COMP9024: Data Structures and Algorithms

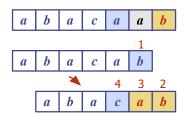
Text Processing

1

Contents

- Pattern matching
- Tries
- · Greedy method
- Text compression
- Dynamic programming

Pattern Matching



3

3

Strings

- A string is a sequence of characters
- Examples of strings:
 - · Java program
 - HTML document
 - DNA sequence
 - Digitized image
- An alphabet Σ is the set of possible characters for a family of strings
- Example of alphabets:
 - ASCII
 - Unicode
 - {0, 1}
 - {A, C, G, T}

- Let ${\it P}$ be a string of size ${\it m}$
 - A substring P[i..j] of P is the subsequence of P consisting of the characters with ranks between i and j
 - A prefix of ${\bf P}$ is a substring of the type ${\bf P}[0 \dots {\bf i}]$
 - A suffix of P is a substring of the type P[i..m 1]
- Given strings T (text) and P (pattern), the pattern matching problem consists of finding a substring of T equal to P
- Applications:
 - Text editors
 - Search engines
 - Biological research

Brute-Force Pattern Matching

- The brute-force pattern matching algorithm compares the pattern P with the text T for each possible shift of P relative to T, until either
 - · a match is found, or
 - all placements of the pattern have been tried
- Brute-force pattern matching runs in time O(nm)
- Example of worst case:
 - $T = aaa \dots ah$
 - P = aaah
 - may occur in images and DNA sequences
 - · unlikely in English text

```
Algorithm BruteForceMatch(T, P)
Input text T of size n and pattern
P of size m

Output starting index of a substring of
T equal to P or -1 if no such
substring exists

{ for ( i = 0; i < n - m + 1; i + + 1)
{ // test shift i of the pattern
j = 0;
while (j < m \land T[i + j] = P[j])
j = j + 1;
if (j = m)
return i; // match at i
}

return -1 // no match anywhere
}
```

-

5

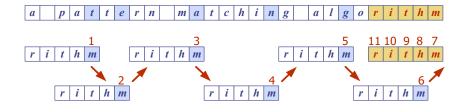
Boyer-Moore Heuristics

• The Boyer-Moore's pattern matching algorithm is based on two heuristics

Looking-glass heuristic: Compare ${\it P}$ with a subsequence of ${\it T}$ moving backwards

Character-jump heuristic: When a mismatch occurs at T[i] = c

- If P contains c, shift P to align the last occurrence of c in P with T[i]
- Else, shift P to align P[0] with T[i+1]
- Example



Last-Occurrence Function

- Boyer-Moore's algorithm preprocesses the pattern P and the alphabet Σ to build the last-occurrence function L mapping Σ to integers, where L(c) is defined as
 - the largest index i such that P[i] = c or
 - \bullet -1 if no such index exists
- Example:
 - $\Sigma = \{a, b, c, d\}$
 - P = abacab

c	а	b	c	d	
L(c)	4	5	3	-1	

- The last-occurrence function can be represented by an array indexed by the numeric codes of the characters
- The last-occurrence function can be computed in time O(m+s), where m is the size of P and s is the size of Σ

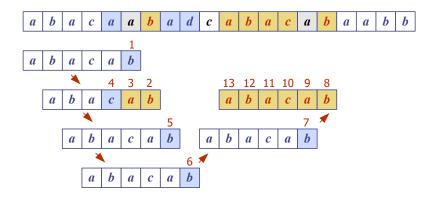
7

7

The Boyer-Moore Algorithm

```
Algorithm BoyerMooreMatch(T, P, \Sigma)
   \{ L = lastOccurenceFunction(P, \Sigma) \}
    i = m - 1
    j = m - 1
     repeat
       if (T[i] = P[j])
           \{ if (j=0) \}
               return i // match at i
             else
               \{i = i - 1;
                 j = j - 1; 
       else // character-jump
           \{l=L[T[i]];
             i = i + m - \min(j, 1 + l);
             j = m - 1; 
     until (i > n - 1)
     return -1 // no match
```





