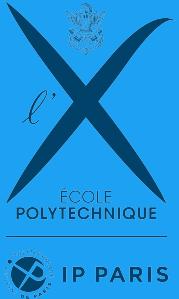
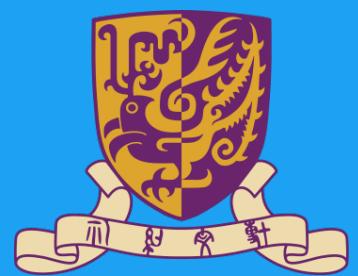


On the Global Convergence of (Fast) Incremental EM Methods

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Maximum Likelihood Estimation (MLE)

- We have vectors of data Y that are *observed* and Z that are *latent*
- We assume a probabilistic model on the observations Y , $g(Y, \theta)$
- We can define $f(Z, Y, \theta)$ as the complete data likelihood and $p(Z|Y, \theta)$ as the conditional distribution of Z given Y
- The MLE problem is, given a model $g(Y, \theta)$ and some actual data Y , find the parameter θ which makes the data most likely:

$$\theta^{ML} := \arg \max_{\theta} g(Y, \theta)$$

- This problem is an **optimization problem**, which we could use any imaginable tool to solve
- In practice, it's often **hard** to get expressions for the **derivatives** needed by **gradient** methods
- **Expectation-Maximization (EM)** method is one popular and powerful way of proceeding, but not the only way. **It takes advantage of the latent data to complete the observations.**

Context

Settings and Notations

- Many problems in machine learning pertain to tackling an empirical risk minimization of the form

$$\min_{\theta \in \Theta} \bar{\mathcal{L}}(\theta) := \mathcal{L}(\theta) + R(\theta) \quad \text{with} \quad \mathcal{L}(\theta) = \frac{1}{n} \sum_{i=1}^n \mathcal{L}_i(\theta) := \frac{1}{n} \sum_{i=1}^n \{-\log g(y_i; \theta)\}$$

- $\{y_i\}_{i=1}^n$ are the observations, Θ is a convex subset of \mathbb{R}^d , $R(\theta)$ is a smooth convex regularization function.
- The objective function $\bar{\mathcal{L}}(\theta)$ is possibly **nonconvex** and is assumed to be **lower bounded** $\bar{\mathcal{L}}(\theta) > -\infty$

Exponential Family

- Latent data model: $\{z_i\}_{i=1}^n$ are not observed
- Complete data likelihood belongs to the curved exponential family:

$$f(z_i, y_i; \theta) = h(z_i, y_i) \exp (\langle S(z_i, y_i) | \phi(\theta) \rangle - \psi(\theta))$$

Sufficient statistics takes values in $S \subset \mathbb{R}^d$

EM Method for Exponential Family

Updates

- **E-step:**

$$\bar{s}(\theta) = \frac{1}{n} \sum_{i=1}^n \bar{s}_i(\theta)$$

where:

$$\bar{s}_i(\theta) = \int_{\mathbf{Z}} S(z_i, y_i) p(z_i | y_i; \theta) \mu(dz_i)$$

- Define the function $L(\cdot; \theta) : S \rightarrow \mathbb{R}$ as:

$$L(s; \theta) := R(\theta) + \psi(\theta) - \langle s | \phi(\theta) \rangle$$

- There exists a function $\bar{\theta} : S \mapsto \Theta$ such that

$$L(s; \bar{\theta}(s)) \leq L(s; \theta)$$

- **M-step:**

$$\theta = \bar{\theta}(\bar{s}) = \arg \min_{\theta \in \Theta} \{R(\theta) + \psi(\theta) - \langle s | \phi(\theta) \rangle\}$$

Limitations

- Even though the EM has appealing features:
 - Monotone in likelihood
 - Invariant w.r.t. parametrization
 - Numerically stable (well defined set)
- It is not applicable with the sheer size of today's data
- Approaches based on Stochastic Optimization:
 - [Neal and Hinton, 1998]: Incremental EM (iEM)
 - [Cappé and Moulines, 2009]: Online EM (sEM)
 - [Chen+, 2018]: Variance Reduces EM (sEM-VR)

