Chapter Two Simple Sorting and Searching Algorithms

Why do we study sorting and searching algorithms?

- These algorithms are the most common and useful tasks operated by computer system.
- Computers spend a lot of time for searching and sorting.

1. Simple Searching algorithms

Searching:- is a process of finding an element in a list of items or determining that the item is not in the list.

- To keep things simple, we shall deal with a list of numbers.
- A search method looks for a key, arrives by parameter.
- By convention, the method will return the index of the element corresponding to the key or, if unsuccessful, the value -1.

There are two simple searching algorithms:

- a) Sequential Search, and
- b) Binary Search
- a). Sequential Searching (Linear)
 - The most natural way of searching an item.
 - Easy to understand and implement.

Algorithm:

- In a linear search, we start with top (beginning) of the list, and compare the element at top with the key.
- If we have a match, the search terminates and the index number is returned.
- If not, we go on the next element in the list.
- If we reach the end of the list without finding a match, we return -1.

Implementation: Assume the size of the list is n.

```
int LinearSearch(int list[], int key)
                             Complexity Analysis:
    index=-1;
                                     Big-Oh of sequential
                                     searching > How many
    for(int i=0; i < n; i++)
                                     comparisons are made in
                                     the worst case? n
       if(list[i] = = key)
                                     →O(n).
           index=i;
           break:
           return index;
```

b). Binary Searching

- Assume sorted data.
- Use Divide and conquer strategy (approach).

Algorithm:

- In a binary search, we look for the key in the *middle* of the list. If we get a match, the search is over.
- II. If the key is greater than the element in the middle of the list, we make the top (upper) half the list to search.
- III. If the key is smaller, we make the bottom (lower) half the list to search.
- Repeat the above <u>steps</u> (I,II and III) until one element remains.
- If this element matches return the index of the element, else return -1 index. (-1 shows that the key is not in the list).

Implementation:

```
int BinarySearch(int list[], int key)
                                      if(found = = 0)
                                         index=-1;
  int found=0,index=0;
                                       else
  int top=n-1,bottom=0,middle;
                                         index=middle;
do{
                                       return index:
    middle=(top + bottom)/2;
  if(key==list[middle])
     found=1;
                                      Complexity Analysis:
  else{
     if(key<list[middle])</pre>
                                       Example: Find Big-Oh of
        top=middle-1;
                                       Binary search algorithm in
     else
                                      the worst case analysis.
       bottom=middle+1;
                                              → O(log n)
\width $$ \while(found = = 0 \&\& top > = bottom);
```

2. Simple Sorting Algorithms

Sorting: is a process of reordering a list of items in either increasing or decreasing order.

- Ordering a list of items is fundamental problem of computer science.
- Sorting is the most important operation performed by computers.
- Sorting is the first step in more complex algorithms.

Two basic properties of sorting algorithms:

<u>In-place:</u> It is possible to sort very large lists without the need to allocate additional working storage.

Simple Sorting Algorithms

<u>Stable:</u> If two elements that are equal, they will remain in the same relative position after sorting is completed.

Two classes of sorting algorithms:

$O(n^2)$:

 Includes the bubble, insertion, and selection sorting algorithms.

O(nlog n):

- Includes the heap, merge, and quick sorting algorithms.
 Simple sorting algorithms include:
 - i. Simple sorting
 - ii. Bubble Sorting
 - iii. Selection Sorting
 - iv. Insertion Sorting

