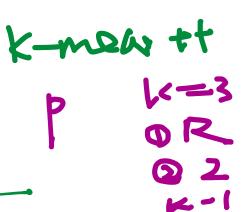
# **CLUSTERING**

#### **CLUSTERING ALGORITHMS**

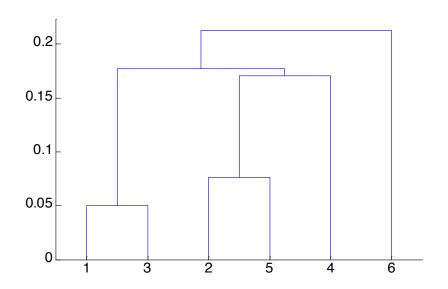
- K-means and its variants
  - What is k-means / algorithm, how to select the initial centroids for k-means (k-means++, bisecting k-means), limitations of k-means (size, density, shape) and the methods to overcome the limitations.

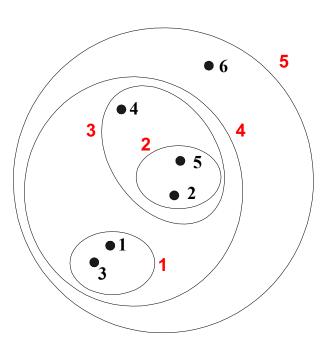
partition based clustering (each cluster / group is not overlapped with any other cluster / group.

- Hierarchical clustering
- Density-based clustering



- Produces a set of nested clusters organized as a hierarchical tree
- Can be visualized as a dendrogram
  - A tree like diagram that records the sequences of merges or splits

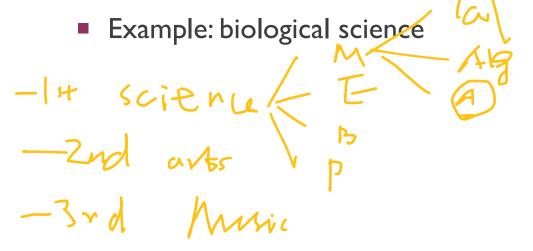


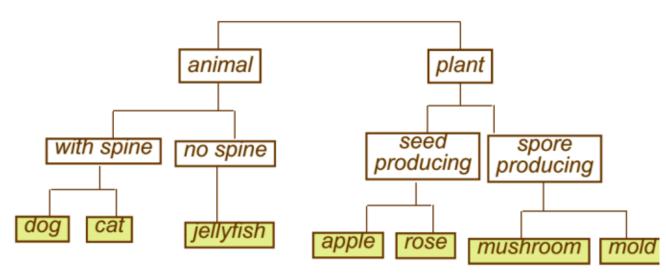


#### STRENGTHS OF HIERARCHICAL CLUSTERING

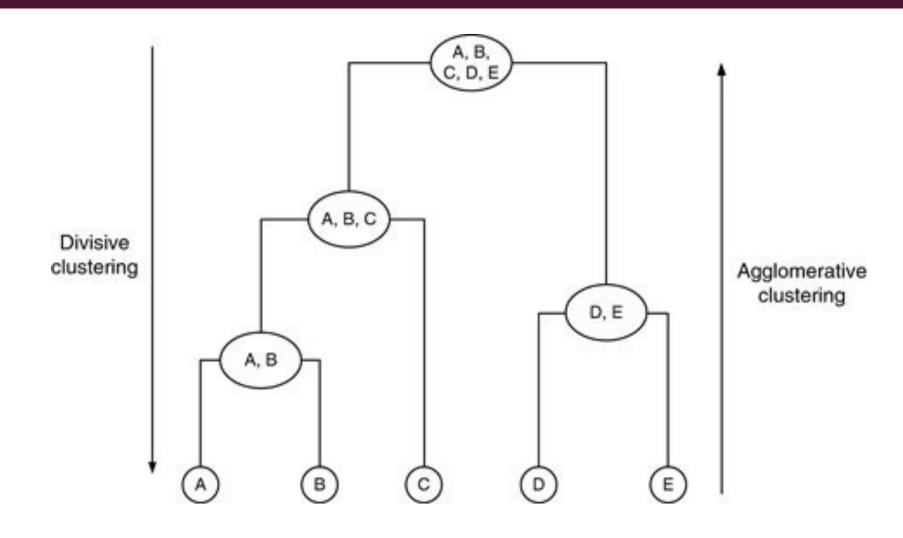
- Do not have to assume any particular number of clusters
  - Any desired number of clusters can be obtained by 'cutting' the dendrogram at the proper level