Stochastic Optimization for EM Methods

General Formulation

- Stochastic EM:

$$\textbf{sE-step: } \hat{\mathbf{s}}^{(k+1)} = \hat{\mathbf{s}}^{(k)} - \gamma_{k+1} \left(\hat{\mathbf{s}}^{(k)} - \mathcal{S}^{(k+1)} \right)$$

where γ_k is the stepsize and $\mathcal{S}^{(k+1)}$ is a proxy for $\bar{\mathbf{s}}(\boldsymbol{\theta}^{(k)})$

- M-step:

$$\boldsymbol{\theta}^{(k+1)} = \bar{\boldsymbol{\theta}}(\hat{\mathbf{s}}^{(k+1)}) = \arg \min_{\boldsymbol{\theta} \in \Theta} \{R(\boldsymbol{\theta}) + \psi(\boldsymbol{\theta}) - \langle \hat{\mathbf{s}}^{(k+1)} | \phi(\boldsymbol{\theta}) \rangle\}$$

- We simplify the notations:

$$\bar{\mathbf{s}}_i^{(k)} := \bar{\mathbf{s}}_i(\boldsymbol{\theta}^{(k)}) = \int_Z S(z_i, y_i) p(z_i | y_i; \hat{\boldsymbol{\theta}}^{(k)}) \mu(dz_i)$$

$$\bar{\mathbf{s}}^{(k)} := \bar{\mathbf{s}}(\boldsymbol{\theta}^{(k)}) = \frac{1}{n} \sum_{i=1}^n \bar{\mathbf{s}}_i^{(k)}$$

$\ell(k) := m \lfloor k/m \rfloor$ First iteration number of the current epoch

(iEM [NH, 1998])

(sEM [CM, 2009])

(sEM – VR [CZTZ., 2018])

(fiEM [KLMW., 2019])

$$\mathcal{S}^{(k+1)} = \mathcal{S}^{(k)} + \frac{1}{n} (\bar{\mathbf{s}}_{i_k}^{(k)} - \bar{\mathbf{s}}_{i_k}^{(\tau_{i_k}^{(k)})}) \quad [1]$$

$$\mathcal{S}^{(k+1)} = \bar{\mathbf{s}}_{i_k}^{(k)} \quad [2]$$

$$\mathcal{S}^{(k+1)} = \bar{\mathbf{s}}^{(\ell(k))} + (\bar{\mathbf{s}}_{i_k}^{(k)} - \bar{\mathbf{s}}_{i_k}^{(\ell(k))}) \quad [3]$$

$$\begin{aligned} \mathcal{S}^{(k+1)} &= \bar{\mathcal{S}}^{(k)} + (\bar{\mathbf{s}}_{i_k}^{(k)} - \bar{\mathbf{s}}_{i_k}^{(t_{i_k}^{(k)})}) \\ \bar{\mathcal{S}}^{(k+1)} &= \bar{\mathcal{S}}^{(k)} + n^{-1} (\bar{\mathbf{s}}_{j_k}^{(k)} - \bar{\mathbf{s}}_{j_k}^{(t_{j_k}^{(k)})}). \end{aligned} \quad [4]$$

Algorithm 3 sEM algorithms

Initialization: initializations $\hat{\boldsymbol{\theta}}^{(0)} \leftarrow 0$, $\hat{\mathbf{s}}^{(0)} \leftarrow \bar{\mathbf{s}}^{(0)}$, $K_{\max} \leftarrow$ max. iteration number.

Set the terminating iteration number, $K \in \{0, \dots, K_{\max} - 1\}$, as a discrete r.v. with:

$$P(K = k) = \frac{\gamma_k}{\sum_{\ell=0}^{K_{\max}-1} \gamma_\ell}. \quad (42)$$

Iteration k: Given the current state of the chain $\psi_i^{(t-1)}$:

1. Draw index $i_k \in \llbracket 1, n \rrbracket$ uniformly (and $j_k \in \llbracket 1, n \rrbracket$ for fiEM).
2. Compute the surrogate sufficient statistics $\mathcal{S}^{(k+1)}$ using [1] or [2] or [3] or [4]
3. Compute $\hat{\mathbf{s}}^{(k+1)}$ via the sE-step
4. Compute $\boldsymbol{\theta}^{(k+1)}$ via the M-step

Return: $\boldsymbol{\theta}^{(K)}$.

