| 求 $|\Psi_{AB}
angle=x_1|0_A,0_B
angle+x_2|0_A,1_B
angle+x_3|1_A,0_B
angle+x_4|1_A,1_B
angle$ 的约化密度矩阵 ho_A 和 ho_B

$$ho_{AB}=\ket{\Psi_{AB}}ra{\Psi_{AB}}$$

$$\begin{split} \rho_{A} &= \mathrm{Tr}_{B}(\rho_{AB}) \\ &= \langle 0_{B} | \rho_{AB} | 0_{B} \rangle + \langle 1_{B} | \rho_{AB} | 1_{B} \rangle \\ &= (|x_{1}|^{2} + |x_{2}|^{2}) |0_{A}\rangle \langle 0_{A}| + (|x_{3}|^{2} + |x_{4}|^{2}) |1_{A}\rangle \langle 1_{A}| + (x_{1}x_{3}^{*} + x_{2}x_{4}^{*}) |0_{A}\rangle \langle 1_{A}| + (x_{3}x_{1}^{*} + x_{4}x_{2}^{*}) |1_{A}\rangle \langle 0_{A}| \end{split}$$

$$\begin{split} \rho_{B} &= \mathrm{Tr}_{A}(\rho_{AB}) \\ &= \langle 0_{A} | \rho_{AB} | 0_{A} \rangle + \langle 1_{A} | \rho_{AB} | 1_{A} \rangle \\ &= (|x_{1}|^{2} + |x_{3}|^{2}) |0_{B} \rangle \langle 0_{B} | + (|x_{2}|^{2} + |x_{4}|^{2}) |1_{B} \rangle \langle 1_{B} | + (x_{1}x_{2}^{*} + x_{3}x_{4}^{*}) |0_{B} \rangle \langle 1_{B} | + (x_{2}x_{1}^{*} + x_{4}x_{3}^{*}) |1_{B} \rangle \langle 0_{B} | \end{split}$$

2

设双电子自旋态为:

$$\rho_{AB} = \alpha \left| + \frac{z}{A}, + \frac{z}{B} \right\rangle \left\langle + \frac{z}{A}, + \frac{z}{B} \right| + \left(1 - \alpha \right) \left| - \frac{z}{A}, - \frac{z}{B} \right\rangle \left\langle - \frac{z}{A}, - \frac{z}{B} \right| + \gamma \left| + \frac{z}{A}, + \frac{z}{B} \right\rangle \left\langle - \frac{z}{A}, - \frac{z}{B} \right| + \gamma^* \left| - \frac{z}{A}, - \frac{z}{B} \right\rangle \left\langle + \frac{z}{A}, + \frac{z}{B} \right|$$

求 $\hat{\sigma}_A^z$ 和 $\hat{\sigma}_A^x$ 在此态的平均值。

$$\begin{aligned} \rho_{A} &= \operatorname{Tr}_{B} \left(\rho_{AB} \right) \\ &= \left\langle +^{z}_{B} |\rho_{AB}| +^{z}_{B} \right\rangle + \left\langle -^{z}_{B} |\rho_{AB}| -^{z}_{B} \right\rangle \\ &= \alpha \left| +^{z}_{A} \right\rangle \left\langle +^{z}_{A} \right| + \left(1 - \alpha \right) \left| -^{z}_{A} \right\rangle \left\langle -^{z}_{A} \right| \end{aligned}$$

由于 $\hat{\sigma}_A^z \ket{+_A^z} = +1 \ket{+_A^z}, \hat{\sigma}_A^z \ket{-_A^z} = -\ket{-_A^z},$ 于是:

$$\hat{\sigma}_{A}^{z} \rho_{A} = \alpha \ket{+_{A}^{z}} \bra{+_{A}^{z}} - (1-\alpha) \ket{-_{A}^{z}} \bra{-_{A}^{z}}$$

 $\hat{\sigma}_A^z$ 在 ρ_{AB} 态的平均值为:

$$\begin{split} \langle \hat{\sigma}_A^z \rangle &= \operatorname{Tr}_A \left(\hat{\sigma}_A^z \rho_A \right) \\ &= \langle +_A^z | \hat{\sigma}_A^z \rho_A | +_A^z \rangle + \langle -_A^z | \hat{\sigma}_A^z \rho_A | -_A^z \rangle \\ &= 2\alpha - 1 \end{split}$$

由于:

$$\hat{\sigma}_A^x = egin{bmatrix} 0 & 1 \ 1 & 0 \end{bmatrix}, \;\;
ho_A = lpha \ket{+_A^z}ra{+_A^z} + (1-lpha)\ket{-_A^z}ra{-_A^z} = egin{bmatrix} lpha & 0 \ 0 & 1-lpha \end{bmatrix} \ \hat{\sigma}_A^x
ho_A \doteq egin{bmatrix} 0 & 1-lpha \ lpha & 0 \end{bmatrix}$$

于是 $\hat{\sigma}_A^x$ 在 ρ_{AB} 的平均值为:

$$\langle \hat{\sigma}_A^x
angle = \mathrm{Tr}_A \left(\hat{\sigma}_A^x
ho_A
ight) = 0$$

求哈密顿量
$$\hat{H}=rac{\hbar\omega_0}{2}\hat{\sigma}_z+rac{\hbar\Omega}{2}[\hat{\sigma}_+\exp(-\mathrm{i}\omega_L t)+\mathrm{h.c.}]$$
 在 $\hat{H}_0=rac{\hbar\omega_L}{2}\hat{\sigma}_z$ 的相互作用绘景的形式。
$$\hat{H}=rac{\hbar\omega_0}{2}\hat{\sigma}_z+rac{\hbar\Omega}{2}[\hat{\sigma}_+\exp(-\mathrm{i}\omega_L t)+\hat{\sigma}_-\exp(\mathrm{i}\omega_L t)]$$

$$egin{aligned} & = rac{\hbar \omega_L}{2} \hat{\sigma}_z + rac{\hbar (\omega_0 - \omega_L)}{2} \hat{\sigma}_z + rac{\hbar \Omega}{2} \left[\hat{\sigma}_+ \exp(-\mathrm{i} \omega_L t) + \hat{\sigma}_- \exp(\mathrm{i} \omega_L t)
ight] \ &= \hat{H}_0 + \hat{V}(t) \end{aligned}$$

其中,

$$\hat{H}_0 = rac{\hbar \omega_L}{2} \hat{\sigma}_z$$
 $\hat{V}(t) = rac{\hbar (\omega_0 - \omega_L)}{2} \hat{\sigma}_z + rac{\hbar \Omega}{2} \left[\hat{\sigma}_+ \exp(-\mathrm{i}\omega_L t) + \hat{\sigma}_- \exp(\mathrm{i}\omega_L t)
ight]$

 \hat{H}_0 的相互作用绘景形式:

$$egin{aligned} \hat{H}_{0,\mathcal{I}} &= \exp(\mathrm{i}\hat{H}_0 t/\hbar) \hat{H}_0 \exp(-\mathrm{i}\hat{H}_0 t/\hbar) \ &= \hat{H}_0 + rac{1}{1!} \left[\mathrm{i}\hat{H}_0 t/\hbar, \hat{H}_0
ight] + \cdots \ &= \hat{H}_0 \ &= rac{\hbar \omega_L}{2} \hat{\sigma}_z \end{aligned}$$

注意到:

$$\begin{split} \exp(\mathrm{i}\omega_L t \hat{\sigma}_z/2) \hat{\sigma}_z \exp(-\mathrm{i}\omega_L t \hat{\sigma}_z/2) &= \hat{\sigma}_z \\ \exp(\mathrm{i}\omega_L t \hat{\sigma}_z/2) \hat{\sigma}_+ \exp(-\mathrm{i}\omega_L t \hat{\sigma}_z/2) &= \hat{\sigma}_+ + [\mathrm{i}\omega_L t \hat{\sigma}_z/2, \hat{\sigma}_+] + \frac{1}{2!} [\mathrm{i}\omega_L t \hat{\sigma}_z/2, [\mathrm{i}\omega_L t \hat{\sigma}_z/2, \hat{\sigma}_+]] + \cdots \\ &= \hat{\sigma}_+ + (\mathrm{i}\omega_L t/2) \hat{\sigma}_+ + \frac{(\mathrm{i}\omega_L t/2)^2}{2!} \hat{\sigma}_+ + \cdots \\ &= [1 + (\mathrm{i}\omega_L t/2) + \frac{(\mathrm{i}\omega_L t/2)^2}{2!} + \cdots] \hat{\sigma}_+ \\ &= \exp(\mathrm{i}\omega_L t/2) \hat{\sigma}_+ \end{split}$$

同理,

$$\begin{split} \exp(\mathrm{i}\omega_L t \hat{\sigma}_z/2) \hat{\sigma}_- \exp(-\mathrm{i}\omega_L t \hat{\sigma}_z/2) &= \hat{\sigma}_- + [\mathrm{i}\omega_L t \hat{\sigma}_z/2, \hat{\sigma}_-] + \frac{1}{2!} [\mathrm{i}\omega_L t \hat{\sigma}_z/2, [\mathrm{i}\omega_L t \hat{\sigma}_z/2, \hat{\sigma}_-]] + \cdots \\ &= \hat{\sigma}_- + (-\mathrm{i}\omega_L t/2) \hat{\sigma}_- + \frac{(-\mathrm{i}\omega_L t/2)^2}{2!} \hat{\sigma}_- + \cdots \\ &= [1 + (-\mathrm{i}\omega_L t/2) + \frac{(-\mathrm{i}\omega_L t/2)^2}{2!} + \cdots] \hat{\sigma}_- \\ &= \exp(-\mathrm{i}\omega_L t/2) \hat{\sigma}_- \end{split}$$

