CS 4342: Class 3

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Combining multiple predictors

- Determining smile/non-smile based on a single comparison is very weak.
- What if we combined multiple pairs and took the majorityvote (choose non-smile if tied) across all m comparisons?

$$g^{(j)}(\mathbf{x}) = \mathbb{I}[\mathbf{x}_{r_1,c_1} > \mathbf{x}_{r_2,c_2}]$$

$$\hat{y} = g(\mathbf{x}) = \mathbb{I}\left[\left(\frac{1}{m}\sum_{j=1}^{m}g^{(j)}(\mathbf{x})\right) > 0.5\right]$$

Step-wise classification

Pseudocode:

```
predictors = [] # Empty list
For j = 1, ..., m:
   1. Find next best predictor given what's already in predictors
   2. Add it to predictors
```

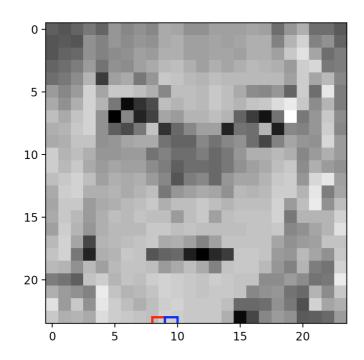
Run smile_demo.py and optimize on 10 images.

Step-wise classification

- Accuracy (on 10 images): 100%.
- Learned feature:

Step-wise classification

- Accuracy (on 10 images): 100%.
- Learned feature (somewhat counterintuitive):



What happened?

Overfitting

- When we optimized the m=1 features on a set of just 10 images, we discovered a spurious relationship between the image x and the target label y.
 - Spurious: the relationship would not generalize to a much larger set of images.

Overfitting

- When we optimized the m=1 features on a set of just 10 images, we discovered a spurious relationship between the image x and the target label y.
 - Spurious: the relationship would not generalize to a much larger set of images.
- Problem: we have many features (331200) but very few images (10) we need to classify.
 - Out of 331200, it's not hard to find a few features that happen to discriminate smiles/non-smiles just by chance.
- This is called overfitting to the dataset.

- In machine learning, we always optimize the parameters/features of our classifier/regressor on a training set $\mathcal{D}^{\mathrm{train}}$.
- We then measure accuracy on a **testing set** \mathcal{D}^{test} that is disjoint from (contains no common elements with) the training set.
- The accuracy on the testing set characterizes how well our machine will perform on new data.
- The training and testing sets should be collected in the same manner.

- What if the test accuracy was bad?
 - Then we should make some changes to the architecture or training procedures of our machine and re-train.
- To estimate the accuracy of the new machine, we should evaluate it on a new test set!
 - Why?

- When we re-train a ML model, there are many things we can change, e.g.:
 - L1/L2 regularization strength
 - SVM kernel type + parameters
 - Number of neural network layers, #units/layer
 - Learning rate, momentum, etc.

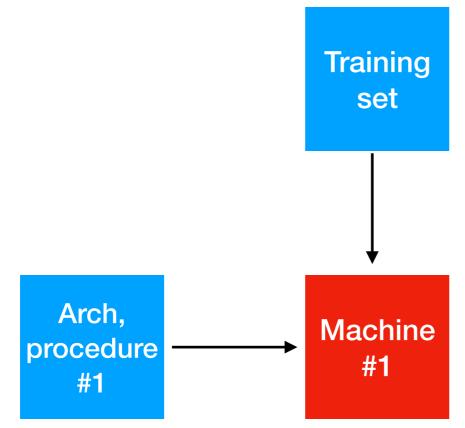
 When we iteratively re-train many ML models by optimizing on the test set, we might find good values for these choices just by chance.

 Train a model on the training set using a particular architecture and training procedure.

