## **(1)**

推导两算符不确定度满足的关系,并说明什么样的两个算符可以同时测准。

#### 解:

schwarz 不等式:

$$\langle \alpha | \alpha \rangle \langle \beta | \beta \rangle \geqslant |\langle \alpha | \beta \rangle|^2$$

令  $|\alpha\rangle=(A-\bar{A})\,|\psi\rangle\,, |\beta\rangle=(B-\bar{B})\,|\psi\rangle\,$ ,其中,A,B 都是厄米算符,则:

$$ra{lpha} = ra{\psi} (A - ar{A})^\dagger = ra{\psi} (A - ar{A}), \ \ raket{eta} = raket{\psi} (B - ar{B})^\dagger = raket{\psi} (B - ar{B})$$

代入 schwarz 不等式:

$$\langle \psi | (A - \bar{A})^2 | \psi \rangle \langle \psi | (B - \bar{B})^2 | \psi \rangle \geqslant |\langle \psi | (A - \bar{A})(B - \bar{B}) | \psi \rangle|^2$$

即:

$$(\Delta A)^{2}(\Delta B)^{2} \geqslant |\langle \psi | (AB - \bar{A}B - \bar{B}A + \bar{A}\bar{B}) | \psi \rangle|^{2}$$
  
=  $|\langle \psi | AB | \psi \rangle - \bar{A}\bar{B}|^{2}$ 

注意到,对于任意复数 z = a + ib,有:

$$|z|^2 = |a|^2 + |b|^2$$
  
 $\geqslant |b|^2$   
 $= \left|\frac{z - z^*}{2\mathrm{i}}\right|^2$ 

于是:

$$\begin{split} (\Delta A)^2 (\Delta B)^2 &\geqslant |\langle \psi | AB | \psi \rangle - \bar{A}\bar{B}|^2 \\ &\geqslant \left| \frac{(\langle \psi | AB | \psi \rangle - \bar{A}\bar{B}) - (\langle \psi | AB | \psi \rangle - \bar{A}\bar{B})^*}{2\mathrm{i}} \right|^2 \\ &= \left| \frac{\langle \psi | AB | \psi \rangle - \langle \psi | AB | \psi \rangle^*}{2\mathrm{i}} \right|^2 \\ &= \left| \frac{\langle \psi | AB | \psi \rangle - \langle A^\dagger \psi | B\psi \rangle^*}{2\mathrm{i}} \right|^2 \\ &= \left| \frac{\langle \psi | AB | \psi \rangle - \langle B\psi | A^\dagger \psi \rangle}{2\mathrm{i}} \right|^2 \\ &= \left| \frac{\langle \psi | AB | \psi \rangle - \langle \psi | B^\dagger \cdot A^\dagger | \psi \rangle}{2\mathrm{i}} \right|^2 \\ &= \left| \frac{\langle \psi | AB | \psi \rangle - \langle \psi | BA | \psi \rangle}{2\mathrm{i}} \right|^2 \\ &= \left| \frac{\langle \psi | AB | \psi \rangle - \langle \psi | BA | \psi \rangle}{2\mathrm{i}} \right|^2 \\ &= \left| \frac{\langle \psi | [A, B] | \psi \rangle}{2\mathrm{i}} \right|^2 \\ &= \frac{\overline{[A, B]}^2}{4} \end{split}$$

即:

$$\Delta A \Delta B \geqslant rac{\overline{[A,B]}}{2}$$

### **(2)**

若两个算符对易,则有什么性质?本征态满足什么性质?

两个对易的算符可以同时测准,本征态具有正交、归一、完备性。

# 四

#### 1

质量为 m 的离子在势场  $V(x)=kx^4, (k>0)$  中运动,用变分法求基态能级近似值,试探波函数(未归一化)取为:

- 1)  $\psi(\lambda,x)=\mathrm{e}^{-\lambda|x|}$
- 2)  $\psi(\lambda,x)=\mathrm{e}^{-\lambda x^2/2}$
- 3) 解释为什么 (1) 项结果较差

