# AniLA: Anisotropic Langevin Dynamics for training Energy-Based Models

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#### Abstract

#### 1 Introduction

Given a stream of input noted x, the energy-based model (EBM) is a Gibbs distribution defined as:

$$p_{\theta}(x) = \frac{1}{Z(\theta)} \exp(f_{\theta}(x)) \tag{1}$$

#### 2 MCMC based EBM

**Energy Based Models:** 

MCMC procedures:

Focus on Langevin Diffusion:

### 3 ANILA sampler based EBM

#### 3.1 Curvature informed MCMC

We introduce a new sampler based on the Langevin updates presented above.

#### Algorithm 1 Anila for Energy-Based Model

- 1: **Input**: Total number of iterations T, number of MCMC transitions K and of samples M learning rate  $\eta$ , initial values  $\theta_0$ ,  $\{z_0^m\}_{m=1}^M$  and n observations  $\{x_i\}_{i=1}^n$ .
- 2: **for** t = 1 to T **do**
- 3: Compute the anisotropic stepsize as follows:

$$\gamma_t = \frac{b}{\max(b, |\nabla f_{\theta_t}(x)|} \tag{2}$$

4: Draw m samples  $\{z_t^m\}_{m=1}^M$  from the objective potential (1) via Langevin diffusion:

$$z_t^m = z_t^m + \gamma_t / 2\nabla f_{\theta_t}(x) + \sqrt{\gamma} \mathsf{B}_t \tag{3}$$

where  $B_t$  is the brownian motion, drawn from a Normal distribution.

- Samples m positive observations  $\{x_i\}_{i=1}^m$  from the empirical data distribution
- 6: Compute the gradient of the empirical log-EBM (1) as follows:

$$\nabla \sum_{i=1}^{m} \log p_{\theta_t}(x_i) = \mathbb{E}_{p_{\text{data}}} \left[ \nabla_{\theta} f_{\theta_t}(x) \right] - \mathbb{E}_{p_{\theta}} \left[ \nabla_{\theta_t} f_{\theta}(z_t^m) \right] \approx \frac{1}{m} \sum_{i=1}^{m} \nabla_{\theta} f_{\theta_t}(x_i) - \frac{1}{m} \sum_{i=1}^{m} \nabla_{\theta} f_{\theta_t}(z_t^m)$$
(4)

7: Update the vector of global parameters of the EBM:

$$\theta_{t+1} = \theta_{t+1} + \eta \nabla \sum_{i=1}^{m} \log p_{\theta_t}(x_i)$$
(5)

- 8: end for
- 9: Output: Generated samples  $\{z_T^m\}_{m=1}^M$

#### 3.2 Geometric ergodicity of ANILA sampler

We will present in this subsection, a convergence result for the Markov Chain constructed using Line3-4.

## 4 Numerical Experiments

#### 5 Conclusion