

C++ Real-Time Audio Programming with Bela

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Course topics

Programming topics

- Working in real time
- Buffers and arrays
- Parameter control
- Classes and objects
- Analog and digital I/O
- Filtering
- Timing in real time
- Circular buffers
- State machines
- MIDI
- Block-based processing
- Threads
- Fixed point arithmetic
- ARM assembly language



Music/audio topics

- Oscillators
- Samples
- Wavetables
- Control voltages
- Gates and triggers
- Filters
- Metronomes and clocks
- Delays and delay-based effects
- Envelopes
- ADSR
- MIDI
- Additive synthesis
- Phase vocoders
- Impulse reverb

Today

Lecture 16: MIDI part 2

What you'll learn today:

Handling the MIDI pitch wheel

Handling MIDI control change messages

Low-frequency oscillators and portamento

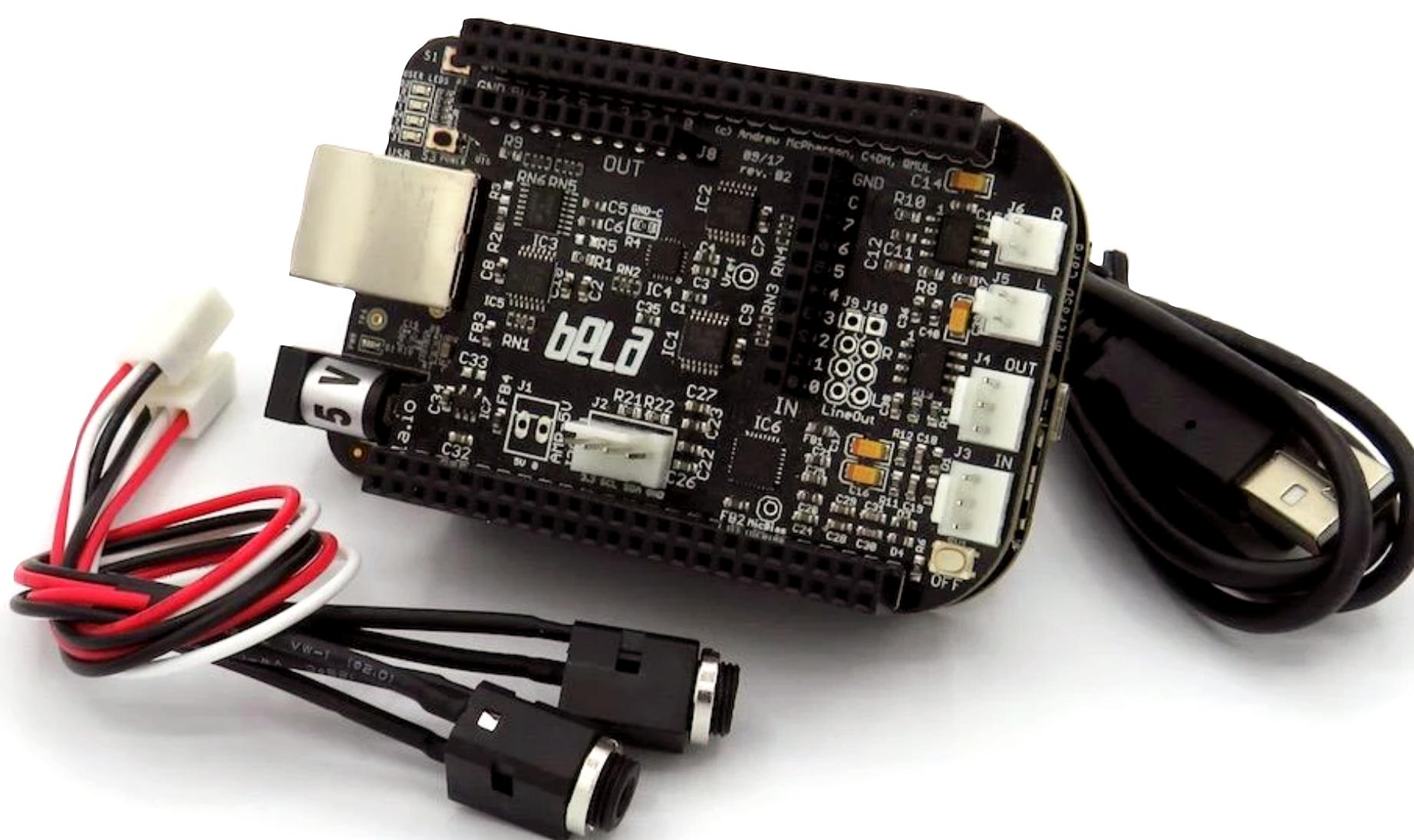
What you'll make today:

Analog-style monophonic MIDI synth

Companion materials:

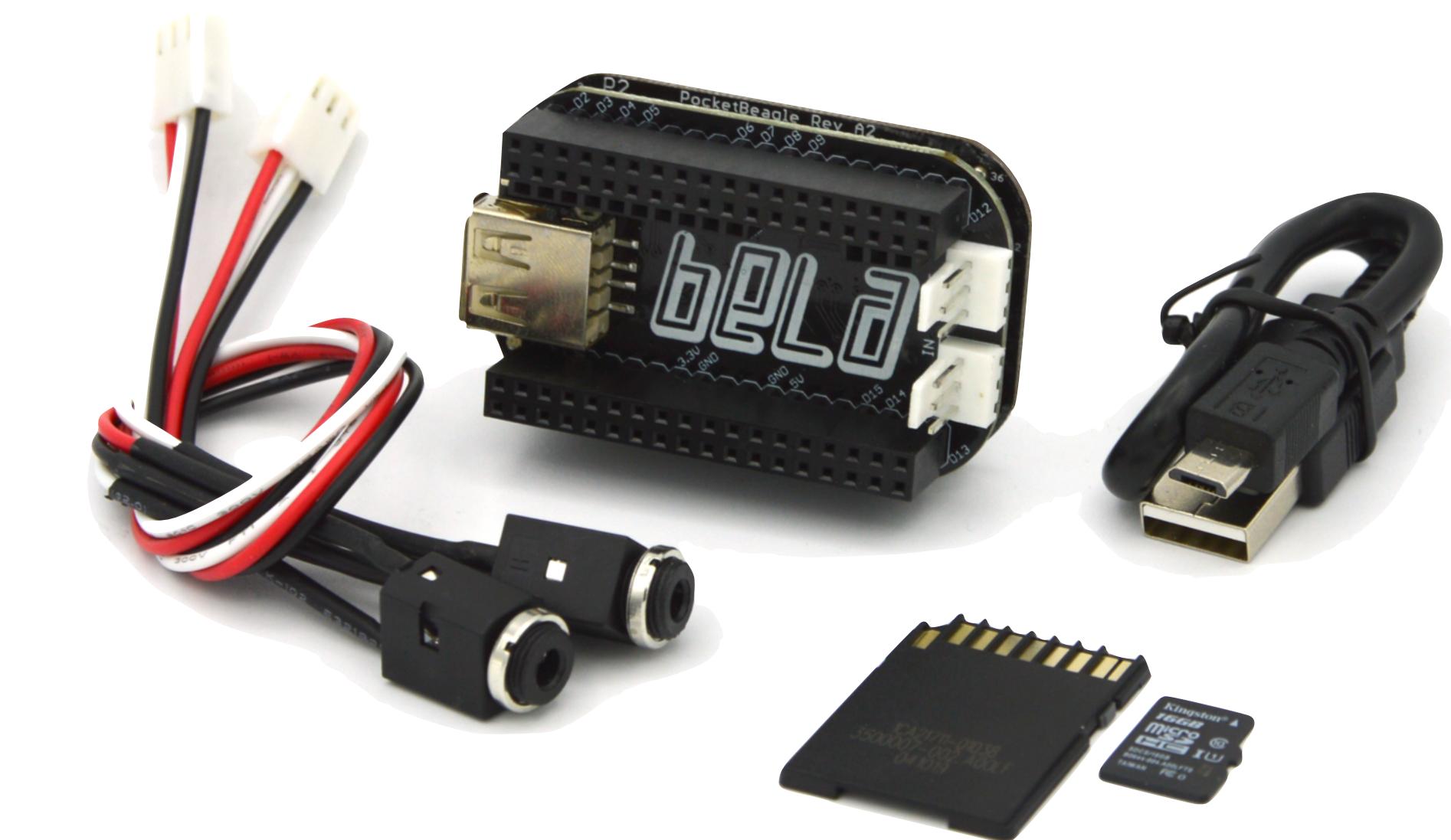
github.com/BelaPlatform/bela-online-course

What you'll need



Bela Starter Kit

or



Bela Mini Starter Kit

Also needed for
this lecture:



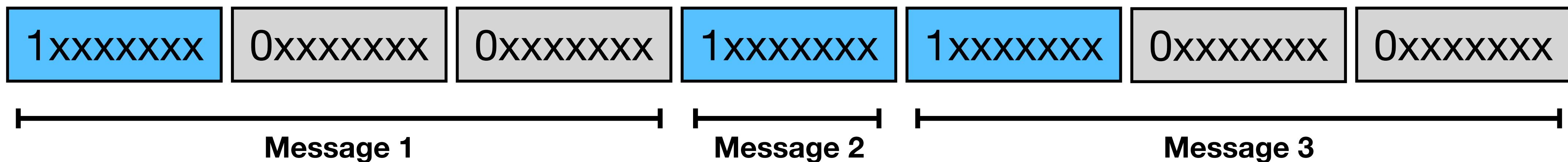
or virtual keyboard software:

MIDIKeys (Mac)
vmpk (cross-platform)

MIDI

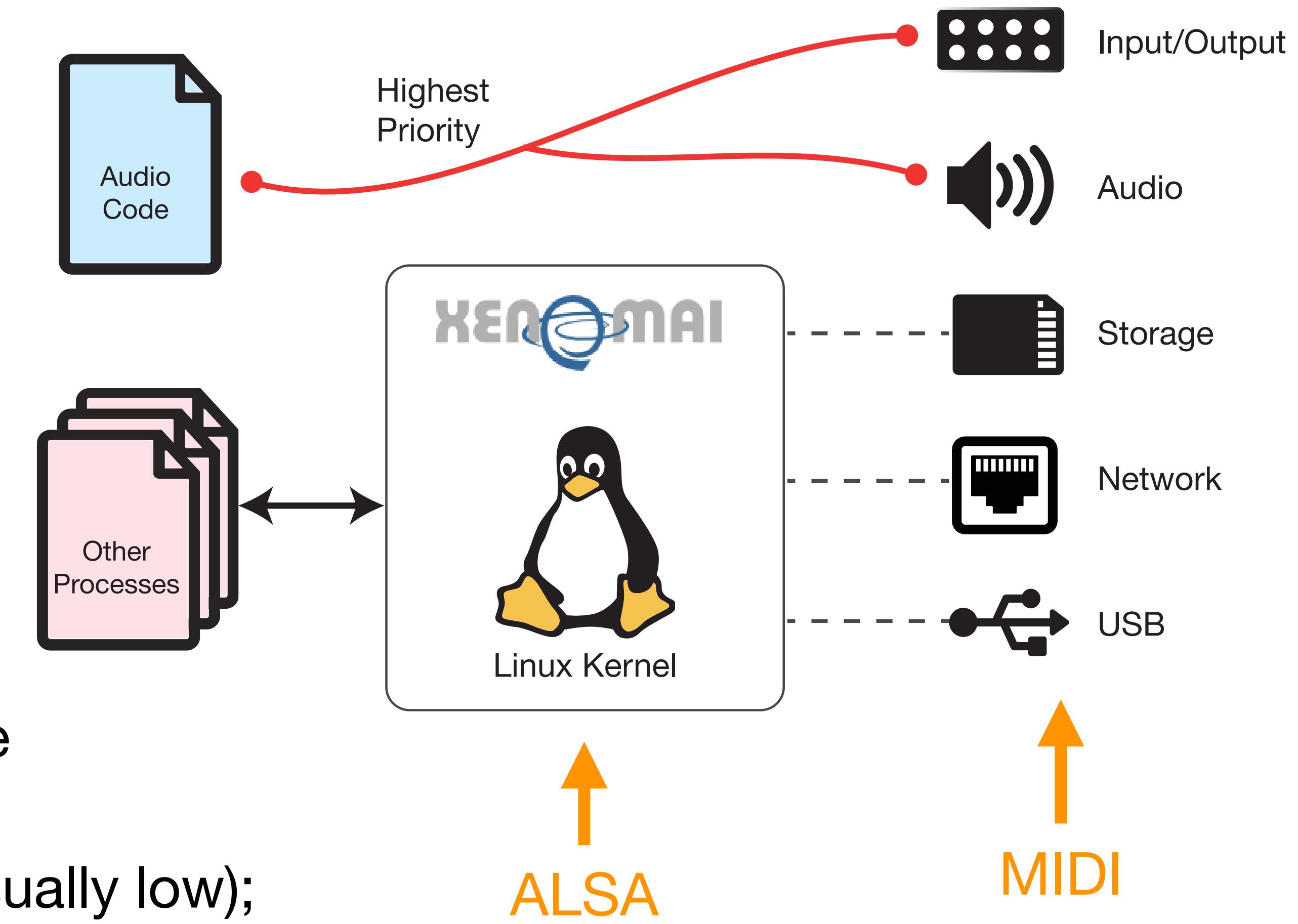


- MIDI: Musical Instrument Digital Interface
 - Industry standard for connecting digital musical devices
 - First published in 1983, with minor updates since
 - Maintained by the MIDI Manufacturer's Association: <http://midi.org>
- The fundamental unit of MIDI is the message
 - A discrete packet of data, consisting of 1-3 bytes



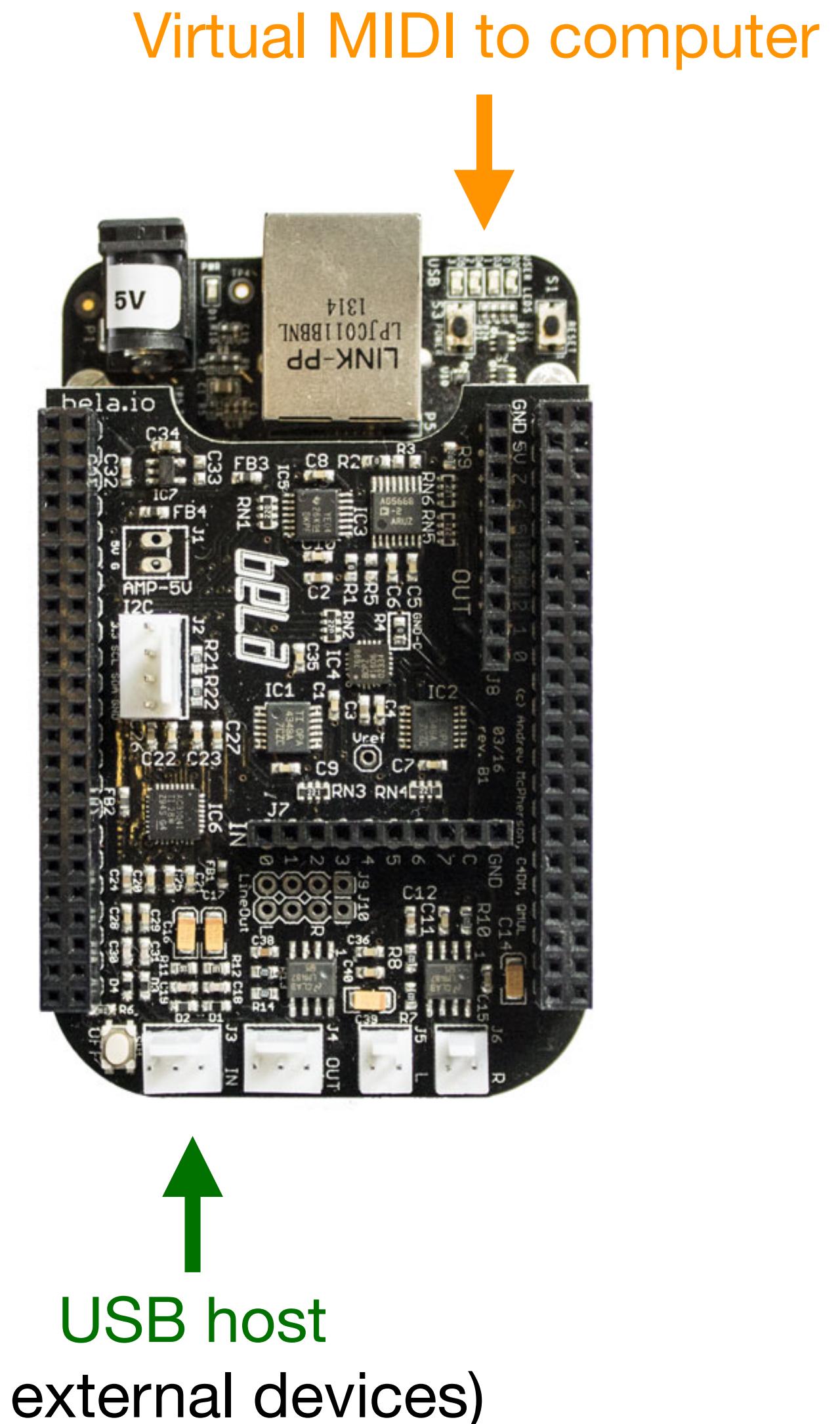
MIDI on Bela

- On Bela, MIDI uses **ALSA** (Advanced Linux Sound Architecture)
 - This is provided by the **Linux kernel**
- **Advantage: compatibility**
 - Any MIDI device that works on Linux works on Bela
 - All sources of MIDI data are treated equivalently (serial, USB, virtual ports)
- **Disadvantage: real-time latency**
 - ALSA cannot use the hard real-time priority of Bela's audio callback
 - We still need a way to pass data from the ALSA system to the Bela audio callback
 - Result: **no latency guarantees** (though usually low); latency could depend on other system load