## (1)

$$ar{H} = rac{\langle \psi | H | \psi 
angle}{\langle \psi | \psi 
angle} = rac{\langle \psi | T + V | \psi 
angle}{\langle \psi | \psi 
angle}$$

$$\begin{split} \langle \psi | \psi \rangle &= \int_{-\infty}^{+\infty} \mathrm{e}^{-\lambda |x|} \cdot \mathrm{e}^{-\lambda |x|} \mathrm{d}x \\ &= \frac{1}{\lambda} \\ \langle \psi | T | \psi \rangle &= \frac{\hbar^2}{2m} \int_{-\infty}^{+\infty} \mathrm{e}^{-\lambda |x|} \frac{\mathrm{d}^2}{\mathrm{d}x^2} \mathrm{e}^{-\lambda |x|} \mathrm{d}x \\ &= \frac{\hbar^2 \lambda}{2m} \\ \langle \psi | V | \psi \rangle &= \int_{-\infty}^{+\infty} k x^4 \mathrm{e}^{-2\lambda |x|} \mathrm{d}x \\ &= \frac{3k}{2\lambda^5} \end{split}$$

于是:

$$ar{H}=rac{\hbar^2\lambda^2}{2m}+rac{3k}{2\lambda^4} \ ar{H}=rac{\hbar^2\lambda^2}{4m}+rac{\hbar^2\lambda^2}{4m}+rac{3k}{2\lambda^4}\geqslant 3\sqrt[3]{rac{\hbar^2\lambda^2}{4m}\cdotrac{\hbar^2\lambda^2}{4m}\cdotrac{3k}{2\lambda^4}}=rac{3}{2}3^{1/3}igg(rac{\hbar^2}{2m}igg)^{2/3}k^{1/3}$$

(2)

(3)

2

对于一个二维各向同性谐振子

- 1) 给出本征能量及对应的本征态
- 2) 给系统加一个微扰  $H'=\lambda xy$ ,试求系统基态的能量修正(准确到二阶)

解:

- (1)
- (2)

## 五

某二能级系统哈密顿量在自身表象下的矩阵形式为

$$H_0 \doteq egin{bmatrix} arepsilon_a & 0 \ 0 & arepsilon_b \end{bmatrix}$$

$$H' \doteq egin{bmatrix} 0 & V \mathrm{e}^{-\mathrm{i}arphi} \ V \mathrm{e}^{\mathrm{i}arphi} & 0 \end{bmatrix}$$

将加上扰动后体系的哈密顿量记为 H

- 1) 求加上扰动后体系的本征能量与本征态
- 2) 求 $H_0$  表象过渡到 H 表象的变换矩阵
- 3) 设初态粒子能量为  $\varepsilon_a$ , 求能量转变至  $\varepsilon_b$  的概率

解:

(1)

$$H = H_0 + H' = egin{bmatrix} arepsilon_a & V \mathrm{e}^{-\mathrm{i}arphi} \ V \mathrm{e}^{\mathrm{i}arphi} & arepsilon_b \end{bmatrix} \ egin{bmatrix} arepsilon_a - E & V \mathrm{e}^{-\mathrm{i}arphi} \ V \mathrm{e}^{\mathrm{i}arphi} & arepsilon_b - E \end{bmatrix} = 0 \ \end{split}$$

解得加上扰动后的本征能量:

$$E_{+} = rac{arepsilon_a + arepsilon_b}{2} + rac{\sqrt{(arepsilon_a - arepsilon_b)^2 + 4V^2}}{2} 
onumber$$
  $E_{-} = rac{arepsilon_a + arepsilon_b}{2} - rac{\sqrt{(arepsilon_a - arepsilon_b)^2 + 4V^2}}{2}$ 

为快速求本征矢, 将哈密顿量改写为:

$$\begin{split} H &\doteq \frac{\varepsilon_a + \varepsilon_b}{2} I + V \cos \varphi \sigma_x + V \sin \varphi \sigma_y + \frac{\varepsilon_a - \varepsilon_b}{2} \sigma_z \\ &= \frac{\varepsilon_a + \varepsilon_b}{2} I + \frac{\sqrt{(\varepsilon_a - \varepsilon_b)^2 + 4V^2}}{2} \left[ \frac{2V \cos \varphi}{\sqrt{(\varepsilon_a - \varepsilon_b)^2 + 4V^2}} \sigma_x + \frac{2V \sin \varphi}{\sqrt{(\varepsilon_a - \varepsilon_b)^2 + 4V^2}} \sigma_y + \frac{\varepsilon_a - \varepsilon_b}{\sqrt{(\varepsilon_a - \varepsilon_b)^2 + 4V^2}} \sigma_z \right] \\ &\equiv \frac{\varepsilon_a + \varepsilon_b}{2} I + \frac{\sqrt{(\varepsilon_a - \varepsilon_b)^2 + 4V^2}}{2} \vec{\sigma} \cdot \vec{n} \end{split}$$

