ESP-WROOM-32 Datasheet



Espressif Systems

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About This Guide

This document introduces the specifications of ESP-WROOM-32 hardware.

The document structure is as follows:

| Chapter | Title | Subject | |
|-----------|----------------------------|--|--|
| Chapter 1 | Preface | A preview of ESP-WROOM-32. | |
| Chapter 2 | Pin Definitions | The pin layout and descriptions. | |
| Chapter 3 | Functional Description | Description of major functional modules and protocols. | |
| Chapter 4 | Electrical Characteristics | The electrical characteristics and data of ESP-WROOM-32. | |
| Chapter 5 | Schematics | The schematics of ESP-WROOM-32. | |

Release Notes

| Date | Version | Release notes |
|---------|---------|----------------|
| 2016.08 | V1.0 | First release. |

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1. Preface

ESP-WROOM-32 is a generic but powerful WiFi-BT-BLE MCU module that targets a wide variety of applications ranging from low power sensor networks to the most demanding tasks such as voice encoding, music streaming and MP3 decoding.

The core of this module is the ESP32 chip, which is designed to be scalable and adaptive. There are 2 CPU cores that can be individually controlled or powered, and the clock frequency is adjustable from 80 MHz to 240 MHz. The user could even power off the CPU and make use of the low power coprocessor to constantly monitor the peripherals for changes or crossing of thresholds. ESP32 integrates a rich set of peripherals, ranging from capacitive touch sensors, Hall sensors, low noise sense amplifiers, SD card interface, Ethernet, high speed SDIO/SPI, UART, I2S and I2C.

The integration of Bluetooth, Bluetooth LE and Wi-Fi ensures that a wide range of applications can be targeted, and that it is future proof: using Wi-Fi allows a large physical range and direct connection to the internet through a Wi-Fi router, while using Bluetooth allows the user to conveniently connect to the phone or broadcast low energy beacons for its detection. The sleep current of the ESP32 chip is less than 5 μ A, making it suitable for battery powered and wearable electronics applications. ESP-WROOM-32 supports data rates up to 150 Mbps, and 22 dBm output power at the PA to ensure the widest physical range. As such the chip does offer industry leading specifications and the best optimized performance for electronic integration, range and power consumption, and connectivity.

The operating system chosen for ESP32 is freeRTOS with LWIP; TLS 1.2 with hardware acceleration is built in as well. Encrypted over the air (OTA) upgrade is also supported, so that developers can continually upgrade their products even after their release. New SDK features, tutorials and example applications will be released over the next few months. The software releases are covered under the ESP32 bug bounty program and any bugs can be reported to bugbounty@espressif.com. As the SDK of ESP-WROOM-32 or ESP32 is open-source, the user can build his own platforms and operating systems. For more in-depth discussion of this, the developer can contact john.lee@espressif.com.

ESP-WROOM-32 has Espressif's long term support — ESP32 will be covered under Espressif's longevity program and be available for the next 12 years. The design of ESP-WROOM-32 will be open-source when it has been fully optimized. It is noted that several TVS components have been integrated in the current version of the module to protect the touch sensor pins of the module from ESD events, since it is expected that many developers will be testing this with their bare fingers. These TVS components will be removed from the module after the beta program. Feedbacks about the module, chip, API or firmware can be sent to feedback@espressif.com.

Table 1 provides the specifications of ESP-WROOM-32.

Table 1: ESP-WROOM-32 Specifications

| Categories | Items | Specifications | | |
|------------|--|---|--|--|
| | Standards | FCC, CE, TELEC, KCC | | |
| \A/: =: | Dratacala | 802.11 b/g/n/d/e/i/k/r (802.11n up to 150 Mbps) | | |
| Wi-Fi | Protocols | A-MPDU and A-MSDU aggregation and 0.4 μs | | |
| | | guard interval support | | |
| | Frequency range | 2.4 ~ 2.5 GHz | | |
| | Protocols | Bluetooth v4.2 BR/EDR and BLE specification | | |
| | Radio | NZIF receiver with -98 dBm sensitivity | | |
| Bluetooth | nadio | Class-1, class-2 and class-3 transmitter | | |
| | | AFH | | |
| | Audio | CVSD and SBC | | |
| | Module interface | SD card, UART, SPI, SDIO, I2C, LED PWM, Motor | | |
| | Module interface | PWM, I2S, I2C, IR | | |
| | | GPIO, capacitive touch sensor, ADC, DAC, LNA | | |
| | | pre-amplier | | |
| Hardware | On-chip sensor Hall sensor, temperature sensor | | | |
| | On-board clock | 26 MHz crystal, 32 kHz crystal | | |
| | Operating voltage | 2.2 ~ 3.6V | | |
| | Operating current | Average: 80 mA | | |
| | Operating temperature range | -40°C ~ 85°C * | | |
| | Ambient temperature range | Normal temperature | | |
| | Package size | 18 mm x 20 mm x 3 mm | | |
| | Wi-Fi mode | Station/softAP/SoftAP+station/P2P | | |
| | Security | WPA/WPA2, WPS, TLS | | |
| | Encryption | WEP/TKIP/AES/RSA/ECC/SHA | | |
| Software | Firmware upgrade | UART Download / OTA (via network) / download | | |
| | | and write firmware via host | | |
| | Software development | Supports Cloud Server Development / SDK for | | |
| | | custom firmware development | | |
| | Network protocols | IPv4, IPv6, SSL, TCP/UDP/HTTP/FTP | | |
| | User configuration | AT instruction set, cloud server, Android/iOS App | | |