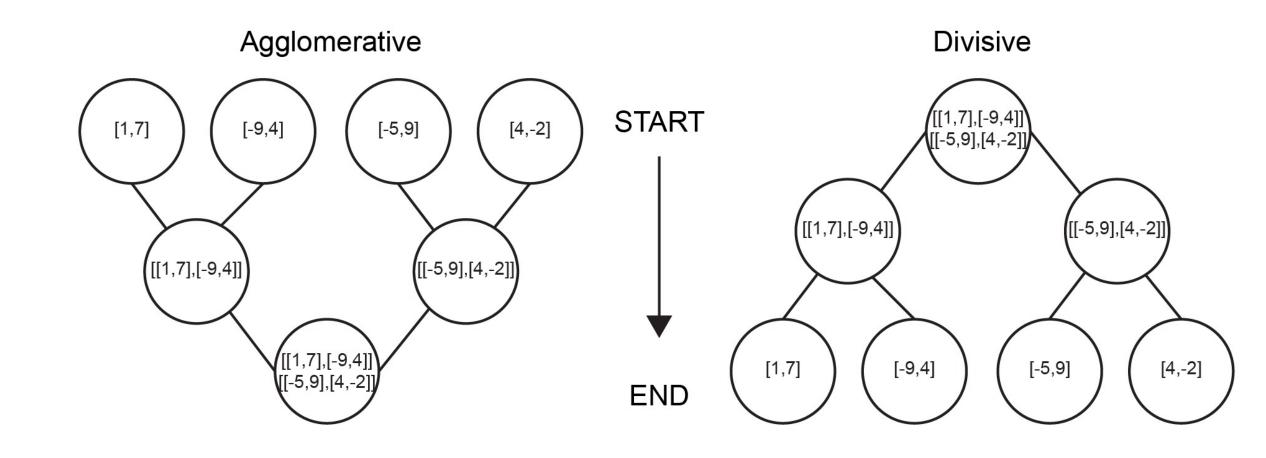
They may correspond to meaningful taxonomies





- Two main types of hierarchical clustering
  - Agglomerative:
    - Start with the points as individual clusters
    - At each step, merge the closest pair of clusters until only one cluster (or k clusters) left
  - Divisive:
    - Start with one, all-inclusive cluster
    - At each step, split a cluster until each cluster contains an individual point (or there are k clusters)
- Traditional hierarchical algorithms use a similarity or distance matrix
  - Merge or split one cluster at a time