MIDI on Bela: devices

- There are two common ways of using MIDI on Bela
 - ▶ Hardware MIDI devices
 - Connect these by USB to the host port on Bela
 - ▶ Bela as virtual MIDI device
 - Bela appears as a MIDI device to the host computer
 - Can exchange MIDI messages back and forth with the computer
- In your code, each MIDI device is specified by a **device name (or port name)**
 - ▶ The virtual device is usually `hw:0,0,0`
 - ▶ The first connected USB device is usually `hw:1,0,0`
 - ▶ To see connected devices, run `amidi -l` on the Bela console



MIDI on Bela: API (option 1)

- Bela provides an API that wraps the ALSA system
- To use it:
 1. Include `Midi.h`
 2. Make a global `Midi` variable
 3. Initialise the settings in `setup()`
 4. Read/write the messages in `render()`

```
#include <Bela.h>
#include <libraries/Midi/Midi.h>

Midi gMidi;
const char* gMidiPort0 = "hw:1,0,0"; // MIDI object
                                         // Port name

bool setup(BelaContext *context, void *userData)
{
    // Initialise the MIDI device
    gMidi.readFrom(gMidiPort0);
    gMidi.writeTo(gMidiPort0);
    gMidi.enableParser(true);
    return true;
}

void render(BelaContext *context, void *userData)
{
    // At the beginning of each callback, look for available MIDI
    // messages that have come in since the last block
    while(gMidi.getParser()->numAvailableMessages() > 0) {
        MidiChannelMessage message;
        message = gMidi.getParser()->getNextChannelMessage();

        // Check message types and decide what to do with each one
        if(message.getType() == kmmNoteOn) {
            // Note on
        }
        // etc.

    }
    // Now calculate the audio for this block
}
```

MIDI on Bela: API (option 2)

- You can also use a separate MIDI callback function

- The system calls your function whenever MIDI data comes in
- MIDI output is handled separately

- To use it:

- In `setup()`, tell the Midi object where to find your callback
- In the callback function, read the incoming message
- Up to you to pass any required data to `render()`, e.g. using global variables

```
#include <Bela.h>
#include <libraries/Midi/Midi.h>

Midi gMidi;                                // MIDI object
const char* gMidiPort0 = "hw:1,0,0";          // Port name

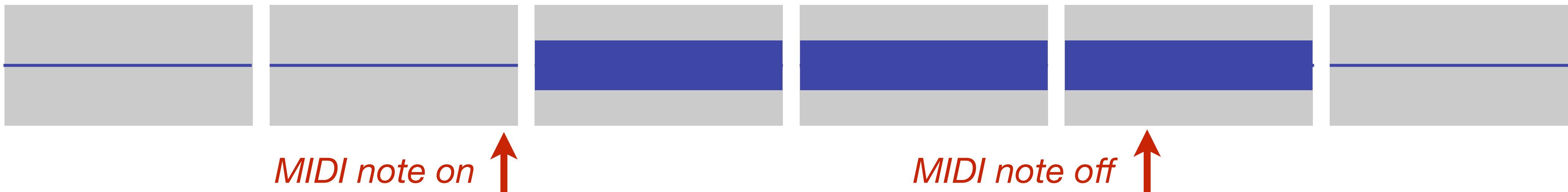
void midiEvent(MidiChannelMessage message, void *arg);

bool setup(BelaContext *context, void *userData)
{
    // Initialise the MIDI device
    gMidi.readFrom(gMidiPort0);
    gMidi.writeTo(gMidiPort0);
    gMidi.enableParser(true);
    gMidi.setParserCallback(midiEvent, (void *)gMidiPort0);
    return true;
}

void midiEvent(MidiChannelMessage message, void *arg)
{
    // Check message types and decide what to do with each one
    if(message.getType() == kmmNoteOn) {
        // Note on
    }
    else if(message.getType() == kmmNoteOff) {
        // Note off
    }
    // etc.
}
```

MIDI on Bela: other considerations

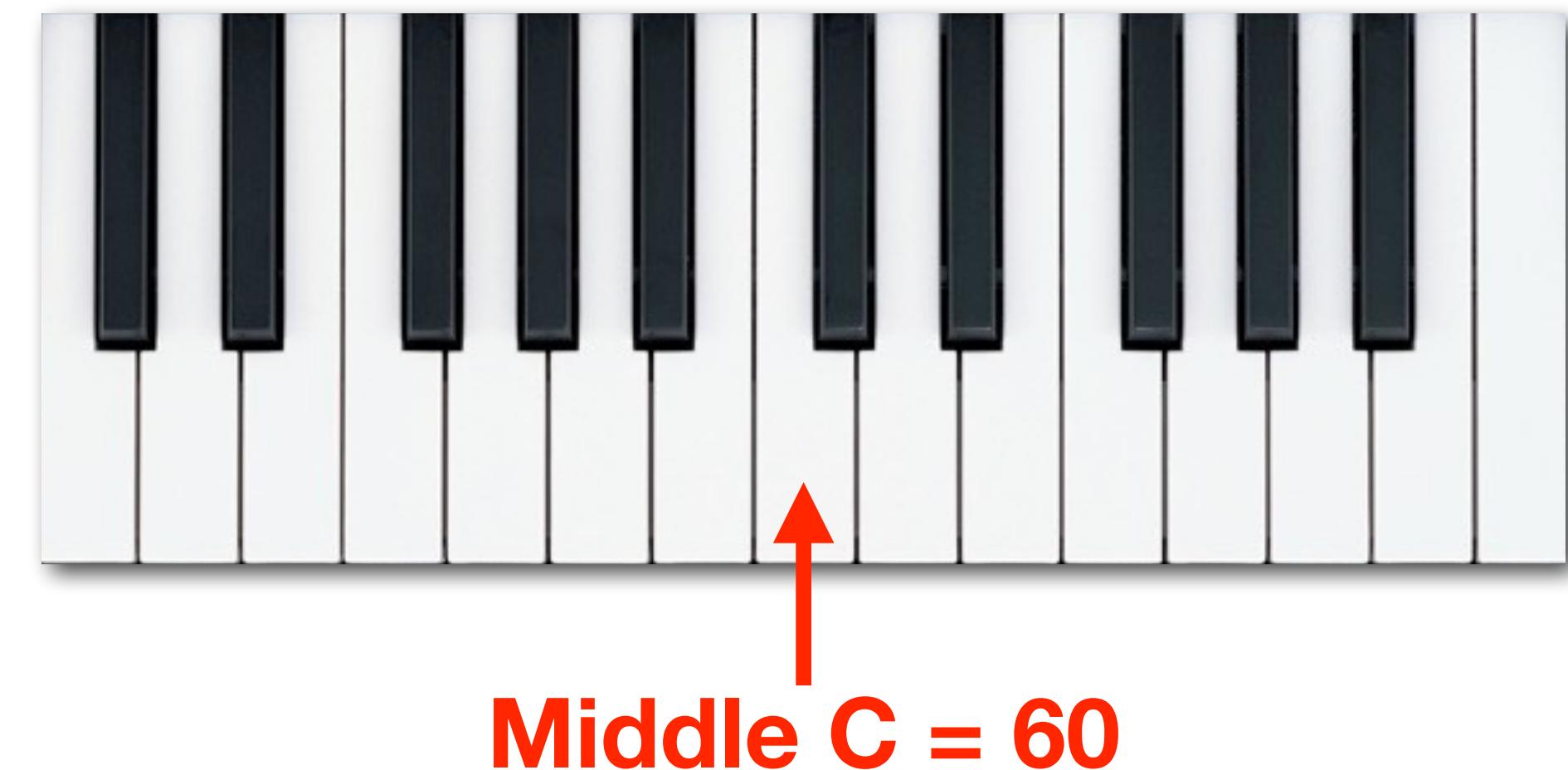
- Remember: MIDI is fundamentally asynchronous with audio
 - ▶ It comes from a different hardware device, via a different thread
 - When you read the messages in `render()`, you're seeing everything that happened since the last block
 - You won't necessarily know exactly which audio frame the message was received at