Global Convergence

Assumptions

(A1) The function ϕ is smooth and bounded on the interior of Θ , noted $\text{int}(\Theta)$

For all $(\theta, \theta') \in \text{int}(\Theta)$, $\|J_\phi^\theta(\theta) - J_\phi^\theta(\theta')\| \leq L_\phi \|\theta - \theta'\|$ and $\|J_\phi^\theta(\theta')\| \leq C_\phi$

(A2) The conditional distribution is smooth on $\text{int}(\Theta)$

$$|p(z|y_i; \theta) - p(z|y_i; \theta')| \leq L_p \|\theta - \theta'\|$$

(A3) The function $\theta \rightarrow L(s; \theta) := R(\theta) + \psi(\theta) - \langle s | \phi(\theta) \rangle$ admits a unique global minimum

Also, $J_\phi^\theta(\bar{\theta}(s))$ is full rank and $\bar{\theta}(s)$ is L_θ -Lipschitz

Define:

$$B(s) := J_\phi^\theta(\bar{\theta}(s)) (H_L^\theta(s, \bar{\theta}(s)))^{-1} J_\phi^\theta(\bar{\theta}(s))^\top$$

(A4) $v_{\max} := \sup_{s \in S} \|B(s)\| < \infty$ and $0 < v_{\min} := \inf_{s \in S} \lambda_{\min}(B(s))$

$$\|B(s) - B(s')\| \leq L_B \|s - s'\|$$

Incremental EM Method

Lemma

Under **(A1)-(A4)**, define $e_i(\theta; \theta') := Q_i(\theta; \theta') - \mathcal{L}_i(\theta)$
We have

$$\|\nabla e_i(\theta; \theta') - \nabla e_i(\bar{\theta}; \theta')\| \leq L_e \|\theta - \bar{\theta}\|$$

where $L_e := C_\phi C_Z L_p + C_S L_\phi$

Theorem

Under **(A1)-(A4)** for the iEM [1] for any $K_{\max} \geq 1$

$$\mathbb{E} \left[\left\| \nabla \bar{\mathcal{L}}(\theta^{(K)}) \right\|^2 \right] \leq n \frac{2L_e}{K_{\max}} \mathbb{E} \left[\bar{\mathcal{L}}(\theta^{(0)}) - \bar{\mathcal{L}}(\theta^{(K_{\max})}) \right]$$

where L_e is defined above and K is a uniform random variable on $[0, K_{\max} - 1]$ and independent of the $\{i_k\}_{k=0}^{K_{\max}}$

Stochastic EM as Scaled Gradient Methods

- From a (Scaled) Gradients Method point of view, we consider the minimization problem:

$$\min_{\mathbf{s} \in S} V(\mathbf{s}) := \bar{\mathcal{L}}(\bar{\boldsymbol{\theta}}(\mathbf{s})) = R(\bar{\boldsymbol{\theta}}(\mathbf{s})) + \frac{1}{n} \sum_{i=1}^n \mathcal{L}_i(\bar{\boldsymbol{\theta}}(\mathbf{s}))$$

Lemma

Under **(A1)-(A4)**, we have

$$\|\bar{s}_i(\bar{\boldsymbol{\theta}}(\mathbf{s})) - \bar{s}_i(\bar{\boldsymbol{\theta}}(\mathbf{s}'))\| \leq L_s \|\mathbf{s} - \mathbf{s}'\|$$

$$\|\nabla V(\mathbf{s}) - \nabla V(\mathbf{s}')\| \leq L_V \|\mathbf{s} - \mathbf{s}'\|$$

where $L_s := C_Z L_p L_\theta$ and $L_V := v_{\max} (1 + L_s) + L_B C_S$

Theorem (sEM-VR)

