CS 4342: Class 9

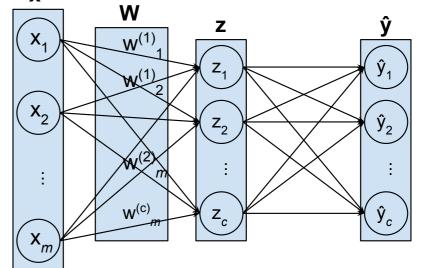
Jacob Whitehill

Softmax regression (aka multinomial logistic regression)

Softmax regression: vectorizaţion

• x: column vector, z: row vector

• Let
$$\mathbf{W} = \begin{bmatrix} & & & | & & \\ \mathbf{w}^{(1)} & \dots & \mathbf{w}^{(c)} & \\ | & & | & \end{bmatrix}$$



 We can compute the "pre-activation scores" z for all c classes in one-fell-swoop with the equation:

$$\mathbf{z} = \mathbf{x}^{\top} \mathbf{W}$$

Note: z is a row vector.

Softmax regression: vectorization

 By vectorizing, we can compute the pre-activation scores for all n examples in one-fell-swoop as:

$$\mathbf{Z} = \mathbf{X}^{\mathsf{T}} \mathbf{W}$$
 n x c matrix

Softmax regression: vectorization

 By vectorizing, we can compute the pre-activation scores for all n examples in one-fell-swoop as:

$$\mathbf{Z} = \mathbf{X}^{\top} \mathbf{W}$$
 n x c matrix

- With numpy, we can call np.exp to exponentiate every element of Z.
- We can then use np.sum and / (element-wise division) to compute the softmax.

- With softmax regression, we need to conduct gradient descent on all c of the weights vectors.
- As usual, let's just consider the gradient of the crossentropy loss for a single example x.
- We will compute the gradient w.r.t. each weight vector \mathbf{w}_k separately (where k = 1, ..., c).

Gradient for each weight vector w_k:

$$\nabla_{\mathbf{w}_k} f_{\text{CE}}(\mathbf{y}, \hat{\mathbf{y}}; \mathbf{W}) = \mathbf{x}(\hat{\mathbf{y}}_k - \mathbf{y}_k)$$

- This is the same expression (for each *k*) as for linear regression and logistic regression.
- We can vectorize this to compute all c gradients over all n examples...

Let Y and Ŷ both be n x c matrices:

$$\mathbf{Y} = egin{bmatrix} \mathbf{y}_1^{(1)} & \mathbf{y}_c^{(1)} \ \mathbf{y}_1^{(n)} & \cdots & \mathbf{y}_c^{(n)} \ \mathbf{y}_1^{(n)} & \cdots & \mathbf{y}_c^{(n)} \end{bmatrix}$$
 One-hot encoded vector of class labels for example 1.

Let Y and Ŷ both be n x c matrices:

$$\mathbf{Y} = egin{bmatrix} \mathbf{y}_1^{(1)} & \dots & \mathbf{y}_c^{(1)} \\ & dots \\ \mathbf{y}_1^{(n)} & \dots & \mathbf{y}_c^{(n)} \end{bmatrix}$$
 One-hot encoded vector of class labels for example n .

Let Y and Ŷ both be n x c matrices:

$$\mathbf{Y} = \left[egin{array}{cccc} \mathbf{y}_1^{(1)} & \dots & \mathbf{y}_c^{(1)} \\ & dots & & & \\ \mathbf{y}_1^{(n)} & \dots & \mathbf{y}_c^{(n)} \end{array}
ight] \qquad \hat{\mathbf{Y}} = \left[egin{array}{cccc} \hat{\mathbf{y}}_1^{(1)} & \dots & \hat{\mathbf{y}}_c^{(1)} \\ & dots & & & \\ \hat{\mathbf{y}}_1^{(n)} & \dots & \hat{\mathbf{y}}_c^{(n)} \end{array}
ight]$$

$$\hat{\mathbf{Y}} = \begin{bmatrix} \hat{\mathbf{y}}_1^{(1)} & \dots & \hat{\mathbf{y}}_c^{(1)} \\ \vdots & \vdots & \vdots \\ \hat{\mathbf{y}}_1^{(n)} & \dots & \hat{\mathbf{y}}_c^{(n)} \end{bmatrix}$$

The machine's estimates of the c class probabilities for example n.