- MIDI messages have persistent effects
 - ▶ When a message comes in, we start doing something and usually continue doing it until we receive another message
 - ▶ Examples:
 - A Note On message starts some sound, which continues after the instant that the message comes in
 - Control Change or Pitch Wheel messages will affect current and future notes on that channel
 - ▶ This implies that we need to remember what happened before (e.g. with global variables)

MIDI note number

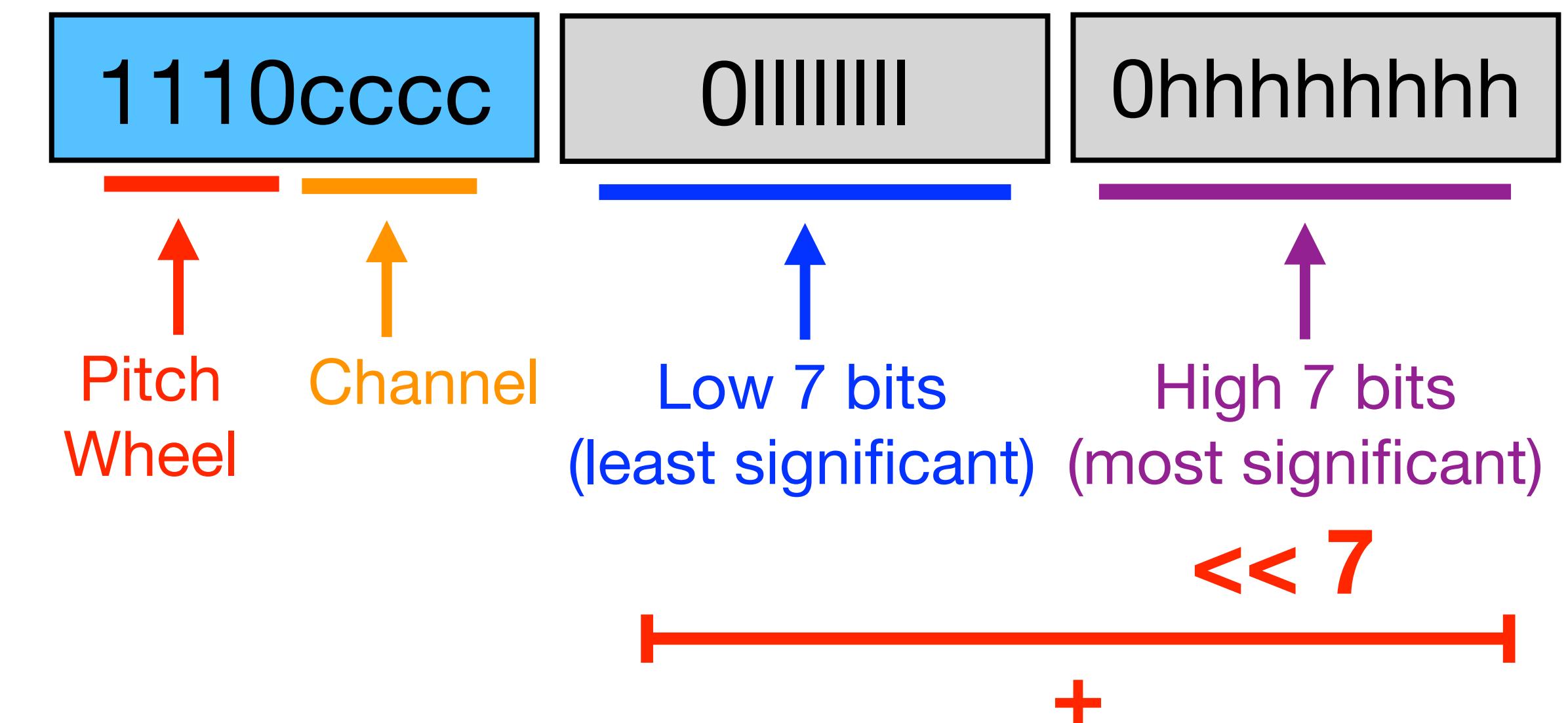
- MIDI note numbers uniquely indicate each key of the keyboard
 - ▶ Numbered sequentially from low to high
 - ▶ By definition, middle C is note number 60
 - It has frequency 261.63Hz
 - ▶ The A above middle C is note number 69
 - It has frequency 440Hz (a commonly used reference, sometimes called “A440”)
- How should we write the formula to go from MIDI note number to frequency?
 - ▶ For a note number N , how do we calculate number of semitones above A440? $N - 69$
 - Number of octaves? $(N - 69) / 12$
 - ▶ If note 69 corresponds to $f_{ref} = 440\text{Hz}$ how do we calculate the frequency for note N?



$$f_{out} = 440 \cdot 2^{\frac{N-69}{12}} \quad (\text{MIDI note number to frequency})$$

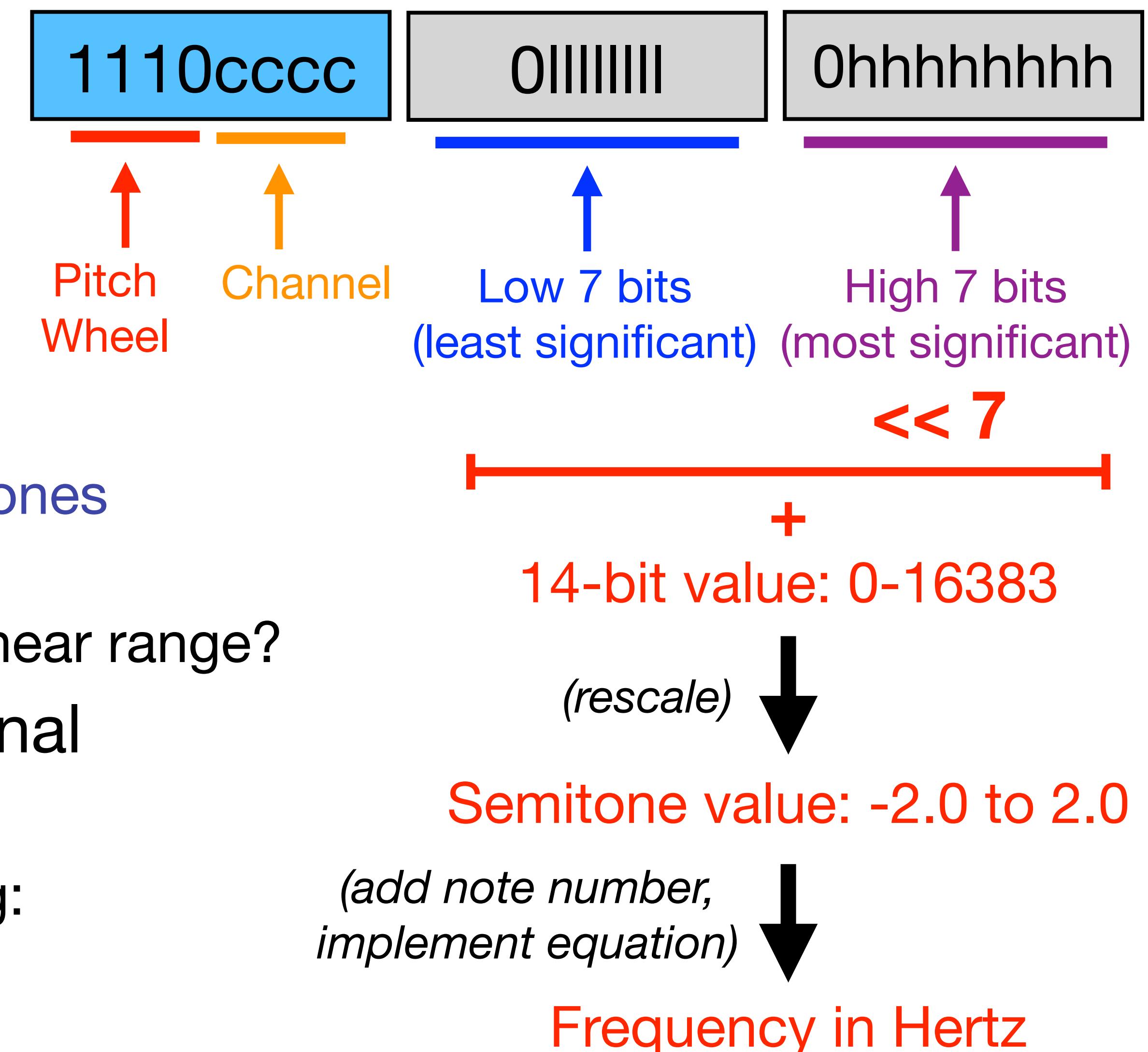
Implementing MIDI pitch wheel

- Pitch Wheel messages create a **relative change in frequency**
 - A change compared to where that note number would normally be tuned
- To calculate the oscillator frequency, we always need **both** of:
 - The **note number** of the most recent Note On message
 - The **value** of the most recent Pitch Wheel message
 - We receive **one message at a time**, which means we have to remember the other one!
- Pitch Wheel messages are **14 bits** (0 to $2^{14}-1$), split over two data bytes
 - Our first task is to reconstruct the 14-bit value
 - Use the bit shift operator `<<` to shift the MSB left by 7 bits (i.e. multiply by 2^7)
 - Then add the two values together