There exists a constant $\mu \in (0, 1)$ such that if
 $\bar{L}_v := \max(L_V, L_s)$ $\gamma = \frac{\mu v_{\min}}{\bar{L}_v n^{2/3}}$ $m = \frac{n}{2\mu^2 v_{\min}^2 + \mu}$

Then:

$$\mathbb{E} \left[\left\| \nabla V \left(\hat{\mathbf{s}}^{(K)} \right) \right\|^2 \right] \leq n^{\frac{2}{3}} \frac{2\bar{L}_v}{\mu K_{\max}} \frac{v_{\max}^2}{v_{\min}^2} \mathbb{E} \left[V \left(\hat{\mathbf{s}}^{(0)} \right) - V \left(\hat{\mathbf{s}}^{(K_{\max})} \right) \right]$$

Theorem (fiEM)

There exists a constant $\mu \in (0, 1)$ such that if
 $\bar{L}_v := \max(L_V, L_s)$ $\gamma = \frac{v_{\min}}{\alpha \bar{L}_v n^{2/3}}$ $\alpha := \max(6, 1 + 4v_{\min})$

Then:

$$\mathbb{E} \left[\left\| \nabla V \left(\hat{\mathbf{s}}^{(K)} \right) \right\|^2 \right] \leq n^{\frac{2}{3}} \frac{\alpha^2 \bar{L}_v}{K_{\max}} \frac{v_{\max}^2}{v_{\min}^2} \mathbb{E} \left[V \left(\hat{\mathbf{s}}^{(0)} \right) - V \left(\hat{\mathbf{s}}^{(K_{\max})} \right) \right]$$

Numerical Applications

Gaussian Mixture Models (GMM)

- Fit a GMM model to a set of n observations
- Each of M components with unit variance
- The complete log likelihood reads:

$$\log f(z_i, y_i; \theta) = \sum_{m=1}^M 1_{\{m\}}(z_i) [\log(\omega_m) - \mu_m^2/2] + \sum_{m=1}^M 1_{\{m\}}(z_i) \mu_m y_i + \text{constant}$$

$$\theta := (\omega, \mu) \quad \omega = \{\omega_m\}_{m=1}^{M-1} \quad \mu = \{\mu_m\}_{m=1}^M$$

