

# 1

(a)

$$\begin{aligned}
 \vec{r}_1 &= l_1 \cos \theta_1 \vec{e}_x + l_1 \sin \theta_1 \vec{e}_y \\
 \vec{r}_2 &= (l_1 \cos \theta_1 + l_2 \cos \theta_2) \vec{e}_x + (l_1 \sin \theta_1 + l_2 \sin \theta_2) \vec{e}_y \\
 \dot{\vec{r}}_1 &= -l_1 \dot{\theta}_1 \sin \theta_1 \vec{e}_x + l_1 \dot{\theta}_1 \cos \theta_1 \vec{e}_y \\
 \dot{\vec{r}}_2 &= (-l_1 \dot{\theta}_1 \sin \theta_1 - l_2 \dot{\theta}_2 \sin \theta_2) \vec{e}_x + (l_1 \dot{\theta}_1 \cos \theta_1 + l_2 \dot{\theta}_2 \cos \theta_2) \vec{e}_y \\
 T &= \frac{1}{2} m_1 \dot{\vec{r}}_1^2 + \frac{1}{2} m_2 \dot{\vec{r}}_2^2 \\
 &= \frac{1}{2} m_1 l_1^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 [l_1^2 \dot{\theta}_1^2 + l_2^2 \dot{\theta}_2^2 + 2l_1 l_2 \dot{\theta}_1 \dot{\theta}_2 (\sin \theta_1 \sin \theta_2 + \cos \theta_1 \cos \theta_2)] \\
 V &= -m_1 g l_1 \cos \theta_1 - m_2 g (l_1 \cos \theta_1 + l_2 \cos \theta_2)
 \end{aligned}$$

拉格朗日量为:

$$\begin{aligned}
 L &= T - V \\
 &= \frac{1}{2} m_1 l_1^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 [l_1^2 \dot{\theta}_1^2 + l_2^2 \dot{\theta}_2^2 + 2l_1 l_2 \dot{\theta}_1 \dot{\theta}_2 (\sin \theta_1 \sin \theta_2 + \cos \theta_1 \cos \theta_2)] + m_1 g l_1 \cos \theta_1 + m_2 g (l_1 \cos \theta_1 + l_2 \cos \theta_2)
 \end{aligned}$$

对于微振动,

$$\begin{aligned}
 \sin \theta_1 \sin \theta_2 + \cos \theta_1 \cos \theta_2 &= \cos(\theta_1 - \theta_2) \approx 1 \\
 V &= -m_1 g l_1 \cos \theta_1 - m_2 g (l_1 \cos \theta_1 + l_2 \cos \theta_2) \\
 &\approx V_0 + \frac{1}{2} (m_1 + m_2) g l_1 \cos \theta_1 \Big|_{\theta_1=0} (\theta_1)^2 + \frac{1}{2} m_2 g l_2 \cos \theta_2 \Big|_{\theta_2=0} (\theta_2)^2 \\
 &= V_0 + \frac{1}{2} (m_1 + m_2) g l_1 \theta_1^2 + \frac{1}{2} m_2 g l_2 \theta_2^2
 \end{aligned}$$

于是:

$$L \approx \frac{1}{2} (m_1 + m_2) l_1^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 l_2^2 \dot{\theta}_2^2 + m_2 l_1 l_2 \dot{\theta}_1 \dot{\theta}_2 - \frac{1}{2} (m_1 + m_2) g l_1 \theta_1^2 - \frac{1}{2} m_2 g l_2 \theta_2^2 + V_0$$

微振动运动方程为:

$$\begin{aligned}
 (m_1 + m_2) l_1 \ddot{\theta}_1 + m_2 l_2 \ddot{\theta}_2 + (m_1 + m_2) g \theta_1 &= 0 \\
 m_2 l_2 \ddot{\theta}_2 + m_2 l_1 \ddot{\theta}_1 + m_2 g \theta_2 &= 0
 \end{aligned}$$

(b)