• Let **Y** and $\hat{\mathbf{Y}}$ both be $n \times c$ matrices:

$$\mathbf{Y} = \left[egin{array}{cccc} \mathbf{y}_1^{(1)} & \dots & \mathbf{y}_c^{(1)} \\ & dots & & & \\ \mathbf{y}_1^{(n)} & \dots & \mathbf{y}_c^{(n)} \end{array}
ight] \qquad \hat{\mathbf{Y}} = \left[egin{array}{cccc} \hat{\mathbf{y}}_1^{(1)} & \dots & \hat{\mathbf{y}}_c^{(1)} \\ & dots & & & \\ \hat{\mathbf{y}}_1^{(n)} & \dots & \hat{\mathbf{y}}_c^{(n)} \end{array}
ight]$$

Then we can compute all c gradient vectors as:

$$\nabla_{\mathbf{W}} f_{\text{CE}}(\mathbf{Y}, \hat{\mathbf{Y}}; \mathbf{W}) = \frac{1}{n} \mathbf{X} (\hat{\mathbf{Y}} - \mathbf{Y})$$

• Let **Y** and $\hat{\mathbf{Y}}$ both be $n \times c$ matrices:

$$\mathbf{Y} = \left[egin{array}{cccc} \mathbf{y}_1^{(1)} & \dots & \mathbf{y}_c^{(1)} \\ & dots & & & \\ \mathbf{y}_1^{(n)} & \dots & \mathbf{y}_c^{(n)} \end{array}
ight] \qquad \hat{\mathbf{Y}} = \left[egin{array}{cccc} \hat{\mathbf{y}}_1^{(1)} & \dots & \hat{\mathbf{y}}_c^{(1)} \\ & dots & & & \\ \hat{\mathbf{y}}_1^{(n)} & \dots & \hat{\mathbf{y}}_c^{(n)} \end{array}
ight]$$

• Then we can compute all c gradient vectors as:

$$\nabla_{\mathbf{W}} f_{\text{CE}}(\mathbf{Y}, \hat{\mathbf{Y}}; \mathbf{W}) = \frac{1}{n} \mathbf{X} (\hat{\mathbf{Y}} - \mathbf{Y})$$

How far the guesses are from ground-truth.

• Let **Y** and $\hat{\mathbf{Y}}$ both be $n \times c$ matrices:

$$\mathbf{Y} = \left[egin{array}{cccc} \mathbf{y}_1^{(1)} & \dots & \mathbf{y}_c^{(1)} \\ & draversize & & & \\ \mathbf{y}_1^{(n)} & \dots & \mathbf{y}_c^{(n)} \end{array}
ight] \qquad \hat{\mathbf{Y}} = \left[egin{array}{cccc} \hat{\mathbf{y}}_1^{(1)} & \dots & \hat{\mathbf{y}}_c^{(1)} \\ & draversize & & & \\ \hat{\mathbf{y}}_1^{(n)} & \dots & \hat{\mathbf{y}}_c^{(n)} \end{array}
ight]$$

• Then we can compute all c gradient vectors as:

$$\nabla_{\mathbf{W}} f_{\text{CE}}(\mathbf{Y}, \hat{\mathbf{Y}}; \mathbf{W}) = \frac{1}{n} \mathbf{X} (\hat{\mathbf{Y}} - \mathbf{Y})$$

The input features (e.g., pixel values).

Softmax regression demo

- Let's apply softmax regression to train a handwriting recognition system that can recognize all 10 digits (0-9).
- We will use the popular MNIST dataset consisting of 60K training examples and 10K testing examples:

```
0123456789
0123456789
0123456789
0123456789
0123456789
```

Stochastic gradient descent (SGD)

Gradient descent

- With gradient descent, we only update the weights after scanning the entire training set.
 - This is slow.
- If the training set contains 60K examples (like in MNIST), then the gradient is an *average* over 60K images.
 - How much would the gradient really change if we just used, say, 30K images? 15K images? 128 images?

$$\nabla_{\mathbf{W}} f_{\text{CE}}(\mathbf{Y}, \hat{\mathbf{Y}}; \mathbf{W}) = \frac{1}{n} \mathbf{X} (\hat{\mathbf{Y}} - \mathbf{Y})$$

Average over entire training set.

- This is the idea behind stochastic gradient descent (SGD):
 - Randomly sample a small (≪ n) mini-batch (or sometimes just batch) of training examples.
 - Estimate the gradient on just the mini-batch.
 - Update weights based on *mini-batch* gradient estimate.
 - Repeat.