Note:

^{*} ESP-WROOM-32 with high temperature range option (-40°C ~ 125°C) is available for custom order.

2.1 Pin Layout 2 PIN DEFINITIONS

2. Pin Definitions

2.1 Pin Layout

The pin distribution of ESP-WROOM-32 module is illustrated in Figure 1.

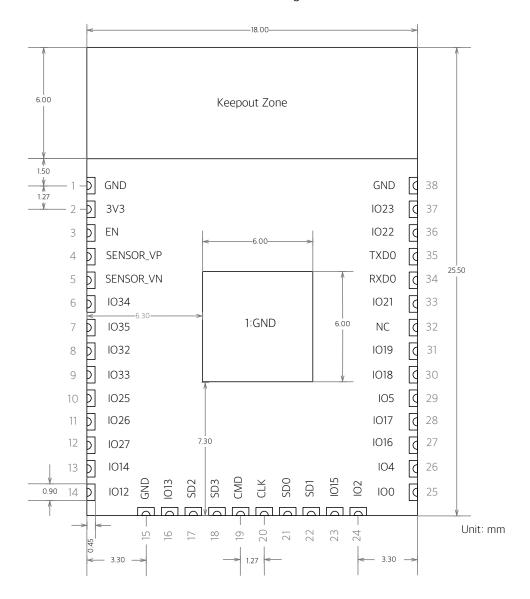


Figure 1: Top View of ESP-WROOM-32

Table 2: ESP-WROOM-32 Dimensions

| Length | Width | Height | PAD size (bottom) | Pin pitch |
|--------|---------|---------|-------------------|-----------|
| 18 mm | 25.5 mm | 2.55 mm | 0.45 mm x 0.9 mm | 1.27 mm |

2.2 Pin Description 2 PIN DEFINITIONS

2.2 Pin Description

ESP-WROOM-32 has 38 pins. See pin definitions in Table 3.