若  $m_1 = m_2 = m, l_1 = l_2 = l$ , 则方程简化为:

$$\begin{aligned}
 \ddot{\theta}_1 + \frac{1}{2} \ddot{\theta}_2 + \frac{g}{l} \theta_1 &= 0 \\
 \ddot{\theta}_2 + \ddot{\theta}_1 + \frac{g}{l} \theta_2 &= 0 \\
 \mathbf{M} &= \begin{bmatrix} 2ml^2 & ml^2 \\ ml^2 & ml^2 \end{bmatrix} \\
 \mathbf{V} &= \begin{bmatrix} 2mgl & 0 \\ 0 & mgl \end{bmatrix}
 \end{aligned}$$

拉格朗日量可写为 (舍去常数项):

$$L = \frac{1}{2}(\dot{\theta}^T \mathbf{M} \dot{\theta} - \theta^T \mathbf{V} \theta), \quad \theta = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}, \quad \dot{\theta} = \begin{bmatrix} \dot{\theta}_1 \\ \dot{\theta}_2 \end{bmatrix}$$

久期方程为：

$$|-\mathbf{M}\omega^2 + \mathbf{V}| = 0$$

解得：

$$\omega_1^2 = (2 + \sqrt{2})\frac{g}{l}, \quad \omega_2^2 = (2 - \sqrt{2})\frac{g}{l}$$

于是简正频率为：

$$\omega_1 = \sqrt{(2 + \sqrt{2})\frac{g}{l}}, \quad \omega_2 = \sqrt{(2 - \sqrt{2})\frac{g}{l}}$$

将简正频率代回方程  $[-\mathbf{M}\omega^2 + \mathbf{V}]\eta(\omega^2) = \mathbf{0}$ ，得：

$$\eta_1 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix}, \quad \eta_2 = \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{\sqrt{2}}{\sqrt{3}} \end{bmatrix}$$

## 2

(a)

$$\vec{r}_1 = l \cos \theta \vec{e}_x + l \sin \theta \vec{e}_y, \quad \dot{\vec{r}}_1 = -l\dot{\theta} \sin \theta \vec{e}_x + l\dot{\theta} \cos \theta \vec{e}_y$$

$$\vec{r}_2 = l \cos \varphi \vec{e}_x + (y_0 + l \sin \varphi) \vec{e}_y, \quad \dot{\vec{r}}_2 = -l\dot{\varphi} \sin \varphi \vec{e}_x + l\dot{\varphi} \cos \varphi \vec{e}_y$$

$$\begin{aligned} T &= \frac{1}{2}m\dot{\vec{r}}_1^2 + \frac{1}{2}m'\dot{\vec{r}}_2^2 \\ &= \frac{1}{2}ml^2\dot{\theta}^2 + \frac{1}{2}m'l^2\dot{\varphi}^2 \end{aligned}$$

设弹簧固有长度为  $l_0$ ，

$$V = -mgl \cos \theta - m'gl \cos \varphi + \frac{1}{2}k(\sqrt{(\vec{r}_1 - \vec{r}_2)^2} - l_0)^2$$

将  $V$  在平衡位置  $\theta = 0, \varphi = 0$  处展开至二阶：

$$V = V_0 + \frac{1}{2}mgl\theta^2 + \frac{1}{2}m'gl\varphi^2 + \frac{1}{2}kl^2\theta^2 + \frac{1}{2}kl^2\varphi^2 - kl^2\theta\varphi$$

拉格朗日量为：

$$\begin{aligned} L &= T - V \\ &= \frac{1}{2}ml^2\dot{\theta}^2 + \frac{1}{2}m'l^2\dot{\varphi}^2 - V_0 - \frac{1}{2}mgl\theta^2 - \frac{1}{2}m'gl\varphi^2 - \frac{1}{2}kl^2\theta^2 - \frac{1}{2}kl^2\varphi^2 + kl^2\theta\varphi \\ &= \frac{1}{2}ml^2\dot{\theta}^2 + \frac{1}{2}m'l^2\dot{\varphi}^2 - V_0 - \frac{1}{2}l(mg + kl)\theta^2 - \frac{1}{2}l(m'g + kl)\varphi^2 + kl^2\theta\varphi \end{aligned}$$