- In practice, SGD is usually conducted over multiple epochs.
 - An epoch is a single pass through the entire training set.
- Procedure:
 - 1. Let $\tilde{n} \ll n$ equal the size of the mini-batch.

- In practice, SGD is usually conducted over multiple epochs.
 - An epoch is a single pass through the entire training set.
- Procedure:
 - 1. Let $\tilde{n} \ll n$ equal the size of the mini-batch.
 - 2. Randomize the order of the examples in the training set.

- In practice, SGD is usually conducted over multiple epochs.
 - An epoch is a single pass through the entire training set.
- Procedure:
 - 1. Let $\tilde{n} \ll n$ equal the size of the mini-batch.
 - 2. Randomize the order of the examples in the training set.
 - 3. For e = 0 to numEpochs:

- In practice, SGD is usually conducted over multiple epochs.
 - An epoch is a single pass through the entire training set.
- Procedure:
 - 1. Let $\tilde{n} \ll n$ equal the size of the mini-batch.
 - 2. Randomize the order of the examples in the training set.
 - 3. For e = 0 to numEpochs:
 - I. For i = 0 to $(\lceil n/\tilde{n} \rceil 1)$ (one epoch):

- In practice, SGD is usually conducted over multiple epochs.
 - An epoch is a single pass through the entire training set.
- Procedure:
 - 1. Let $\tilde{n} \ll n$ equal the size of the mini-batch.
 - 2. Randomize the order of the examples in the training set.
 - 3. For e = 0 to numEpochs:
 - I. For i = 0 to $(\lceil n/\tilde{n} \rceil 1)$ (one epoch):
 - A. Select a mini-batch \mathcal{J} containing the next \tilde{n} examples.

- In practice, SGD is usually conducted over multiple epochs.
 - An epoch is a single pass through the entire training set.
- Procedure:
 - 1. Let $\tilde{n} \ll n$ equal the size of the mini-batch.
 - 2. Randomize the order of the examples in the training set.
 - 3. For e = 0 to numEpochs:
 - I. For i = 0 to $(\lceil n/\tilde{n} \rceil 1)$ (one epoch):
 - A. Select a mini-batch \mathcal{J} containing the next \tilde{n} examples.
 - B. Compute the gradient on this mini-batch: $\frac{1}{\tilde{n}}\sum_{i\in\mathcal{I}}\nabla\mathbf{w}f(\mathbf{y}^{(i)},\hat{\mathbf{y}}^{(i)};\mathbf{W})$

- In practice, SGD is usually conducted over multiple epochs.
 - An epoch is a single pass through the entire training set.
- Procedure:
 - 1. Let $\tilde{n} \ll n$ equal the size of the mini-batch.
 - 2. Randomize the order of the examples in the training set.
 - 3. For e = 0 to numEpochs:
 - I. For i = 0 to $(\lceil n/\tilde{n} \rceil 1)$ (one epoch):
 - A. Select a mini-batch \mathcal{J} containing the next \tilde{n} examples.
 - B. Compute the gradient on this mini-batch: $\frac{1}{\tilde{n}} \sum_{i \in \mathcal{I}} \nabla_{\mathbf{W}} f(\mathbf{y}^{(i)}, \hat{\mathbf{y}}^{(i)}; \mathbf{W})$
 - C. Update the weights based on the current mini-batch gradient.

- Suppose our training set contains n=8 examples.
- Here is how regular gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.

1
2
3
4
5
6
7
8

- Suppose our training set contains n=8 examples.
- Here is how regular gradient descent would proceed:
 - Initialize weights **w**⁽⁰⁾ to random values.
 - For each round:
 - Compute gradient on all n examples.

examples
1
2
3
4
5
6
7
8

Training

- Suppose our training set contains n=8 examples.
- Here is how regular gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.
 - For each round:
 - Compute gradient on all n examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \boldsymbol{\varepsilon} \nabla_{\mathbf{w}} f$

1	
2	
3	
4	
5	
6	
7	
8	

- Suppose our training set contains n=8 examples.
- Here is how regular gradient descent would proceed:
 - Initialize weights **w**⁽⁰⁾ to random values.
 - For each round:
 - Compute gradient on all n examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \epsilon \nabla_{\mathbf{w}} f$

examples
1
2
3
4
5
6
7
8

Training

- Suppose our training set contains n=8 examples.
- Here is how regular gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.
 - For each round:
 - Compute gradient on all n examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \boldsymbol{\varepsilon} \nabla_{\mathbf{w}} f$

1	
2	
3	
4	
5	
6	
7	
8	

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.