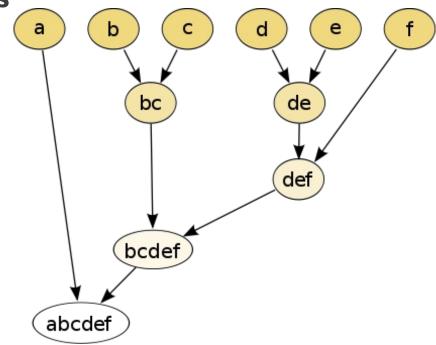




#### AGGLOMERATIVE CLUSTERING ALGORITHM

Key Idea: Successively merge closest clusters

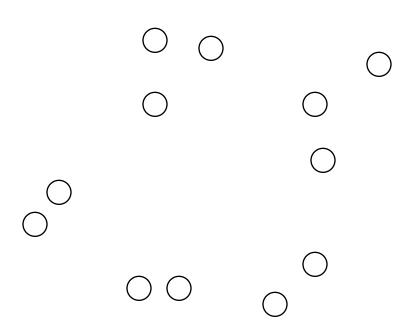
- Basic algorithm
  - I. Compute the proximity matrix
  - 2. Let each data point be a cluster
  - 3. Repeat
  - 4. Merge the two closest clusters
  - 5. Update the proximity matrix
  - **6. Until** only a single cluster remains



- Key operation is the computation of the proximity of two clusters
  - Different approaches to defining the distance between clusters distinguish the different algorithms

# STEPS I AND 2

Start with clusters of individual points and a proximity matrix

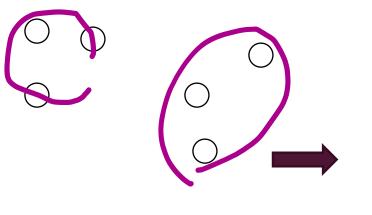


	р1	p2	рЗ	p4	р5	<u> </u>
<b>p1</b>						
<b>p2</b>						
<u>p2</u> <u>p3</u>						
<u>р4</u> р5						
•						



# INTERMEDIATE SITUATION

After some merging steps, we have some clusters





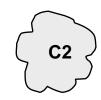


	C1	C2	<b>C</b> 3	C4	<b>C</b> 5
<b>C1</b>					
C2					
<b>C</b> 3					
C4					
<b>C</b> 5					

