```
Input: Y = \{Y_1, Y_2, \cdots, Y_T\}, \pi, A, B
Output: X = \{X_1, X_2, \cdots, X_T\}
begin
      \mathbf{O} \leftarrow \{O_1, O_2, \cdots, O_N\}; \\ \mathbf{S} \leftarrow \{S_1, S_2, \cdots, S_K\};
      for each state i \in \{1, 2, \dots K\} do
           T_1[i,1] \leftarrow \pi \cdot \mathbf{B}_{iy_1};
        T_2[i,1] \leftarrow 0
      \mathbf{end}
      for each observation i \in \{2, 3, \dots T\} do
            for each state j \in \{1, 2, \dots K\} do
                 T_1[j,i] \leftarrow \mathbf{B}_{jy_i} \cdot \max\{T_1[k,i-1] \cdot A_{kj}\};
                 T_2[j,i] \leftarrow \operatorname{argmax} \{T_1[k,i-1] \cdot A_{kj}\}
            \mathbf{end}
      end
      Z_T \leftarrow \operatorname{argmax} \{T_1[k,T]\};
     X_T \leftarrow S_{Z_T};

for i \leftarrow T, T - 1, \cdots, 2 do
           Z_{i-1} \leftarrow T_2[Z_i, i];
           X_{i-1} \leftarrow S_{Z_{i-1}}
     \mathbf{end}
\mathbf{end}
```

Algorithm 1: Viterbi Algorithm