Table 3: ESP-WROOM-32 Pin Definitions

| Name | No. | Function | |
|-----------|-----|--|--|
| GND | 1 | Ground | |
| 3V3 | 2 | Power supply. | |
| EN | 3 | Chip-enable signal. Active high. | |
| SENSOR_VP | 4 | GPI36, SENSOR_VP, ADC_H, ADC1_CH0, RTC_GPI00 | |
| SENSOR_VN | 5 | GPI39, SENSOR_VN, ADC1_CH3, ADC_H, RTC_GPIO3 | |
| IO34 | 6 | GPI34, ADC1_CH6, RTC_GPIO4 | |
| IO35 | 7 | GPI35, ADC1_CH7, RTC_GPIO5 | |
| IO32 | 8 | GPIO32, XTAL_32K_P (32.768 kHz crystal oscillator input), ADC1_CH4, | |
| | | TOUCH9, RTC_GPIO9 | |
| IO33 | 9 | GPIO33, XTAL_32K_N (32.768 kHz crystal oscillator output), ADC1_CH5, | |
| | | TOUCH8, RTC_GPIO8 | |
| IO25 | 10 | GPIO25, DAC_1, ADC2_CH8, RTC_GPIO6, EMAC_RXD0 | |
| IO26 | 11 | GPIO26, DAC_2, ADC2_CH9, RTC_GPIO7, EMAC_RXD1 | |
| 1027 | 12 | GPIO27, ADC2_CH7, TOUCH7, RTC_GPIO17, EMAC_RX_DV | |
| IO14 | 13 | GPIO14, ADC2_CH6, TOUCH6, RTC_GPIO16, MTMS, HSPICLK, HS2_CLK, | |
| | | SD_CLK, EMAC_TXD2 | |
| IO12 | 14 | GPIO12, ADC2_CH5, TOUCH5, RTC_GPIO15, MTDI, HSPIQ, HS2_DATA2, | |
| | | SD_DATA2, EMAC_TXD3 | |
| GND | 15 | Ground | |
| IO13 | 16 | GPIO13, ADC2_CH4, TOUCH4, RTC_GPIO14, MTCK, HSPID, HS2_DATA3, | |
| | | SD_DATA3, EMAC_RX_ER | |
| SHD/SD2 | 17 | GPIO9, SD_DATA2, SPIHD, HS1_DATA2, U1RXD | |
| SWP/SD3 | 18 | GPIO10, SD_DATA3, SPIWP, HS1_DATA3, U1TXD | |
| SCS/CMD | 19 | GPIO11, SD_CMD, SPICS0, HS1_CMD, U1RTS | |
| SCK/CLK | 20 | GPIO6, SD_CLK, SPICLK, HS1_CLK, U1CTS | |
| SDO/SD0 | 21 | GPIO7, SD_DATA0, SPIQ, HS1_DATA0, U2RTS | |
| SDI/SD1 | 22 | GPIO8, SD_DATA1, SPID, HS1_DATA1, U2CTS | |
| IO15 | 23 | GPIO15, ADC2_CH3, TOUCH3, MTDO, HSPICS0, RTC_GPIO13, HS2_CMD, | |
| | | SD_CMD, EMAC_RXD3 | |
| IO2 | 24 | GPIO2, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATA0, | |
| | | SD_DATA0 | |
| 100 | 25 | GPIO0, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK | |
| 104 | 26 | GPIO4, ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1, | |
| | | SD_DATA1, EMAC_TX_ER | |
| IO16 | 27 | GPIO16, HS1_DATA4, U2RXD, EMAC_CLK_OUT | |
| IO17 | 28 | GPIO17, HS1_DATA5, U2TXD, EMAC_CLK_OUT_180 | |
| IO5 | 29 | GPIO5, VSPICS0, HS1_DATA6, EMAC_RX_CLK | |
| IO18 | 30 | GPIO18, VSPICLK, HS1_DATA7 | |
| IO19 | 31 | GPIO19, VSPIQ, U0CTS, EMAC_TXD0 | |
| NC | 32 | - | |

2.2 Pin Description 2 PIN DEFINITIONS

| Name | No. | Function | |
|------|-----|-----------------------------------|--|
| IO21 | 33 | GPIO21, VSPIHD, EMAC_TX_EN | |
| RXD0 | 34 | GPIO3, U0RXD, CLK_OUT2 | |
| TXD0 | 35 | GPIO1, U0TXD, CLK_OUT3, EMAC_RXD2 | |
| IO22 | 36 | GPIO22, VSPIWP, U0RTS, EMAC_TXD1 | |
| IO23 | 37 | GPIO23, VSPID, HS1_STROBE | |
| GND | 38 | Ground | |

During the chip power-on reset, the latches of the strapping pins sample the voltage level as strapping bits of "0" or "1", and hold these bits until the chip is power-down or shut-down.

Each strapping pin is with the internal pull-up or the internal pull-down during the chip reset. If a strapping pin is unconnected or the connected external circuit is high-impendence, the internal weak pull-up/pull-down will determine the input level of the strapping pins. So these internal pull-up/pull-down provide the default values for these strapping pins. To change the strapping bit values, Users can apply the external pull-down/pull-up resistances, or apply the host MCU's GPIOs to control the voltage level of these pins when powering on ESP32.

After reset, the strapping pins work as the normal functions pins.

Table 4: Strapping Pins

| | Voltage of Internal LDO (VDD_SDIO) | | | | | |
|-------|---------------------------------------|--|--------------|---------------------|--------------------|--|
| Pin | Default | 3.3 | 3V | 1.8V | | |
| MTDI | Pull-down | (|) | | 1 | |
| | | | Booting Mode | | | |
| Pin | Default | SPL | Boot | Downlo | ad Boot | |
| GPIO0 | Pull-up | - | 1 | | 0 | |
| GPIO2 | Pull-down | Don't | -care | 0 | | |
| | Debugging Log on U0TXD During Booting | | | | | |
| Pin | Default | U0TXD . | Toggling | UOTXI |) Silent | |
| MTDO | Pull-up | 1 | | | 0 | |
| | Timing of SDIO Slave | | | | | |
| Pin | Default | Falling-edge Input Falling-edge Input | | Rising-edge Input | Rising-edge Input | |
| | | Falling-edge Output Rising-edge Output | | Falling-edge Output | Rising-edge Output | |
| MTDO | Pull-up | 0 0 | | 1 | 1 | |
| GPIO5 | Pull-up | 0 1 | | 0 | 1 | |

Note:

Firmware can configure register bits to change the setting of "Voltage of Internal LDO" and "Timing of SDIO Slave" after booting.