Implementing MIDI pitch wheel

- Once we have the 14-bit value, convert it to a bend in **semitones**
 - The 14-bit value ranges from 0-16383
 - The centre value is 8192: this corresponds to no bend
 - A value of 0 corresponds to **-2 semitones**
 - A value of 16383 corresponds to **+2 semitones**
 - Though these ranges are adjustable
 - What function could we use to rescale a linear range?
- Finally, add the bend value to the original note number
 - Then convert the sum to a frequency using:
$$f_{out} = 440 \cdot 2^{\frac{N-69}{12}}$$



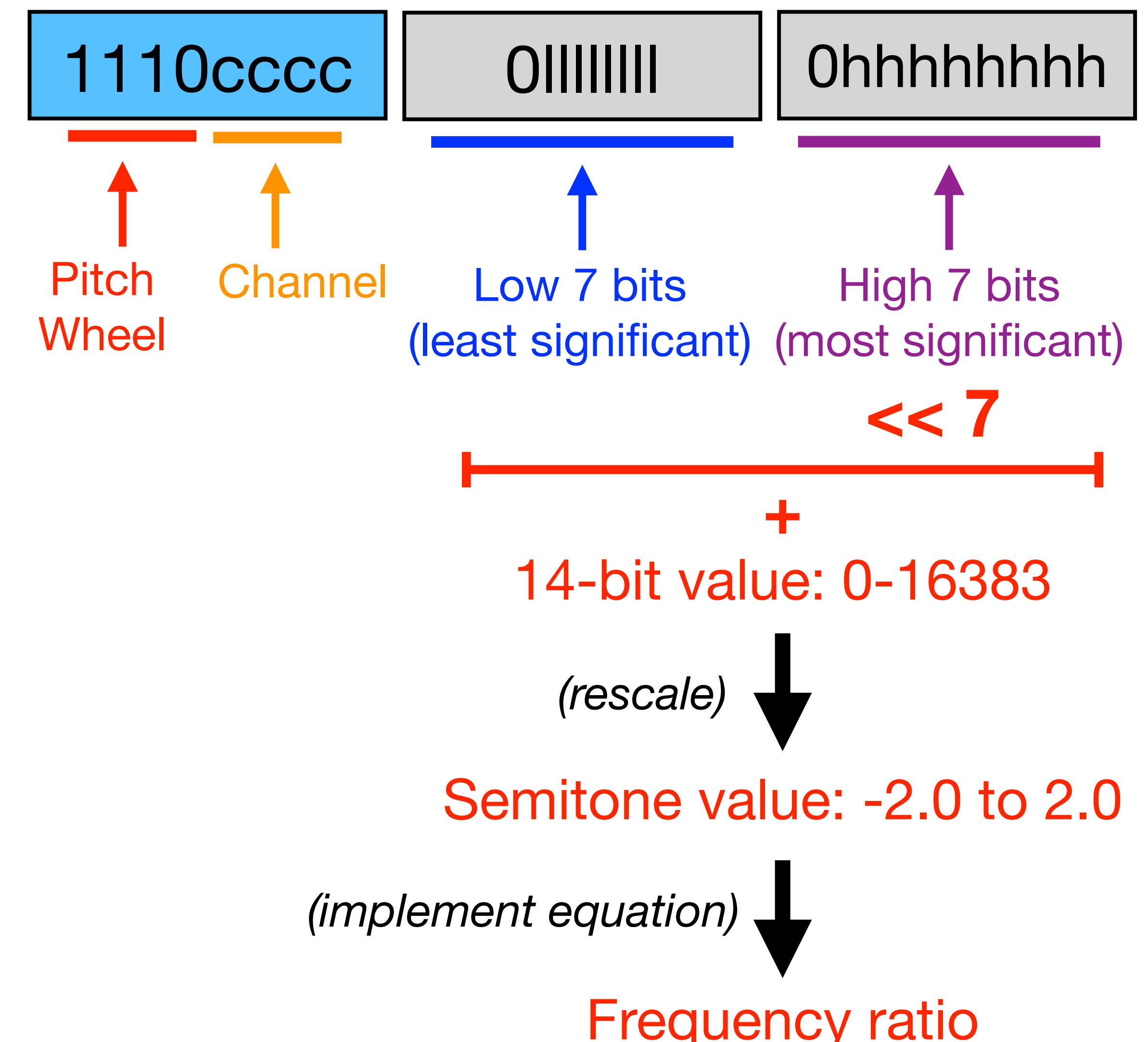
Implementing MIDI pitch wheel

- Alternatively: convert the pitch bend directly into a frequency ratio

- Store the frequency f_{note} of the MIDI note elsewhere

$$f_{out} = f_{note} \cdot 2^{\frac{N}{12}}$$

- Multiply the two values together to get the final frequency
- We'll take this approach for reasons we'll see later

