Minimization by Incremental Stochastic Surrogate with Application to Bayesian Deep Learning

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We are interested in the constrained minimization of a large sum of nonconvex functions defined as:

$$\min_{\theta \in \Theta} \left[f(\theta) \triangleq \sum_{i=1}^{N} f_i(\theta) \right] \tag{1}$$

Beforehand, let $\mathcal{T}(\Theta)$ be a neighborhood of Θ and assume that:

M 1. For all $i \in [N]$, f_i is continuously differentiable on $\mathcal{T}(\Theta)$.

M 2. For all $i \in [N]$, f_i is bounded from below, i.e. there exist a constant $M_i \in \mathbb{R}$ such as for all $\theta \in \Theta$, $f_i(\theta) \geq M_i$.

For any $\theta \in \Theta$ and $i \in [N]$, we say, following (Mairal, 2015) that a function $f_{i,\theta} : \mathbb{R}^p \to \mathbb{R}$ is a surrogate of f_i at θ if the following properties are satisfied:

• the function $\vartheta \to f_{i,\theta}(\vartheta)$ is continuously differentiable on $\mathcal{T}(\Theta)$

ullet for all $\vartheta \in \Theta$, $f_{i,\theta}(\vartheta) \geq f_i(\vartheta)$, $f_{i,\theta}(\theta) = f_i(\theta)$ and $\nabla f_{i,\theta}(\vartheta)\Big|_{\vartheta = \theta} = \nabla f_i(\vartheta)\Big|_{\vartheta = \theta}$.

The gap $f_{i,\theta} - f_i$ plays a key role in the convergence analysis and we require this error to be L-smooth for some constant L>0 Denote by $\langle\cdot,\cdot\rangle$ the scalar product, we also introduce the following stationary point condition:

Definition 1. (Asymptotic Stationary Point Condition)

A sequence $(\theta^k)_{k>0}$ satisfies the asymptotic stationary point condition if

$$\liminf_{k \to \infty} \inf_{\theta \in \Theta} \frac{\langle \nabla f(\theta^k), \theta - \theta^k \rangle}{\|\theta - \theta^k\|_2} \ge 0.$$
 (2)

MISO Scheme

The incremental scheme of (Mairal, 2015) computes surrogate functions, at each iteration of the algorithm, for a mini-batch of components:

Algorithm 1 MISO algorithm

Initialization: given an initial parameter estimate θ^0 , for all $i \in [N]$ compute a surrogate function $\vartheta \to f_{i,\theta^0}(\vartheta)$.

Iteration k: given the current estimate θ^{k-1} :

1. Pick a set I_k uniformly on $\{A \subset [N], \operatorname{card}(A) = p\}$

2. For all $i \in I_k$ and compute $\vartheta \to f_{i,\theta^{k-1}}(\vartheta)$, a surrogate of f_i at θ^{k-1} .

3. Set $\theta^k \in \arg\min_{\vartheta \in \Theta} \sum_{i=1}^N a_i^k(\vartheta)$ where $a_i^k(\vartheta)$ are defined recursively as follows:

$$a_i^k(\vartheta) \triangleq \begin{cases} f_{i,\theta^{k-1}}(\vartheta) & \text{if } i \in I_k \\ a_i^{k-1}(\vartheta) & \text{otherwise} \end{cases} \tag{3}$$

MISSO Scheme

• Case when the surrogate functions computed in Algorithm 1 are not tractable.

Assume that the surrogate can be expressed as an integral over a set of latent variables $z = (z_i \in Z_i, i \in [N]) \in Z$ where $Z = X_{i=1}^N Z_i$ where Z_i is a subset of \mathbb{R}^{m_i} .

$$f_{i,\theta}(\vartheta) \triangleq \int_{\mathbf{7}} r_{i,\theta}(z_i,\vartheta) p_i(z_i,\theta) \mu_i(\mathrm{d}z_i) \quad \text{for all } (\theta,\vartheta) \in \Theta^2.$$
 (4)

Our scheme is based on the computation, at each iteration, of stochastic auxiliary functions for a mini-batch of components. For $i \in [N]$, the auxiliary function, noted $\hat{f}_{i,\theta}(\vartheta)$ is a Monte Carlo approximation of the surrogate function $f_{i,\theta}(\vartheta)$ defined by (4) such that:

$$\hat{f}_{i,\theta}(\vartheta) \triangleq \frac{1}{M} \sum_{m=0}^{M-1} r_{i,\theta}(z_i^m, \vartheta) \quad \text{for all } (\theta, \vartheta) \in \Theta^2$$
 (5)

where $\{z_i^m\}_{m=0}^{M-1}$ is a Monte Carlo batch.