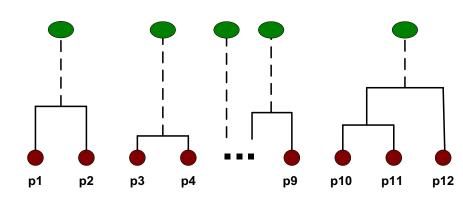
**Proximity Matrix** 







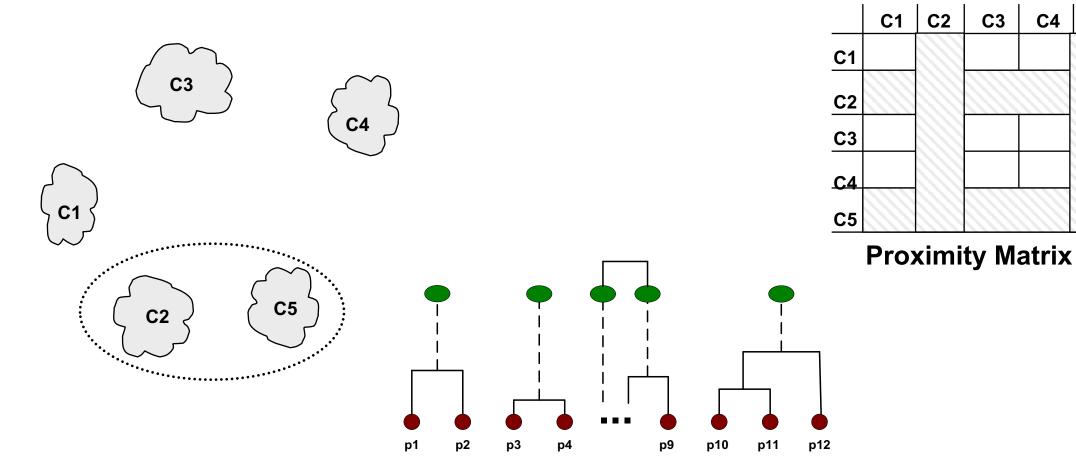




# STEP 4

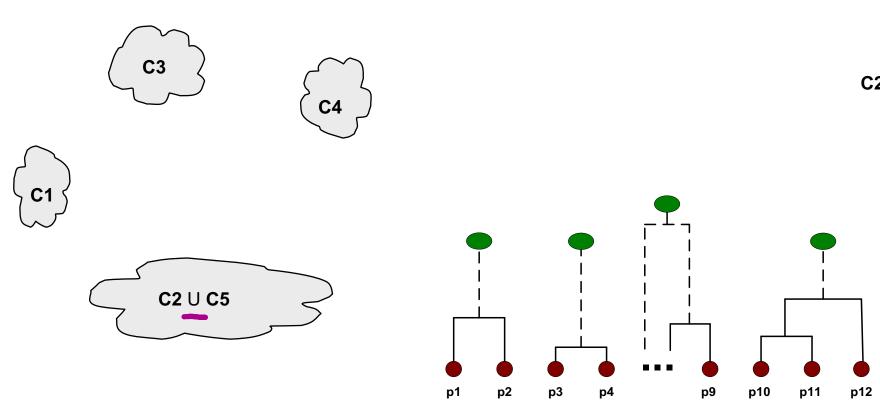
■ We want to merge the two closest clusters (C2 and C5) and update the proximity matrix.

**C5** 



# STEP 5

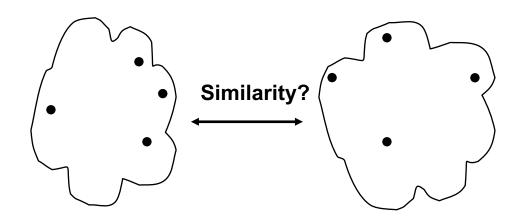
■ The question is "How do we update the proximity matrix?"



			<b>C2</b> U		
		C1	U <b>C5</b>	<b>C</b> 3	C4
	<b>C1</b>		?:		
<b>C2</b> U	<b>C</b> 5	?	?	?	?
	<b>C</b> 3		?		
	<u>C4</u>		?		

**Proximity Matrix** 

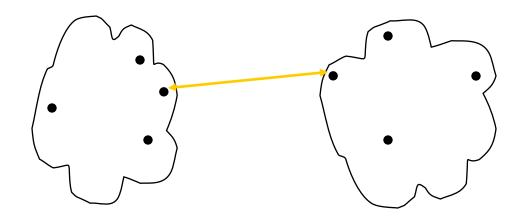
# HOW TO DEFINE INTER-CLUSTER DISTANCE



	M	IN
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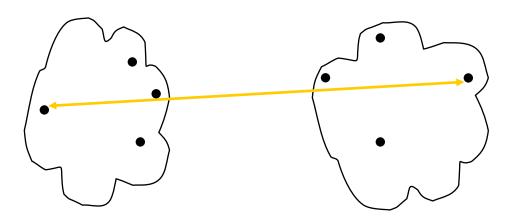
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error

	<b>p1</b>	p2	р3	р4	<b>p</b> 5	<u>.</u> .
<b>p1</b>						
<b>p2</b>						
р3						
<b>p4</b>						
<b>p</b> 5						



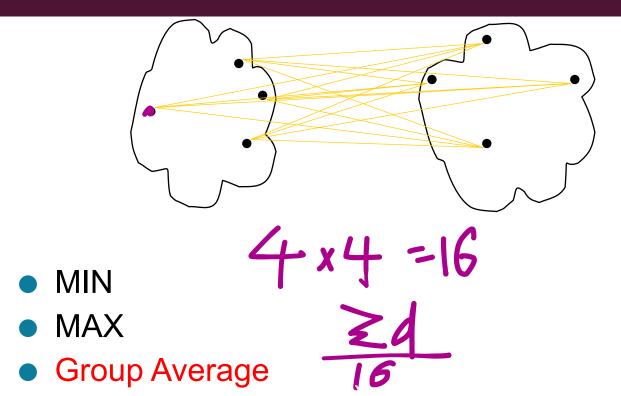
- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error

	p1	<b>p2</b>	р3	p4	<b>p5</b>	<u> </u>
<b>p1</b>						
<b>p2</b>						
р3						
p4						
p5						