9

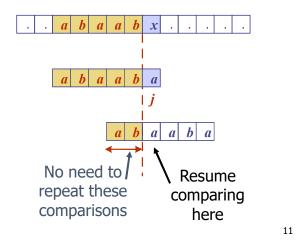
9

Analysis

- Boyer-Moore's algorithm runs in time O(nm + s)
- Example of worst case:
 - $T = aaa \dots a$
 - P = baaa
- The worst case may occur in images and DNA sequences but is unlikely in English text
- Boyer-Moore's algorithm is significantly faster than the brute-force algorithm on English text

The KMP Algorithm

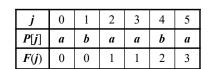
- Knuth-Morris-Pratt's algorithm compares the pattern to the text in left-toright, but shifts the pattern more intelligently than the brute-force algorithm.
- When a mismatch occurs, what is the most we can shift the pattern so as to avoid redundant comparisons?
- Answer: the largest prefix of P[0..j-1] that is a suffix of P[1..j-1]

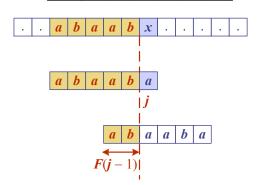


11

KMP Failure Function

- Knuth-Morris-Pratt's algorithm preprocesses the pattern to find matches of prefixes of the pattern with the pattern itself
- The failure function F(j) is defined as the size of the largest prefix of P[0..j] that is also a suffix of P[1..j]
- Knuth-Morris-Pratt's algorithm modifies the brute-force algorithm so that if a mismatch occurs at P[j] ≠ T[i] we set j ← F(j-1)





The KMP Algorithm

- The failure function can be represented by an array and can be computed in O(m) time
- At each iteration of the whileloop, either
 - *i* increases by one, or
 - the shift amount i − j increases by at least one (observe that F(j − 1) < j)
- Hence, there are no more than 2n iterations of the while-loop
- Thus, KMP's algorithm runs in optimal time O(m + n)

```
Algorithm KMPMatch(T, P)  \{ F = failureFunction(P); \\ i = 0; \\ j = 0; \\ while (i < n) \\ if (T[i] = P[j]) \\ \{ if (j = m - 1) \\ return i - j; // match \\ else \\ \{ i = i + 1; j = j + 1; \} \\ else \\ if (j > 0) \\ j = F[j - 1]; \\ else \\ i = i + 1; \\ return - 1; // no match \\ \}
```