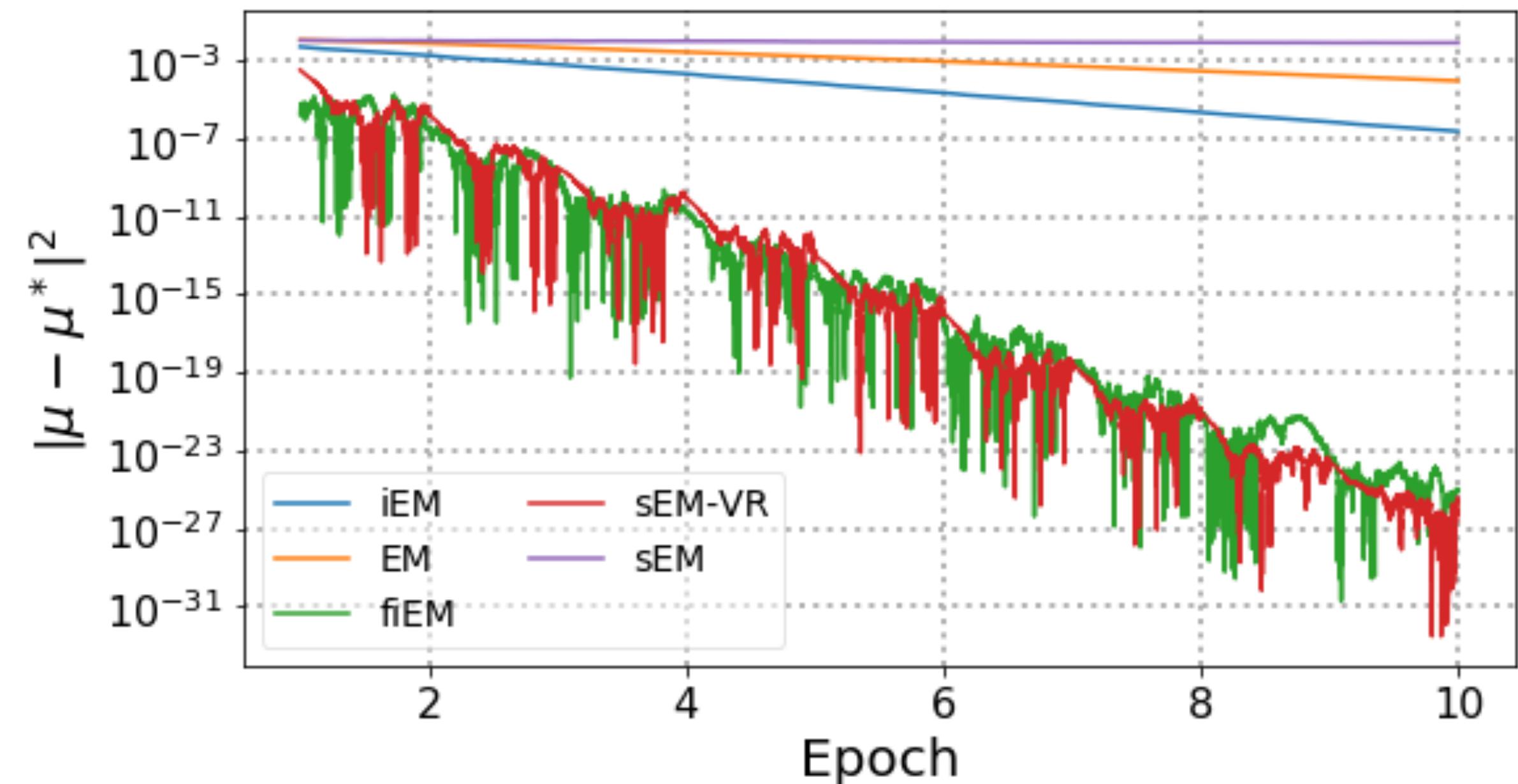
- Penalization used:

$$R(\theta) = \frac{\delta}{2} \sum_{m=1}^M \mu_m^2 - \log \text{Dir}(\omega; M, \epsilon)$$

- Numerical: GMM with $M=2$ and $\mu_1 = -\mu_2 = 0.5$

Experiments

- Fixed sample size:** size $n = 10^4$ and run to get μ^*
- Stepsize for sEM $\gamma_k = 3/(k+10)$
- Stepsize for sEM-VR and fiEM prop. to $1/n^{2/3}$