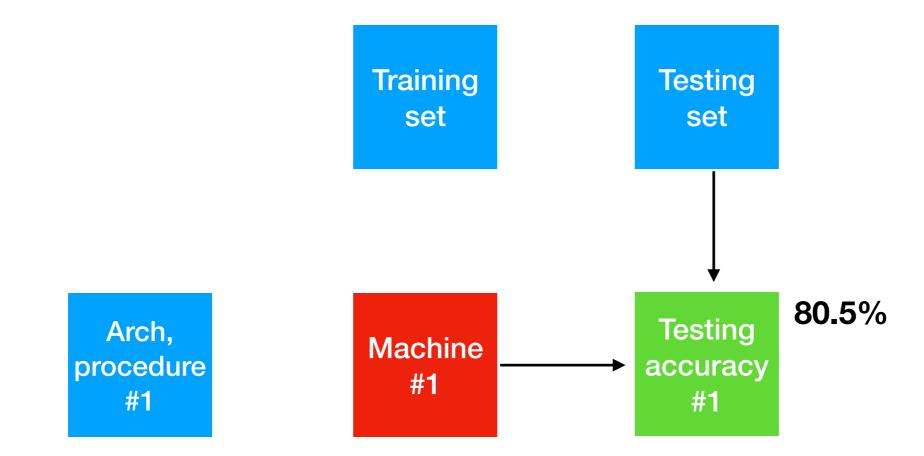
Training set

Arch, procedure #1

 Train a model on the training set using a particular architecture and training procedure.



Evaluate the trained machine on the testing set.



Accuracy not good enough?

Training set

Testing set

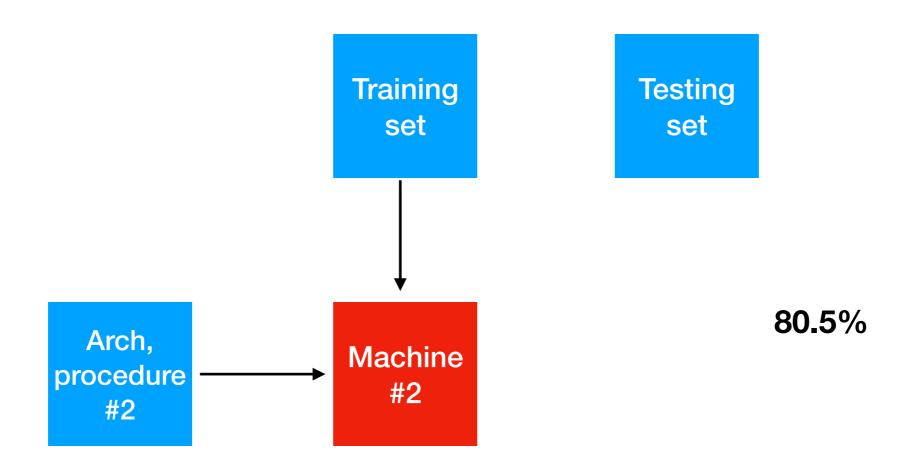
Arch, procedure #1



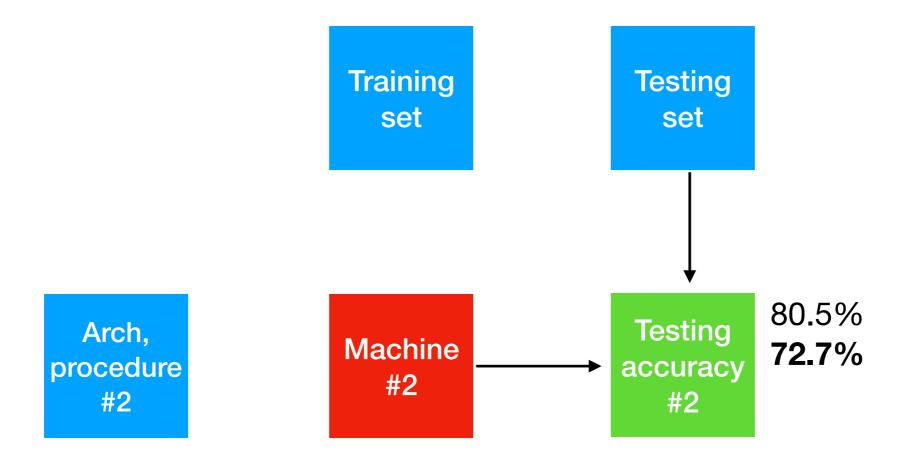


80.5%

Choose a different design and try again!



Evaluate the new machine on the testing set.



Accuracy still not good enough?