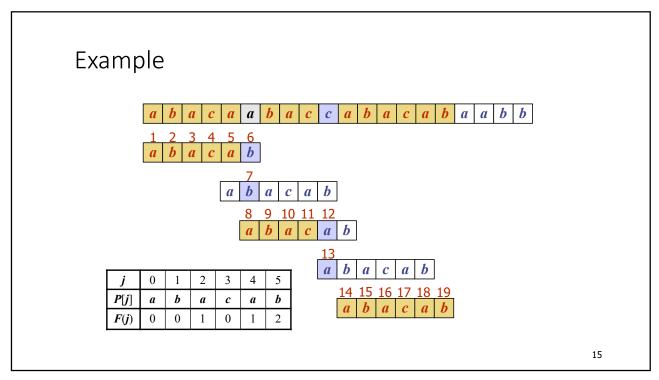
13

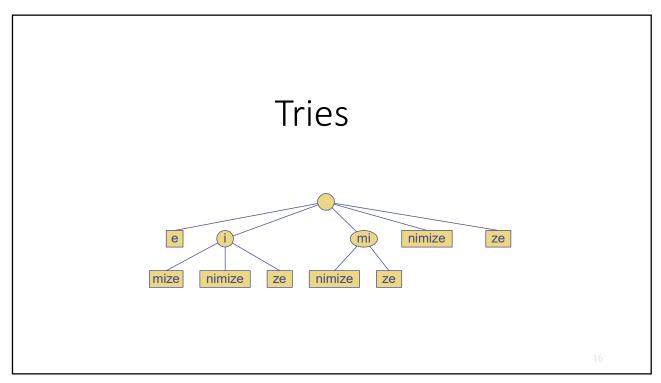
13

Computing the Failure Function

- The failure function can be represented by an array and can be computed in O(m) time
- The construction is similar to the KMP algorithm itself
- At each iteration of the whileloop, either
 - *i* increases by one, or
 - the shift amount i − j increases by at least one (observe that F(j −1) < j)
- Hence, there are no more than 2m iterations of the while-loop

```
Algorithm failureFunction(P)
 \{ F[0] = 0;
    i = 1;
    j = 0;
    while (i < m)
       if (P[i] = P[j])
          \{ // \text{ we have matched } \boldsymbol{j} + 1 \text{ char }
            F[i] = j + 1;
             i = i + 1;
             j = j + 1; 
       else if (j>0)
           // use failure function to shift P
                 j = F[j-1];
                \{ F[i] = 0; // \text{ no match } 
                  i = i + 1;
 }
```





Preprocessing Strings

- Preprocessing the pattern speeds up pattern matching queries
 - After preprocessing the pattern, KMP's algorithm performs pattern matching in time proportional to the text size
- If the text is large, immutable and searched for often (e.g., works by Shakespeare), we may want to preprocess the text instead of the pattern
- A trie is a compact data structure for representing a set of strings, such as all the words in a text
 - A tries supports pattern matching queries in time proportional to the pattern size

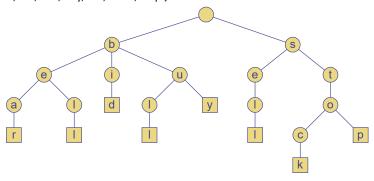
17

17

Standard Tries

- The standard trie for a set of strings S is an ordered tree such that:
 - Each node but the root is labeled with a character
 - The children of a node are alphabetically ordered
 - The paths from the external nodes to the root yield the strings of S
- Example: standard trie for the set of strings

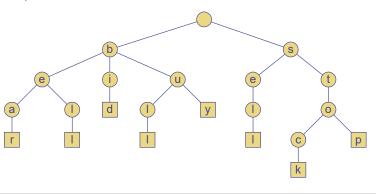
S = { bear, bell, bid, bull, buy, sell, stock, stop }



18

Analysis of Standard Tries

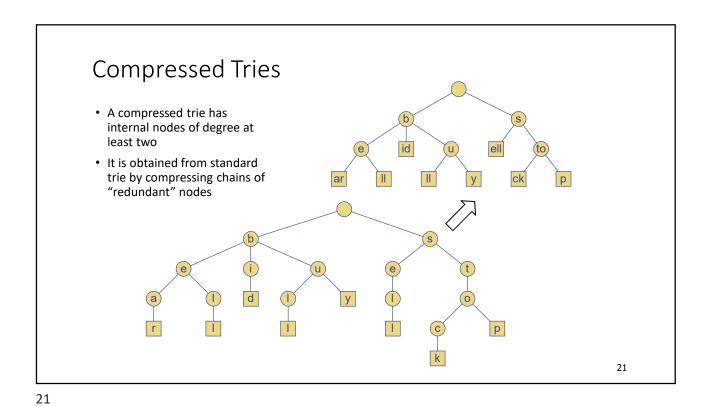
- A standard trie uses O(n) space and supports searches, insertions and deletions in time O(dm), where:
 - n total size of the strings in S
 - *m* size of the string parameter of the operation
 - d size of the alphabet



19

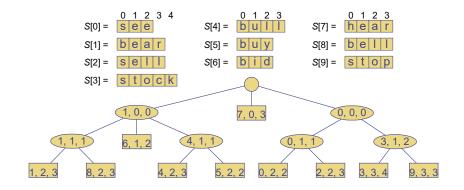
19

Word Matching with a Trie · We insert the s e e a b e a r ? s e I I 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 words of the text into a trie s e e a b u I I ? b u y s t o c k ! 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 · Each leaf stores | b | i | d | | s | t | o | c | k | ! | | b | i | d | | s | t | o | c | k | ! | the occurrences of h e a r t h e b e l l ? the associated 69 70 71 72 73 74 75 76 77 78 79 80 81 82 83 84 85 86 87 88 word in the text d 0, 24 30 17, 40, 51, 62 20