1
2
3
4
5
6
7
8

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.
 - Randomize the order of the training data.

4
1
3
5
7
6
8
2

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.
 - Randomize the order of the training data.
 - For each epoch (e=1, ..., *E*): e=1
 - For each round ($r=1, ..., \lceil n/\tilde{n} \rceil$):
 - Compute gradient on next \tilde{n} examples.

4
1
3
5
7
6
8
2

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.
 - Randomize the order of the training data.
 - For each epoch (e=1, ..., *E*): e=1
 - For each round ($r=1, ..., \lceil n/\tilde{n} \rceil$):
 - Compute gradient on next \tilde{n} examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \boldsymbol{\epsilon} \widetilde{\nabla}_{\mathbf{w}} f$

4
1
3
5
7
6
8
2

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.
 - Randomize the order of the training data.
 - For each epoch (e=1, ..., *E*): e=1
 - For each round ($r=1, ..., \lceil n/\tilde{n} \rceil$):
 - Compute gradient on next \tilde{n} examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \epsilon \widetilde{\nabla}_{\mathbf{w}} f$

4
1
3
5
7
6
8
2

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.
 - Randomize the order of the training data.
 - For each epoch (e=1, ..., *E*): e=1
 - For each round ($r=1, ..., \lceil n/\tilde{n} \rceil$):
 - Compute gradient on next \tilde{n} examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \boldsymbol{\varepsilon} \widetilde{\nabla}_{\mathbf{w}} f$

4
1
3
5
7
6
8
2

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.
 - Randomize the order of the training data.
 - For each epoch (e=1, ..., *E*): e=1
 - For each round ($r=1, ..., \lceil n/\tilde{n} \rceil$):
 - Compute gradient on next \tilde{n} examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \epsilon \widetilde{\nabla}_{\mathbf{w}} f$

4
1
3
5
7
6
8
2

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights **w**⁽⁰⁾ to random values.
 - Randomize the order of the training data.
 - For each epoch (e=1, ..., E): e=1
 - For each round ($r=1, ..., \lceil n/\tilde{n} \rceil$):
 - Compute gradient on next \tilde{n} examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \boldsymbol{\varepsilon} \widetilde{\nabla}_{\mathbf{w}} f$

4
1
3
5
7
6
8
2

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights **w**⁽⁰⁾ to random values.
 - Randomize the order of the training data.
 - For each epoch (e=1, ..., *E*): e=1
 - For each round ($r=1, ..., \lceil n/\tilde{n} \rceil$):
 - Compute gradient on next \tilde{n} examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \epsilon \widetilde{\nabla}_{\mathbf{w}} f$

4
1
3
5
7
6
8
2

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights w⁽⁰⁾ to random values.
 - Randomize the order of the training data.
 - For each epoch (e=1, ..., *E*): e=1
 - For each round ($r=1, ..., \lceil n/\tilde{n} \rceil$):
 - Compute gradient on next \tilde{n} examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \boldsymbol{\varepsilon} \widetilde{\nabla}_{\mathbf{w}} f$

4
1
3
5
7
6
8
2

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights **w**⁽⁰⁾ to random values.
 - Randomize the order of the training data.
 - For each epoch (e=1, ..., *E*): e=2
 - For each round ($r=1, ..., \lceil n/\tilde{n} \rceil$):
 - Compute gradient on next \tilde{n} examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \epsilon \widetilde{\nabla}_{\mathbf{w}} f$

4	
1	
3	
5	
7	
6	
8	
2	

- Suppose our training set contains n=8 examples with $\tilde{n}=2$.
- Here is how stochastic gradient descent would proceed:
 - Initialize weights **w**⁽⁰⁾ to random values.
 - Randomize the order of the training data.
 - For each epoch (e=1, ..., E): e=2
 - For each round ($r=1, ..., \lceil n/\tilde{n} \rceil$):
 - Compute gradient on next \tilde{n} examples.
 - Update weights: $\mathbf{w}^{(t+1)} \longleftarrow \mathbf{w}^{(t)} \epsilon \widetilde{\nabla}_{\mathbf{w}} f$

Training examples

4
1
3
5
7
6
8
2

. . .