3. Functional Descriptions

This chapter describes the modules and functions implemented in ESP-WROOM-32.

3.1 CPU and Internal Memory

ESP32 contains two low-power Xtensa® 32-bit LX6 microprocessors. The internal memory includes:

- 448 KBytes ROM for booting and core functions.
- 520 KBytes on-chip SRAM for data and instruction.
- 8 KBytes SRAM in RTC, which is called RTC SLOW Memory and can be used for co-processor accessing during the deep sleep mode.
- 8 KBytes SRAM in RTC, which is called RTC FAST Memory and can be used for data storage and main CPU during RTC Boot from the deep sleep mode.
- 1 Kbit of EFUSE, of which 256 bits are used for the system (MAC address and chip configuration) and the remaining 768 bits are reserved for customer applications, including Flash-Encryption and Chip-ID.

3.2 External Flash and SRAM

ESP32 supports 4 x 16 MBytes of external QSPI flash and SRAM with hardware encryption based on AES to protect developer's programs and data.

ESP32 accesses external QSPI flash and SRAM by the high-speed caches. Up to 16 MBytes of external flash are memory mapped into the CPU code space, supporting 8, 16 and 32-bit access. Code execution is supported. Up to 8 MByte of external SRAM are memory mapped into the CPU data space, supporting 8, 16 and 32-bit access. Data read is supported on the flash and SRAM. Data write is supported on the SRAM.

3.3 Crystal Oscillators

The frequencies of the main crystal oscillator supported include 40 MHz, 26 MHz and 24 MHz. The accuracy of crystal oscillators applied should be ± 10 PPM, and the operating temperature range -40° C to 85°C.

When using the downloading tools, remember to select the right crystal oscillator type. In circuit design, capacitors C1 and C2 that connects to the earth, are added to the input and output terminals of the crystal oscillator respectively. The values of the two capacitors can be flexible, ranging from 6 pF to 22 pF. However, the specific capacitive values of C1 and C2 depend on further testing and adjustment of the overall performance of the whole circuit. Normally, the capacitive values of C1 and C2 are within 10 pF if the crystal oscillator frequency is 26 MHz, while 10pF<C1 and C2<22pF if the crystal oscillator frequency is 40 MHz.

The frequency of the RTC crystal oscillator is typically 32 kHz or 32.768 kHz. The accuracy can be out of the range of ± 20 PPM, since the internal calibration is applied to correct the frequency offset. When the chip operates in low power modes, the application chooses the external low speed (32 kHz) crystal clock rather than the internal RC oscillators to achieve the accurate wakeup time.

3.3.1 Power Consumption

With the advanced power management technologies, ESP32 can switch between different power modes as follows:

Power mode

- Active mode: chip radio is powered on. The chip can receive, transmit, or listen.
- Modem-sleep mode: the CPU is operational and the clock is configurable. Wi-Fi / Bluetooth baseband and radio are disabled.
- Light-sleep mode: the CPU is paused. The RTC and ULP-coprocessor are running. Any wake-up events (MAC, host, RTC timer, or external interrupts) will wake up the chip.
- Deep-sleep mode: Only RTC is powered on. Wi-Fi and Bluetooth connection data are stored in RTC memory. The ULP-coprocessor can work.
- Hibernate mode: The internal 8MHz oscillator and ULP-coprocessor are disabled. The RTC recovery
 memory are power-down. Only one RTC timer on the slow clock and some RTC GPIOs are active. The
 RTC timer or the RTC GPIOs can wake up the chip from the Hibernate mode.

• Sleep Pattern

- Association sleep pattern: The power mode switches between the active mode and light sleep mode during this sleep pattern. The CPU, Wi-Fi, Bluetooth, and radio wake up at pre-determined intervals to keep Wi-Fi / BT connections alive.
- Sensor-monitored deep-sleep pattern: The ULP co-processor is enabled or disabled at intervals depending on the measured data from sensors.

The power consumption varies with different power modes/sleep patterns and work status of functional modules (see Table 5).