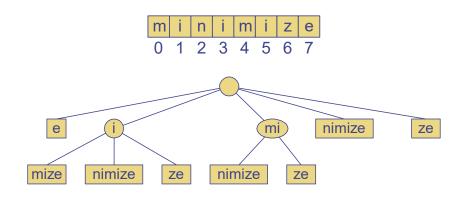
Compact Representation

- Compact representation of a compressed trie for an array of strings:
 - Stores at the nodes ranges of indices instead of substrings
 - Uses O(s) space, where s is the number of strings in the array
 - Serves as an auxiliary index structure



Suffix Trie

ullet The suffix trie of a string X is the compressed trie of all the suffixes of X



23

23

Pattern Matching Using Suffix Trie (1/2)

```
Algorithm suffixTrieMatch(T, P)
 { p = P.length; j = 0; v = T.root();
      { for each child w of v do
           \{ // \text{ we have matched } j + 1 \text{ char }
              childTraversed=false; i = \text{start}(w); // start(w) is the start index of w
              if (P[j] = X[i]) // process child w
                 { childTraversed=true;
                   x = \text{end}(w) - i + 1; // end(w) is the end index of w
                   if (p \le x)
                    // suffix is shorter than or of the same length of the node label
                      { if (P[j:j+p-1] = X[i:i+p-1]) return i-j; else return "P is not a substring of X"; }
                   else // the pattern goes beyond the substring stored at w
                      { if (P[j:j+x-1] = X[i:i+x-1])
                           { p = p - x; // update suffix length
                             j = j + x; // update suffix start index
                              v = w; break;
                        else return "P is not a substring of X"; \}\}\}\}
    until childTraversed=false or T.isExternal(v);
    return "P is not a substring of X"; }
```

Pattern Matching Using Suffix Trie (2/2)

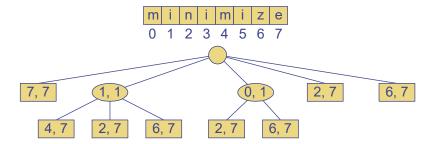
- Input of the algorithm:
 - Compact suffix trie T for a text X and pattern P.
- Output of the algorithm:
 - Starting index of a substring of X matching P or an indication that P is not a substring.
- The algorithm assumes the following additional property on the labels of the nodes in the compact representation of the suffix trie:
 - If node v has label (i, j) and Y is the string of length y associated with the path from the root to v (included), then X[j-y+1..j]=Y.
- This property ensures that we can easily compute the start index of the pattern in the text when a match occurs.

25

25

Analysis of Suffix Tries

- Compact representation of the suffix trie for a string X of size n from an alphabet of size d
 - Uses O(n) space
 - Supports arbitrary pattern matching queries in X in O(dm) time, where m is the size of the pattern
 - Can be constructed in O(n) time



Greedy Method and Text Compression



27

27

The Greedy Method Technique

- The greedy method is a general algorithm design paradigm, built on the following elements:
 - configurations: different choices, collections, or values to find
 - **objective function**: a score assigned to configurations, which we want to either maximize or minimize
- It works best when applied to problems with the greedy-choice property:
 - a globally-optimal solution can always be found by a series of local improvements from a starting configuration.

Text Compression

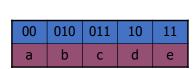
- Given a string X, efficiently encode X into a smaller string Y
 - Saves memory and/or bandwidth
- A good approach: Huffman encoding
 - Compute frequency f(c) for each character c.
 - Encode high-frequency characters with short code words
 - No code word is a prefix for another code
 - Use an optimal encoding tree to determine the code words

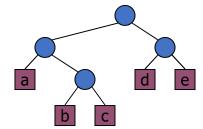
29

29

Encoding Tree Example

- A code is a mapping of each character of an alphabet to a binary codeword
- A prefix code is a binary code such that no code-word is the prefix of another code-word
- An encoding tree represents a prefix code
 - Each external node stores a character
 - The code word of a character is given by the path from the root to the external node storing the character (0 for a left child and 1 for a right child)