于是可得 $\hat{V}(t)$ 的相互作用绘景形式:

$$\begin{split} \hat{V}_{\mathcal{I}}(t) &= \exp(\mathrm{i}\hat{H}_{0}t/\hbar)\hat{V}(t) \exp(-\mathrm{i}\hat{H}_{0}t/\hbar) \\ &= \exp(\mathrm{i}\omega_{L}t\hat{\sigma}_{z}/2)\hat{V}(t) \exp(-\mathrm{i}\omega_{L}t\hat{\sigma}_{z}/2) \\ &= \exp(\mathrm{i}\omega_{L}t\hat{\sigma}_{z}/2) \left\{ \frac{\hbar(\omega_{0} - \omega_{L})}{2}\hat{\sigma}_{z} + \frac{\hbar\Omega}{2} \left[\hat{\sigma}_{+} \exp(-\mathrm{i}\omega_{L}t) + \hat{\sigma}_{-} \exp(\mathrm{i}\omega_{L}t) \right] \right\} \exp(-\mathrm{i}\omega_{L}t\hat{\sigma}_{z}/2) \\ &= \frac{\hbar(\omega_{0} - \omega_{L})}{2}\hat{\sigma}_{z} + \frac{\hbar\Omega}{2} \left[\exp(\mathrm{i}\omega_{L}t/2)\hat{\sigma}_{+} \exp(-\mathrm{i}\omega_{L}t) + \exp(-\mathrm{i}\omega_{L}t/2)\hat{\sigma}_{-} \exp(\mathrm{i}\omega_{L}t) \right] \\ &= \frac{\hbar(\omega_{0} - \omega_{L})}{2}\hat{\sigma}_{z} + \frac{\hbar\Omega}{2} \left[\exp(-\mathrm{i}\omega_{L}t/2)\hat{\sigma}_{+} + \exp(\mathrm{i}\omega_{L}t/2)\hat{\sigma}_{-} \right] \\ &= \frac{\hbar(\omega_{0} - \omega_{L})}{2}\hat{\sigma}_{z} + \hbar\Omega \left[\cos(\omega_{L}t/2)\hat{\sigma}_{x} + \sin(\omega_{L}t/2)\hat{\sigma}_{y} \right] \end{split}$$

综上,

$$\begin{split} H_{\mathcal{I}} &= H_{0,\mathcal{I}} + V_{\mathcal{I}}(t) \\ &= \frac{\hbar \omega_L}{2} \hat{\sigma}_z + \frac{\hbar (\omega_0 - \omega_L)}{2} \hat{\sigma}_z + \hbar \Omega \left[\cos(\omega_L t/2) \hat{\sigma}_x + \sin(\omega_L t/2) \hat{\sigma}_y \right] \\ &= \frac{\hbar \omega_0}{2} \hat{\sigma}_z + \hbar \Omega \left[\cos(\omega_L t/2) \hat{\sigma}_x + \sin(\omega_L t/2) \hat{\sigma}_y \right] \end{split}$$

求哈密顿量 $\hat{H}=rac{\hbar\omega_0}{2}\hat{\sigma}_z+\hbar\omega\hat{a}^\dagger\hat{a}+\hbar g\hat{\sigma}_x\left(\hat{a}+\hat{a}^\dagger\right)$ 在 $\hat{H}_0=rac{\hbar\omega_0}{2}\hat{\sigma}_z+\hbar\omega\hat{a}\hat{a}^\dagger$ 的相互作用绘景的形式。

$$\hat{V}=\hbar g\hat{\sigma}_x\left(\hat{a}+\hat{a}^\dagger
ight)$$

$$\hat{H}_{0,\mathcal{I}} = \hat{H}_0 = rac{\hbar \omega_0}{2} \hat{\sigma}_z + \hbar \omega \hat{a} \hat{a}^\dagger$$

由于:

$$\left[rac{\omega_0}{2}\hat{\sigma}_z,\omega\hat{a}\hat{a}^\dagger
ight]=0$$

于是:

$$\begin{split} \exp(\mathrm{i}\hat{H}_0 t/\hbar) &= \exp\left[\mathrm{i}t\left(\frac{\omega_0}{2}\hat{\sigma}_z + \omega\hat{a}\hat{a}^\dagger\right)\right] \\ &= \exp\left[\mathrm{i}t\left(\frac{\omega_0}{2}\hat{\sigma}_z\right)\right] \exp\left[\mathrm{i}t\left(\omega\hat{a}\hat{a}^\dagger\right)\right] \end{split}$$

于是:

$$\begin{split} \frac{\hat{V}_{\mathcal{I}}(t)}{\hbar g} &= \exp(\mathrm{i} \hat{H}_0 t/\hbar) \frac{\hat{V}}{\hbar g} \exp(-\mathrm{i} \hat{H}_0 t/\hbar) \\ &= \exp\left[\mathrm{it} \left(\frac{\omega_0}{2} \hat{\sigma}_z + \omega \hat{a} \hat{a}^\dagger\right)\right] \left[\hat{\sigma}_x \left(\hat{a} + \hat{a}^\dagger\right)\right] \exp\left[-\mathrm{it} \left(\frac{\omega_0}{2} \hat{\sigma}_z + \omega \hat{a} \hat{a}^\dagger\right)\right] \\ &= \exp\left[\mathrm{it} \left(\frac{\omega_0}{2} \hat{\sigma}_z\right)\right] \exp\left[\mathrm{it} \left(\omega \hat{a} \hat{a}^\dagger\right)\right] \left[\hat{\sigma}_x \left(\hat{a} + \hat{a}^\dagger\right)\right] \exp\left[-\mathrm{it} \left(\omega \hat{a} \hat{a}^\dagger\right)\right] \exp\left[-\mathrm{it} \left(\frac{\omega_0}{2} \hat{\sigma}_z\right)\right] \\ &= \exp\left[\mathrm{it} \left(\frac{\omega_0}{2} \hat{\sigma}_z\right)\right] \hat{\sigma}_x \exp\left[-\mathrm{it} \left(\frac{\omega_0}{2} \hat{\sigma}_z\right)\right] \exp\left[\mathrm{it} \left(\omega \hat{a} \hat{a}^\dagger\right)\right] \left(\hat{a} + \hat{a}^\dagger\right) \exp\left[-\mathrm{it} \left(\omega \hat{a} \hat{a}^\dagger\right)\right] \\ &= \frac{1}{0!} \hat{\sigma}_x + \frac{1}{1!} \left[\mathrm{it} \left(\frac{\omega_0}{2} \hat{\sigma}_z\right), \hat{\sigma}_x\right] + \dots + \frac{1}{0!} \left(\hat{a} + \hat{a}^\dagger\right) + \frac{1}{1!} \left[\mathrm{it} \left(\omega \hat{a} \hat{a}^\dagger\right), \left(\hat{a} + \hat{a}^\dagger\right)\right] + \dots \\ &= \frac{1}{0!} \hat{\sigma}_x + \frac{1}{1!} \left(-t\omega_0 \hat{\sigma}_y\right) + \frac{1}{2!} \left[\mathrm{it} \left(\frac{\omega_0}{2} \hat{\sigma}_z\right), \left(-t\omega_0 \hat{\sigma}_y\right)\right] + \dots + \frac{1}{0!} \left(\hat{a} + \hat{a}^\dagger\right) + \frac{1}{1!} \mathrm{it} \omega \left(\hat{a}^\dagger - \hat{a}\right) + \frac{1}{2!} \left[\mathrm{it} \left(\omega \hat{a} \hat{a}^\dagger\right), \mathrm{it} \omega \left(\hat{a}^\dagger - \hat{a}\right)\right] + \dots \\ &= \frac{1}{0!} \hat{\sigma}_x + \frac{1}{1!} \left(-t\omega_0 \hat{\sigma}_y\right) + \frac{1}{2!} \left(-t^2\omega_0^2 \hat{\sigma}_x\right) + \frac{1}{3!} \left[\mathrm{it} \left(\frac{\omega_0}{2} \hat{\sigma}_z\right), \left(-t^2\omega_0^2 \hat{\sigma}_x\right)\right] + \dots + \frac{1}{0!} \left(\hat{a} + \hat{a}^\dagger\right) + \frac{1}{1!} \mathrm{it} \omega \left(\hat{a}^\dagger - \hat{a}\right) + \frac{1}{2!} \mathrm{it} \omega \left(\hat{a}^\dagger - \hat{a}\right) + \frac{1}{2!} \mathrm{it} \omega^2 \hat{\sigma}_z + \omega_0^2 \hat{\sigma}_z +$$

于是:

$$\begin{split} \hat{H}_{\mathcal{I}} &= \hat{H}_{0,\mathcal{I}} + \hat{V}_{\mathcal{I}}(t) \\ &= \frac{\hbar \omega_0}{2} \hat{\sigma}_z + \hbar \omega \hat{a} \hat{a}^\dagger + \hbar g \left[\cos \left(\omega_0 t \right) \hat{\sigma}_x - \sin \left(\omega_0 t \right) \hat{\sigma}_y + \mathrm{e}^{-\mathrm{i} \omega t} \hat{a} + \mathrm{e}^{\mathrm{i} \omega t} \hat{a}^\dagger \right] \end{split}$$

5

设仅存两种中微子 ν_{μ} 和 ν_{τ} ,其哈密顿量为 $\hat{H}=\sum_{j=1}^{2}E_{j}\left|\nu_{j}\right\rangle\left\langle\nu_{j}\right|$,其中 $E_{j}=\sqrt{c^{2}p^{2}+m_{j}^{2}c^{4}}$ 。已知两种中微子的状态可表示为 $\left|\nu_{\mu}\right\rangle=\cos\theta\left|\nu_{1}\right\rangle+\sin\theta\left|\nu_{2}\right\rangle$ 和 $\left|\nu_{\tau}\right\rangle=-\sin\theta\left|\nu_{1}\right\rangle+\cos\theta\left|\nu_{2}\right\rangle$,设 t=0 时刻体系产生一个 ν_{μ} ,求 t 时刻探测到 ν_{τ} 的概率。

采用薛定谔绘景, 态矢随时间演化, 哈密顿量不随时间演化。

时间演化算符为:

$$\hat{U}(t,0) = \exp(-i\hat{H}t/\hbar)$$

初态:

$$|\psi(0)\rangle = |\nu_{\mu}\rangle = \cos\theta |\nu_{1}\rangle + \sin\theta |\nu_{2}\rangle$$

演化到 t 时刻的态矢:

$$\begin{aligned} |\psi(t)\rangle &= \hat{U}(t,0) |\psi(0)\rangle \\ &= \exp(-\mathrm{i}\hat{H}t/\hbar) \left(\cos\theta |\nu_1\rangle + \sin\theta |\nu_2\rangle\right) \\ &= \exp\left(-\mathrm{i}E_1t/\hbar\right) \cos\theta |\nu_1\rangle + \exp\left(-\mathrm{i}E_2t/\hbar\right) \sin\theta |\nu_2\rangle \end{aligned}$$

t 时刻探测到 $|\nu_{\tau}\rangle = -\sin\theta |\nu_{1}\rangle + \cos\theta |\nu_{2}\rangle$ 的概率:

$$\begin{split} P &= \left| \left\langle \nu_{\tau} | \psi(t) \right\rangle \right|^2 \\ &= \left| \left(-\sin\theta \left\langle \nu_1 \right| + \cos\theta \left\langle \nu_2 \right| \right) \left(\exp\left(-\mathrm{i}E_1 t/\hbar \right) \cos\theta \left| \nu_1 \right\rangle + \exp\left(-\mathrm{i}E_2 t/\hbar \right) \sin\theta \left| \nu_2 \right\rangle \right) \right|^2 \\ &= \sin^2\theta \cos^2\theta \left[2 - 2\cos\left(\frac{E_1 - E_2}{\hbar} t \right) \right] \\ &= \sin^2(2\theta) \sin^2\left(\frac{E_1 - E_2}{2\hbar} t \right) \end{split}$$

6

体系哈密顿量 \hat{H} 不含时且具有非简并本征值 $\hbar\nu_n$ 和本征态 $|\nu_n\rangle$,物理量 \hat{A} 的本征解 $\hat{A}\,|a_m\rangle=a_m\,|a_m\rangle$ 。设 $|\Psi(0)\rangle=|\nu_1\rangle$,此时测 \hat{A} 得 a_m 的概率和总平均值为多少?; 若测得 a_m ,经 t 时间后再重复测量,再次得到 a_m 的概率为多少?