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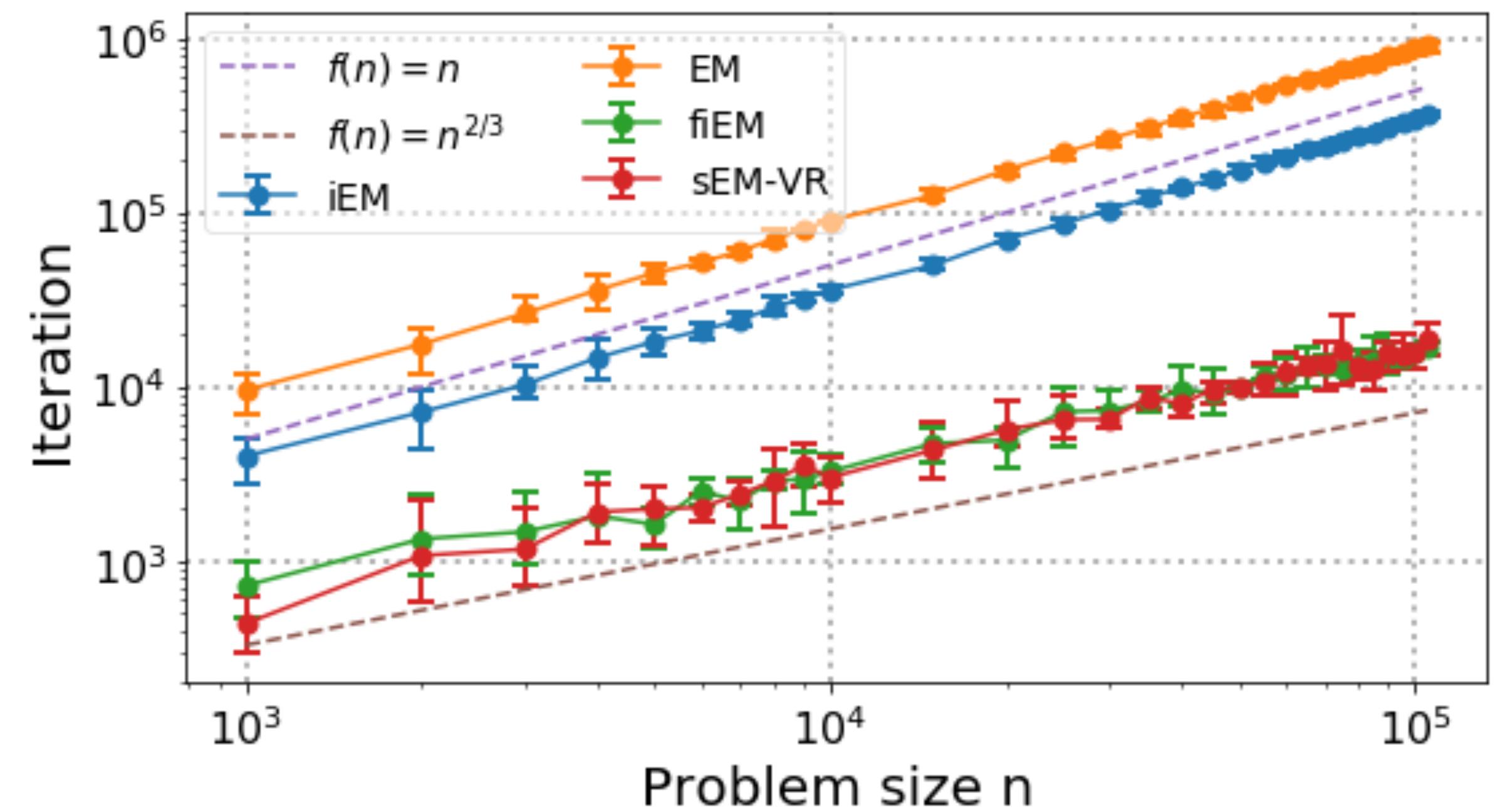
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- Varying sample size:** nb. Iterations required to reach a precision of 10^{-3} from $n = 10^3$ to $n = 10^5$



Numerical Applications

Probabilistic Latent Semantic Analysis

- Consider D documents with terms from a vocabulary of size V.
- Data is summarized by a list of tokens

$$\{y_i\}_{i=1}^n \quad y_i = \left(y_i^{(d)}, y_i^{(w)} \right)$$

- The goal of pLSA is to classify the documents into K topics which is modeled as a latent variable associated with each token $z_i \in [1, K]$