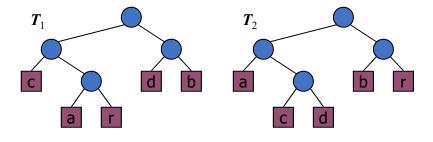




30

Encoding Tree Optimization

- Given a text string X, we want to find a prefix code for the characters of X that yields a small encoding for X
 - Frequent characters should have short code-words
 - Rare characters should have long code-words
- Example
 - X = abracadabra
 - T_1 encodes X into 29 bits
 - T₂ encodes X into 24 bits



31

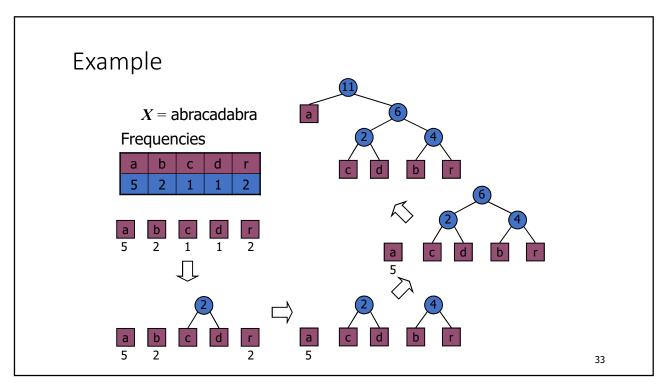
31

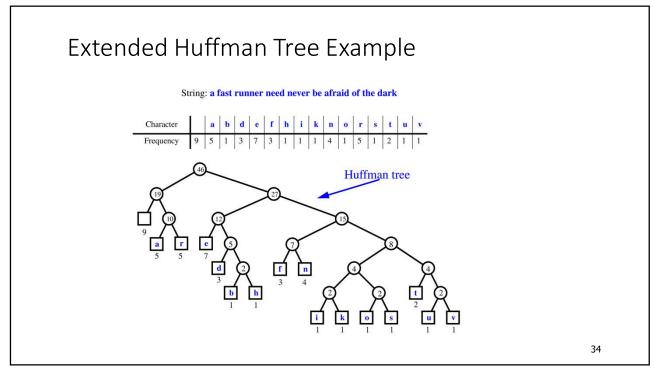
Huffman's Algorithm

- Given a string X,
 Huffman's algorithm
 construct a prefix code
 the minimizes the size
 of the encoding of X
- It runs in time
 O(n + d log d), where n
 is the size of X and d is
 the number of distinct
 characters of X
- A heap-based priority queue is used as an auxiliary structure

```
Algorithm HuffmanEncoding(X)
  Input string X of size n
  Output optimal encoding trie for X
  C = distinctCharacters(X);
  computeFrequencies(C, X);
  Q = \text{new empty heap};
  for all c \in C
    { T = \text{new single-node tree storing } c;
      Q.insert(getFrequency(c), T); }
  while (Q.size() > 1)
     \{ f_1 = Q.minKey(); 

T_1 = Q.removeMin(); 
       f_2 = \overline{Q}.minKey();
       T_2 = Q.removeMin();
        T = join(T_1, T_2);
        Q.insert(f_1 + f_2, T);
  return Q.removeMin();
```





The Fractional Knapsack Problem

- Given: A set S of n items, with each item i having
 - b_i a positive benefit
 - w_i a positive weight
- Goal: Choose items with maximum total benefit but with weight at most W.
- If we are allowed to take fractional amounts, then this is the fractional knapsack problem.
 - In this case, we let x_i denote the amount we take of item i
 - Objective: maximize $\sum_{i \in S} b_i (x_i \, / \, w_i)$
 - Constraint:

$$\sum_{i \in S} x_i \le W$$

35

35

Example

(\$ per ml)

- Given: A set S of n items, with each item i having
 - b_i a positive benefit
 - w_i a positive weight

• Goal: Choose items with maximum total benefit but with weight at most W.