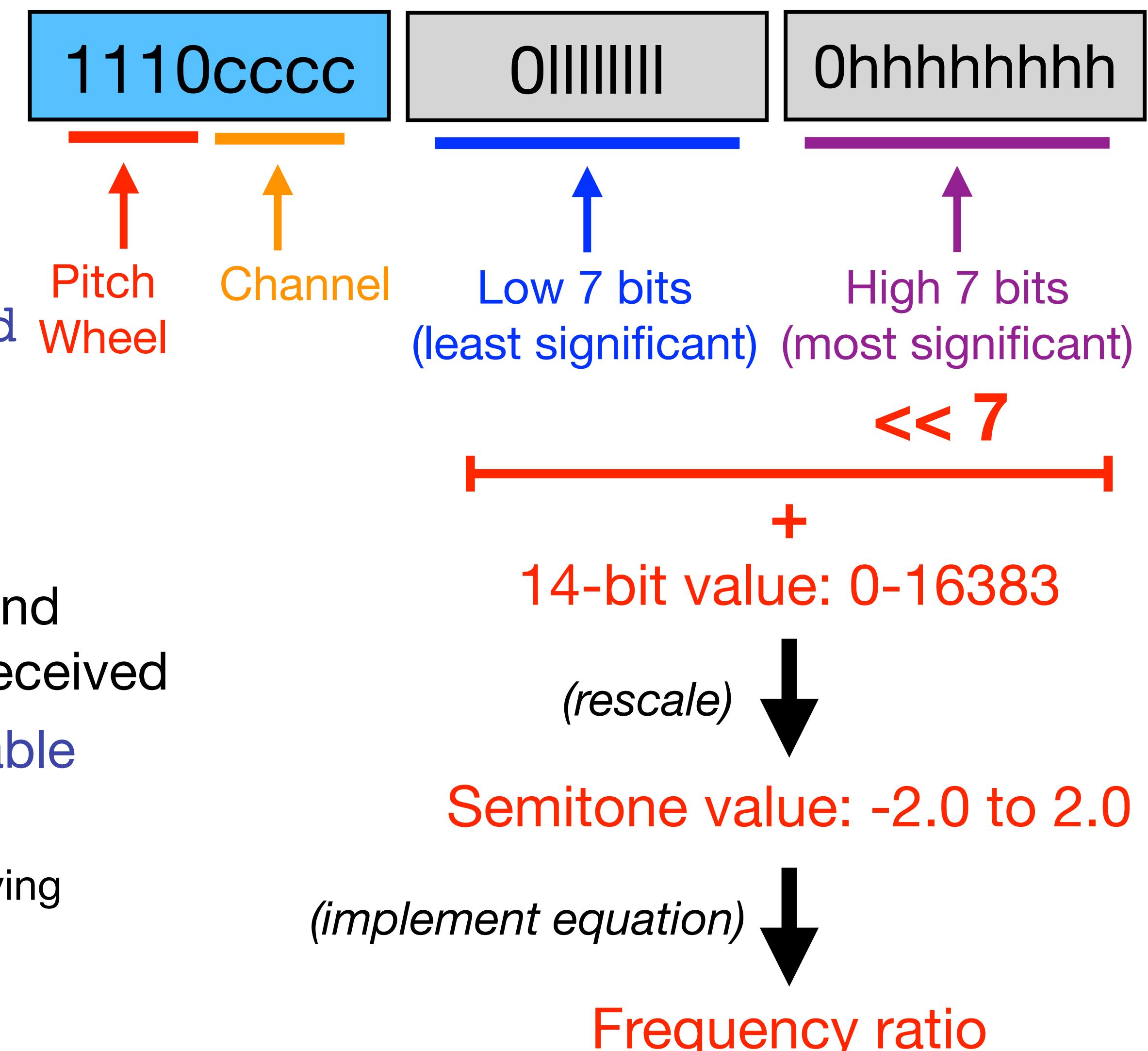


Implementing MIDI pitch wheel

- Task: using the `midi-pitchwheel`

example, implement the pitch wheel

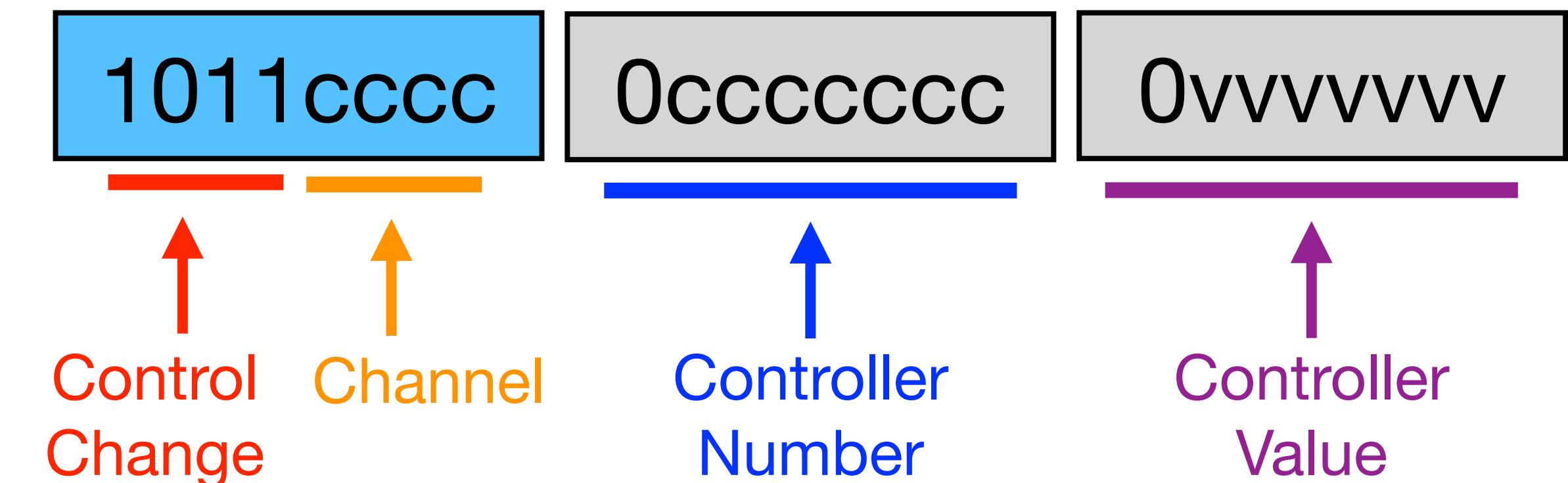
- In `midiEvent()`, add a new `if()` statement looking for a message of type `kmmPitchBend`
- Get the two data bytes from the message (see how it's done for `kmmNoteOn`)
 - Convert the two bytes to a single 14-bit number
- Write a new function called `pitchWheel()` and call it when the `kmmPitchBend` message is received
- Store the frequency ratio in a new global variable called `gPitchBendRatio`
 - In `render()`, calculate the final frequency by multiplying the note frequency by this value



MIDI control change messages

- Control Change

- Status byte begins with 1011 (hexadecimal 0xB)
 - Indicates that a controller changed value
 - Controllers in MIDI might be dials, sliders, pedals, breath controllers, etc.
 - They produce a continuous value (0-127) which affects all notes on the channel
 - 2 data bytes: controller number, value
 - Controller numbers are standardised in the MIDI specification
 - e.g. CC1 = modulation wheel; CC7 = volume; CC11 = expression; CC64 = damper/sustain pedal
 - Controllers 120-127 are used for special functions on the channel, e.g. CC123 = all notes off



- Like all MIDI messages, the effect is persistent

- When you receive a Control Change message, you'll need to keep track of its effect
- Typically, rescale the range: from 0-127 to an appropriate range for the specific control

Multiple oscillators

- On analog synths, it's common to use **2 or more oscillators** for a single voice
 - The oscillators are tuned nearly, **but not exactly**, to the same frequency
 - Slight **detuning** results in **beat frequencies** according to the mathematical relationship:

$$\sin(x) + \sin(y) = 2 \sin\left(\frac{x+y}{2}\right) \cos\left(\frac{x-y}{2}\right)$$

- We will use two controls to adjust the oscillator frequencies:
 - One for setting the **centre frequency** of both oscillators
 - Based on MIDI Note On messages, like before
 - One for changing the **detuning** (the slight difference between the oscillators)
 - We will implement this with a MIDI **Control Change** message
 - If the centre frequency is ***f*** and the detuning amount is ***r***, we should have:
$$f_1 = (1 + r)f \quad f_2 = (1 - r)f$$
 - In this case, $r = 0$ corresponds to no detuning (both oscillators the same frequency)

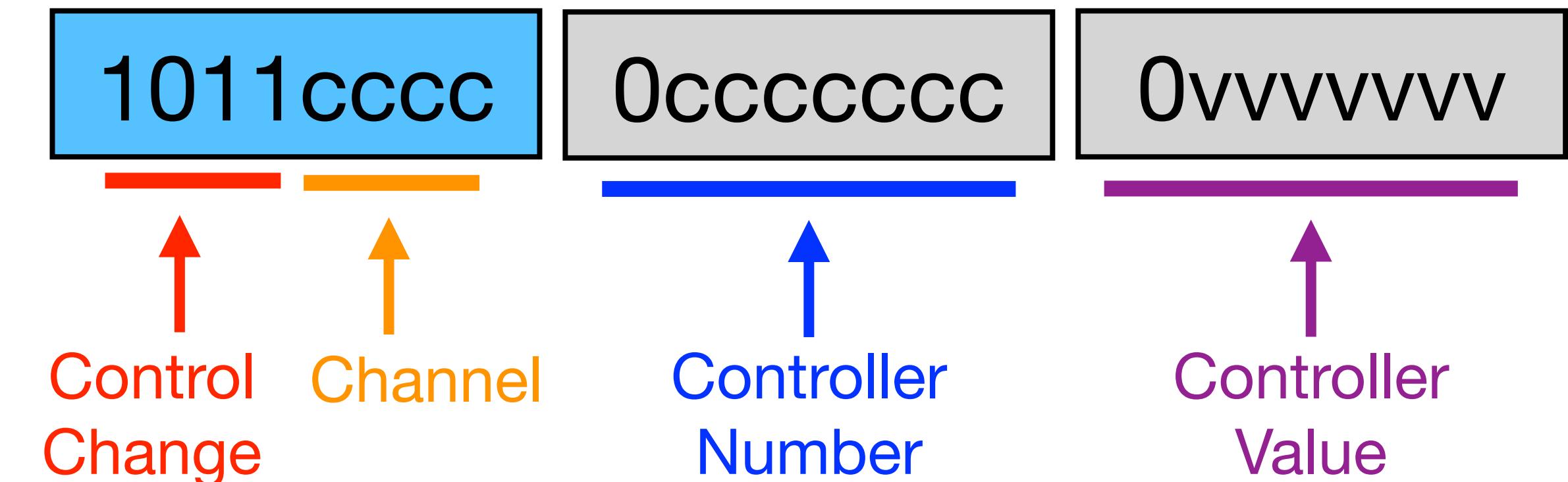
MIDI control change messages

- **Task 1:** in project midi-pitchwheel, implement two detuned oscillators

- Replace the Wavetable object `gOscillator` with a two-element array
- Initialise both oscillators in `setup()`
 - You don't have to recalculate the table
- Declare a global variable `gDetuning` which holds the detuning amount
 - Try a default value of `0.002` for a good effect
- In `render()`, set the frequency of both oscillators using the detuning amount
- Mix both oscillator outputs together before applying the filter

- **Task 2:** use a MIDI control change to change the detuning ratio

- Choose a controller number based on your keyboard's controls
 - Look in the console when the project is running and you adjust a controller
- In `midiEvent()`, look for messages of type `kmmControlChange`
 - If the controller number matches, rescale the range to be between `0-0.01`