Table 5: Power Consumption by Power Modes

| Power mode | Comment | Power consumption |
|--------------------------|--|----------------------------|
| | Wi-Fi Tx packet 13 dBm ~ 21 dBm | 160 ~ 260 mA |
| Active mode (RF working) | Wi-Fi / BT Tx packet 0 dBm | 120 mA |
| Active mode (hr working) | Wi-Fi / BT Rx and listening | 80 ~ 90 mA |
| | Association sleep pattern (by light sleep) | 0.9 mA@DTIM3, 1.2 mA@DTIM1 |
| | | Max speed: 20 mA |
| Modem-sleep mode | The CPU is powered on. | Normal: 5 ~ 10 mA |
| | | Slow speed: 3 mA |
| Light-sleep mode | - | 0.8 mA |
| | The ULP-coprocessor is powered on | 0.5 mA |
| Deep-sleep mode | Sensor-monitored deep sleep pattern | 25 μA @1% duty |
| | RTC timer + recovery-memory | 20 μΑ |
| Hibernate mode | RTC timer only | 2.5 μΑ |

3.4 Interface Description

Table 6: Interface Description

| Interface | Signal | Pin | Function | |
|----------------------|-----------|-----------|--|--|
| | ADC1_CH0 | SENSOR_VP | | |
| | ADC1_CH3 | SENSOR_VN | | |
| | ADC1_CH4 | IO32 | | |
| | ADC1_CH5 | IO33 | | |
| | ADC1_CH6 | IO34 | | |
| | ADC1_CH7 | IO35 | | |
| | ADC2_CH0 | IO4 | | |
| ADC | ADC2_CH1 | IO0 | Two 12-bit SAR ADCs | |
| ADO | ADC2_CH2 | IO2 | 1 IWO 12-DIL SAN ADOS | |
| | ADC2_CH3 | IO15 | | |
| | ADC2_CH4 | IO13 | | |
| | ADC2_CH5 | IO12 | | |
| | ADC2_CH6 | IO14 | | |
| | ADC2_CH7 | 1027 | | |
| | ADC2_CH8 | IO25 | | |
| | ADC2_CH9 | IO26 | | |
| Ultra Low Noise | SENSOR_VP | IO36 | Provides about 60dB gain by using larger | |
| Analog Pre-Amplifier | SENSOR_VN | IO39 | capacitors on PCB | |
| DAC | DAC_1 | IO25 | Two 8-bit DACs | |
| DAC | DAC_2 | IO26 | 1 IWO 8-BIL DACS | |
| | TOUCH0 | IO4 | | |
| | TOUCH1 | IO0 | | |
| | TOUCH2 | IO2 | | |
| | TOUCH3 | IO15 | | |
| Touch Sensor | TOUCH4 | IO13 | Capacitive touch sensors | |
| TOUCH Sensor | TOUCH5 | IO12 | - Capacitive touch sensors | |
| | TOUCH6 | IO14 | | |
| | TOUCH7 | IO27 | | |
| | TOUCH8 | IO33 | | |
| | TOUCH9 | IO32 | | |
| | HS2_CLK | MTMS | | |
| | HS2_CMD | MTDO | | |
| SD / SDIO / MMC | HS2_DATA0 | IO2 | Cumparts CD mamaric said VO 01 start law | |
| Host Controller | HS2_DATA1 | IO4 | Supports SD memory card V3.01 standard | |
| | HS2_DATA2 | MTDI | | |
| | HS2_DATA3 | MTCK | | |

| Interface | Signal | Pin | Function | | |
|-----------|--------------------|------------|--|--|--|
| | PWM0_OUT0~2 | | | | |
| | PWM1_OUT_IN0~2 | | Thus shapped of 10 bit timesus suppusts | | |
| | PWM0_FLT_IN0~2 | | Three channels of 16-bit timers generate | | |
| Matax DMM | PWM1_FLT_IN0~2 | Amy ODIO | PWM waveforms; each has a pair of | | |
| Motor PWM | PWM0_CAP_IN0~2 | - Any GPIO | output signals. Three fault detection | | |
| | PWM1_CAP_IN0~2 | | signals. Three even capture signals. Three | | |
| | PWM0_SYNC_IN0~2 | | sync signals. | | |
| | PWM1_SYNC_IN0~2 | | | | |
| LED PWM | ledc_hs_sig_out0~7 | Any CDIO | 16 independent channels @80MHz | | |
| | ledc_ls_sig_out0~7 | - Any GPIO | clock/RTC CLK. Duty accuracy: 16bits. | | |
| | U0RXD_in | | Two UART devices with hardware | | |
| | U0CTS_in | | flow-control and DMA | | |
| | U0DSR_in | | | | |
| | U0TXD_out | - | | | |
| | U0RTS_out | | | | |
| | U0DTR_out | | | | |
| UART | U1RXD_in | Any GPIO | | | |
| UANT | U1CTS_in | Any GFIO | | | |
| | U1TXD_out | | | | |
| | U1RTS_out | | | | |
| | U2RXD_in | | | | |
| | U2CTS_in | | | | |
| | U2TXD_out | | | | |
| | U2RTS_out | | | | |
| | I2CEXT0_SCL_in | | | | |
| | I2CEXTO_SDA_in | | | | |
| | I2CEXT1_SCL_in | | | | |
| | I2CEXT1_SDA_in | Any GPIO | Two I2C devices in slave or master modes | | |
| 120 | I2CEXT0_SCL_out | ALLY GETO | 100 120 devices in sidve of master modes | | |
| | I2CEXT0_SDA_out | | | | |
| | I2CEXT1_SCL_out | | | | |
| | I2CEXT1_SDA_out | | | | |

