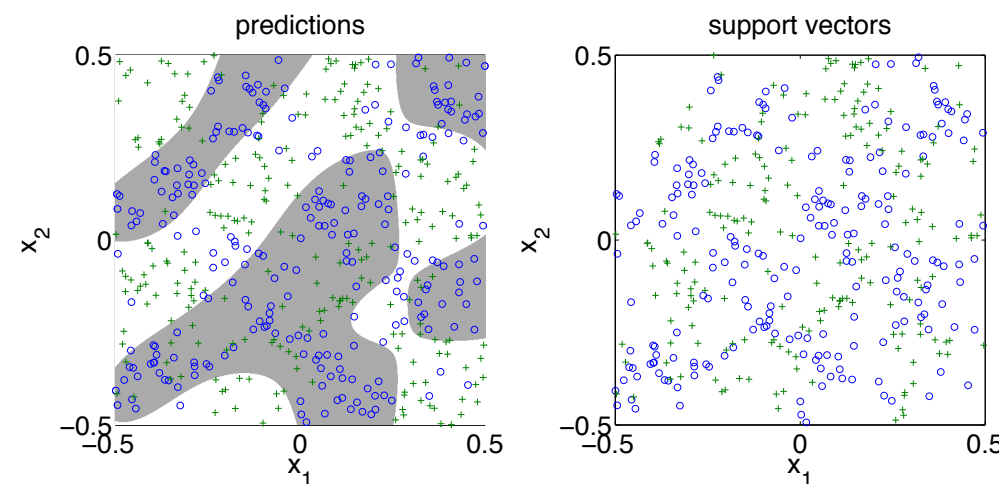


Dataset C, $c = 10^5$, $k(\mathbf{x}, \mathbf{v}) = (1 + \mathbf{x} \cdot \mathbf{v})^{10}$.

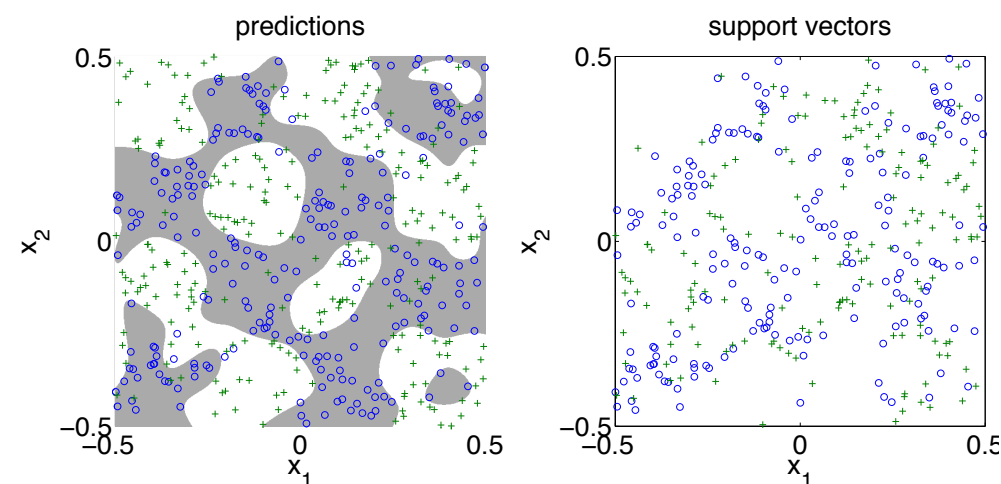


Non-linear decision boundaries

Dataset C (dataset B with noise), $c = 10^5$, $k(\mathbf{x}, \mathbf{v}) = \exp(-2\|\mathbf{x} - \mathbf{v}\|^2)$.



Dataset C, $c = 10^5$, $k(\mathbf{x}, \mathbf{v}) = \exp(-20\|\mathbf{x} - \mathbf{v}\|^2)$.



Dataset C, $c = 10^5$, $k(\mathbf{x}, \mathbf{v}) = \exp(-200\|\mathbf{x} - \mathbf{v}\|^2)$.