运动方程为：

$$ml\ddot{\theta} + (mg + kl)\theta - kl\varphi = 0$$

$$m'l\ddot{\varphi} + (m'g + kl)\varphi - kl\theta = 0$$

(b)

$$\mathbf{M} = \begin{bmatrix} ml^2 & 0 \\ 0 & m'l^2 \end{bmatrix}$$

$$\mathbf{V} = \begin{bmatrix} l(mg + kl) & -kl^2 \\ -kl^2 & l(m'g + kl) \end{bmatrix}$$

拉格朗日量可写为（舍去常数项）：

$$L = \frac{1}{2}(\dot{q}^T \mathbf{M} \dot{q} - q^T \mathbf{V} q), \quad q = \begin{bmatrix} \theta \\ \varphi \end{bmatrix}, \quad \dot{q} = \begin{bmatrix} \dot{\theta} \\ \dot{\varphi} \end{bmatrix}$$

久期方程为：

$$| -\mathbf{M}\omega^2 + \mathbf{V} | = 0$$

解得：

$$\omega_1^2 = \frac{g}{l}, \quad \omega_2^2 = \frac{g}{l} + \frac{m+m'}{mm'}k$$

于是简正频率为：

$$\omega_1 = \sqrt{\frac{g}{l}}, \quad \omega_2 = \sqrt{\frac{g}{l} + \frac{m+m'}{mm'}k}$$

将简正频率代回方程  $[-\mathbf{M}\omega^2 + \mathbf{V}]\eta(\omega^2) = \mathbf{0}$ ，得：

$$\eta_1 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}, \quad \eta_2 = \begin{bmatrix} \frac{m'}{\sqrt{m^2+m'^2}} \\ \frac{-m}{\sqrt{m^2+m'^2}} \end{bmatrix}$$

(c)

$$\begin{bmatrix} \tilde{\theta} \\ \tilde{\varphi} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{m'}{\sqrt{m^2+m'^2}} \\ \frac{1}{\sqrt{2}} & \frac{-m}{\sqrt{m^2+m'^2}} \end{bmatrix} \begin{bmatrix} A_1 e^{i\omega_1 t} \\ A_2 e^{i\omega_2 t} \end{bmatrix}$$

代入初始条件  $t = 0$  时,  $\theta = \theta_0, \varphi = 0$ ，得：

$$A_1 = \frac{\sqrt{2}m\theta_0}{m+m'}, \quad A_2 = \frac{\sqrt{m^2+m'^2}\theta_0}{m+m'}$$

于是：

$$\tilde{\theta} = \frac{m\theta_0}{m+m'}e^{i\omega_1 t} + \frac{m'\theta_0}{m+m'}e^{i\omega_2 t}, \quad \tilde{\varphi} = \frac{m\theta_0}{m+m'}e^{i\omega_1 t} - \frac{m\theta_0}{m+m'}e^{i\omega_2 t}$$

取实部，得：

$$\theta = \frac{m\theta_0}{m+m'}\cos\omega_1 t + \frac{m'\theta_0}{m+m'}\cos\omega_2 t, \quad \varphi = \frac{m\theta_0}{m+m'}\cos\omega_1 t - \frac{m\theta_0}{m+m'}\cos\omega_2 t$$

其中，

$$\omega_1 = \sqrt{\frac{g}{l}}, \quad \omega_2 = \sqrt{\frac{g}{l} + \frac{m+m'}{mm'}k}$$

当  $\frac{g}{l} \gg \frac{k}{m}, \frac{k}{m'}$ ,  $\omega_1 = \omega_2 = \omega = \sqrt{\frac{g}{l}}$ ，由辅助角公式，

$\theta$  摆幅：

$$A_\theta = \sqrt{\left(\frac{m\theta_0}{m+m'}\right)^2 + \left(\frac{m'\theta_0}{m+m'}\right)^2} = \frac{\sqrt{m^2+m'^2}\theta_0}{m+m'}$$

$\varphi$  摆幅：

$$A_\varphi = \sqrt{\left(\frac{m\theta_0}{m+m'}\right)^2 + \left(-\frac{m\theta_0}{m+m'}\right)^2} = \frac{\sqrt{2}m\theta_0}{m+m'}$$