| Interface | Signal | Pin | Function |
|---------------------|--------------------|-----------|--|
| | I2S0I_DATA_in0~15 | | |
| | I2S0O_BCK_in | | |
| | 12S0O_WS_in | | |
| | I2S0I_BCK_in | | |
| | I2S0I_WS_in | | |
| | I2S0I_H_SYNC | | |
| | I2S0I_V_SYNC | | |
| | I2S0I_H_ENABLE | | |
| | I2S0O_BCK_out | | |
| | I2S0O_WS_out | | |
| | I2S0I_BCK_out | | |
| | I2S0I_WS_out | | |
| 128 | I2S0O_DATA_out0~23 | Any GPIO | Stereo input and stereo output from/to the |
| 123 | I2S1I_DATA_in0~15 | | audio codec |
| | I2S1O_BCK_in | | |
| | I2S10_WS_in | | |
| | I2S1I_BCK_in | | |
| | I2S1I_WS_in | | |
| | I2S1I_H_SYNC | | |
| | I2S1I_V_SYNC | | |
| | I2S1I_H_ENABLE | | |
| | I2S1O_BCK_out | | |
| | I2S1O_WS_out | | |
| | I2S1I_BCK_out | | |
| | I2S1I_WS_out | | |
| | I2S1O_DATA_out0~23 | | |
| Remote Controller | RMT_SIG_IN0~7 | Any GPIO | Eight channels of IR transmitter and |
| LIGITIOLE COLLINIEL | RMT_SIG_OUT0~7 | Ally GFIO | receiver for various waveforms |

| Interface | Signal | Pin | Function |
|------------------|------------------|----------|--|
| | SPIHD | SHD/SD2 | |
| | SPIWP | SWP/SD3 | |
| | SPICS0 | SCS/CMD | |
| | SPICLK | SCK/CLK | |
| | SPIQ | SDO/SD0 | |
| | SPID | SDI/SD1 | |
| | HSPICLK | IO14 | |
| | HSPICS0 | IO15 | Ourse sets Otses devid ODL Devid ODL seed |
| Davidle OCDI | HSPIQ | IO12 | Supports Standard SPI, Dual SPI, and |
| Parallel QSPI | HSPID | IO13 | Quad SPI that can be connected to the |
| | HSPIHD | IO4 | external flash and SRAM |
| | HSPIWP | IO2 | |
| | VSPICLK | IO18 | |
| | VSPICS0 | IO5 | |
| | VSPIQ | IO19 | |
| | VSPID | IO23 | |
| | VSPIHD | IO21 | |
| | VSPIWP | IO22 | |
| | HSPIQ_in/_out | | Standard SPI consists of clock, |
| | HSPID_in/_out | | chip-select, MOSI and MISO. These SPIs |
| | HSPICLK_in/_out | | can be connected to LCD and other |
| | HSPI_CS0_in/_out | | external devices. They support the |
| Canaval Duva and | HSPI_CS1_out | | following features: |
| General Purpose | HSPI_CS2_out | Any GPIO | (a) both master and slave modes; |
| SPI | VSPIQ_in/_out | | (b) 4 sub-modes of the SPI format transfer |
| | VSPID_in/_out | | that depend on the polarity (POL) and the |
| | VSPICLK_in/_out | | phase (PHA); |
| | VSPI_CS0_in/_out | | (c) CLK frequencies by a divider; |
| | VSPI_CS1_out | | (d) up to 64byte FIFO and DMA. |
| | VSPI_CS2_out | | |
| | MTDI | IO12 | |
| ITAC | MTCK | IO13 | ITAC for ooth your doly and to |
| JTAG | MTMS | IO14 | JTAG for software debugging |
| | MTDO | IO15 | |

