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Machine Learning I
Exercise Sheet 6
Due on Mon, December 12, 12:15

If you turn in your solutions via email, please send to:

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Include [ML1-1617] in the subject line, turn in a single PDF file and include your name in the file name.

Exercise 1. *'Completing the square': suppose you encounter an expression*

$$\frac{1}{2}\mathbf{w}^T C \mathbf{w} + \mathbf{b}^T \mathbf{w} + a \quad (1)$$

with a symmetric square matrix C , vectors \mathbf{w} and \mathbf{b} , and constant a . Show that you can bring this into the form

$$\frac{1}{2}(\mathbf{w} - \mathbf{m})^T C (\mathbf{w} - \mathbf{m}) + u, \quad (2)$$

where $\mathbf{m} = -C^{-1}\mathbf{b}$ and $u = a - \frac{1}{2}\mathbf{b}^T C^{-1}\mathbf{b}$. Hint: insert \mathbf{m} and u into the expression (2) above.

1 point + 2 bonus points

Exercise 2. *Now use the method of 'completing the square' in the exponential to derive the N -dimensional posterior distribution for Bayesian regression. Assume a prior of the form*

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{w} | \mathbf{0}, \alpha^{-1} \mathbf{I})$$

and the likelihood

$$p(\mathbf{t} | \mathbf{X}, \mathbf{w}, \beta) = \prod_{n=1}^N \mathcal{N}(t_n | \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_n), \beta^{-1}),$$

and show that the posterior is given by

$$p(\mathbf{w} | \mathbf{t}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_N, \mathbf{S}_N)$$

with

$$\mathbf{m}_N = \beta \mathbf{S}_N \boldsymbol{\Phi}^T \mathbf{t}$$

and

$$\mathbf{S}_N^{-1} = \alpha \mathbf{I} + \beta \boldsymbol{\Phi}^T \boldsymbol{\Phi},$$

where $\boldsymbol{\Phi}$ is the design matrix.

1 point + 3 bonus points

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Exercise 3. Reproduce the plots shown in Figure 1 (from the book by CM Bishop (Springer Series), p.155), using a slightly more complicated model. Generate your own synthetic data from the function

$$f(x, \mathbf{a}) = a_0 + a_1x + a_2x^2$$

with parameter values $a_0 = -0.3$, $a_1 = 0.5$, $a_2 = 0.4$ by first choosing values of x_n from the uniform distribution $U(x|-1, 1)$, then evaluating $f(x_n, \mathbf{a})$, and finally adding Gaussian noise with standard deviation of $s=0.2$ to obtain the target values t_n . The goal is to recover the values of a_0 , a_1 and a_2 from such data, and to explore the dependence on the size of the data set. To achieve this, assume a model in which individual data points are generated by

$$p(t|x, \mathbf{w}) = \mathcal{N}(t|y(x, \mathbf{w}), s^2) ,$$

where $y(x, \mathbf{w}) = w_0 + w_1x + w_2x^2$ with weights \mathbf{w} to be estimated and a fixed standard deviation $s = 0.2$, i.e. assumed to be known. The likelihood is then given by

$$p(\mathbf{t}|X, \mathbf{w}) = \prod_{n=1}^N \mathcal{N}(t_n|y(x_n, \mathbf{w}), s^2) .$$

Finally, assume a Gaussian distributed prior $p(\mathbf{w}|\alpha) = \mathcal{N}(\mathbf{w}|\mathbf{0}, \alpha)$ with $\alpha = 2$. Generate two plots analog to those shown in Figure 1, one for (w_0, w_1) and one for (w_1, w_2) . Describe and interpret these plots thoroughly.

8 points

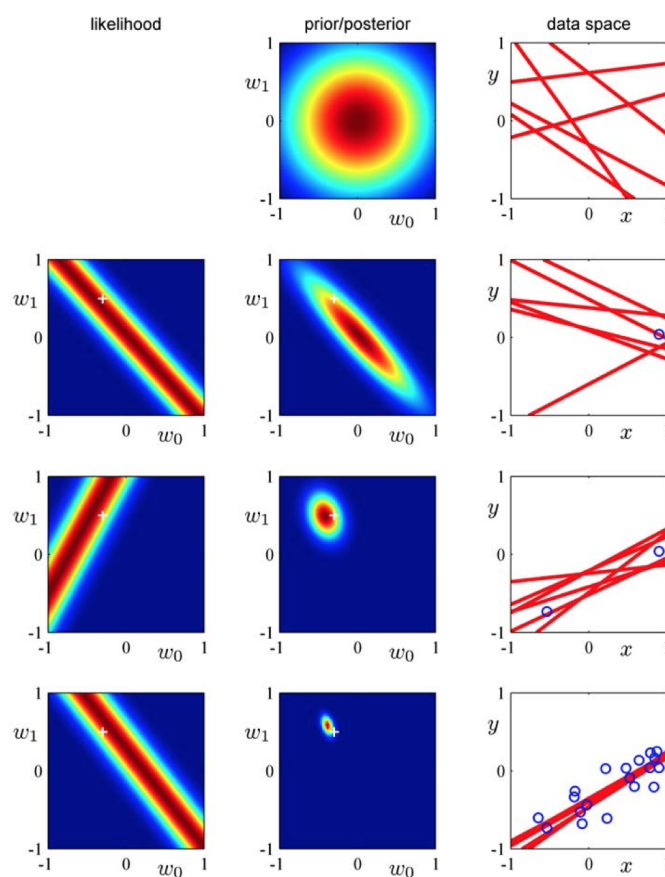


Figure 1: Illustration of sequential Bayesian learning for a linear model.