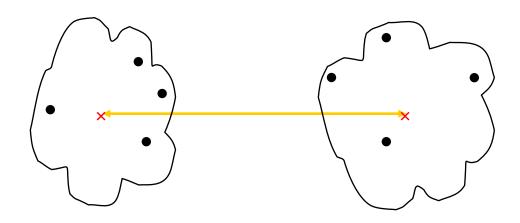
- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error

	<b>p</b> 1	p2	рЗ	p4	<b>p</b> 5	<u> </u>
p1						
<b>p2</b>						
<b>p3</b>						
<u>p4</u> p5						

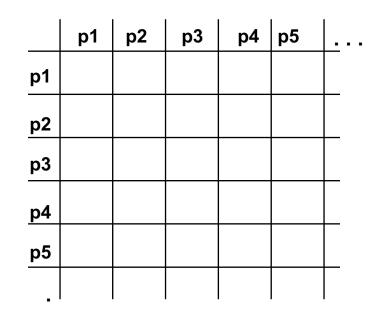


- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error

	<b>p</b> 1	p2	рЗ	p4	р5	<u>.</u>
<b>p1</b>						
<b>p2</b>						
р3						
<b>p4</b>						
р5						



- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error

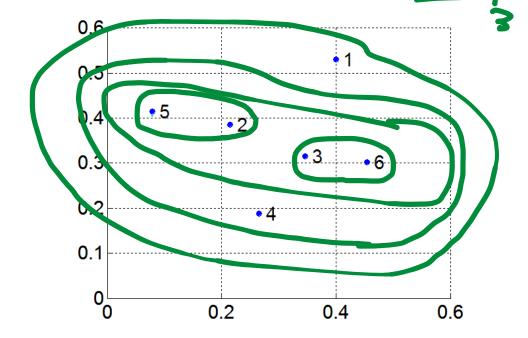


#### MIN OR SINGLE LINK

Proximity of two clusters is based on the two closest points in the different clusters

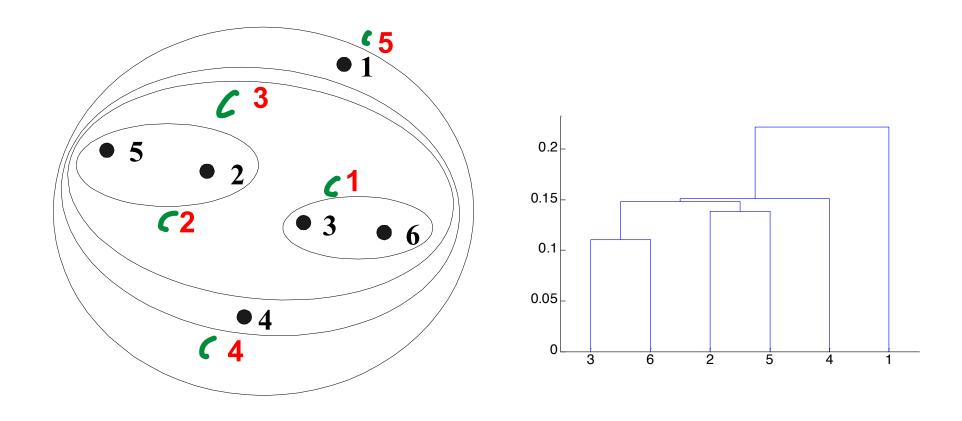
Determined by one pair of points, i.e., by one link in the proximity graph

Example:



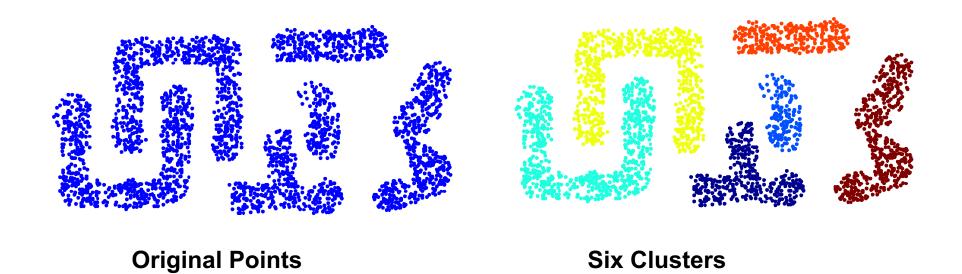
_		
D:_4		<b>Matrix:</b>
I DICTS	nce i	viatriy:
レいろに		viati in.

	p1	p2	р3	p4	p5	p6
p1	5	0.24	0.22	0.37	0.34	0.23
p2	0.24	3	0.15	0.20	0.14	0.25
р3	0.22	0.15	0.	0.15	0.28	0.11
p4	0.37	0.20	0.15	Une	0.29	0.22
p5	0.34	0.14	0.28	0.29	0.0	0.39
p6	0.23	0.25	0.11	0.22	0.39	0.02



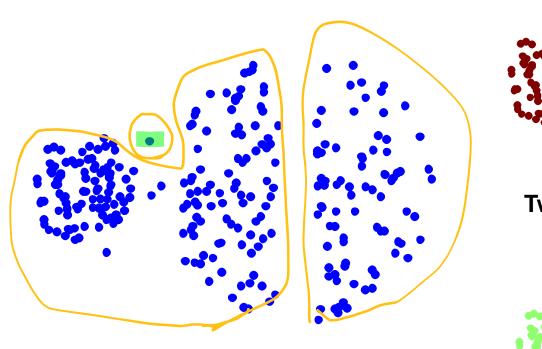
#### **Dendrogram**

# STRENGTH OF MIN



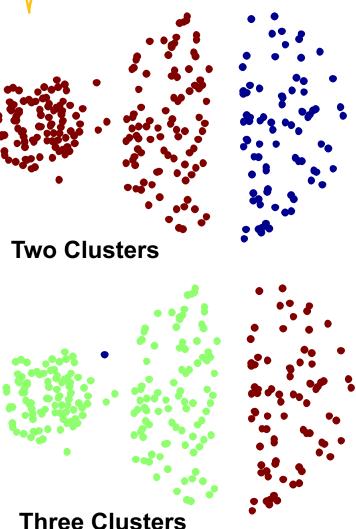
Can handle non-elliptical shapes

# 



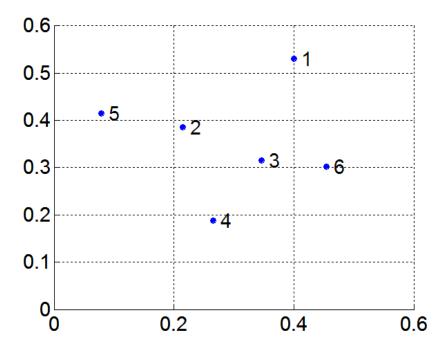
**Original Points** 

Sensitive to noise



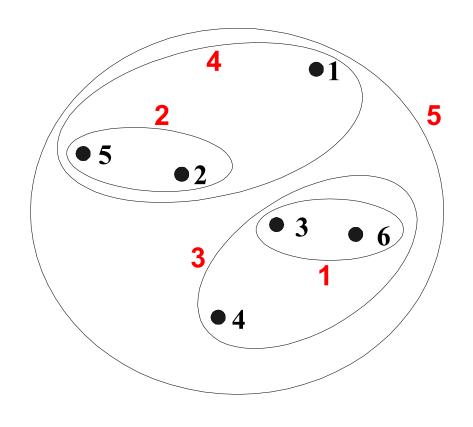
#### MAX OR COMPLETE LINKAGE

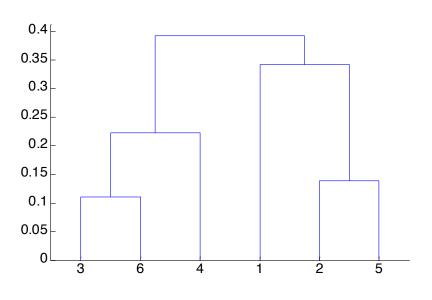
- Proximity of two clusters is based on the two most distant points in the different clusters
  - Determined by all pairs of points in the two clusters



