Neo6502 API

The Neo6502 API is a messaging system. Messages are passed through a block of memory stored from $FF00 to $FF0F which is allocated as below.

There are *no* methods of directly accessing the hardware.

Address	Contents		
$FF00	Group. API Commands are grouped by functionality ; so group 1 is the system function, and group 2 is the console I/O function for example. Once a non zero value is written here the system will respond by setting values in the other registers appropriately, at the end they will clear this location.		
$FF01	Function. A command within the group, so for example Group 1 command 0 writes a value to the console, and Group 1 command 1 reads the keyboard		
$FF02	Return any error values, 0 = no error.		
$FF03	Information	7	Set to '1' if the ESCape key has been pressed. This is not automatically reset.
		6	Unused
		5	Unused
		4	Unused
		3	Unused
		2	Unused
		1	Unused
		0	Unused
$FF04-B	Parameters, known as Params 0 through 7. These can be combined to form 16 or 32 bit integers.		
$FF0C-F	Reserved		

In the include file neo6502.inc the value of the first is the identifier ControlPort. This also has addresses of WaitMessage, SendMessage and some helper functions.

Messages are sent as follows.

1	Wait for any pending command to complete. There is a subroutine WaitMessage which does this for the developer
2	Set up the parameters if any. For example printing a character to the console is done by putting its ASCII value into $FF04.
3	Setting the function code at $FF01
4	Writing the command to $FF00. This h*as* to be done last as setting it to non zero before the parameters are set up may cause the message to be processed. On a technical point, both implementations process the message immediately on write.
5	Optionally, wait for completion. Some commands, e.g. 2,2 which reads from the keyboard queue return a value in a parameter. Things like writing to the console do not need to wait for completion, as any subsequent command will wait for the command to complete as per 1.

There is a support function SendMessage which inlines the command and function e.g. this code from the Kernel.

```
jsr  KSendMessage         ; send command 2,1 read keyboard
.byte 2,1
jsr  KWaitMessage         ; waiting for message to be sent back
lda  DParameters          ; read result
```

You could write this as the following – it's just more longwinded.

```
      lda  #1                   ; do command 2,1
      sta  DFunction
      lda  #2
      sta      DCommand
Loop:
      lda  DCommand             ; signal done by this being zero
      bne  Loop
      lda  DParameters          ; get result
```

Group	Func	Description
1	0	Resets the messaging system and its components. Should not normally be used.
	1	Return the value of the 100Hz system timer in Params 0-3
2	0	Write character Param0 to the console. 32-127 are standard ASCII, 8 is Backspace, 13 Return. There are other console codes documented later.
	1	Read and remove a key press from the keyboard queue into Param0 , this is the ASCII value of the keystroke. If there are no key presses in the queue, Param0 is zero. Note that this method is *not* for games, where key presses and releases replace a joystick. The system maintains a bit array to check if keys are pressed.
	2	Check to see if the keyboard queue is empty. If it is Param0 is $FF, otherwise it is $00

Console Codes (tbc)