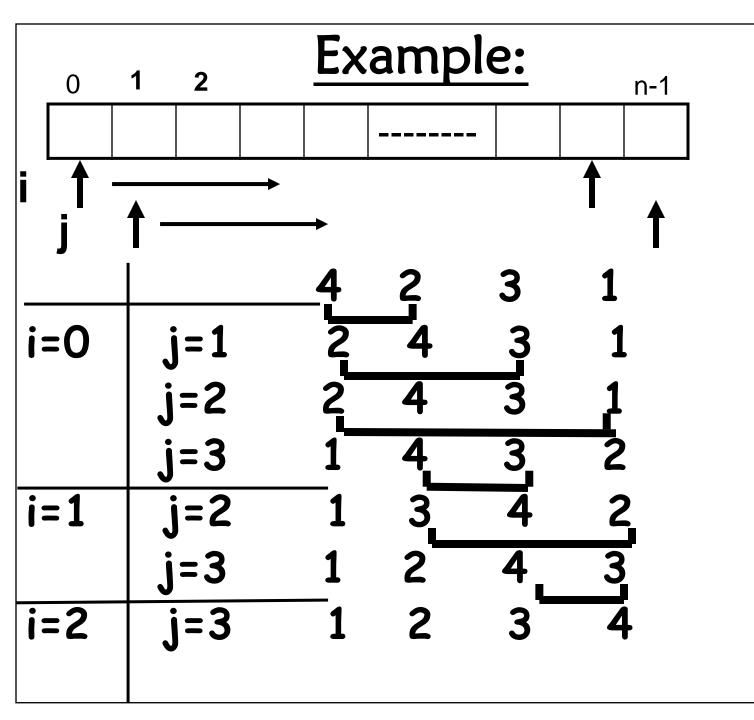
I. Simple sorting

Algorithm:

- In simple sort algorithm the first element is compared with the second, third and all subsequent elements.
- If any one of the other elements is less than the current first element then the first element is swapped with that element.
- Eventually, after the last element of the list is considered and swapped, then the first element has the smallest element in the list.
- The above steps are repeated with the second, third and all subsequent elements.

Implementation:

```
Void SimpleSort(int list[])
 for(int i=0; i < = n-2; i++)
    for(int j=i+1; j < = n-1; j++)
       if(list[i] > list[j])
           int temp;
           temp=list[i];
           list[i]=list[j];
           list[j]=temp;
```



```
Analysis: O(?)
1^{st} pass----- (n-1) comparisons
2^{nd} pass---- (n-2) comparisons
(n-1)^{th} pass---- 1 comparison
T(n)=1+2+3+4+----+(n-2)+(n-1)
  = (n*(n-1))/2
   = n^2/2 - n/2
   =O(n^2)
```

Complexity Analysis:

- Analysis involves number of comparisons and swaps.
- How many comparisons?

$$1+2+3+...+(n-1)=O(n^2)$$

How many swaps?

$$1+2+3+...+(n-1) = O(n^2)$$

Example: Suppose we have 32 unsorted data.

- a). How many comparisons are made by sequential search in the worst-case?
 - \rightarrow Number of comparisons = 32.
- b). How many comparisons are made by binary search in the worst-case? (Assuming simple sorting).
 - → Number of comparisons = Number of comparisons for sorting + Number of comparisons for binary search

```
= (n*(n-1))/2 + logn
= 32/2(32-1) + log 32
= 16*31 + 5
```

- c). How many comparisons are made by binary search in the worst-case if data is found to be already sorted?
 - \rightarrow Number of comparisons = $log_2 32 = 5$.

II.Bubble sort

Algorithm:

- Compare each element (except the last one) with its neighbor to the right.
 - If they are out of order, swap them
 - This puts the largest element at the very end
 - The last element is now in the correct and final place
- II. Compare each element (except the last two) with its neighbor to the right.
 - If they are out of order, swap them
 - This puts the second largest element before last
 - The last two elements are now in their correct and final places

- III. Compare each element (except the last three) with its neighbor to the right.
- IV. Continue as above until you have no unsorted elements on the left.
 - Is the oldest, simplest, and slowest sort in use.
 - It works by comparing each item in a list with an item next to it, and swap them if required.
 - This causes the larger values to "bubble" to the end of the list while smaller values to "sink" towards the beginning of the list.
 - In general case, bubble sort has O(n²) level of complexity.

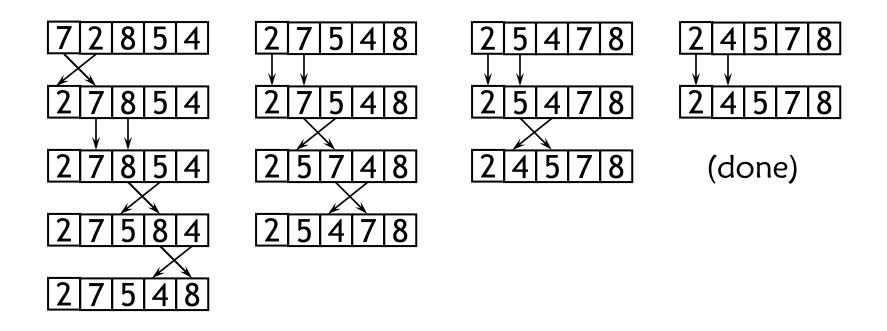
Advantage: Simplicity and ease of implementation.