#### **Distance Matrix:**

	р1	p2	р3	p4	p5	p6
p1	0.00	0.24	0.22	0.37	0.34	0.23
p2	0.24	0.00	0.15	0.20	0.14	0.25
p3	0.22	0.15	0.00	0.15	0.28	0.11
p4	0.37	0.20	0.15	0.00	0.29	0.22
p5	0.34	0.14	0.28	0.29	6.00	0.39
p6	0.23	0.25	0.11	0.22	0.39	0.00

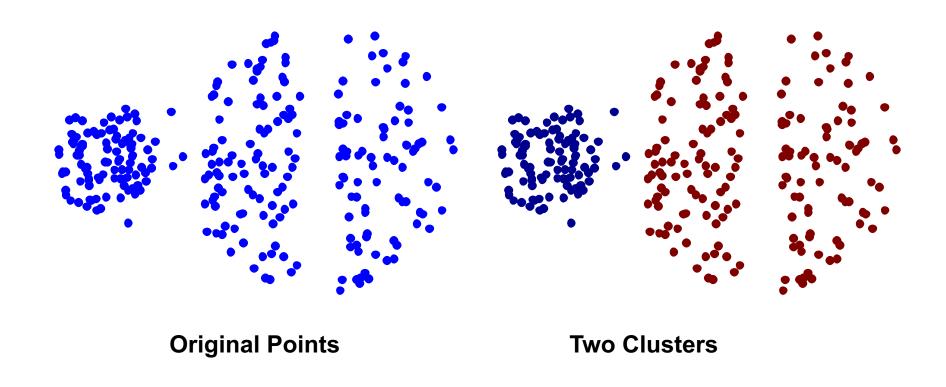




**Nested Clusters** 

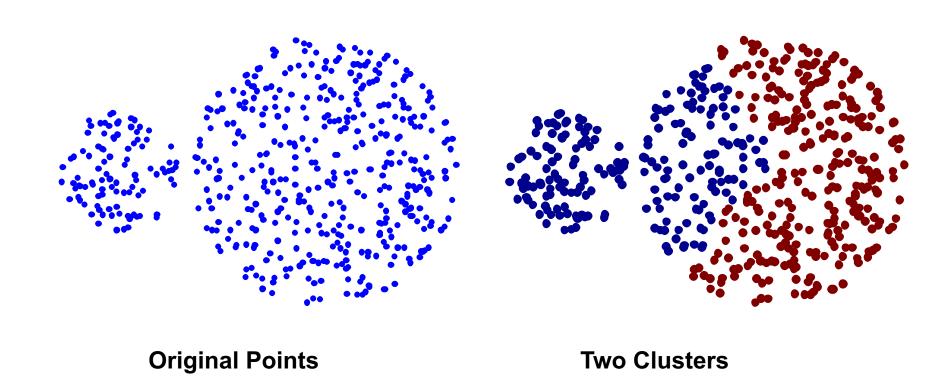
**Dendrogram** 

# STRENGTH OF MAX



Less susceptible to noise

# LIMITATIONS OF MAX

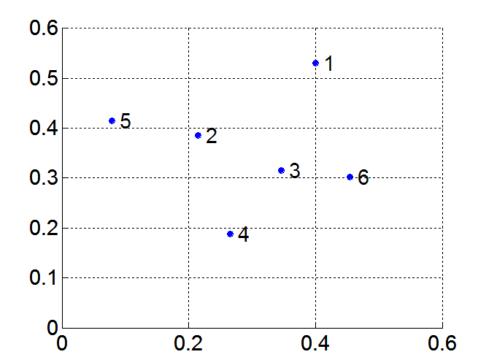


- Tends to break large clusters
- Biased towards globular clusters

## **GROUP AVERAGE**

Proximity of two clusters is the average of pairwise proximity between points in the two clusters.