 $|\Psi(0)
angle=|
u_1
angle$,测 \hat{A} 得 a_m 的概率:

$$P = |\langle a_m | \Psi(0) \rangle|^2$$

= $|\langle a_m | \nu_1 \rangle|^2$

总平均值:

$$egin{aligned} ar{A} &= \langle \Psi(0) | \hat{A} | \Psi(0)
angle \ &= \langle
u_1 | \hat{A} |
u_1
angle \end{aligned}$$

若测得 a_m ,则 $\Psi(0)=|
u_1\rangle$ 塌缩到 $\Psi(0)=|a_m\rangle$,经时间 t 后,由于哈密顿量不含时,于是态矢演化到:

$$egin{aligned} \ket{\Psi(t)} &= \hat{U}(t,0) \ket{\Psi(0)} \ &= \exp\left(-\mathrm{i}\hat{H}t/\hbar\right)\ket{a_m} \ &= \sum_n raket{\nu_n|a_m} \exp\left(-\mathrm{i}\hat{H}t/\hbar\right)\ket{
u_n} \ &= \sum_n c_{nm} \exp(-\mathrm{i}
u_n t)\ket{
u_n}, \;\; c_{nm} &= raket{\nu_n|a_m} \end{aligned}$$

再次对 \hat{A} 进行测量,再次测得 a_m 的概率为:

$$egin{aligned} P' &= |raket{a_m|\Psi(t)}|^2 \ &= \left|\sum_n c_{nm}raket{a_m|
u_n}\exp(-\mathrm{i}
u_n t)
ight|^2 \ &= \left|\sum_n |c_{nm}|^2\exp(-\mathrm{i}
u_n t)
ight|^2 \ &= \sum_{n,l} |c_{nm}|^2|c_{lm}|^2\exp\left[\mathrm{i}\left(
u_l -
u_n
ight) t
ight] \end{aligned}$$

 σ_z 表象下,

$$\ket{\Psi} = egin{bmatrix} \cosrac{ heta}{2} \ \sinrac{ heta}{2} \end{bmatrix} \
ho = \ket{\Psi}ra{\Psi} = egin{bmatrix} \cos^2rac{ heta}{2} & \sinrac{ heta}{2}\cosrac{ heta}{2} \ \sinrac{ heta}{2}\cosrac{ heta}{2} & \sin^2rac{ heta}{2} \end{bmatrix}$$

$$\begin{split} \vec{r} &= \operatorname{Tr} \left(\rho \vec{\sigma} \right) \\ &= \operatorname{Tr} \left(\begin{bmatrix} \cos^2 \frac{\theta}{2} & \sin \frac{\theta}{2} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \cos \frac{\theta}{2} & \sin^2 \frac{\theta}{2} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \vec{e}_x + \begin{bmatrix} \cos^2 \frac{\theta}{2} & \sin \frac{\theta}{2} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \cos \frac{\theta}{2} & \sin^2 \frac{\theta}{2} \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \vec{e}_y + \begin{bmatrix} \cos^2 \frac{\theta}{2} & \sin \frac{\theta}{2} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \cos \frac{\theta}{2} & \sin^2 \frac{\theta}{2} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \vec{e}_z \right) \\ &= \sin \theta \vec{e}_x + \cos \theta \vec{e}_z \end{split}$$

8

设某二能级系统的哈密顿量为 $\hat{H}=\hbar\vec{\omega}\cdot\hat{\vec{\sigma}}=\hbar\sum_{j=x,y,z}\omega_j\hat{\sigma}_j$,求其 Bloch 矢量 $\vec{r}(t)$ 满足的动力学方程。

薛定谔绘景下密度矩阵的动力学方程为:

$$\mathrm{i}\hbar rac{\mathrm{d}
ho}{\mathrm{d}t} = [\hat{H},
ho]$$

在 $\hat{\sigma}_z$ 表象下, 二能级系统的密度矩阵 ρ 可写为:

$$ho = rac{1}{2} \left(I + ec{r}(t) \cdot ec{\sigma}
ight)$$

计算对易关系(采用爱因斯坦求和约定):

$$\begin{split} [\hat{H},\rho] &= \left[\hbar\omega_{i}\hat{\sigma}_{i},\frac{1}{2}\left(I+\vec{r}(t)\cdot\hat{\vec{\sigma}}\right)\right] \\ &= \frac{\hbar}{2}\left[\omega_{i}\hat{\sigma}_{i},r_{j}(t)\hat{\sigma}_{j}\right] \\ &= \frac{\hbar}{2}\omega_{i}r_{j}(t)\left[\hat{\sigma}_{i},\hat{\sigma_{j}}\right] \\ &= \frac{\hbar}{2}\omega_{i}r_{j}(t)\cdot2\mathrm{i}\varepsilon_{ijk}\hat{\sigma}_{k} \\ &= \mathrm{i}\hbar\varepsilon_{ijk}\omega_{i}r_{j}(t)\hat{\sigma}_{k} \\ &= \mathrm{i}\hbar\left\{\omega_{x}\left[y(t)\hat{\sigma}_{z}-z(t)\hat{\sigma}_{y}\right]+\omega_{y}\left[z(t)\hat{\omega}_{x}-x(t)\hat{\sigma}_{z}\right]+\omega_{z}\left[x(t)\hat{\sigma}_{y}-y(t)\hat{\sigma}_{x}\right]\right\} \end{split}$$

代入密度矩阵动力学方程可得 Bloch 矢量 $\vec{r}(t)=x(t)\vec{\mathrm{e}}_x+y(t)\vec{\mathrm{e}}_y+z(t)\vec{\mathrm{e}}_z$ 动力学方程:

$$rac{\mathrm{d}ec{r}(t)}{\mathrm{d}t}\cdotec{\sigma}=2\left\{\omega_x\left[y(t)\hat{\sigma}_z-z(t)\hat{\sigma}_y
ight]+\omega_y\left[z(t)\hat{\omega}_x-x(t)\hat{\sigma}_z
ight]+\omega_z\left[x(t)\hat{\sigma}_y-y(t)\hat{\sigma}_x
ight]
ight\}$$

求
$$\hat{S}\hat{J}_z\hat{S}^\dagger$$
,其中 $\hat{S}=\exp\left(-\mathrm{i}\phi\hat{J}_z/\hbar
ight)\exp\left(-\mathrm{i}\theta\hat{J}_y/\hbar
ight)$

$$\begin{split} \exp\left(-\mathrm{i}\theta\hat{J}_y/\hbar\right)\hat{J}_z\exp\left(\mathrm{i}\theta\hat{J}_y/\hbar\right) &= \hat{J}_z + \frac{1}{1!}\left[-\mathrm{i}\theta\hat{J}_y/\hbar,\hat{J}_z\right] + \cdots \\ &= \hat{J}_z + \frac{1}{1!}\left(\theta\hat{J}_x\right) + \frac{1}{2!}\left[-\mathrm{i}\theta\hat{J}_y/\hbar,\theta\hat{J}_x\right] + \cdots \\ &= \hat{J}_z + \frac{1}{1!}\left(\theta\hat{J}_x\right) + \frac{1}{2!}\left(-\theta^2\hat{J}_z\right) + \frac{1}{3!}\left[-\mathrm{i}\theta\hat{J}_y/\hbar,-\theta^2\hat{J}_z\right] + \cdots \\ &= \hat{J}_z + \frac{1}{1!}\left(\theta\hat{J}_x\right) + \frac{1}{2!}\left(-\theta^2\hat{J}_z\right) + \frac{1}{3!}\left(-\theta^3\hat{J}_x\right) + \frac{1}{4!}\left[-\mathrm{i}\theta\hat{J}_y/\hbar,-\theta^3\hat{J}_x\right] + \cdots \\ &= \hat{J}_z + \frac{1}{1!}\left(\theta\hat{J}_x\right) + \frac{1}{2!}\left(-\theta^2\hat{J}_z\right) + \frac{1}{3!}\left(-\theta^3\hat{J}_x\right) + \frac{1}{4!}\left(\theta^4\hat{J}_z\right) + \cdots \\ &= \left[1 + \frac{-\theta^2}{2!} + \frac{\theta^4}{4!} + \cdots\right]\hat{J}_z + \left[\frac{\theta}{1!} + \frac{-\theta^3}{3!} + \cdots\right]\hat{J}_x \\ &= \cos\theta\hat{J}_z + \sin\theta\hat{J}_x \\ &= \exp\left(-\mathrm{i}\phi\hat{J}_z/\hbar\right)\hat{J}_z\exp\left(\mathrm{i}\phi\hat{J}_z/\hbar\right) = \hat{J}_z \end{split}$$

$$\begin{split} \exp\left(-\mathrm{i}\phi\hat{J}_{z}/\hbar\right)\hat{J}_{x} \exp\left(\mathrm{i}\phi\hat{J}_{z}/\hbar\right) &= \hat{J}_{x} + \frac{1}{1!}\left[-\mathrm{i}\phi\hat{J}_{z}/\hbar, \hat{J}_{x}\right] + \cdots \\ &= \hat{J}_{x} + \frac{1}{1!}\left(\phi\hat{J}_{y}\right) + \frac{1}{2!}\left[-\mathrm{i}\phi\hat{J}_{z}/\hbar, \phi\hat{J}_{y}\right] + \cdots \\ &= \hat{J}_{x} + \frac{1}{1!}\left(\phi\hat{J}_{y}\right) + \frac{1}{2!}\left(-\phi^{2}\hat{J}_{x}\right) + \frac{1}{3!}\left[-\mathrm{i}\phi\hat{J}_{z}/\hbar, -\phi^{2}\hat{J}_{x}\right] + \cdots \\ &= \hat{J}_{x} + \frac{1}{1!}\left(\phi\hat{J}_{y}\right) + \frac{1}{2!}\left(-\phi^{2}\hat{J}_{x}\right) + \frac{1}{3!}\left(-\phi^{3}\hat{J}_{y}\right) + \cdots \\ &= \left[1 + \frac{1}{2!}\left(-\phi^{2}\right) + \cdots\right]\hat{J}_{x} + \left[\frac{1}{1!}\left(\phi\right) + \frac{1}{3!}\left(-\phi^{3}\right) + \cdots\right]\hat{J}_{y} \\ &= \cos\phi\hat{J}_{x} + \sin\phi\hat{J}_{y} \end{split}$$

