ECE 235: Growth of Functions, Data structures, Thu 9/27/01 (Ch. 3,10)

Pai H. Chou, University of California at Irvine

This lecture:

- big O, big Ω , and big Θ , how they grow
- · fundamental data structures

1 Asymptotic Notations

- purpose: express run time as T(n), n =input size
- assumption: $n \in \mathbb{N} = \{0, 1, 2, ...\}$ natural numbers

1.1 big O =asymptotic upper bound: (page 44)

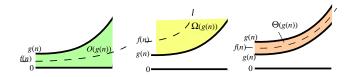
- f(n) = O(g(n)) is a *set of functions* that are upper-bounded by $0 \le f(n) \le c \cdot g(n)$ for some $n \ge n_0$
- $\Rightarrow f(n)$ grows no faster than g(n)
- example: $2n^2 = O(n^3)$, for $c = 1, n_0 \ge 2$
- funny equality, more like a membership: $2n^2 \in O(n^3)$
- n² and n³ are actually functions, not values.
 ⇒ sloppy but convenient

1.2 big Ω = asymptotic lower bound (page 45)

- swap the place between f(n) and $c \cdot g(n)$: $0 \le c \cdot g(n) \le f(n)$ for some $n \ge n_0$
- example: $\sqrt{n} = \Omega(\lg n)$, for $c = 1, n_0 = 16$

1.3 big Θ = asymptitic tight bounds

- need two constants c_1 and c_2 to sandwich f(n).
- example: $\frac{1}{2}n^2 2n = \Theta(n^2)$ for $c_1 = \frac{1}{4}$, $c_2 = \frac{1}{2}$, $n_0 = 8$
- Theorem: $(O \text{ and } \Omega) \Leftrightarrow \Theta$



Example: insertion sort

$$O(n^2)$$
 worst case, $\Omega(n)$ best case
$$T(n) = \begin{array}{ccc} c_1 \cdot n & \text{// for loop} \\ + & c_2 \cdot (n-1) & \text{// key} \leftarrow A \\ + & \sum_{j=2}^n Insert(j) & \text{// loop to insert } j \\ + & c_8 \cdot (n-1) & \text{// } A[i+1] \leftarrow \text{key} \end{array}$$

- Best case of Insert(j) is $\Theta(1)$, Worst is $\Theta(j)$
- Issue: $\Theta(n^2) + \Theta(n)$ is still $\Theta(n^2)$

Example: MergeSort(A, p, r)

where p, r are the lower and upper bound indexes to array A.

$$\begin{aligned} &\text{if } p < r \text{ then} \\ &q := \lfloor (p+r)/2 \rfloor \\ &\text{MergeSort}(A,p,q), \text{MergeSort}(A,q+1,r) \\ &\text{Merge}(A,p,q,r) \end{aligned}$$

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1\\ 2 \cdot T(\frac{n}{2}) + \Theta(n) & \text{if } n > 1 \end{cases}$$

T(n) is expressed in terms of T itself! This is called *recurrence*. We want a closed-form solution (no T on the right-hand-side of the equation).

To solve recurrence:

$$\bullet \ \ \text{rewrite as} \ T(n) = \left\{ \begin{array}{ll} c & \text{if} \ n=1 \\ 2 \cdot T(\frac{n}{2}) + c \cdot n & \text{if} \ n>1 \end{array} \right.$$

$$T(n) = 2T(\frac{n}{2}) + cn$$
 Expand
$$= 2(2T(\frac{n/2}{2}) + c \cdot \frac{n}{2}) + cn$$

$$= 4T(\frac{n}{4}) + 2c\frac{n}{2} + cn = 4T(\frac{n}{4}) + 2cn$$

$$= 8T(\frac{n}{8}) + 3cn = \dots$$

$$= (2^{i})T(\frac{n}{2^{i}}) + i \cdot cn$$

• We can divide n by 2 at most $\lg n$ times before n = 1. So, $T(n) = (\lg n) \cdot cn + cn = \Theta(n \lg n)$.

Chapter 4 will show how to solve recurrence systematically.

1.4 little-o, little- ω not asymptotically tight

$$\begin{split} o(g(n)) &= \{f(n): \forall c > 0 \exists n_0 > 0: 0 \leq \boxed{f(n) < cg(n)} \ \forall n \geq n_0\} \\ \omega(g(n)) &= \{f(n): \forall c > 0 \exists n_0 > 0: 0 \leq \boxed{cg(n) < f(n)} \ \forall n \geq n_0\} \end{split}$$

Example

- $2n^2 = O(n^2)$ is a tight bound $\Rightarrow 2n^2 \neq o(n^2)$.
- $2n = O(n^2)$ is not tight $\Rightarrow 2n = o(n^2)$.
- does not make sense to have little- θ

2 Polynomials, log, factorial, fibonacci

2.1 Polynomial in n of degree d:

$$p(n) = \sum_{i=0}^{d} a_i n_i = \Theta(n^d)$$

Polynomially bounded: $f(n) = O(n^k)$ for constant k .

2.2 logarithm

- useful identity: $a^{\log_b c} = c^{\log_b a}$.
- polylogarithmically bounded if $f(n) = O(\lg^k n)$ for constant k
- grows slower than any polynimial: $\lg^b n = o(n^a)$ for any constant a > 0.
- "log-star": $\lg^* n = \min\{i \ge 0 : \lg^{(i)} n \le 1\}$ (log of log of log ... of log of n) grows very very slowly. Example: $\lg^*(2^{65536}) = 5$.