Items: 1 2 3 4 5
Weight: 4 ml 8 ml 2 ml 6 ml 1 ml

Weight: 4 ml 8 ml 2 ml 6 ml 1 ml Benefit: \$12 \$32 \$40 \$30 \$50 Value: 3 4 20 5 50

"knapsack"

Solution:

- 1 ml of 5
- 2 ml of 3
- 6 ml of 4
- 1 ml of 2

36

The Fractional Knapsack Algorithm

- Greedy choice: Keep taking item with highest value (benefit to weight ratio)
 - Since $\sum_{i \in S} b_i(x_i / w_i) = \sum_{i \in S} (b_i / w_i) x_i$
 - Run time: O(n log n). Why?
- Correctness: Suppose there is a better solution
 - there is an item i with higher value than a chosen item j, but x_i<w_i, x_i>0 and v_i<v_i
 - If we substitute some i with j, we get a better solution
 - How much of i: min{w_i-x_i, x_i}
 - Thus, there is no better solution than the greedy one

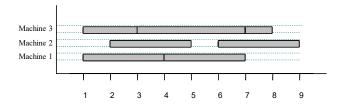
```
Algorithm fractionalKnapsack(S, W)
    Input: set S of items with benefit b_i
        and weight w_i; max. weight W
    Output: amount x_i of each item i
       to maximize benefit with weight
       at most W
  { for each item i in S
      \{x_i = \theta;
         v_i = b_i / w_i; // value
    w = 0;
                        // total weight
    while (w < W)
      \{ \text{ remove item } i \text{ with highest } v_i \}
         x_i = \min\{w_i, W-w\};
         w = w + \min\{w_i, W - w\};
      }
   }
```

37

37

Task Scheduling

- Given: a set T of n tasks, each having:
 - A start time, s_i
 - A finish time, f_i (where $s_i < f_i$)
- Goal: Perform all the tasks using a minimum number of "machines."



Task Scheduling Algorithm

- Greedy choice: consider tasks by their start time and use as few machines as possible with this order.
 - Run time: O(n log n). Why?
- Correctness: Suppose there is a better schedule.
 - We can use k-1 machines
 - The algorithm uses k
 - Let i be first task scheduled on machine k
 - Machine i must conflict with k-1 other tasks
 - But that means there is no nonconflicting schedule using k-1 machines

```
Algorithm taskSchedule(T)

Input: set T of tasks with start time s<sub>i</sub> and finish time f<sub>i</sub>

Output: non-conflicting schedule with minimum number of machines

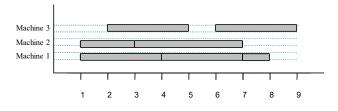
{ m = 0; // no. of machines
 while T is not empty
 { remove task i with smallest s<sub>i</sub> if there's a machine j for i then schedule i on machine j; else
 { m = m + 1; schedule i on machine m; }
 }
```

39

39

Example

- Given: a set T of n tasks, each having:
 - A start time, s_i
 - A finish time, f_i (where $s_i < f_i$)
 - [1,4], [1,3], [2,5], [3,7], [4,7], [6,9], [7,8] (ordered by start)
- Goal: Perform all tasks on min. number of machines



Dynamic Programming



41

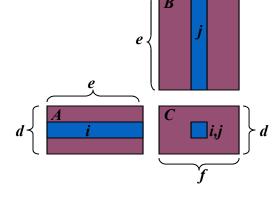
41

Matrix Chain-Products

- Dynamic Programming is a general algorithm design paradigm.
 - Rather than give the general structure, let us first give a motivating example:
 - Matrix Chain-Products
- Review: Matrix Multiplication.
 - C = A * B
 - A is $d \times e$ and B is $e \times f$

$$C[i,j] = \sum_{k=0}^{e-1} A[i,k] * B[k,j]$$

• *O*(*def*) time



Matrix Chain-Products

• Matrix Chain-Product:

- Compute A=A₀*A₁*...*A_{n-1}
- A_i is $d_i \times d_{i+1}$
- Problem: How to parenthesize?

Example

- B is 3 × 100
- C is 100 × 5
- D is 5 × 5
- (B*C)*D takes 1500 + 75 = 1575 ops
- B*(C*D) takes 1500 + 2500 = 4000 ops

43

43

An Enumeration Approach

Matrix Chain-Product Alg.:

- Try all possible ways to parenthesize $A=A_0*A_1*...*A_{n-1}$
- Calculate number of ops for each one
- · Pick the one that is best

• Running time:

- The number of parenthesizations is equal to the number of binary trees with n nodes
- This is exponential!
- It is called the Catalan number, and it is almost 4ⁿ.
- This is a terrible algorithm!