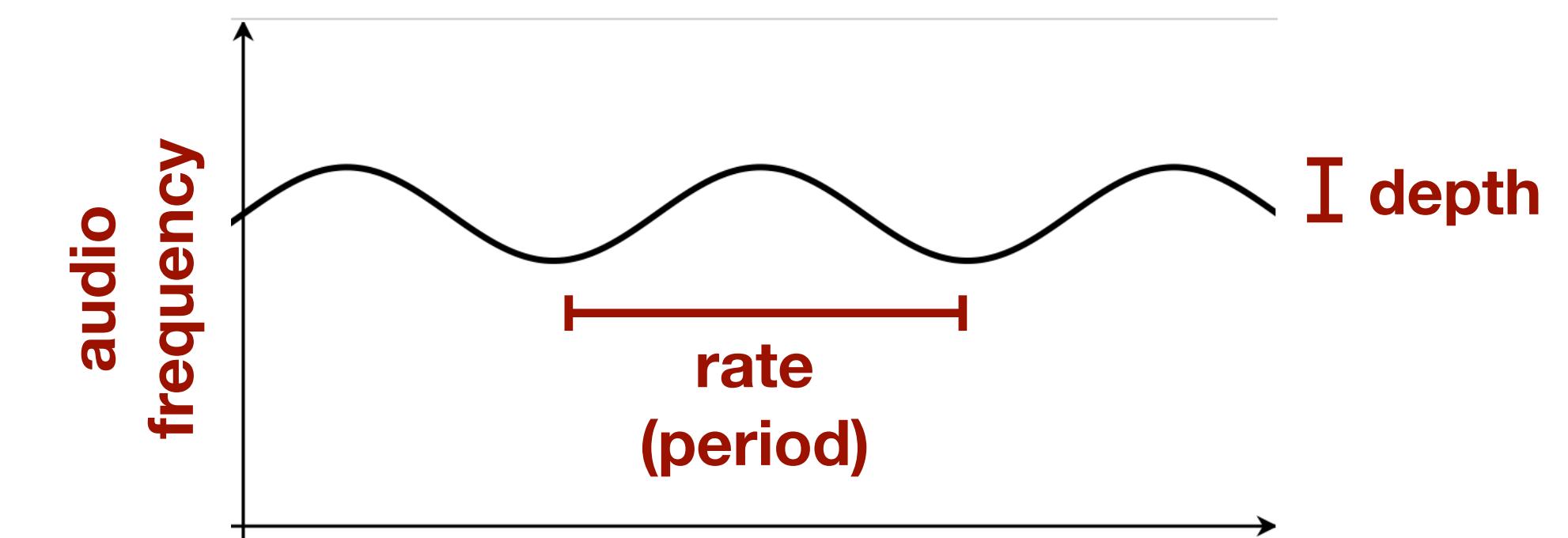
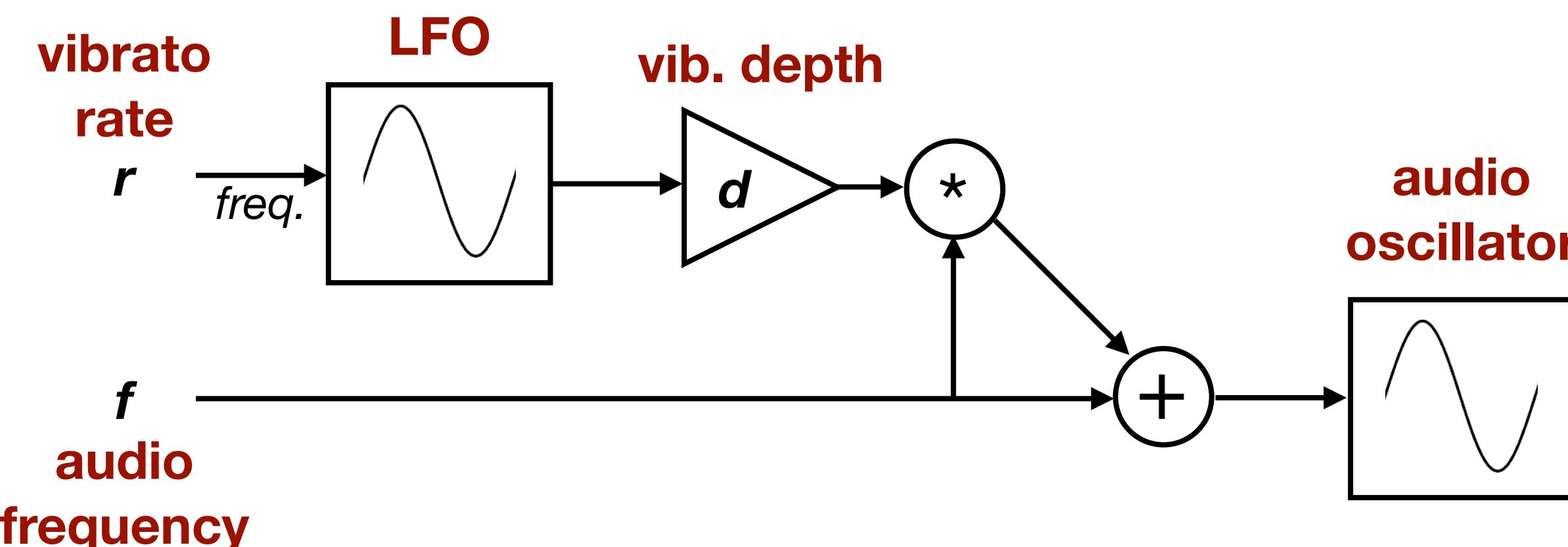
Modulation wheel

- In addition to the pitch wheel, most keyboards have a **modulation wheel** (“mod wheel”)
 - Introduced on the Minimoog in 1970 (before MIDI)
 - Unlike the pitch wheel which snaps back to centre, the modulation wheel stays in place
- The mod wheel can affect various parameters:
 - Filter cutoff frequency
 - Oscillator parameters (e.g. waveform)
 - **Vibrato** depth
 - Do this by change the **amplitude** of a low-frequency oscillator (LFO)
 - The LFO will then affect the **oscillator frequency**