于是:

$$\begin{split} \hat{S}\hat{J}_z\hat{S}^\dagger &= \exp\left(-\mathrm{i}\phi\hat{J}_z/\hbar\right)\exp\left(-\mathrm{i}\theta\hat{J}_y/\hbar\right)\hat{J}_z\exp\left(\mathrm{i}\theta\hat{J}_y/\hbar\right)\exp\left(\mathrm{i}\phi\hat{J}_z/\hbar\right) \\ &= \exp\left(-\mathrm{i}\phi\hat{J}_z/\hbar\right)\left(\cos\theta\hat{J}_z + \sin\theta\hat{J}_x\right)\exp\left(\mathrm{i}\phi\hat{J}_z/\hbar\right) \\ &= \cos\theta\left(\hat{J}_z\right) + \sin\theta\left(\cos\phi\hat{J}_x + \sin\phi\hat{J}_y\right) \\ &= \sin\theta\cos\phi\hat{J}_x + \sin\theta\sin\phi\hat{J}_z + \cos\theta\hat{J}_z \end{split}$$

10

在 Ramsey 谱学中,需要测量如下二能级系统哈密顿量中的频率 $\Delta:\hat{H}=-\Delta\hat{\sigma}_z$ 。为此制备系统初态 $|\Psi(0)\rangle=\frac{1}{\sqrt{2}}\left(|+_z\rangle+|-_z\rangle\right)$,并让它在 \hat{H} 支配下演化固定时间 T,然后测量 $\hat{\sigma}_x$,求测得 $+_x$ 的概率,从中解出 Δ ;如果重复该实验 N 次,计算得到 n 次 $+_x$ 的概率。

 $\hat{\sigma}_z$ 表象下,

$$|\Psi(0)
angle = rac{1}{\sqrt{2}} egin{bmatrix} 1 \ 1 \end{bmatrix}, \;\; \hat{H} = - arDelta egin{bmatrix} 1 & 0 \ 0 & -1 \end{bmatrix}$$

让 $|\Psi(0)\rangle$ 在 \hat{H} 支配下演化时间 T , 态矢演化到:

$$\begin{split} |\Psi(T)\rangle &= \exp(-\mathrm{i}\hat{H}T/\hbar) \, |\Psi(0)\rangle \\ &= \exp\left(\mathrm{i}T\Delta\hat{\sigma}_z/\hbar\right) \frac{1}{\sqrt{2}} \left(|+_z\rangle + |-_z\rangle\right) \\ &= \frac{1}{\sqrt{2}} \left[\exp\left(\mathrm{i}T\Delta/\hbar\right) |+_z\rangle + \exp\left(-\mathrm{i}T\Delta/\hbar\right) |-_z\rangle\right] \end{split}$$

 $\hat{\sigma}_z$ 表象下,

$$|+_z
angle = egin{bmatrix} 1 \ 0 \end{bmatrix}, \ \ |-_z
angle = egin{bmatrix} 0 \ 1 \end{bmatrix}, \ \ |+_x
angle = rac{1}{\sqrt{2}} egin{bmatrix} 1 \ 1 \end{bmatrix}$$

.

$$\langle +_x | +_z \rangle = \frac{1}{\sqrt{2}}, \ \langle +_x | -_z \rangle = \frac{1}{\sqrt{2}}$$

对 $\hat{\sigma}_x$ 测量, 测得 $+_x$ 的概率为:

$$\begin{split} P &= \left| \left\langle +_x | \Psi(T) \right\rangle \right|^2 \\ &= \left| \frac{1}{\sqrt{2}} \left[\exp \left(\mathrm{i} T \Delta / \hbar \right) \left\langle +_x | +_z \right\rangle + \exp \left(- \mathrm{i} T \Delta / \hbar \right) \left\langle +_x | -_z \right\rangle \right] \right|^2 \\ &= \cos^2 \left(\frac{T \Delta}{\hbar} \right) \end{split}$$

将该实验重复 N 次, n 次得到 $+_x$ 的概率为:

$$P' = C_N^n P^n (1 - P)^{N-n}$$

$$= \frac{N!}{n!(N-n)!} \cos^{2n} \left(\frac{T\Delta}{\hbar}\right) \sin^{2(N-n)} \left(\frac{T\Delta}{\hbar}\right)$$

11

求量子谐振子降算符 \hat{a} 的本征解 $\hat{a} \ket{\alpha} = \alpha \ket{\alpha}$

 \hat{a} 的本征方程:

$$\hat{a}\ket{lpha}=lpha\ket{lpha}$$

设 $|\alpha\rangle$ 可展为:

$$\ket{lpha} = \sum_n C_n \ket{n}$$

代入 \hat{a} 的本征方程得:

$$\sum_{n=1}^{\infty} C_n \sqrt{n} \ket{n-1} = \sum_{m=0}^{\infty} lpha C_m \ket{m}$$

对比得:

$$\frac{C_n}{C_{n-1}} = \frac{\alpha}{\sqrt{n}}$$

于是:

$$C_n = \frac{C_n}{C_{n-1}} \frac{C_{n-1}}{C_{n-2}} \cdots \frac{C_2}{C_1} \frac{C_1}{C_0} C_0 = \frac{\alpha^n}{\sqrt{n!}} C_0$$

由归一化条件 $\langle \alpha | \alpha \rangle = 1$ 可得:

$$|C_0|^2 \sum_{n=0}^{\infty} \frac{\left|\alpha^2\right|^n}{n!} = 1$$

即:

$$|C_0|^2\mathrm{e}^{|\alpha|^2}=1$$

实数解为:

$$C_0=\mathrm{e}^{-|lpha|^2/2}$$

综上, α 可表达为:

$$|lpha
angle = \mathrm{e}^{-|lpha|^2/2} \sum_{n=0}^{\infty} rac{lpha^n}{\sqrt{n!}} \ket{n}$$

12

证明量子谐振子降算符 \hat{a} 的本征态 |lpha
angle 可以写为 $|lpha
angle=\hat{D}(lpha)\,|0
angle$,其中 $\hat{D}(lpha)=\exp(lpha\hat{a}^\dagger-lpha^*\hat{a})$

注意到 $\hat{D}^{\dagger}(\alpha)$ 是幺正的:

$$\begin{split} \hat{D}^{\dagger}(\alpha)\hat{D}(\alpha) &= \exp\left(\alpha^{*}\hat{a} - \alpha\hat{a}^{\dagger}\right) \exp\left(\alpha\hat{a}^{\dagger} - \alpha^{*}\hat{a}\right) \\ &= \exp\left(\left[\alpha^{*}\hat{a} - \alpha\hat{a}^{\dagger}\right] + \left[\alpha\hat{a}^{\dagger} - \alpha^{*}\hat{a}\right] + \frac{1}{2}\left[\alpha^{*}\hat{a} - \alpha\hat{a}^{\dagger}, \alpha\hat{a}^{\dagger} - \alpha^{*}\hat{a}\right] + \cdots\right) \\ &= \hat{I} \\ \hat{D}^{\dagger}(\alpha)\hat{a}\hat{D}(\alpha) &= \exp\left(\alpha^{*}\hat{a} - \alpha\hat{a}^{\dagger}\right)\hat{a} \exp\left(\alpha\hat{a}^{\dagger} - \alpha^{*}\hat{a}\right) \\ &= \hat{a} + \frac{1}{1!}\left[\alpha^{*}\hat{a} - \alpha\hat{a}^{\dagger}, \hat{a}\right] + \cdots \\ &= \hat{a} + \frac{1}{1!}\alpha + \frac{1}{2!}\left[\alpha^{*}\hat{a} - \alpha\hat{a}^{\dagger}, \alpha\right] + \cdots \\ &= \hat{a} + \alpha \end{split}$$

两边左乘 $\hat{D}(\alpha)$ 得:

$$\hat{a}\hat{D}(\alpha) = \hat{D}(\alpha)(\hat{a} + \alpha)$$

同时作用在真空态上:

$$\hat{a}\hat{D}(lpha)\ket{0}=\hat{D}(lpha)\left(\hat{a}+lpha
ight)\ket{0}=lpha\hat{D}(lpha)\ket{0}$$

