Pattern recognition in high-dimensional spaces

- Problems arise when performing recognition in a high-dimensional space (curse of dimensionality).
- Significant improvements can be achieved by first mapping the data into a lower-dimensional sub-space.

$$x = \begin{bmatrix} a_1 \\ a_2 \\ \dots \\ a_N \end{bmatrix} --> reduce \ dimensionality --> y = \begin{bmatrix} b_1 \\ b_2 \\ \dots \\ b_K \end{bmatrix} \ (K << N)$$

 The goal of PCA is to reduce the dimensionality of the data while retaining as much information as possible in the original dataset.

Dimensionality reduction

 PCA allows us to compute a linear transformation that maps data from a high dimensional space to a lower dimensional sub-space.

 $K \times N$

$$y = Tx \text{ where } T = \begin{bmatrix} t_{11} & t_{12} & \dots & t_{1N} \\ t_{21} & t_{22} & \dots & t_{2N} \\ \dots & \dots & \dots & \dots \\ t_{K1} & t_{K2} & \dots & t_{KN} \end{bmatrix}$$

$$b_1 = t_{11}a_1 + t_{12}a_2 + \dots + t_{1n}a_N$$

$$b_2 = t_{21}a_1 + t_{22}a_2 + \dots + t_{2n}a_N$$

$$\dots$$

$$b_K = t_{K1}a_1 + t_{K2}a_2 + \dots + t_{KN}a_N$$

Methodology

- Suppose $x_1, x_2, ..., x_M$ are $N \times 1$ vectors

Step 1:
$$\bar{x} = \frac{1}{M} \sum_{i=1}^{M} x_i$$

Step 2: subtract the mean: $\Phi_i = x_i - \bar{x}$ (i.e., center at zero)

Step 3: form the matrix $A = [\Phi_1 \ \Phi_2 \cdots \Phi_M]$ (NxM matrix), then compute:

$$C = \frac{1}{M} \sum_{n=1}^{M} \Phi_n \Phi_n^T = \frac{1}{M} A^T$$

(sample **covariance** matrix, NxN, characterizes the *scatter* of the data)

Step 4: compute the eigenvalues of $C: \mathbf{\lambda}_1 > \mathbf{\lambda}_2 > \cdots > \mathbf{\lambda}_N$

Step 5: compute the eigenvectors of $C: u_1, u_2, \dots, u_N$

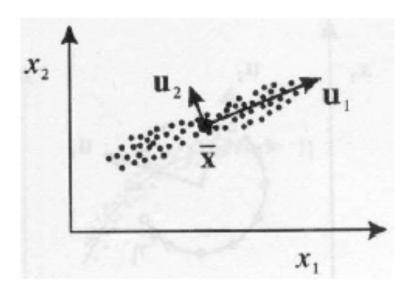
- Linear transformation implied by PCA
 - The effective linear transformation $R^N \to R^K$ that performs the dimensionality reduction is:

$$\begin{bmatrix} b_1 \\ b_2 \\ \dots \\ b_K \end{bmatrix} = \begin{bmatrix} u_1^T \\ u_2^T \\ \dots \\ u_K^T \end{bmatrix} (x - \bar{x}) = U^T (x - \bar{x})$$

(i.e., simply computing coefficients of linear expansion)

Geometric interpretation

- PCA projects the data along the directions where the data varies the most.
- These directions are determined by the eigenvectors of the covariance matrix corresponding to the largest eigenvalues.
- The magnitude of the eigenvalues corresponds to the variance of the data along the eigenvector directions.



- How to choose K (i.e., number of principal components) ?
 - To choose *K*, use the following criterion:

$$\frac{\sum\limits_{i=1}^{K} \boldsymbol{\lambda}_{i}}{\sum\limits_{i=1}^{N} \boldsymbol{\lambda}_{i}} > Threshold \quad (\text{e.g., 0.9 or 0.95})$$

- In this case, we say that we "preserve" 90% or 95% of the information in our data. If K=N, then we "preserve" 100% of the information in our data.
- PCA minimizes the reconstruction error, e, and it can be shown that the error is equal to:

$$e = ||x - \hat{x}|| \rightarrow e = 1/2 \sum_{i=K+1}^{N} \lambda_i$$

PCA Standardization

Standardization

- The principal components are dependent on the *units* used to measure the original variables as well as on the *range* of values they assume.
- Always standardize the data prior to using PCA.
- A common standardization method is to transform all the data to have zero mean and unit standard deviation:

$$\frac{x_i - \mu}{\sigma}$$
 (μ and σ are the mean and standard deviation of x_i 's)