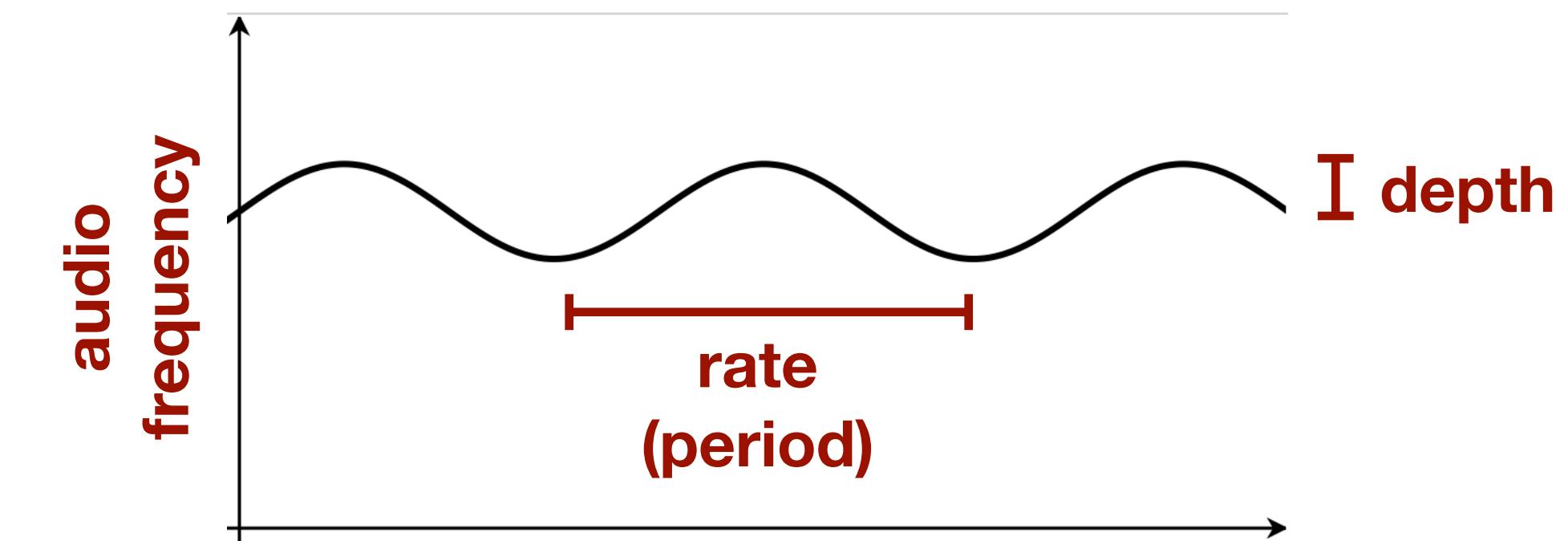
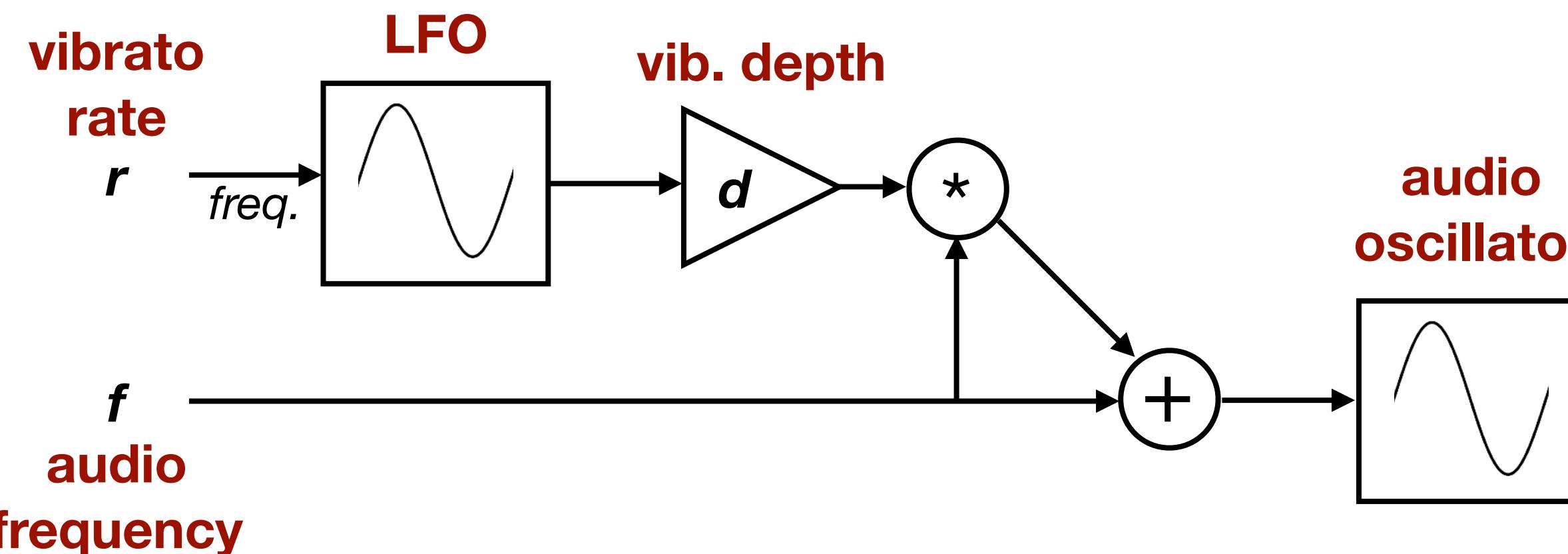


Low-frequency oscillators

- We have seen **oscillators** (sine, sawtooth, wavetable) as **audio sources**
- In digital musical systems, oscillators are also often used as **control signals**
 - Typically these control signals will change more slowly than the audio waveform
 - Hence we refer to such oscillators as **low-frequency oscillators** or LFOs
- Example: **Vibrato**
 - **Periodic modulation of frequency**, typically changing at 3-6Hz (**vibrato rate**)
 - Typical amount of frequency variation $\pm 0.5\text{-}3\%$ (**vibrato depth**)
 - To implement: use an LFO to control the frequency of another (audio frequency) oscillator



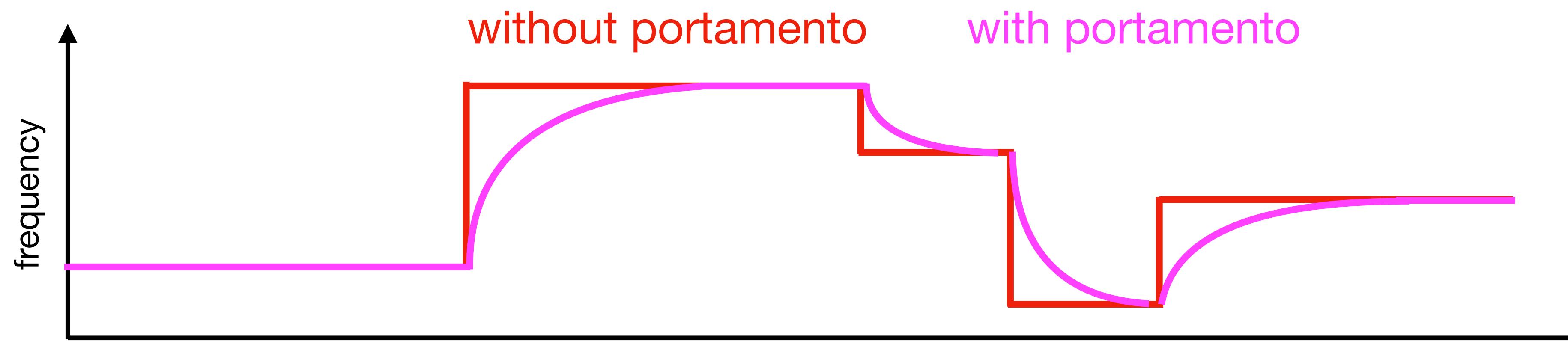
Low-frequency oscillators



- **Task 1:** in `midi-pitchwheel`, use a `Wavetable` object to implement an LFO
 - In `setup()`, calculate a wavetable for a single sine wave (different than the current oscillators)
 - Set its default frequency to something low (e.g. 5Hz)
 - Use the output of the LFO to **modulate the frequency** of the main oscillators
- **Task 2:** make the vibrato depth controllable with the mod wheel
 - The mod wheel produces a **MIDI control change message** with a controller number of 1
 - Range of values is 0-127. Need to rescale to a suitable range of **vibrato depth** (e.g. 0-0.05)
 - Optionally add another MIDI controller to adjust **vibrato speed** (range 1-10Hz)

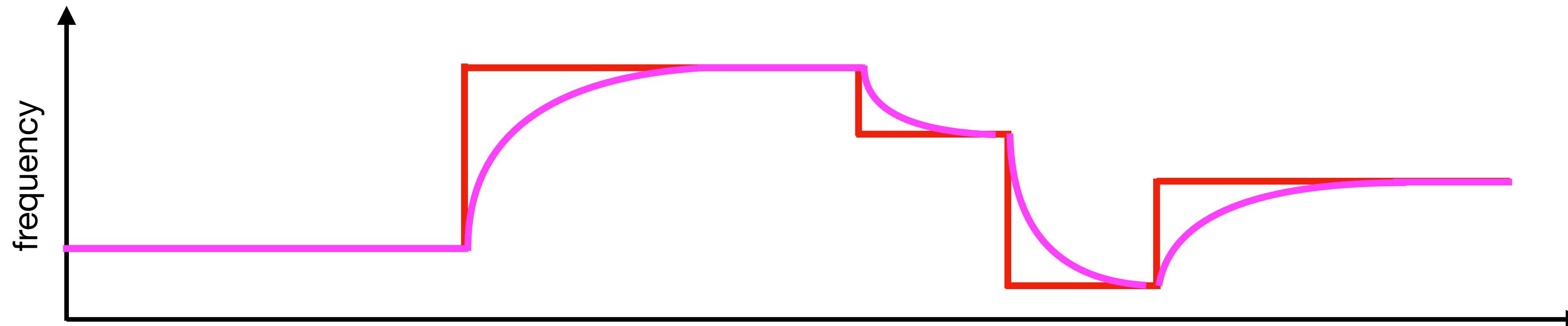
Portamento

- Portamento is a musical effect where the pitch moves gradually, rather than abruptly, from one note to the next:



- It is commonly found on analog synths, where the effect can be achieved by putting a low-pass filter on the pitch CV
 - Lower cutoff frequency → slower change in pitch → more pronounced portamento
- Equivalently, we can use an exponential segment to change frequency every time the MIDI note changes
 - Use the ExponentialSegment class from Lecture 14

Portamento implementation



- **Task:** in the [midi-pitchwheel](#) project, add portamento to the note frequency
 - Use the [ExponentialSegment](#) class (already included in the project)
 - Two possible approaches:
 1. Use [ExponentialSegment](#) to control the [current centre frequency](#) (not including pitch/mod wheels)
 2. Use [ExponentialSegment](#) to control the [current \(fractional\) MIDI note number](#)
 - Add a new MIDI control change message to adjust the [portamento time](#)
 - This will affect the time passed to the `ExponentialSegment::rampTo()`

Keep in touch!

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More resources and contact info at:

learn.bela.io/resources