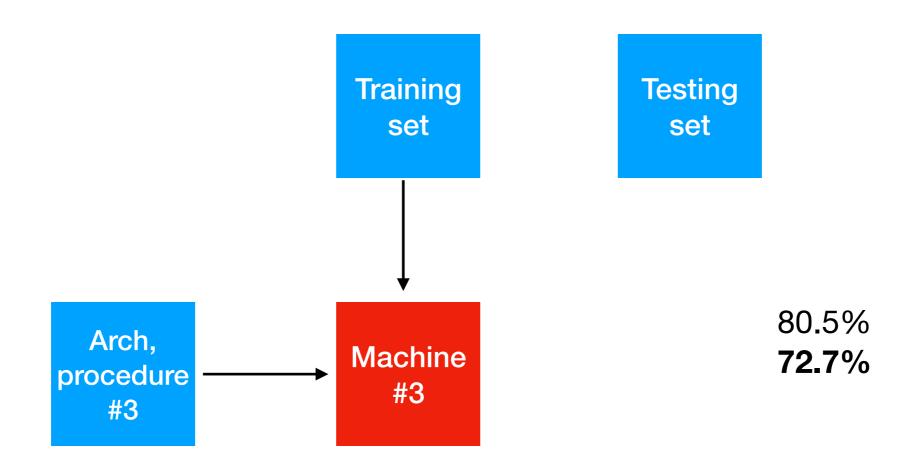
Training set

Testing set

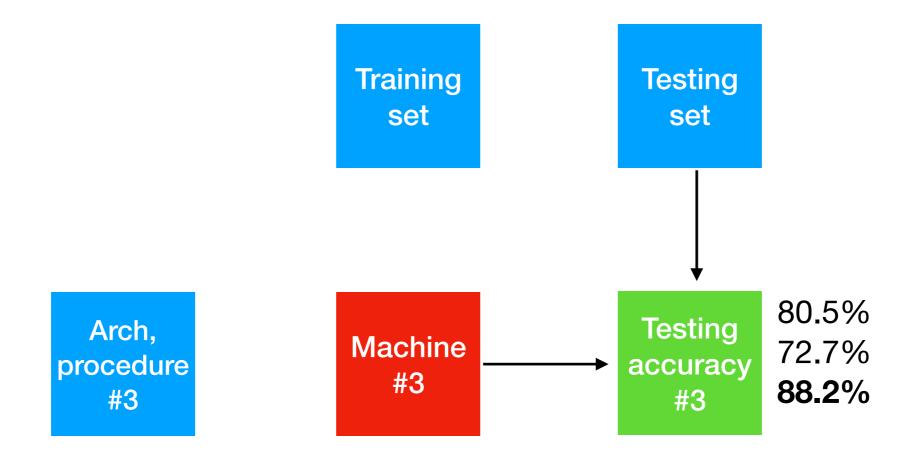
Arch, procedure #2 Machine #2 Testing accuracy #2

80.5% **72.7%**

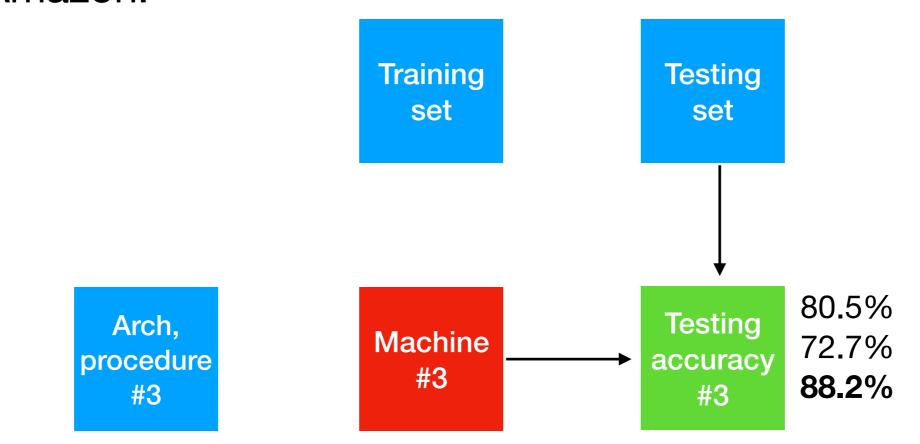
Choose yet another design and try again!