Stochastic gradient descent

- Despite "noise" (statistical inaccuracy) in the mini-batch gradient estimates, we will still converge to local minimum.
- Training can be much faster than regular gradient descent because we adjust the weights many times per epoch.

$$\hat{\mathbf{y}}_1 = \frac{\exp \mathbf{z}_1}{\sum_{k'=1}^2 \exp \mathbf{z}_{k'}}$$

$$\hat{\mathbf{y}}_1 = \frac{\exp \mathbf{z}_1}{\sum_{k'=1}^2 \exp \mathbf{z}_{k'}}$$

$$= \frac{\exp \mathbf{z}_1}{\exp \mathbf{z}_1 + \exp \mathbf{z}_2}$$

$$\hat{\mathbf{y}}_1 = \frac{\exp \mathbf{z}_1}{\sum_{k'=1}^2 \exp \mathbf{z}_{k'}}$$

$$= \frac{\exp \mathbf{z}_1}{\exp \mathbf{z}_1 + \exp \mathbf{z}_2}$$

$$= \frac{1}{1 + \exp \mathbf{z}_2 / \exp \mathbf{z}_1}$$

$$\hat{\mathbf{y}}_{1} = \frac{\exp \mathbf{z}_{1}}{\sum_{k'=1}^{2} \exp \mathbf{z}_{k'}}$$

$$= \frac{\exp \mathbf{z}_{1}}{\exp \mathbf{z}_{1} + \exp \mathbf{z}_{2}}$$

$$= \frac{1}{1 + \exp \mathbf{z}_{2} / \exp \mathbf{z}_{1}}$$

$$= \frac{1}{1 + \exp (\mathbf{z}_{2} - \mathbf{z}_{1})}$$

$$\hat{\mathbf{y}}_{1} = \frac{\exp \mathbf{z}_{1}}{\sum_{k'=1}^{2} \exp \mathbf{z}_{k'}}$$

$$= \frac{\exp \mathbf{z}_{1}}{\exp \mathbf{z}_{1} + \exp \mathbf{z}_{2}}$$

$$= \frac{1}{1 + \exp \mathbf{z}_{2} / \exp \mathbf{z}_{1}}$$

$$= \frac{1}{1 + \exp (\mathbf{z}_{2} - \mathbf{z}_{1})}$$

$$= \frac{1}{1 + \exp (-z)}$$

$$\hat{\mathbf{y}}_{1} = \frac{\exp \mathbf{z}_{1}}{\sum_{k'=1}^{2} \exp \mathbf{z}_{k'}}$$

$$= \frac{\exp \mathbf{z}_{1}}{\exp \mathbf{z}_{1} + \exp \mathbf{z}_{2}}$$

$$= \frac{1}{1 + \exp \mathbf{z}_{2} / \exp \mathbf{z}_{1}}$$

$$= \frac{1}{1 + \exp (\mathbf{z}_{2} - \mathbf{z}_{1})}$$

$$= \frac{1}{1 + \exp (-z)}$$

$$= \frac{1}{1 + \exp (-x^{\top} \mathbf{w})}$$

Suppose c=2. Then even though there are two weight vectors w⁽¹⁾, w⁽²⁾ in softmax regression, they are equivalent to just a single weight vector w:

$$\hat{\mathbf{y}}_{1} = \frac{\exp \mathbf{z}_{1}}{\sum_{k'=1}^{2} \exp \mathbf{z}_{k'}}$$

$$= \frac{\exp \mathbf{z}_{1}}{\exp \mathbf{z}_{1} + \exp \mathbf{z}_{2}}$$

$$= \frac{1}{1 + \exp \mathbf{z}_{2} / \exp \mathbf{z}_{1}}$$

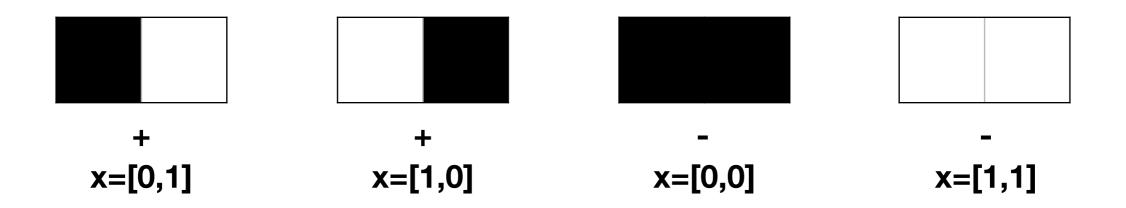
$$= \frac{1}{1 + \exp (\mathbf{z}_{2} - \mathbf{z}_{1})}$$

$$= \frac{1}{1 + \exp (-\mathbf{z})}$$

$$= \frac{1}{1 + \exp (-\mathbf{z})}$$

$$\hat{\mathbf{y}}_{2} = \frac{1}{1 + \exp (\mathbf{x}^{\top}\mathbf{w})}$$

 Suppose we use logistic regression to distinguish between the positive and negative classes of the following "image" dataset (where m=2):