即:

$$\hat{a}\left(\hat{D}(lpha)\ket{0}
ight)=lpha\left(\hat{D}(lpha)\ket{0}
ight)$$

与 \hat{a} 的本征方程 $\hat{a} | \alpha \rangle = \alpha | \alpha \rangle$ 比较,结合归—化条件,得:

$$\hat{D}(\alpha)|0\rangle = |\alpha\rangle$$

求
$$\hat{S}^{\dagger}\hat{a}\hat{S}$$
,其中 $\hat{S}=\exp\left[rac{1}{2}\left(\xi^{*}\hat{a}^{2}-\xi\hat{a}^{\dagger2}
ight)
ight]$ 与 $\xi=r\mathrm{e}^{\mathrm{i} heta}$

$$\begin{split} \hat{S}^{\dagger}\hat{a}\hat{S} &= \exp\left[\frac{1}{2}\left(\xi\hat{a}^{\dagger2} - \xi^{*}\hat{a}^{2}\right)\right]\hat{a}\exp\left[\frac{1}{2}\left(\xi^{*}\hat{a}^{2} - \xi\hat{a}^{\dagger2}\right)\right] \\ &= \frac{1}{0!}\hat{a} + \frac{1}{1!}\left[\frac{1}{2}\left(\xi\hat{a}^{\dagger2} - \xi^{*}\hat{a}^{2}\right),\hat{a}\right] + \cdots \\ &= \frac{1}{0!}\hat{a} + \frac{1}{1!}\left(-\xi\hat{a}^{\dagger}\right) + \frac{1}{2!}\left[\frac{1}{2}\left(\xi\hat{a}^{\dagger2} - \xi^{*}\hat{a}^{2}\right), -\xi\hat{a}^{\dagger}\right] + \cdots \\ &= \frac{1}{0!}\hat{a} + \frac{1}{1!}\left(-\xi\hat{a}^{\dagger}\right) + \frac{1}{2!}\left(\xi^{*}\xi\hat{a}\right) + \frac{1}{3!}\left[\frac{1}{2}\left(\xi\hat{a}^{\dagger2} - \xi^{*}\hat{a}^{2}\right), \xi^{*}\xi\hat{a}\right] + \cdots \\ &= \frac{1}{0!}\hat{a} + \frac{1}{1!}\left(-\xi\hat{a}^{\dagger}\right) + \frac{1}{2!}\left(\xi^{*}\xi\hat{a}\right) + \frac{1}{3!}\left(-\xi\xi^{*}\xi\hat{a}^{\dagger}\right) + \frac{1}{4!}\left[\frac{1}{2}\left(\xi\hat{a}^{\dagger2} - \xi^{*}\hat{a}^{2}\right), -\xi\xi^{*}\xi\hat{a}^{\dagger}\right] + \cdots \\ &= \frac{1}{0!}\hat{a} + \frac{1}{1!}\left(-\xi\hat{a}^{\dagger}\right) + \frac{1}{2!}\left(\xi^{*}\xi\hat{a}\right) + \frac{1}{3!}\left(-\xi\xi^{*}\xi\hat{a}^{\dagger}\right) + \frac{1}{4!}\left(\xi^{*}\xi\xi^{*}\xi\hat{a}\right) + \frac{1}{5!}\left[\frac{1}{2}\left(\xi\hat{a}^{\dagger2} - \xi^{*}\hat{a}^{2}\right), \xi^{*}\xi\xi^{*}\xi\hat{a}\right] + \cdots \\ &= \frac{1}{0!}\hat{a} + \frac{1}{1!}\left(-\xi\hat{a}^{\dagger}\right) + \frac{1}{2!}\left(\xi^{*}\xi\hat{a}\right) + \frac{1}{3!}\left(-\xi\xi^{*}\xi\hat{a}^{\dagger}\right) + \frac{1}{4!}\left(\xi^{*}\xi\xi^{*}\xi\hat{a}\right) + \frac{1}{5!}\left(-\xi\xi^{*}\xi\xi^{*}\xi\hat{a}^{\dagger}\right) + \cdots \\ &= \left[\frac{1}{0!}|\xi|^{0} + \frac{1}{2!}|\xi|^{2} + \frac{1}{4!}|\xi|^{4} + \cdots\right]\hat{a} + \left[\frac{1}{1!}|\xi|^{0} + \frac{1}{3!}|\xi|^{2} + \frac{1}{5!}|\xi|^{4} + \cdots\right]\left(-\xi\hat{a}^{\dagger}\right) \\ &= \left[\frac{1}{0!}|\xi|^{0} + \frac{1}{2!}|\xi|^{2} + \frac{1}{4!}|\xi|^{4} + \cdots\right]\hat{a} + \left[\frac{1}{1!}|\xi|^{1} + \frac{1}{3!}|\xi|^{3} + \frac{1}{5!}|\xi|^{5} + \cdots\right]\left(-\frac{\xi}{|\xi|}\hat{a}^{\dagger}\right) \\ &= \left(\cosh|\xi|\right)\hat{a} + \left(\sinh|\xi|\right)\left(-\frac{\xi}{|\xi|}\hat{a}^{\dagger}\right) \\ &= \left(\cosh|\xi|\right)\hat{a} - \left(\sinh|\xi|\right)\left(-\frac{\xi}{|\xi|}\hat{a}^{\dagger}\right) \end{split}$$

14

用 Peres-Horodecki 判据判断如下态是纠缠态的条件,其中
$$0\leqslant\lambda\leqslant1$$
, $|\Psi_\pm
angle=rac{|01
angle\pm|10
angle}{\sqrt{2}}, |\Phi_\pm
angle=rac{|00
angle\pm|11
angle}{\sqrt{2}}$

$$ho_{1}=\lambda\ket{\Phi_{+}}ra{\Phi_{+}}+\left(1-\lambda
ight)\ket{\Psi_{+}}ra{\Psi_{+}}$$

$$ho_{2}=\left(1-\lambda
ight)\left|\Psi_{-}
ight
angle \left\langle \Psi_{-}
ight|+\lambda\left|11
ight
angle \left\langle 11
ight|$$

$$\left|
ight.
ho_{3} = \lambda \left| \Psi_{-}
ight
angle \left\langle \Psi_{-}
ight| + rac{1-\lambda}{3} (\left| \Psi_{+}
ight
angle \left\langle \Psi_{+}
ight| + \left| \Phi_{+}
ight
angle \left\langle \Phi_{+}
ight| + \left| \Phi_{-}
ight
angle \left\langle \Phi_{-}
ight|)$$

以 $\{|00\rangle, |01\rangle, |10\rangle, |11\rangle\}$ 为基,

$$\ket{\Psi_+}ra{\Psi_+} = rac{1}{2}egin{bmatrix} 0 & 0 & 0 & 0 \ 0 & 1 & 1 & 0 \ 0 & 1 & 1 & 0 \ 0 & 0 & 0 & 0 \end{bmatrix}, \; \ket{\Psi_-}ra{\Psi_-} = rac{1}{2}egin{bmatrix} 0 & 0 & 0 & 0 \ 0 & 1 & -1 & 0 \ 0 & -1 & 1 & 0 \ 0 & 0 & 0 & 0 \end{bmatrix},$$
 $\begin{bmatrix} 1 & 0 & 0 & -1 \end{bmatrix}$

$$\ket{\Phi_+}ra{\Phi_+} = rac{1}{2}egin{bmatrix} 1 & 0 & 0 & 1 \ 0 & 0 & 0 & 0 \ 0 & 0 & 0 & 0 \ 1 & 0 & 0 & 1 \end{bmatrix}, \;\; \ket{\Phi_-}ra{\Phi_-} = rac{1}{2}egin{bmatrix} 1 & 0 & 0 & -1 \ 0 & 0 & 0 & 0 \ 0 & 0 & 0 & 0 \ -1 & 0 & 0 & 1 \end{bmatrix},$$

$$ho_{1}=\lambda\ket{\Phi_{+}}ra{\Phi_{+}}+\left(1-\lambda
ight)\ket{\Psi_{+}}ra{\Psi_{+}} \ =egin{bmatrix} rac{\lambda}{2} & 0 & 0 & rac{\lambda}{2} \ 0 & rac{1-\lambda}{2} & rac{1-\lambda}{2} & 0 \ 0 & rac{1-\lambda}{2} & rac{1-\lambda}{2} & 0 \ rac{\lambda}{2} & 0 & 0 & rac{\lambda}{2} \end{bmatrix}$$

部分转置:

$$ho_1^{T_B} = egin{bmatrix} rac{\lambda}{2} & 0 & 0 & rac{1-\lambda}{2} \ 0 & rac{1-\lambda}{2} & rac{\lambda}{2} & 0 \ 0 & rac{\lambda}{2} & rac{1-\lambda}{2} & 0 \ rac{1-\lambda}{2} & 0 & 0 & rac{\lambda}{2} \end{bmatrix}$$

利用 Mathematica, 可以解得 $\rho_1^{T_B}$ 的本征值为:

$$\lambda'_{1,2,3,4} = rac{1}{2}, rac{1}{2}, rac{1-2\lambda}{2}, rac{-1+2\lambda}{2}$$

当 $\lambda=\frac{1}{2}$, ho_1 不是纠缠态; 当 $0\leqslant\lambda\leqslant1,\lambda
eqrac{1}{2}$, ho_1 是纠缠态。

$$egin{aligned}
ho_2 &= (1-\lambda)\ket{\Psi_-}ra{\Psi_-}+\lambda\ket{11}ra{11} \ &= egin{bmatrix} 0 & 0 & 0 & 0 \ 0 & rac{1-\lambda}{2} & rac{\lambda-1}{2} & 0 \ 0 & rac{\lambda-1}{2} & rac{1-\lambda}{2} & 0 \ 0 & 0 & 0 & \lambda \end{bmatrix} \end{aligned}$$

部分转置:

$$ho_2^{T_B} = egin{bmatrix} 0 & 0 & 0 & rac{\lambda-1}{2} \ 0 & rac{1-\lambda}{2} & 0 & 0 \ 0 & 0 & rac{1-\lambda}{2} & 0 \ rac{\lambda-1}{2} & 0 & 0 \ \end{pmatrix} \ rac{\lambda-1}{2} & 0 & 0 & \lambda \ \end{pmatrix}$$

利用 Mathematica,可以解得 $ho_2^{T_B}$ 的特征值为:

$$\lambda_{1,2,3,4}'=\frac{1-\lambda}{2},\frac{1-\lambda}{2},\frac{\lambda-\sqrt{1-2\lambda+2\lambda^2}}{2},\frac{\lambda+\sqrt{1-2\lambda+2\lambda^2}}{2}$$

当 $0 \leqslant \lambda \leqslant 1$,四个本征值 $\lambda'_{1,2,3,4} \geqslant 0$,因此 ρ_2 不是纠缠态。

$$\begin{split} \rho_{3} &= \lambda \left| \Psi_{-} \right\rangle \left\langle \Psi_{-} \right| + \frac{1 - \lambda}{3} (\left| \Psi_{+} \right\rangle \left\langle \Psi_{+} \right| + \left| \Phi_{+} \right\rangle \left\langle \Phi_{+} \right| + \left| \Phi_{-} \right\rangle \left\langle \Phi_{-} \right|) \\ &= \begin{bmatrix} \frac{1 - \lambda}{3} & 0 & 0 & 0 \\ 0 & \frac{1 + 2\lambda}{6} & \frac{1 - 4\lambda}{6} & 0 \\ 0 & \frac{1 - 4\lambda}{6} & \frac{1 + 2\lambda}{6} & 0 \\ 0 & 0 & 0 & \frac{1 - \lambda}{3} \end{bmatrix} \end{split}$$