其中,  $\vec{n} = \sin \theta \cos \phi \vec{e}_x + \sin \theta \cos \phi \vec{e}_z + \cos \theta \vec{e}_z$ 

对比可得:

$$\tan \theta = \frac{2V}{\varepsilon_a - \varepsilon_b}, \ \phi = \frac{\pi}{2} - \varphi$$

注意利用以下几个结论:

$$Aec{x} = \lambda ec{x} \Longrightarrow (cA)ec{x} = (c\lambda)ec{x}$$
  $Aec{x} = \lambda ec{x} \Longrightarrow (A+I)ec{x} = (\lambda+1)ec{x}$ 

当  $\vec{n}(\theta,\phi) = \sin\theta\cos\phi\vec{e}_x + \sin\theta\sin\phi\vec{e}_y + \cos\theta\vec{e}_z$  时, $\vec{\sigma}\cdot\vec{n}$  的本征解为:

$$\left(ec{\sigma}\cdotec{n}
ight)\left|ec{n},+
ight
angle = 1\cdot\left|ec{n},+
ight
angle,\;\;\left|ec{n},+
ight
angle \stackrel{\sigma_z}{=} \left[ rac{\cosrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}}}{\sinrac{ heta}{2}\mathrm{e}^{\mathrm{i}rac{\phi}{2}}}
ight]$$

$$egin{aligned} \left(ec{\sigma}\cdotec{n}
ight)\left|ec{n},-
ight> = -1\cdot\left|ec{n},-
ight>, \;\; \left|ec{n},-
ight> rac{\sigma_z}{=} egin{bmatrix} -\sinrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}} \ \cosrac{ heta}{2}\mathrm{e}^{\mathrm{i}rac{\phi}{2}} \ \end{bmatrix} \end{aligned}$$

利用上面几个结论,可以得到 H 的本征解:

$$\ket{\psi_+} = egin{bmatrix} \cosrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}} \ \sinrac{ heta}{2}\mathrm{e}^{\mathrm{i}rac{\phi}{2}} \end{bmatrix} \ -\sinrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}} \end{bmatrix}$$

$$\ket{\psi_-} = egin{bmatrix} -\sinrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}} \ \cosrac{ heta}{2}\mathrm{e}^{\mathrm{i}rac{\phi}{2}} \end{bmatrix}$$

其中,

$$an heta = rac{2V}{arepsilon_a - arepsilon_b}, \ \ \phi = rac{\pi}{2} - arphi$$

(2)

从  $H_0$  表象变换到 H 表象的变换矩阵元:

$$egin{aligned} S_{11} &= \langle \psi_+ | \psi_a 
angle \stackrel{H_0}{=} \left[\cos rac{ heta}{2} \mathrm{e}^{\mathrm{i} rac{\phi}{2}} \quad \sin rac{ heta}{2} \mathrm{e}^{-\mathrm{i} rac{\phi}{2}} 
ight] \left[egin{aligned} 1 \ 0 \end{aligned}
ight] = \cos rac{ heta}{2} \mathrm{e}^{\mathrm{i} rac{\phi}{2}} \ S_{12} &= \langle \psi_+ | \psi_b 
angle \stackrel{H_0}{=} \left[\cos rac{ heta}{2} \mathrm{e}^{\mathrm{i} rac{\phi}{2}} \quad \sin rac{ heta}{2} \mathrm{e}^{-\mathrm{i} rac{\phi}{2}} 
ight] \left[egin{aligned} 0 \ 1 \end{aligned}
ight] = \sin rac{ heta}{2} \mathrm{e}^{-\mathrm{i} rac{\phi}{2}} \ S_{21} &= \langle \psi_- | \psi_a 
angle \stackrel{H_0}{=} \left[ -\sin rac{ heta}{2} \mathrm{e}^{\mathrm{i} rac{\phi}{2}} \quad \cos rac{ heta}{2} \mathrm{e}^{-\mathrm{i} rac{\phi}{2}} 
ight] \left[egin{aligned} 1 \ 0 \end{aligned}
ight] = -\sin rac{ heta}{2} \mathrm{e}^{\mathrm{i} rac{\phi}{2}} \ S_{22} &= \langle \psi_- | \psi_b 
angle \stackrel{H_0}{=} \left[ -\sin rac{ heta}{2} \mathrm{e}^{\mathrm{i} rac{\phi}{2}} \quad \cos rac{ heta}{2} \mathrm{e}^{-\mathrm{i} rac{\phi}{2}} 
ight] \left[egin{aligned} 0 \ 1 \end{aligned}
ight] = \cos rac{ heta}{2} \mathrm{e}^{-\mathrm{i} rac{\phi}{2}} \ \end{array}$$