Disadvantage: Horribly inefficient.

Example of Bubble sort

		4		3	1
i=3	j=1	2		3	1
	j=2	2	3	4	1
	j=3	2	3	1	4
i=2	j=1	2	 3	1	4
	j=2	2	1	3	4
i=1	j=1	1	2	3	4

Example of Bubble sort



Implementation:

```
Void BubbleSort(int list[])
    int temp;
 for (int i=n-2; i>=0; i--) {
 for(int j=0; j < =i; j++)
     if (\operatorname{list}[j] > \operatorname{list}[j+1])
            temp=list[j];
            list[j] = list[j+1];
            list[j]=temp;
```

Complexity Analysis:

- Analysis involves number of comparisons and swaps.
- How many comparisons? $1+2+3+...+(n-1)=O(n^2)$
- How many swaps? $1+2+3+...+(n-1)=O(n^2)$

III. Selection Sort

Algorithm

- The selection sort algorithm is in many ways similar to simple sort algorithms.
- The idea of algorithm is quite simple. Array is imaginary divided into two parts - sorted one and unsorted one.
- At the beginning, sorted part is empty, while unsorted one contains whole array.
- At every step, algorithm finds minimal element in the unsorted part and adds it to the end of the sorted one.
- When unsorted part becomes empty, algorithm stops.

- Works by selecting the smallest unsorted item remaining in the list, and then swapping it with the item in the next position to be filled.
- Similar to the more efficient insertion sort.
- It yields a 60% performance improvement over the bubble sort.

Advantage: Simple and easy to implement.

Disadvantage: Inefficient for larger lists.

Example:		ı	1			
		,	7	9	11	3
i=0	j =1	,	7	9	11	3
	j =2		7	9	,11	_3 7
	j=3		3	9	11	7
i=1	j =2		3	2	11	_7
	j =3		3	7	11	9
i=2	j =3		3	7	9	11



Implementation:

```
void selectionSort(int list[]) {
    int minIndex, temp;
    for (int i = 0; i <= n - 2; i++) {
               minIndex = i:
        for (j = i + 1; j \le n-1; j++)
          if (list[j] < list[minIndex])</pre>
               minIndex = j;
        if (minIndex != i) {
             temp = list[i];
             list[i] = list[minIndex];
             list[minIndex] = temp;
```

Complexity Analysis

- Selection sort stops, when unsorted part becomes empty.
- As we know, on every step number of unsorted elements decreased by one.
- Therefore, selection sort makes <u>n-1</u> steps (*n* is number of elements in array) of outer loop, before stop.
- Every step of outer loop requires finding minimum in unsorted part. Summing up, (n 1) + (n 2) + ... + 1, results in $O(n^2)$ number of comparisons.
- Number of swaps may vary from zero (in case of sorted array) to n-1 (in case array was sorted in reversed order), which results in O(n) number of swaps.
- Overall algorithm complexity is O(n²).
- Fact, that selection sort requires <u>n-1</u> number of swaps at most, makes it very efficient in situations, when write operation is significantly more expensive, than read operation.

IV. Insertion Sort

Algorithm:

- Insertion sort algorithm somewhat resembles Selection Sort and Bubble sort.
- Array is imaginary divided into two parts sorted one and unsorted one.
- At the beginning, sorted part contains first element of the array and unsorted one contains the rest.
- At every step, algorithm takes first element in the unsorted part and inserts it to the right place of the sorted one.
- When unsorted part becomes empty, algorithm stops.