部分转置 $\rho_3^{T_B}$ 为:

$$ho_3^{T_B} = egin{bmatrix} rac{1-\lambda}{3} & 0 & 0 & rac{1-4\lambda}{6} \ 0 & rac{1+2\lambda}{6} & 0 & 0 \ 0 & 0 & rac{1+2\lambda}{6} & 0 \ rac{1-4\lambda}{6} & 0 & 0 & rac{1-2\lambda}{6} \ \end{pmatrix}$$

利用 Mathematica, 可以解得本征值为:

$$\lambda'_{1,2,3,4} = rac{1-2\lambda}{2}, rac{1+2\lambda}{6}, rac{1+2\lambda}{6}, rac{1+2\lambda}{6}$$

当 $0 \leqslant \lambda \leqslant \frac{1}{2}$, ho_3 不是纠缠态; 当 $\frac{1}{2} < \lambda \leqslant 1$, ho_3 是纠缠态。

15

定义量子谐振子的两个正交分量 $\hat{X}_1=rac{\hat{a}+\hat{a}^\dagger}{2}$ 和 $\hat{X}_2=rac{\hat{a}-\hat{a}^\dagger}{2i}$,求在降算符本征态 $|lpha\rangle$ 的 $\Delta\hat{X}_{ heta}$,其中 $\hat{X}_{ heta}=\cos heta\hat{X}_1+\sin heta\hat{X}_2$

$$\begin{split} \hat{X}_{\theta} &= \cos\theta \hat{X}_1 + \sin\theta \hat{X}_2 \\ &= \cos\theta \frac{\hat{a} + \hat{a}^{\dagger}}{2} + \sin\theta \frac{\hat{a} - \hat{a}^{\dagger}}{2\mathrm{i}} \\ &= \left(\frac{\cos\theta}{2} + \frac{\sin\theta}{2\mathrm{i}}\right) \hat{a} + \left(\frac{\cos\theta}{2} - \frac{\sin\theta}{2\mathrm{i}}\right) \hat{a}^{\dagger} \\ &= \frac{\cos\theta - \mathrm{i}\sin\theta}{2} \hat{a} + \frac{\cos\theta + \mathrm{i}\sin\theta}{2} \hat{a}^{\dagger} \\ &= \frac{1}{2} \mathrm{e}^{-\mathrm{i}\theta} \hat{a} + \frac{1}{2} \mathrm{e}^{\mathrm{i}\theta} \hat{a}^{\dagger} \end{split}$$

$$egin{aligned} \hat{X}_{ heta}^2 &= \left(rac{1}{2}\mathrm{e}^{-\mathrm{i} heta}\hat{a} + rac{1}{2}\mathrm{e}^{\mathrm{i} heta}\hat{a}^\dagger
ight)^2 \ &= rac{1}{4}\mathrm{e}^{-\mathrm{i}2 heta}\hat{a}^2 + rac{1}{4}\mathrm{e}^{\mathrm{i}2 heta}\hat{a}^{\dagger2} + rac{1}{4}\left(\hat{a}\hat{a}^\dagger + \hat{a}^\dagger\hat{a}
ight) \end{aligned}$$

$$\hat{a}\left|\alpha\right>=\alpha\left|\alpha\right>,\ \left<\alpha\right|\hat{a}^{\dagger}=\alpha^{*}\left<\alpha\right|,\ \left[\hat{a},\hat{a}^{\dagger}\right]=1\Longrightarrow\hat{a}\hat{a}^{\dagger}=\hat{a}^{\dagger}\hat{a}+1$$

在 $|\alpha\rangle$ 态下 \hat{X}_{θ} 的平均值:

$$\begin{split} \left\langle \hat{X}_{\theta} \right\rangle &= \left\langle \alpha \, \middle| \, \hat{X}_{\theta} \, \middle| \, \alpha \right\rangle \\ &= \left\langle \alpha \, \middle| \, \frac{1}{2} \mathrm{e}^{-\mathrm{i}\theta} \hat{a} + \frac{1}{2} \mathrm{e}^{\mathrm{i}\theta} \hat{a}^{\dagger} \, \middle| \, \alpha \right\rangle \\ &= \frac{1}{2} \mathrm{e}^{-\mathrm{i}\theta} \alpha + \frac{1}{2} \mathrm{e}^{\mathrm{i}\theta} \alpha^{*} \end{split}$$

在 $|\alpha\rangle$ 态下 \hat{X}^2_{θ} 的平均值:

$$\begin{split} \left\langle \hat{X}_{\theta}^{2} \right\rangle &= \left\langle \alpha \left| \frac{1}{4} \mathrm{e}^{-\mathrm{i}2\theta} \hat{a}^{2} + \frac{1}{4} \mathrm{e}^{\mathrm{i}2\theta} \hat{a}^{\dagger 2} + \frac{1}{4} \left(\hat{a} \hat{a}^{\dagger} + \hat{a}^{\dagger} \hat{a} \right) \right| \alpha \right\rangle \\ &= \left\langle \alpha \left| \frac{1}{4} \mathrm{e}^{-\mathrm{i}2\theta} \hat{a}^{2} + \frac{1}{4} \mathrm{e}^{\mathrm{i}2\theta} \hat{a}^{\dagger 2} + \frac{1}{4} \left(\hat{a}^{\dagger} \hat{a} + 1 + \hat{a}^{\dagger} \hat{a} \right) \right| \alpha \right\rangle \\ &= \frac{1}{4} \mathrm{e}^{-\mathrm{i}2\theta} \alpha^{2} + \frac{1}{4} \mathrm{e}^{\mathrm{i}2\theta} \alpha^{*2} + \frac{1}{2} |\alpha|^{2} + \frac{1}{4} \end{split}$$

在 $|\alpha\rangle$ 态下 \hat{X}_{θ} 的不确定度:

$$\begin{split} \Delta \hat{X}_{\theta} &= \sqrt{\left\langle \hat{X}_{\theta}^2 \right\rangle - \left\langle \hat{X}_{\theta} \right\rangle^2} \\ &= \sqrt{\frac{1}{4} \mathrm{e}^{-\mathrm{i}2\theta} \alpha^2 + \frac{1}{4} \mathrm{e}^{\mathrm{i}2\theta} \alpha^{*2} + \frac{1}{2} |\alpha|^2 + \frac{1}{4} - \left(\frac{1}{2} \mathrm{e}^{-\mathrm{i}\theta} \alpha + \frac{1}{2} \mathrm{e}^{\mathrm{i}\theta} \alpha^* \right)^2} \\ &= \frac{1}{2} \end{split}$$

16

求
$$|\Psi
angle=\sum_{i,j=0}^{1}a_{ij}\left|ij
ight>$$
 的 von Neumann 熵,其中 $\sum_{i,j=0}^{1}\left|a_{ij}
ight|^{2}=1$

以 $\{|00\rangle, |01\rangle, |10\rangle, |11\rangle\}$ 为基,密度矩阵可写为:

$$egin{aligned}
ho &= |\Psi
angle \left\langle \Psi
ight| \ &= egin{bmatrix} |a_{00}|^2 & a_{00}a_{01}^* & a_{00}a_{10}^* & a_{00}a_{11}^* \ a_{01}a_{00}^* & |a_{01}|^2 & a_{01}a_{10}^* & a_{01}a_{11}^* \ a_{10}a_{00}^* & a_{10}a_{01}^* & |a_{10}|^2 & a_{10}a_{11}^* \ a_{11}a_{00}^* & a_{11}a_{01}^* & a_{11}a_{10}^* & |a_{11}|^2 \end{bmatrix} \end{aligned}$$

利用 Mathematica, 可以解得其本征值分别为:

$$\lambda_1 = \lambda_2 = \lambda_3 = 0, \;\; \lambda_4 = |a_{00}|^2 + |a_{01}|^2 + |a_{10}|^2 + |a_{11}|^2 = 1$$

因此 ρ 可化为:

$$\rho = PDP^{-1}$$

其中,

$$D = \text{diag}(0, 0, 0, 1)$$

von Neumann 熵 为:

$$\begin{split} S &= -\text{Tr} \left(\rho \ln \rho \right) \\ &= -\text{Tr} \left(PDP^{-1}P \ln DP^{-1} \right) \\ &= -\text{Tr} \left(PD \ln DP^{-1} \right) \\ &= -\text{Tr} \left(D \ln DP^{-1}P \right) \\ &= -\text{Tr} \left(D \ln D \right) \\ &= -\text{Tr} \left[\text{diag} \left(0, 0, 0, 1 \right) \text{diag} \left(-\infty, -\infty, -\infty, 0 \right) \right] \\ &= -\text{Tr} \left[\text{diag} \left(0, 0, 0, 0 \right) \right] \\ &= 0 \end{split}$$

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求以下状态的 Concurrence:(1) Bell 态: $|\Psi_+\rangle=\frac{|01\rangle+|10\rangle}{\sqrt{2}}$;(2) Werner 态: $\rho_{\mathrm{W}}=p\,|\Psi_+\rangle\,\langle\Psi_+|+(1-p)\frac{I_{4\times4}}{4}$,其中 $I_{4\times4}$ 为四维单位矩阵。

(1)

 $\{|00\rangle, |01\rangle, |10\rangle, |11\rangle\}$ 基矢下,

$$ho_{AB} = \ket{\Psi_+}ra{\Psi_+} \ = rac{1}{2}egin{bmatrix} 0 & 0 & 0 & 0 \ 0 & 1 & 1 & 0 \ 0 & 1 & 1 & 0 \ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\sigma_y \otimes \sigma_y = egin{bmatrix} 0 & -\mathrm{i} \ \mathrm{i} & 0 \end{bmatrix} \otimes \sigma_y \ &= egin{bmatrix} 0\sigma_y & -\mathrm{i}\sigma_y \ \mathrm{i}\sigma_y & 0\sigma_y \end{bmatrix} \ &= egin{bmatrix} 0 & 0 & 0 & -1 \ 0 & 0 & 1 & 0 \ 0 & 1 & 0 & 0 \ -1 & 0 & 0 & 0 \end{bmatrix}$$