2.3 Factorial:

- Loose bound: n! is faster than 2^n but slower than n^n
- precisely, $n! = \Theta(n^{n+1/2}e^{-\lg n})$ (Stirling's approximation)
- $\lg(n!) = \Theta(n \lg n)$

2.4 Fibonacci

grows exponentially

2.5 misc

- 2^{2^n} grows faster than n!
- (n+1)! grows faster than n!
- n! grows faster than $n \cdot 2^n$ faster than 2^n
- $2^{\lg n} = n$

3 Python: Functions

- function definition: **def** functionName (paramList):
- · variables have local scope by default
- control flow: for, while, if
- range(a, b) function: returns the list [a, ... b-1]
 range(1,5)
 2, 3, 4]

Algorithm from book (p.24)	Python code (file isort.py)
INSERTION-SORT(A)	def InsertionSort(A):
1 for $j \leftarrow 2$ to length[A]	for j in range(1, len(A)):
2 do $key \leftarrow A[j]$	key = A[j]
$i \leftarrow j-1$	i = j - 1
4 while $i > 0$ and $A[i] > k$	ey while (i>= 0) and (A[i]>key):
5 do $A[i+1] \leftarrow A[i]$	A[i+1] = A[i]
$6 i \leftarrow i - 1$	i = i - 1
7 $A[i+1] \leftarrow key$	A[i+1] = key

- Don't forget the colon: for def, for, and while constructs
- Book $A[1...n] \Rightarrow \text{Python } A[0...n-1]$ Book's $2...n \Rightarrow \text{Python } 1...n-1$.
- line 1: range(1,len(A))⇒ [1...len(A)-1]

% python >>> from isort import * # read file isort.py >>> x = [2,7,3,8,1] # create test case >>> InsertionSort(x) # call routine >>> x # look at result [1, 2, 3, 7, 8] Works for other data types, too!

4 Data Structures Review

Concepts:

• Stacks: Last-in First-out

• Queue: First-in First-out

• Trees: Root, children

4.1 Array implementation

Stack S: need a stack pointer (top)

Push(x): $S[++top] \leftarrow x$ Pop(): return S[top--]

Note: Actually stacks can grow downward also. Note: To be safe, check stack underflow/overflow.

Queue Q: need 2 pointers (head, tail)

Enqueue(x): Q[tail] $\leftarrow x$

 $tail \leftarrow (tail mod len(Q)) + 1$

Dequeue(): temp $\leftarrow Q[\text{head}]$

 $\texttt{head} \leftarrow (\texttt{head} \; \texttt{mod} \; \texttt{len}(Q)) \; + \; 1$

return temp

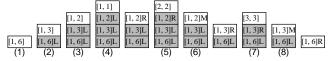
Note: To be safe, check queue underflow/overflow.

4.2 Stack and Calls/Recursion

- Calling routine ⇒ Push local, param, return address
- Return ⇒ Pop and continue

Example: MergeSort (cf. MergeSort Fig. from last lecture)

L (Left), R (Right), M (Merge)



4.3 Linked List x

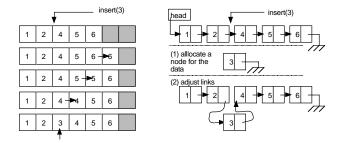
- Singly linked (next) or Doubly linked (next, prev)
- need a key
- need a NIL value

How to implement linked lists?

- Pre-allocate arrays prev[1:n], next[1:n], key[1:n], and x is an index $\in \{0...n\}$, where 0 is NIL.
- Records (structures in C, classes in Java): x.prev, x.next, x.key, and NULL for NIL.

Rearrange by adjusting links, not moving data (key)

- Recall: INSERTIONSORT with array need to copy object to insert.
- Linked list representation: once we know where to insert, adjust link in O(1) time.
- Array version: best case O(1), worst case O(n), average case $O(\frac{n}{2}) = O(n)$.

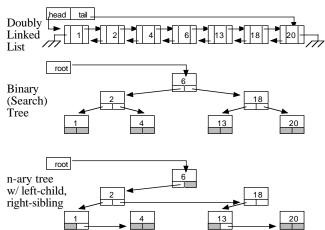


Search for the item

- e.g., where to insert?
- list is unsorted, worst/average case O(n) time to find it! (compare keys one at a time).
- list is *sorted*:
 - Array: binary search in $O(\lg n)$ times
 - Singly linked list: O(n) avg/worst case, need to do linear search
 - Doubly linked list: does not help! still O(n) can't jump to the middle of the list, because link is to the head/tail.

4.4 Binary search tree

- pointer to root; each node has pointer to left-child, right-child
- optional pointer to parent
- left \Rightarrow smaller, right \Rightarrow bigger key value
- $O(\lg n)$ search, if BALANCED
- Can still be O(n) if not balanced!!
 ⇒ Red-black tree (Ch.13) is a way to keep BST balanced
- a *Heap* (Ch.6) implements balanced BST using array; no pointers



4.5 rooted trees w/ unbounded branches

Could have arbitrary number of children!

- left-child: head of linked list to children (down one level)
- right-sibling: link to next on same level
- optional link back to parent