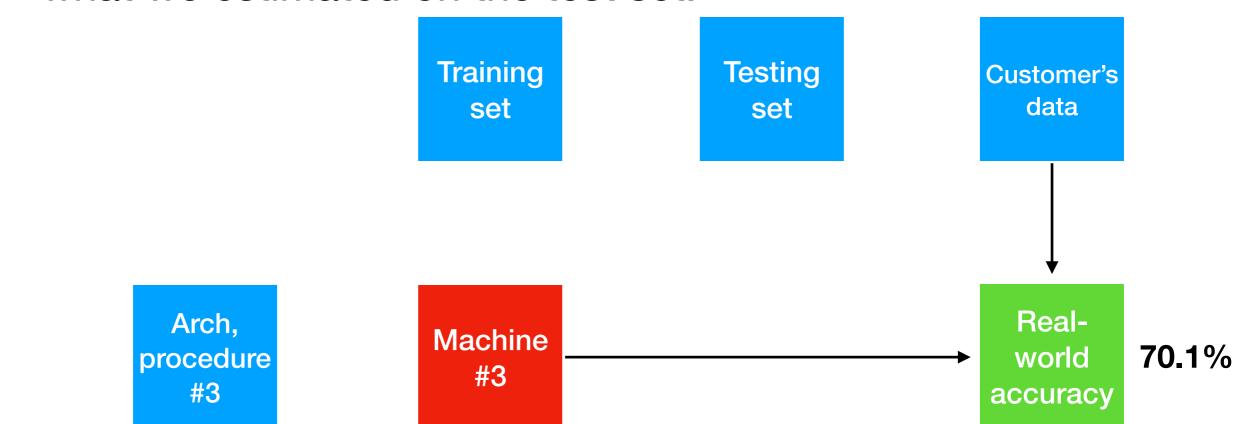
Evaluate the new machine on the testing set.



 Much better! Let's keep machine #3 and sell it on Amazon!



 Oops — the real-world accuracy was much less than what we estimated on the test set!



Limitations of our feature set

- So far, the predictors we have considered are very simple:
 - Is pixel (r_1,c_1) brighter than pixel (r_2,c_2) ?
- We can't even express simple relationships such as:
 - "Pixel (r_1,c_1) is at least 5 bigger than pixel (r_2,c_2) "
 - "2 times pixel (r_1,c_1) is bigger than pixel (r_2,c_2) "
 - "2 times pixel (r_1,c_1) plus 4 times pixel (r_2,c_2) is larger than pixel (r_3,c_3) ".

- We can harness these kinds of relationships using linear regression.
- Let's switch back to the age estimation problem...

- A column vector is a (n x 1) matrix.
- A row vector is a (1 x n) matrix.
- The **transpose** of $(n \times k)$ matrix **A**, denoted **A**^T, is $(k \times n)$.
- Multiplication of matrices A and B:
 - Only possible when: **A** is $(n \times k)$ and **B** is $(k \times m)$
 - Result: (n x m)

 The inner product between two column vectors (same length) x, y can be written as: x^Ty

$$\begin{bmatrix} x_1 & \dots & x_m \end{bmatrix} \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix} = \sum_{i=1}^m x_i y_i$$

An inner product produces a scalar.

 The outer product between two column vectors (same length) x, y can be written as: xy^T:

$$\begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix} \begin{bmatrix} y_1 & \dots & y_m \end{bmatrix} = \begin{bmatrix} x_1y_1 & \dots & x_1y_m \\ \vdots & \ddots & \vdots \\ x_my_1 & \dots & x_my_m \end{bmatrix}$$

An outer product produces a matrix.

Example

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 4 & -1 \end{bmatrix} = \begin{bmatrix} 4 & -1 \\ 8 & -2 \end{bmatrix}$$
$$\begin{bmatrix} -1 \\ 3 \end{bmatrix} \begin{bmatrix} 2 & 0 \end{bmatrix} = \begin{bmatrix} -2 & 0 \\ 6 & 0 \end{bmatrix}$$

 The sum of multiple outer products can be expressed as the multiplication of two matrices:

$$\mathbf{x}^{(1)}\mathbf{y}^{(1)^{\top}} + \dots \mathbf{x}^{(n)}\mathbf{y}^{(n)^{\top}} = \sum_{i=1}^{n} \mathbf{x}^{(i)}\mathbf{y}^{(i)^{\top}}$$

$$= \begin{bmatrix} & & & & & & & & & & \\ & \mathbf{x}^{(1)} & \dots & \mathbf{x}^{(n)} & \end{bmatrix} \begin{bmatrix} & & & \mathbf{y}^{(1)} & \dots & \\ & & \vdots & & & \\ & & & & \end{bmatrix}$$

$$\stackrel{\dot{=}}{=} \mathbf{X}\mathbf{Y}^{\top}$$

Example \mathbf{V}^{T}

$$\left[\begin{array}{c}1\\2\end{array}\right]\left[\begin{array}{cc}4&-1\end{array}\right]=\left[\begin{array}{cc}4&-1\\8&-2\end{array}\right]$$

$$\left[\begin{array}{c} -1\\3 \end{array}\right] \left[\begin{array}{ccc} 2 & 0 \end{array}\right] = \left[\begin{array}{ccc} -2 & 0\\6 & 0 \end{array}\right]$$

$$\begin{bmatrix} 1 & -1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 4 & -1 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 14 & -2 \end{bmatrix}$$

