# **Variance Reduced Federated Learning**

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#### **Abstract**

To be completed

## 2 1 SAGA-like Algorithms

#### 3 1.1 Local SGD

### Algorithm 1 SAGA Local SGD

- 1: **Input:** Local learning rate  $\gamma$  and global learning rate  $\eta$  and communication period p.
- 2: **Init:**  $g^{(k)} = \frac{1}{n} \sum_{i=1}^{n} g^{(0)}$ . 3: **for** k = 0, 1, ..., K **do**
- 4: Draw two independent and distinct indices  $i_k$  and  $j_k$
- 5: **for**  $\tau = k, ..., k + p 1$  **do**
- 6: Compute the following quantity

$$v_{i_k}^{(\tau)} = v_{i_k}^{(\tau-1)} - \gamma(\nabla f_{i_k} \left( x^{(k)} \right) - \nabla f_{i_k} \left( \alpha_{i_{(k)}}^t \right) + g^{(k)})$$

- $\begin{array}{ll} \text{7:} & \textbf{end for} \\ \text{8:} & v_{i_k}^{(k)} \leftarrow v_{i_k}^{(k+p-1)} \\ \text{9:} & \textbf{Update the global model} \end{array}$

$$x^{(k+1)} = x^{(k)} - \eta v_{i_k}^{(k)}$$

- $\begin{array}{ll} \text{10:} & \text{Update } \alpha_{j_k}^{(k+1)} = x^{(k)} \text{ and } \alpha_{j}^{(k+1)} = \alpha_{j}^{(k)} \text{ for } j \neq j_k \\ \text{11:} & \text{Update } g^{(k+1)} = g^{(k)} \frac{1}{n} \left( \nabla f_{j_k} \left( \alpha_{j_k}^{(k)} \right) \nabla f_{j_k} \left( \alpha_{j_k}^{(k+1)} \right) \right) \\ \end{array}$
- 12: **end for**

#### 4 1.2 FedSVRG with Sketching

## Algorithm 2 FedSVRG: SVRG Federated Learning algorithm with Sketching.

```
1: Inputs: x^{(0)} initial common model, communication rounds R, the number of local updates K,
       and global and local learning rates \gamma and \eta
 2: for r = 0, \dots, R - 1 do
                 parallel for device j=1,\ldots,n do: Computes \Phi^{(r)} \triangleq \mathbb{Q}\left[\mathbf{S}^{(r-1)}\right] (Q is any query function)
 3:
 4:
                       Set \boldsymbol{x}^{(r)} = \boldsymbol{x}^{(r-1)} - \gamma \boldsymbol{\Phi}^{(r)}
 5:
                       Set \boldsymbol{x}_{i}^{(0,r)} = \boldsymbol{x}^{(r)}
 6:
                       Compute full gradient \nabla f_j(\boldsymbol{x}^{(\kappa(r))}) = \frac{1}{n_i} \sum_{i=1}^{n_j} \nabla f_j(\boldsymbol{x}^{(\kappa(r))}, \xi_i)
 7:
                      for \ell = 0, ..., K - 1 do
 8:
                           Sample an index i_{\ell} uniformly on [n_j]
\boldsymbol{x}_j^{(\ell+1,r)} = \boldsymbol{x}_j^{(\ell,r)} - \eta \left( \nabla f_j(\boldsymbol{x}_j^{(\ell,r)}, \xi_{j,i_{\ell}}) - \nabla f_j(\boldsymbol{x}^{(\kappa(r))}, \xi_{j,i_{\ell}}) + \nabla f_j(\boldsymbol{x}^{(\kappa(r))}) \right)
 9:
10:
11:
                          Device j sends \mathbf{S}_{j}^{(r)} \triangleq \mathbf{S}_{j} \left( \boldsymbol{x}_{j}^{(0,r)} - \ \boldsymbol{x}_{j}^{(K,r)} \right) back to the server.
12:
                 Server computes
13:
                          \mathbf{S}^{(r)} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{S}_{i}^{(r)} and broadcasts \mathbf{S}^{(r)} to all devices.
14:
15:
                 end parallel for
16: end
17: Output: x^{(R-1)}
```

- 5 **Particularity:**  $\kappa(r)$  is the epoch number at which we compute both control variate terms. We can
- 6 have  $\kappa(r) = r$  or something else (to tune).

#### 7 1.3 FedSAGA with Sketching

#### Algorithm 3 FedSAGA: SAGA Federated Learning algorithm with Sketching.

```
1: Inputs: x^{(0)} initial common model, communication rounds R, the number of local updates K,
       and global and local learning rates \gamma and \eta
 2: for r = 0, \dots, R-1 do
                parallel for device j=1,\ldots,n do: Computes \Phi^{(r)} \triangleq \mathbb{Q}\left[\mathbf{S}^{(r-1)}\right] (Q is any query function)
 3:
 4:
                      Set \boldsymbol{x}^{(r)} = \boldsymbol{x}^{(r-1)} - \gamma \boldsymbol{\Phi}^{(r)}
 5:
                      Set \boldsymbol{x}_i^{(0,r)} = \boldsymbol{x}^{(r)}
 6:
                      Compute full gradient \nabla f_j(\boldsymbol{x}^{(r)}) = \frac{1}{n_i} \sum_{i=1}^{n_j} \nabla f_j(\boldsymbol{x}^{(r)}, \xi_i)
 7:
                     for \ell = 0, \dots, K-1 do
 8:
                          Sample an indices (i_\ell,q_\ell) independently and uniformly on [n_j]
 9:
                          where \overline{F}_{j}^{(r)} = \frac{1}{n_{j}} \sum_{i=1}^{n_{j}} \nabla f_{j}(\boldsymbol{x}_{j}^{(\ell,r)}, \xi_{i}) + \frac{1}{n_{j}} (\nabla f_{j}(\boldsymbol{x}_{j}^{(\ell,r)}, \xi_{j,i_{\ell}}) - \nabla f_{j}(\boldsymbol{x}_{j}^{(t_{i_{\ell}},r)}, \xi_{j,i_{\ell}}) + \overline{F}_{j}^{(r)})
10:
11:
12:
                          Device j sends \mathbf{S}_{j}^{(r)} \triangleq \mathbf{S}_{j} \left( \boldsymbol{x}_{j}^{(0,r)} - \ \boldsymbol{x}_{j}^{(K,r)} \right) back to the server.
13:
                Server computes
14:
                         \mathbf{S}^{(r)} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{S}_{i}^{(r)} and broadcasts \mathbf{S}^{(r)} to all devices.
15:
16:
                end parallel for
17: end
18: Output: x^{(R-1)}
```

- **Particularity:** We need to store each local models on each device j in order to compute the control variate terms. No epoch tuning though. Indeed  $x_j^{(t_{i_\ell},r)}$  is the value of local model on device j when index  $i_\ell$  was drawn last.

#### 2 Numerical Examples 11