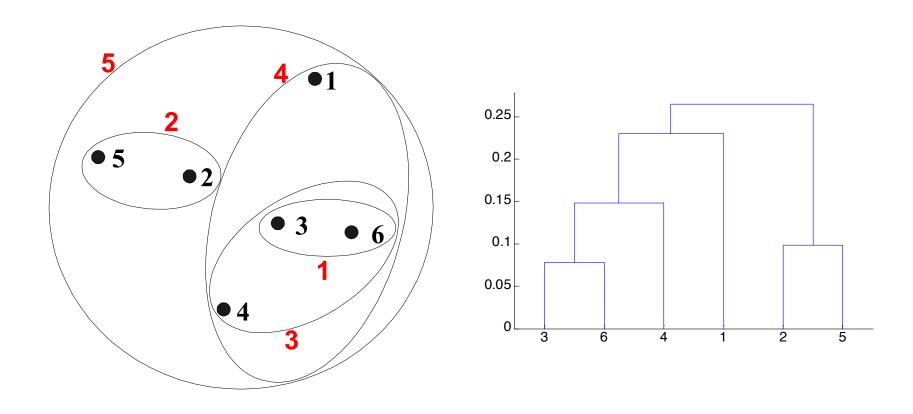
$$proximity(Cluster_{i}, Cluster_{j}) = \frac{\sum\limits_{\substack{p_{i} \in Cluster_{i} \\ p_{j} \in Cluster_{j}}} \sum\limits_{\substack{p_{i} \in Cluster_{j} \\ |Cluster_{i}| \times |Cluster_{j}|}} \frac{\sum\limits_{\substack{p_{i} \in Cluster_{i} \\ |Cluster_{i}|}} \sum\limits_{\substack{p_{i} \in Cluster_{j} \\ |Cluster_{i}|}} \frac{\sum\limits_{\substack{p_{i} \in Cluster_{i} \\ |Cluster_{j}|}} \frac{\sum\limits_{\substack{p_{i} \in Cluster_{i} \\ |Cluster_{i}|}} \frac{\sum\limits_{\substack{p_{i} \in Cluster_{i}|}} \frac{\sum\limits_{\substack{p_{i} \in$$



#### **Distance Matrix:**

	p1	p2	р3	p4	p5	p6
p1	0.00	0.24	0.22	0.37	0.34	0.23
p2	0.24	0.00	0.15	0.20	0.14	0.25
р3	0.22	0.15	0.00	0.15	0.28	0.11
p4	0.37	0.20	0.15	0.00	0.29	0.22
p5	0.34	0.14	0.28	0.29	0.00	0.39
p6	0.23	0.25	0.11	0.22	0.39	0.00

# HIERARCHICAL CLUSTERING: GROUP AVERAGE



**Nested Clusters** 

**Dendrogram** 

#### HIERARCHICAL CLUSTERING: GROUP AVERAGE

Compromise between Single and Complete Link
Max

- Strengths
  - Less susceptible to noise

- Limitations
  - Biased towards globular clusters

#### **CLUSTER SIMILARITY: WARD'S METHOD**

- Similarity of two clusters is based on the increase in squared error when two clusters are merged
  - Similar to group average if distance between points is distance squared

- Less susceptible to noise
- Biased towards globular clusters

- Hierarchical analogue of K-means
  - Can be used to initialize K-means

## HIERARCHICAL CLUSTERING: COMPARISON