利用 Mathematica 计算可得, $ho_{AB}\left(\sigma_{y}\otimes\sigma_{y}
ho_{AB}^{*}\sigma_{y}\otimes\sigma_{y}\right)$ 的本征值为:

$$\lambda'_{1,2,3,4} = 1, 0, 0, 0$$

本征值的平方根为:

$$\lambda_{1,2,3,4} = \sqrt{\lambda'_{1,2,3,4}} = 1,0,0,0$$

Concurrence 为:

$$C = \max\{0, \lambda_1 - \lambda_2 - \lambda_3 - \lambda_4\} = 1$$

(2)

 $\{\left|00\right\rangle,\left|01\right\rangle,\left|10\right\rangle,\left|11\right\rangle\}$ 基矢下,

$$ho_{\mathrm{W}} = p \ket{\Psi_{+}} ra{\Psi_{+}} + (1-p) rac{I_{4 imes 4}}{4} \ = egin{bmatrix} rac{1-p}{4} & 0 & 0 & 0 \ 0 & rac{1+p}{4} & rac{p}{2} & 0 \ 0 & rac{p}{2} & rac{1+p}{4} & 0 \ 0 & 0 & 0 & rac{1-p}{4} \end{bmatrix}$$

利用 Mathematica 计算可得, $\rho_{\mathrm{W}}\left(\sigma_{y}\otimes\sigma_{y}\rho_{\mathrm{W}}^{*}\sigma_{y}\otimes\sigma_{y}\right)$ 的本征值为:

$$\lambda_{1,2,3,4}' = \frac{(3p+1)^2}{16}, \frac{(p-1)^2}{16}, \frac{(p-1)^2}{16}, \frac{(p-1)^2}{16}$$

本征值的平方根为:

$$\begin{split} \lambda_{1,2,3,4} &= \sqrt{\lambda_{1,2,3,4}'} = \frac{3p+1}{4}, \frac{1-p}{4}, \frac{1-p}{4}, \frac{1-p}{4} \\ C &= \max\left\{0, \frac{3p+1}{4} - 3 \times \frac{1-p}{4}\right\} \\ &= \max\left\{0, \frac{3p-1}{2}\right\} \\ &= \begin{cases} 0 &, \ 0 \leqslant p \leqslant \frac{1}{3} \\ \frac{3p-1}{2} &, \ \frac{1}{3}$$

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两种电子自旋处于 $\left|\Psi^{AB}\right>=rac{1}{\sqrt{2}}\left(\left|+_{z}^{A}-_{z}^{B}\right>-\left|-_{z}^{A}+_{z}^{B}\right>
ight)$

(1) 先后测量 \hat{S}_z^A 和 \hat{S}_z^B , 测值和概率为多少?

先测量 \hat{S}_z^A ,测得 $+\hbar/2$ 的概率为 1/2,测得 $-\hbar/2$ 的概率为 1/2。

若测得 \hat{S}_z^A 测值为 $+\hbar/2$ 后对 \hat{S}_z^B 进行测量,测得 \hat{S}_z^B 测值 $-\hbar/2$ 的概率为 1

若测得 \hat{S}_z^A 测值为 $-\hbar/2$ 后对 \hat{S}_z^B 进行测量,测得 \hat{S}_z^B 测值 $+\hbar/2$ 的概率为 1

(2) 先后测量 \hat{S}_x^A 和 \hat{S}_x^B , 测值和概率为多少?

由于:

$$\begin{aligned} \left| + {}_{z}^{A} \right\rangle &= \frac{1}{\sqrt{2}} \left(\left| + {}_{x}^{A} \right\rangle + \left| - {}_{x}^{A} \right\rangle \right), \ \left| - {}_{z}^{A} \right\rangle &= \frac{1}{\sqrt{2}} \left(\left| + {}_{x}^{A} \right\rangle - \left| - {}_{x}^{A} \right\rangle \right) \\ \left| + {}_{z}^{B} \right\rangle &= \frac{1}{\sqrt{2}} \left(\left| + {}_{x}^{B} \right\rangle + \left| - {}_{x}^{B} \right\rangle \right), \ \left| - {}_{z}^{B} \right\rangle &= \frac{1}{\sqrt{2}} \left(\left| + {}_{x}^{B} \right\rangle - \left| - {}_{x}^{B} \right\rangle \right) \end{aligned}$$

于是:

$$\begin{split} \left| \Psi^{AB} \right\rangle &= \frac{1}{\sqrt{2}} \left(\left| +_z^A -_z^B \right\rangle - \left| -_z^A +_z^B \right\rangle \right) \\ &= \frac{1}{\sqrt{2}} \left[\frac{1}{\sqrt{2}} \left(\left| +_x^A \right\rangle + \left| -_x^A \right\rangle \right) \otimes \frac{1}{\sqrt{2}} \left(\left| +_x^B \right\rangle - \left| -_x^B \right\rangle \right) - \frac{1}{\sqrt{2}} \left(\left| +_x^A \right\rangle - \left| -_x^A \right\rangle \right) \otimes \frac{1}{\sqrt{2}} \left(\left| +_x^B \right\rangle + \left| -_x^B \right\rangle \right) \right] \\ &= \frac{1}{\sqrt{2}} \left(\left| -_x^A +_x^B \right\rangle - \left| +_x^A -_x^B \right\rangle \right) \end{split}$$

先测量 \hat{S}_x^A ,测得 $+\hbar/2$ 的概率为 1/2,测得 $-\hbar/2$ 的概率为 1/2。

若测得 \hat{S}^A_x 测值为 $+\hbar/2$ 后对 \hat{S}^B_x 进行测量,测得 \hat{S}^B_x 测值 $-\hbar/2$ 的概率为 1

若测得 \hat{S}^A_x 测值为 $-\hbar/2$ 后对 \hat{S}^B_x 进行测量,测得 \hat{S}^B_x 测值 $+\hbar/2$ 的概率为 1

(3) 先后测量 \hat{S}_n^A 和 \hat{S}_n^B ,测值和概率为多少?其中, $\hat{S}_n = \vec{n} \cdot \hat{\vec{S}}, \vec{n} = \sin \theta \cos \varphi \vec{e}_x + \sin \theta \sin \varphi \vec{e}_y + \cos \theta \vec{e}_z$ 在 $\hat{\sigma}_z$ 表象下,

$$egin{aligned} \hat{\sigma}_n &= ec{n} \cdot \hat{ec{\sigma}} \ &= \sin heta \cos arphi \hat{\sigma}_x + \sin heta \sin arphi \hat{\sigma}_y + \cos heta \hat{\sigma}_z \ &= egin{bmatrix} \cos heta & \sin heta \mathrm{e}^{-\mathrm{i}arphi} \ \sin heta \mathrm{e}^{\mathrm{i}arphi} & -\cos heta \end{bmatrix} \end{aligned}$$

 $\hat{\sigma}_n$ 的两个本征态 $|+_n\rangle$ 和 $|-_n\rangle$ 在 $\hat{\sigma}_z$ 表象下的表示为:

$$|+_n\rangle = \begin{bmatrix} \cos\frac{\theta}{2} \\ \sin\frac{\theta}{2} \mathrm{e}^{\mathrm{i}\varphi} \end{bmatrix}, \ |-_n\rangle = \begin{bmatrix} \sin\frac{\theta}{2} \\ -\cos\frac{\theta}{2} \mathrm{e}^{\mathrm{i}\varphi} \end{bmatrix}$$

即:

$$\begin{cases} \left| +_{n} \right\rangle = \cos\frac{\theta}{2} \left| +_{z} \right\rangle + \sin\frac{\theta}{2} \mathrm{e}^{\mathrm{i}\varphi} \left| -_{z} \right\rangle \\ \left| -_{n} \right\rangle = \sin\frac{\theta}{2} \left| +_{z} \right\rangle - \cos\frac{\theta}{2} \mathrm{e}^{\mathrm{i}\varphi} \left| -_{z} \right\rangle \end{cases} \Longrightarrow \begin{cases} \left| +_{z} \right\rangle = \cos\frac{\theta}{2} \left| +_{n} \right\rangle + \sin\frac{\theta}{2} \left| -_{n} \right\rangle \\ \left| -_{z} \right\rangle = \sin\frac{\theta}{2} \mathrm{e}^{-\mathrm{i}\varphi} \left| +_{n} \right\rangle - \cos\frac{\theta}{2} \mathrm{e}^{-\mathrm{i}\varphi} \left| -_{n} \right\rangle \end{cases}$$

于是:

$$\begin{split} \left| \Psi^{AB} \right\rangle &= \frac{1}{\sqrt{2}} \left(\left| +_z^A -_z^B \right\rangle - \left| -_z^A +_z^B \right\rangle \right) \\ &= \frac{1}{\sqrt{2}} \left[\left(\cos \frac{\theta}{2} \left| +_n^A \right\rangle + \sin \frac{\theta}{2} \left| -_n^A \right\rangle \right) \otimes \left(\sin \frac{\theta}{2} \mathrm{e}^{-\mathrm{i}\varphi} \left| +_n^B \right\rangle - \cos \frac{\theta}{2} \mathrm{e}^{-\mathrm{i}\varphi} \left| -_n^B \right\rangle \right) - \left(\sin \frac{\theta}{2} \mathrm{e}^{-\mathrm{i}\varphi} \left| +_n^A \right\rangle - \cos \frac{\theta}{2} \mathrm{e}^{-\mathrm{i}\varphi} \left| -_n^A \right\rangle \right) \otimes \left(\cos \frac{\theta}{2} \left| +_n^B \right\rangle - \left| +_n^A -_n^B \right\rangle \right) \\ &= \frac{\mathrm{e}^{-\mathrm{i}\varphi}}{\sqrt{2}} \left(\left| -_n^A +_n^B \right\rangle - \left| +_n^A -_n^B \right\rangle \right) \end{split}$$

先测量 \hat{S}_n^A ,测得 $+\hbar/2$ 的概率为 1/2,测得 $-\hbar/2$ 的概率为 1/2。

若测得 \hat{S}_n^A 测值为 $+\hbar/2$ 后对 \hat{S}_n^B 进行测量,测得 \hat{S}_n^B 测值 $-\hbar/2$ 的概率为 1