Algorithm 2 MISSO algorithm

Initialization: given an initial parameter estimate θ^0 , for all $i \in [N]$ compute the function $\vartheta \to f_{i,\theta^0}(\vartheta)$ defined by (5).

Iteration k: given the current estimate θ^{k-1} :

1. Pick a set I_k uniformly on $\{A \subset [N], \operatorname{card}(A) = p\}$

2. For all $i \in I_k$, sample a Monte Carlo batch $\{z_i^{k,m}\}_{m=0}^{M_k-1}$ from $p_i(z_i, \theta^{k-1})$.

3. For all $i \in I_k$, compute the function $\vartheta \to \hat{f}_{i,\theta^{k-1}}(\vartheta)$ defined by (5).

4. Set $\theta^k \in \arg\min_{\vartheta \in \Theta} \sum_{i=1}^N \hat{a}_i^k(\vartheta)$ where $\hat{a}_i^k(\vartheta)$ are defined recursively as follows:

$$\hat{a}_i^k(\vartheta) \triangleq \begin{cases} \hat{f}_{i,\theta^{k-1}}(\vartheta) & \text{if } i \in I_k \\ \hat{a}_i^{k-1}(\vartheta) & \text{otherwise} \end{cases} \tag{6}$$

Convergence Guarantees Assumptions

Whether we use Markov Chain Monte Carlo or direct simulation, we need to control the supremum norm of the fluctuations of the Monte Carlo approximation. Let $i \in [N]$, $\{j_i(z_i,\vartheta),z_i\in\mathsf{Z}_i,\vartheta\in\Theta\}$ be a family of measurable functions, λ_i a probability measure on $Z_i \times Z_i$. We define:

$$C_{i}(j_{i}) \triangleq \sup_{\theta \in \Theta} \sup_{M>0} M^{-1/2} \mathbb{E}_{i,\theta} \left[\sup_{\theta \in \Theta} \left| \sum_{m=0}^{M-1} \left\{ j_{i}(z_{i}^{m}, \theta) - \int_{\mathsf{Z}_{i}} j_{i}(z_{i}, \theta) p_{i}(z_{i}, \theta) \lambda_{i}(\mathrm{d}z_{i}) \right\} \right]$$
(7

M 3. For all $i \in [N]$ and $\theta \in \Theta$:

$$\lim_{k \to \infty} C_i(r_{i,\theta}) < \infty \quad and \quad \lim_{k \to \infty} C_i(\nabla r_{i,\theta}) < \infty. \tag{8}$$

M 4. $\{M_k\}_{k\geq 0}$ is a non deacreasing sequence of integers which satisfies $\sum_{k=0}^{\infty} M_k^{-1/2} < \infty$.





Theorem: MISSO Convergence Guarantees

Assume M1-M4. Let $(\theta^k)_{l>1}$ be a sequence generated from $\theta^0\in\Theta$ by the iterative application described by Algorithm 2. Then:

(i) $\left(f(\theta^k)\right)_{k>1}$ converges almost surely.

(ii) $\left(\theta^k\right)_{k\geq 1}$ satisfies the Asymptotic Stationary Point Condition.

Application to Variational Bayesian Inference

• Let $x=(x_i, i\in [\![N]\!])$ and $y=(y_i, i\in [\![N]\!])$ be i.i.d. input-output pairs and w be a global latent variable taking values in W as subset of \mathbb{R}^J . A natural decomposition of the joint distribution is:

$$p(y, x, w) = p(w) \prod_{i=1}^{N} p_i(y_i | x_i, w)$$
(9)

The goal is to calculate the posterior distribution p(w|y,x).

Variational inference problem boils down to minimizing the following KL divergence:

$$\theta^* = \arg\min_{\theta \in \Theta} \text{KL}(q(w; \theta) \parallel p(w|y, x)) = \arg\min_{\theta \in \Theta} f(\theta)$$
(10)

where for all $\theta \in \Theta$, $f(\theta) = \sum_{i=1}^{N} f_i(\theta)$ with :

$$f_i(\theta) \triangleq -\int_{\mathsf{W}} q(w;\theta) \log p_i(y_i, x_i | w) \mathrm{d}w + \frac{1}{N} \mathrm{KL}(q(w;\theta) \parallel p(w)) = r_i(\theta) + d(\theta)$$
 (11)

• Define following quadratic surrogate at $\theta \in \Theta$:

$$f_{i,\theta}(\vartheta) \triangleq f_i(\theta) + \nabla f_i(\theta)^{\top} (\vartheta - \theta) + \frac{L}{2} \|\vartheta - \theta\|_2^2$$
 (12)

where $\|\cdot\|_2$ is the ℓ_2 -norm and L is an upper bound of the spectral norm of the Hessian of f_i at θ .