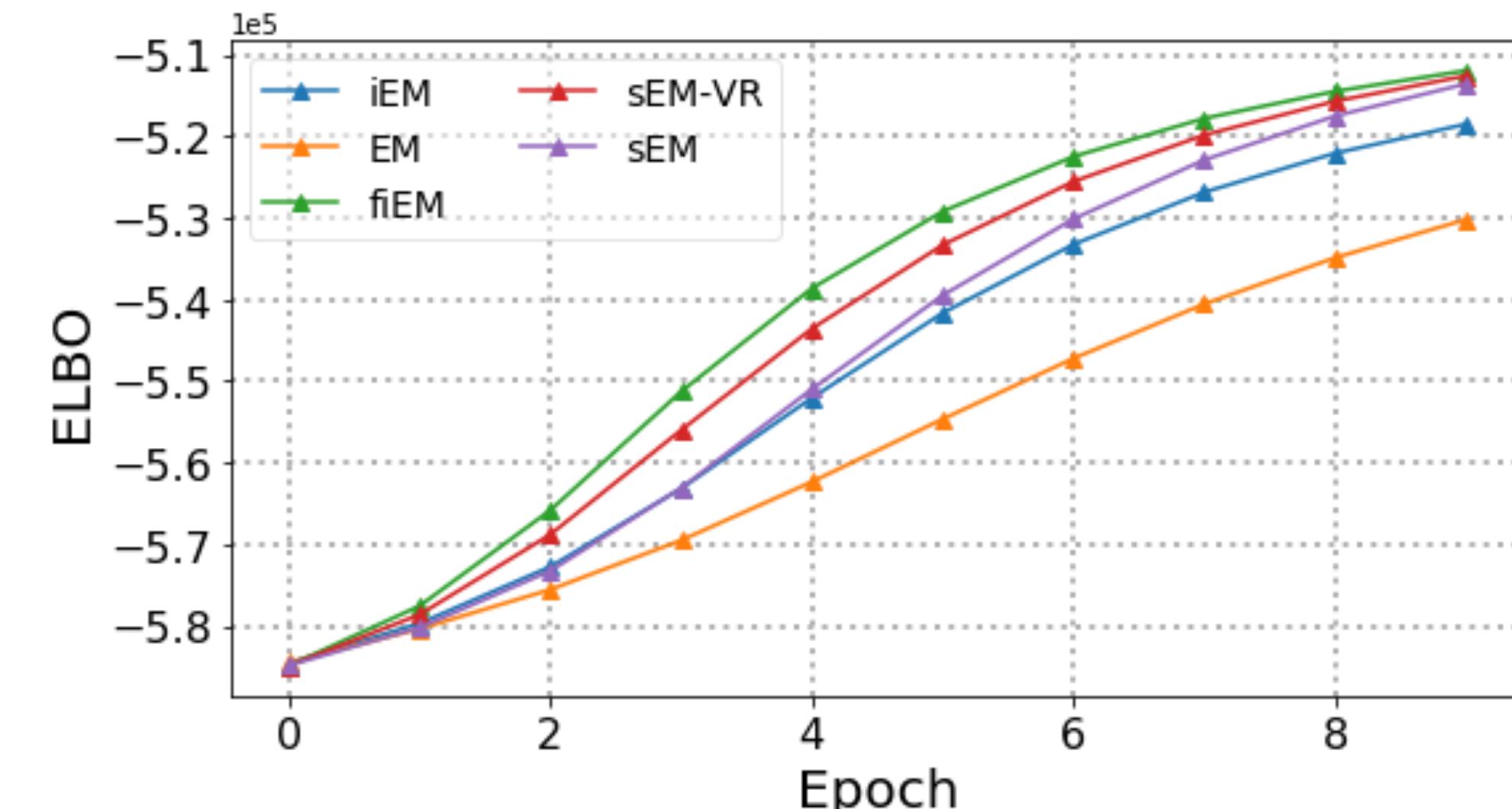
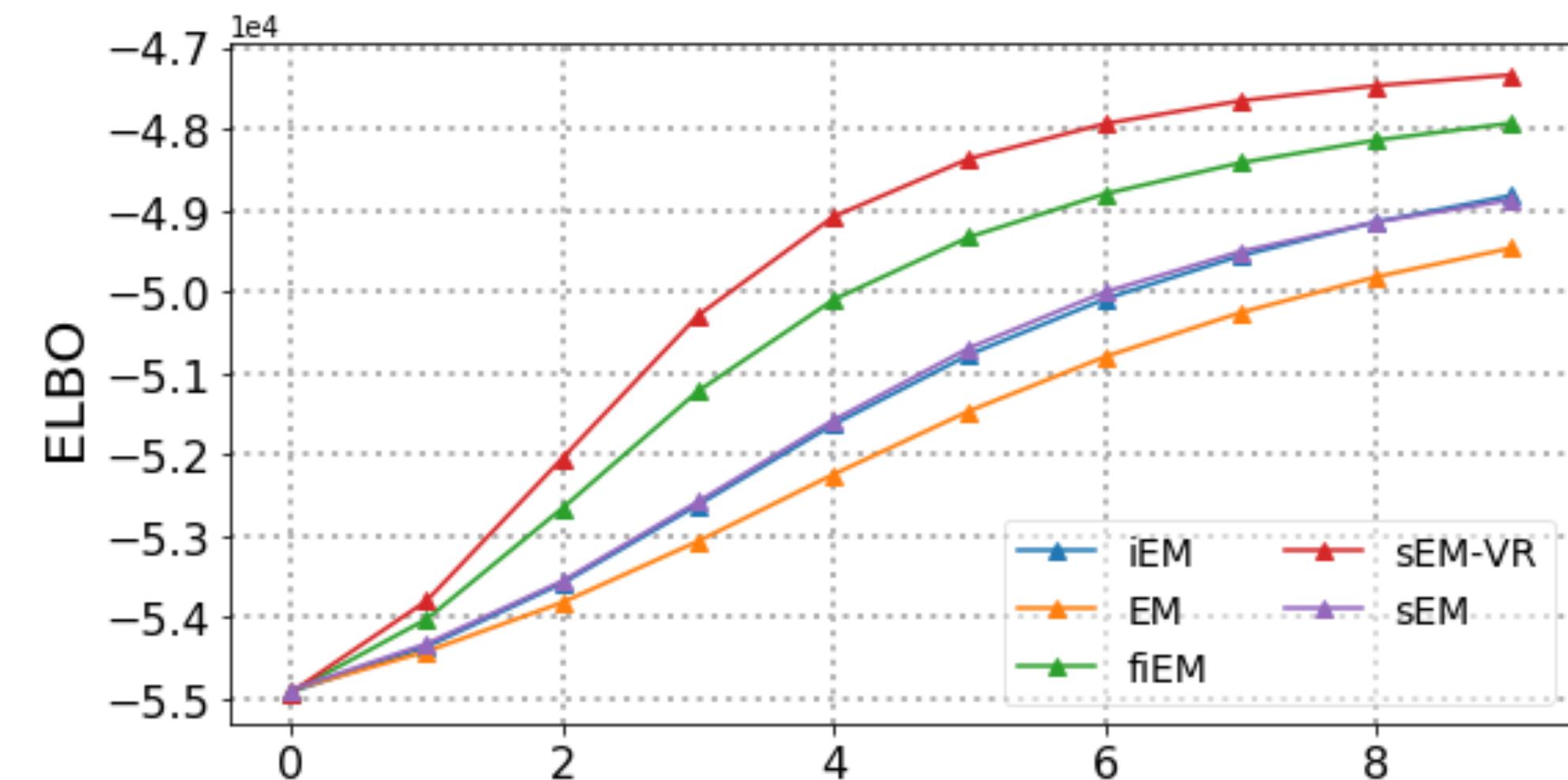
$$\begin{aligned} \log f(z_i, y_i; \theta) &= \sum_{k=1}^K \sum_{d=1}^D \log(\theta_{d,k}^{(t|d)}) \mathbb{1}_{\{k,d\}}(z_i, y_i^{(d)}) \\ &\quad + \sum_{k=1}^K \sum_{v=1}^V \log(\theta_{k,v}^{(w|t)}) \mathbb{1}_{\{k,v\}}(z_i, y_i^{(w)}) \end{aligned}$$

- Penalization used:

$$R(\theta^{(t|d)}, \theta^{(w|t)}) = -\log \text{Dir}(\theta^{(t|d)}; K, \alpha') - \log \text{Dir}(\theta^{(w|t)}; V, \beta')$$

$$\theta := (\theta^{(t|d)}, \theta^{(w|t)})$$

Experiments



Conclusion

Take-Aways

- We studied the global convergence of stochastic EM Methods
 - Globally (independent of initialization)
 - Non-asymptotic results
- We used a Majorization-Minimization scheme to analyze the incremental EM method
- We interpreted the variance-reduced and the fast incremental method using a scaled gradient scheme to find a stationary point of a well defined Lyapunov function

Thank You !