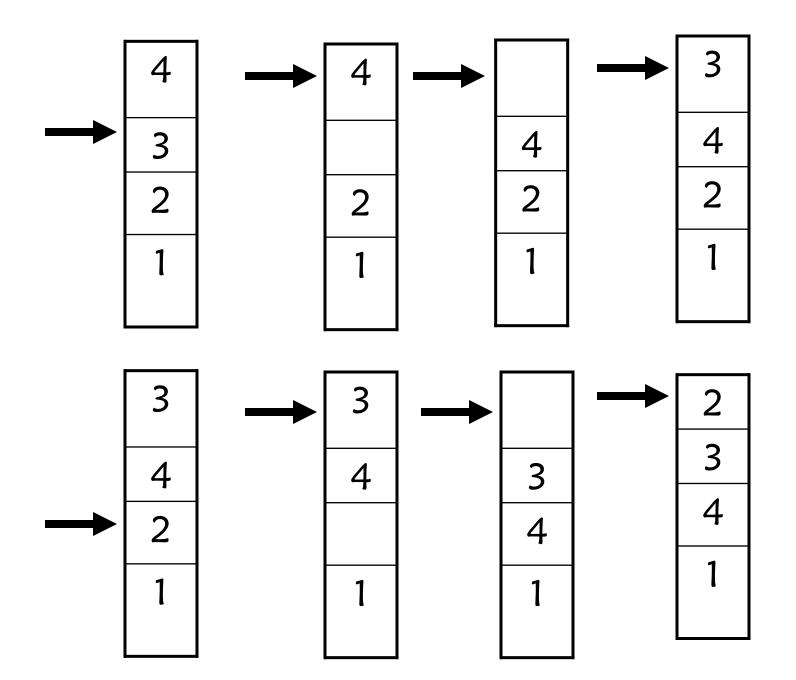
Using binary search

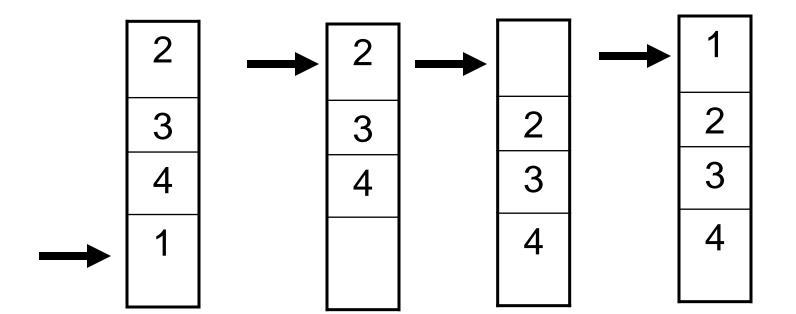
- It is reasonable to use binary search algorithm to find a proper place for insertion.
- This variant of the insertion sort is called binary insertion sort.
- After position for insertion is found, algorithm shifts the part of the array and inserts the element.

- Insertion sort works by inserting item into its proper place in the list.
- Insertion sort is simply like playing cards: To sort the cards in your hand, you extract a card, shift the remaining cards and then insert the extracted card in the correct place.
- This process is repeated until all the cards are in the correct sequence.
- Is over twice as fast as the bubble sort and is just as easy to implement as the selection sort.

Advantage: Relatively simple and easy to implement.

Disadvantage: Inefficient for large lists.





16 unsorted 16 -5 to be inserted 16 7 > -5, shift 16 reached left boundary, insert -5 16 2 to be inserted 16 7 > 2, shift 16 -5 < 2, insert 2 16 16 to be inserted 16 7 < 16, insert 16 4 to be inserted 16 16 16 > 4, shift 16 7 > 4, shift 2 < 4, insert 4 sorted

C++ implementation

```
void InsertionSort(int list[])
     for (int i = 1; i <= n-1; i++) {
        for(int j = i; j > = 1; j - -) {
          if(list[j-1] > list[j])
             int temp = list[j];
             list[j] = list[j-1];
             list[j-1] = temp;
           else
              break;
```

Complexity Analysis

- The complexity of insertion sorting is <u>O(n)</u> at best case of an already sorted array and <u>O(n²)</u> at worst case, regardless of the method of insertion.
- Number of comparisons may vary depending on the insertion algorithm.
 - O(n²) for shifting or swapping methods.
 - O(nlogn) for binary insertion sort.