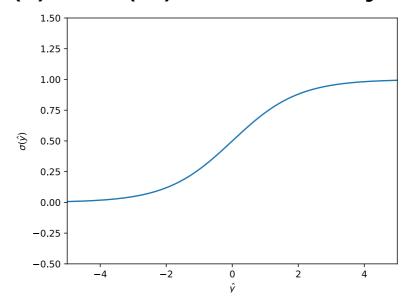
 Suppose we use logistic regression to distinguish between the positive and negative classes of the following "image" dataset (where m=2):



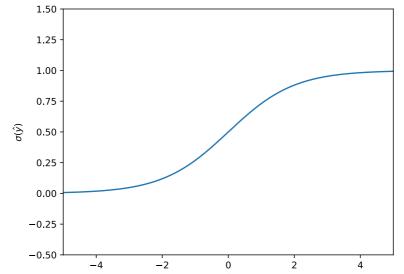
• **Exercise**: find a vector of weights $\mathbf{w} = [w_1, w_2]$ such that, for each positive example \mathbf{x}^+ and each negative example \mathbf{x}^- , we have $\sigma(\mathbf{x}^{+\top}\mathbf{w}) > \sigma(\mathbf{x}^{-\top}\mathbf{w})$, where:

$$\sigma(\mathbf{x}^{\top}\mathbf{w}) = \frac{1}{1 + \exp(-\mathbf{x}^{\top}\mathbf{w})}$$

- Why is this task impossible with logistic regression?
- First, note that $\sigma(z) > \sigma(z')$ if and only if z > z'.



- Why is this task impossible with logistic regression?
- First, note that $\sigma(z) > \sigma(z')$ if and only if z > z'.



• Hence, it suffices to show that no w satisfies:

$$(\mathbf{x}^+)^\top \mathbf{w} > (\mathbf{x}^-)^\top \mathbf{w}$$

for each positive example x+ and negative example x-.

• Then:
$$\begin{bmatrix} 1 & 0 \\ 0 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} > \begin{bmatrix} 1 & 1 \\ 0 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$$
 example example

• Then:
$$\left[\begin{array}{cc} 1 & 0 \end{array}\right] \left[\begin{array}{c} w_1 \\ w_2 \end{array}\right] > \left[\begin{array}{c} 1 & 1 \end{array}\right] \left[\begin{array}{c} w_1 \\ w_2 \end{array}\right]$$
 $w_1 > w_1 + w_2$

• Then:
$$\left[\begin{array}{cc} 1 & 0 \end{array}\right] \left[\begin{array}{c} w_1 \\ w_2 \end{array}\right] > \left[\begin{array}{c} 1 & 1 \end{array}\right] \left[\begin{array}{c} w_1 \\ w_2 \end{array}\right]$$
 $w_1 > w_1 + w_2$ $w_2 < 0$

$$\begin{array}{c|c} \bullet \text{ Then:} & \left[\begin{array}{c} 1 & 0 \end{array}\right] \left[\begin{array}{c} w_1 \\ w_2 \end{array}\right] > \left[\begin{array}{c} 1 & 1 \end{array}\right] \left[\begin{array}{c} w_1 \\ w_2 \end{array}\right] \\ & w_1 > w_1 + w_2 \\ & w_2 < 0 \\ \\ \left[\begin{array}{c} 0 & 1 \end{array}\right] \left[\begin{array}{c} w_1 \\ w_2 \end{array}\right] > \left[\begin{array}{c} 0 & 0 \end{array}\right] \left[\begin{array}{c} w_1 \\ w_2 \end{array}\right] \\ \begin{array}{c} \text{Negative} \\ \text{example} \end{array}$$

Suppose (by way of contradiction) such a w did exist.

Contradiction

- This is an instance of the classic XOR problem:
 - 10 => 1
 01 => 1
 00 => 0
 11 => 0
- No linear or generalized linear model can solve this.
- Instead, we need non-linear models (more soon).

Smirk?









Neutral (0)

Smile (0)

Smirk left (1)

Smirk right (1)