| Interface | Signal | Pin | Function |
|------------|------------------|----------|--|
| | SD_CLK | IO6 | |
| | SD_CMD | IO11 | SDIO interface that conforms to the |
| SDIO Slave | SD_DATA0 | 107 | |
| SDIO Slave | SD_DATA1 | IO8 | industry standard SDIO 2.0 card specification. |
| | SD_DATA2 | 109 | - specification. |
| | SD_DATA3 | IO10 | |
| | EMAC_TX_CLK | IO0 | |
| | EMAC_RX_CLK | IO5 | |
| | EMAC_TX_EN | IO21 | |
| | EMAC_TXD0 | IO19 | |
| | EMAC_TXD1 | 1022 | |
| | EMAC_TXD2 | IO14 | |
| | EMAC_TXD3 | IO12 | |
| | EMAC_RX_ER | IO13 | |
| | EMAC_RX_DV | 1027 | |
| | EMAC_RXD0 | IO25 | |
| EMAC | EMAC_RXD1 | IO26 | Ethernet MAC with MII/RMII interface |
| | EMAC_RXD2 | TXD | |
| | EMAC_RXD3 | IO15 | |
| | EMAC_CLK_OUT | IO16 | |
| | EMAC_CLK_OUT_180 | IO17 | |
| | EMAC_TX_ER | 104 | |
| | EMAC_MDC_out | Any GPIO | |
| | EMAC_MDI_in | Any GPIO | |
| | EMAC_MDO_out | Any GPIO | |
| | EMAC_CRS_out | Any GPIO | |
| | EMAC_COL_out | Any GPIO | |

Note:

Functions of Motor PWM, LED PWM, UART, I2C, I2S and Remote Controller can be configured to any GPIO.

4. Electrical Specifications

Note:

The specifications in this charpter are tested in general condition: VBAT = 3.3V, TA = 27°C, unless otherwise specified.

4.1 Absolute Maximum Ratings

Table 7: Absolute Maximum Ratings

| Rating | Condition | Value | Unit |
|-------------------------------|---------------------|-------------|------|
| Storage temperatue | - | -40 ~ 85 | °C |
| Maximum soldering temperature | - | 260 | °C |
| Supply voltage | IPC/JEDEC J-STD-020 | +3.0 ~ +3.6 | V |

4.2 Recommended Operating Conditions

Table 8: Recommended Operating Conditions

| Operating condition | Symbol | Min | Тур | Max | Unit |
|-----------------------|--------|-----|-----|-----|------|
| Operating temperature | - | -40 | 20 | 85 | °C |
| Supply voltage | VDD | 3.0 | 3.3 | 3.6 | V |

4.3 Digital Terminal Characteristics

Table 9: Digital Terminal Characteristics

| Terminals | Symbol | Min | Туре | Max | Unit |
|-------------------------|----------|---------|------|---------|------|
| Input logic level low | V_{IL} | -0.3 | - | 0.25VDD | V |
| Input logic level high | V_{IH} | 0.75VDD | - | VDD+0.3 | V |
| Output logic level low | V_{OL} | N | - | 0.1VDD | V |
| Output logic level high | V_{OH} | 0.8VDD | - | N | V |

4.4 Wi-Fi Radio

Table 10: Wi-Fi Radio Characteristics

| Description | Min | Typical | Max | Unit | | |
|--------------------|----------------------------|---------|------|------|--|--|
| Ge | neral Characteris | tics | | | | |
| Input frequency | 2412 | - | 2484 | MHz | | |
| Input impedance | - | 50 | - | | | |
| Input reflection | - | - | -10 | dB | | |
| Output power of PA | 15.5 | 16.5 | 21.5 | dBm | | |
| | Sensitivity | | | | | |
| DSSS, 1 Mbps | - | -98 | - | dBm | | |
| CCK, 11 Mbps | - | -90 | - | dBm | | |
| OFDM, 6 Mbps | - | -93 | - | dBm | | |
| OFDM, 54 Mbps | - | -75 | - | dBm | | |
| HT20, MCS0 | - | -93 | - | dBm | | |
| HT20, MCS7 | - | -73 | - | dBm | | |
| HT40, MCS0 | - | -90 | - | dBm | | |
| HT40, MCS7 | - | -70 | - | dBm | | |
| MCS32 | - | -91 | - | dBm | | |
| Adjad | Adjacent Channel Rejection | | | | | |
| OFDM, 6 Mbps | - | 37 | - | dB | | |
| OFDM, 54 Mbps | - | 21 | | dB | | |
| HT20, MCS0 | - | 37 | | dB | | |
| HT20, MCS7 | - | 20 | | dB | | |