A Greedy Approach

- Idea #1: repeatedly select the product that uses (up) the most operations.
- Counter-example:
 - A is 10 × 5
 - B is 5 × 10
 - C is 10 × 5
 - D is 5 × 10
 - Greedy idea #1 gives (A*B)*(C*D), which takes 500+1000+500 = 2000 ops
 - A*((B*C)*D) takes 500+250+250 = 1000 ops

45

45

Another Greedy Approach

- Idea #2: repeatedly select the product that uses the fewest operations.
- Counter-example:
 - A is 101 × 11
 - B is 11 × 9
 - C is 9 × 100
 - D is 100 × 99
 - Greedy idea #2 gives A*((B*C)*D)), which takes 109989+9900+108900=228789
 ops
 - (A*B)*(C*D) takes 9999+89991+89100=189090 ops
- The greedy approach is not giving us the optimal value.

A "Recursive" Approach

- Define subproblems:
 - Find the best parenthesization of A_i*A_{i+1}*...*A_i.
 - Let N_{i,i} denote the number of operations done by this subproblem.
 - The optimal solution for the whole problem is $N_{0,n-1}$.
- Subproblem optimality: The optimal solution can be defined in terms of optimal subproblems
 - There has to be a final multiplication (root of the expression tree) for the optimal solution.
 - Say, the final multiply is at index i: $(A_0^*...^*A_i)^*(A_{i+1}^*...^*A_{n-1})$.
 - Then the optimal solution $N_{0,n-1}$ is the sum of two optimal subproblems, $N_{0,i}$ and $N_{i+1,n-1}$ plus the time for the last multiply.
 - If the global optimum did not have these optimal subproblems, we could define an even better "optimal" solution.

47

47

A Characterizing Equation

- The global optimal has to be defined in terms of optimal subproblems, depending on where the final multiply is at.
- Let us consider all possible places for that final multiply:
 - Recall that A_i is a $d_i \times d_{i+1}$ dimensional matrix.
 - So, a characterizing equation for N_{i,i} is the following:

$$N_{i,j} = \min_{i \le k < j} \{ N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1} \}$$

 Note that subproblems are not independent--the subproblems overlap.

A Dynamic Programming Algorithm

- Since subproblems overlap, we don't use recursion.
- Instead, we construct optimal subproblems "bottom-up."
- N_{i,i}'s are easy, so start with them
- Then do length 2,3,... subproblems, and so on.
- Running time: O(n3)

```
Algorithm matrixChain(S):

Input: sequence S of n matrices to be multiplied

Output: number of operations in an optimal parenthesization of S

{ for ( i = 1; i \le n-1; i++)

N_{i,i} = 0;

for ( b = 1; b \le n-1; b++)

for ( i = 0; i \le n-b-1; i++)

{ j = i+b;

N_{i,j} = +infinity;

for ( k = i; k \le j-1; i++)

N_{i,j} = \min\{N_{i,j}, N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1}\};

}

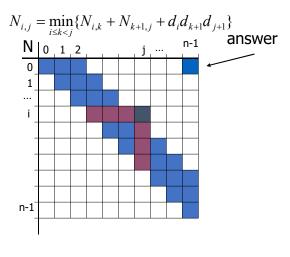
}
```

49

49

A Dynamic Programming Algorithm Visualization

- The bottom-up construction fills in the N array by diagonals
- N_{i,j} gets values from pervious entries in i-th row and j-th column
- Filling in each entry in the N table takes O(n) time.
- Total running time: O(n³)
- Getting actual parenthesization can be done by remembering "k" for each N entry



The General Dynamic Programming Technique

- Applies to a problem that at first seems to require a lot of time (possibly exponential), provided we have:
 - **Simple subproblems:** the subproblems can be defined in terms of a few variables, such as j, k, l, m, and so on.
 - Subproblem optimality: the global optimum value can be defined in terms of optimal subproblems
 - Subproblem overlap: the subproblems are not independent, but instead they overlap (hence, should be constructed bottom-up).