综上,从  $H_0$  表象到 H 表象的变换矩阵为:

$$S_{H_0 o H} = egin{bmatrix} \cosrac{ heta}{2}\mathrm{e}^{\mathrm{i}rac{\phi}{2}} & \sinrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}} \ -\sinrac{ heta}{2}\mathrm{e}^{\mathrm{i}rac{\phi}{2}} & \cosrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}} \end{bmatrix}$$

其中,

$$an heta=rac{2V}{arepsilon_a-arepsilon_b}, \ \ \phi=rac{\pi}{2}-arphi$$

(3)

初态为  $|\psi(t=0)
angle=|\psi_a
angle$ ,利用变换矩阵,将其变换到 H 表象:

$$egin{aligned} \ket{\psi(t=0)} &\stackrel{H_0}{=} egin{bmatrix} 1 \ 0 \end{bmatrix} \ &\stackrel{H}{=} S_{H_0 o H} egin{bmatrix} 1 \ 0 \end{bmatrix} \ &\stackrel{H}{=} egin{bmatrix} \cos rac{ heta}{2} \mathrm{e}^{\mathrm{i} rac{\phi}{2}} & \sin rac{ heta}{2} \mathrm{e}^{-\mathrm{i} rac{\phi}{2}} \ -\sin rac{ heta}{2} \mathrm{e}^{\mathrm{i} rac{\phi}{2}} & \cos rac{ heta}{2} \mathrm{e}^{-\mathrm{i} rac{\phi}{2}} \end{bmatrix} egin{bmatrix} 1 \ 0 \end{bmatrix} \ &\stackrel{H}{=} egin{bmatrix} \cos rac{ heta}{2} \mathrm{e}^{\mathrm{i} rac{\phi}{2}} \ -\sin rac{ heta}{2} \mathrm{e}^{\mathrm{i} rac{\phi}{2}} \end{bmatrix} \end{aligned}$$

t 时刻波函数:

$$|\psi(t)
angle = egin{bmatrix} \cosrac{ heta}{2}\mathrm{e}^{\mathrm{i}(rac{\phi}{2}-E_{+}t/\hbar)} \ -\sinrac{ heta}{2}\mathrm{e}^{\mathrm{i}(rac{\phi}{2}-E_{-}t/\hbar)} \end{bmatrix}$$

t 时刻观测到粒子处于  $|\psi_b\rangle$  态的概率:

$$egin{aligned} P_{a o b} &= |raket{\psi_b|\psi(t)}|^2 \ |\psi_b
angle &\stackrel{H_0}{=} egin{bmatrix} 0 \ 1 \end{bmatrix} \ &\stackrel{H}{=} S_{H_0 o H} egin{bmatrix} 0 \ 1 \end{bmatrix} \ &\stackrel{H}{=} egin{bmatrix} \cosrac{ heta}{2}\mathrm{e}^{\mathrm{i}rac{\phi}{2}} & \sinrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}} \ -\sinrac{ heta}{2}\mathrm{e}^{\mathrm{i}rac{\phi}{2}} & \cosrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}} \end{bmatrix} egin{bmatrix} 0 \ 1 \end{bmatrix} \ &\stackrel{H}{=} egin{bmatrix} \sinrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}} \ \cosrac{ heta}{2}\mathrm{e}^{-\mathrm{i}rac{\phi}{2}} \end{bmatrix} \end{aligned}$$

于是:

$$\begin{split} P_{a \to b} &= | \left< \psi_b | \psi(t) \right> |^2 \\ &= \left| \left[ \sin \frac{\theta}{2} \mathrm{e}^{\mathrm{i} \frac{\phi}{2}} \quad \cos \frac{\theta}{2} \mathrm{e}^{\mathrm{i} \frac{\phi}{2}} \right] \left[ \cos \frac{\theta}{2} \mathrm{e}^{\mathrm{i} (\frac{\phi}{2} - E_+ t/\hbar)} \right] \right|^2 \\ &= \frac{\sin^2 \theta}{4} \left( 2 - 2 \cos \frac{E_+ - E_-}{\hbar} t \right) \\ &= \frac{4V^2}{(\varepsilon_a - \varepsilon_b)^2 + 4V^2} \sin^2 \left( \frac{\sqrt{(\varepsilon_a - \varepsilon_b)^2 + 4V^2}}{2\hbar} t \right) \end{split}$$