若测得 \hat{S}_n^A 测值为 $-\hbar/2$ 后对 \hat{S}_n^B 进行测量,测得 \hat{S}_n^B 测值 $+\hbar/2$ 的概率为 1

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求证三粒子自旋态 $|W
angle=rac{1}{\sqrt{3}}(|+_z-_z-_z
angle+|-_z+_z-_z
angle+|-_z-_z+_z
angle)$ 是总自旋算符平方及其第三分量的共同本征态 $\left|rac{3}{2},-rac{1}{2}
ight
angle$

$$\ket{+_z -_z -_z} \equiv \ket{a}, \ket{-_z +_z -_z} \equiv \ket{b}, \ket{-_z -_z +_z} \equiv \ket{c}$$

由于:

$$\begin{split} \hat{S}_z \, |W\rangle &= \left(\hat{S}_{1z} + \hat{S}_{2z} + \hat{S}_{3z} \right) \frac{1}{\sqrt{3}} \left(|a\rangle + |b\rangle + |c\rangle \right) \\ &= \frac{1}{\sqrt{3}} \cdot \frac{\hbar}{2} \left(|a\rangle - |b\rangle - |c\rangle - |a\rangle + |b\rangle - |c\rangle - |a\rangle - |b\rangle + |c\rangle) \\ &= \frac{-\hbar}{2\sqrt{3}} \left(|a\rangle + |b\rangle + |c\rangle \right) \\ &= -\frac{\hbar}{2} \, |W\rangle \\ \hat{S}^2 &= \left(\hat{S}_1 + \hat{S}_2 + \hat{S}_3 \right) \cdot \left(\hat{S}_1 + \hat{S}_2 + \hat{S}_3 \right) \\ &= \hat{S}_1^2 + \hat{S}_2^2 + \hat{S}_3^2 + 2 \left(\hat{S}_1 \cdot \hat{S}_2 + \hat{S}_2 \cdot \hat{S}_3 + \hat{S}_3 \cdot \hat{S}_1 \right) \\ \hat{S}_1^2 \, |W\rangle &= \frac{1}{\sqrt{3}} \hat{S}_1^2 \left(|+_z -_z -_z\rangle + |-_z +_z -_z\rangle + |-_z -_z +_z\rangle \right) \\ &= \frac{3\hbar^2}{4} \frac{1}{\sqrt{3}} \left(|+_z -_z -_z\rangle + |-_z +_z -_z\rangle + |-_z -_z +_z\rangle \right) \\ &= \frac{3\hbar^2}{4} \, |W\rangle \\ \hat{S}_1 \cdot \hat{S}_2 &= \hat{S}_{1x} \hat{S}_{2x} + \hat{S}_{1y} \hat{S}_{2y} + \hat{S}_{1z} \hat{S}_{2z} \\ &= \frac{\hat{S}_{1+} + \hat{S}_{1-}}{2} \frac{\hat{S}_{2+} + \hat{S}_{2-}}{2} + \frac{\hat{S}_{1+} - \hat{S}_{1-}}{2i} \frac{\hat{S}_{2+} - \hat{S}_{2-}}{2i} + \hat{S}_{1z} \hat{S}_{2z} \\ &= \frac{1}{2} \left(\hat{S}_{1+} \hat{S}_{2-} + \hat{S}_{1-} \hat{S}_{2+} \right) + \hat{S}_{1z} \hat{S}_{2z} \end{split}$$

$$\begin{split} \hat{\vec{S}}_1 \cdot \hat{\vec{S}}_2 \left| W \right> &= \left(\frac{1}{2} \left(\hat{S}_{1+} \hat{S}_{2-} + \hat{S}_{1-} \hat{S}_{2+} \right) + \hat{S}_{1z} \hat{S}_{2z} \right) \frac{1}{\sqrt{3}} (\left| +_z -_z -_z \right> + \left| -_z +_z -_z \right> + \left| -_z -_z +_z \right>) \\ &= \frac{1}{\sqrt{3}} \left[\frac{1}{2} \left(\hbar^2 \left| +_z -_z -_z \right> + \hbar^2 \left| -_z +_z -_z \right> \right) + \frac{\hbar^2}{4} \left(-\left| +_z -_z -_z \right> - \left| -_z +_z -_z \right> + \left| -_z -_z +_z \right> \right) \right] \\ &= \frac{\hbar^2}{4\sqrt{3}} \left(\left| a \right> + \left| b \right> + \left| c \right> \right) \\ &= \frac{\hbar^2}{4} \left| W \right> \end{split}$$

$$egin{aligned} \left(\hat{S}_1^2 + 2 \hat{ec{S}_1} \cdot \hat{ec{S}_2}
ight) |W
angle &= rac{3\hbar^2}{4} \ket{W} + 2 \cdot rac{\hbar^2}{4} \ket{W} \ &= rac{5\hbar^2}{4} \ket{W} \end{aligned}$$

由轮换对称性可知:

$$egin{aligned} \left(\hat{S}_1^2+2\vec{\hat{S}}_1\cdot\hat{ar{S}}_2
ight)|W
angle &=\left(\hat{S}_2^2+2\vec{\hat{S}}_2\cdot\hat{ar{S}}_3
ight)|W
angle &=\left(\hat{S}_3^2+2\vec{\hat{S}}_3\cdot\hat{ar{S}}_1
ight)|W
angle &=rac{5\hbar^2}{4}|W
angle \\ \hat{S}^2|W
angle &=\left[\hat{S}_1^2+\hat{S}_2^2+\hat{S}_3^2+2\left(\hat{ar{S}}_1\cdot\hat{ar{S}}_2+\hat{ar{S}}_2\cdot\hat{ar{S}}_3+\hat{ar{S}}_3\cdot\hat{ar{S}}_1
ight)
ight]|W
angle \\ &=rac{15\hbar^2}{4}|W
angle \end{aligned}$$

$$\left|\hat{S}_{z}\left|W
ight
angle =-rac{\hbar}{2}\left|W
ight
angle =-rac{1}{2}\hbar\left|W
ight
angle \,,\,\,\,\,\hat{S}^{2}\left|W
ight
angle =rac{15\hbar^{2}}{4}=rac{3}{2}\left(rac{3}{2}+1
ight)\hbar^{2}\left|W
ight
angle \,.$$

综上,|W
angle 是总自旋算符平方 \hat{S}^2 及其第三分量 \hat{S}_z 的共同本征态 $\left|\frac{3}{2},-\frac{1}{2}
ight
angle$

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考虑一个处于 $|+_z\rangle$ 的粒子,执行 N 次关于算符 $\hat{\sigma}_k=\vec{n}_k\cdot\hat{\vec{\sigma}}$ 的测量,其中 $\vec{n}_k=\sin\frac{k\pi}{2N}\vec{\mathrm{e}}_x+\cos\frac{k\pi}{2N}\vec{\mathrm{e}}_z(k=1,2,\cdots,N)$,求:

(1) 全部测量结果都是 +1 的概率。当 $N o \infty$ 时出现什么?

在 $\hat{\sigma}_z$ 表象下,

$$\hat{\sigma}_k = ec{n}_k \cdot \hat{ec{\sigma}} = \sin rac{k\pi}{2N} \hat{\sigma}_x + \cos rac{k\pi}{2N} \hat{\sigma}_z = egin{bmatrix} \cos rac{k\pi}{2N} & \sin rac{k\pi}{2N} \ \sin rac{k\pi}{2N} & -\cos rac{k\pi}{2N} \end{bmatrix}$$

 $\hat{\sigma}_k$ 的本征方程:

$$\hat{\sigma}_k \ket{\lambda} = \lambda \ket{\lambda}$$

解得:

$$\lambda = \pm 1$$

当 $\lambda = +1$, 对应的本征态记为 $|+_k\rangle$, 在 $\hat{\sigma}_z$ 表象下,

$$|+_k\rangle = \begin{bmatrix} \cosrac{k\pi}{4N} \\ \sinrac{k\pi}{4N} \end{bmatrix}$$

当 $\lambda = -1$, 对应的本征态记为 $|-_k\rangle$, 在 $\hat{\sigma}_z$ 表象下,

$$|-_k
angle = egin{bmatrix} \sinrac{k\pi}{4N} \ -\cosrac{k\pi}{4N} \end{bmatrix}$$

第一次测量 $\hat{\sigma}_1$, k=1 , 测量前系统处于 $|+_z\rangle$, 测得 +1 的概率为:

$$P_1 = \left| \left\langle +_z \right| +_1 \right\rangle \right|^2$$
$$= \cos^2 \frac{\pi}{4N}$$

第一次测量 $\hat{\sigma}_1$ 得到 +1 后系统塌缩到 $|+_1\rangle$,第二次测量 $\hat{\sigma}_2$,k=2,显然,第二次测量测得 +1 的概率与第一次相同,即:

$$P_2 = P_1 = \cos^2 \frac{\pi}{4N}$$

以此类推,

$$P_3 = P_4 = \dots = P_n = \cos^2 \frac{\pi}{4N}$$

全部测量结果都是 +1 的概率为:

$$P = P_1 P_2 \cdots P_N = \cos^{2N} \frac{\pi}{4N}$$

当 $N \to \infty$,

$$P = \lim_{N o \infty} \cos^{2N} rac{\pi}{4N} = 1$$

(2) 若初态为 $|-_z\rangle$,全部测量结果都是 +1 的概率。当 $N o\infty$ 时 出现什么?

第一次测量 $\hat{\sigma}_1$, k=1 , 测量前系统处于 $|-_z\rangle$, 测得 +1 的概率为:

$$P_1' = \left| \left\langle -_z \right| +_1 \right\rangle \right|^2$$
$$= \sin^2 \frac{\pi}{4N}$$

第一次测量 $\hat{\sigma}_1$ 得到 +1 后系统塌缩到 $|+_1\rangle$, 从第二次测量开始的结果应与 (1) 中一致, 即:

$$P_2' = P_1 = \cos^2 \frac{\pi}{4N}$$

以此类推,

$$P_3' = P_4' = \dots = P_N' = \cos^2 \frac{\pi}{4N}$$

全部测量结果都是 +1 的概率为:

$$P' = P_1' P_2' \cdots P_N' = \sin^2 \frac{\pi}{4N} \cos^{2N-2} \frac{\pi}{4N}$$

当 $N \to \infty$,

$$P'=\lim_{N o\infty}\sin^2rac{\pi}{4N}\cos^{2N-2}rac{\pi}{4N}=0$$