Here's a special case:

$$\mathbf{x}^{(1)}\mathbf{x}^{(1)^{\top}} + \dots \mathbf{x}^{(n)}\mathbf{x}^{(n)^{\top}} = \sum_{i=1}^{n} \mathbf{x}^{(i)}\mathbf{x}^{(i)^{\top}}$$

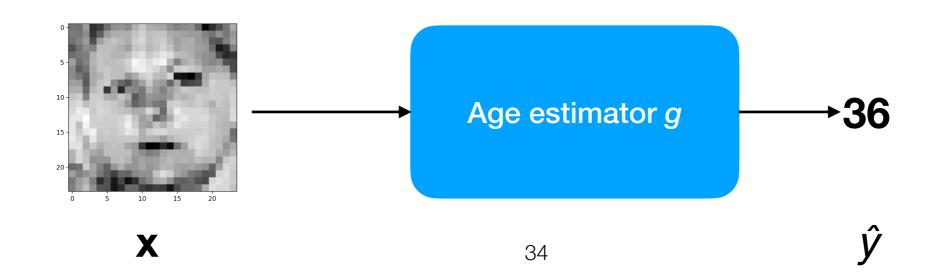
$$= \begin{bmatrix} \mathbf{x}^{(1)} & \dots & \mathbf{x}^{(n)} \\ \mathbf{x}^{(1)} & \dots & \mathbf{x}^{(n)} \end{bmatrix} \begin{bmatrix} \mathbf{x}^{(1)} & \mathbf{x}^{(1)} & \mathbf{x}^{(n)} \\ \vdots & \vdots & \vdots \\ \mathbf{x}^{(n)} & \mathbf{x}^{(n)} & \mathbf{x}^{(n)} \end{bmatrix}$$

$$\stackrel{\dot{=}}{=} \mathbf{X}\mathbf{X}^{\top}$$

 Linear regression is built as a linear combination of all the inputs x:

$$\hat{y} = g(\mathbf{x}; \mathbf{w}) = \sum_{j=1}^{m} \mathbf{x}_j \mathbf{w}_j = \mathbf{x}^{ op} \mathbf{w}_j$$

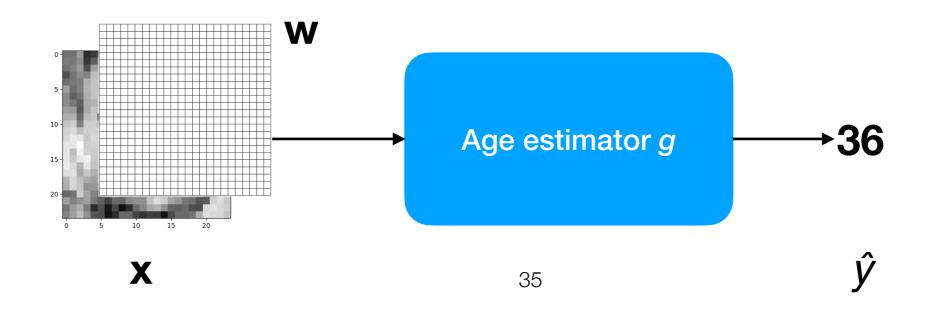
• Here, we treat the image **x** as a *vector* (even though it represents a 2-d image).



 Linear regression is built as a linear combination of all the inputs x:

$$\hat{y} = g(\mathbf{x}; \mathbf{w}) = \sum_{j=1}^{m} \mathbf{x}_j \mathbf{w}_j = \mathbf{x}^{ op} \mathbf{w}_j$$

 Vector w represent an "overlay image" that weights the different pixel intensities of x.



• Imagine a 2x2 pixel "image" x and a weight matrix w:

2	5
0	3
X	



• Then $\hat{y} =$

?