51

51

Subsequences

- A *subsequence* of a character string $x_0x_1x_2...x_{n-1}$ is a string of the form $x_{i_1}x_{i_2}...x_{i_k}$, where $i_j < i_{j+1}$.
- Not the same as substring!
- Example String: ABCDEFGHIJK
 - Subsequence: ACEGJIKSubsequence: DFGHKNot subsequence: DAGH

The Longest Common Subsequence (LCS) Problem

- Given two strings X and Y, the longest common subsequence (LCS) problem is to find a longest subsequence common to both X and Y
- Has applications to DNA similarity testing (alphabet is {A,C,G,T})
- Example: ABCDEFG and XZACKDFWGH have ACDFG as a longest common subsequence

53

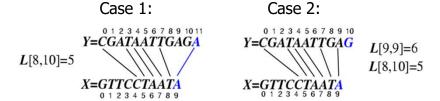
53

A Poor Approach to the LCS Problem

- A Brute-force solution:
 - Enumerate all subsequences of X
 - Test which ones are also subsequences of Y
 - Pick the longest one.
- Analysis:
 - If X is of length n, then it has 2ⁿ subsequences
 - This is an exponential-time algorithm!

A Dynamic-Programming Approach to the LCS Problem

- Define L[i,j] to be the length of the longest common subsequence of X[0..i] and Y[0..j].
- Allow for -1 as an index, so L[-1,k] = 0 and L[k,-1]=0, to indicate that the null part of X or Y has no match with the other.
- Then we can define L[i,j] in the general case as follows:
 - 1. If $x_i=y_i$, then L[i,j]=L[i-1,j-1]+1 (we can add this match)
 - 2. If $x_i \neq y_i$, then $L[i,j] = max\{L[i-1,j], L[i,j-1]\}$ (we have no match here)



55

An LCS Algorithm

```
Algorithm LCS(X,Y):

Input: Strings X and Y with n and m elements, respectively

Output: For i = 0,...,n-1, j = 0,...,m-1, the length L[i,j] of a longest string that is a subsequence of both the string X[0...i] = x_0x_1x_2...x_i and the string Y[0...] = y_0y_1y_2...y_j

{ for (i = -1; i \le m-1, i++)

L[i,-1] = 0;

for (j = -1; i \le m-1, j++)

L[-1,j] = 0;

for (i = 0; i \le m-1, i++)

if (x_i = y_j)

L[i,j] = L[i-1,j-1] + 1;

else

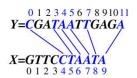
L[i,j] = \max\{L[i-1,j], L[i,j-1]\};

return array L;
```

56

Visualizing the LCS Algorithm

\boldsymbol{L}	-1	0	1	2	3	4	5	6	7	8	9	10	11
-1	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	1	1	1	1	1	1	1	1
1	0	0	1	1	2	2	2	2	2	2	2	2	2
2	0	0	1	1	2	2	2	3	3	3	3	3	3
3	0	1	1	1	2	2	2	3	3	3	3	3	3
4	0	1	1	1	2	2	2	3	3	3	3	3	3
5	0	1	1	1	2	2	2	3	4	4	4	4	4
6	0	1	1	2	2	3	3	3	4	4	5	5	5
7	0	1	1	2	2	3	4	4	4	4	5	5	6
8	0	1	1	2	3	3	4	5	5	5	5	5	6
9	0	1	1	2	3	4	4	5	5	5	6	6	6



57

57

Analysis of LCS Algorithm

- We have two nested loops
 - The outer one iterates *n* times
 - The inner one iterates *m* times
 - A constant amount of work is done inside each iteration of the inner loop
 - Thus, the total running time is O(nm)
- Answer is contained in L[n,m] (and the subsequence can be recovered from the L table).

Summary

- 1. Boyer-Moore algorithm
- 2. KMP algorithm
- 3. Standard tries
- 4. Compressed tries
- 5. Compact representation of compressed tries
- 6. Greedy method
- 7. Dynamic programming
- 8. Suggested reading: Sedgewick, Ch. 5.3, 15.2, 15.3.