4.5 Bluetooth Radio

4.5.1 Receiver

Table 11: Receiver Characteristics - BLE

| Parameter | Conditions | Min | Туре | Max | Unit |
|-----------------------------------|---------------------|-----|------|-----|------|
| Sensitivity @0.1% BER | - | - | -98 | - | dBm |
| Maximum received signal @0.1% BER | - | 0 | - | - | dBm |
| Co-channel C/I | - | - | +10 | - | dB |
| Adjacent channel selectivity C/I | F=F0 + 1 MHz | - | -5 | - | dB |
| | F=F0 - 1 MHz | - | -5 | - | dB |
| | F=F0 + 2 MHz | - | -35 | - | dB |
| | F=F0 - 2 MHz | - | -35 | - | dB |
| | F=F0 + 3 MHz | - | -25 | - | dB |
| | F=F0 - 3 MHz | - | -45 | - | dB |
| | 30 MHz - 2000 MHz | -10 | - | - | dBm |
| Out-of-band blocking performance | 2000 MHz - 2400 MHz | -27 | - | - | dBm |
| | 2500 MHz - 3000 MHz | -27 | - | - | dBm |
| | 3000 MHz - 12.5 GHz | -10 | - | - | dBm |

| Intermodulation dBr |
|---------------------|
|---------------------|

4.5.2 Transmit

Table 12: Transmit Characteristics - BLE

| Parameter | Conditions | Min | Туре | Max | Unit |
|---|---------------|-----|-------|-----|---------|
| RF transmit power | - | - | +7.5 | +10 | dBm |
| RF power control range | - | - | 25 | - | dB |
| | F=F0 + 1 MHz | - | -14.6 | - | dBm |
| | F=F0 - 1 MHz | - | -12.7 | - | dBm |
| | F=F0 + 2 MHz | - | -44.3 | - | dBm |
| Adiacont channel transmit newer | F=F0 - 2 MHz | - | -38.7 | - | dBm |
| Adjacent channel transmit power | F=F0 + 3 MHz | - | -49.2 | - | dBm |
| | F=F0 - 3 MHz | - | -44.7 | - | dBm |
| | F=F0 + >3 MHz | - | -50 | - | dBm |
| | F=F0 - >3 MHz | - | -50 | - | dBm |
| $\Delta {\rm f1}_{avg} { m Maximum modulation}$ | - | - | 265 | - | kHz |
| Δ f2 $_{max}$ Minimum modulation | - | - | 247 | - | kHz |
| Δ f2 $_{avg}/\Delta$ f1 $_{avg}$ | - | - | -0.92 | - | - |
| ICFT | - | - | -10 | - | kHz |
| Drift rate | - | - | 0.7 | - | kHz/50 |
| | | | | | μ S |
| Drift | - | - | 2 | - | kHz |

4.6 Reflow Profile

Table 13: Reflow Profile

| Item | Value |
|---|---------------------------|
| T_s max to TL (Ramp-up Rate) | 3°C/second max |
| Preheat | |
| Temperature Min. (T_s Min.) | 150°C |
| Temperature Typ. $(T_s \text{ Typ.})$ | 175°C |
| Temperature Min. (T_s Max.) | 200°C |
| Time (T_s) | 60 ~ 180 seconds |
| Ramp-up rate (T_L to T_P) | 3°C/second max |
| Time maintained above: –Temperature (T_L) /Time (T_L) | 217°C/60 ~ 150 seconds |
| Peak temperature (T _P) | 260°C max, for 10 seconds |
| Target peak temperature (T _P Target) | 260°C +0/-5°C |
| Time within 5°C of actual peak (t _P) | 20 ~ 40 seconds |
| T_S max to T_L (Ramp-down Rate) | 6°C/second max |
| Tune 25°C to Peak Temperature (t) | 8 minutes max |

Note:

The 32 kHz crystal is on board connected to ESP32's IO32 and IO33. To use ADC, Touch or GPIO functions of IO32 and IO33, please remove the 32 kHz crystal and its capacitors — C13 and C17, and solder the 0ohm resisters — R5 and R6.

5. Schematics

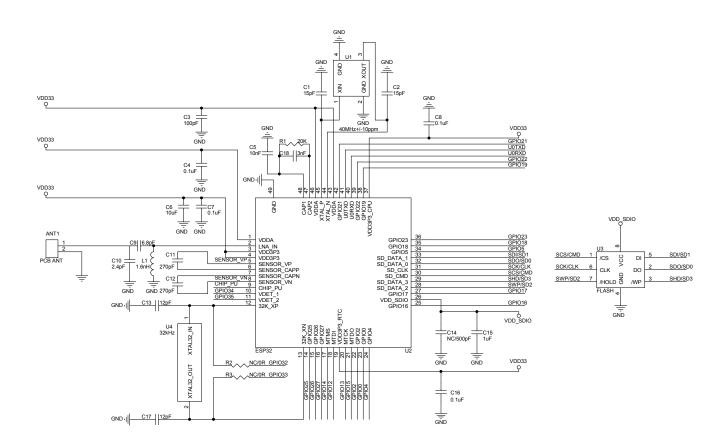


Figure 2: ESP-WROOM-32 Schematics