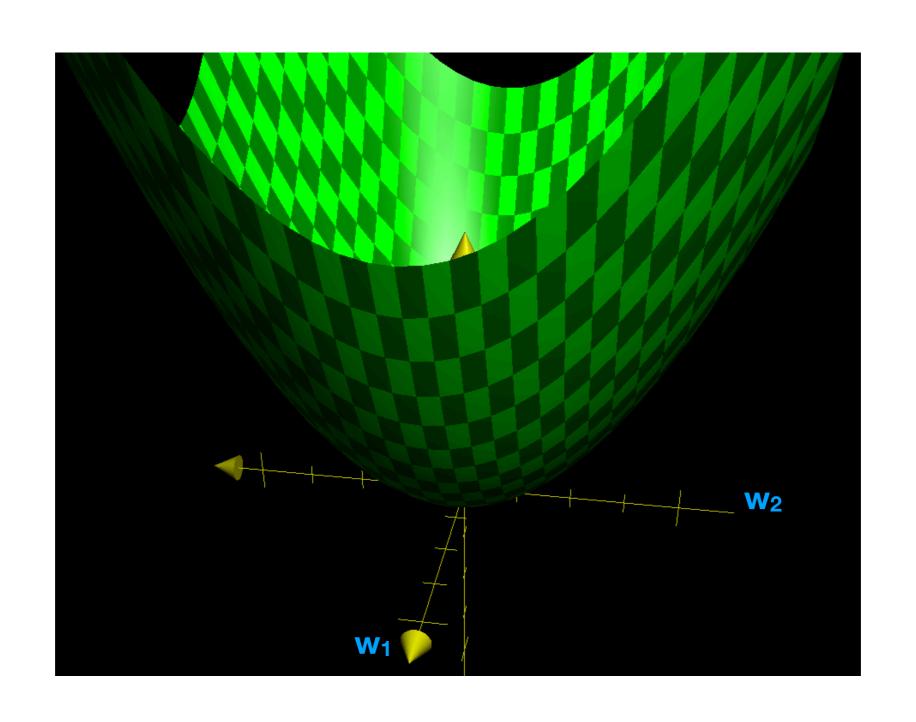
Linear regression

- How should we choose each "weight" w_j?
- Let's define the loss function that we seek to minimize:

$$f_{\text{MSE}}(\mathbf{y}, \hat{\mathbf{y}}; \mathbf{w}) = \frac{1}{2n} \sum_{i=1}^{n} \left(g(\mathbf{x}^{(i)}; \mathbf{w}) - y^{(i)} \right)^{2}$$
$$= \frac{1}{2n} \sum_{i=1}^{n} \left(\mathbf{x}^{(i)} \mathbf{w} - y^{(i)} \right)^{2}$$

The 2 in the denominator will slightly simplify the algebra later...

What does f(w) look like?



Linear regression

- w can be any real-valued vector; hence, we can use differential calculus to find the minimum of f_{MSE} .
- Just derive the gradient of f_{MSE} w.r.t. w, set to 0, and solve.
- Since f_{MSE} is a convex function, we are guaranteed that this critical point is a global minimum.

Gradient vector

• For a real-valued function $f: \mathbb{R}^m \to \mathbb{R}$, we define the gradient w.r.t. **w** as:

$$\nabla_{\mathbf{w}} f = \begin{bmatrix} \frac{\partial f}{\partial \mathbf{w}_1} \\ \vdots \\ \frac{\partial f}{\partial \mathbf{w}_m} \end{bmatrix}$$

 In other words, the gradient is a column vector containing all first partial derivatives w.r.t. w.

Gradient vector: exercise 1

$$f(\mathbf{w}) = f\left(\begin{bmatrix} w_1 \\ w_2 \end{bmatrix}\right) = 3w_1^2 - \sin(2w_2)$$

$$\nabla_{\mathbf{w}} f(\mathbf{w}) =$$

Gradient vector: exercise 2

$$f(\mathbf{x}, \mathbf{w}, y) = \frac{1}{2} (\mathbf{x}^{\mathsf{T}} \mathbf{w} - y)^2$$

$$\nabla_{\mathbf{w}} f(\mathbf{x}, \mathbf{w}, y) =$$

Gradient vector: exercise 2

$$f(\mathbf{x}, \mathbf{w}, y) = \frac{1}{2} (\mathbf{x}^{\mathsf{T}} \mathbf{w} - y)^{2}$$
$$= \frac{1}{2} (x_{1}w_{1} + x_{2}w_{2} - y)^{2}$$

$$\nabla_{\mathbf{w}} f(\mathbf{x}, \mathbf{w}, y) =$$

• The gradient of f_{MSE} is thus:

$$\nabla_{\mathbf{w}} f_{\text{MSE}}(\mathbf{y}, \hat{\mathbf{y}}; \mathbf{w}) = \nabla_{\mathbf{w}} \left[\frac{1}{2n} \sum_{i=1}^{n} \left(\mathbf{x}^{(i)^{\top}} \mathbf{w} - y^{(i)} \right)^{2} \right]$$

$$= \frac{1}{2n} \sum_{i=1}^{n} \nabla_{\mathbf{w}} \left[\left(\mathbf{x}^{(i)^{\top}} \mathbf{w} - y^{(i)} \right)^{2} \right]$$

$$= \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}^{(i)} \left(\mathbf{x}^{(i)^{\top}} \mathbf{w} - y^{(i)} \right)$$

 By setting to 0, splitting the sum apart, and solving, we reach the solution:

$$\frac{1}{n} \sum_{i=1}^{n} \mathbf{x}^{(i)} \left(\mathbf{x}^{(i)}^{\top} \mathbf{w} - y^{(i)} \right)$$

$$0 = \sum_{i} \mathbf{x}^{(i)} \mathbf{x}^{(i)^{\top}} \mathbf{w} - \sum_{i} \mathbf{x}^{(i)} y^{(i)}$$

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$$\sum_{i} \mathbf{x}^{(i)} \mathbf{x}^{(i)^{\top}} \mathbf{w} = \sum_{i} \mathbf{x}^{(i)} y^{(i)}$$
$$\mathbf{w} = \left(\sum_{i} \mathbf{x}^{(i)} \mathbf{x}^{(i)^{\top}}\right)^{-1} \sum_{i} \mathbf{x}^{(i)} y^{(i)}$$

- To compute **w**, do *not* use np.linalg.inv.
- Instead, use np.linalg.solve, which avoids explicitly computing the matrix inverse.

Let's define a matrix X to contain all the training images:

$$\mathbf{X} = \left[egin{array}{ccccc} \mathbf{x}^{(1)} & \dots & \mathbf{x}^{(n)} \\ & & & \end{array}
ight]$$

- In statistics, X is called the design matrix.
- Let's define vector y to contain all the training labels:

$$\mathbf{y} = \left[egin{array}{c} y^{(1)} \ dots \ y^{(n)} \end{array}
ight]$$

Using summation notation, we derived:

$$\mathbf{w} = \left(\sum_{i=1}^{n} \mathbf{x}^{(i)} \mathbf{x}^{(i)}^{\top}\right)^{-1} \left(\sum_{i=1}^{n} \mathbf{x}^{(i)} y^{(i)}\right)$$

Using matrix notation, we can write the solution as:

$$\mathbf{w} =$$
 ?

- Once we've "trained" the weights w, we can estimate the y-value (label) for any x.
- We can compute the $\{\hat{y}^{(i)}\}$ for a set of images $\{\mathbf{x}^{(i)}\}$ in one-fell-swoop using matrix operations.
- Let's define our design matrix **X** as before:

$$\mathbf{X} = \left[egin{array}{ccccc} \mathbf{x}^{(1)} & \dots & \mathbf{x}^{(n)} \\ & & & \end{array}
ight]$$

Then our estimates of the labels is given by:

$$\hat{\mathbf{y}} = \mathbf{X}^{\top} \mathbf{w}$$

• Suppose we have *n* images, each with just 2 pixels.

$$\hat{\mathbf{y}} = \mathbf{X}^{\top} \mathbf{w}$$

Suppose we have n images, each with just 2 pixels.

$$\hat{\mathbf{y}} = \mathbf{X}^{\top} \mathbf{w}$$

$$= \begin{bmatrix} \mathbf{x}_1^{(1)} & \dots & \mathbf{x}_1^{(n)} \\ \mathbf{x}_2^{(1)} & \dots & \mathbf{x}_2^{(n)} \end{bmatrix}^{\top} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$$

This is the index of the *image*.

Suppose we have n images, each with just 2 pixels.

$$\hat{\mathbf{y}} = \mathbf{X}^{\top} \mathbf{w} \\
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$$= \begin{bmatrix} \mathbf{x}_{1}^{(1)} w_{1} + \mathbf{x}_{2}^{(1)} w_{2} \\ \vdots \\ \mathbf{x}_{1}^{(n)} w_{1} + \mathbf{x}_{2}^{(n)} w_{2} \end{bmatrix}$$