• Reparametrization trick: We assume that for all $\theta \in \Theta$, the distribution of the random vector $W=t(\theta,\epsilon)$ where $\epsilon\sim\mathcal{N}_d(0,\mathrm{Id})$ has a density $q(\cdot,\theta)$. Then, following (Proposition 1)blundell:

$$\nabla \int_{\mathsf{W}} \log p_i(y_i, x_i | w) q(w, \theta) dw = \int_{\mathsf{W}} J(\theta, e) \nabla \log p_i(y_i, x_i | t(\theta, e)) \phi(e) de$$

where for each $e \in \mathbb{R}^d$, $J(\theta, e)$ is the Jacobian of the function $t(\cdot, e)$ with respect to θ .

• The pair $(r_{i,\theta}(e,\vartheta),\phi(e))$ defining $f_{i,\theta}(\vartheta)$ is given by:

$$r_{i,\theta}(e,\vartheta) \triangleq \left(-\log p_i(y_i, x_i | t(\theta, e)) + d(\theta)\right) + \left(-J(\theta, e)\nabla \log p_i(y_i, x_i | t(\theta, e)) + \nabla d(\theta)\right)^{\top} (\vartheta - \theta) + \frac{L}{2} \|\vartheta - \theta\|_2^2$$
(13)

The MISSO algorithm consists in:

. Picking a set I_k uniformly on $\{A \subset [N], \operatorname{card}(A) = p\}$.

2. Sampling a Monte Carlo batch $\{\epsilon^{k,m}\}_{m=0}^{M_k-1}$ from the standard Gaussian distribution.

3. Setting $\theta^k = \theta^{k-1} - \frac{1}{L} \sum_{i=1}^N \hat{a}_i^k$ where \hat{a}_i^k are defined recursively as follows:

$$\hat{a}_i^k \triangleq \begin{cases} -\frac{1}{M_k} \sum_{m=0}^{M_k-1} \mathbf{J}(\theta, e^{k,m}) \nabla_{\theta} \log p_i(y_i, x_i | t(\theta, e^{k,m})) + \nabla d(\theta^{k-1}) & \text{if } i \in I_k \\ \hat{a}_i^{k-1} & \text{otherwise} \end{cases}$$
(14)

Training a Bayesian Neural Network on MNIST

Settings

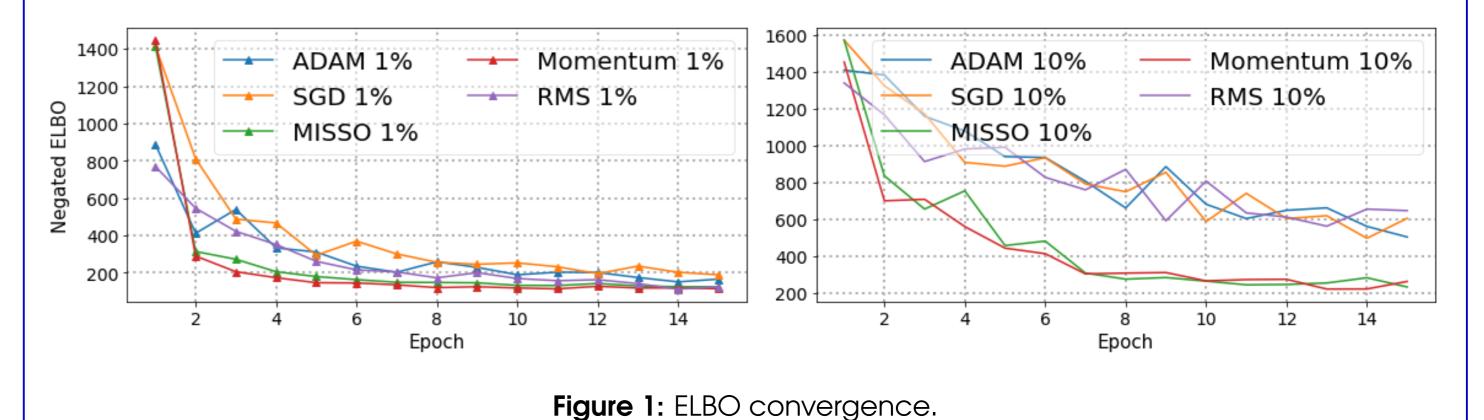
References

- 2-layer bayesian neural network
- Tanh activation function
- Standard Gaussian prior on the weight
- Gaussian variational posterior independent of i and l (layers)

$$p(w) = \mathcal{N}(0, \text{Id})$$

 $p(y_i|x_i, w) = \text{Softmax}(f(x_i, w))$

- Input layer d = 784
- \bullet A single hidden layer of p=100 hyperbolic tangent units
- ullet Final softmax output layer with K=10 classes
- MNIST dataset $N=60\,000$



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