

Ex 4:

$$① \quad r(t) = s(t) * h(t) + N(t).$$

$$s(t) * h(t) = \sum_k a[k] p(t - kT) * h(t)$$

$$s(t) * h(t) = \sum_k a[k] \int h(\tau) p(t - kT - \tau) d\tau = \sum_k a[k] \cdot (p * h)(t - kT)$$

$$\Rightarrow r(t) = \sum_k a[k] (p * h)(t - kT) + N(t) //$$

$$② \quad y(t) = \sum_n a[n] (p * h)(t - nT) * q^*(t) + N(t) * q^*(t).$$

$$y(t) = \sum_n a[n] (p * h * q^*)(t - nT) + N(t) * q^*(t).$$

$$y[k] = \sum_n a[n] (p * h * q^*)(kT - nT) + (N * q^*)(kT)$$

$$\text{let } h[n] = (p * h * q^*)(nT) \text{ and } (N * q^*)(kT) = z[k]$$

$$y[k] = \sum_n a[n] h[k - n] + z[k] = a[k] * h[k] + z[k]$$

$$y[k] = \sum_n a[n] h[k - n] + z[k] //$$

$$\text{assume } N(t) \sim N(0, \sigma^2).$$

$$\bullet \quad z_k = z[k] = \int N(\tau) q^*(\tau - kT) d\tau. \Rightarrow E[z_k] = \int E[N(\tau)] q^*(\tau - kT) d\tau = 0 //$$

$$E[z_k z_{k'}^*] = E \left[ \int N(\tau) q^*(\tau - kT) d\tau \cdot \int N(\tau') q^*(\tau' - k'T) d\tau' \right] \\ = \iint E[N(\tau) \cdot N(\tau')] q^*(\tau - kT) \cdot q^*(\tau' - k'T) d\tau d\tau'$$

$$= \iint \sigma^2 \delta(\tau - \tau') q^*(\tau - kT) \cdot q^*(\tau' - k'T) d\tau d\tau'$$

$$= \sigma^2 \int q^*(\tau - kT) q^*(\tau - k'T) d\tau =$$

$$\Rightarrow E[z_k z_{k'}^*] = \sigma^2 \cdot \langle q(t - k'T), q(t - kT) \rangle //$$

③  $z_k$  is AWGN if it is gaussian, with the following 2 properties:

$$E[z_k] = 0$$

$$E[z_k z_{k'}^*] = \sigma^2 \delta[k - k']$$

Thus if  $q(t)$  is Nyquist pulse, we have  $\langle q(t - kT), q(t - k'T) \rangle = \delta[k - k'] //$

④ As seen previously, if  $q(t) = p(t)$ ,  $y[k]$  will be sufficient statistics for deciding on  $a[k]$ .

⑤ We have:  $h(t) = \sum_{l=0}^{m-1} \alpha_l f(t - \tau_l)$

$$p(t) * h(t) * q^*(-t) = \sum_{l=0}^m \alpha_l \delta(t - \tau_l) * \underbrace{p(t) * q^*(-t)}_{f(t)} = \sum_{l=0}^m \alpha_l f(t - \tau_l).$$

$$\Rightarrow h[n] = p(t) * h(t) * q^*(-t) \Big|_{t=nT} = \sum_{l=0}^m \alpha_l f(nT - \tau_l) //$$